

20171104: Pset 04, Mathematical Foundations- 01

We are given:  $P(B_1) = 0.6$      $P(B_2) = 0.4$

Conditional probabilities:  $P(M|B_1) = \frac{2}{3}$      $P(A|B_1) = \frac{1}{3}$

$P(M|B_2) = \frac{1}{3}$      $P(A|B_2) = \frac{2}{3}$

We want to find  $P(B_2|M)$

Using Bayes Theorem,

$$P(B_2|M) = \frac{P(M|B_2) \times P(B_2)}{P(M|B_2) \times P(B_2) + P(M|B_1) \times P(B_1)}$$

$$= \frac{\frac{1}{3} \times 0.4}{\frac{1}{3} \times 0.4 + \frac{2}{3} \times 0.6}$$

$$= \frac{0.4}{0.4 + 1.2}$$

$$= \frac{1}{4}$$

Probability that mango was picked from bag 2 =  $\frac{1}{4} = 0.25$

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Pset 04, Mathematical Foundations-02

$$B = P^{-1}AP \Rightarrow A = PB^{-1}P$$

If  $Ax = \lambda x$  where  $\lambda$  is eigenvalue &  $x$  is eigenvector of  $A$ ,

$$P^*BP^{-1}x = \lambda x$$

$$BP^{-1}x = P^{-1}(\lambda x) \Rightarrow B(P^{-1}x) = \lambda(P^{-1}x)$$

Let  $P^{-1}x = v$

$$\therefore Bv = \lambda v$$

$\Rightarrow v$  is eigenvector of  $B$  &  $\lambda$  is eigenvalue.

$\therefore$  Every eigenvalue of  $A$  is an eigenvalue of  $B$  and vice-versa

$\Rightarrow$  Proved that  $A$  and  $B$  have same eigenvalues

If  $x$  is eigenvector of  $A$ , then eigenvector of  $B = P^{-1}x$

$\Rightarrow$  Similar matrices have same eigenvalues but do not have same eigenvectors.

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## Psct 4 - Mathematical Foundations - 3

1)  $\mu_1 = [0.5, 0.6, 0.2]^T \quad \mu_2 = [0.3, 0.2, 0.5]^T$

$$\Sigma = \begin{bmatrix} 0.6 & 0 & 0 \\ 0 & 0.4 & 0 \\ 0 & 0 & 0.5 \end{bmatrix}$$

2)  $\mu_1 = [0.2, 0.9, 0.4]^T \quad \mu_2 = [0.5, 0.1, 0.7]^T$

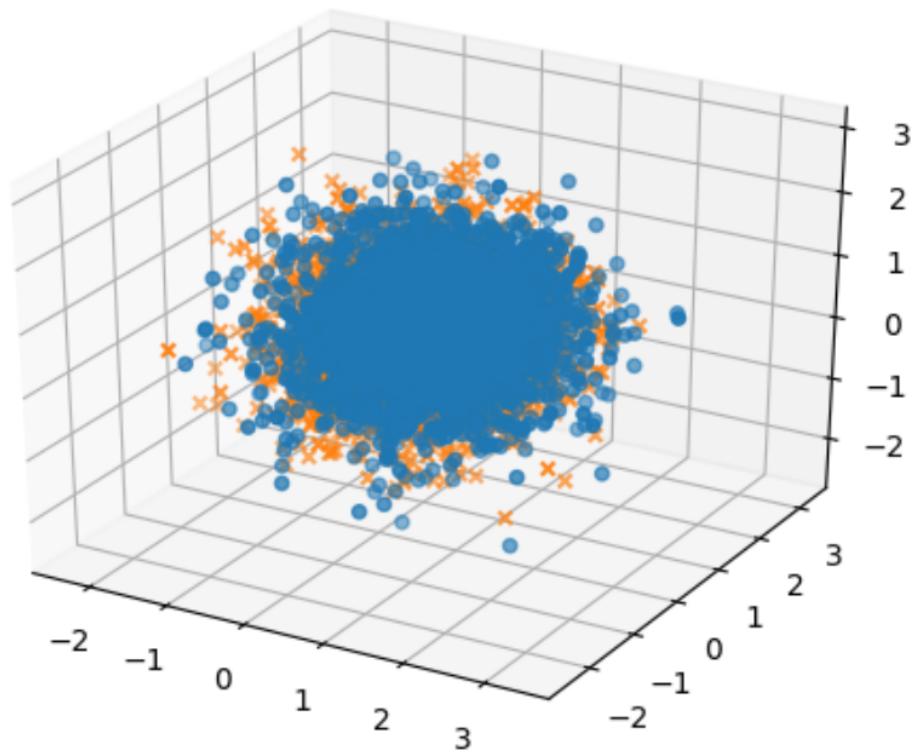
$$\Sigma = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

