

ELEC 4700

**ASSIGNMENT 3 – MONTE CARLO/ FINITE
DIFFERENCE METHOD**

Submitted By:

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Introduction:

Part 1:

The differential equations that represent the network in the time domain using KCL (Summation of $I=0$ at the node) can be found below:

Equations:

$$\begin{aligned}V_1 &= V_{in} \\G_1(V_2 - V_1) + C \frac{d(V_2 - V_1)}{dt} + G_2 V_2 - I_L &= 0 \\V_2 - V_3 - L \frac{dI_L}{dt} &= 0 \\-I_L + G_3 V_3 &= 0 \\V_4 - \alpha I_3 &= 0 \\G_3 V_3 - I_3 &= 0 \\G_4(V_O - V_4) + G_O V_O &= 0\end{aligned}$$

Matrices:

$$\mathbf{C} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -C & C & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -L & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \mathbf{G} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -G_1 & G_1 + G_2 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & G_3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -\alpha & 1 & 0 & 0 \\ 0 & 0 & 0 & G_3 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -G_4 & G_4 + G_O & 0 \end{bmatrix}$$
$$\mathbf{V} = \begin{bmatrix} V_1 \\ V_2 \\ I_L \\ V_3 \\ I_3 \\ V_4 \\ V_O \end{bmatrix} \quad \mathbf{F} = \begin{bmatrix} V_{in} \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Equations in the frequency domain can be found below:

In the frequency domain:

Date

$$V_1 = V_{in}$$

$$G_1(V_2 - V_1) + Cj\omega(V_2 - V_1) + G_2V_2 - I_L = 0$$

$$V_2 - V_1 - Lj\omega I_L = 0$$

$$-I_L + G_3V_3 = 0$$

$$V_4 - \alpha I_3 = 0$$

$$G_3V_3 - I_3 = 0$$

$$G_4(V_0 - V_4) + G_0V_0 = 0$$

Programming section:

