

IE 411: Introduction to Nonlinear Optimization

Fall 2022 - Homework Assignment 5

Due: December 20 2022

Question 1. Consider the optimization problem:

$$\begin{aligned} &\text{minimize} && x_1 - 4x_2 + x_3 \\ &\text{subject to} && x_1 + 2x_2 + 2x_3 = -2 \\ &&& x_1^2 + x_2^2 + x_3^2 \leq 1. \end{aligned}$$

- a) Given a KKT point of this problem, must it be an optimal solution? Explain/show your reasoning.
- b) Solve the problem using KKT conditions.

Sol:

- a)
 - $x_1 - 4x_2 + x_3, x_1^2 + x_2^2 + x_3^2 - 1$ are continuously differentiable convex functions over \mathbb{R}^3 , (first one is an affine function and the second one is $\|\mathbf{x}\|^2 - 1$),
 - $x_1 + 2x_2 + 2x_3 + 2$ is an affine function.

Hence KKT points are sufficient for optimality.

- b) We write KKT conditions,

$$\begin{aligned} \begin{bmatrix} 1 \\ -4 \\ 1 \end{bmatrix} + \lambda \begin{bmatrix} 2x_1 \\ 2x_2 \\ 2x_3 \end{bmatrix} + \mu \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \\ \lambda(x_1^2 + x_2^2 + x_3^2 - 1) &= 0, \\ \lambda &\geq 0. \end{aligned}$$

$\lambda = 0$ is not possible, so we must have $x_1^2 + x_2^2 + x_3^2 = 1$. Then we have the following system of equations,

$$x_1 = \frac{-1 - \mu}{2\lambda}, \quad x_2 = \frac{4 - 2\mu}{2\lambda}, \quad x_3 = \frac{-1 - 2\mu}{2\lambda}.$$

Using this system we obtain the following system,

$$\begin{aligned}\frac{-1-\mu}{2\lambda} + 2\left(\frac{4-2\mu}{2\lambda}\right) + 2\left(\frac{-1-2\mu}{2\lambda}\right) &= -2 \\ \left(\frac{-1-\mu}{2\lambda}\right)^2 + \left(\frac{4-2\mu}{2\lambda}\right)^2 + \left(\frac{-1-2\mu}{2\lambda}\right)^2 &= 1\end{aligned}$$

Then we have only one solution satisfying $\lambda \geq 0$, that is

$$\mu = \frac{5 + 2\sqrt{\frac{137}{5}}}{9} \approx 1.7188, \quad \lambda = \frac{\sqrt{\frac{137}{5}}}{2} \approx 2.6173.$$

x_1, x_2, x_3 can be found accordingly. Due to the choice of λ, μ it will satisfy $x_1 + 2x_2 + 2x_3 = -2$ and $x_1^2 + x_2^2 + x_3^2 = 1$.

Correction: Previously I wrote that there are no feasible KKT points. I made a mistake while calculating the quadratic roots. Nevermind, it is deleted now.

Question 2. Consider the optimization problem:

$$\begin{aligned}\text{minimize} \quad & x_1^2 - x_2^2 - x_3^2 \\ \text{subject to} \quad & x_1^4 + x_2^4 + x_3^4 \leq 1.\end{aligned}$$

- Is this a convex programming problem? Explain/show your reasoning.
- Find all the KKT points of the problem.
- Find the optimal solution of the problem.

Sol:

- Objective is non-convex since Hessian is $\begin{bmatrix} 2 & & \\ & -2 & \\ & & -2 \end{bmatrix}$. So the problem is not a convex problem.

b) We have the KKT conditions

$$\begin{aligned} \begin{bmatrix} 2x_1 \\ -2x_2 \\ -2x_3 \end{bmatrix} + \lambda \begin{bmatrix} 4x_1^3 \\ 4x_2^3 \\ 4x_3^3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \\ \lambda(x_1^4 + x_2^4 + x_3^4 - 1) &= 0 \\ x_1^4 + x_2^4 + x_3^4 - 1 &\leq 0 \\ \lambda &\geq 0. \end{aligned}$$

c) If $\lambda = 0$, then we should have $(0, 0, 0)$ as the KKT point. If $\lambda \neq 0$, then $x_1^4 + x_2^4 + x_3^4 = 1$ and

$$\begin{aligned} 2x_1(2\lambda x_1^2 + 1) &= 0 \\ 2x_2(2\lambda x_2^2 - 1) &= 0 \\ 2x_3(2\lambda x_3^2 - 1) &= 0 \end{aligned}$$