3)  $\mu_1 = \mu_2 = [0.7, 0.6, 0.3]^T$

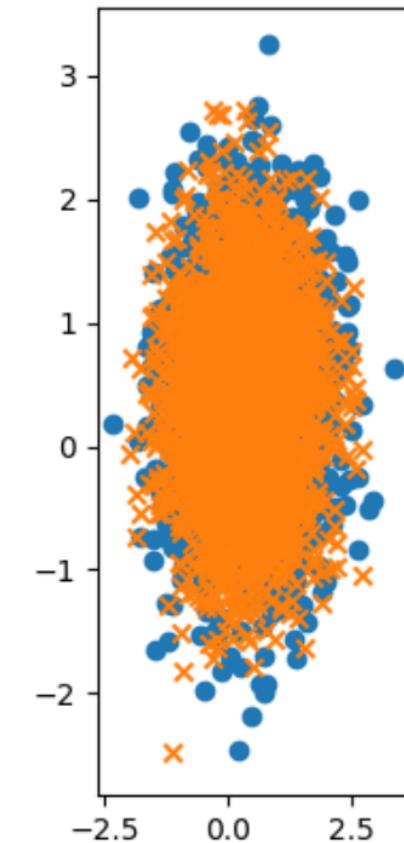
$$\Sigma_1 = \begin{bmatrix} 0.6 & 0 & 0 \\ 0 & 0.4 & 0 \\ 0 & 0 & 0.5 \end{bmatrix}$$

$$\Sigma_2 = \begin{bmatrix} 0.3 & 0 & 0 \\ 0 & 0.1 & 0 \\ 0 & 0 & 0.8 \end{bmatrix}$$

