DIGITAL MODULATION METHODS IN AN ADDITIVE WHITE GAUSSIAN NOISE (AWGN) CHANNEL

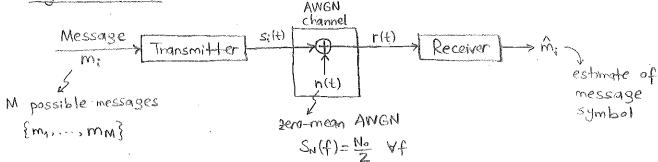
- · Advantages of digital comm. over analog comm.
 - Resistance to channel impairments
 - Higher spectral (bandwidth) efficiency -> more data per Hz. of bandwidth
 - Powerful error correction techniques
 - More efficient multiple access strategies
 - Better security and privacy
 - Cheaper implementation

[Introduction:

Insert digital message (information) into waveform → Digital modulation:
 mi → sift) i∈ {1,...,m}

Digital demodulation: Extract message from noise corrupted waveform.

· System model:



- Commonly, each message represents a sequence of bits:

$$m = b_1 \cdots b_K$$
 where $K = log_2 M$ (or, $M = 2^K$)

- Prior (a prior) probability of message m:

$$P_i = P(m_i \text{ sent})$$
, $i=1,...,M \rightarrow \sum_{i=1}^{M} p_i = 1$

For equally likely messages (symbols):

$$P_i = \frac{1}{M}$$
, $i=1,...,M \rightarrow equal priors$

- Transmitted signal: S1(1),..., SM(t) for te[0,T) T: symbol interval
- Received signal: $r(t) = s_i(t) + n(t)$ $t \in [0,T]$ real-valued serv-mean AWGN

 energy signal $s_i(t) = \frac{N_0}{2}$ $v \in [0,T]$

Geometric Representation of Signals: 27 Represent signals in a compact form and provide geometric intuition.

• Consider M energy signals $S_1(t)$, ..., $S_m(t)$ for $t \in [0,T)$ Express them as linear combinations of N <u>orthonormal basis functions</u>, $Y_1(t)$, ..., $Y_n(t)$, where $N \leq M$.

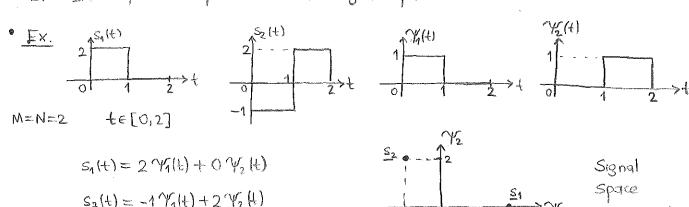
$$-\int_{0}^{T} Y_{i}(t) Y_{j}(t) dt = 0 \quad \forall i \neq j \quad \rightarrow \underline{\text{Orthogonal}}$$
 Orthonormal basis fn.s
$$-\int_{0}^{T} Y_{i}^{2}(t) dt = 1 \quad \forall i \quad \rightarrow \underline{\text{Normalized}}$$

Basis function representation of Si(+), , Sm(+):

- When $s_1(t)$, $s_n(t)$ can be represented as in (*), we say that the basis functions $\Upsilon(t)$, ..., $\Upsilon_n(t)$ span the set $S=\{s_1(t),...,s_n(t)\}$; or, we say that $s_i(t)$ resides in the signal space specified by $\Upsilon_i(t)$,..., $\Upsilon_n(t)$, $\forall i$.
- · Represent silt) as an N-dimensional vector:

· <u>Signal space</u>: N-dimensional vector space with N perpendicular axes labeled as $V_1,...,V_N$.

Sin Sm define M points in this signal space.



$$S_2(+) = -1 \gamma_1(+) + 2 \gamma_2(+)$$

$$S_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$S_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

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Space temperature in the presentation of the presentation in the presentation

· Relations between function and vector operations:

$$\underline{X}^{T}\underline{Y} = \sum_{i} x_{i} y_{i}$$
 - Inner product of two vectors.

$$= \left[E_i = \int_{0}^{T} S_i^2(t) dt = ||S_i||^2 \right]$$
 (||S_i||^2 = S_i^T S_i)

Proof:
$$E_i = \int_{0}^{T} \left(\sum_{j=1}^{N} S_{ij} \gamma_{j}(t) \right)^2 dt = \sum_{j=1}^{N} \sum_{k=1}^{N} S_{ij} S_{ik} \int_{0}^{T} \gamma_{j}(t) \gamma_{k}(t) dt = \sum_{j=1}^{N} S_{ij}^2 = ||S_{i}||^2$$

$$= \int_{0}^{T} \left(\sum_{j=1}^{N} S_{ij} \gamma_{j}(t) \right)^2 dt = \sum_{j=1}^{N} \sum_{k=1}^{N} S_{ij} S_{ik} \int_{0}^{T} \gamma_{j}(t) \gamma_{k}(t) dt = \sum_{j=1}^{N} S_{ij}^2 = ||S_{i}||^2$$

 $\langle S_i(t), S_j(t) \rangle = S_i^T S_j$

$$\underline{Proof:} \langle S_{i}(t)S_{j}(t) \rangle = \int_{0}^{T} S_{i}(t)S_{j}(t)dt = \int_{0}^{T} \sum_{k=1}^{N} S_{ik} \gamma_{k}(t) \sum_{\ell=1}^{N} S_{j\ell} \gamma_{\ell}(t)dt$$

$$= \sum_{k=1}^{N} \sum_{\ell=1}^{N} s_{ik} s_{i\ell} \int_{0}^{\infty} \gamma_{k}(t) \gamma_{\ell}(t) dt = \sum_{k=1}^{N} s_{ik} s_{jk} = \sum_{\ell=1}^{N} \sum_{i} s_{i\ell} s_{i\ell}$$

$$\int_{0}^{T} (S_{i}(t) - S_{j}(t))^{2} dt = \| \underline{S}_{i} - \underline{S}_{j} \|^{2} = \sum_{k=1}^{N} (S_{ik} - S_{jk})^{2}$$

Angle between two signals:

$$\underline{S_i} = \|\underline{S_i}\|\|\underline{S_i}\|\cos\theta_{ij} \Rightarrow \langle S_iH\rangle, S_jH\rangle = \sqrt{E_i}\sqrt{E_j}\cos\theta_{ij}$$

$$\cos \Theta_{ij} = \frac{\langle S_i | H \rangle, S_j | H \rangle}{\sqrt{E_i E_j}}$$

Gram-Schmidt Orthonormalization:

A technique for constructing an arthonormal basis for a given set of energy signals, $S_1(t),...,S_M(t)$, for $t \in [0,T)$

Step-1:
$$\sqrt{1} = \frac{S_1(t)}{\sqrt{E_1}}$$
, $E_1 = \int_0^t S_1^2(t) dt$
Step-2: $S_{21} = \int_0^t S_2(t) \sqrt{1}(t) dt$

$$d_{2}(t) = S_{2}(t) - S_{2}(Y_{1}(t))$$

$$\gamma_2(t) = \frac{d_2(t)}{\sqrt{\int_0^1 d_2^2(t)dt}}$$

Step-i:
$$S_{ij} = \int_{0}^{T} S_{i}(t) \gamma_{i}(t) dt$$
, $j=1,...,i-1$

$$d_i(t) = S_i(t) - \sum_{j=1}^{i-1} S_{ij} \gamma_i(t)$$

$$\gamma_{i}(t) = \frac{d_{i}(t)}{\sqrt{\int_{0}^{T} d_{i}^{2}(t) dt}}$$

Similar to vector case:

$$e_1 = \frac{d_1}{\|g_1\|}, e_2 = \frac{d_2 - (g_1^T e_1)e_1}{\|g_2 - g_1^T e_1\|e_1\|},$$

& Continue until i=M, and consider only non-zero basis functions at the end.

