

The Remote Sensing Vocabulary (F1.3)

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Overview

The purpose of this chapter is to introduce some of the principal characteristics of remotely sensed images and how they can be examined in Earth Engine. We discuss spatial resolution, temporal resolution, and spectral resolution, along with how to access important image metadata. You will be introduced to image data from several sensors aboard various satellite platforms. At the completion of the chapter, you will be able to understand the difference between remotely sensed datasets based on these characteristics, and how to choose an appropriate dataset for your analysis based on these concepts.

Learning Outcomes

- Understanding spatial, temporal, and spectral resolution.
- Navigating the Earth Engine **Console** to gather information about a digital image, including resolution and other data documentation.

Assumes you know how to:

- Navigate among Earth Engine result tabs (Chap. F1.0).
- Visualize images with a variety of false-color band combinations (Chap. F1.1).

Introduction to Theory

Images and image collections form the basis of many remote sensing analyses in Earth Engine. There are many different types of satellite imagery available to use in these analyses, but not every dataset is appropriate for every analysis. To choose the most appropriate dataset for your analysis, you should consider multiple factors. Among these are the resolution of the dataset—including the spatial, temporal, and spectral resolutions—as well as how the dataset was created and its quality.

The resolution of a dataset can influence the granularity of the results, the accuracy of the results, and how long it will take the analysis to run, among other things. For example, spatial resolution, which you will learn more about in Sect. 1, indicates the amount of Earth's surface area covered by a single pixel. One recent study compared

the results of a land use classification (the process by which different areas of the Earth's surface are classified as forest, urban areas, etc.) and peak total suspended solids (TSS) loads using two datasets with different spatial resolution. One dataset had pixels representing 900 m² of the Earth's surface, and the other represented 1 m². The higher resolution dataset (1 m²) had higher accuracy for the land use classification and better predicted TSS loads for the full study area. On the other hand, the lower resolution dataset was less costly and required less analysis time (Fisher et al. 2018).

Temporal and spectral resolution can also strongly affect analysis outcomes. In the Practicum that follows, we will showcase each of these types of resolution, along with key metadata types. We will also show you how to find more information about the characteristics of a given dataset in Earth Engine.

Practicum

Section 1. Searching for and Viewing Image Collection Information

If you have not already done so, you can add the book's code repository to the Code Editor by entering

https://code.earthengine.google.com/?accept_repo=projects/gee-edu/book (or the short URL bit.ly/EEFA-repo) into your browser. The book's scripts will then be available in the script manager panel to view, run, or modify. If you have trouble finding the repo, you can visit bit.ly/EEFA-repo-help for help.

Earth Engine's search bar can be used to find imagery and to locate important information about datasets in Earth Engine. Let's use the search bar, located above the Earth Engine code, to find out information about the Landsat 7 Collection 2 Raw Scenes. First, type "landsat 7 collection 2" into the search bar (Fig. F1.3.1). Without hitting Enter, matches to that search term will appear.

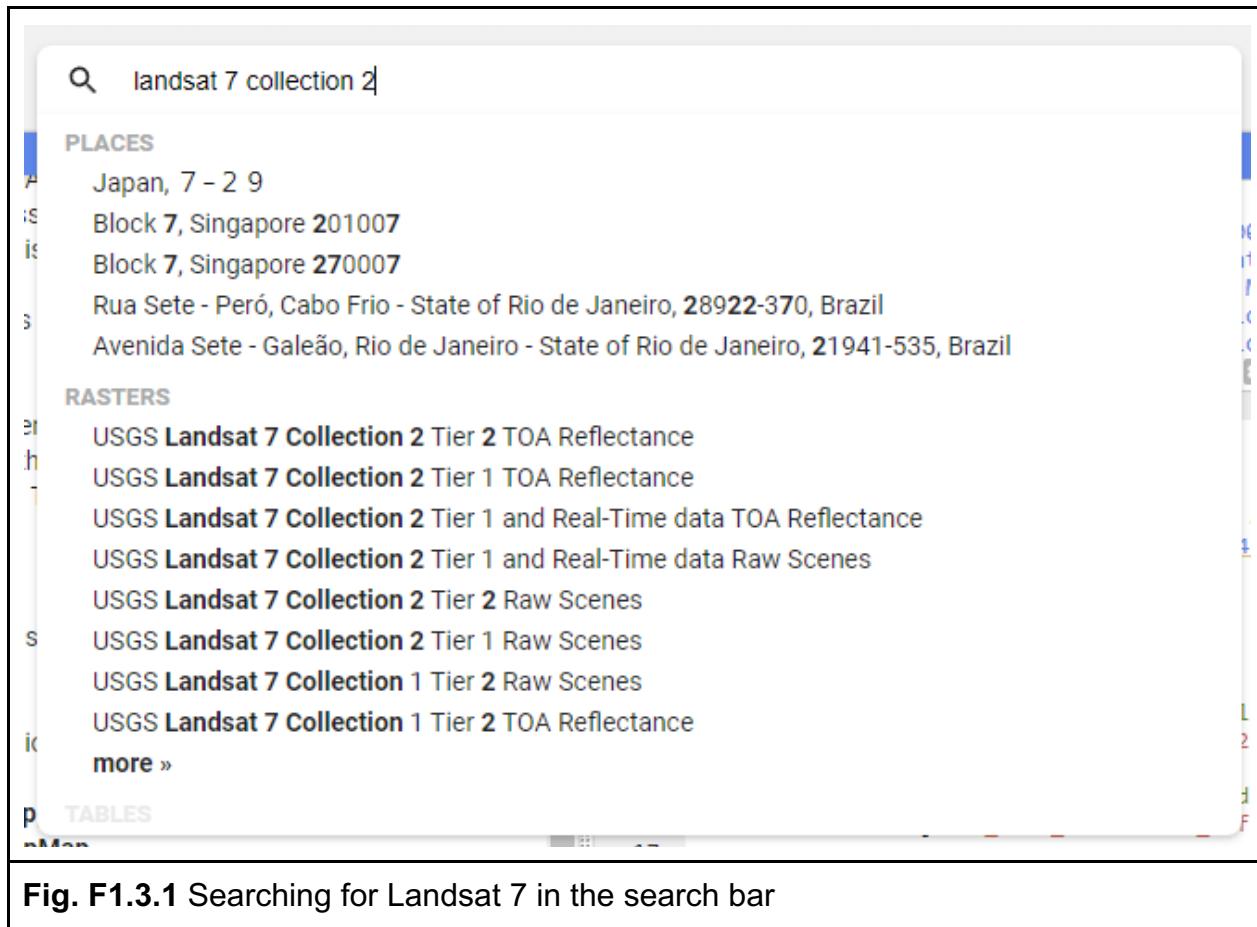


Fig. F1.3.1 Searching for Landsat 7 in the search bar

Now, click on **USGS Landsat 7 Collection 2 Tier 1 Raw Scenes**. A new inset window will appear (Fig. F1.3.2).

