

Bilkent University Department of Computer Engineering CS342 Operating Systems

Introduction - 2 Operating System Structures

Last Update: Sep 20, 2022

Outline

Outline

- Operating System Services
- User Operating System Interface
- System Calls
- System Programs
- Operating System Structure

Objectives

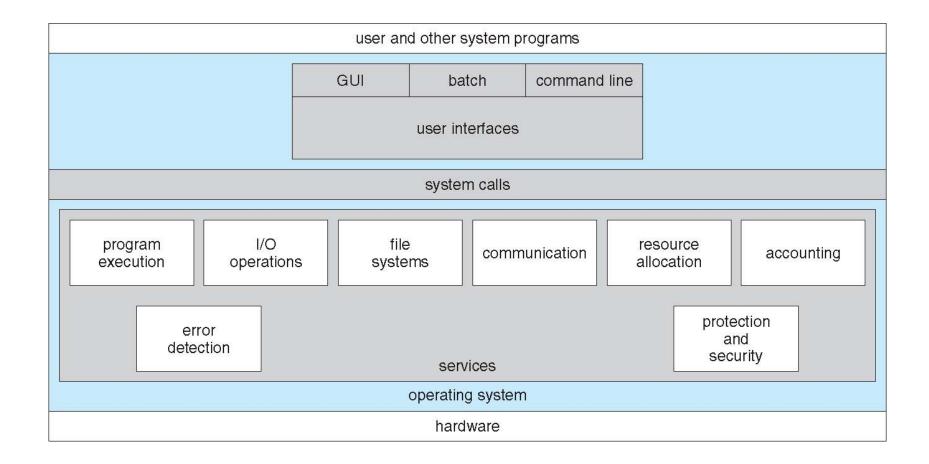
- To describe the services an operating system provides to users, processes, and other systems
- To discuss the various ways of structuring an operating system

Operating System Services

- For user
 - User interface
 - Program execution
 - I/O operations
 - File-system manipulation
 - Process communication
 - Error detection and handling

- For System: efficiency and sharing
 - Resource allocation
 - Accounting
 - Protection and security

OS Services

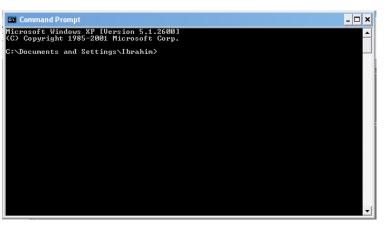


[User - Operating System] Interface - CLI

CLI: Command Line Interface (CLI) or

command interpreter (shell)

- fetches a command from user and executes it
- Interpreter is in kernel or is a system program,
- many flavors
 - Some commands may be built-in to the shell,
 - Come commands may be another program
- GUI: User-friendly desktop interface
 - lcons represent files, programs, actions, etc.

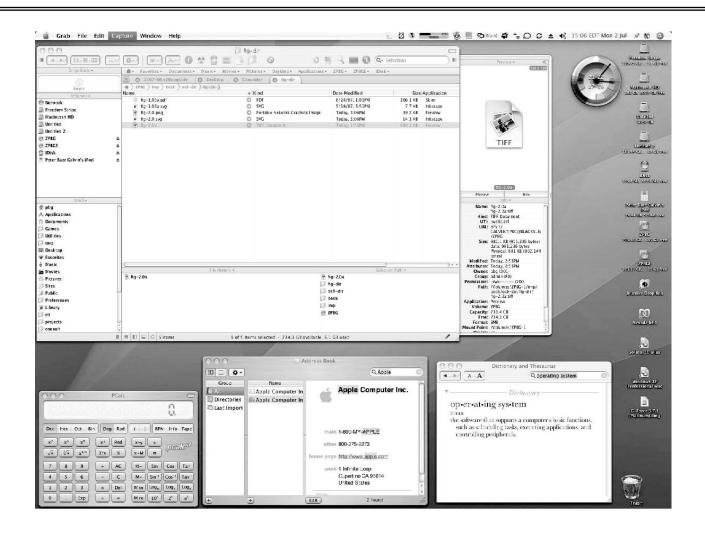


Many operating systems now include both CLI and GUI interfaces Linux: command shells available (CLI); KDE as GUI

Bourne Shell Command Interpreter

```
Terminal
                                                                         File Edit View Terminal Tabs Help
                                               0.0
fd0
          0.0
                0.0
                       0.0
                              0.0
                                   0.0
                                        0.0
sd0
          0.0
                0.2
                       0.0
                              0.2 0.0
                                        0.0
                                               0.4
                              0.0 0.0 0.0
                                               0.0
          0.0
                0.0
sd1
                       0.0
                 extended device statistics
device
          r/s
                W/S
                      kr/s
                            kw/s wait actv svc_t
fd0
                       0.0
          0.0
                0.0
                              0.0 0.0 0.0
                                               0.0
sd0
          0.6
                0.0
                       38.4
                              0.0 0.0 0.0
                                               8.2
                              0.0 0.0 0.0
sd1
          0.0
                0.0
                       0.0
                                               0.0
(root@pbg-nv64-vm)-(11/pts)-(00:53 15-Jun-2007)-(global)
-(/var/tmp/system-contents/scripts)# swap -sh
total: 1.1G allocated + 190M reserved = 1.3G used, 1.6G available
(root@pbq-nv64-vm)-(12/pts)-(00:53 15-Jun-2007)-(global)
-(/var/tmp/system-contents/scripts)# uptime
12:53am up 9 min(s), 3 users, load average: 33.29, 67.68, 36.81
(root@pbg-nv64-vm)-(13/pts)-(00:53 15-Jun-2007)-(global)
-(/var/tmp/system-contents/scripts)# w
  4:07pm up 17 day(s), 15:24, 3 users, load average: 0.09, 0.11, 8.66
                      login@ idle
                                    JCPU
                                            PCPU what
User
         tty
                                                  /usr/bin/ssh-agent -- /usr/bi
                     15Jun0718days
root
         console
                                        1
n/d
         pts/3
                      15Jun07
                                       18
root
                     15Jun0718days
root
         pts/4
(root@pbg-nv64-vm)-(14/pts)-(16:07 02-Jul-2007)-(global)
-(/var/tmp/system-contents/scripts)#
```