VERT ,..., VERT , NEM . (NEM iff SI(H),... Sult) are

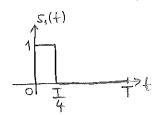
N: # non-sero {diff)}. (linearly independent)

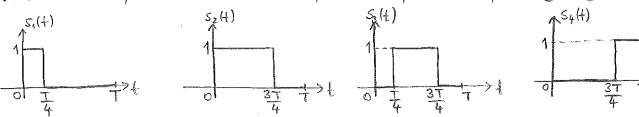
Notation \ in textbook

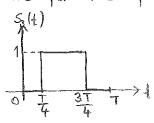
* Note that the choice of orthonormal basis {\mathbb{Y}_i(t)}_i= is not unique. But that choice does not affect the dimension of the signal space, and the norms and inner products of the vectors.

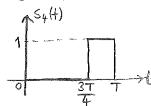
Example:

Find a set of orthonormal basis functions for the following signals.

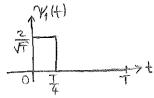








•
$$E_1 = \int_0^{7/4} (1)^2 dt = \frac{T}{4}$$
 $\gamma_1(t) = \frac{S_1(t)}{\sqrt{T}} = \frac{2}{\sqrt{T}} S_1(t)$
 $\gamma_1(t) = \frac{S_1(t)}{\sqrt{T}} = \frac{2}{\sqrt{T}} S_1(t)$

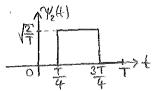


•
$$S_{21} = \int_{0}^{T} S_{2}(t) \Upsilon_{1}(t) dt = \int_{0}^{T/4} 1. \frac{2}{\sqrt{T}} dt = \frac{\sqrt{T}}{2}$$

$$S_{21} = \int_{0}^{1} S_{2}(t)^{2} \gamma_{1}(t) dt = \int_{0}^{1} 1 \cdot \frac{1}{\sqrt{T}} dt = \frac{1}{2}$$

$$d_{2}(t) = S_{2}(t) - S_{21} \gamma_{1}(t) = S_{2}(t) - \frac{1}{2} \gamma_{1}(t) = S_{2}(t) - S_{1}(t)$$

$$d_{2}(t) = S_{2}(t) - S_{2}(t) + S_{2}(t) - S_{1}(t) = S_{2}(t) - S_{1}(t) + S_{2}(t) - S_{2}(t) - S_{1}(t) + S_{2}(t) - S_{2}(t)$$



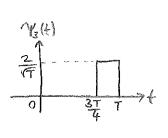
$$S_{31} = \int_{0}^{T} S_{3}(t) \gamma_{2}(t) dt = 0$$

$$S_{32} = \int_{0}^{T} S_{3}(t) \gamma_{2}(t) dt = \sqrt{\frac{T}{2}}$$

 $d_3(t) = s_3(t) - s_{21} \gamma_1(t) - s_{32} \gamma_2(t) = s_3(t) - \sqrt{\frac{1}{2}} \gamma_2(t) = 0$ ~ No new basis function of this step!

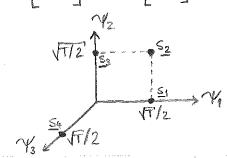
•
$$S_{41} = \int_{0}^{T} S_{4}(t) \phi_{1}(t) dt = 0$$

 $S_{42} = \int_{0}^{T} S_{4}(t) \phi_{2}(t) dt = 0$
 $C_{4}(t) = S_{4}(t) - S_{41} Y_{1}(t) - S_{42} Y_{2}(t) = S_{4}(t)$
 $S_{0}, \quad Y_{3}(t) = \frac{S_{4}(t)}{\sqrt{\int_{0}^{T} S_{4}(t) dt}} = \frac{2}{\sqrt{\int_{0}^{T}} S_{4}(t)}$



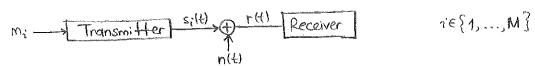
Overall,

$$S_{1} = \begin{bmatrix} F_{1}/2 \\ O \\ O \end{bmatrix} \qquad S_{2} = \begin{bmatrix} F_{1}/2 \\ F_{1}/2 \\ O \end{bmatrix} \qquad S_{3} = \begin{bmatrix} O \\ F_{1}/2 \\ O \end{bmatrix} \qquad S_{4} = \begin{bmatrix} O \\ O \\ F_{1}/2 \end{bmatrix}$$

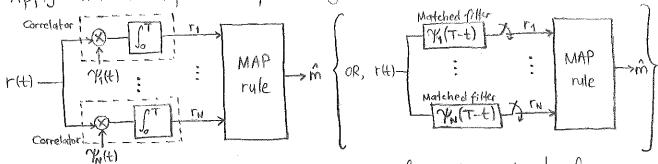


Optimal Receiver Structure for AWGN Channels:

• Consider a communications system in which one of M possible messages is transmitted via signals $s_i(t),...,s_m(t)$, and the channel is modeled as AWGN channel with $S_N(f)=N_0/2$ Vf.



- · For the optimal receiver design:
 - Obtain a set of orthonormal boisis functions WH),..., YNH for signals salt),..., SmH).
 - Obtain projection of r(t) anto the signal space specified by Y1(t),..., Y1(t).
 - Apply maximum a-posteriori probability (MAP) decision rule to estimate the message



 $|r(t)| = s_{i}(t) + n(t), \quad t \in [0,T)$ $r_{j} = \int_{r_{i}}^{T} (t) \gamma_{j}^{*}(t) dt = \int_{s_{i}}^{T} (s_{i}(t) + n(t)) \gamma_{j}^{*}(t) dt = \int_{s_{i}}^{T} (s_{i}(t) + n(t)) \gamma_{j}^{*}(t) dt + \int_{s_{i}}^{T} n(t) \gamma_{j}^{*}(t) dt$ $|r_{j}| = S_{i,j} + n_{j}$