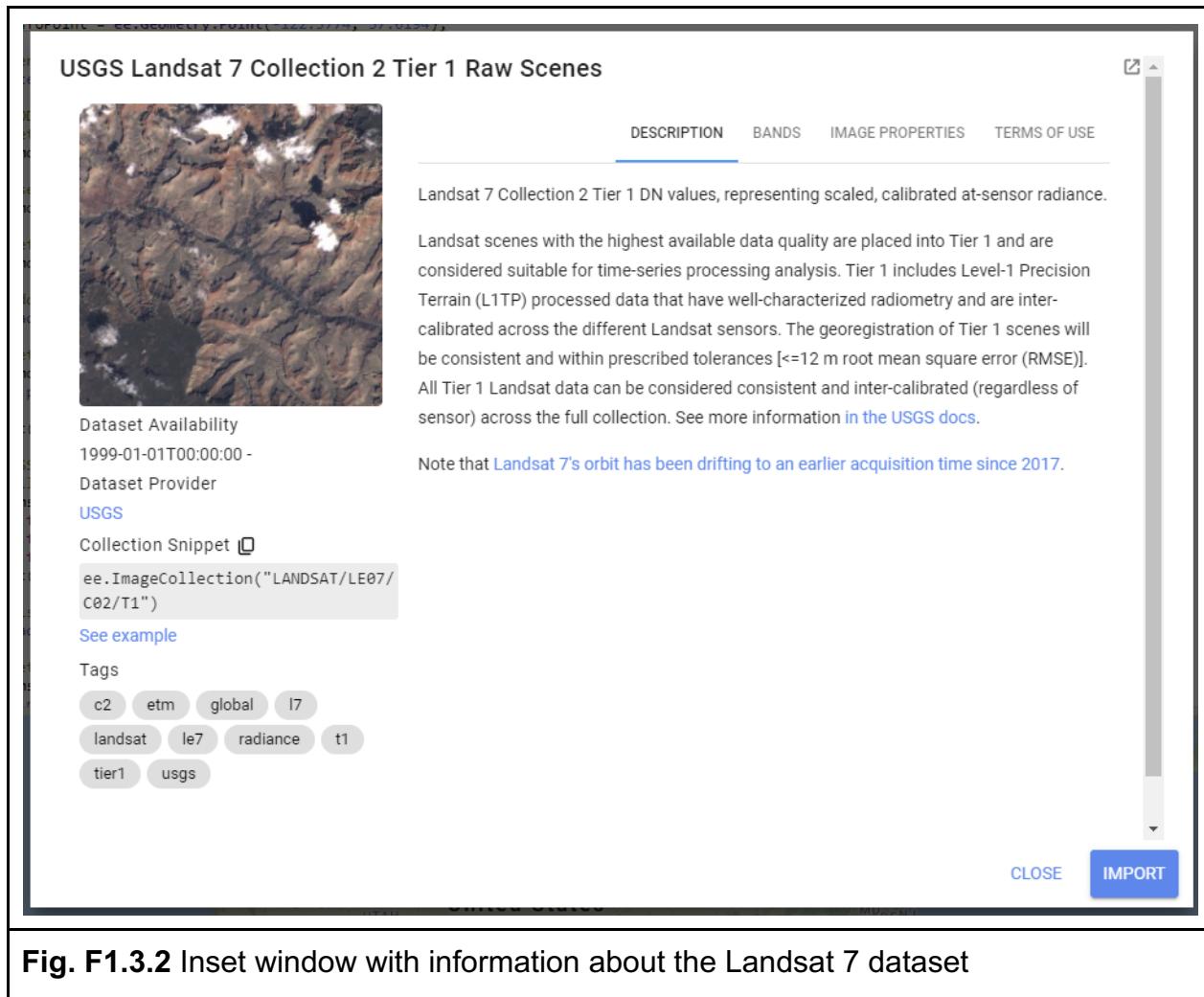


Fig. F1.3.2 Inset window with information about the Landsat 7 dataset

The inset window has information about the dataset, including a description, bands that are available, image properties, and terms of use for the data across the top. Click on each of these tabs and read the information provided. While you may not understand all of the information right now, it will set you up for success in future chapters.

On the left-hand side of this window, you will see a range of dates when the data is available, a link to the dataset provider's webpage, and a collection snippet. This collection snippet can be used to import the dataset by pasting it into your script, as you did in previous chapters. You can also use the large **Import** button to import the dataset into your current workspace. In addition, if you click on the **See example** link, Earth Engine will open a new code window with a snippet of code that shows code using the dataset. Code snippets like this can be very helpful when learning how to use a dataset that is new to you.

For now, click on the small “pop out” button in the upper right corner of the window. This will open a new window with the same information (Fig. F1.3.3); you can keep this new window open and use it as a reference as you proceed.

Earth Engine Data Catalog

Home View all datasets Browse by tags Landsat MODIS Sentinel API Docs

USGS Landsat 7 Collection 2 Tier 1 Raw Scenes



Dataset Availability
1999-01-01T00:00:00Z - 2022-01-04T00:00:00

Dataset Provider
USGS

Earth Engine Snippet
`ee.ImageCollection("LANDSAT/LE07/C02/T1")`

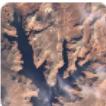
Tags
c2 etm global l7 landsat le7 radiance t1
tier1 usgs

Description	Bands	Image Properties	Terms of Use
Image Properties			
Name	Type	Description	
CLOUD_COVER	DOUBLE	Percentage cloud cover (0-100), -1 = not calculated.	

Fig. F1.3.3 The Data Catalog page for Landsat 7 with information about the dataset

Switch back to your code window. Your “landsat 7 collection 2” search term should still be in the search bar. This time, click the “Enter” key or click on the search magnifying glass icon. This will open a **Search results** inset window (Fig. F1.3.4).

Search results matching "landsat 7 collection 2"

-  [USGS Landsat 7 Collection 2 Tier 2 TOA Reflectance](#)
USGS/Google
Landsat 7 Collection 2 Tier 2 calibrated top-of-atmosphere (TOA) reflectance. Calibration coefficients are extracted from the image metadata. See [Chan...]
-  [USGS Landsat 7 Collection 2 Tier 1 TOA Reflectance](#)
USGS/Google
Landsat 7 Collection 2 Tier 1 calibrated top-of-atmosphere (TOA) reflectance. Calibration coefficients are extracted from the image metadata. See [Chan...]
-  [USGS Landsat 7 Collection 2 Tier 1 and Real-Time data TOA Reflectance](#)
USGS/Google
Landsat 7 Collection 2 Tier 1 and Real-Time data calibrated top-of-atmosphere (TOA) reflectance. Calibration coefficients are extracted from the image me...
-  [USGS Landsat 7 Collection 2 Tier 1 and Real-Time data Raw Scenes](#)
USGS
Landsat 7 Collection 2 Tier 1 and Real-Time data DN values, representing scaled, calibrated at-sensor radiance. Landsat scenes with the highest available da...
-  [USGS Landsat 7 Collection 2 Tier 2 Raw Scenes](#)
USGS
Landsat 7 Collection 2 Tier 2 DN values, representing scaled, calibrated at-sensor radiance. Scenes not meeting Tier 1 criteria during processing are assigne...
-  [USGS Landsat 7 Collection 2 Tier 1 Raw Scenes](#)
USGS
Landsat 7 Collection 2 Tier 1 DN values, representing scaled, calibrated at-sensor radiance. Landsat scenes with the highest available data quality are plac...

[CLOSE](#) [OPEN IN CATALOG](#)

Fig. F1.3.4 Search results matching “landsat 7 collection 2”

This more complete search results inset window contains short descriptions about each of the datasets matching your search, to help you choose which dataset you want to use. Click on the **Open in Catalog** button to view these search results in the Earth Engine Data Catalog (Fig. F1.3.5). Note that you may need to click **Enter** in the data catalog search bar with your phrase to bring up the results in this new window.

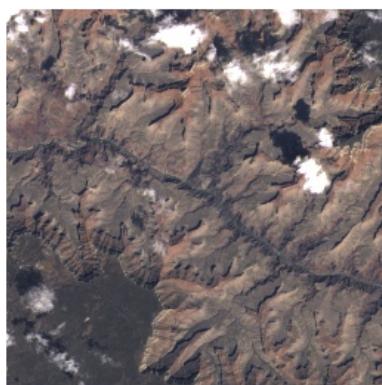
Earth Engine Data Catalog

Earth Engine's public data catalog includes a variety of standard Earth science raster datasets. You can import these datasets into your script environment with a single click. You can also upload your own [raster data](#) or vector data for private use or sharing in your scripts.

Looking for another dataset not in Earth Engine yet? Let us know by [suggesting a dataset](#).

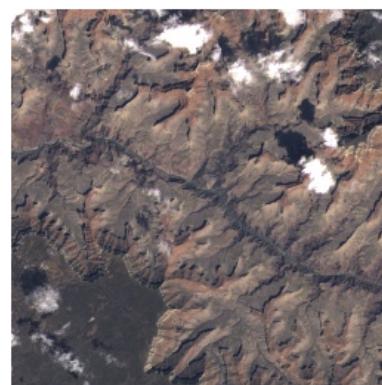
landsat 7 collection 2

USGS Landsat 7 Collection 2 Tier 1 Raw Scenes



Landsat 7 Collection 2 Tier 1 DN values, representing scaled, calibrated at-sensor radiance. Landsat scenes

USGS Landsat 7 Collection 2 Tier 1 and Real-Time data Raw Scenes



Landsat 7 Collection 2 Tier 1 and Real-Time data DN values, representing scaled, calibrated at-sensor

Fig. F1.3.5 Earth Engine Data Catalog results for the “landsat 7 collection 2” search term

Now that we know how to view this information, let's dive into some important remote sensing terminology.

Section 2. Spatial Resolution

Spatial resolution relates to the amount of Earth's surface area covered by a single pixel. It is typically referred to in linear units, for a single side of a square pixel: for example, we typically say that Landsat 7 has “30 m” color imagery. This means that each pixel is 30 m to a side, covering a total area of 900 m² of the Earth's surface. Spatial resolution is often interchangeably also referred to as the *scale*, as will be seen in this chapter when we print that value. The spatial resolution of a given data set greatly affects the

appearance of images, and the information in them, when you are viewing them on Earth's surface.