Then $x_1 = 0$, and $x_2, x_3 = \{0, \pm\sqrt{\frac{1}{2\lambda}}\}$, which yields,

λ	x_1	x_2	x_3	Obj
0	0	0	0	0
$\frac{1}{2}$	0	± 1	0	-1
$\frac{1}{2}$	0	0	± 1	-1
$\frac{1}{\sqrt{2}}$	0	$\pm\sqrt[4]{\frac{1}{2}}$	$\pm\sqrt[4]{\frac{1}{2}}$	$-\sqrt{2}$

Therefore the solution is $(0, \pm\sqrt[4]{\frac{1}{2}}, \pm\sqrt[4]{\frac{1}{2}})$ with objective $-\sqrt{2}$.

Question 3. Use KKT conditions to solve the following problem. Explain/show your reasoning in detail.

$$\begin{aligned} \text{minimize} \quad & x_1^4 - x_2^2 \\ \text{subject to} \quad & x_1^2 + x_2^2 \leq 1 \\ & 2x_2 + 1 \leq 0. \end{aligned}$$

Sol: KKT conditions are

$$\begin{aligned}\begin{bmatrix} 4x_1^3 \\ -2x_2 \end{bmatrix} + \lambda_1 \begin{bmatrix} 2x_1 \\ 2x_2 \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \lambda_1(x_1^2 + x_2^2 - 1) &= 0 \\ \lambda_2(2x_2 + 1) &= 0 \\ x_1^2 + x_2^2 &\leq 1 \\ 2x_2 + 1 &\leq 0 \\ \lambda_1, \lambda_2 &\geq 0\end{aligned}$$

Using the fact that $x_1^2 + x_2^2 \leq 1$ we know that

$$x_1^4 - x_2^2 \geq x_1^4 + x_1^2 - x_1^2 - x_2^2 \geq 0 + 0 - 1 \geq -1.$$

So if we show that $(0, -1)$ is a KKT point, then we are done.

$$\begin{aligned}\begin{bmatrix} 0 \\ 2 \end{bmatrix} + \lambda_1 \begin{bmatrix} 0 \\ -2 \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \lambda_2 &= 0 \\ \lambda_1, \lambda_2 &\geq 0\end{aligned}$$

For $\lambda_1 = 1, \lambda_2 = 0$ our point is a KKT point and it attains the lower bound for the objective.

Question 4. Consider the optimization problem:

$$\begin{aligned}\text{minimize} \quad & (x_1 - 3)^2 + (x_2 - 2)^2 \\ \text{subject to} \quad & x_1 + x_2 = 1 \\ & x_1, x_2 \geq 0.\end{aligned}$$

- Solve the problem using KKT conditions. Explain each step clearly.
- Derive the Lagrange dual problem. What can you say about strong duality without solving the dual problem.
- Solve the dual problem.

Sol:

a) We write the KKT conditions

$$\begin{aligned} \begin{bmatrix} 2x_1 - 6 \\ 2x_2 - 4 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \mu \begin{bmatrix} 1 \\ 1 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \lambda_1 x_1 &= 0 \\ \lambda_2 x_2 &= 0 \\ x_1 + x_2 &= 1 \\ x_1, x_2 &\geq 0 \\ \lambda_1, \lambda_2 &\geq 0. \end{aligned}$$

Then we have three cases:

Case 1: $x_1 = 0, x_2 > 0$.

Then we have $x_1 = 0, x_2 = 1, \lambda_1 = -4, \lambda_2 = 0, \mu = 2$ by inspection. INFEASIBLE.

Case 2: $x_1 > 0, x_2 = 0$.

Then we have $x_1 = 1, x_2 = 0, \lambda_1 = 0, \lambda_2 = 0, \mu = 4$ by inspection. KKT POINT.

Case 3: $x_1, x_2 > 0$.

Then we have $x_1 = 1, x_2 = 0, \lambda_1 = 0, \lambda_2 = 0, \mu = 4$ by inspection. INFEASIBLE.

