

Tema 3

Ecuación 1D de Transporte

Ecuación 1D de transporte. Métodos explícitos e implícitos.

Referencias del Capítulo:

- Numerical Recipes. W.H. Press, B.P. Flannery, S.A. Teukolsky and W.T. Vetterling. Cambridge University Press (1988).
- Computational Techniques for Fluid Dynamics. C.A.J. Fletcher. Springer-Verlag (1991).

M3: Ecuación de Transporte.

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} - \alpha \frac{\partial^2 T}{\partial x^2} = 0$$

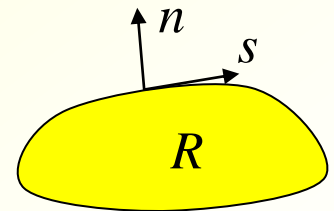
Consideramos un sistema en el que el transporte de información puede ser difusivo y/o convectivo. La forma de ecuación más general tiene la forma:

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} - \alpha \frac{\partial^2 T}{\partial x^2} = 0$$

donde T es la variable a estudiar (p.e.: temperatura) que se ve forzada con una velocidad de convección u y se difunde con una difusividad α .

Para tener un problema bien planteado necesitamos aportar:

- Condiciones iniciales (especificar $T(x)$ para un t_o y todo x).
- Condiciones de frontera para todo t .



∂R =frontera

1. Condiciones de Dirichlet: $T=f$ en ∂R .

2. Condiciones de Neumann (de la derivada): $\frac{\partial T}{\partial n} = f$ o $\frac{\partial T}{\partial s} = g$ en ∂R

3. Condiciones de mezcla o de Robin:

$$\frac{\partial T}{\partial n} + kT = f \text{ con } k > 0 \text{ en } \partial R$$

M3: Ecuación de Transporte. Esquema FTCS

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} - \alpha \frac{\partial^2 T}{\partial x^2} = 0$$

$$\frac{\partial T}{\partial t} = \frac{T_i^{n+1} - T_i^n}{\Delta t}$$

$$\frac{\partial T}{\partial x} = \frac{T_{i+1}^n - T_{i-1}^n}{2\Delta x} \Rightarrow \frac{T_i^{n+1} - T_i^n}{\Delta t} + u \frac{T_{i+1}^n - T_{i-1}^n}{2\Delta x} - \alpha \frac{T_{i-1}^n - 2T_i^n + T_{i+1}^n}{\Delta x^2} = 0$$

$$\frac{\partial^2 T}{\partial x^2} = \frac{T_{i-1}^n - 2T_i^n + T_{i+1}^n}{\Delta x^2}$$

Consistencia:

$$E_i^n = Cu(\Delta x/2) \frac{\partial^2 T}{\partial x^2} - [C\alpha\Delta x - u(\Delta x^2/6)(1 + 2C^2)] \frac{\partial^3 T}{\partial x^3}$$

Estabilidad: Factor amplificación: $G = 1 - 2s(1 - \cos\theta) - iC \sin\theta$

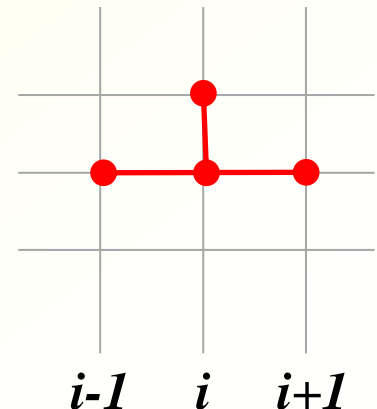
Condición Estabilidad: $0 \leq C^2 \leq 2s \leq 1$

$$|G| \leq 1 \quad \forall \theta$$

$n+1$

n




$n-1$



M3: Ecuación de Transporte.