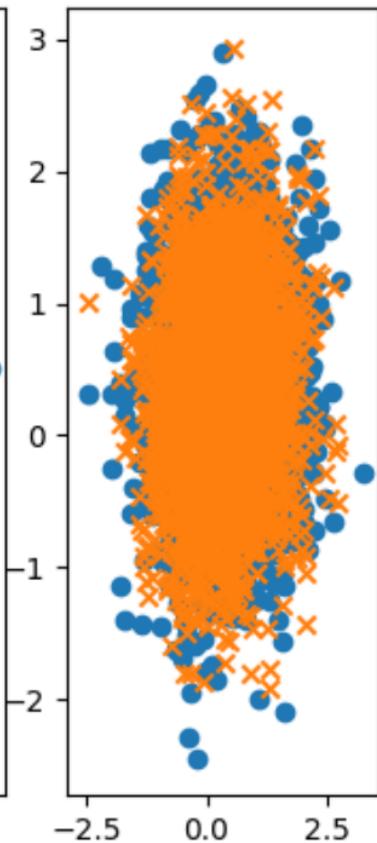
Data Plot



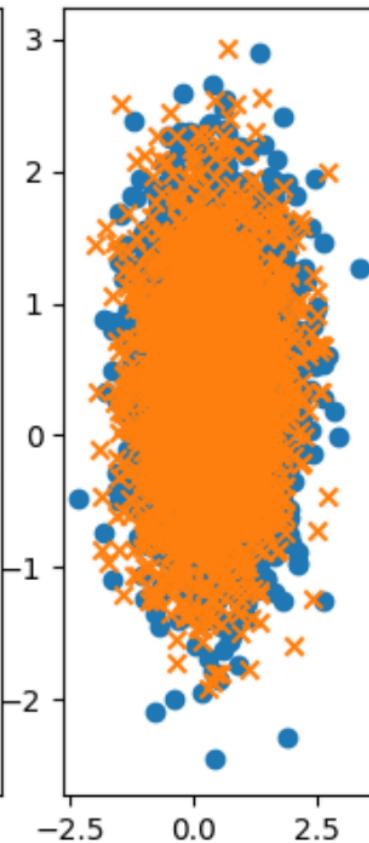
x-y plane



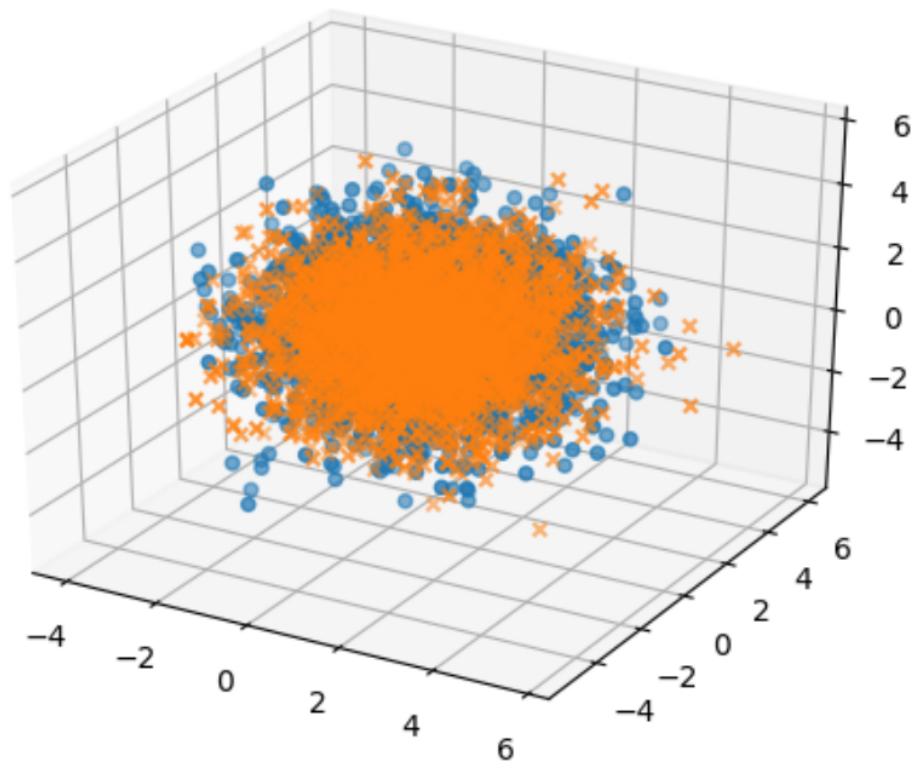
y-z plane



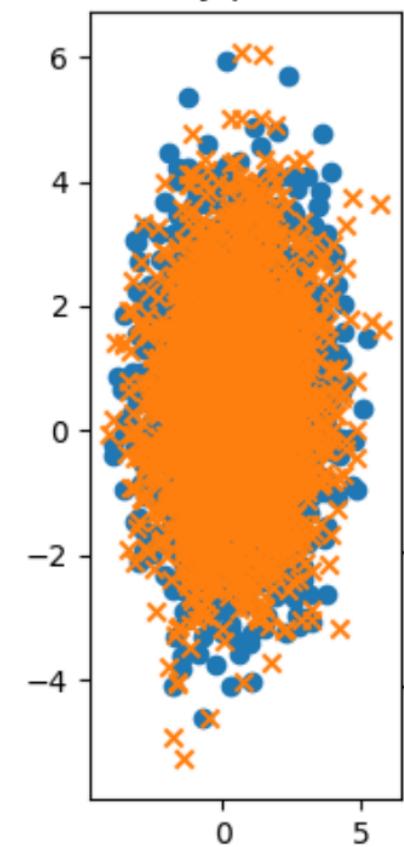
x-z plane



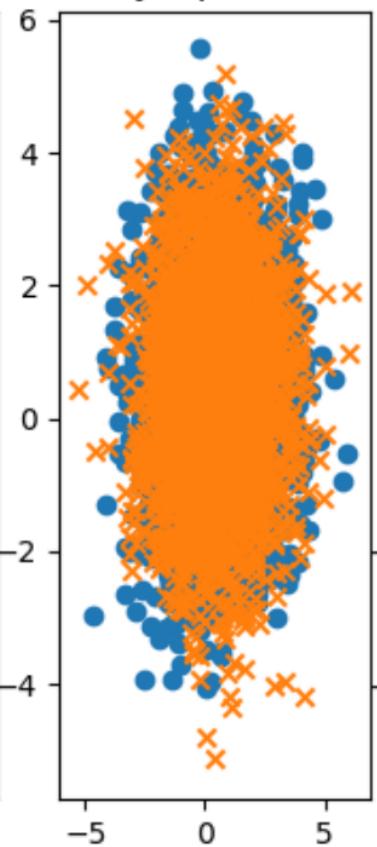