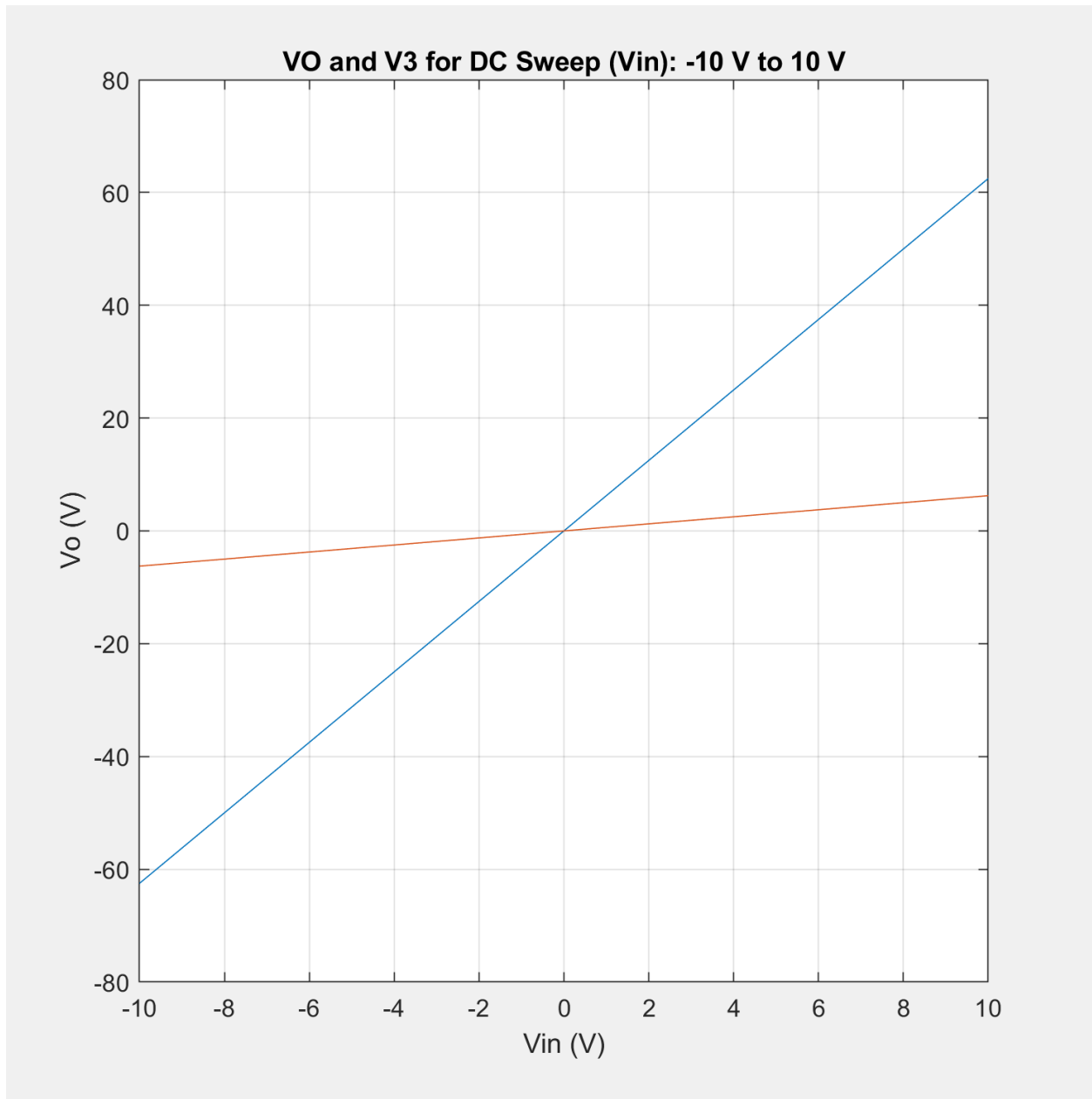


Figure 1: DC Sweep of the input voltage

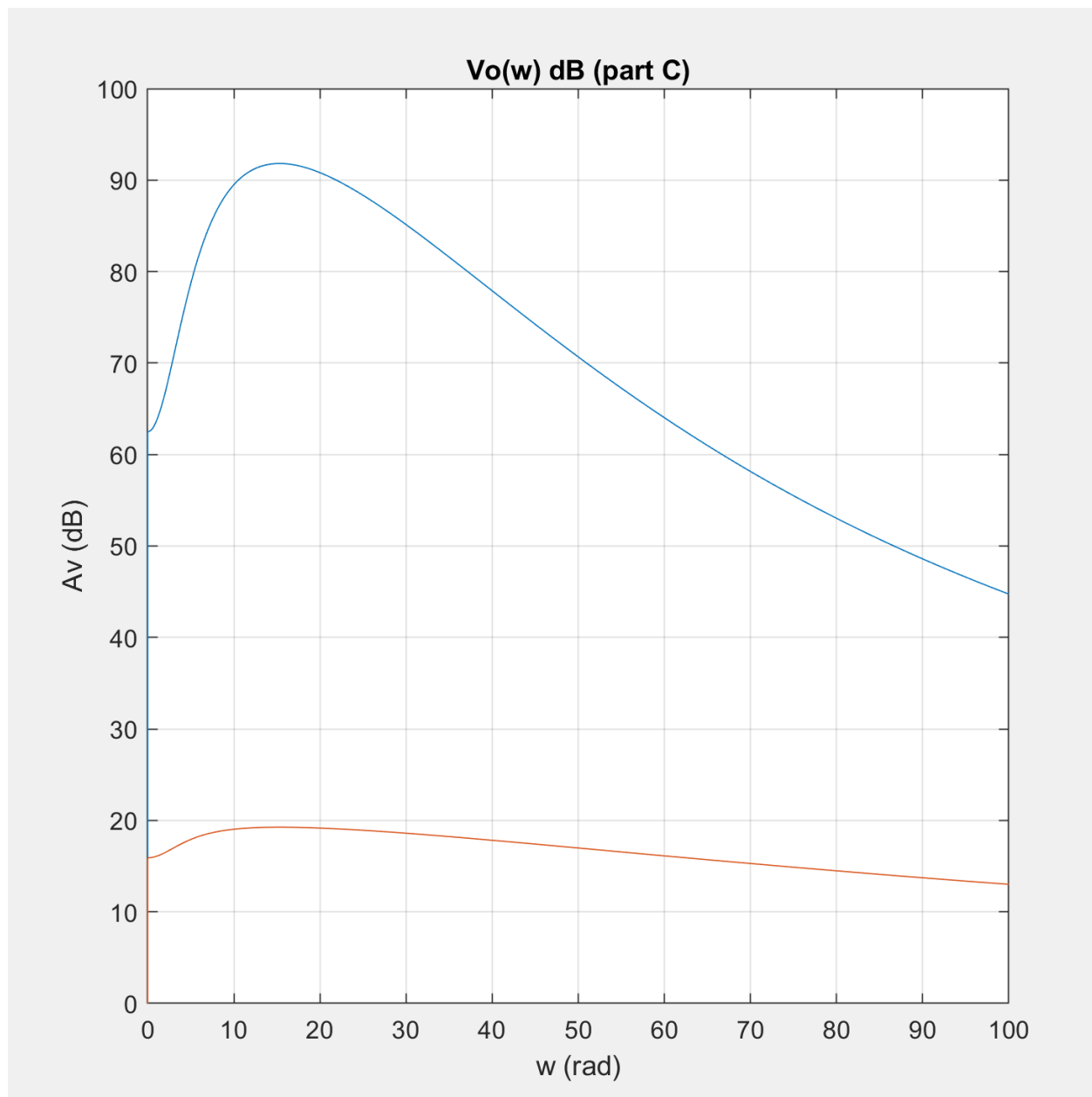


Figure 2: Ac plot of Vo as a fuction of w

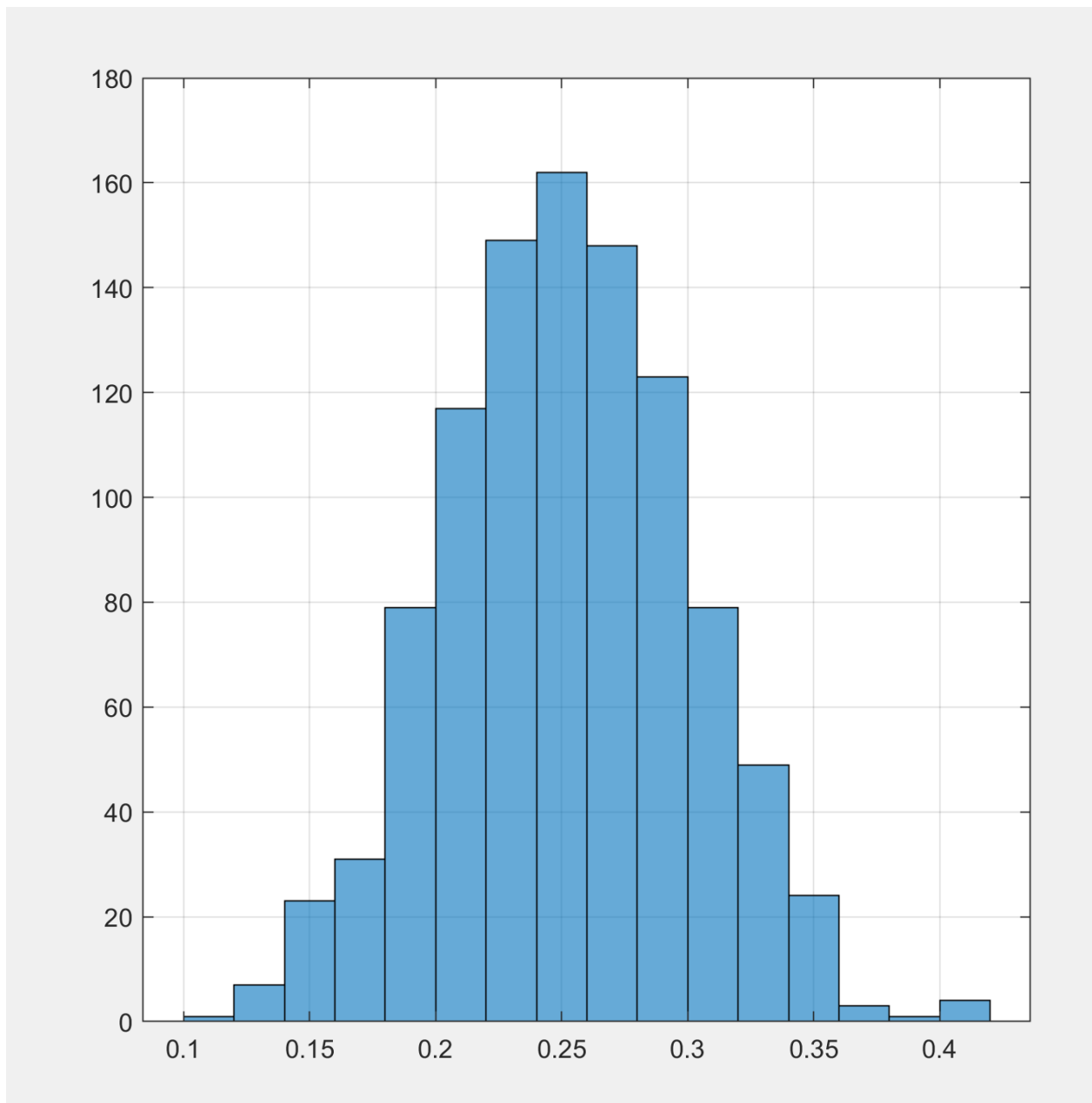


