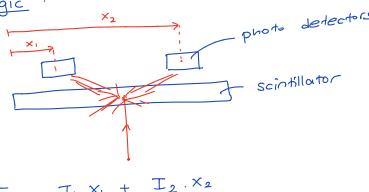


Positioning Logic :

in 10:



$$\overline{X} = \underline{I_1. \times_1 + I_2. \times_2}$$

$$\overline{I_1 + I_2}$$

Image Formation:

Evert position Estimation:

* the height of the response from each photomultiplier tube is related to its distance to the scintillation

ak: amplitude response from photomultiplier tuke k of (xeige): positions

 $\frac{K}{2} = \frac{K}{2} a_k \qquad \text{i total amplitude response}$ $\frac{K}{k=1} \qquad \text{i mass'' of the light distribution}$

 $X = \frac{1}{2} \sum_{k=1}^{K} x_k \alpha_k$ The,

 $y = \frac{1}{7} \stackrel{K}{\leq} y_k \alpha_k$

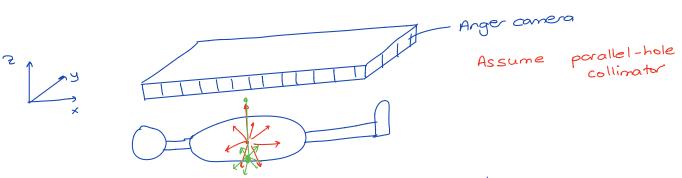
"Certer of mass" equations

(x, y, Z)
position amplitude of signal

Radioactivity in the body: A(x,y,12)

Energy of each photon (Y-ray photon) : E

We want to image: photon fluence rate coming from the patient # of photons per unit area per unit time.



* For radioactivity at point (x,y,7) only:

the body = attenuation along directions the line

in line with the collimation: * Combine all sources

This is like projection *

- Simpler because energy range is restricted
- more complex because two sources of depth-dependent signal loss:
 - 1) inverse square law
 - 2) object dependent attenuation
- -> Activity close to the camera contributes more to the image.

Planar source: a simplified case

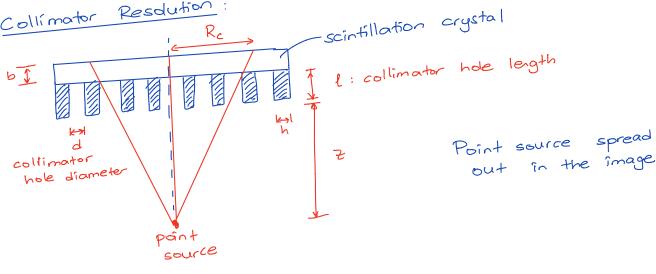
$$A(x,y,z) = A_{z_0}(x,y) \cdot \delta(z-z_0)$$

Even for planar source, intensity depends on Malong the path, which is not uniform.

(3)

Image Quality: resolution vs. sensitivity trade-off

Collimator Resolution:



from geometry:
$$\frac{d}{l} = \frac{R_c}{l+b+|2|}$$

$$R_{c} = \frac{d}{\ell} \left(\ell + b + |z| \right)$$

resolution depends on depth [2]

So, targets farther away are blurred more.

Solution? make collimator hole longer: l -> 21

make collimans
$$R_{c} = \frac{d}{2l} \left(2l + b + |z| \right) = d + \frac{b + |z|}{2l}$$

$$R_{c} = \frac{d}{2l} \left(2l + b + |z| \right) = d + \frac{b + |z|}{2l}$$

=> reduces sensitivity. fewer activity is detected.

* limit to resolution Rc: limit to resolution

* making d smaller reduces sensitivity: less events

Trade-off between resolution and sensitivity.

* Collimator PSF ~ Gaussian with FWHM = Rc Remember: for a Gaussian function FWHM = 2 T V2 In2

So,
$$h_c(x,y;|z|) = exp \left\{ -4(x^2+y^2) \ln 2/R_c^2(|z|) \right\}$$
depends on source depth

* Additional blurring in scintillator itself

-> called the intrinsic resolution of the Anger camera Also modeled as a Gaussian:

modeled as a Gaussian h_I (x,y) = exp
$$\{-4(x^2+y^2) \ln 2/2I^2\}$$

T does not depend on source depth

4 So, for a planar source: $A(x_1y_1z) = A_{20}(x_1y_1) \delta(z_1-z_0)$

Typically, RI 24 Rc. So, collimator's response dominates.

SNR: SNR $\propto \sqrt{N}$ mean total number of acquired photons