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} - \alpha \frac{\partial^2 T}{\partial x^2} = 0$$

Table 9.3. Algebraic (discretised) schemes for the transport equation $\partial \bar{T} / \partial t + u \partial \bar{T} / \partial x - \alpha \partial^2 \bar{T} / \partial x^2 = 0$

Scheme	Algebraic form	Truncation error ^a (E) (leading terms)	Amplification factor <i>G</i> ($\theta = m\pi\Delta x$)	Stability Restrictions	Remarks
FTCS 	$\frac{\Delta T_j^{n+1}}{\Delta t} + u L_x T_j^n - \alpha L_{xx} T_j^n = 0$	$Cu(\Delta x/2) \frac{\partial^2 T}{\partial x^2}$ $- [C\alpha\Delta x - u(\Delta x^2/6)(1 + 2C^2)] \frac{\partial^3 T}{\partial x^3}$	$1 - 2s(1 - \cos\theta) - iC\sin\theta$	$0 \leq C^2 \leq 2s \leq 1$	$R_{\text{cell}} \ll 2/C$ for accuracy
Upwind 	$\frac{\Delta T_j^{n+1}}{\Delta t} + u \frac{(T_j^n - T_{j-1}^n)}{\Delta x} - \alpha L_{xx} T_j^n = 0$	$-u(\Delta x/2)(1 - C) \frac{\partial^2 T}{\partial x^2} - [C\alpha\Delta x$ $- u(\Delta x^2/6)(1 - 3C + 2C^2)] \frac{\partial^3 T}{\partial x^3}$	$1 - (2s + C)(1 - \cos\theta) - iC\sin\theta$	$C + 2s \leq 1$	$R_{\text{cell}} \ll 2/(1 - C)$ for accuracy
DuFort-Frankel 	$(T_j^{n+1} - T_j^{n-1})/2\Delta t + u L_x T_j^n$ $-\frac{\alpha}{\Delta x^2} \{T_{j-1}^n - (T_j^{n-1} + T_j^{n+1})$ $+ T_{j+1}^n\} = 0$	$\alpha C^2 \frac{\partial^2 T}{\partial x^2} + (1 - C^2)[u\Delta x^2/6$ $- 2\alpha^2 C^2/u] \frac{\partial^3 T}{\partial x^3}$	$\frac{B \pm [B^2 - 8s(1 + 2s)]^{\frac{1}{2}}}{(2 + 4s)}$ where $B = 1 + 4s\cos\theta - i2C\sin\theta$	$C \leq 1$	$C^2 \ll 1$ for accuracy

M3: Ecuación de Transporte.

Esquema completamente implícito

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} - \alpha \frac{\partial^2 T}{\partial x^2} = 0$$

$$\frac{\partial T}{\partial t} = \frac{T_i^{n+1} - T_i^n}{\Delta t}$$

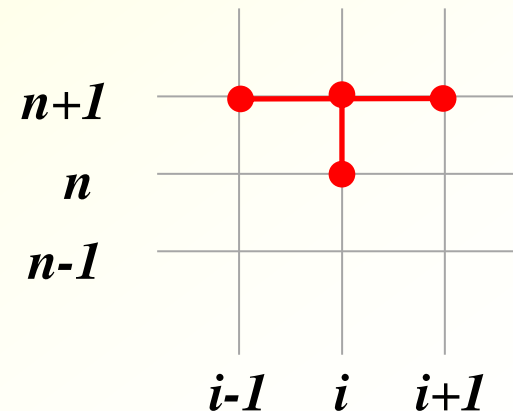
$$\frac{\partial T}{\partial x} = \frac{T_{i+1}^{n+1} - T_{i-1}^{n+1}}{2\Delta x} \Rightarrow \frac{T_i^{n+1} - T_i^n}{\Delta t} + u \frac{T_{i+1}^{n+1} - T_{i-1}^{n+1}}{2\Delta x} - \alpha \frac{T_{i-1}^{n+1} - 2T_i^{n+1} + T_{i+1}^{n+1}}{\Delta x^2} = 0$$

$$\frac{\partial^2 T}{\partial x^2} = \frac{T_{i-1}^{n+1} - 2T_i^{n+1} + T_{i+1}^{n+1}}{\Delta x^2}$$

$i = 1 \dots N - 1$
+ 2 cond. frontera





Consistencia: $E_i^n \propto \frac{\partial^3 T}{\partial T^3}$

Estabilidad: incondicionalmente estable



M3: Ecuación de Transporte.