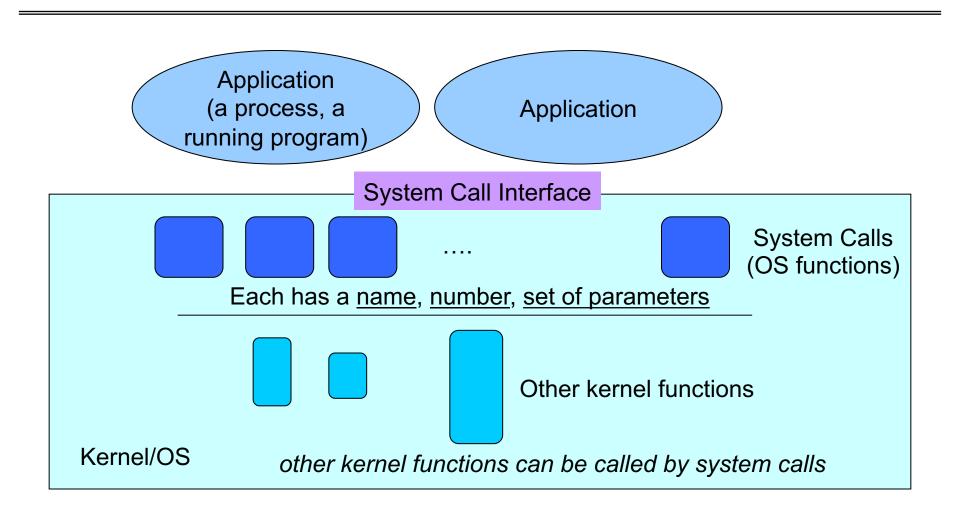
The MacOS X GUI



System Calls

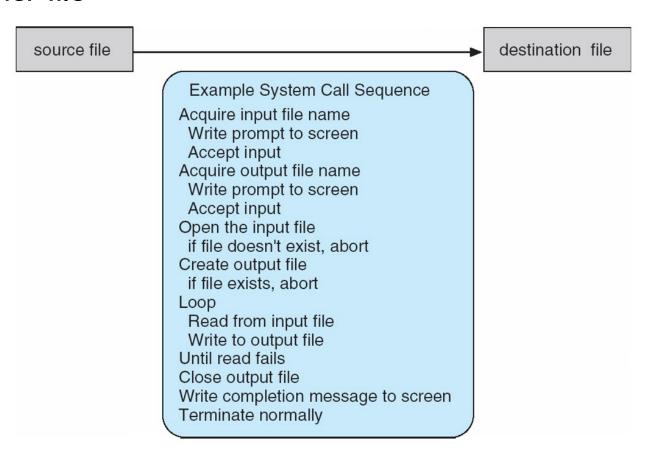
- Programming interface to the services provided by the OS
 - i.e., interface provided to applications (to commands and programs
- Typically written in a high-level language (C or C++)
- Are called by a running program to get service from kernel
 - We say "making a system call" or "calling a system call"
- Even a simple program may make a lot of system calls per second.

System Calls



Example of System Calls

 System call sequence to copy the contents of one file to another file



Example copy program

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include<sys/types.h>
#include<sys/stat.h>
#include <fcntl.h>

#define INSIZE 10

char infilename[128];
char outfilename[128];
char buf[1024];

int fd1;
int fd2;
```

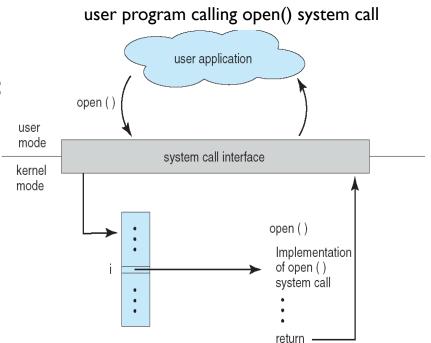
```
int main()
{
   printf ("enter input filename\n");
    scanf ("%s", infilename);
   printf ("enter output filename\n");
    scanf ("%s", outfilename);
   printf ("%s %s\n", infilename, outfilename);
    fd1 = open (infilename, O RDONLY);
    if (fd1 < 0) {
        printf ("error in opening");
        exit (1);
    fd2 = open (outfilename, O WRONLY | O CREAT, 0600);
    int n, m;
   while (1) {
        n = read (fd1, buf, INSIZE);
        if (n > 1) {
            m = write (fd2, buf, n);
            if (m < 0)
                printf ("write failed\n");
        } else
            break;
    }
   close (fd1);
    close (fd2);
    printf ("finished copying\n");
}
```

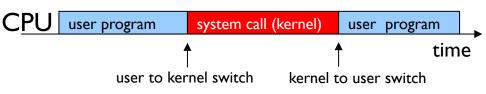
strace output

