

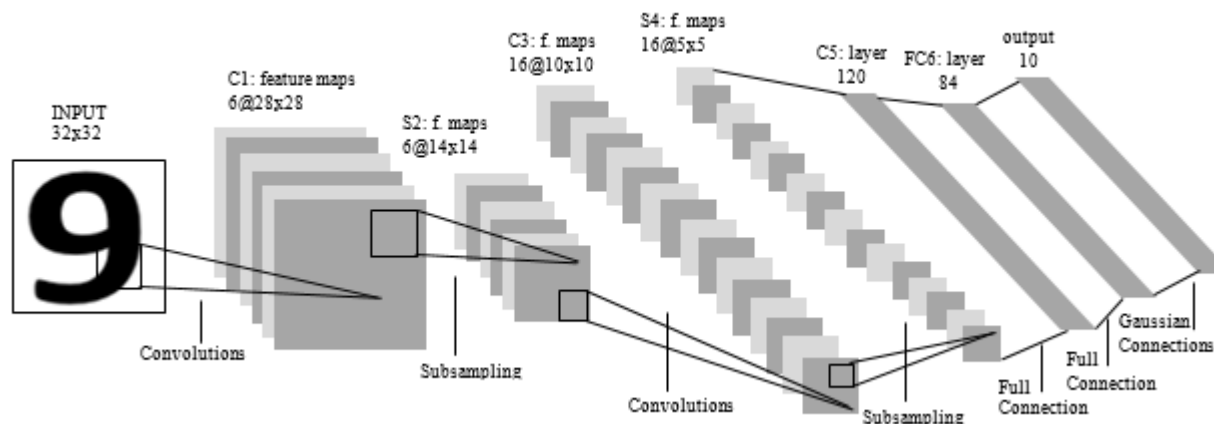
# Course Outline

- TOPICS

1. What is Machine Learning and Image Processing
2. Traditional Features, K-NN classifier
3. Linear Classification
4. Perceptron Algorithm, Sigmoid Activation Function, Gradient Descent
5. Stochastic Gradient Descent, Back-Propagation
6. Multi-Layer Neural Network
7. Convolution and Pooling
8. Mid-Term Examination
9. Mid-Term Examination
10. Convolutional Neural Networks.
11. Training Convolutional Neural Networks: Hyper-Parameters, Activation functions, initialization, dropout, batch normalization
12. Recurrent Neural Networks
13. Applications of Convolutional Neural Networks for Image Segmentation and Object Classification
14. Project Presentations

# Convolution LeNet5

|       |             |          |              |
|-------|-------------|----------|--------------|
| input |             | 32x32    |              |
| conv1 | 5x5 @6      | 28x28x6  |              |
| pool  | 2x2         | 14x14x6  |              |
| conv2 | 5x5x6 @16   | 10x10x16 |              |
| pool  | 2x2         | 5x5x16   |              |
| FC    | 5x5x16 @120 | 1x120    |              |
| FC    | 1x120 @84   | 1x84     |              |
| out   | 1x84 @10    | 1x10     | predicted    |
|       |             | 1x10     | ground Truth |



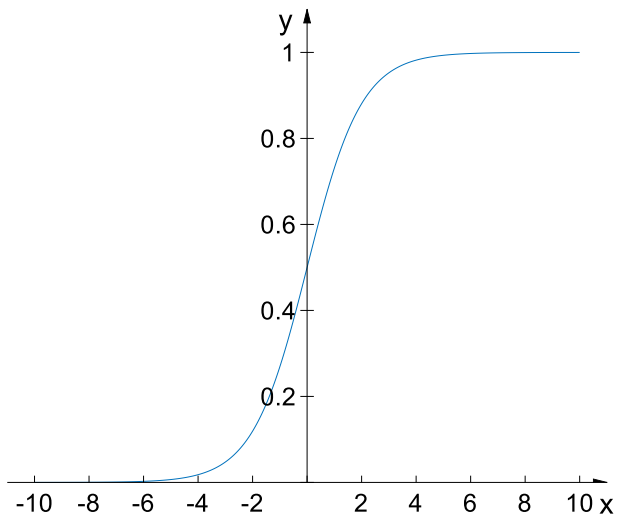
# Convolution LeNet5

|       |             |          |              |
|-------|-------------|----------|--------------|
| input |             | 32x32    |              |
| conv1 | 5x5 @6      | 28x28x6  |              |
| reLU  |             | 28x28x6  |              |
| pool  | 2x2         | 14x14x6  |              |
| conv2 | 5x5x6 @16   | 10x10x16 |              |
| reLU  |             | 10x10x16 |              |
| pool  | 2x2         | 5x5x16   |              |
| FC    | 5x5x16 @120 | 1x120    |              |
| FC    | 1x120 @84   | 1x84     |              |
| out   | 1x84 @10    | 1x10     | predicted    |
|       |             | 1x10     | softmax      |
|       |             | 1x10     | ground Truth |