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} - \alpha \frac{\partial^2 T}{\partial x^2} = 0$$

<p>Lax-Wendroff</p> 	$\frac{\Delta T_j^{n+1}}{\Delta t} + u L_x T_j^n - \alpha^* L_{xx} T_j^n = 0$ <p>where $\alpha^* = \alpha + 0.5u C \Delta x$</p>	$- [C \alpha \Delta x - u(\Delta x^2/6)(1 - C^2)] \frac{\partial^3 T}{\partial x^3}$ $+ [C \alpha^2 u(\Delta x/2) - \alpha \Delta x^2/12 - u C(\Delta x^3/8)(C^2 - 1)] \frac{\partial^4 T}{\partial x^4}$	$1 - 2s^*(1 - \cos \theta) - i C \sin \theta$ <p>where $s^* = \alpha^* \Delta t / \Delta x^2$</p>	$0 \leq C^2 \leq 2s^* \leq 1$	$R_{\text{cell}} \leq 2$ to avoid spatial oscillations
<p>Crank-Nicolson</p> 	$\frac{\Delta T_j^{n+1}}{\Delta t} + \{u L_x - \alpha L_{xx}\} \left\{ \frac{T_j^n + T_j^{n+1}}{2} \right\} = 0$	$u(\Delta x^2/6)(1 + 0.5C^2) \frac{\partial^3 T}{\partial x^3}$ $- \alpha(\Delta x^2/12)(1 + 3C^2) \frac{\partial^4 T}{\partial x^4}$	$\frac{1 - s(1 - \cos \theta) - i 0.5C \sin \theta}{1 + s(1 - \cos \theta) + i 0.5C \sin \theta}$	None	$R_{\text{cell}} \leq 2$ to avoid spatial oscillations
<p>Three-level fully implicit</p> 	$\frac{3 \Delta T_j^{n+1}}{2 \Delta t} - \frac{1 \Delta T_j^n}{2 \Delta t} + \{u L_x - \alpha L_{xx}\} T_j^{n+1} = 0$	$u(\Delta x^2/6)(1 + 2C^2) \frac{\partial^3 T}{\partial x^3}$ $- \alpha(\Delta x^2/12)(1 + 12C^2) \frac{\partial^4 T}{\partial x^4}$	$\frac{1 \pm \frac{1}{3} i [3 + 16s(1 - \cos \theta) + i 8C \sin \theta]^{\frac{1}{2}}}{2(1 + \frac{2}{3} [2s(1 - \cos \theta) + i C \sin \theta])}$	None	$R_{\text{cell}} \leq 2$ to avoid spatial oscillations
<p>Linear F.E.M./ Crank-Nicolson</p> 	$M_x \frac{\Delta T_j^{n+1}}{\Delta t} + u L_x \left\{ \frac{T_j^n + T_j^{n+1}}{2} \right\} - \alpha L_{xx} \left\{ \frac{T_j^n + T_j^{n+1}}{2} \right\} = 0$	$u C^2 (\Delta x^2/12) \frac{\partial^3 T}{\partial x^3}$ $+ \alpha (\Delta x^2/12)(1 - 3C^2) \frac{\partial^4 T}{\partial x^4}$	$\frac{2 + 3 \cos \theta - 3s(1 - \cos \theta) - i 1.5C \sin \theta}{2 + 3 \cos \theta + 3s(1 - \cos \theta) + i 1.5C \sin \theta}$	None	$R_{\text{cell}} \leq 2$ to avoid spatial oscillations