Hence $(1, 0)$ is the optimal solution for the problem with objective 8.

b) Let

$$\begin{aligned} L(x_1, x_2, \lambda_1, \lambda_2, \mu) &= (x_1 - 3)^2 + (x_2 - 2)^2 - \lambda_1 x_1 - \lambda_2 x_2 + \mu(x_1 + x_2 - 1) \\ &= x_1^2 - (6 + \lambda_1 - \mu)x_1 + x_2^2 - (4 + \lambda_2 - \mu)x_2 + 13 - \mu \\ &= \left(x_1 - \frac{6 + \lambda_1 - \mu}{2}\right)^2 + \left(x_2 - \frac{4 + \lambda_2 - \mu}{2}\right)^2 + 13 \\ &\quad - \mu - \left(\frac{6 + \lambda_1 - \mu}{2}\right)^2 - \left(\frac{4 + \lambda_2 - \mu}{2}\right)^2 \\ &\geq 13 - \mu - \left(\frac{6 + \lambda_1 - \mu}{2}\right)^2 - \left(\frac{4 + \lambda_2 - \mu}{2}\right)^2. \end{aligned}$$

$L(x_1, x_2, \lambda_1, \lambda_2, \mu)$ cannot be $-\infty$ for fixed $\lambda_1, \lambda_2, \mu$ so the dual problem turns out to be

$$\max 13 - \mu - \left(\frac{6 + \lambda_1 - \mu}{2} \right)^2 - \left(\frac{4 + \lambda_2 - \mu}{2} \right)^2 \text{ subject to } \lambda_1, \lambda_2 \geq 0, \mu \in \mathbb{R}.$$

- $\{x_1, x_2 : x_1 + x_2 = 1\}$ is a convex set.
- $(x_1 - 3)^2 + (x_2 - 2)^2, -x_1, -x_2$ are convex functions.
- Problem has a finite optimal value (by part a)
- $(x_1, x_2) = (0.5, 0.5)$ satisfies $-x_1 < 0$ and $-x_2 < 0$.

Then by Theorem 12.8 we have strong duality.

- c) We substitute $\max g(\lambda_1, \lambda_2, \mu) = -\min -g(\lambda_1, \lambda_2, \mu)$. Then $-g(\lambda_1, \lambda_2, \mu)$ is a convex function with a convex set so KKT is sufficient. Let $x_1, x_2 \geq 0$ such that KKT conditions are

$$\begin{bmatrix} 1 - \left(\frac{6 + \lambda_1 - \mu}{2} \right) - \left(\frac{4 + \lambda_2 - \mu}{2} \right) \\ \frac{6 + \lambda_1 - \mu}{2} \\ \frac{4 + \lambda_2 - \mu}{2} \end{bmatrix} - x_1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} - x_2 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{aligned} x_1 \lambda_1 &= 0 \\ x_2 \lambda_2 &= 0 \\ \lambda_1, \lambda_2, x_1, x_2 &\geq 0. \end{aligned}$$

Case 1: $\lambda_1, \lambda_2 = 0$.

Then $\mu = 4$ which makes $x_1 = 1, x_2 = 0$ a KKT point. It is sufficient and we stop. It returns -8 as the objective. But the original objective will be 8, as expected due to strong duality.

Question 5. Consider the optimization problem:

$$\begin{aligned} \text{minimize} \quad & x_1^2 + 2x_2^2 + 2x_1x_2 + x_1 - x_2 - x_3 \\ \text{subject to} \quad & x_1 + x_2 + x_3 \leq 1 \\ & x_3 \leq 3. \end{aligned}$$

- a) Is the problem convex?

- b) Find an optimal solution to this problem. Explain each step clearly.
- c) Derive the Lagrange dual problem. What can you say about strong duality without solving the dual problem.
- d) Solve the dual problem.

Sol:

- a) Problem is a minimization problem, it has a convex objective with affine constraints, so it is a convex problem.
- b) KKT conditions are sufficient, so

$$\begin{bmatrix} 2x_1 + 2x_2 + 1 \\ 2x_1 + 4x_2 - 1 \\ -1 \end{bmatrix} + \lambda_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{aligned} \lambda_1(x_1 + x_2 + x_3 - 1) &= 0 \\ \lambda_2(x_3 - 3) &= 0 \\ x_1 + x_2 + x_3 &\leq 1 \\ x_3 &\leq 3 \\ \lambda_1, \lambda_2 &\geq 0 \end{aligned}$$

We have 4 cases:

Case 1: $\lambda_1 = \lambda_2 = 0$.

INFEASIBLE, since first equality returns $-1 = 0$.