```
read(0, Makefile
"Makefile\n", 1024)
                         = 9
write(1, "enter output file\n", 18enter output file
read(0, out
"out\n", 1024)
write(1, "Makefile out\n", 13Makefile out
          = 13
openat(AT FDCWD, "Makefile", O RDONLY) = 3
openat(AT FDCWD, "out", O WRONLY O CREAT, 0600) = 4
read(3, "\n\nall: myc", 10)
                                       = 10
write(4, "\n\nall: myc", 10)
                                       = 10
read(3, "opy\n\nmycop", 10)
                                       = 10
write(4, "opy\n\nmycop", 10)
                                       = 10
read(3, "y:\tmycopy.", 10)
                                       = 10
write(4, "y:\tmycopy.", 10)
                                       = 10
read(3, "c\n\tgcc -Wa", 10)
                                      = 10
write(4, "c\n\tqcc -Wa", 10)
                                       = 10
read(3, "ll -o myco", 10)
                                       = 10
write(4, "ll -o myco", 10)
                                       = 10
read(3, "py mycopy.", 10)
                                       = 10
write(4, "py mycopy.", 10)
                              = 10
read(3, "c\n\n\nclean:", 10)
                             = 10
write(4, "c\n\n\nclean:", 10)
                                       = 10
```

System Call Implementation and Calling

- Typically,
 - a number associated with each system call
 - Number is used as index to a table:
 System Call Table
 - Table keeps addresses of system calls (system routines)
- When called, system call:
 - runs
 - may block (e.g., read system call)
 - returns
- Caller does not know system call implementation
 - Just knows the interface



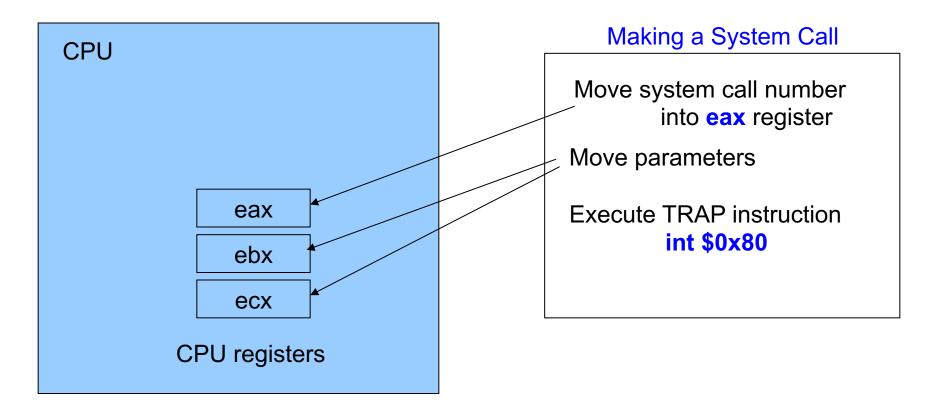


Some Linux x86-64 system calls (64 bit)

```
0 read // read from a file
                                          33 pause
I write // write into a file
                                          37 alarm // set an alarm
2 open // open a file
                                          39 getpid // get process id
3 close // close a file
                                          57 fork // create a new process
4 stat // get file attributes
                                          59 execve // run a new program
9 mmap // map a file
                                          60 exit // terminate the program
12 brk // extend heap segment
                                          61 wait4 // wait for child
32 dup2 // dup file desc
                                          62 kill // send signal
```

Around 400 system calls in total in Linux Kernel.

Invoking a system: Linux and x86 32 bit architecture



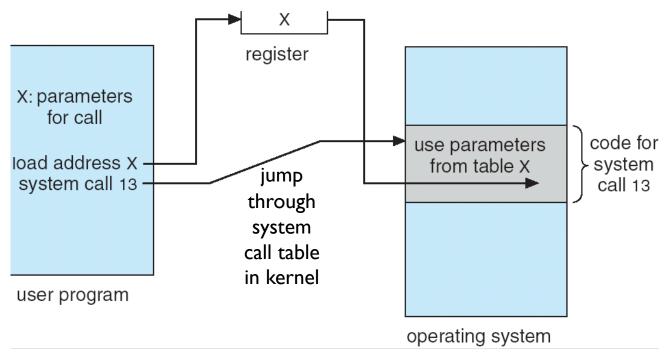
syscall or int instruction is used to make system call

System Call Parameter Passing

- Often, more information is required than the identity (number) of the desired system call
 - Exact type and amount of information vary according to OS and call
- Three general methods used to pass parameters to the system call
 - I) Simplest: pass the parameters in registers
 - In some cases, may be more parameters than registers
 - 2) Parameters stored in a block, or table, in memory, and address of the block passed as a parameter in a register
 - 3) Parameters placed, or pushed, onto the stack by the program and popped off the stack by the operating system

Last two methods do not limit the number or length of parameters being passed

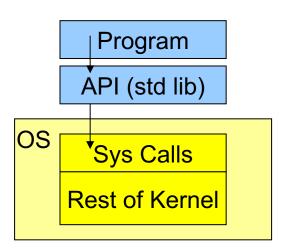
Parameter Passing via Table



kernel can access user memory

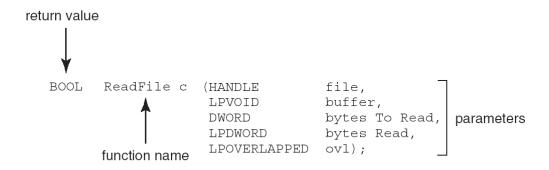
Accessing and executing System Calls

- System calls typically not accessed directly by programs
- Mostly accessed by programs via a high-level Application Program Interface (API) (i.e., a library) rather than direct system call use
- Three most common APIs are:
 - Win32 API for Windows 32 bit system,
 - POSIX API for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X),
 - Java API for the Java virtual machine (JVM)



Example of Standard API - Windows

 Consider the ReadFile() function in the Win32 API — a function for reading from a file



- A description of the parameters passed to ReadFile()
 - HANDLE file—the file to be read
 - LPVOID buffer—a buffer where the data will be read into and written from
 - DWORD bytesToRead—the number of bytes to be read into the buffer
 - LPDWORD bytesRead—the number of bytes read during the last read
 - LPOVERLAPPED ovl—indicates if overlapped I/O is being used

Example of Standard API - Linux

EXAMPLE OF STANDARD API

As an example of a standard API, consider the read() function that is available in UNIX and Linux systems. The API for this function is obtained from the man page by invoking the command

man read

on the command line. A description of this API appears below:

```
#include <unistd.h>
ssize_t read(int fd, void *buf, size_t count)

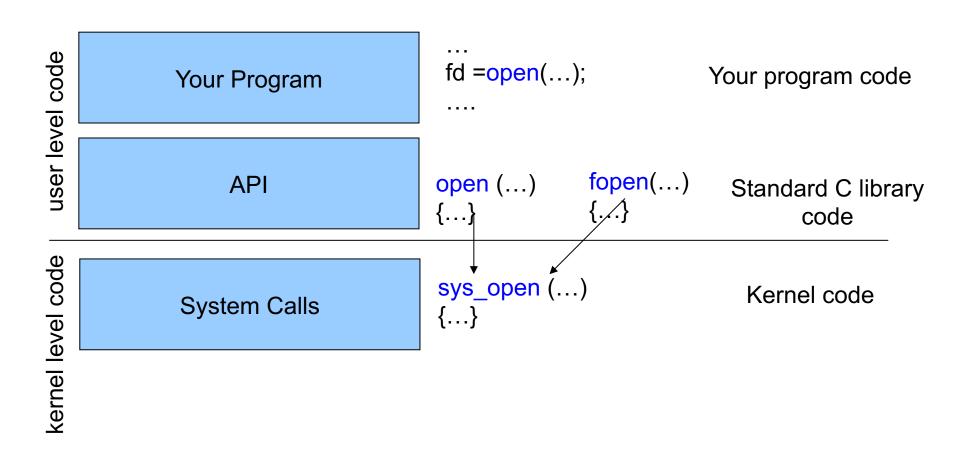
return function parameters
value name
```

A program that uses the read() function must include the unistd.h header file, as this file defines the ssize_t and size_t data types (among other things). The parameters passed to read() are as follows:

- int fd—the file descriptor to be read
- void *buf—a buffer where the data will be read into
- size_t count—the maximum number of bytes to be read into the buffer

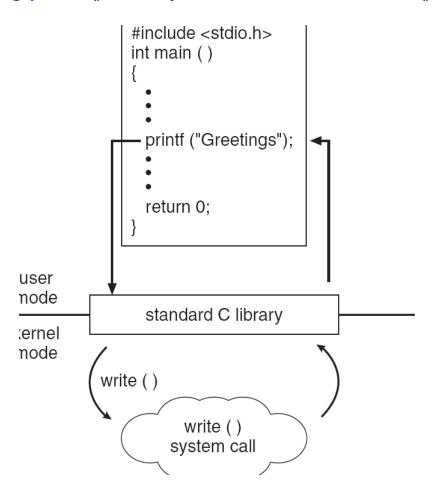
On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, read() returns -1.

Why use APIs rather than system calls directly?



Standard C Library Example

C program invoking printf() library call, which calls write() system call



Types of System Calls

- We can categorize system calls:
 - Process control
 - File management
 - Device management
 - Information maintenance
 - Communications
 - Protection

Examples of Windows and Unix System Calls

	Windows	Unix
Process Control	<pre>CreateProcess() ExitProcess() WaitForSingleObject()</pre>	<pre>fork() exit() wait()</pre>
File Manipulation	<pre>CreateFile() ReadFile() WriteFile() CloseHandle()</pre>	<pre>open() read() write() close()</pre>
Device Manipulation	SetConsoleMode() ReadConsole() WriteConsole()	ioctl() read() write()
Information Maintenance	<pre>GetCurrentProcessID() SetTimer() Sleep()</pre>	<pre>getpid() alarm() sleep()</pre>
Communication	<pre>CreatePipe() CreateFileMapping() MapViewOfFile()</pre>	<pre>pipe() shmget() mmap()</pre>
Protection	SetFileSecurity() InitlializeSecurityDescriptor() SetSecurityDescriptorGroup()	<pre>chmod() umask() chown()</pre>

Hello World with Linux System Call

hello.c

hello.S

.equ len, string_end - string.section

.ascii "hello, world\n"

```
.section .data
string:
.ascii
string_end:
.equ
.text.globl
main:
```

```
movq $1, %rax # write system call number movq $1, %rdi # put file handle for output movq $string, %rsi #put the string movq $len, %rdx #put length syscall #make the call movq $60, %rax #exit system call number movq $0, %rdi syscall. #make the call
```

In 64 bit Linux for x86 64 arch

Hello World with direct Linux System Call

Compile and run the assembly version as below:

```
$ gcc -c hello.S -o hello.o
$ gcc -no-pie hello.o -o hello
```

\$./hello

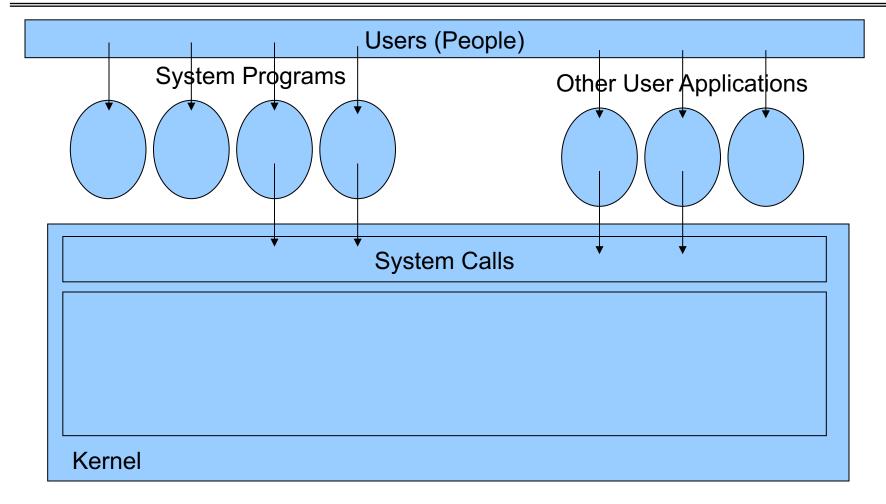
System Services/Programs

- System programs provide a convenient environment for program development and execution. They help you to manage the system. They can be divided into categories:
 - File manipulation (create, delete, copy, rename, print, list, ...)
 - Status information (date, time, amount of available memory, disk space, who is logged on, ...)
 - File modification (text editors, grep, ...)
 - Programming language support (compiler, debuggers, ...)
 - Program loading and execution (loaders, linkers)
 - Communications (ftp, browsers, ssh, ...)
- Other System Utilities/Applications may come with OS CD (games, math solvers, plotting tools, database systems, spreadsheets, word processors, ...).

System Services/Programs

- Most users' view of the operation system is defined by system programs, not the actual system calls.
- Some of the system programs are simply user interfaces to system calls; others are considerably more complex.
 - create file: simple system program that can just call "create" system call or something similar (open system call with O_CREAT flag).
 - compiler: complex system program.

System Programs



From OS's view: system+user programs are all applications

Linkers and loaders

They generate and load executable files. source main.c other.c **ELF** format: executable and linkable format program (this is the format of executable and object files in Linux) gcc -c other.c gcc -c main.c compiler other object main.o other.o object file files` To get information about an object gcc -o prog main.o other.o -lm linker or executable file, we can use the math following tools: library executable dynamically readelf prog file linked objdump (more general) libraries ./prog libc loader program in

memory

30

OS Design and Implementation Issues

- We need to set design goals
 - User goals: some goals are user oriented.
 - System goals: some goals are system related, not directly visible to users.
- Mechanisms and policies
 - Principle: Separate mechanisms from policies
 - Mechanism: how to do
 - Policy: what to do
- Implementation
 - C, C++ (high level language)
 - Porting to different architectures

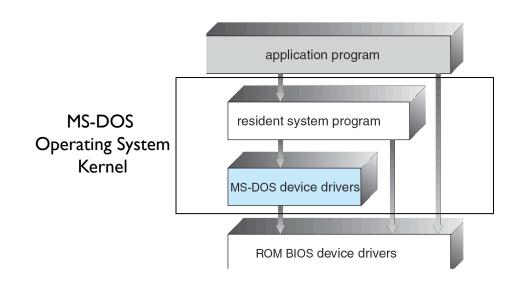
Structuring Operating System

OS Structure

- Simple Structure (MSDOS)
- Layered Approach
- Microkernel Approach
- Modules Approach

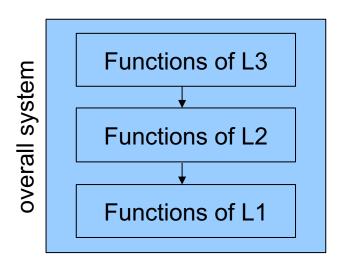
Simple Structure

- MS-DOS: written to provide the most functionality in the least space