Next, we will visualize data from multiple sensors that capture data at different spatial resolutions, to compare the effect of different pixel sizes on the information and detail in an image. We'll be selecting a single image from each `ImageCollection` to visualize. To view the image, we will draw them each as a color-IR image, a type of false-color image (described in detail in Chap. F1.1) that uses the infrared, red, and green bands. As you move through this portion of the Practicum, zoom in and out to see differences in the pixel size and the image size.

MODIS (on the Aqua and Terra satellites)

As discussed in Chap. F1.2, the common resolution collected by MODIS for the infrared, red, and green bands is 500 m. This means that each pixel is 500 m on a side, with a pixel thus representing 0.25 km^2 of area on the Earth's surface.

Use the following code to center the map on the San Francisco airport at a zoom level of 16.

```
/////
// Explore spatial resolution
/////

// Define a region of interest as a point at San Francisco airport.
var sfoPoint = ee.Geometry.Point(-122.3774, 37.6194);

// Center the map at that point.
Map.centerObject(sfoPoint, 16);
```

Let's use what we learned in the previous section to search for, get information about, and import the MODIS data into our Earth Engine workspace. Start by searching for "MODIS 500" in the Earth Engine search bar.

Fig. F1.3.6 Using the search bar for the MODIS dataset

Use this to import the “MOD09A1.061 Terra Surface Reflectance 8-day Global 500m” [ImageCollection](#). A default name for the import appears at the top of your script; change the name of the import to `mod09`.

```
▶ var mod09: ImageCollection MODIS/061/MOD09A1
```

Fig. F1.3.7 Rename the imported MODIS dataset

When exploring a new dataset, you can find the names of bands in images from that set by reading the summary documentation, known as the metadata, of the dataset. In this dataset, the three bands for a color-IR image are “sur_refl_b02” (infrared), “sur_refl_b01” (red), and “sur_refl_b04” (green).

```
// MODIS
// Get an image from your imported MODIS MYD09GA collection.
var modisImage = mod09.filterDate('2020-02-01', '2020-03-01').first();

// Use these MODIS bands for near infrared, red, and green,
```

```

respectively.

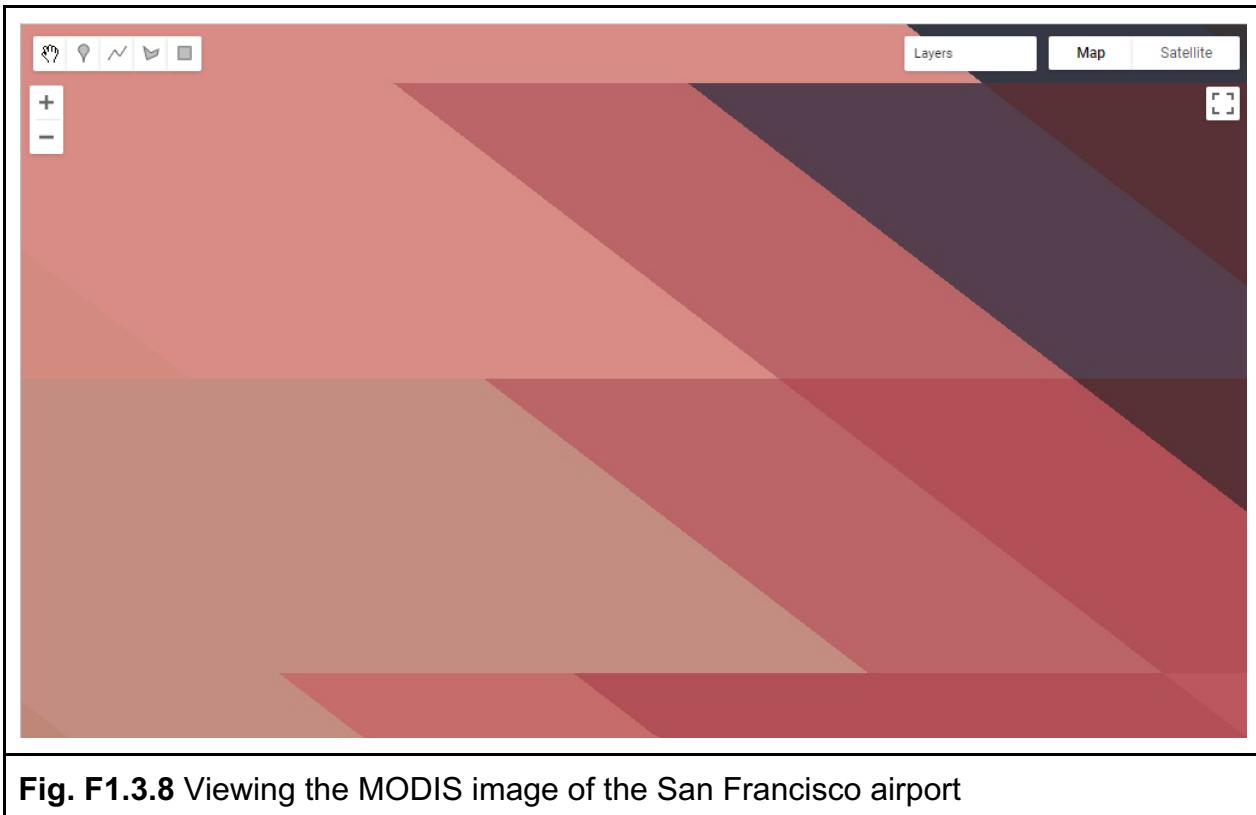
var modisBands = ['sur_refl_b02', 'sur_refl_b01', 'sur_refl_b04'];

// Define visualization parameters for MODIS.
var modisVis = {
  bands: modisBands,
  min: 0,
  max: 3000
};

// Add the MODIS image to the map.
Map.addLayer(modisImage, modisVis, 'MODIS');

```

In your map window, you should now see something like this.



You might be surprised to see that the pixels, which are typically referred to as “square”, are shown as parallelograms. The shape and orientation of pixels are controlled by the “projection” of the dataset, as well as the projection we are viewing them in. Most users do not have to be very concerned about different projections in Earth Engine, which automatically transfers data between different coordinate systems as it did here. For

more details about projections in general and their use in Earth Engine, you can consult the official documentation.

Let's view the size of pixels with respect to objects on the ground. Turn on the satellite basemap to see high-resolution data for comparison by clicking on **Satellite** in the upper-right corner of the map window. Then, decrease the layer's opacity: set the opacity in the **Layers** manager using the layer's slider (see Chap. F1.1). The result will look like Fig. F1.3.9.

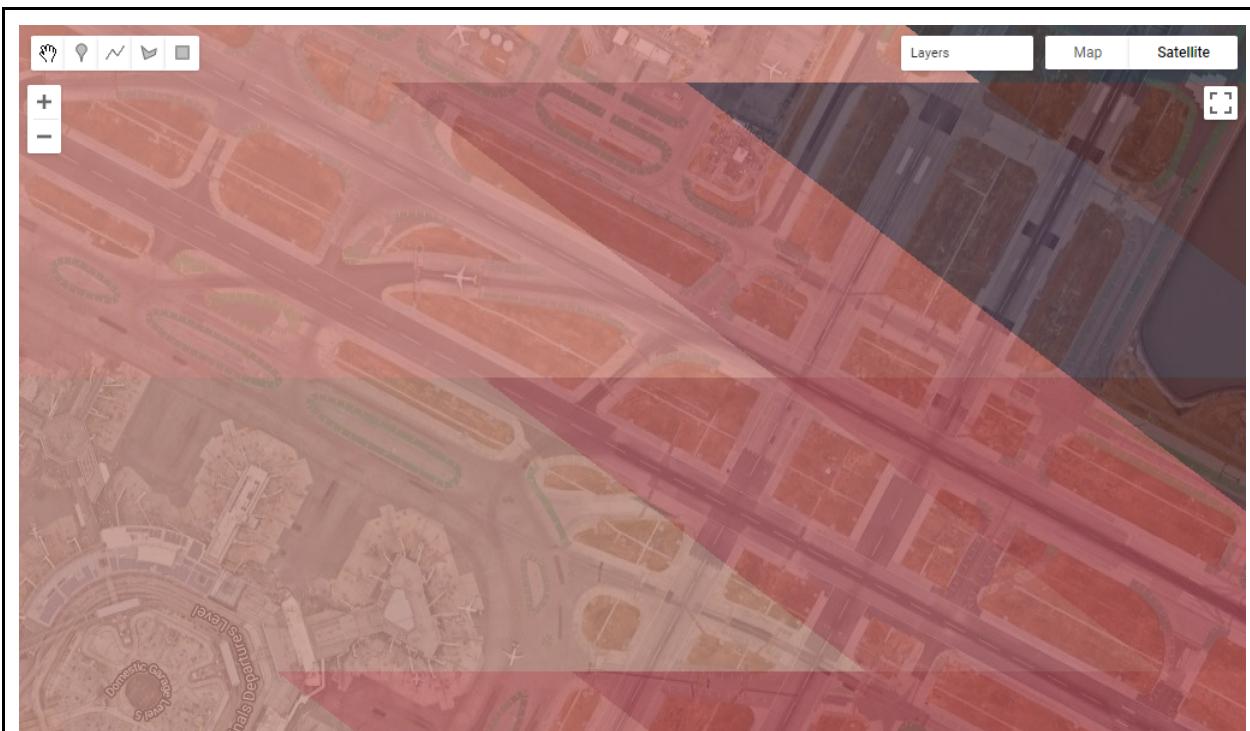


Fig. F1.3.9 Using transparency to view the MODIS pixel size in relation to high-resolution imagery of the San Francisco airport