Figure 3: Histogram plot 1

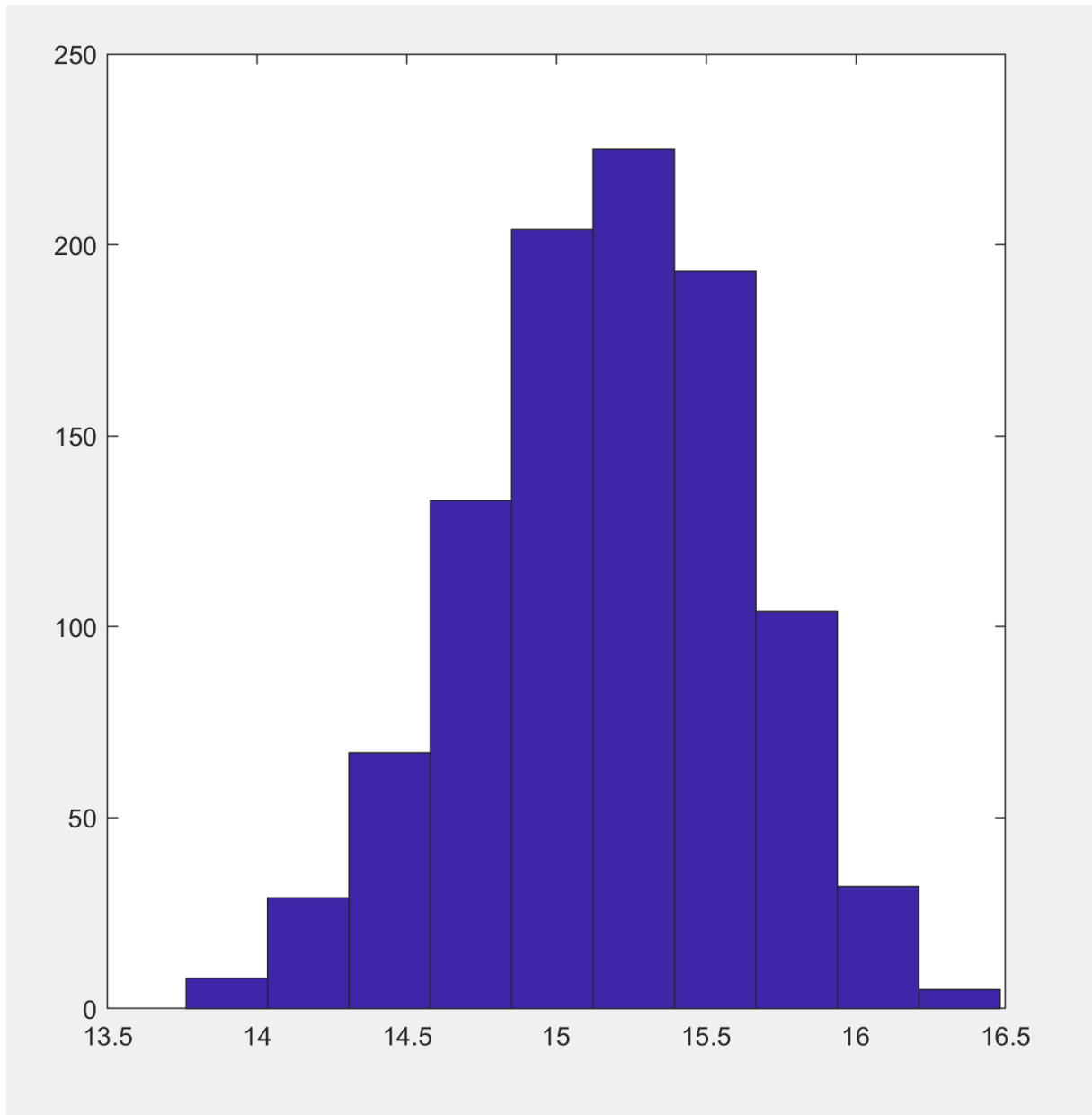


Figure 4: Histogram plot 2

Transient Simulation:

The circuit can be simulated in the time domain by solving the equation of $CdV/dt + GV = F$