 - Not divided into modules
- Although MS-DOS has some structure, its interfaces and levels of functionality are not well separated.

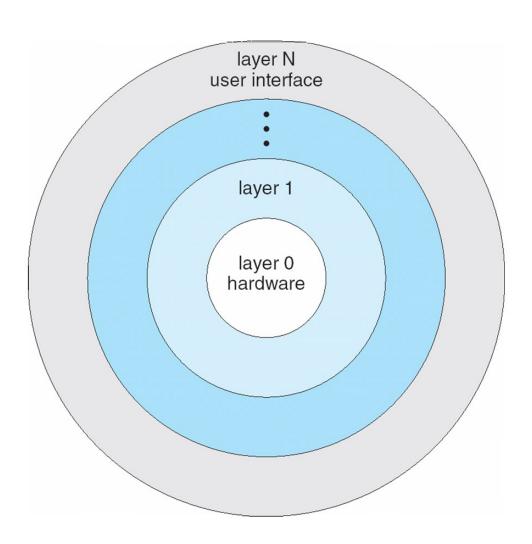


Layered Approach

- The operating system is divided into a number of layers (levels), each built on each other. The bottom layer (layer 0) is the hardware; the highest (layer N) is the user interface.
- Layers are selected such that each layer uses functions (operations) and services of only the layer below it.



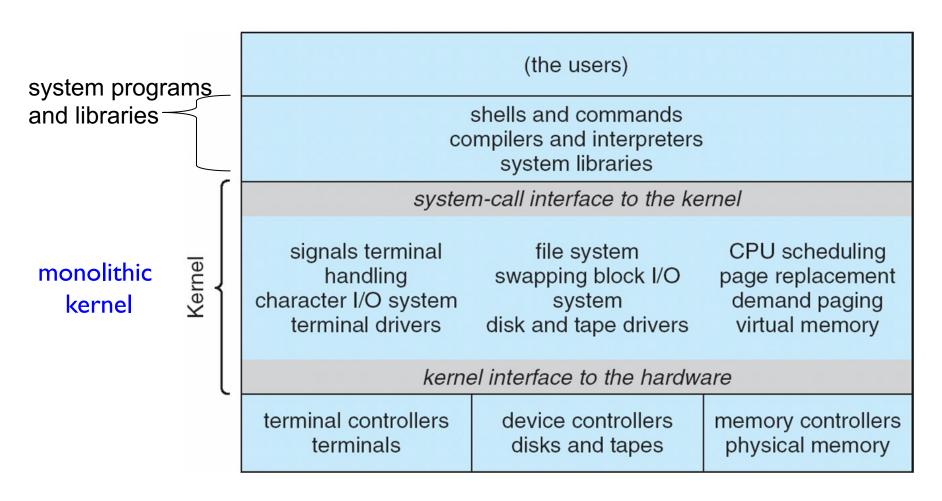
Layered Operating System



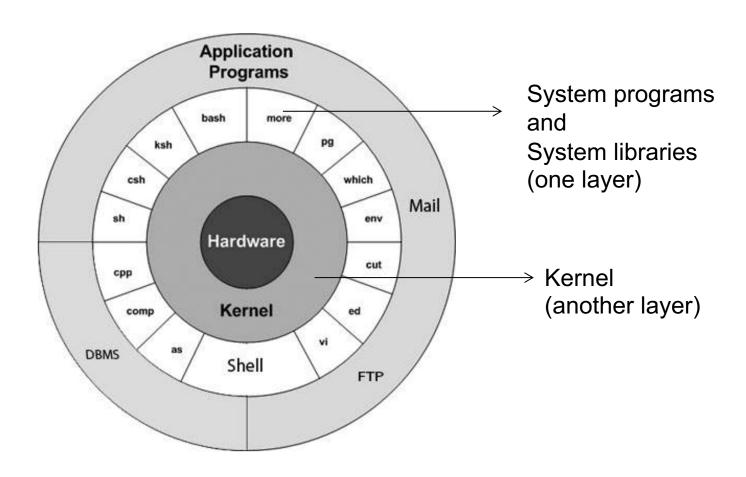
Unix

- UNIX: limited by hardware functionality, the original UNIX operating system had limited structuring. The UNIX OS consists of two separable parts:
 - Systems programs and libraries (run in user mode)
 - The kernel (runs in kernel mode)
- The kernel consists of everything below the system-call interface and above the physical hardware. Provides:
 - file system,
 - CPU scheduling,
 - memory management,
 - and other operating-system functions.
 - a large number of functions for one level (monolithic kernel)

Traditional UNIX System Structure



Unix OS architecture



From https://www.tutorialspoint.com

Linux OS architecture

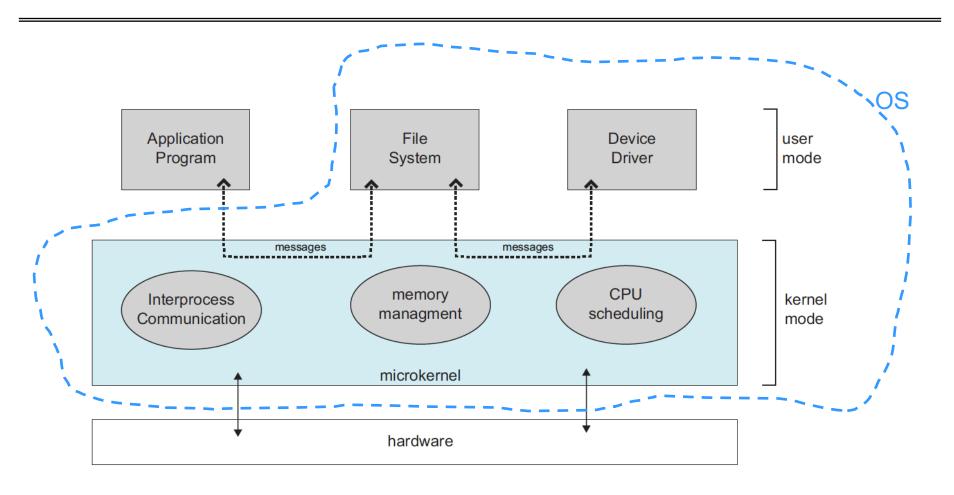
Various layers within Linux, also showing separation between the userland and kernel space

User mode	User applications	For example, bash, LibreOffice, GIMP, Blender, 0 A.D., Mozilla Firefox, etc.				
	Low-level system components:	System daemons: systemd, runit, logind, networkd, PulseAudio,	Windowing system: X11, Wayland, Mir, SurfaceFlinger (Android)	Other libraries: GTK+, Qt, EFL, SDL, SFML, FLTK, GNUstep, etc.		Graphics: Mesa, AMD Catalyst,
	C standard library	open(), exec(), sbrk(), socket(), fopen(), calloc(), (up to 2000 subroutines) glibc aims to be POSIX/SUS-compatible, uClibc targets embedded systems, bionic written for Android, etc.				
Kernel mode	Linux kernel	stat, splice, dup, read, open, ioctl, write, mmap, close, exit, etc. (about 380 system calls) The Linux kernel System Call Interface (SCI, aims to be POSIX/SUS-compatible)				
		Process scheduling subsystem	IPC subsystem	Memory management subsystem	Virtual files subsystem	Network subsystem
		Other components: ALSA, DRI, evdev, LVM, device mapper, Linux Network Scheduler, Netfilter Linux Security Modules: SELinux, TOMOYO, AppArmor, Smack				
Hardware (CPU, main memory, data storage devices, etc.)						

Microkernel System Structure

