

Name:

1. (4 points) Give the characteristic polynomial of

$$A = \begin{pmatrix} 4 & -3 \\ 2 & 5 \end{pmatrix}$$

2. (5 points) Find the determinant of the matrix

$$D = \begin{pmatrix} 0 & 5 & 6 & 0 \\ 1 & 0 & 0 & 4 \\ 0 & 15 & 26 & 9 \\ -2 & 0 & 0 & 2 \end{pmatrix}$$

3. (3 points) The matrix

$$B = \begin{pmatrix} -12 & -15 \\ 6 & 7 \end{pmatrix}$$

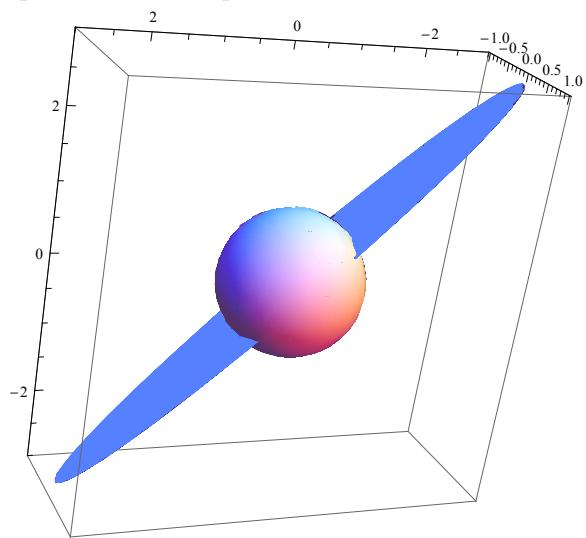
has eigenvector $v = \begin{pmatrix} -5 \\ 3 \end{pmatrix}$. Determine the associated eigenvalue.

4. (5 points) The matrix

$$C = \begin{pmatrix} 9 & 8 & 0 \\ -10 & -9 & 0 \\ 20 & 20 & 1 \end{pmatrix}$$

has eigenvalue 1. Give a basis of the eigenspace $\mathcal{E}_C(1)$.

5. (5 points) A 3×3 real matrix G is applied to all the points on the unit sphere in \mathbb{R}^3 . The image of the sphere is a flat elliptical disc:



- (a) Describe everything you know about the eigenvalues of G .
- (b) Describe the limit of the sphere under repeated transformations by G .

6. (5 points) Prove that if $\lambda \neq \gamma$ are two distinct eigenvalues of a matrix F , then the intersection of the eigenspaces is trivial, i.e. $\mathcal{E}_F(\lambda) \cap \mathcal{E}_F(\gamma) = \{\vec{0}\}$

7. (5 points) Prove that if matrix H is similar to matrix K then $\det(H) = \det(K)$.

8. (5 points) The matrix $L = \begin{pmatrix} \frac{-1+i}{2} & \frac{-1-i}{2} \\ \frac{-1-i}{2} & \frac{-1+i}{2} \end{pmatrix}$ has eigenvalues $\lambda_1 = i$ and $\lambda_2 = -1$ for eigenvectors $v_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and $v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$. Compute L^6 .

Bonus. (5 points) Suppose M is a diagonalizable matrix such that there exists a positive integer n with $M^n = M$. Show that all the eigenvalues of M are either 0 or of the form $\lambda_i = e^{2\pi i k_i / (n-1)}$ for integers k_i .

Name:

1. (6 points) Suppose U is a vector space with operations of vector addition and scalar multiplication denoted by \oplus and \otimes , respectively. Suppose V is a vector space V with operations of vector addition and scalar multiplication denoted by \vee and \star , respectively. Define what it means to say T is a linear transformation from U to V .

2. (3 points) Define: A linear transformation $T : U \rightarrow V$ is 1-to-1 (also known as injective):

3. (3 points) Define: A linear transformation $T : U \rightarrow V$ is onto (also known as surjective):

4. (15 points) Suppose $T : \mathbb{C}^4 \rightarrow \mathbb{C}^3$ is given by

$$T \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} a - b + 3c - 2d \\ 2b + 4c - 6d \\ a + b + 8c - 8d \end{pmatrix}$$

- (a) Which do you know immediately: T is not 1-to-1 T is not onto.
Why do you know this?

- (b) Give the matrix representation of T using the standard basis for both \mathbb{C}^4 and \mathbb{C}^3 .

- (c) In part (a) you gave a reason why T is not one of those things. Explain how we know/prove that T is the other one.

- (d) Give a basis for $\ker(T)$.

5. (4 points) Give an example, in pictures/cartoons of blobs and arrows, of two functions $f : U \rightarrow V$ and $g : V \rightarrow W$ such that f is 1-to-1 and g is onto, but $g \circ f$ is neither.

6. (4 points) Give an example, in pictures/cartoons of blobs and arrows, of two functions $f : U \rightarrow V$ and $g : V \rightarrow W$ such that f is onto and g is 1-to-1, but $g \circ f$ is neither.

