EEE 431: Telecommunications 1

Quiz 2

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Instructor: Sinan Gezici

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Bilkent ID:		

Prob. 1: _____ / 22
Prob. 2: _____ / 15
Prob. 3: _____ / 28
Prob. 4: _____ / 35
Total: _____ / 100

Some trigonometric identities: $\sin(2x) = 2\sin(x)\cos(x)$ $\cos(2x) = 1 - 2\sin^2(x) = 2\cos^2(x) - 1$ $\cos(x+y) = \cos(x)\cos(y) - \sin(x)\sin(y)$ $\sin(x+y) = \sin(x)\cos(y) + \cos(x)\sin(y)$ $\sin(x)\cos(y) = 0.5\sin(x+y) + 0.5\sin(x-y)$ $\cos(x)\cos(y) = 0.5\cos(x+y) + 0.5\cos(x-y)$ $\sin(x)\sin(y) = 0.5\cos(x-y) - 0.5\cos(x+y)$. **Problem 1** Suppose that we have two analog messages $m_1(t)$ and $m_2(t)$, and we insert them into a signal x(t) as follows: $x(t) = (m_1(t) + m_2(t)) \cos(2\pi f_c t) + (m_1(t) - m_2(t)) \sin(2\pi f_c t)$. Assume that the bandwidths of the analog messages are much lower than f_c . Design a receiver to extract both $m_1(t)$ and $m_2(t)$ from x(t) by using only one local oscillator (which generates a sinusoidal signal at frequency f_c) and any other components that might be needed. Specify all the parameters at the receiver. The final outputs of the receiver must be $m_1(t)$ and $m_2(t)$. [Hint: A phase shifter (with a suitable value of phase shift) can be used to generate a cosine from a sine, or vice versa.]

Problem 2 Prove or disprove the following statement: "If a random process X(t) is stationary in the strict sense, then $E[(X(t))^3]$ does not depend on t, where E denotes the expectation operator."

Problem 3 Let X denote a random variable with the following probability density function (PDF):

$$f_X(x) = \begin{cases} 2(x+2)/9, & \text{if } -2 \le x \le 1\\ 0, & \text{otherwise} \end{cases}.$$

Suppose that X is input to a 2-level (1-bit) quantizer with the decision boundary at zero and the reconstruction (quantization) levels of a and b, where a < b. (That is, if the input is negative, the reconstruction level is a, and if the input is non-negative, the reconstruction level is b.)

- a) Find the probability that the quantizer output is strictly less than b, that is, find P(Q(X) < b).
- **b)** Find the (locally) optimal values of a and b that minimize the mean-squared error distortion D, where $D = E[(X Q(X))^2]$, with Q(X) denoting the quantizer output.

Problem 4 Consider a random process Y(t), which is expressed as $Y(t) = (2\sin(200\pi t + \theta) - A)^2$, where θ is a uniform random variable in the interval $[0, 2\pi)$, and A is a uniform random variable in the interval [-1, 1]. In addition, θ and A are independent. Calculate the mean and autocorrelation function of Y(t). Is Y(t) wide-sense stationary (WSS)? Why or why not? In addition, find $E[(Y(10))^2]$.

2) If
$$XHI$$
 is SSS, $f_{X(t+T)}(x) = f_{XHI}(x)$ $\forall t, \tau$. So $f_{XHI}(x)$ does not depend on t . Therefore,
$$E[X^3(t)] = \int_{-\infty}^{\infty} x^3 f_{XHI}(x) dx \quad does \quad not \quad depend \quad on \quad t. \quad \vee$$

$$f_{XHI}(x) = \int_{-\infty}^{\infty} x^3 f_{XHI}(x) dx \quad does \quad not \quad depend \quad on \quad t. \quad \vee$$

$$(4) \quad \forall \{1\} = 4 \sin^{2}(200+\pi+0) - 4A \sin(200\pi+1+0) + A^{2}$$

$$= 2 - 2 \cos(400\pi+120) - 4A \sin(200\pi+1+0) + A^{2}$$

$$E[\forall H] = 2 + E[A^{2}] = 2 + \int_{1}^{2} a^{2} \frac{1}{2} da = 2 + \frac{2}{6} = \frac{7}{3}$$

$$R_{y}(H_{1}, H_{2}) = E[\forall H_{1}) \forall H_{2}]$$

$$= 4 + 2 \underbrace{E[A^{2}]}_{H_{3}} + 2 \cos(400\pi(H_{1}-H_{2})) + 8 \underbrace{E[A^{2}]}_{H_{3}} \cos(200\pi(H_{1}-H_{2})) + 2 \underbrace{E[A^{2}]}_{H_{3}} + \underbrace{E[A^{4}]}_{H_{5}}$$

$$= \left[4 + \frac{28}{3} + \frac{1}{5} + 2 \cos(400\pi(H_{1}-H_{2})) + \frac{56}{3} \cos(200\pi(H_{1}-H_{2}))\right]$$

$$WSS. \quad E[Y^{2}(0)] = R_{y}(0) = 4 + \frac{28}{3} + \frac{1}{5} + 2 + \frac{56}{3} = |34.2|$$

(3) a)
$$P(Q(X) < b) = P(Q(X) = a) = \int_{-2}^{0} \frac{2(x+2)}{3} dx = \left[\frac{4}{3}\right]$$

b) $D = E[(X - Q(X))^{2}] = \int_{-2}^{0} (x-a)^{2} \frac{2(x+2)}{3} dx + \int_{0}^{1} (x-b)^{2} \frac{2(x+2)}{3} dx$
 $\frac{\partial D}{\partial a} = -\int_{-2}^{0} (x-a) \frac{4}{3} (x+2) dx = 0 \Rightarrow \int_{-2}^{0} (x^{2}+2x) dx = a \int_{-2}^{0} (x+2) dx \Rightarrow a = \frac{2}{3}$
 $\frac{\partial D}{\partial b} = -\int_{0}^{1} (x-b) \frac{4}{3} (x+2) dx = 0 \Rightarrow \int_{0}^{1} (x^{2}+2x) dx = b \int_{0}^{1} (x+2) dx \Rightarrow b = \frac{8}{15}$