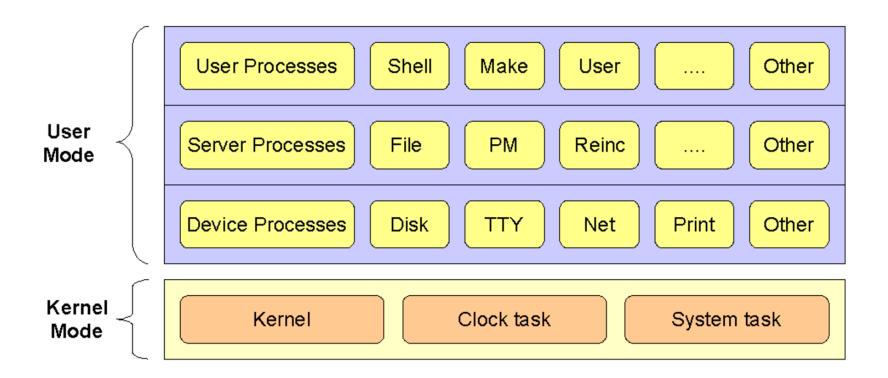
- Moves as much from the kernel into user space
- Communication takes place between user-mode OS processes using message passing.
- Benefits:
 - Easier to extend a microkernel
 - Easier to port the operating system to new architectures
 - More reliable (less code is running in kernel mode)
 - More secure
- Detriments:
 - Performance overhead of user space to kernel space communication.

Microkernels



Architecture of a typical microkernel OS

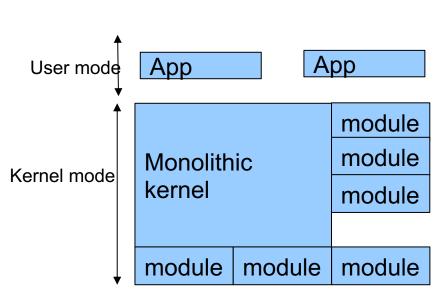
MINIX3 OS architecture a microkernel operating system



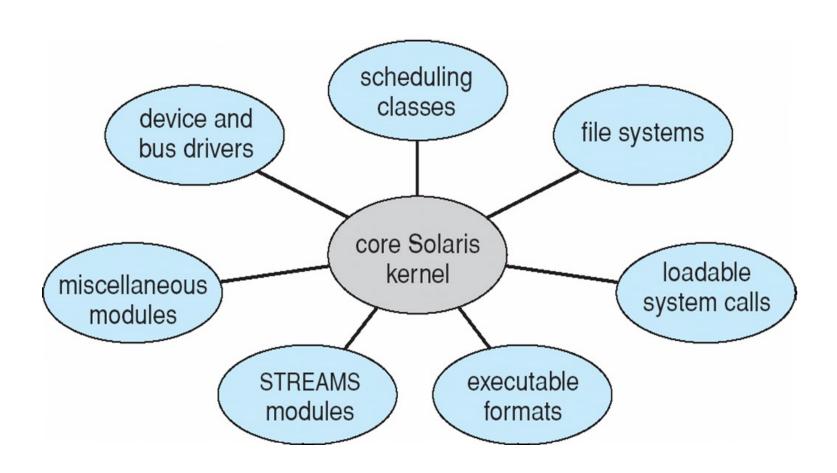
The MINIX 3 Microkernel Architecture

Modules

- Most modern operating systems implement kernel modules. In this way they improve their monolithic nature.
 - Uses object-oriented approach
 - Each core component is separate
 - Each talks to the others over known interfaces (function calls in the same address space)
 - Each is loadable as needed within the kernel
- Overall, similar to layers but more flexible.
- Linux supports modules.
- You can insert modules.
- You can remove modules.

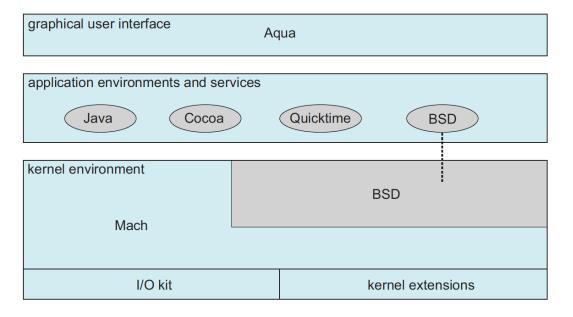


Solaris Modular Approach



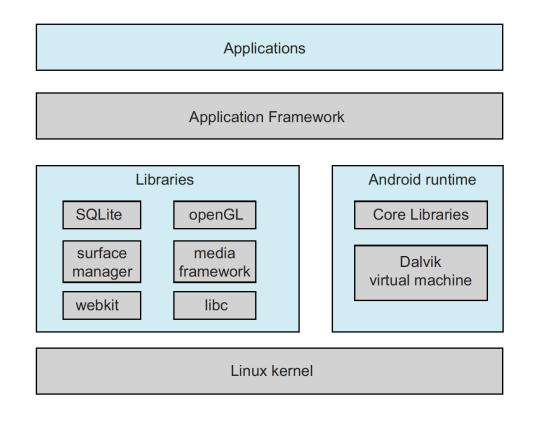
Hybrid Systems

- Mac OS X
 - Uses Mach and BSD kernels
 - Mach: microkernel
 - BSD: monolithic



Hybrid Systems

- Android
 - Uses Linux kernel
 - Layered stack of software on Linux kernel.
- A rich set of frameworks to develop and run Android applications.



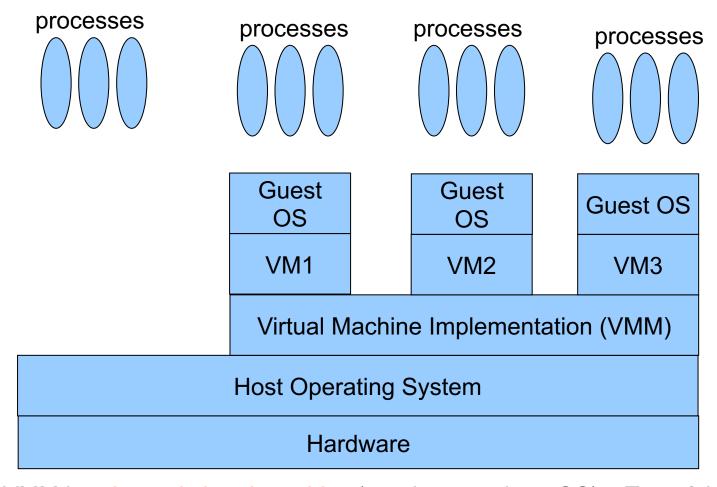
Virtualization

- Virtualization abstracts/virtualizes the hardware so that OSs and programs can run on a virtualized machine or a virtual environment
- Many different types of virtualizations:
 - Virtual machines: run OS/Apps on a VM that is identical to the bare hardware
 - For example: run Linux OS compiled for Intel x86 on a virtual machine duplicating x86 hardware.
 - Emulation: run OS or App developed for a machine that is different than the bare hardware
 - For example: run app developed for MIPS on Intel x86 machine using an emulator (MIPS emulation on Intel x86).
 - Abstract machines: run applications developed/compiled for an abstract machine running on bare hardware (interpretation)
 - For example JVM. Run a Java app on JVM running on x86

Virtual Machines

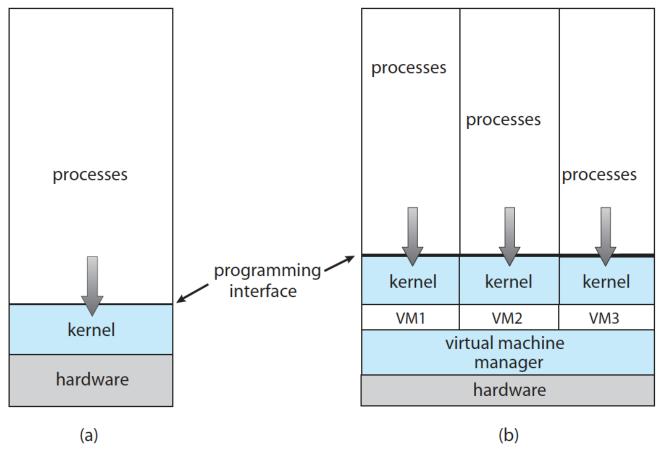
- Hardware is abstracted into several different execution environments.
 - Virtual machines.
- Each virtual machine provides an interface that is identical to the bare hardware.