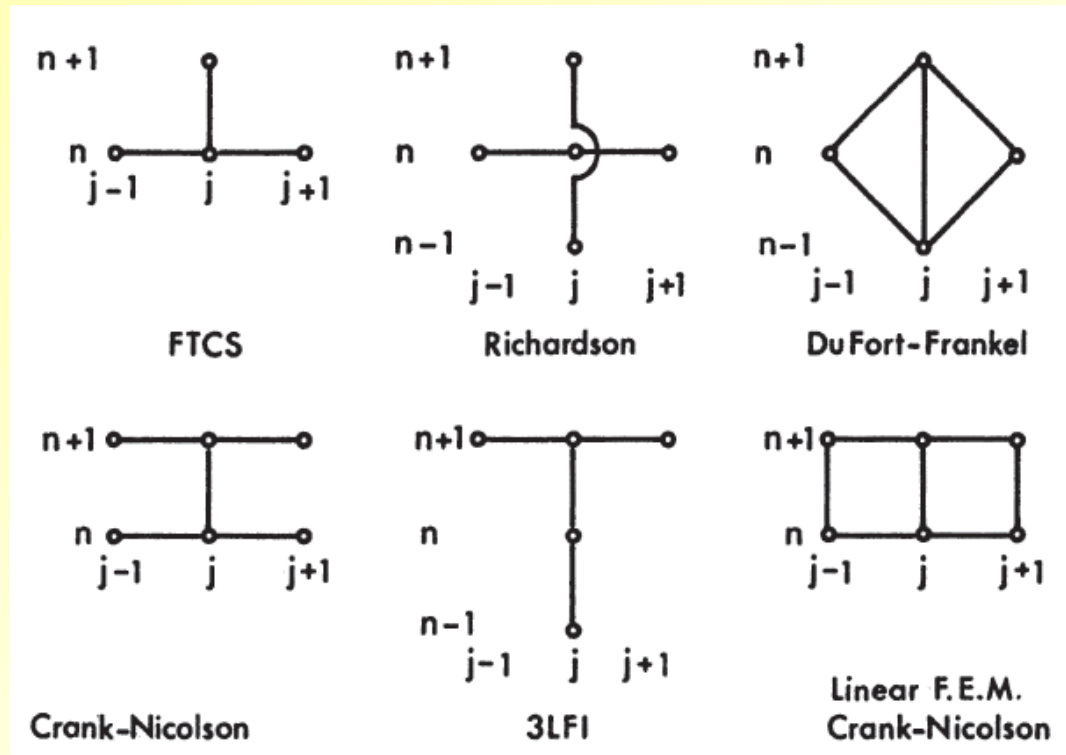
* The algebraic scheme is equivalent to $\partial T / \partial t + u \partial T / \partial x - \alpha \partial^2 T / \partial x^2 + E(T) = 0$

$$L_x = \frac{1}{2\Delta x} \{-1, 0, 1\}, L_{xx} = \frac{1}{\Delta x^2} \{1, -2, 1\}, M_x = \{\frac{1}{6}, \frac{2}{3}, \frac{1}{6}\}, C = u \Delta t / \Delta x, s = \alpha \Delta t / \Delta x^2, R_{\text{cell}} = C/s = u \Delta x / \alpha$$

M3: Ecuación de Transporte.

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} - \alpha \frac{\partial^2 T}{\partial x^2} = 0$$

Esquemas de nodos activos para los principales esquemas de integración considerados:



Ecuación Unidimensional de Transporte

Implementar los siguientes algoritmos en un programa que resuelva la ecuación unidimensional de transporte:

Métodos Explícitos:

6*.- Esquema Forward in Time Centered in Space (FTCS).

7*.- Esquema upstream.

8*.- Esquema DuFort-Frankel.

Métodos Implícitos:

9.- Esquema totalmente implícito a dos niveles.

10.- Esquema Crank-Nicolson.

11*.- Calcular la estabilidad y la consistencia de uno de los métodos anteriores.