

Q1HW#3Efe Eren Ceylan
21503359

$$f(x, y) \rightarrow g(l, \theta)$$

$$f(x-x_0, y-y_0) \rightarrow ?$$

$$h(x, y) = f(x-x_0, y-y_0) \quad , \quad h(x, y) \rightarrow k(l, \theta)$$

$$\mathcal{R}\{h(x, y)\} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(x, y) \delta(x \cos \theta + y \sin \theta - l) dx dy$$

$$k(l, \theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x-x_0, y-y_0) \delta(x \cos \theta + y \sin \theta - l) dx dy$$

$$x' = x - x_0$$

$$y' = y - y_0$$

$$k(l, \theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x', y') \delta(x' \cos \theta + x_0 \cos \theta + y' \sin \theta + y_0 \sin \theta - l) dx' dy'$$

$$k(l, \theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x', y') \delta(\underbrace{l - x_0 \cos \theta - y_0 \sin \theta}_{\text{new line argument}} - (x' \cos \theta + y' \sin \theta)) dx' dy'$$

$$\Rightarrow k(l, \theta) = \boxed{\mathcal{R}\{f(x-x_0, y-y_0)\} = g(l - x_0 \cos \theta - y_0 \sin \theta, \theta)}$$

Q2 $f(x,y) = e^{-\frac{x^2+y^2}{2}}$

Efe Eren Ceylan
21903359

a) Let's find $F(u,v)$.

$$f(x,y) = e^{-\frac{x^2+y^2}{2}} = e^{-\pi \left(\left(\frac{x}{\sqrt{2\pi}} \right)^2 + \left(\frac{y}{\sqrt{2\pi}} \right)^2 \right)} \xleftrightarrow{2D \text{ FT}} F(u,v) = 2\pi e^{-2\pi^2(u^2+v^2)}$$

$$F(\rho) = 2\pi e^{-2\pi^2 \rho^2}$$

No θ dependence

Projection
slice

$$F(\rho \cos \theta, \rho \sin \theta) = F(u,v) = G(\rho, \theta) = 2\pi e^{-2\pi^2 \rho^2} = 2\pi e^{-\pi (\sqrt{2\pi} \rho)^2}$$

\uparrow 1D FT

$$g(l, \theta) = \sqrt{2\pi} e^{-\frac{l^2}{2}}$$

b) $w(\rho) = e^{-\frac{\rho^2}{4}} = e^{-\pi \left(\frac{\rho}{2\sqrt{\pi}} \right)^2} \xleftrightarrow{1D \text{ FT}} 2\sqrt{\pi} e^{-4\pi^2 \rho^2} = w(l)$

$$\hat{f}(x,y) = f(x,y) * \mathcal{R}^{-1} \{ \tilde{h}(l) \}, \quad \tilde{h}(l) = w(l)$$

$$\Rightarrow h(r) = \mathcal{F}^{-1}(w(\rho))$$

$$h(r) = 4\pi e^{-4\pi^2 r^2}$$

$$\hat{f}(x,y) = e^{-\pi \left(\left(\frac{x}{\sqrt{2\pi}} \right)^2 + \left(\frac{y}{\sqrt{2\pi}} \right)^2 \right)} * 4\pi e^{-\pi \left((2\sqrt{\pi}x)^2 + (2\sqrt{\pi}y)^2 \right)}$$

$$\hat{f}(u,v) = 2\pi e^{-2\pi^2(u^2+v^2)} \cdot 4\pi \cdot \frac{1}{4\pi} e^{-\frac{1}{4}(u^2+v^2)} = 2\pi e^{-(u^2+v^2) \left(2\pi^2 + \frac{1}{4} \right)}$$

$$= 2\pi e^{-\pi \left(\left(\sqrt{\frac{a}{\pi}} u \right)^2 + \left(\sqrt{\frac{a}{\pi}} v \right)^2 \right)}$$

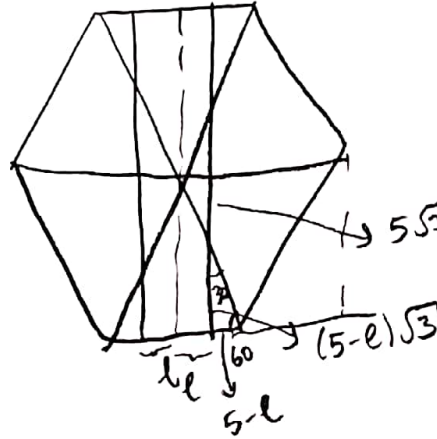
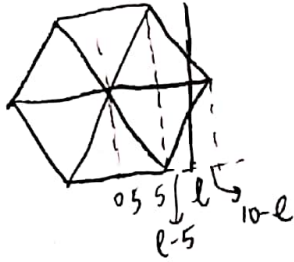
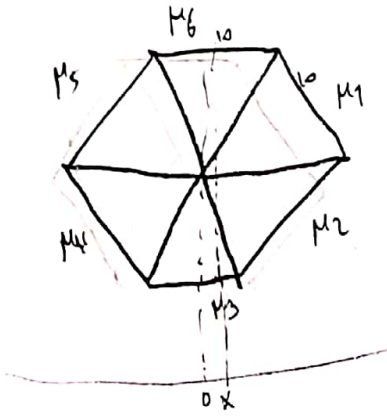
\uparrow 2D FT