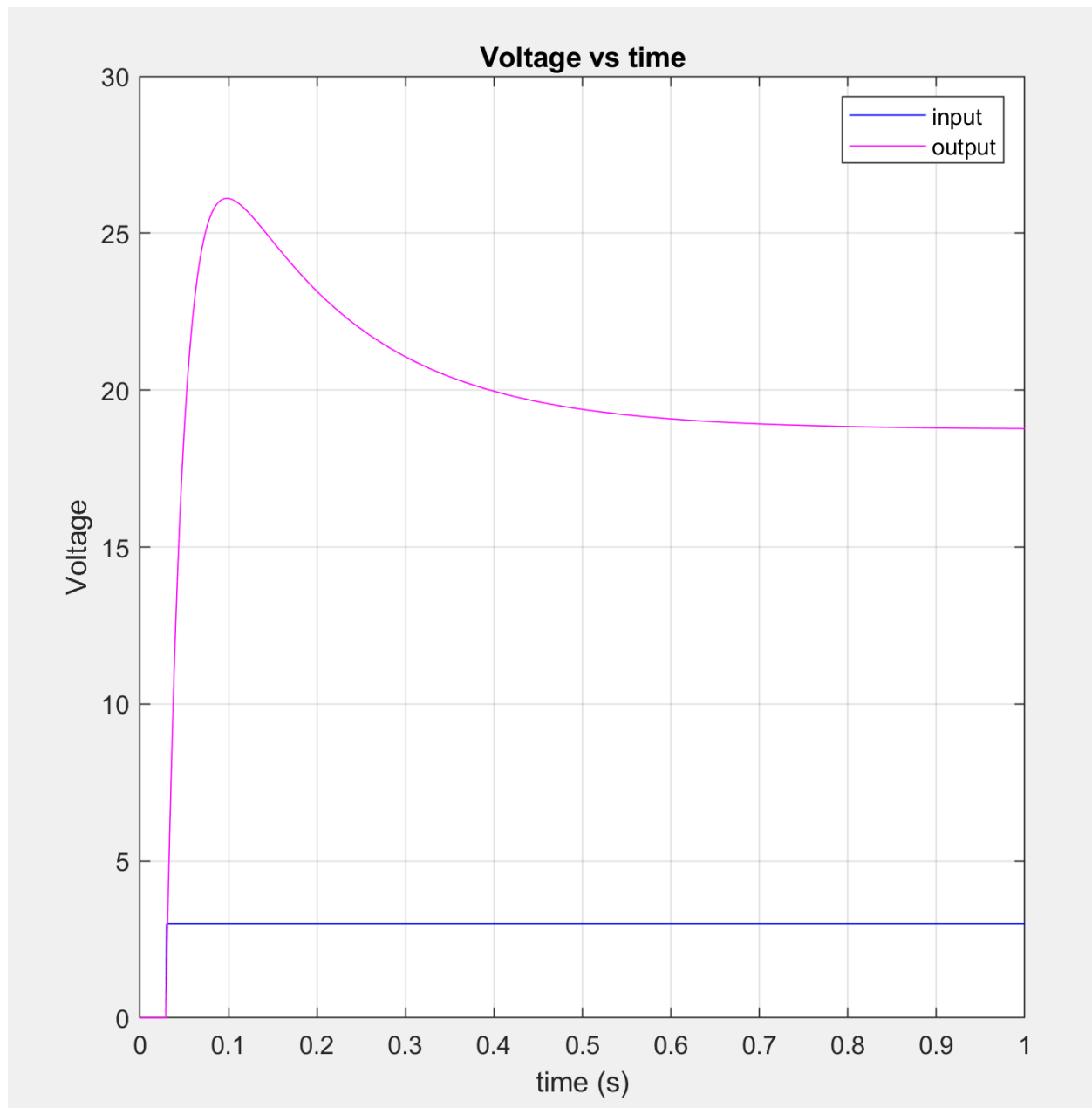


Figure 5: Plot of the voltage vs time

- a.) By inspection the circuit is a low pass filter
- b.) We should expect the frequency response to cut off high frequencies and allow only the low frequencies to go through.
- d.) Part v: As the time step is increased the accuracy of the simulation is decreased.