· Statistics of E= [n... rn]T:

$$\begin{array}{c|c} \Gamma_{i} \\ \vdots \\ \Gamma_{N} \end{array} = \begin{array}{c|c} S_{i1} \\ \vdots \\ S_{iN} \end{array} + \begin{array}{c|c} n_{i} \\ \vdots \\ n_{N} \end{array} \longrightarrow \begin{array}{c|c} \Gamma = S_{i} + N \\ \vdots \\ S_{iN} \end{array} \longrightarrow \begin{array}{c|c} \Gamma : Observation \ vector \end{array}$$

$$\begin{split} & E\left\{n_{j} n_{k}\right\} = E\left\{\int_{0}^{\infty} h(t_{1}) \gamma_{j}^{2}(t_{1}) \, dt_{1} \int_{0}^{\infty} h(t_{2}) \gamma_{k}^{2}(t_{2}) \, dt_{1} \, dt_{2}\right\} \\ & = \iint_{0}^{\infty} \frac{E\left\{n(t_{1}) n(t_{2})\right\}}{\sqrt{2} \left\{(t_{1}-t_{2})\right\}} \gamma_{j}^{2}(t_{1}) \gamma_{k}^{2}(t_{2}) \, dt_{1} \, dt_{2} \\ & = \frac{N_{0}}{2} \int_{0}^{\infty} \gamma_{j}^{2}(t_{1}) \gamma_{k}^{2}(t_{1}) \, dt_{2} = \left\{\begin{array}{c} N_{0}/2 \ , \ \text{if} \ j = k \\ 0 \ , \ \text{if} \ j \neq k \end{array}\right. \end{split}$$

$$\begin{cases} h(t) \rightarrow 2ero-mean \\ AWGN \end{cases}$$

$$S_{N}(f) = \frac{N_{0}}{2}, \forall f$$

$$R_{N}(z) = \frac{N_{0}}{2} S(z)$$

$$\int_{0}^{T} h(t) \phi_{j}(t) dt \rightarrow Gaussian \\ r.v.$$

So, $n \sim N(0, \frac{N_0}{2}I)$ - $2 \times (n_1, ..., n_N)$ are i.i.d. Gaussian with $N(0, N_0/2)$.

Hence, $r \mid \underline{s}_i \sim N\left(\underline{s}_i, \frac{N_0}{2}\underline{I}\right)$

{i.i.d.: Independent & identically distributed}
{I > N × N identity matrix}

• Although r(t) cannot be reconstructed perfectly from r, r carries all the information related to the transmitted message.

$$\Gamma \rightarrow Sufficient statistics$$

$$\Gamma(t) = S_{i}(t) + n(t) = \sum_{j=1}^{N} S_{ij} \gamma_{j}(t) + \sum_{j=1}^{N} n_{j} \gamma_{j}(t) + n'(t)$$

$$S_{i}(t) \qquad Projection of Remainder of Noise on the noise on the signal space.$$

$$= \sum_{j=1}^{N} (S_{ij} + n_{j}) \gamma_{j}(t) + n'(t)$$

$$\Gamma(t) = \sum_{j=1}^{N} r_{j} \gamma_{j}(t) + n'(t)$$

$$\Gamma = \begin{bmatrix} r_{i} \\ \vdots \\ r_{N} \end{bmatrix} \qquad Projection of Projection of Signal space.$$

$$\Gamma = \begin{bmatrix} r_{i} \\ \vdots \\ r_{N} \end{bmatrix} \qquad Projection of Signal space$$

Why is r sufficient statistics?

Because n'(4) is independent of $\Gamma_1, ..., \Gamma_N$; hence, carries no information related to which message is transmitted (see (+)).

$$\begin{split} & \underbrace{Pmof:}_{E \{ n'(t) r_{j} \} = E \{ (n(t) - \sum_{\ell=1}^{N} n_{\ell} \gamma_{\ell}(t) (s_{ij} + n_{i}) \}}_{e=1} \\ & = s_{ij} E \{ n(t) - \sum_{\ell=1}^{N} n_{\ell} \gamma_{\ell}(t) \} + E \{ n(t) n_{j} - \sum_{\ell=1}^{N} n_{\ell} n_{j} \gamma_{\ell}(t) \} \\ & = s_{ij} (E \{ n(t) \} - \sum_{\ell=1}^{N} E \{ n_{\ell} \} \gamma_{\ell}(t)) + \underbrace{\int E \{ n(t) n_{\ell} F \{ \gamma_{j}(z) dz - \sum_{\ell=1}^{N} E \{ n_{\ell} n_{j} \} \gamma_{\ell}(t) \}}_{N_{0} S(t-z)} \\ & = s_{ij} (0-0) + \frac{N_{0}}{2} \gamma_{j}(t) - \frac{N_{0}}{2} \gamma_{j}(t) \end{split}$$

Since, $E\{n'(t)\}=E\{n(t)-\sum_{j=1}^{d}n_j\gamma_j(t)\}=0$, we obtain $E\{n'(t)r_j\}=E\{n'(t)\}E\{r_j\}=0$. Therefore n'(t) and r_j are uncorrelated for all t and j.

Since they are also Gaussian, n'(+) are r; are independent Yt, j.

· Equivalent vector channel model:

$$\Gamma = \underline{S}_i + \underline{n}$$
, $\underline{n} \sim N(\underline{Q}, \frac{N_2}{2}\underline{I})$, $i \in \{1, ..., M\}$

= 0 $\forall t, j \in \{1, ..., N\}$

Given I, find a decision rule that maps I into m in such a way that the average probability of error is minimized.

· MAP Decision Rule:

equivalent (

equivalent

Choose $\hat{m} = m_i$ if $P(m_i sent|r) > P(m_i sent|r)$ for all $j \neq i$

Aposteriori probability: $P(m_i \text{ sent } | \Gamma) = \frac{P(\Gamma | m_i) P(m_i)}{P(r)}$

Pi=P(mi) -> Prior Probability

Choose M=m; if PiP([Im;) ≥ P; P([Im;) for all j≠i

In other words, choose m=m; if [e]; where

 $2_i = \left\{ \underline{\Gamma} : P_i P(\underline{\Gamma}|m_i) \ge P_j P(\underline{\Gamma}|m_j) \quad \forall j \neq i \right\} , i = 1, ..., M.$

· Maximum Likelihood (ML) Decision Rule:

Special case of MAP rule for equal priors (P:= 1, 1=1,...,M)

Choose $\hat{m}=m_i$ if $P(\underline{r}|m_i) \ge P(\underline{r}|m_i)$ for all $j \ne i$

Likelihood function: [P[[mi]] = L[mi]] → likelihood of m: (conditional probability of I given mi)

Log-likelihood function: \(\left(m_i) = log P[r[m_i] \)\\ \text{Log-seasier to deal with.}

(Choose m=m; if e(mi) > e(mi) for all j≠i

ML based receiver for AWGN channel:

$$\underline{\Gamma} = \underline{Si} + \underline{n}$$
, $\underline{n} \sim \mathcal{N}(0, \frac{N_0}{2}\mathbf{I})$

$$P_{N}(\underline{n}) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi} \sqrt{N_{0}}} e^{-\frac{N_{0}^{2}}{2 \cdot \frac{N_{0}}{2}}} = (\pi N_{0})^{-\frac{N}{2}} \exp\left\{-\frac{1}{N_{0}} \sum_{i=1}^{N} n_{i}^{2}\right\} = (\pi N_{0})^{-\frac{N}{2}} e^{-\frac{||\underline{n}||^{2}}{N_{0}}}$$

$$P(\underline{\Gamma}|m_i) = P_{\underline{N}}(\underline{\Gamma} - \underline{S}_i) = \left| (\underline{T} N_0)^{-\frac{N_0}{2}} e^{-\frac{\|\underline{\Gamma} - \underline{S}_i\|^2}{N_0}} \right|$$

$$\ell(m_i) = \log p(\underline{r} \mid m_i) = -\frac{N_c}{2} \log (\overline{r} \mid N_c) - \frac{1}{N_c} ||\underline{r} - \underline{S}_i||^2$$

ML rule: Choose m; if l(m;) is the max of l(m,),..., l(m,).

Equivalently, choose mi if III-sill is the minimum of III-sill, ..., III-sull.