Print the size of the pixels (in meters) by running this code:

```
// Get the scale of the data from the NIR band's projection:  
var modisScale = modisImage.select('sur_refl_b02')  
    .projection().nominalScale();  
  
print('MODIS NIR scale:', modisScale);
```

In that call, we used the `nominalScale` function here after accessing the projection information from the MODIS NIR band. That function extracts the spatial resolution from

the projection information, in a format suitable to be printed to the screen. The nominalScale function returns a value just under the stated 500m resolution due to the sinusoidal projection of MODIS data and the distance of the pixel from nadir--that is, where the satellite is pointing directly down at the Earth's surface.

TM (on early Landsat satellites)

Thematic Mapper (TM) sensors were flown aboard Landsat 4 and 5. TM data have been processed to a spatial resolution of 30m, and were active from 1982 to 2012. Search for “Landsat 5 TM” and import the result called “USGS Landsat 5 TM Collection 2 Tier 1 Raw Scenes”. In the same way you renamed the MODIS collection, rename the import `tm`. In this dataset, the three bands for a color-IR image are called “B4” (infrared), “B3” (red), and “B2” (green). Let’s now visualize TM data over the airport and compare it with the MODIS data. Note that we can either define the visualization parameters as a variable (as in the previous code snippet) or place them in curly braces in the `Map.addLayer` function (as in this code snippet).

When you run this code, the TM image will display. Notice how many more pixels are displayed on your screen when compared to the MODIS image.

```
// TM
// Filter TM imagery by location and date.
var tmImage = tm
  .filterBounds(Map.getCenter())
  .filterDate('1987-03-01', '1987-08-01')
  .first();

// Display the TM image as a false color composite.
Map.addLayer(tmImage, {
  bands: ['B4', 'B3', 'B2'],
  min: 0,
  max: 100
}, 'TM');
```

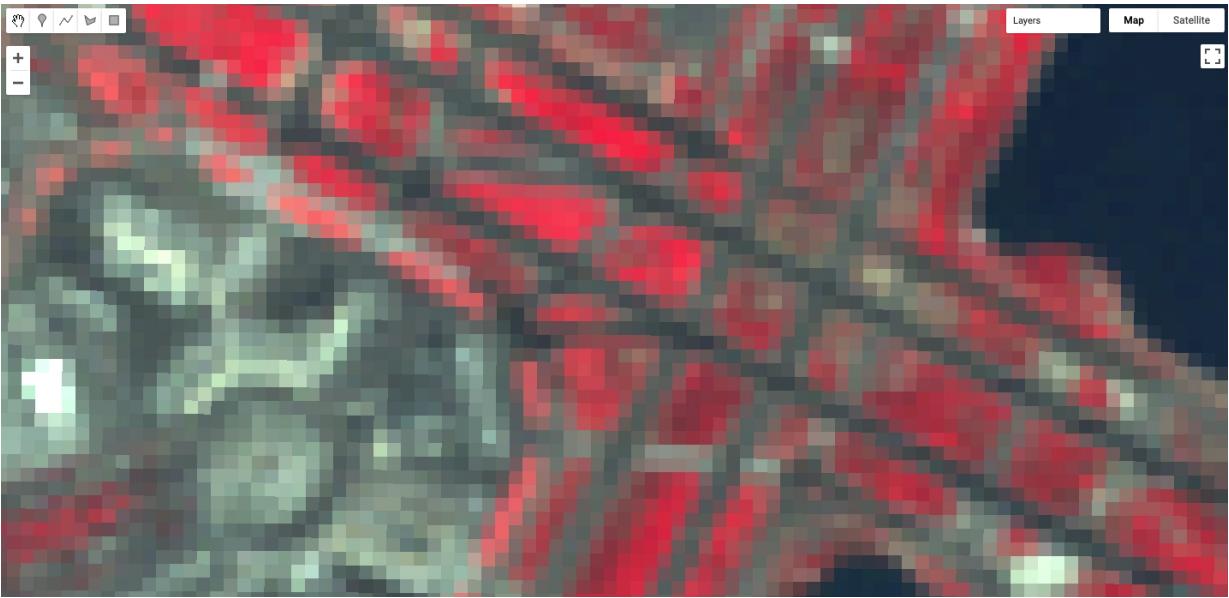


Fig. F1.3.10 Visualizing the TM imagery from the Landsat 5 satellite

As we did for the MODIS data, let's check the scale. The scale is expressed in meters:

```
// Get the scale of the TM data from its projection:  
var tmScale = tmImage.select('B4')  
    .projection().nominalScale();  
  
print('TM NIR scale:', tmScale);
```

MSI (on the Sentinel-2 satellites)

The MultiSpectral Instrument (MSI) flies aboard the Sentinel-2 satellites, which are operated by the European Space Agency. The red, green, blue, and near-infrared bands are captured at 10 m resolution, while other bands are captured at 20 m and 30 m. The Sentinel-2A satellite was launched in 2015 and the 2B satellite was launched in 2017.

Search for “Sentinel 2 MSI” in the search bar, and add the “Sentinel-2 MSI: MultiSpectral Instrument, Level-1C” dataset to your workspace. Name it `msi`. In this dataset, the three bands for a color-IR image are called “B8” (infrared), “B4” (red), and “B3” (green).

```
// MSI  
// Filter MSI imagery by location and date.  
var msiImage = msi  
    .filterBounds(Map.getCenter())
```

```

.filterDate('2020-02-01', '2020-04-01')
.first();

// Display the MSI image as a false color composite.
Map.addLayer(msiImage, {
  bands: ['B8', 'B4', 'B3'],
  min: 0,
  max: 2000
}, 'MSI');

```

Compare the MSI imagery with the TM and MODIS imagery, using the opacity slider. Notice how much more detail you can see on the airport terminal and surrounding landscape. The 10 m spatial resolution means that each pixel covers approximately 100 m² of the Earth's surface, a much smaller area than the TM imagery (900 m²) or the MODIS imagery (0.25 km²).



Fig. F1.3.11 Visualizing the MSI imagery

The extent of the MSI image displayed is also smaller than that for the other instruments we have looked at. Zoom out until you can see the entire San Francisco Bay. The MODIS image covers the entire globe, the TM image covers the entire San Francisco

Bay and the surrounding area south towards Monterey, while the MSI image captures a much smaller area.

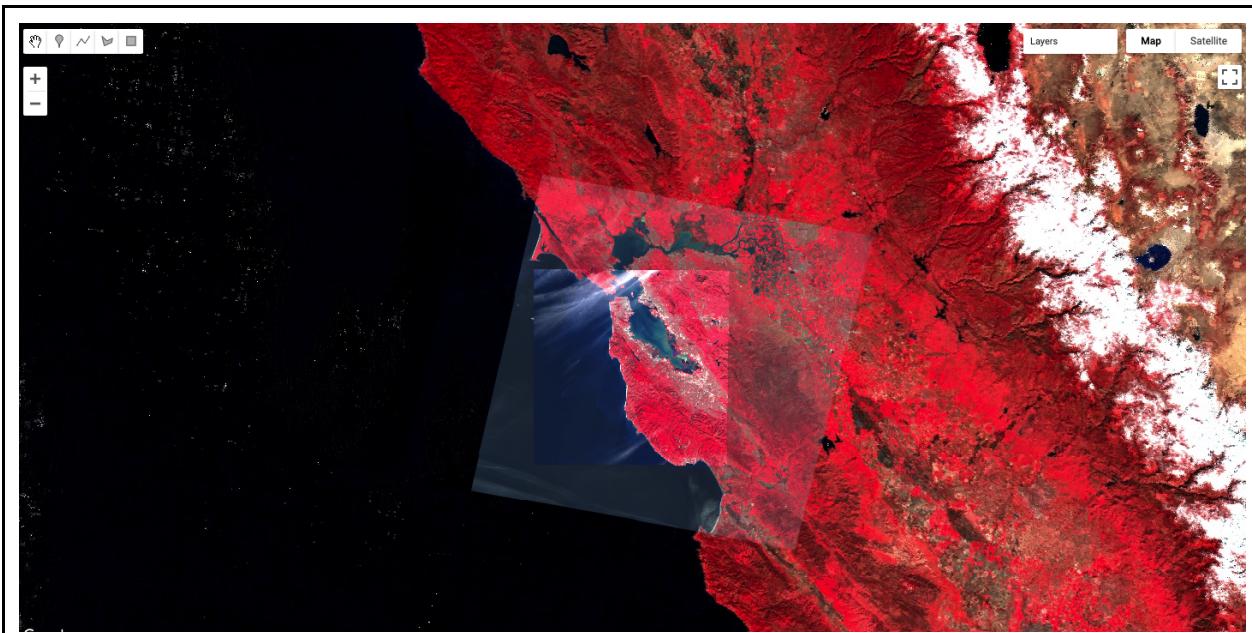


Fig. F1.3.12 Visualizing the image size for the MODIS, Landsat 5 (TM instrument), and Sentinel-2 (MSI instrument) datasets