$$\hat{f}(x,y) = \frac{2\pi^2}{a} e^{-\frac{\pi^2}{a}(x^2+y^2)}$$

$$\hat{f}(x,y) = \frac{2\pi^2}{2\pi^2 + \frac{1}{4}} e^{-\frac{\pi^2}{2\pi^2 + \frac{1}{4}}(x^2+y^2)}$$

Q3

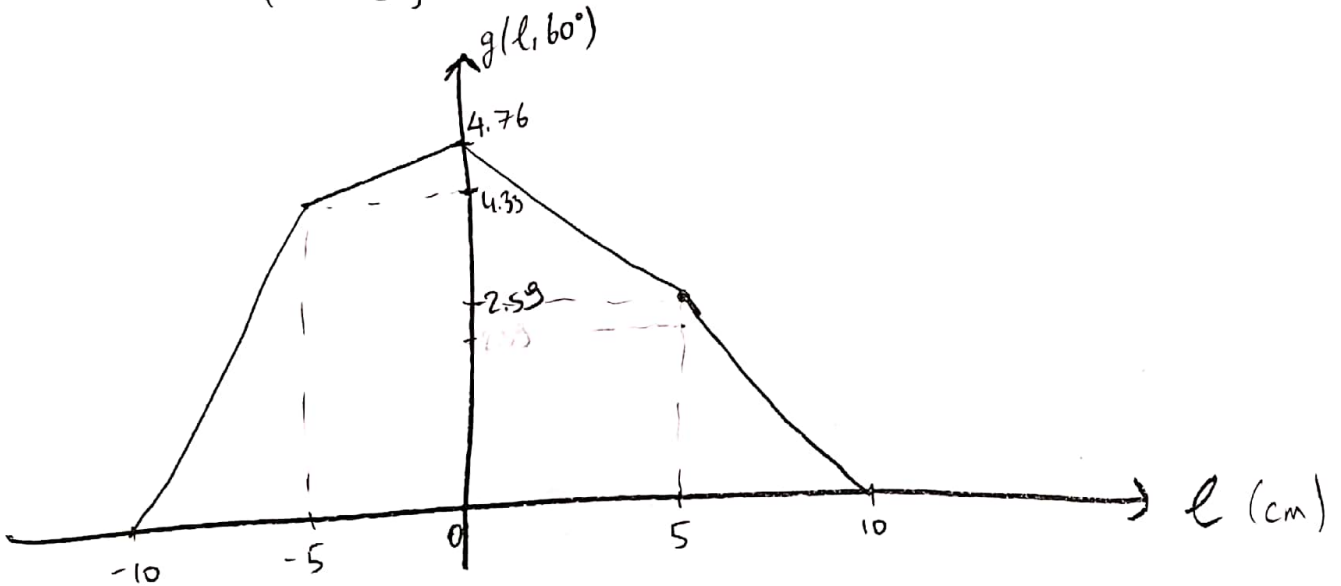
Efe Eren Ceylan
21903359



$$5\sqrt{3} - 5\sqrt{3} + l\sqrt{3} = l\sqrt{3}$$

$$\begin{aligned}\mu_1 + \mu_2 &= 0.3 \\ \mu_3 + \mu_6 &= 0.55 \\ \mu_4 + \mu_5 &= 0.5\end{aligned}$$

$$g(l, 60^\circ) = \begin{cases} (5-l)\sqrt{3}(\mu_3 + \mu_6) + l\sqrt{3}(\mu_1 + \mu_2), & 0 \leq l < 5 \\ (10-l)\sqrt{3}(\mu_1 + \mu_2), & 5 \leq l \leq 10 \\ (5+l)\sqrt{3}(\mu_3 + \mu_6) - l\sqrt{3}(\mu_4 + \mu_5), & -5 \leq l < 0 \\ (10+l)\sqrt{3}(\mu_4 + \mu_5), & -10 \leq l < -5 \\ 0, & \text{o.w.} \end{cases}$$



Q4

Efe Eren Ceylan
21903353

a) The smallest ~~FOV's~~ ^{width-length} ~~width~~ is 10cm.

So, we must at least use a detector array which is 20cm long.

b) $N_{proj} \geq \frac{\pi}{2} N_{points} \Rightarrow N_{projmin} = 403$

$$\Delta x = \frac{FOV}{256} = \frac{20cm}{256} = 0.078cm$$

Small pixel width \Rightarrow Better Resolution