> Minimum distance decision rule.

4

· Theorem: MAP rule minimizes the probability of error.

Probability of error (Pe):
$$P_e = \sum_{i=1}^{M} p_i P(\hat{m} \neq m_i | m_i \text{ sent}) \triangleq \sum_{i=1}^{M} p_i P_{e,i}$$

Probability
$$S_{c} = \sum_{i=1}^{M} P_{i} P(\hat{m} = m_{i} | m_{i} \text{ sent}) \triangleq \sum_{i=1}^{M} P_{i} P_{c,i}$$
 (of course, $P_{c,i} = 1 - P_{e,i}$, $P_{c} = 1 - P_{e}$) of correct

Proof: Show that MAP rule maximizes Pe.

$$P_c = \sum_{i=1}^{M} P_i \int_{\mathcal{Z}_i} p(\varepsilon | m_i) d\varepsilon = \sum_{i=1}^{M} \int_{\mathcal{Z}_i} (p_i p(\varepsilon | m_i)) d\varepsilon$$

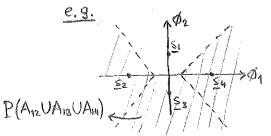
For each I, assign I to Z; if P:P(Imi) > P; P(Imi) > Y; + i to maximize P. ⇒ MAP rule maximizes Pc, and minimizes Pe.

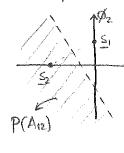
Union Bound on the Probability of Error:

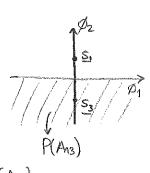
- · When it is difficult to calculate an exact expression for Pe, the union bound can be used to obtain an upper bound.
- Define event Aik as follows:

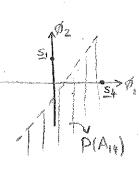
Aik: Event that observation vector I is closer to sk than Si when si is sent.

$$P_{e,i} = P\left(\bigcup_{k=1}^{M} A_{ik}\right) \leq \sum_{k=1}^{M} P(A_{ik}), \quad i=1,...,M$$
 $\leftarrow Z$ Union bound $\downarrow P_{k\neq i}$ Pdirwise error prob.









· Pairwise error probabilities are easy to obtain.

$$P(A_{ik}) = P(||\underline{r} - \underline{s}_{k}|| < ||\underline{r} - \underline{s}_{i}|| | m_{i})$$

$$n \sim N(0, \frac{N_{0}}{2}) = P(m_{i} > \frac{||\underline{s}_{i} - \underline{s}_{k}||}{2})$$

$$N(0,1) \stackrel{=}{=} P\left(\frac{n_1}{\sqrt{N_0/2}}\right) > \frac{\|\underline{s}_i - \underline{s}_k\|}{2\sqrt{N_0/2}}$$

$$P(A_{ik}) = Q\left(\frac{\|\underline{s}_i - \underline{s}_k\|}{\sqrt{2N_0}}\right)$$

So,
$$P_{e,i} \leq \sum_{k=1}^{M} Q\left(\frac{\|\mathbf{S}_{i} - \mathbf{S}_{k}\|}{\sqrt{2N_{o}}}\right)$$

$$\begin{array}{c|c}
 & & \downarrow & \downarrow \\
\hline
 & \downarrow & \downarrow \\$$

M1: Noise component along 41.

So, $P_{e,i} \leq \sum_{k=1}^{M} Q\left(\frac{\|S_i - S_k\|}{\sqrt{2N_o}}\right)$ Union bound for conditional probability of error when mi is sent.

Hence,
$$P_e = \sum_{i=1}^{M} P_i P_{e,i} \Rightarrow P_e \leq \frac{1}{M} \sum_{i=1}^{M} \sum_{k=1}^{M} Q\left(\frac{||s_i - s_{k}||}{\sqrt{2N_o}}\right)^{-1}$$
 Union bound for the probability of error.

· A looser version of union bound:

$$Q\left(\frac{||\underline{S}_i - \underline{S}_k||}{\sqrt{2N_0}}\right) \leq Q\left(\frac{|\underline{O}_{min}|}{\sqrt{2N_0}}\right) \quad \forall i,k \quad \text{since } Q(\cdot) \text{ is all monotone decreasing. fn.}$$

Then,
$$P_e \leqslant (M-1) \Re \left(\frac{d_{min}}{\sqrt{2N_0}} \right)$$

M-ARY PULSE AMPLITUDE MODULATION (PAM)

· Information is carried by the signal amplitude

$$S_{i}(t) = A_{i} p(t) = S_{i} \gamma(t), \quad i=1,...,M, \quad t \in [0,T]$$

$$\gamma(t) = \frac{p(t)}{\sqrt{E_{p}}} \quad \text{where} \quad E_{p} = \int_{-\infty}^{\infty} |pH|^{2} dt \quad \gamma \in [0,T]$$

Hence, Si = Ai /Ep

• Commonly, $A_i = (2i-1-M)A$, $i=1,...,M \Rightarrow S_i = (2i-1-M)A\sqrt{E_p} = (2i-1-M)d$

$$\frac{m_1}{-(M-1)d}$$
 $\frac{m_2}{-(M-3)d}$ $\frac{m_1}{-d}$ $\frac{m_2}{d}$ $\frac{m_2}{(M-3)d}$ $\frac{m_1}{(M-1)d}$

Assume equal -> ML rule: $\hat{m} = \begin{cases} 1, & \text{if } r_1 < -(M-2)d \\ i, & \text{if } (2i-2-M)d \leq r_1 < (2i-M)d \end{cases}$ $r_1 = \int_{0}^{T} (4) \Upsilon(4) d4$ priors

$$\frac{\text{Ex. } M=4 \text{ (2 bits)}}{-3d-d-d-d-3d} \Rightarrow Gray encoding$$

• <u>Carner-Modulated PAM for Bandpass Channels (M-any ASK)</u>:

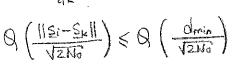
$$\begin{array}{c|c} U_i(t) = S_i(t) \cos(2\pi f_c t), & i=1,...,M \\ \hline S_i(t) & S_i(t) \\ \hline E_{u_i} = \int_{-\infty}^{\infty} S_i^2(t) \cos^2(2\pi f_c t) dt & cos(2\pi f_c t). \end{array}$$

$$=\frac{1}{2}\int_{-\infty}^{\infty} s_i^2(t) dt + \frac{1}{2}\int_{-\infty}^{\infty} s_i^2(t) \cos(4\pi f_c t) dt \approx \frac{1}{2}\int_{-\infty}^{\infty} s_i^2(t) dt$$

$$u_i(t) = A_i p(t) \cos(2\pi f_i(t)), \quad i=1,..., M$$

Then, $u_i = [A_i \sqrt{\frac{p}{2}}], \quad i=1,..., M$

$$\gamma(t) = \sqrt{\frac{2}{E_p}} p(t) \cos(2\pi f_c t)$$
 3-dimensional space



$$P_e \leq (M-1) \otimes \left(\frac{d_{min}}{\sqrt{2No}}\right)$$

· Probability of Error:

Consider
$$s_i(t) = A_i p(t) = s_i \gamma(t) \rightarrow \underline{s}_i = [A_i(\overline{\epsilon}p)] = [(2i-1-M)d], i=1,...,M.$$

$$P_e = \frac{1}{M} \sum_{i=1}^{M} P_{e,i}$$

For $S_i = (2i-1-M)d$, i=1,...,M, we have $P_{e,1} = P_{e,M}$ and $P_{e,2} = ... = P_{e,M-1}$ due to symmetry.