Case 2: $\lambda_1 = 0, \lambda_2 > 0$.

Then $\lambda_2 = 1, x_1 = -\frac{3}{2}, x_2 = 1, x_3 = 3$. INFEASIBLE.

Case 3: $\lambda_1 > 0, \lambda_2 = 0$.

Then $\lambda_1 = 1, x_1 = -2, x_2 = 1, x_3 = 2$. KKT POINT.

Case 4: $\lambda_1, \lambda_2 > 0$.

Then $\lambda_2 = -2$. INFEASIBLE.

Hence the optimal solution is $(-2, 1, 2)$ with objective value -3 .

c) We write the Lagrangian,

$$\begin{aligned}
L(x_1, x_2, x_3, \lambda_1, \lambda_2) &= x_1^2 + 2x_2^2 + 2x_1x_2 + x_1 - x_2 - x_3 \\
&\quad + \lambda_1(x_1 + x_2 + x_3 - 1) + \lambda_2(x_3 - 3) \\
g(\lambda_1, \lambda_2) &= \inf_{x_1, x_2} \{x_1^2 + 2x_1x_2 + 2x_2^2 + x_1 - x_2 + \lambda_1x_1 + \lambda_1x_2\} \\
&\quad + \inf_{x_3} \{(\lambda_1 + \lambda_2 - 1)x_3\} - \lambda_1 - 3\lambda_2 \\
&= \begin{cases} \inf_{x_1, x_2} \left\{ \mathbf{x}^T \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \mathbf{x} + \begin{bmatrix} \lambda_1 + 1 \\ \lambda_1 - 1 \end{bmatrix}^T \mathbf{x} \right\} - \lambda_1 - 3\lambda_2, & \lambda_1 + \lambda_2 = 1, \\ -\infty, & \lambda_1 + \lambda_2 \neq 1. \end{cases}
\end{aligned}$$

Hessian of $\mathbf{x}^T \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \mathbf{x} + \begin{bmatrix} \lambda_1 + 1 \\ \lambda_1 - 1 \end{bmatrix}^T \mathbf{x}$ is a p.d. matrix so the function is convex and attains its minimum at stationary points, that is

$$\left. \begin{aligned} 2x_1 + 2x_2 &= -\lambda_1 - 1 \\ 2x_1 + 4x_2 &= -\lambda_1 + 1 \end{aligned} \right\} \Rightarrow x_1 = \frac{-\lambda_1 - 3}{2}, x_2 = 1$$

Then

$$g(\lambda_1, \lambda_2) = \begin{cases} \left(-\frac{\lambda_1^2 + 2\lambda_1 + 5}{4} \right) - \lambda_1 - 3\lambda_2, & \lambda_1 + \lambda_2 = 1, \\ -\infty, & \lambda_1 + \lambda_2 \neq 1. \end{cases}$$

Then we have

$$\max -\frac{1}{4}\lambda_1^2 - \frac{3}{2}\lambda_1 - 3\lambda_2 - \frac{5}{4} \text{ subject to } \lambda_1 + \lambda_2 = 1, \lambda_1, \lambda_2 \geq 0.$$

Substitute $\lambda_2 = 1 - \lambda_1$. Then

$$\max -\frac{1}{4}\lambda_1^2 + \frac{3}{2}\lambda_1 - \frac{17}{4} \text{ subject to } 1 \geq \lambda_1 \geq 0.$$

- $x_1^2 + 2x_2^2 + 2x_1x_2 + x_1 - x_2 - x_3, x_1 + x_2 + x_3 - 1, x_3 - 3$ are convex functions,
- \mathbb{R}^3 is a convex set,
- Problem has a finite optimal value by part b).
- $(x_1, x_2, x_3) = (0.3, 0.3, 0.3)$ satisfies $x_1 + x_2 + x_3 < 1$ and $x_3 < 3$.

Hence Theorem 12.8 provides strong duality.

d) We may solve

$$- \min \frac{1}{4}\lambda_1^2 - \frac{3}{2}\lambda_1 + \frac{17}{4} \text{ subject to } 1 \geq \lambda_1 \geq 0.$$

It is a convex quadratic function, stationary point is at $\lambda_1 = 3$ which is out of feasible region. Hence optimal solution must be on one of the endpoints which is $\lambda_1 = 1$ with the original objective -3 , as expected due to strong duality.