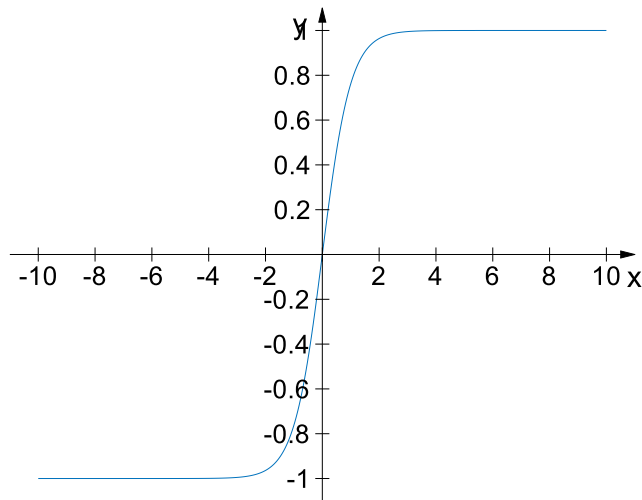
# Hyper Parameters

- **Training samples:** assume that we have  $n$  training samples for  $m$  classes.
- **Learning Rate:** used in stochastic gradient descent
  - A.k.a. 0.001. 0.0001. or 0.000001
- **Epoch: 1 epoch** equals to number of all training samples passed through both of forward and backward process.
- **Batch Size:**
  - if mini batch size is 1, it means that 1 sample sent to the feed-forward process. Iteration becomes  $n$ .
  - if mini batch size is 5, it means that 5 samples sent to the feed-forward process. Iteration becomes  $n/5$ .
- **Activation Functions:** ReLU, Sigmoid, tanh.
- **Dropout:** used to avoid overfitting thus increasing generalization.
  - If the drop out rate 50%, then 50% nodes set with 0.
- **Number of Hidden Layer and Units:** number of convolutions, pooling, momentum rate.
- **Loss functions:** L1, L2, Huber loss etc...
- **Weight Initialization:** set with random small numbers or Xavier initialization.

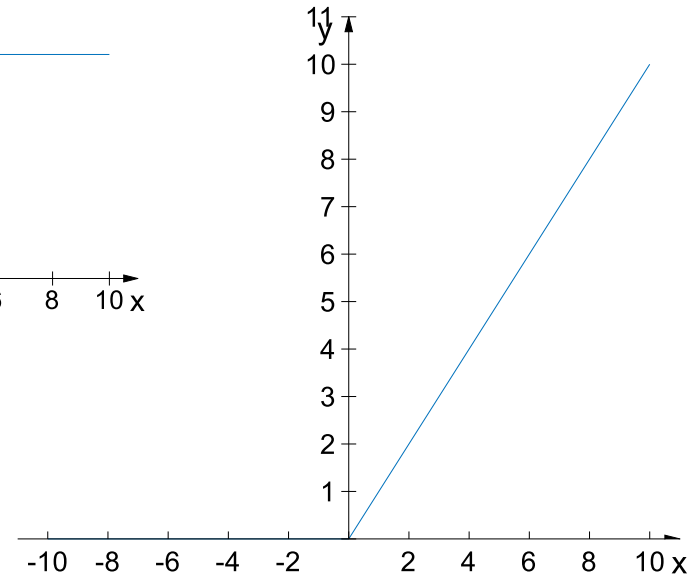
# Activation Functions



sigmoid



tanh



ReLU

# Initialization of Weights

**input :  $224 \times 224 \times 5$**

**f :  $3 \times 3 \times 5 \times 64$**

**h : 3, w : 3, in : 5, out : 64**

Gaussian

**type = 'single'**

**sc = 0.01;**

**weights = randn(h, w, in, out, type)\*sc;**

Xavier

**type = 'single'**

**sc = sqrt(3/(h\*w\*in)) ;**

**weights = (rand(h, w, in, out, type)\*2 - 1)\*sc ;**

Xavier Improved

**type = 'single'**

**sc = sqrt(2/(h\*w\*out)) ;**

**weights = randn(h, w, in, out, type)\*sc ;**

# Dropout

|   |   |   |   |
|---|---|---|---|
| 1 | 1 | 3 | 4 |
|---|---|---|---|

**50% dropout**

|   |   |   |   |
|---|---|---|---|
| 1 | 0 | 3 | 0 |
|---|---|---|---|

|   |   |   |   |
|---|---|---|---|
| 1 | 1 | 3 | 4 |
|---|---|---|---|

**25% dropout**

|   |   |   |   |
|---|---|---|---|
| 1 | 1 | 3 | 0 |
|---|---|---|---|

# Batch Normalization

- Affects the learning process with SGDM.
- Improve stability.
- Avoid the over-fitting and under-fitting.