$$P_{e,1} = P(\hat{m} \neq m_1 \mid m_1 \text{ sent}) = P(r_1 \ge -(M-2)d \mid m_1 \text{ sent})$$

$$= P(-(M-1)d + n_1 \ge -(M-2)d)$$

$$= P(n_1 \ge d) = P(\frac{n_1}{\sqrt{N_0/2}} \ge \frac{d}{\sqrt{N_0/2}})$$

$$= R(\frac{d}{\sqrt{N_0/2}}) = R(\frac{d}{\sqrt{N_0/2}}) = R(\frac{2d^2}{N_0})$$

 $P_{e,2} = P(\hat{m} \neq m_2 \mid m_2 \text{ sent}) = P(r_1 < -(M-2)d \text{ or } r_1 \ge -(M-4)d \mid m_2 \text{ sent})$

=
$$P(-(M-3)d+m < -(M-2)d$$
 or $-(M-3)d+m \ge -(M-4)d)$

$$=P(n_1<-d \text{ or } n_1\geqslant d)$$

$$= P\left(\frac{n_1}{\sqrt{N_0/2}} < -\frac{d}{\sqrt{N_0/2}} \text{ or } \frac{n_1}{\sqrt{N_0/2}} > \frac{d}{\sqrt{N_0/2}}\right)$$

$$= \left[O\left(\sqrt{2d^2} \right) \right]$$

$$= 2 \, \Omega \left(\sqrt{\frac{2 \, d^2}{N_0}} \right)$$

So,
$$P_e = \frac{2}{M} P_{e,1} + \frac{(M-2)}{M} P_{e,2} = \frac{2M-2}{M} Q(\sqrt{\frac{2d^2}{No}})$$

$$\begin{cases} 1^2 + 3^2 + \cdots + (2j-1)^2 = \frac{j(2j-1)(2j+1)}{3} \end{cases}$$

Average energy per symbol: $E_s = \frac{1}{M} \sum_{i=1}^{M} A_i^2 = \frac{1}{M} \sum_{i=1}^{M} (2i-1-M)^2 d^2 = \frac{(M^2-1)d^2}{3}$

So,
$$P_e = \frac{2(M-1)}{M} O_s \left(\sqrt{\frac{2 \cdot 3E_s}{N_0 \cdot (M^2-1)}} \right) = \frac{2(M-1)}{M} O_s \left(\sqrt{\frac{6 \overline{s}_s}{M^2-1}} \right)$$
 where $\overline{s}_s = \frac{E_s}{N_0}$ symbols

M-ARY PHASE-SHIFT KEYING (PSK):

•
$$S_i(t) = A p(t) cos(2\pi fet + \emptyset_i)$$
, $i=1,...,M$, $t \in [0,T_s)$
information is
corried in the phase

Commonly,
$$\phi_i = \frac{2\pi(i-1)}{M}$$
, $i=1,...,M$. Then, $S_i(t) = A \cdot p(t) \cos\left(2\pi f_c t + \frac{2\pi(i-1)}{M}\right)$, $i=1,...,M$.

=
$$A \cos\left(\frac{2\pi(i-1)}{M}\right) p(t) \cos\left(2\pi f_c t\right) - A \sin\left(\frac{2\pi(i-1)}{M}\right) p(t) \sin\left(2\pi f_c t\right)$$

· If p(+) is a rectangular pulse with amplitude (over [0, Ts] and fcTs is an integer,

$$Y_{2}(t) = p(t) \cos(2\pi f_{c}t)$$

$$Y_{2}(t) = -p(t) \sin(2\pi f_{c}t)$$

$$\frac{f_{3}^{2}}{o} \xrightarrow{T_{6}} t$$

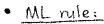
Exercise: Show that $\int_{0}^{T_{S}} \gamma_{1}^{2}H dt = \int_{0}^{T_{S}} \gamma_{2}^{2}H dt = 1$ and $\int_{0}^{T_{S}} \gamma_{1}^{2}H dt = 0$ (Even if p(H) is not rectangular and fcTs is non-in-teger, these results hold approximately for fc $\gg \frac{1}{T_{S}}$.) I.e., any pulse with energy 2 and domain [0,75].

· Vector representation:

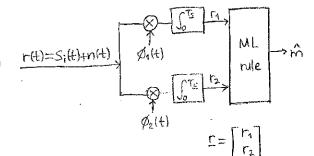
$$\underline{S_{i}} = \begin{bmatrix} S_{i1} \\ S_{i2} \end{bmatrix} = \begin{bmatrix} A \cos\left(\frac{2\pi(i-1)}{M}\right) \\ A \sin\left(\frac{2\pi(i-1)}{M}\right) \end{bmatrix}, i=1,...,M \longrightarrow \text{Two-dimensional}$$
Signal space

• Symbol energy:
$$\|S_i\|^2 = A^2 = E_S$$

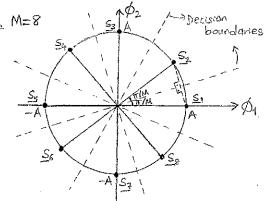
we will denote it by $E_b \longrightarrow bH$ energy in the bindry case



$$|\hat{m}=i|$$
 if $(2i-3)\frac{\pi}{M} < tan^{-1}(\frac{r_2}{r_1}) < (2i-1)\frac{\pi}{M}$, $i=1,...,M$ $\underline{r(t)}=S_i(t)+n(t)$



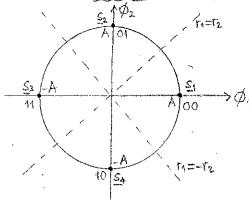
<u>es.</u> M=8



Decision regions:

$$Z_{i} = \left\{ \underline{r} : (2i-3) \frac{\pi}{M} < \tan^{-1}\left(\frac{r_{2}}{r_{4}}\right) \leq (2i-1) \frac{\pi}{M} \right\} \quad i=1,...,M$$

e.s. M=4 => APSK (quadri-phase shift keying)



$$\hat{m} = \begin{cases} 1, & \text{if } r_1 \ge r_2 & \text{if } r_1 \ge -r_2 \\ 2, & \text{if } r_1 < r_2 & \text{if } r_1 < r_2 \\ 3, & \text{if } r_1 < r_2 & \text{if } r_1 < -r_2 \\ 4, & \text{if } r_1 \ge r_2 & \text{if } r_1 < -r_2 \end{cases}$$

$$E = Si + D$$
, where $E = \begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$.