7. (4 points) The linear transformation $T : P_1 \rightarrow \mathbb{C}^2$ given by

$$T(ax + b) = \begin{pmatrix} 3a + 7b \\ 2a + 5b \end{pmatrix}$$

is a bijection. Give $T^{-1} \left(\begin{pmatrix} r \\ s \end{pmatrix} \right)$.

8. (5 points) Suppose $S : U \rightarrow V$ is a linear transformation and that

$$S(3u_1 - 4u_3) = v_1, S(u_1 + u_3) = v_2, S(u_2) = v_3 \text{ and } S(u_2 + u_3) = v_4.$$

Show that the set $\{v_1, v_2, v_3, v_4\}$ is linearly dependent by exhibiting a linear combination that gives the zero vector. Make sure to justify your answer completely.

9. (6 points) The linear transformation $R : P_2 \rightarrow \mathbb{C}^4$ has the properties:

$$R(5) = \begin{pmatrix} 10 \\ 5 \\ -5 \\ 15 \end{pmatrix}, R(x+1) = \begin{pmatrix} 3 \\ 1 \\ 4 \\ 1 \end{pmatrix} \text{ and } R(x^2+x+1) = \begin{pmatrix} -1 \\ 1 \\ -1 \\ 2 \end{pmatrix}.$$

Give the general formula for $R(ax^2 + bx + c)$.

Bonus. Let U be a vector space. Recall that

$$\mathcal{L}(U) = \{\text{All linear transformations } T : U \rightarrow U\}$$

is also a vector space (with operations of $(T_1 + T_2)(u) = T_1(u) + T_2(u)$ and $(\alpha T)(u) = \alpha T(u)$).

Now suppose $S : U \xrightarrow{\cong} V$ is a bijective linear transformation, i.e. $U \cong V$. Show that $\mathcal{L}(U) \cong \mathcal{L}(V)$.

Steps: For $T \in \mathcal{L}(U)$ define $\phi_S(T) \in \mathcal{L}(V)$ by $(\phi_S(T))(v) = S(T(S^{-1}(v)))$

(a) (4 points) Show that ϕ_S satisfies the properties of a linear transformation.

(b) (4 points) Show that ϕ_S is 1-to-1. Do this by supposing for all $v \in V$ that $(\phi_S(T_1))(v) = (\phi_S(T_2))(v)$ and then showing $T_1(u) = T_2(u)$ for all $u \in U$.

(c) (4 points) Show that ϕ_S is onto. Do this by supposing $R \in \mathcal{L}(V)$ and finding $T \in \mathcal{L}(U)$ such that $\phi_S(T) = R$.

Name:

1. (15 points) Give as good of a definition as you can for each bolded term:

(a) The linear system, **LS**(**A**, **b**), associated to the matrix *A* and vector of constants *b*.

(b) The **Solution Set** of a system of equations.

(c) The **null space** of a matrix *A*.

(d) A **nonsingular** matrix *A*.

(e) **Equivalent** linear systems of equations.

2. (28 points) Label the following statements as ‘True’ or ‘False’ (1 point each). Explain why (3 points each). (Note: An example where it is true is not enough to justify a ‘True’ answer.)

- (a) If two linear systems have the same solution set then the two associated augmented matrices are row-equivalent.
 - (b) If $r > n$ then the system is inconsistent.
 - (c) It's possible for a matrix to have $D = \{1, 3, 4, 7\}$ and $F = \{2, 5\}$.
 - (d) The identity matrix is consistent.

- (e) If the augmented matrix $[A|b]$ row-reduces to the identity, then there is a unique solution to the associated system of equations.
- (f) It's possible for the zero vector to be a solution to an inhomogeneous system of equations.
- (g) If A reduces to the identity matrix, then the null space of A contains only the zero vector.
3. (3 points) Suppose you have a linear system $LS(A, b)$ of 5 equations with 4 complex variables. You put the augmented matrix, $[A|b]$, into SAGE and have return the row-reduced echelon form. The output from SAGE is

$$\left[\begin{array}{cccc|c} 1 & 0 & 2 & 0 & 1 \\ 0 & 1 & 3 + I & 0 & 2 \\ 0 & 0 & 0 & 1 & 4 * I \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Give the solution set using proper written/human notation.

4. (4 points) Suppose you know a system of equations has 5 equations in 9 variables. Say **as much as possible** about what you know about the system (especially regarding the solution set and any definitions/terms that apply).

5. (4 points) Put the following matrix in row-reduced echelon form. Make sure to annotate your intermediate steps and box your final answer.

$$\begin{pmatrix} 7 & 3 & 1 \\ 2 & 8 & 2 \\ 0 & 5 & 0 \end{pmatrix}$$

6. (4 points) Prove/explain why: if A is row-equivalent to B and B is row equivalent to C , then we know A is row-equivalent to C .

7. (4 points) Suppose that A is a nonsingular matrix and A is row-equivalent to the matrix B . Prove/explain why: B must be nonsingular.

Bonus 1. (5 points)

(a) Solve $2x + 3 = 4 \pmod{7}$.

(b) Explain why $2x + 3 = 4 \pmod{6}$ doesn't have a solution.

Bonus 2. (5 points) Suppose that the coefficient matrix of a consistent system of linear equations has two columns that are identical. Prove that the system has infinitely many solutions.