Check the scale of the MSI instrument (in meters):

```
// Get the scale of the MSI data from its projection:  
var msiScale = msiImage.select('B8')  
    .projection().nominalScale();  
print('MSI scale:', msiScale);
```

NAIP

The National Agriculture Imagery Program (NAIP) is a U.S. government program to acquire imagery over the continental United States using airborne sensors. Data is collected for each state approximately every three years. The imagery has a spatial resolution of 0.5–2 m, depending on the state and the date collected.

Search for “naip” and import the data set for “NAIP: National Agriculture Imagery Program”. Name the import `naip`. In this dataset, the three bands for a color-IR image are called “N” (infrared), “R” (red), and “G” (green).

```
// NAIP
```

```

// Get NAIP images for the study period and region of interest.
var naipImage = naip
  .filterBounds(Map.getCenter())
  .filterDate('2018-01-01', '2018-12-31')
  .first();

// Display the NAIP mosaic as a color-IR composite.
Map.addLayer(naipImage, {
  bands: ['N', 'R', 'G']
}, 'NAIP');

```

The NAIP imagery is even more spatially detailed than the Sentinel-2 MSI imagery. However, we can see that our one NAIP image doesn't totally cover the San Francisco airport. If you like, zoom out to see the boundaries of the NAIP image as we did for the Sentinel-2 MSI imagery.

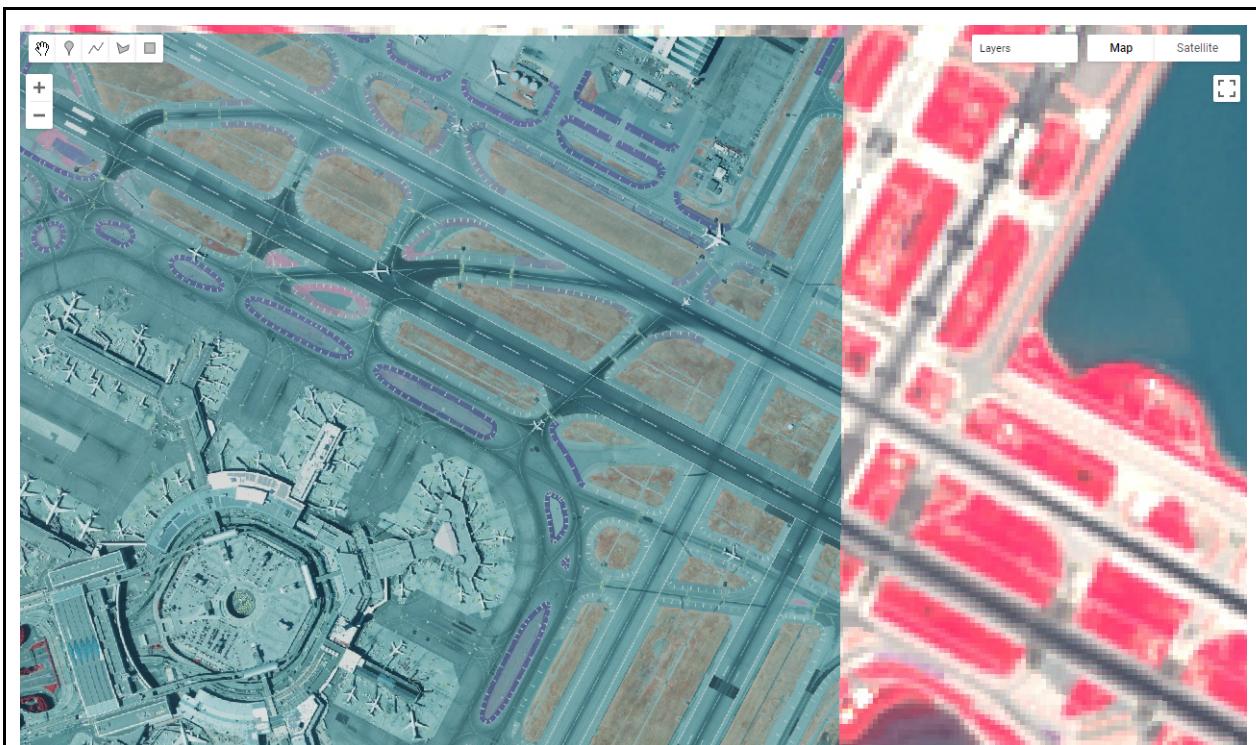


Fig. F1.3.13 NAIP color-IR composite over the San Francisco airport

And get the scale, as we did before.

```
// Get the NAIP resolution from the first image in the mosaic.
```

```
var naipScale = naipImage.select('N')
    .projection().nominalScale();

print('NAIP NIR scale:', naipScale);
```

Each of the datasets we've examined has a different spatial resolution. By comparing the different images over the same location in space, you have seen the differences between the large pixels of MODIS, the medium-sized pixels of TM (Landsat 5) and MSI (Sentinel-2), and the small pixels of the NAIP. Datasets with large-sized pixels are also called “coarse resolution,” those with medium-sized pixels are also called “moderate resolution,” and those with small-sized pixels are also called “fine resolution.”

Code Checkpoint F13a. The book's repository contains a script that shows what your code should look like at this point.

Section 3. Temporal Resolution

Temporal resolution refers to the revisit time, or temporal cadence of a particular sensor's image stream. Revisit time is the number of days between sequential visits of the satellite to the same location on the Earth's surface. Think of this as the frequency of pixels in a time series at a given location.

Landsat

The Landsat satellites 5 and later are able to image a given location every 16 days. Let's use our existing `tm` dataset from Landsat 5. To see the time series of images at a location, you can filter an `ImageCollection` to an area and date range of interest and then `print` it. For example, to see the Landsat 5 images for three months in 1987, run the following code:

```
/////
// Explore Temporal Resolution
////
// Use Print to see Landsat revisit time
print('Landsat-5 series:', tm
    .filterBounds(Map.getCenter())
    .filterDate('1987-06-01', '1987-09-01'));

// Create a chart to see Landsat 5's 16 day revisit time.
var tmChart = ui.Chart.image.series({
```

```
imageCollection: tm.select('B4').filterDate('1987-06-01',
    '1987-09-01'),
region: sfoPoint
}).setSeriesNames(['NIR']);
```

Expand the features property of the printed `ImageCollection` in the **Console** output to see a `List` of all the images in the collection. Observe that the date of each image is part of the filename (e.g., `LANDSAT/LT05/C02/T1/LT05_044034_19870628`).

```
1: Image LANDSAT/LT05/C02/T1/LT05_044034_19870628 (13 bands)
  type: Image
  id: LANDSAT/LT05/C02/T1/LT05_044034_19870628
  version: 1652688761628442
  ▶ bands: List (13 elements)
  ▶ properties: Object (106 properties)
```

Fig. F1.3.14 Landsat image name and feature properties

However, viewing this list doesn't make it easy to see the temporal resolution of the dataset. We can use Earth Engine's plotting functionality to visualize the temporal resolution of different datasets. For each of the different temporal resolutions, we will create a per-pixel chart of the NIR band that we mapped previously. To do this, we will use the `ui.Chart.image.series` function.