- A guest process/kernel can run on top of a virtual machine.
 - We can run several operating systems on the same host.
 - Each virtual machine will run another operating system (guest).

Virtual Machines



1) VMM is a *hosted virtual machine* (running on a host OS) – Type-2 Hypervisor Example: WMware Workstation 50

Virtual Machines



2) VMM is *running directly on hardware* like an OS: Type-1 Hypervisor Example: Wmware ESX Hypervisor

Virtualization

- Vmware (Virtual Machine Manager

 VMM)
 - Abstracts Intel x86 hardware
- Java virtual machine (JVM)
 - Specification of an abstract computer
- .NET Framework
 - Specification of an abstract computer again

Operating System Debugging

- Failure analysis
 - Log files
 - Core dump
 - Crash dump
- Performance tuning
 - Monitor system performance
 - Add code to kernel
 - Use system tools like "top"
- DTrace
 - Facility for dynamically adding probes to a running system (both to processes and to the kernel)
 - Probes can be queried using D programming language to obtain info

Operating System Generation

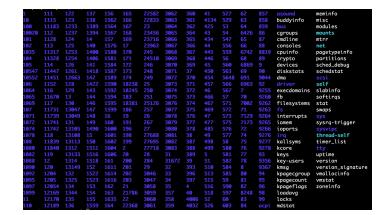
- Configure the kernel
- Compile the kernel

System Boot

- Bootstrap program (loader) locates the kernel, loads it and starts the kernel.
- This can be a two-step procedure.
 - Bootstrap program loads another more complex boot program
 - That boot program loads the kernel
- Then control is given to the kernel.
- Kernel starts the environment and makes the computer ready to interact with the user (via a GUI or command shell).
- Details depend on the system.

Performance Monitoring and Tuning

- We may need to monitor system performance.
- There are tools for that
- In Linux, for exmaple,
 - ps
 - top
 - vmstat (memory usage statistics)
 - netstat (network usage statistics)
 - iostat (I/O device usage statistics)
- In Linux, /proc file system gives kernel information (statistics)
 - cd /proc
 - we see lots of directories
 - one directory per process (named with process id pid)



Summary

- System calls are the programming interface to kernel (used by programs)
- System programs are useful for users (a nice environment for program development and running)
- Different approaches to structure kernel
 - monolithic
 - layered
 - microkernel
- Virtualization is important
 - Has various forms.

References

- Operating System Concepts, Silberschatz et al.
- Modern Operating Systems, Andrew S. Tanenbaum et al.
- Computer Systems, A Programmer's Perspective, 3rd edition, R. E. Bryant and D. R. O'Hallaron, Pearson, 2016.

Additional Study Material