$$\hat{\mathbf{x}}_i = \frac{\mathbf{x}_i}{\sqrt{\sigma_b^2 + \text{eps}}}$$

$\sigma_b$  = variance of batch

eps :  $1 \times 10^{-9}$

**data is normalized**



# Layers Matlab

```
lr = [.1 2] ;

% Define network CIFAR10-quick
net.layers = {} ;

% Block 1
net.layers{end+1} = struct('type', 'conv', ...
    'weights', {{0.01*randn(5,5,3,6, 'single'), zeros(1, 32, 'single')}} , ...
    'learningRate', lr, ...
    'stride', 1, ...
    'pad', 0) ;
net.layers{end+1} = struct('type', 'pool', ...
    'method', 'max', ...
    'pool', [2 2], ...
    'stride', 2, ...
    'pad', 0) ;
net.layers{end+1} = struct('type', 'relu') ;
```

# Layers Python Tensorflow

```
# TODO: Layer 1: Convolutional. Input = 32x32x1. Output = 28x28x6.
conv1_w = tf.Variable(tf.truncated_normal(shape = [5,5,1,6],mean = mu, stddev = sigma))
conv1_b = tf.Variable(tf.zeros(6))
conv1 = tf.nn.conv2d(x,conv1_w, strides = [1,1,1,1], padding = 'VALID') + conv1_b
# TODO: Activation.
conv1 = tf.nn.relu(conv1)

# TODO: Pooling. Input = 28x28x6. Output = 14x14x6.
pool_1 = tf.nn.max_pool(conv1,ksize = [1,2,2,1], strides = [1,2,2,1], padding = 'VALID')

# TODO: Layer 2: Convolutional. Output = 10x10x16.
conv2_w = tf.Variable(tf.truncated_normal(shape = [5,5,6,16], mean = mu, stddev = sigma))
conv2_b = tf.Variable(tf.zeros(16))
conv2 = tf.nn.conv2d(pool_1, conv2_w, strides = [1,1,1,1], padding = 'VALID') + conv2_b
# TODO: Activation.
conv2 = tf.nn.relu(conv2)

# TODO: Pooling. Input = 10x10x16. Output = 5x5x16.
pool_2 = tf.nn.max_pool(conv2, ksize = [1,2,2,1], strides = [1,2,2,1], padding = 'VALID')
```

# Layers Python Keras

```
1 import keras
2 from keras.models import Sequential
3 from keras.layers import Conv2D
4 from keras.layers import MaxPooling2D
5 from keras.layers import Flatten
6 from keras.layers import Dense
7 def getModel():
8     model = Sequential()
9     #Layer 1
10    #Conv Layer 1
11    model.add(Conv2D(filters = 6,
12                     kernel_size = 5,
13                     strides = 1,
14                     activation = 'relu',
15                     input_shape = (32,32,1)))
16    #Pooling layer 1
17    model.add(MaxPooling2D(pool_size = 2, strides = 2))
18    #Layer 2
19    #Conv Layer 2
20    model.add(Conv2D(filters = 16,
21                     kernel_size = 5,
22                     strides = 1,
23                     activation = 'relu',
24                     input_shape = (14,14,6)))
25    #Pooling Layer 2
26    model.add(MaxPooling2D(pool_size = 2, strides = 2))
27    #Flatten
28    model.add(Flatten())
29    #Layer 3
30    #Fully connected layer 1
31    model.add(Dense(units = 120, activation = 'relu'))
32    #Layer 4
33    #Fully connected layer 2
34    model.add(Dense(units = 84, activation = 'relu'))
35    #Layer 5
36    #Output Layer
37    model.add(Dense(units = 10, activation = 'softmax'))
38    model.compile(optimizer = 'adam', loss = 'categorical_crossentropy', metrics = ['accuracy'])
39    return model
40
```

check the  
**LENET5KERAS.sln**

# About Final Project

- In your project, you must use the Keras model with respect to facilities behind the Keras.
- The another advantage of using Keras is expressed with that you can migrate any Keras model to Tensorflow, Matlab and other formats.
- Your project topic would be about classification.