



User / Technician : actor

Web interface : boundary

Controller : control

Motor(s) : entity

GPS : boundary

RequestDiagnostics()

GetDiagnostics()

GetThrust()

thrust

GetGPSData()

gps\_data

GetGPSDiagnostics()

gps\_diagnostics

GetConnectionDiagnostics()

connection\_diagnostics

thrust,  
gps\_data,  
gps\_diagnostics,  
connection\_diagnostics

DisplayDiagnostics(thrust,  
gps\_data,  
gps\_diagnostics,  
connection\_diagnostics)

DisplayOnMap(gps\_data)

