

# FALL 2021 - EEE 473/573 Medical Imaging

## HW1 Solutions

### 1

There are endless possibilities of images.

### 2

a) **Linearity:** Let  $g'(x, y)$  be the response of the system to the input  $f'(x, y) = \sum_{k=1}^K w_k f_k(x, y)$ :

$$\begin{aligned} g'(x, y) &= f'(x, -1) + f'(0, y) = \sum_{k=1}^K w_k f_k(x, -1) + \sum_{k=1}^K w_k f_k(0, y) \\ &= \sum_{k=1}^K w_k (f_k(x, -1) + f_k(0, y)) = \sum_{k=1}^K w_k g_k(x, y), \end{aligned}$$

where  $g_k(x, y) = f_k(x, -1) + f_k(0, y)$ . So, the system is LINEAR.

**Shift Invariance:** Let  $g'(x, y)$  be the response of the system to the input  $f'(x, y) = f(x - x_0, y - y_0)$ :

$$\begin{aligned} g'(x, y) &= f'(x, -1) + f'(0, y) = f(x - x_0, -1 - y_0) + f(-x_0, y - y_0) \\ &\neq g(x - x_0, y - y_0), \end{aligned}$$

where  $g(x - x_0, y - y_0) = f(x - x_0, -1) + f(0, y - y_0)$ . So, the system is NOT SHIFT INVARIANT.

b) **Linearity:** Let  $g_k(x, y) = \max\{f_k(x, y), 0\}$ , and let  $g'(x, y)$  be the response of the system to the input  $f'(x, y) = \sum_{k=1}^K w_k f_k(x, y)$

$$\begin{aligned} g'(x, y) &= \max\{f'(x, y), 0\} = \max\left\{\sum_{k=1}^K w_k f_k(x, y), 0\right\} \\ &\neq \sum_{k=1}^K w_k \max\{f_k(x, y), 0\} = \sum_{k=1}^K w_k g_k(x, y). \end{aligned}$$

So, the system is NOT LINEAR. <sup>1</sup>

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<sup>1</sup>At first sight, the system may look linear. In fact, if all  $f_k(x, y) = h(x, y)$  (i.e., if all  $f_k(x, y)$  are identical), then the system will be linear. Otherwise, the system will not be linear. For example, for  $f_1(x, y) = x$ , and  $f_2(x, y) = \sin(x)$ , one can see that the system is not linear.

**Shift Invariance:** Let  $g'(x, y)$ , be the response of the system to the input  $f'(x, y) = f(x - x_0, y - y_0)$ ,

$$g'(x, y) = \max(f'(x, y), 0) = \max(f(x - x_0, y - y_0), 0) = g(x - x_0, y - y_0).$$

So the system is SHIFT INVARIANT.

### 3

Given  $f(x, y) = e^{j2\pi(x+y)}$ , evaluate the following for given  $x_1$  and  $y_1$ :

- a)  $f(x, y)\delta(x - x_1, y + y_1) = e^{j2\pi(x_1 - y_1)}\delta(x - x_1, y + y_1)$
- b)  $f(x, y) * \delta(x - x_1, y + y_1) = f(x - x_1, y + y_1) = e^{j2\pi(x - x_1 + y + y_1)}$
- c)  $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \delta(x - x_1, 3y + y_1) f(x, y) dx dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{1}{3} \delta(x - x_1, y + \frac{y_1}{3}) f(x, y) dx dy = \frac{e^{j2\pi(x_1 - \frac{y_1}{3})}}{3}$
- d)  $f(x + 1, -y_1) * \delta(x - x_1, y + 1) = f(x - x_1 + 1, -y_1) = e^{j2\pi(x - x_1 + 1 - y_1)}$

### 4

Find the 2D Fourier transforms of the following continuous signals:

- a) Using the scaling and sifting property of the impulse:

$$\begin{aligned} G(u, v) &= \mathcal{F}\left\{\delta\left(\frac{x}{x_1}, y_1 y - 1\right)\right\} \\ &= \left|\frac{x_1}{y_1}\right| \mathcal{F}\left\{\delta\left(x, y - \frac{1}{y_1}\right)\right\} \\ &= \left|\frac{x_1}{y_1}\right| e^{j2\pi \frac{v}{y_1}} \end{aligned}$$

- b) Using the linearity property of FT and the transform table:

$$G(u, v) = \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \delta(u - n, v - m)$$

- c) Using the scaling and shifting properties of FT and the transform table:

$$G(u, v) = \left|\frac{1}{3y_1}\right| e^{-j2\pi(-\frac{ux_1}{3} + \frac{v}{y_1})} \text{rect}\left(\frac{u}{3}, \frac{v}{y_1}\right)$$

- d) Using the scaling and product properties of FT and the transform table:

$$\begin{aligned} G(u, v) &= \mathcal{F}\left\{\text{rect}\left(x_1 x, \frac{y}{y_1}\right) e^{j2\pi(u_0 x + 4v_0 y)}\right\} \\ &= \mathcal{F}\left\{\text{rect}\left(x_1 x, \frac{y}{y_1}\right)\right\} * \mathcal{F}\left\{e^{j2\pi(u_0 x + 4v_0 y)}\right\} \\ &= \left|\frac{y_1}{x_1}\right| \text{sinc}\left(\frac{u}{x_1}, y_1 v\right) * \delta(u - u_0, v - 4v_0) \\ &= \left|\frac{y_1}{x_1}\right| \text{sinc}\left(\frac{u - u_0}{x_1}, y_1(v - 4v_0)\right) \end{aligned}$$

e) Using the scaling and convolution properties of FT and the transform table:

$$\begin{aligned}
\mathcal{F}\{e^{-2\pi(4x^2+y^2)} * \cos(2\pi x + \pi y)\} &= \mathcal{F}\{e^{-2\pi(4x^2+y^2)}\} \mathcal{F}\{\cos(2\pi x + \pi y)\} \\
&= \mathcal{F}\{e^{-\pi((2\sqrt{2}x)^2 + (\sqrt{2}y)^2)}\} \frac{1}{2} \left( \delta(u-1, v-\frac{1}{2}) + \delta(u+1, v+\frac{1}{2}) \right) \\
&= \frac{1}{4} e^{-\pi((\frac{u}{2\sqrt{2}})^2 + (\frac{v}{\sqrt{2}})^2)} \frac{1}{2} \left( \delta(u-1, v-\frac{1}{2}) + \delta(u+1, v+\frac{1}{2}) \right) \\
&= \frac{1}{8} e^{-\pi(1/8+1/8)} \delta(u-1, v-\frac{1}{2}) + \frac{1}{8} e^{-\pi(1/8+1/8)} \delta(u+1, v+\frac{1}{2}) \\
&= \frac{e^{-\pi/4}}{8} \left( \delta(u-1, v-\frac{1}{2}) + \delta(u+1, v+\frac{1}{2}) \right)
\end{aligned}$$

f)

$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy$$

and  $f(x, y)$  is a real-valued signal,

i.

$$\begin{aligned}
F^*(u, v) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} [f(x, y) e^{-j2\pi(ux+vy)}]^* dx dy \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f^*(x, y) e^{j2\pi(ux+vy)} dx dy \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{j2\pi(ux+vy)} dx dy, \text{ since } f(x, y) \text{ is real valued,} \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(-\xi, -\zeta) e^{-j2\pi(u\xi+v\zeta)} d\xi d\zeta, \text{ with } \xi = -x \text{ and } \zeta = -y, \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\xi, \zeta) e^{-j2\pi(u\xi+v\zeta)} d\xi d\zeta, \text{ since } f(x, y) = f(-x, -y), \\
&= F(u, v).
\end{aligned}$$

ii. Very similar to (i).

## 5

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