M=2 => BPSK (bindry phase shift keying) 2, can be regarded as

$$\begin{array}{c|c} -A & A \\ \hline \underline{s}_2 & \underline{s}_1 \\ \end{array} \rightarrow \emptyset_1$$

$$\hat{m} = \begin{cases} 1, & \text{if } r_1 > 0 \\ 2, & \text{if } r_1 < 0 \end{cases}$$

$$r_{4} = \int_{0}^{T_{5}} r(t) \phi_{1}(t) dt = S_{1} + n_{4}$$

$$\mathcal{N}(0, \frac{N_{0}}{2})$$

· Probability of Error:

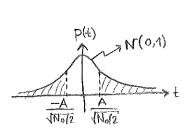
■ BPSK (M=2):

$$P_{e} = \frac{1}{2} P_{e,1} + \frac{1}{2} P_{e,2} = \frac{1}{2} P(r_{1} < 0 \mid m_{1} \text{ sent}) + \frac{1}{2} P(r_{1} > 0 \mid m_{2} \text{ sent})$$

$$= \frac{1}{2} P(A + n_{1} < 0) + \frac{1}{2} P(-A + n_{1} > 0)$$

$$= \frac{1}{2} P\left(\frac{n_{1}}{|N_{0}|^{2}} < \frac{-A}{|N_{0}|^{2}}\right) + \frac{1}{2} P\left(\frac{n_{1}}{|N_{0}|^{2}} > \frac{A}{|N_{0}|^{2}}\right)$$

$$= \frac{1}{2} \Theta\left(\frac{A}{|N_{0}|^{2}}\right) + \frac{1}{2} O\left(\frac{A}{|N_{0}|^{2}}\right)$$



$$P_e = Q\left(\sqrt{\frac{2E_b}{N_o}}\right) = Q\left(\sqrt{2V_b}\right)$$

- QPSK (M=4):

$$P_{e,1} = 1 - P_{c,1} = 1 - P(r_1 > r_2 \& r_1 > -r_2 | m_1 \text{ sent})$$

=
$$1 - P\left(\frac{n_1 - n_2}{N(0, N_0)} - A & \frac{n_1 + n_2}{N(0, N_0)} - A\right)$$

=
$$1 - P(n_1 - n_2 > -A)P(n_1 + n_2 > -A)$$

$$= 1 - \beta \left(\frac{A}{\sqrt{N_0}} \right) \beta \left(\frac{A}{\sqrt{N_0}} \right)$$

independent
$$n_{1} \sim N\left(0, \frac{N_{0}}{2}\right), n_{2} \sim N\left(0, \frac{N_{0}}{2}\right)$$

$$E\{(n_4-n_2)(n_4+n_2)\}$$

$$=E\{n_4^2-n_2^2\}=E\{n_4^2\}-E\{n_2^2\}=0$$

Since
$$E_S = A^2$$
, $P_{e,A} = 1 - \left(Q\left(-\sqrt{\frac{E_S}{N_o}}\right)\right)^2$.



So,
$$P_e = 1 - \left[1 - B_s \left(\frac{E_s}{No}\right)^2\right]$$

$$=1-\left[1-O_{1}(\overline{N}_{5})\right]^{2}$$

$$=1-\Gamma_{4}-Q(\sqrt{2}\sigma_{b})]^{2}$$

$$= 1 - \left[1 - O_1(\overline{N_s})\right]^2 \qquad \forall_s = \frac{E_s}{N_0} \rightarrow SNR \text{ per symbol}$$

=1-
$$\left[1-Q(\sqrt{2\delta_b})\right]^2$$
 Since $E_b = \frac{E_s}{2}$, $\delta_s = 2\delta_b$

Alternatively,
$$P_e = 2 \Theta_s \left(\sqrt{\frac{E_s}{N_o}} \right) - \Theta^2 \left(\sqrt{\frac{E_s}{N_o}} \right)$$
.

With gray encoding, assuming errors only between adjacent symbols

at high SNRs
$$\rightarrow P_b = \frac{1}{2}P_e = Q(\sqrt{\frac{2E_b}{N_o}})$$
 ~ same as BPSK!



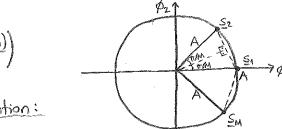
MPSK (M>4):

Since exact expression is difficult, we use the union bound.

$$P_{e,1} \leq \sum_{k=2}^{M} \Theta\left(\frac{\|S_1 - S_k\|}{\sqrt{2N_0}}\right)$$

 $\|\underline{s}_1 - \underline{s}_2\| = \|\underline{s}_1 - \underline{s}_M\| = 2 A \sin\left(\frac{\pi}{M}\right)$

bound (see p.\$)



Nearest neighbor approximation:

$$P_{e,a} \approx 2 Q \left(\frac{2 A sm(T/M)}{\sqrt{2W_0}} \right)$$

$$P_{e} \approx M_{d_{min}} Q\left(\frac{d_{min}}{\sqrt{2No}}\right)$$

$$= \frac{1}{11} \int_{0}^{\infty} \exp\left\{-\frac{\sin^{2}(\pi/M)}{\sin^{2}\phi}\right\} d\phi$$

$$= \frac{1}{11} \int_{0}^{\infty} \exp\left\{-\frac{\sin^{2}(\pi/M)}{\sin^{2}\phi}\right\} d\phi$$

Due to symmetry, Pe, = ···= Pe, m = Pe.

$$P_{e} \approx 2 Q \left(\frac{\sqrt{2} A \sin(\pi/M)}{\sqrt{N_{o}}} \right) = 2 Q \left(\sqrt{2} \delta_{s} \sin(\pi/M) \right) \qquad \delta_{s} = \frac{E_{s}}{N_{o}} = \frac{A^{2}}{N_{o}}$$

$$\delta_s = \frac{E_s}{N_0} = \frac{\Lambda^2}{N_0}$$

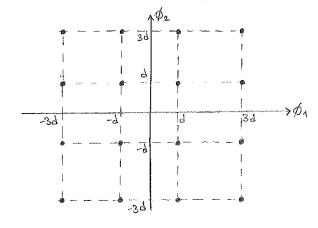
M-ARY QUADRATURE AMPLITUDE MODULATION (QAM):

- $S_i(t) = A_i \cos \theta_i$ gltl $\cos(2\pi f_c t) A_i \sin \theta_i$ gltl $\sin(2\pi f_c t)$, $t \in [0, T_c)$, i = 1, ..., M.
- Orthonormal basis functions: (M(t)=g(t) cos (211fct), (M(t)=-g(t) sin (211fct).

$$S_{i} = \begin{bmatrix} S_{i1} \\ S_{i2} \end{bmatrix} = \begin{bmatrix} A_{i} \cos \theta_{i} \\ A_{i} \sin \theta_{i} \end{bmatrix}, \quad i=1,...,M$$

consider similar arguments as in

- Energy of sitt): $E_{s_i} = ||s_i||^2 = A_i^2$
- Square constellation: Even number of bits (log_M > even) Cross constellation: Odd number of bits (log_M - odd)
- Ex. M=16 (4 bits/symbol)



For square constellations:

MQAM = LPAM x LPAM

 $M = L^2$

· Probability of Error:

Consider square constellation with M=L2,

MO, AM = LPAM x LPAM ~ [Ai = (2i-1-L)d, i=1,...,L & for each (in-phase & quadrature).

Prob. of correct decision for LPAM:

$$1 - \frac{2(L-1)}{L} O\left(\frac{2d^2}{N_0}\right)$$
 < Z see page \triangle .