The `ui.Chart.image.series` function requires you to specify a few things in order to calculate the point to chart for each time step. First, we filter the `ImageCollection` (you can also do this outside the function and then specify the `ImageCollection` directly). We select the B4 (near infrared) band and then select three months by using `filterDate` on the `ImageCollection`. Next, we need to specify the location to chart; this is the `region` argument. We'll use the `sfoPoint` variable we defined earlier.

```
// Create a chart to see Landsat 5's 16 day revisit time.
var tmChart = ui.Chart.image.series({
  imageCollection: tm.select('B4').filterDate('1987-06-01',
    '1987-09-01'),
  region: sfoPoint
}).setSeriesNames(['NIR']);
```

By default, this function creates a trend line. It's difficult to see precisely when each image was collected, so let's create a specialized chart style that adds points for each observation.

```
// Define a chart style that will let us see the individual dates.  
var chartStyle = {  
    hAxis: {  
        title: 'Date'  
    },  
    vAxis: {  
        title: 'NIR Mean'  
    },  
    series: {  
        0: {  
            lineWidth: 3,  
            pointSize: 6  
        }  
    },  
};  
  
// Apply custom style properties to the chart.  
tmChart.setOptions(chartStyle);  
  
// Print the chart.  
print('TM Chart', tmChart);
```

When you print the chart, it will have a point each time an image was collected by the TM instrument (Fig. F1.3.15). In the **Console**, you can move the mouse over the different points and see more information. Also note that you can expand the chart using the button in the upper right-hand corner. We will see many more examples of charts, particularly in the chapters in Part F4.

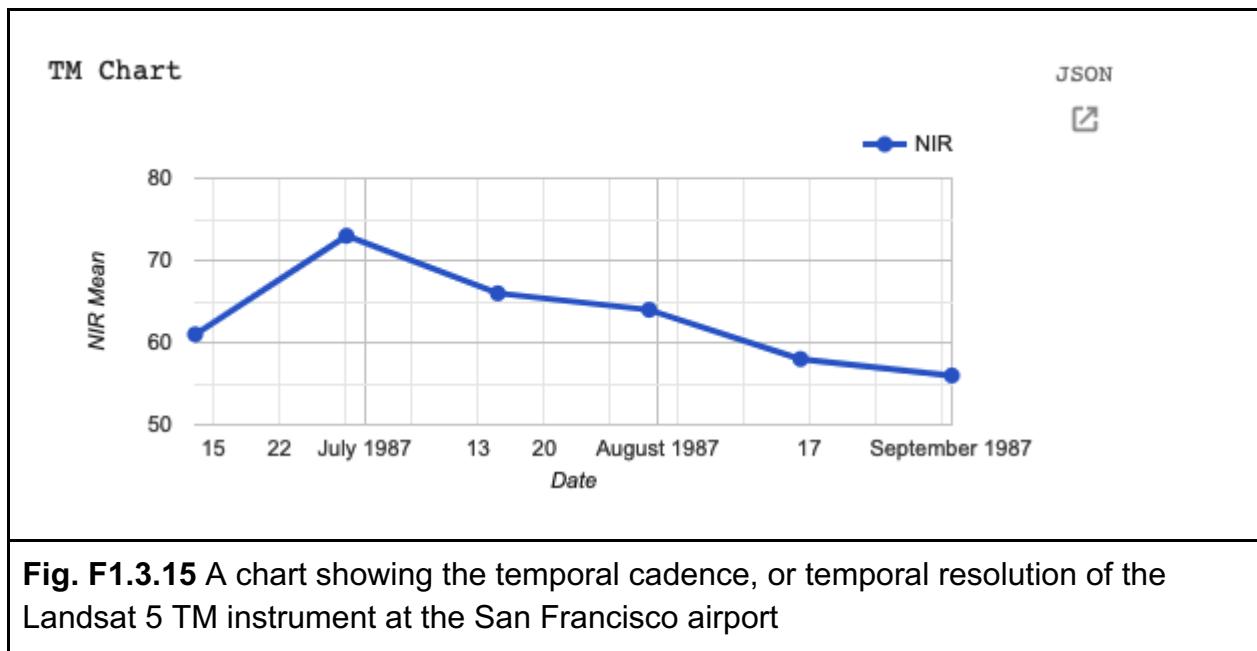


Fig. F1.3.15 A chart showing the temporal cadence, or temporal resolution of the Landsat 5 TM instrument at the San Francisco airport

Sentinel-2

The Sentinel-2 program's two satellites are in coordinated orbits, so that each spot on Earth gets visited about every 5 days. Within Earth Engine, images from these two sensors are pooled in the same dataset. Let's create a chart using the MSI instrument dataset we have already imported.

```
// Sentinel-2 has a 5 day revisit time.
var msiChart = ui.Chart.image.series({
  imageCollection: msi.select('B8').filterDate('2020-06-01',
    '2020-09-01'),
  region: sfoPoint
}).setSeriesNames(['NIR']);

// Apply the previously defined custom style properties to the chart.
msiChart.setOptions(chartStyle);

// Print the chart.
print('MSI Chart', msiChart);
```

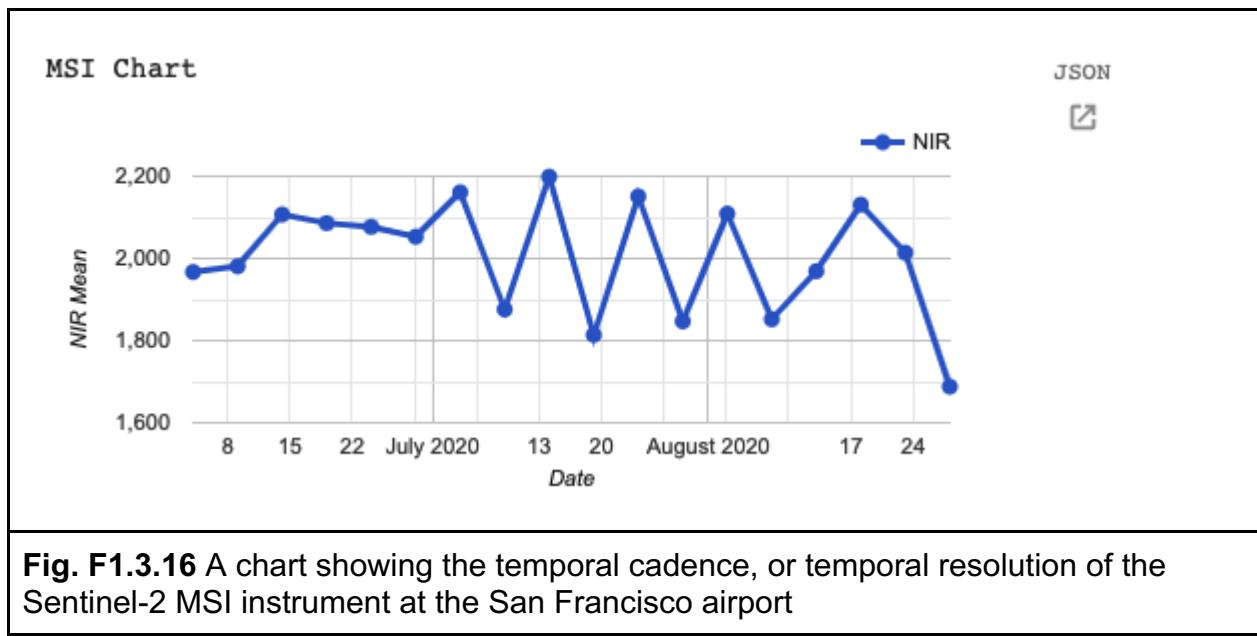


Fig. F1.3.16 A chart showing the temporal cadence, or temporal resolution of the Sentinel-2 MSI instrument at the San Francisco airport

Compare this Sentinel-2 graph (Fig. F1.3.16) with the Landsat graph you just produced (Fig. F1.3.15). Both cover a period of six months, yet there are many more points through time for the Sentinel-2 satellite, reflecting the greater temporal resolution.

Code Checkpoint F13b. The book's repository contains a script that shows what your code should look like at this point.

Section 4. Spectral Resolution

Spectral resolution refers to the number and width of spectral bands in which the sensor takes measurements. You can think of the width of spectral bands as the wavelength intervals for each band. A sensor that measures radiance in multiple bands is called a *multiplespectral* sensor (generally 3–10 bands), while a sensor with many bands (possibly hundreds) is called a *hyperspectral* sensor; however, these are relative terms without universally accepted definitions.

Let's compare the multispectral MODIS instrument with the hyperspectral Hyperion sensor aboard the EO-1 satellite, which is also available in Earth Engine.