Data Plot



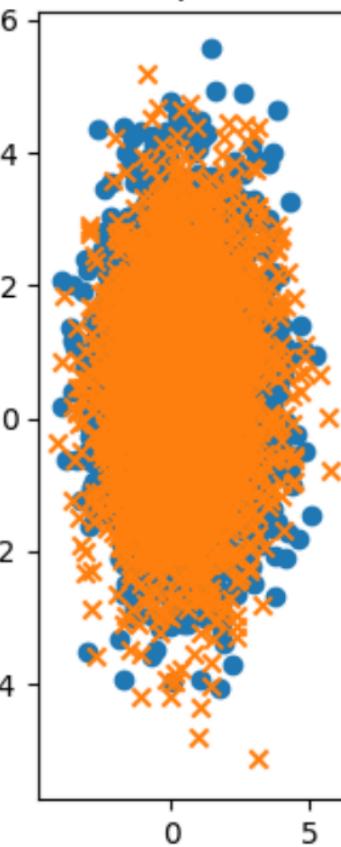
x-y plane



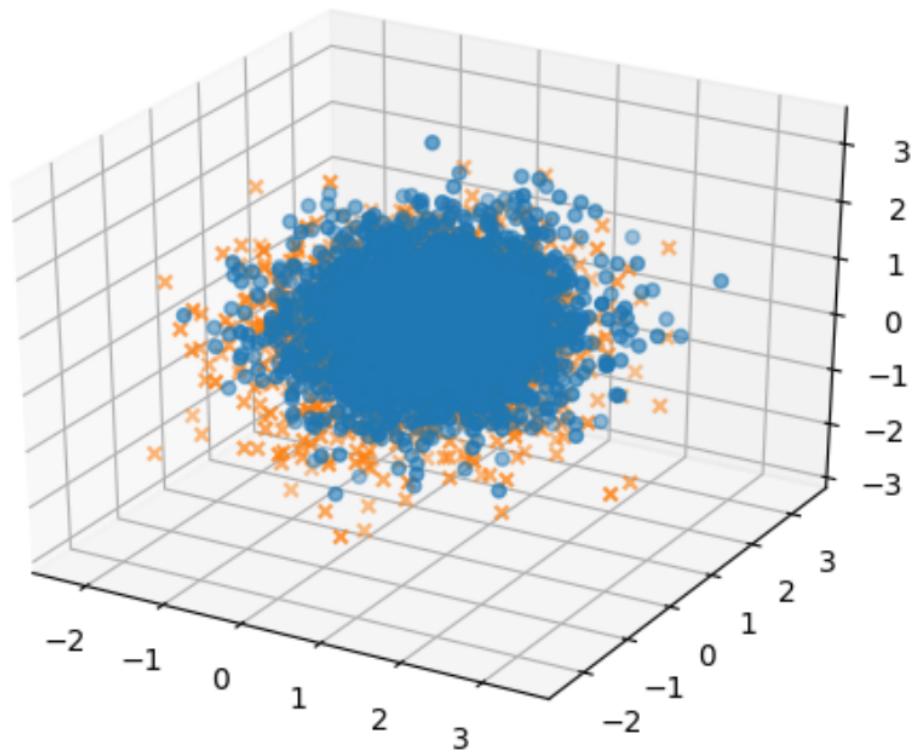
y-z plane



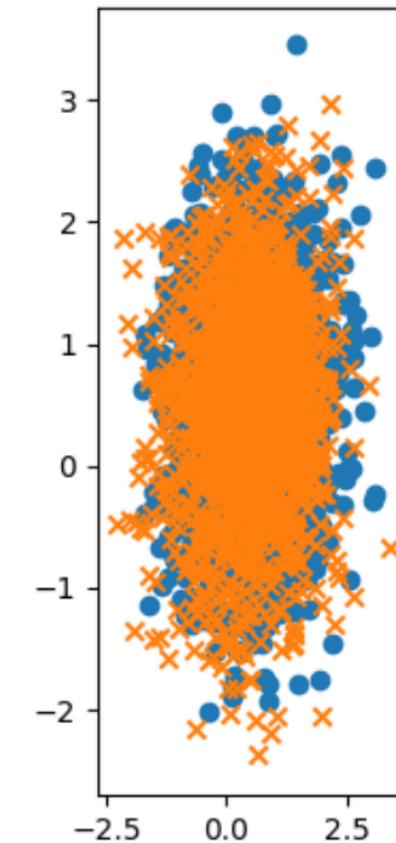
x-z plane



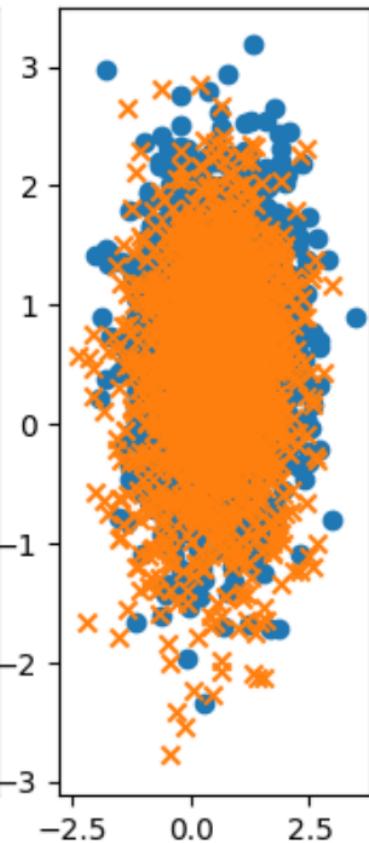
Data Plot



x-y plane



y-z plane



x-z plane