Prob. of correct decision for MO, AM:

$$P_c = \left(1 - \frac{2(L-1)}{L} \Theta\left(\sqrt{\frac{2d^2}{N_0}}\right)^2\right)$$

Prob. of error for MO,AM:

$$P_{e} = 1 - P_{c}$$

$$= \left| \frac{4(\sqrt{M'-1})}{\sqrt{M}} O_{s} \left(\sqrt{\frac{2d^{2}}{N_{o}}} \right) - \frac{4(\sqrt{M-1})^{2}}{M} O_{s}^{2} \left(\sqrt{\frac{2d^{2}}{N_{o}}} \right) \right|$$

At high SNRs
$$\rightarrow P_e \approx 4\left(1-\frac{1}{\sqrt{M}}\right) O_s\left(\sqrt{\frac{2d^2}{No}}\right)$$

$$P_e \approx 4\left(1 - \frac{1}{\sqrt{M}}\right) Q\left(\frac{3\overline{8}_s}{M-1}\right)$$

• Average energy of MQAM signals:
$$\underline{S}_{1} = \begin{bmatrix} \mp (2j-1)d \\ \mp (2\ell-1)d \end{bmatrix}, \quad j=1,...,1/2$$

$$\overline{E}_{s} = \frac{1}{M} \sum_{j=1}^{M} \frac{\|S_{i}\|^{2}}{\sum_{j=1}^{2} \sum_{\ell=1}^{2} \left[(2_{j} - 1)^{2} + (2\ell - 1)^{2} \right] d^{2}}$$
where $\left[\frac{4}{M} \sum_{j=1}^{M} \sum_{\ell=1}^{M} \left[(2_{j} - 1)^{2} + (2\ell - 1)^{2} \right] d^{2} \right]$

Exercise
$$= \frac{4}{M} \int_{j=1}^{L/2} \frac{L/2}{e^{-1}} \left[(2j-1)^2 + (2\ell-1)^2 \right] d^2$$

$$= \frac{2 d^2 (M-1)}{3}$$

$$= \frac{2 d^2 (M-1)}{3}$$

1 Acas (27/1/1+94)

FREQUENCY-SHIFT KEYING (FSK):

 $S_{i}(t) = A \cos(2\pi f_{i}t + \varphi_{i})$, $t \in [0, T_{s})$, i = 1, 2, ..., M.

Each symbol corresponds to a different frequency fi. \$i: Phase of the ith cornier.

First, assume that the value of Q is known at the receiver (via phase estimation). ⇒ Coherent receiver: A receiver that uses the phase info.

Assume fitfs Vitj and fits -integer Vi.

Then
$$V_i(t) = \sqrt{\frac{2}{T_s}} \cos(2\pi f_i t + Q_i)$$
, $t \in [0, T_s]$, $i = 1, ..., M$

Orthonormal basis functions: M(+),..., M(+).

$$\int_{T_s}^{T_s} \gamma_i(t) \gamma_i(t) dt = \frac{2}{T_s} \int_{0}^{T_s} \cos(2\pi f_i t + \phi_i) \cos(2\pi f_i t + \phi_i) dt$$

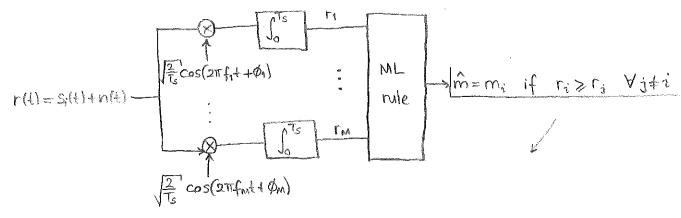
$$= \frac{1}{T_{s}} \int_{-T_{s}}^{T_{s}} \left[\cos \left(2\pi (f_{i} + f_{i}) + \phi_{i} + \phi_{i} \right) + \cos \left(2\pi (f_{i} - f_{i}) + \phi_{i} - \phi_{i} \right) \right] dt = \begin{cases} 0, & \text{if } i \neq j \\ 1, & \text{if } i = j \end{cases}$$

• S_=[A√Ts/2 0...0] S2=[0 A√Ts/2 0...0] ... SM=[0...0 A√Ts/2]

<u> 15</u>

· Optimal coherent FSK receiver

(Assume equal priors)



ML rule: Choose mi if III-sill < III-sill, Viti

$$\left(\underline{r}^{T}\underline{s}_{i} = \int_{C} (H s_{i} H) dH = \underbrace{A \sqrt{\frac{r}{2}} \int_{C} (H) \phi_{i} H) dH}_{E} \right) = \underbrace{2 \underbrace{r}^{T}\underline{s}_{i} + \|\underline{s}_{i}\|^{2}}_{E.r_{i}} + \underbrace{-2 \underbrace{r}^{T}\underline{s}_{i}}_{E.r_{i}} + \underbrace{-2 \underbrace{r}^{T}\underline{s}_{i}}_{E.r$$

• Let $f_i = f_c + \alpha_i \Delta f_c$, i = 1,...,MThen, $s_i(t) = A \cos(2\pi f_c t + 2\pi \alpha_i \Delta f_c t + \phi_i)$, $t \in [0,T_s]$, i = 1,...,Mwith $\alpha_i = (2i-1-M)$. Frequency spacing of $2\Delta f_c$

· Minimum-Shift Keying (MSK):

A special case of binary FSK where $\phi_1 = \phi_2$, and $|f_1 - f_2| = \frac{1}{2T_s}$. Let $\phi_1 = \phi_2 = 0$. $|s_1 + t| = A \cos(2\pi f_1 + t)$, $|s_2 + t| = A \cos(2\pi f_2 + t)$, $|t| = A \cos(2\pi f_2 + t)$.

$$\langle S_1(H), S_2(H) \rangle = \int_0^{T_S} A^2 \frac{1}{2} \left[\cos \left(2\pi (f_1 + f_2) + \right) + \cos \left(2\pi (f_1 - f_2) + \right) \right] dH = 0$$
Half osc. over [0, T_S]

* 1/216 is the minimum freq. separation in FSK to provide orthogonality.

· Non-coherent receiver for FSK:

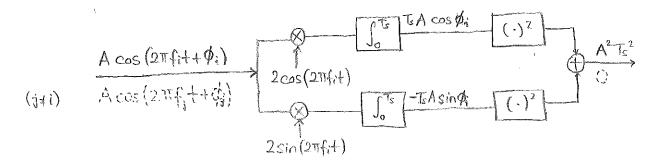
A non-coherent receiver doesn't use the phase information.

Advantage: No need for phase estimation at the receiver -> less complex/costly Disadvantage: Worse error performance than a coherent receiver.

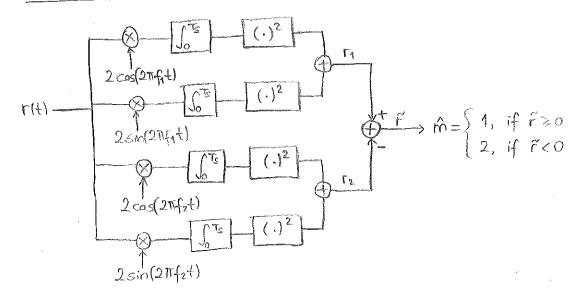
$$S_1(t) = A \cos(2\pi f_1 t + \phi_1)$$

= $A \cos \phi_1 \cos(2\pi f_1 t) - A \sin \phi_1 \sin(2\pi f_1 t)$

Since ϕ_i is unknown for a non-coherent receiver, we should correlate with both $\cos(2\pi f_i t)$ and $\sin(2\pi f_i t)$ to collect all the energy of the signal. To provide intuition, ignore noise and consider the following:

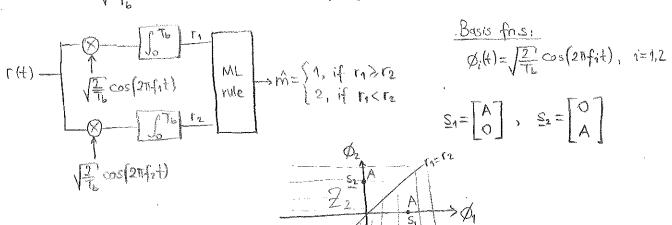


Non-coherent BFSK receiver:



· Error Probability for Coherent BFSK:

$$S_1(t) = A\sqrt{\frac{2}{T_b}}\cos(2\pi f_1 t)$$
, $S_2(t) = A\sqrt{\frac{2}{T_b}}\cos(2\pi f_2 t)$, $t \in [0, T_b)$





$$P_{e,1} = P(r_1 < r_2 \mid m_1 \text{ sent})$$

$$= P(A + n_1 < 0 + n_2) = P(\underbrace{n_2 - n_1} > A) = P(\underbrace{n_2 - n_1} > \underbrace{A}_{NN_0})$$

$$= Q(\underbrace{A}_{NN_0})$$

$$P_{e,2} = P(r_1 > r_2 \mid m_2 \text{ sent}) = P(O + n_1 > A + n_2) = P(n_1 - n_2 > A) = Q(\underbrace{A}_{NN_0})$$

$$P_{e,2} = Q(\underbrace{A}_{NN_0}) = Q(\underbrace{NN_0}) = Q(\underbrace{NN_0})$$

$$E_b = A^2 \leftarrow bit \text{ energy}$$

$$\delta_b = \underbrace{E_b}_{N_0} \leftarrow \text{SNR} \text{ per bit}$$

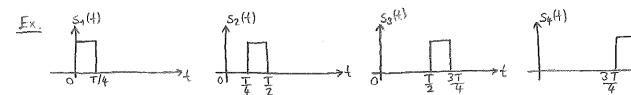
(compared to BPSK, BFSK needs 3dB more SNR to achieve the same) error rate. BPSK $\rightarrow P_e = O(\sqrt{206})$

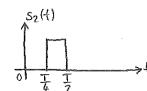
FSK is an example of orthogonal signaling.

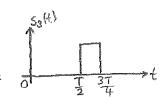
In general, M-ary orthogonal signals satisfy

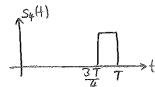
$$\int_{0}^{T} S_{i}(t) S_{j}(t) dt = 0 \quad \forall j \neq i$$

Basis functions: $V_i(H) = \frac{S_i(H)}{\sqrt{E_{S_i}}}$, $i=1,...,M \rightarrow M$ -dimensional signal space.

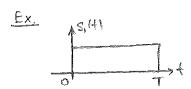


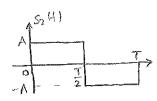


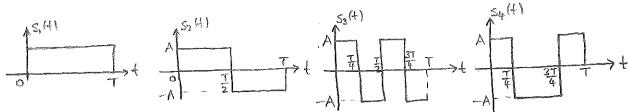


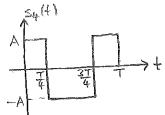


Pulse position modulation (PPM).





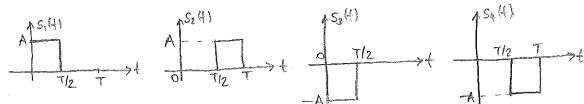


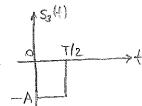


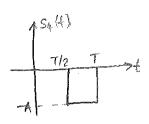
Biorthogonal Signals:

Constructed from M/2 orthogonal signals and their negatives.

$$S_1(t), \ldots, S_{MR}(t), S_1(t), \ldots, -S_{MR}(t)$$
 $t \in [0, T_6]$







Simplex Signals:

constructed from M orthogonal signals by subtracting the average of the M orthogonal signals from each signal.

$$S_i(t) = S_i(t) - \frac{1}{M} \sum_{k=1}^{M} S_k(t)$$

 $\tilde{\mathcal{E}}_{s} = \int^{T_{s}} \left(s_{i}(t) - \frac{1}{M} \sum_{k=1}^{M} s_{k}(t) \right)^{2} dt = \int^{T_{s}} s_{i}^{2}(t) dt - \frac{2}{M} \sum_{k=1}^{M} \int_{s_{i}}^{T_{s}} s_{i}(t) s_{k}(t) dt + \frac{1}{M^{2}} \sum_{k=1}^{M} \int_{s_{i}}^{T_{s}} s_{k}(t) s_{k}(t) dt$ $= E_s - \frac{2}{M} E_s + \frac{1}{M^2} M. E_s = (1 - \frac{1}{M}) E_s$ teach signal has smaller energy

$$\int_{S_{i}}^{S_{i}}(t)S_{j}(t)dt = \left| \frac{E_{s}}{M-1}, if i\neq j \right|$$

COMPARISON OF MODULATION METHODS:

- · Consider fixed bit rate Rb.
- · Required channel bandwidth for transmission:

-M-PAM: Pulse duration:
$$T_s \rightarrow Bandwidth \approx \frac{1}{2T_s}$$

$$\log_2 M \text{ bits per symbol} \rightarrow T_s = \frac{\log_2 M}{R_b}$$

$$W = \frac{R_b}{2 \log_2 M} \leftarrow \frac{multiply}{by 2 for}$$

$$double-sideband$$

$$-\frac{Q.AM:}{T_s}, \quad T_s = \frac{2 \log_2 M_{PAM}}{R_b} \Rightarrow W = \frac{R_b}{2 \log_2 M_{PAM}} = \frac{R_b}{\log_2 M_{QAM}}$$
due to two

$$\frac{-M-PSK:}{(M>2)}W = \frac{1}{T_S}, T_S = \frac{log_2M}{R_b} \Rightarrow W = \frac{R_b}{log_2M}$$

$$-\frac{M-FSK:}{2} = \frac{M}{2T_S} = \frac{M}{2 \frac{\log_2 M}{R_b}} = \frac{MR_b}{2 \log_2 M}$$

Valid for <u>orthogonal signaline</u> in general

• for compact and meaningful companison, consider <u>normalized data rate</u> (spectral bit rate): versus SNR per bit (Eb/No).

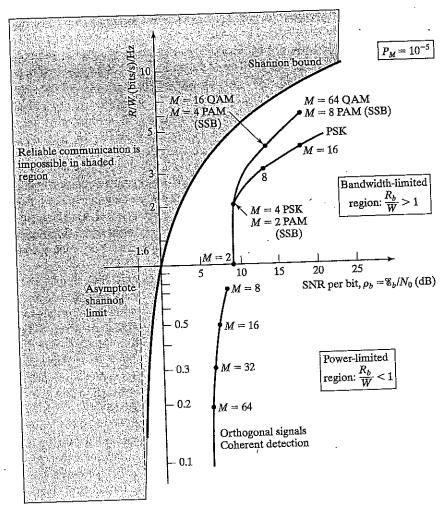


Figure 9.29 Comparison of several modulation methods at 10^{-5} symbol rate.

TABLE 9.2 QAM SIGNAL CONSTELLATIONS

Number of signal points M	Increase in average power (dB) relative to $M=2$
4	3
8	6.7
16	10.0
32	13.2
64	16.2
128	19.2