MODIS

There is an easy way to check the number of bands in an image:

```
/////
// Explore spectral resolution
/////
```

```

// Get the MODIS band names as an ee.List
var modisBands = modisImage.bandNames();

// Print the list.
print('MODIS bands:', modisBands);

// Print the length of the list.
print('Length of the bands list:', modisBands.length());

```

Note that not all of the bands are spectral bands. As we did with the temporal resolution, let's graph the spectral bands to examine the spectral resolution. If you ever have questions about what the different bands in the band list are, remember that you can find this information by visiting the dataset information page in Earth Engine or the data or satellite's webpage.

```

// Graph the MODIS spectral bands (bands 11-17).

// Select only the reflectance bands of interest.
var reflectanceImage = modisImage.select(
  'sur_refl_b01',
  'sur_refl_b02',
  'sur_refl_b03',
  'sur_refl_b04',
  'sur_refl_b05',
  'sur_refl_b06',
  'sur_refl_b07'
);

```

As before, we'll customize the chart to make it easier to read.

```

// Define an object of customization parameters for the chart.
var options = {
  title: 'MODIS spectrum at SFO',
  hAxis: {
    title: 'Band'
  },
  vAxis: {
    title: 'Reflectance'
  }
}

```

```
},
legend: {
    position: 'none'
},
pointSize: 3
};
```

And create a chart using the `ui.Chart.image.regions` function.

```
// Make the chart.
var modisReflectanceChart = ui.Chart.image.regions({
    image: reflectanceImage,
    regions: sfoPoint
}).setOptions(options);

// Display the chart.
print(modisReflectanceChart);
```

The resulting chart is shown in Fig. F1.3.17. Use the expand button in the upper right to see a larger version of the chart than the one printed to the **Console**.

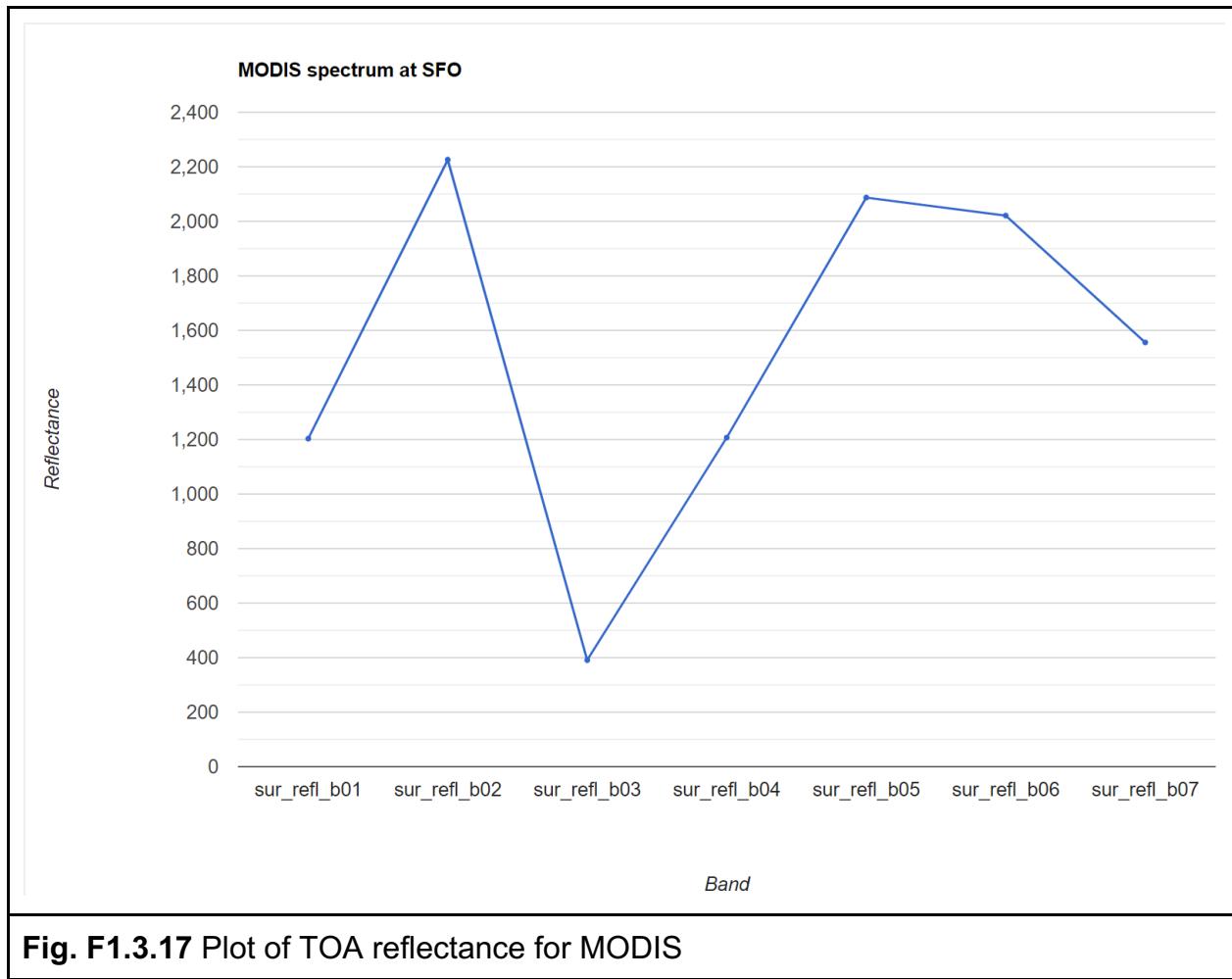


Fig. F1.3.17 Plot of TOA reflectance for MODIS

EO-1

Now let's compare MODIS with the EO-1 satellite's hyperspectral sensor. Search for "eo-1" and import the "EO-1 Hyperion Hyperspectral Imager" dataset. Name it `eo1`. We can look at the number of bands from the EO-1 sensor.

```
// Get the EO-1 band names as a ee.List
var eo1Image = eo1
  .filterDate('2015-01-01', '2016-01-01')
  .first();

// Extract the EO-1 band names.
var eo1Bands = eo1Image.bandNames();

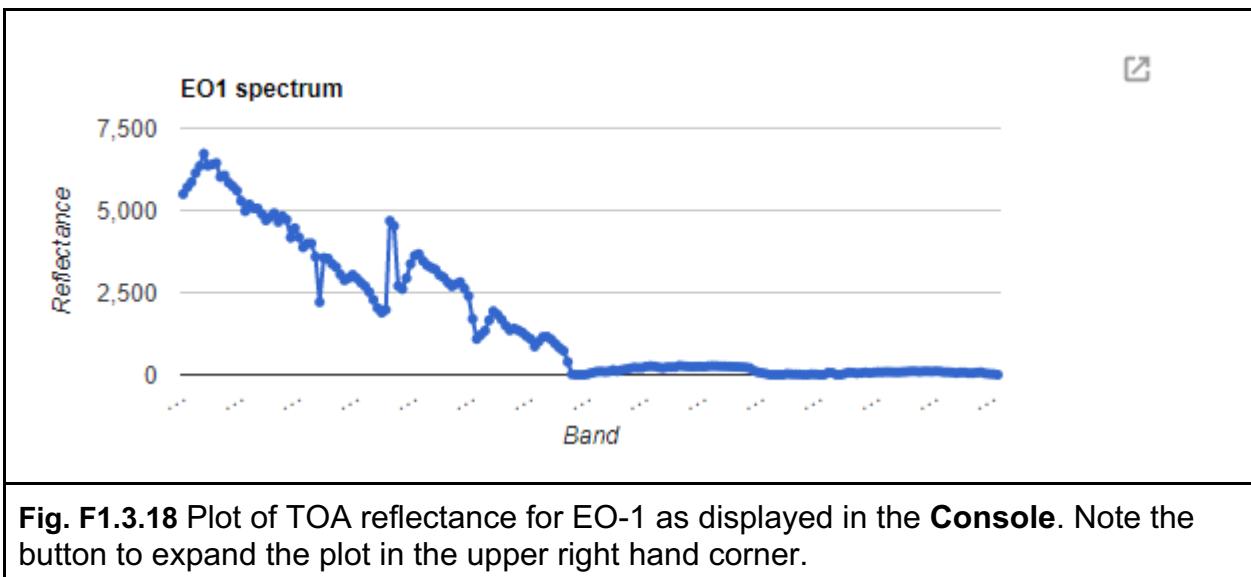
// Print the list of band names.
print('EO-1 bands:', eo1Bands);
```

Examine the list of bands that are printed in the **Console**. Notice how many more bands the hyperspectral instrument provides.

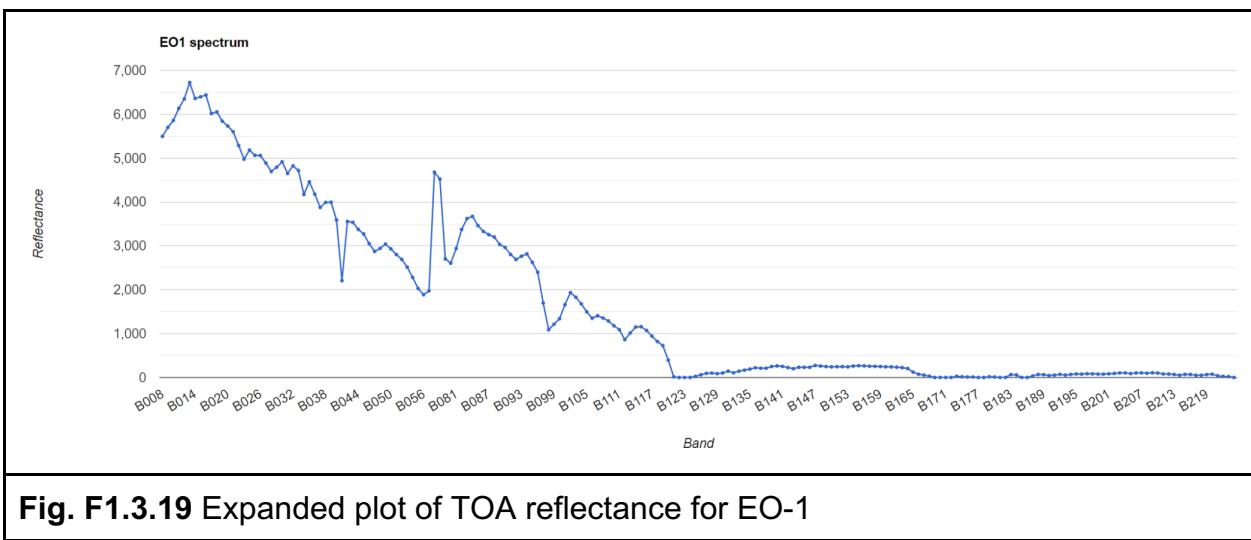
Now let's create a reflectance chart as we did with the MODIS data.

```
// Create an options object for our chart.  
var optionsE01 = {  
    title: 'EO1 spectrum',  
    hAxis: {  
        title: 'Band'  
    },  
    vAxis: {  
        title: 'Reflectance'  
    },  
    legend: {  
        position: 'none'  
    },  
    pointSize: 3  
};  
  
// Make the chart and set the options.  
var eo1Chart = ui.Chart.image.regions({  
    image: eo1Image,  
    regions: ee.Geometry.Point([6.10, 81.12])  
}).setOptions(optionsE01);  
  
// Display the chart.  
print(eo1Chart);
```

The resulting chart is seen in Fig. F1.3.18. There are so many bands that their names only appear as “...”!



If we click on the expand icon in the top right corner of the chart, it's a little easier to see the band identifiers, as shown in Fig. F1.3.19.



Compare this hyperspectral instrument chart with the multispectral chart we plotted above for MODIS.

Code Checkpoint F13c. The book's repository contains a script that shows what your code should look like at this point.

Section 5. Per-Pixel Quality

As you saw above, an image consists of many bands. Some of these bands contain spectral responses of Earth's surface, including the NIR, red, and green bands we examined in the Spectral Resolution section. What about the other bands? Some of these other bands contain valuable information, like pixel-by-pixel quality-control data.

For example, Sentinel-2 has a QA60 band, which contains the surface reflectance quality assurance information. Let's map it to inspect the values.

```
/////
// Examine pixel quality
/////

// Sentinel Quality Visualization.
var msiCloud = msi
    .filterBounds(Map.getCenter())
    .filterDate('2019-12-31', '2020-02-01')
    .first();

// Display the MSI image as a false color composite.
Map.addLayer(msiCloud,
{
    bands: ['B8', 'B4', 'B3'],
    min: 0,
    max: 2000
},
'MSI Quality Image');

Map.addLayer(msiCloud,
{
    bands: ['QA60'],
    min: 0,
    max: 2000
},
'Sentinel Quality Visualization');
```

Use the **Inspector** tool to examine some of the values. You may see values of 0 (black), 1024 (gray), and 2048 (white). The QA60 band has values of 1024 for opaque clouds, and 2048 for cirrus clouds. Compare the false-color image with the QA60 band to see

these values. More information about how to interpret these complex values is given in [Chap. F4.3](#), which explains the treatment of clouds.

Code Checkpoint F13d. The book's repository contains a script that shows what your code should look like at this point.

Section 6. Metadata

In addition to band imagery and per-pixel quality flags, Earth Engine allows you to access substantial amounts of metadata associated with an image. This can all be easily printed to the **Console** for a single image.

Let's examine the metadata for the Sentinel-2 MSI.

```
/////
// Metadata
////
print('MSI Image Metadata', msiImage);
```

Examine the object you've created in the **Console** (Fig. F1.3.20). Expand the image name, then the **properties** object.

MSI Image Metadata

▼ Image COPERNICUS/S2/20200204T185551_20200204T190203_T10SEG (16 bands) JSON

 type: Image
 id: COPERNICUS/S2/20200204T185551_20200204T190203_T10SEG
 version: 1580901045654538
 ► bands: List (16 elements)
 ▼ properties: Object (66 properties)
 CLOUDY_PIXEL_PERCENTAGE: 15.9791
 CLOUD_COVERAGE_ASSESSMENT: 15.9791
 DATASTRIP_ID: S2A_OPER_MSI_L1C_DS_MPS__20200204T220958_S20200204T190203_N02.09
 DATATAKE_IDENTIFIER: GS2A_20200204T185551_024134_N02.09
 DATATAKE_TYPE: INS-NOBS
 DEGRADED_MSI_DATA_PERCENTAGE: 0
 FORMAT_CORRECTNESS: PASSED
 GENERAL_QUALITY: PASSED
 GENERATION_TIME: 1580854198000
 GEOMETRIC_QUALITY: PASSED
 GRANULE_ID: L1C_T10SEG_A024134_20200204T190203
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B1: 112.234421367
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B10: 114.760758382
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B11: 113.013631158
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B12: 112.144265308
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B2: 118.166658878
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B3: 115.782426186
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B4: 114.361737025
 MEAN_INCIDENCE_AZIMUTH_ANGLE_B5: 113.78411373

Fig. F1.3.20 Checking the “CLOUDY_PIXEL_PERCENTAGE” property in the

metadata for Sentinel-2

The first entry is the `CLOUDY_PIXEL_PERCENTAGE` information. Distinct from the cloudiness flag attached to every pixel, this is an image-level summary assessment of the overall cloudiness in the image. In addition to viewing the value, you might find it useful to print it to the screen, for example, or to record a list of cloudiness values in a set of images. Metadata properties can be extracted from an image's properties using the `get` function, and printed to the **Console**.

```
// Image-level Cloud info
var msiCloudiness = msiImage.get('CLOUDY_PIXEL_PERCENTAGE');

print('MSI CLOUDY_PIXEL_PERCENTAGE:', msiCloudiness);
```

Code Checkpoint F13e. The book's repository contains a script that shows what your code should look like at this point.

Synthesis

Assignment 1. Recall the plots of spectral resolution we created for MODIS and EO-1. Create a plot of spectral resolution for one of the other sensors described in this chapter. What are the bands called? What wavelengths of the electromagnetic spectrum do they correspond to?

Assignment 2. Recall how we extracted the spatial resolution and saved it to a variable. In your code, set the following variables to the scales of the bands shown in Table F1.3.1.

Table F1.3.1 The three datasets and bands to use.

Dataset	Band	Variable name
MODIS MYD09A1	sur_refl_b01	modisB01Scale
Sentinel-2 MSI	B5	msiB5Scale
NAIP	R	naipScale

Assignment 3. Make this point in your code: `ee.Geometry.Point([-122.30144, 37.80215])`. How many MYD09A1 images are there in 2017 at this point? Set a variable called `mod09ImageCount` with that value, and print it. How many Sentinel-2 MSI surface reflectance images are there in 2017 at this point? Set a variable called `msiImageCount` with that value, and print it.

Conclusion

A good understanding of the characteristics of your images is critical to your work in Earth Engine and the chapters going forward. You now know how to observe and query a variety of remote sensing datasets, and can choose among them for your work. For example, if you are interested in change detection, you might require a dataset with spectral resolution including near-infrared imagery and a fine temporal resolution. For analyses at a continental scale, you may prefer data with a coarse spatial scale, while analyses for specific forest stands may benefit from a very fine spatial scale.

Feedback

To review this chapter and make suggestions or note any problems, please go now to bit.ly/EEFA-review. You can find summary statistics from past reviews at bit.ly/EEFA-reviews-stats.

References

Fisher JRB, Acosta EA, Dennedy-Frank PJ, et al (2018) Impact of satellite imagery spatial resolution on land use classification accuracy and modeled water quality. *Remote Sens Ecol Conserv* 4:137–149. <https://doi.org/10.1002/rse2.61>