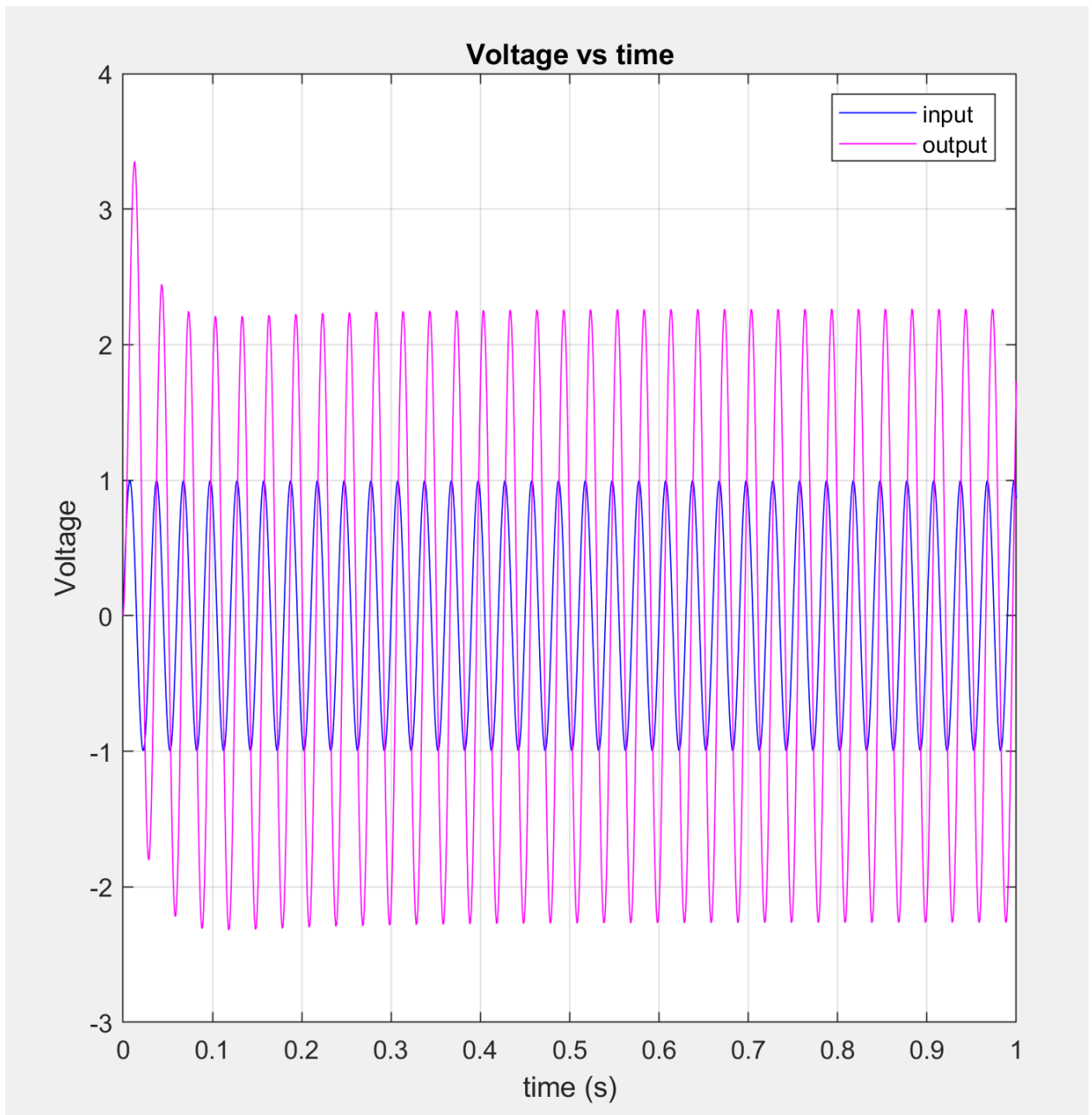


Figure 6: voltage vs time input and output sinusoid

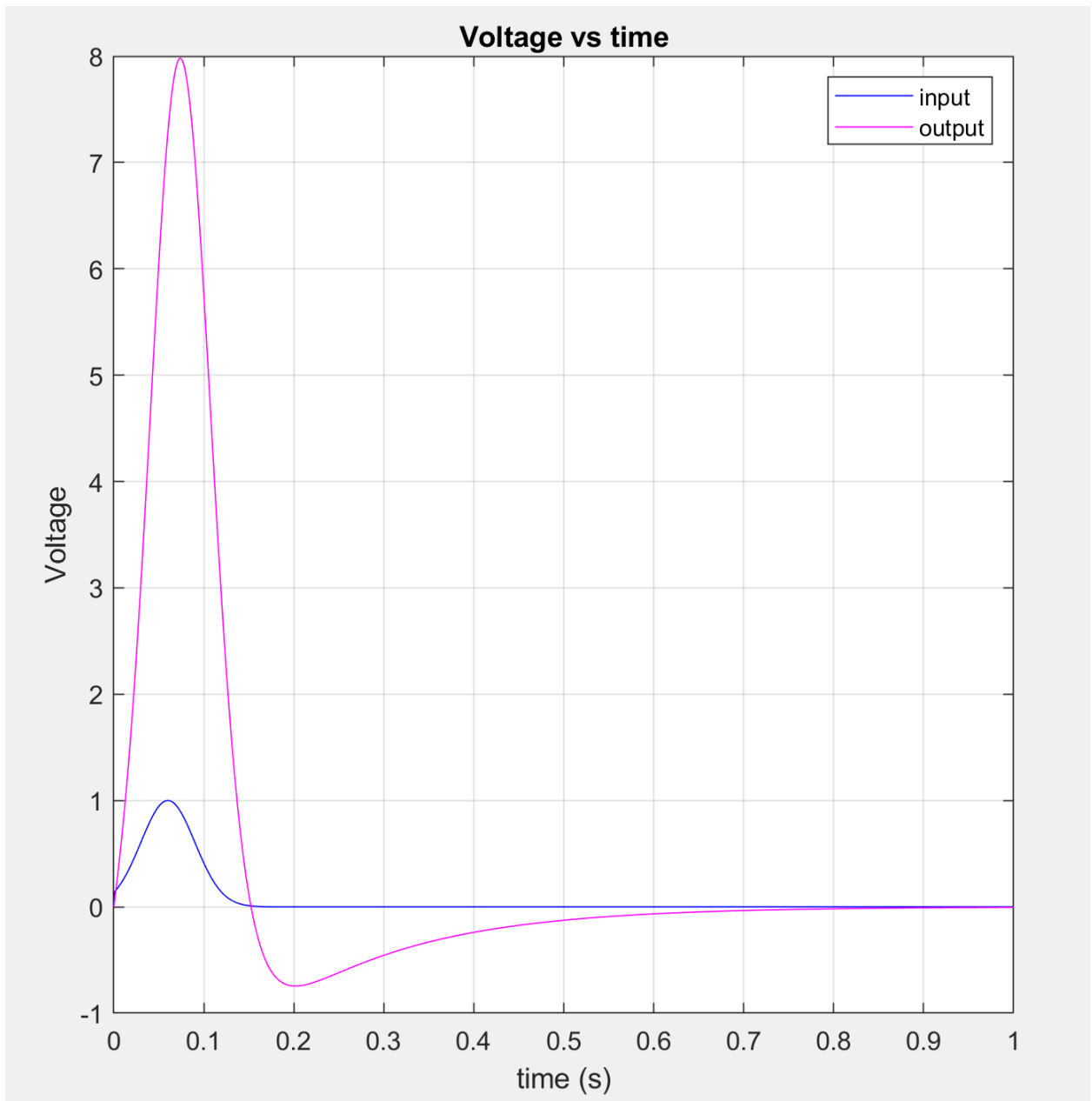


Figure 7: voltage vs time with input and output

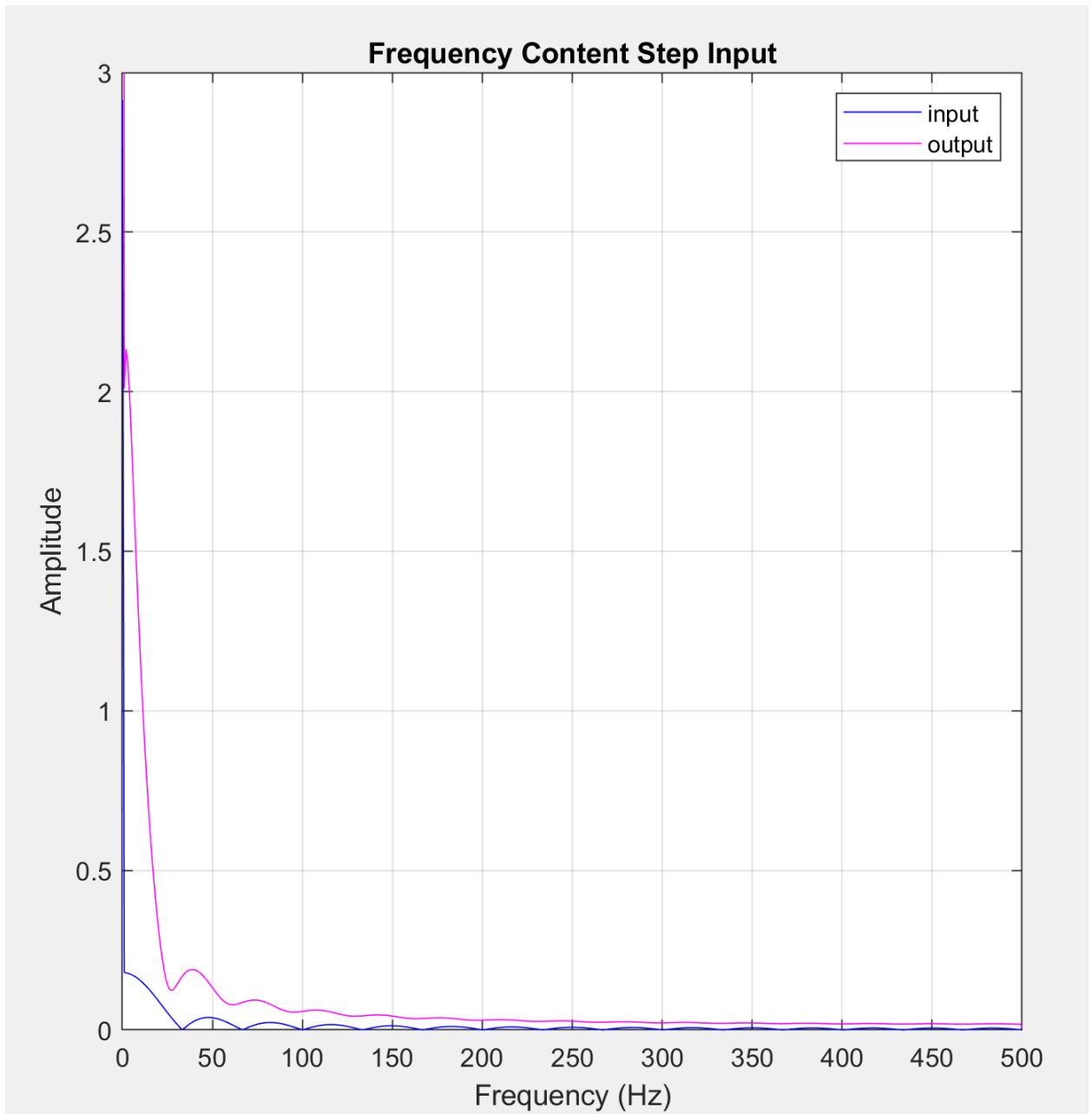


Figure 8: frequency content step input

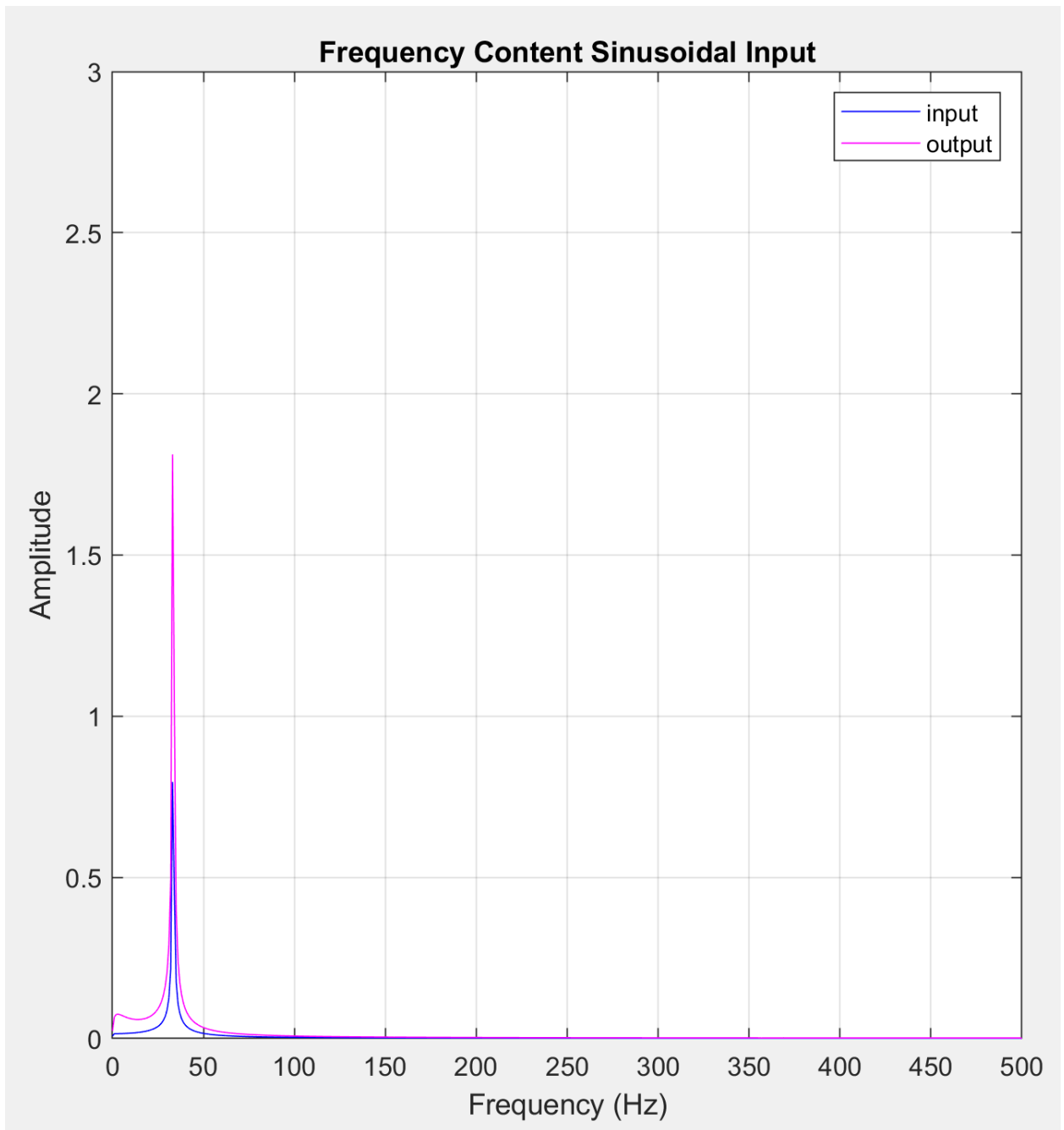


Figure 9: Frequency content sinuisoidal input

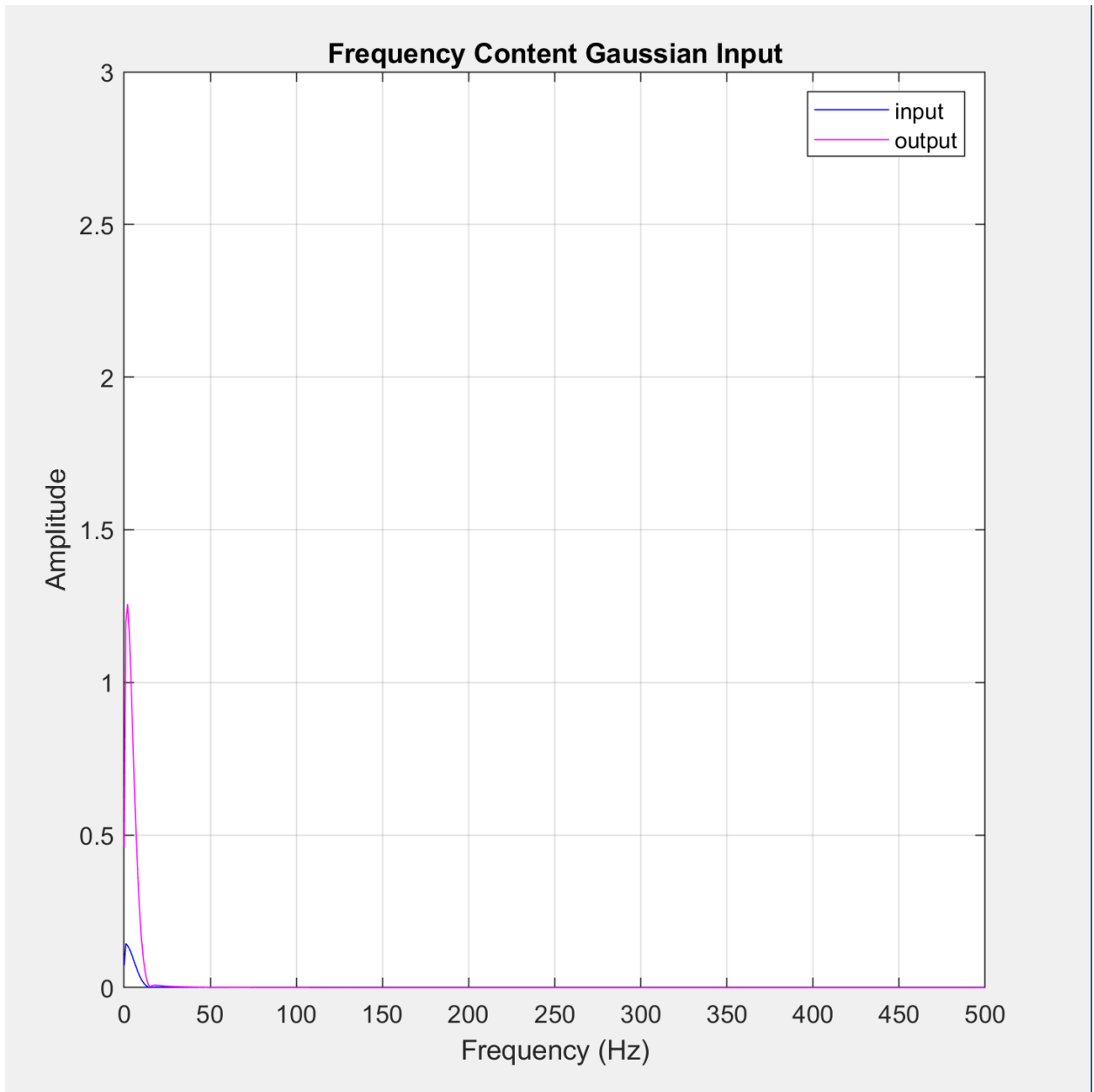


Figure 10: Frequency content Gaussian input

C matrix:

C1 =

0.2500	-0.2500	0	0	0	0	0	0
-0.2500	0.2500	0	0	0	0	0	0
0	0	0.0000	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	-0.2000	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

Note That Cn1 = 0.00001

$C1(1,:) = [C \quad -C \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0];$

$C1(2,:) = [-C \quad C \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0];$

$C1(3,:) = [0 \quad 0 \quad cn1 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0];$

$C1(4,:) = [0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0];$

$C1(5,:) = [0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0];$

$C1(6,:) = [0 \quad 0 \quad 0 \quad 0 \quad 0 \quad -L \quad 0 \quad 0];$

$C1(7,:) = [0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0];$

$C1(8,:) = [0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0];$

Varying Cn:

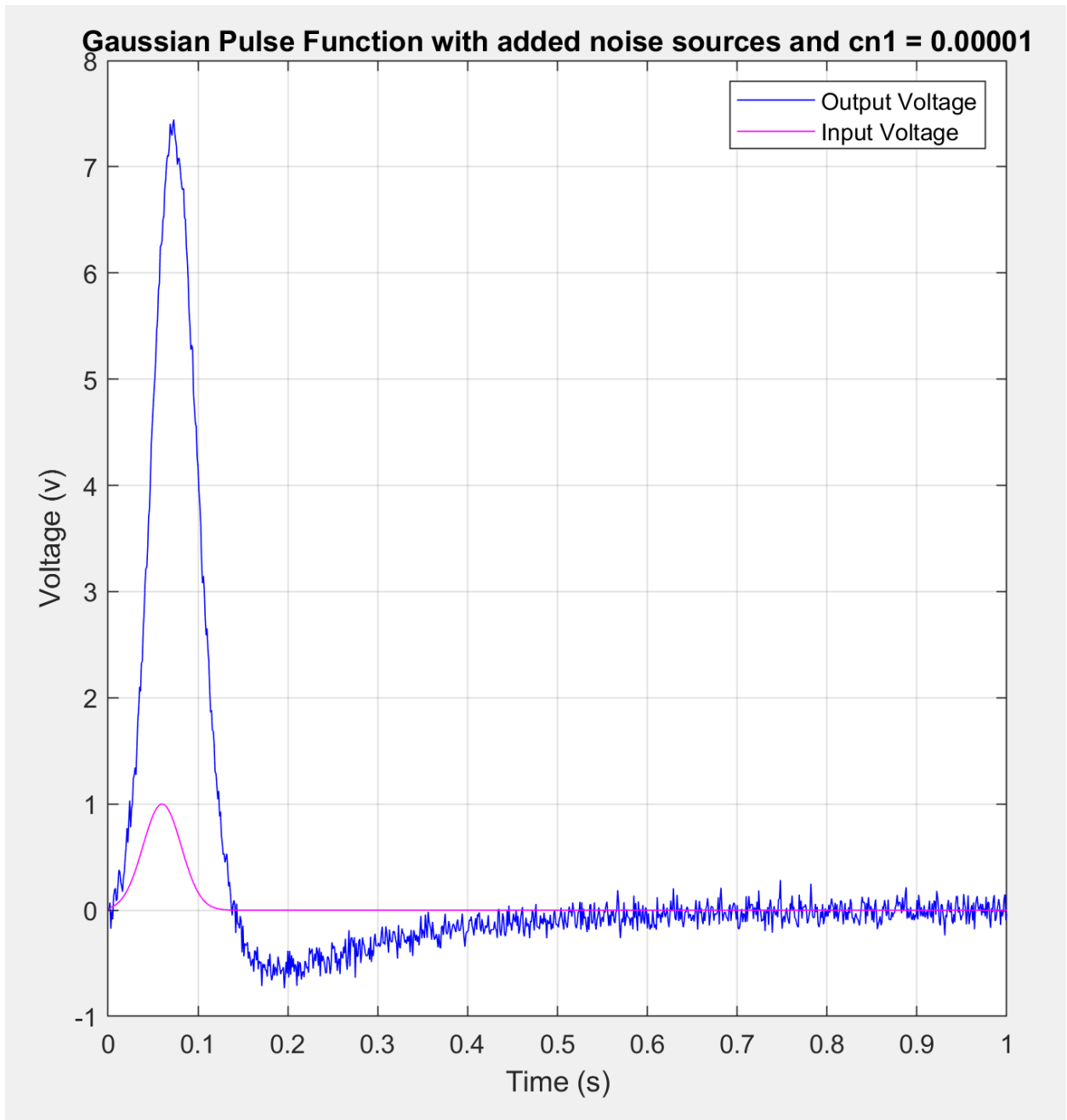


Figure 11: Gaussian Pulse function with added noise sources and $cn1 = 0.00001$

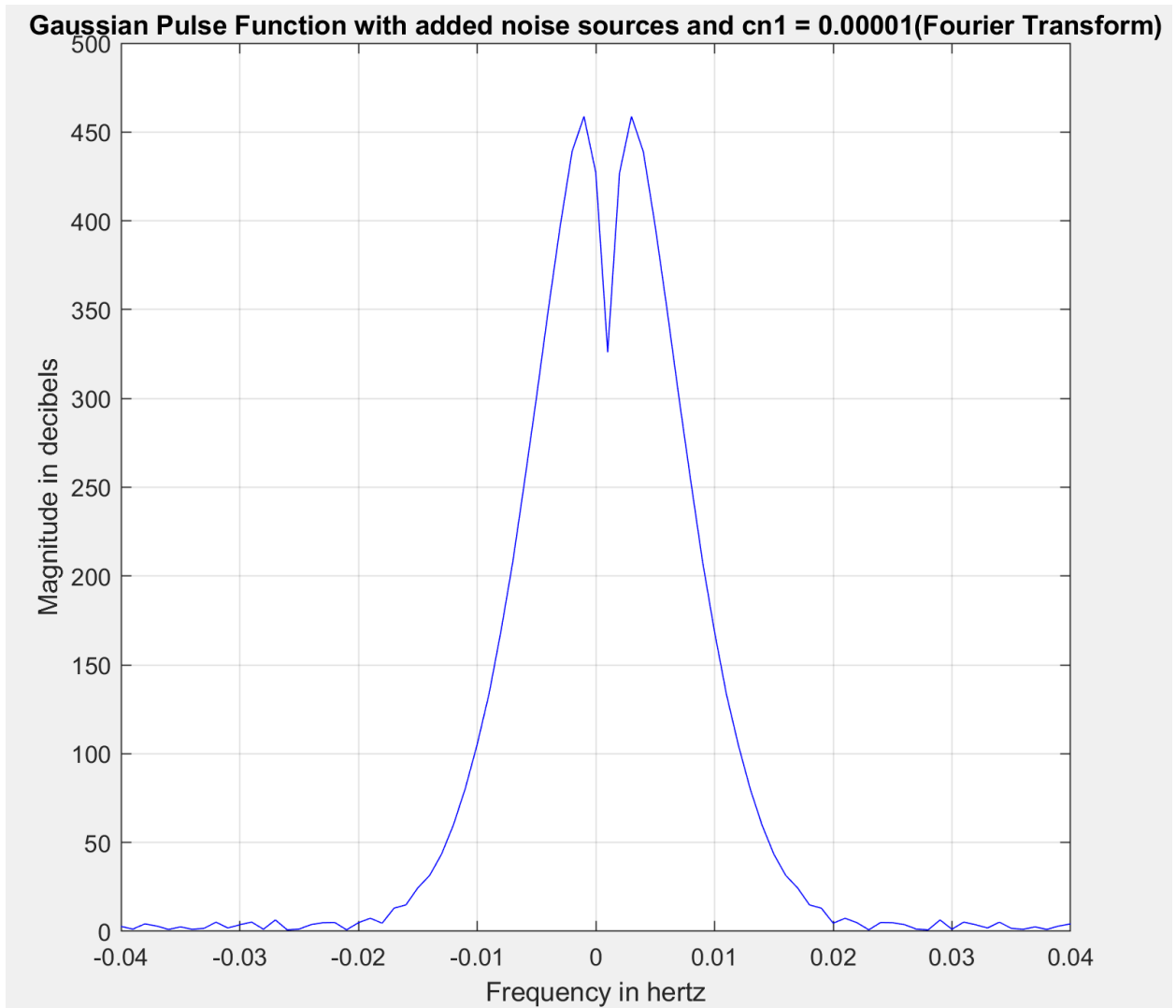


Figure 12: Gaussian Pulse function with added noise sources and $cn1=0.00001$
fourier transform

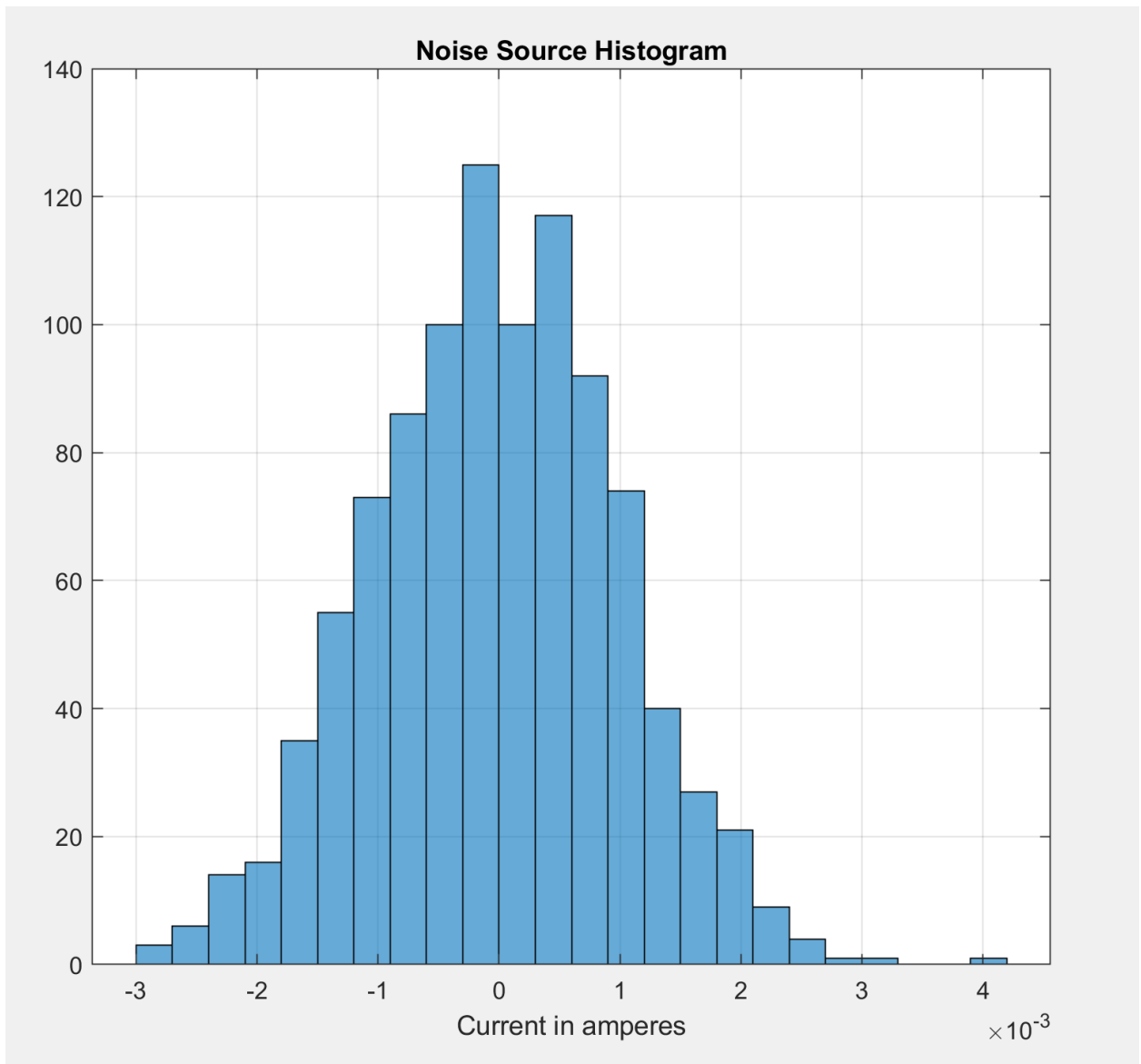


Figure 13: Noise Source Histogram

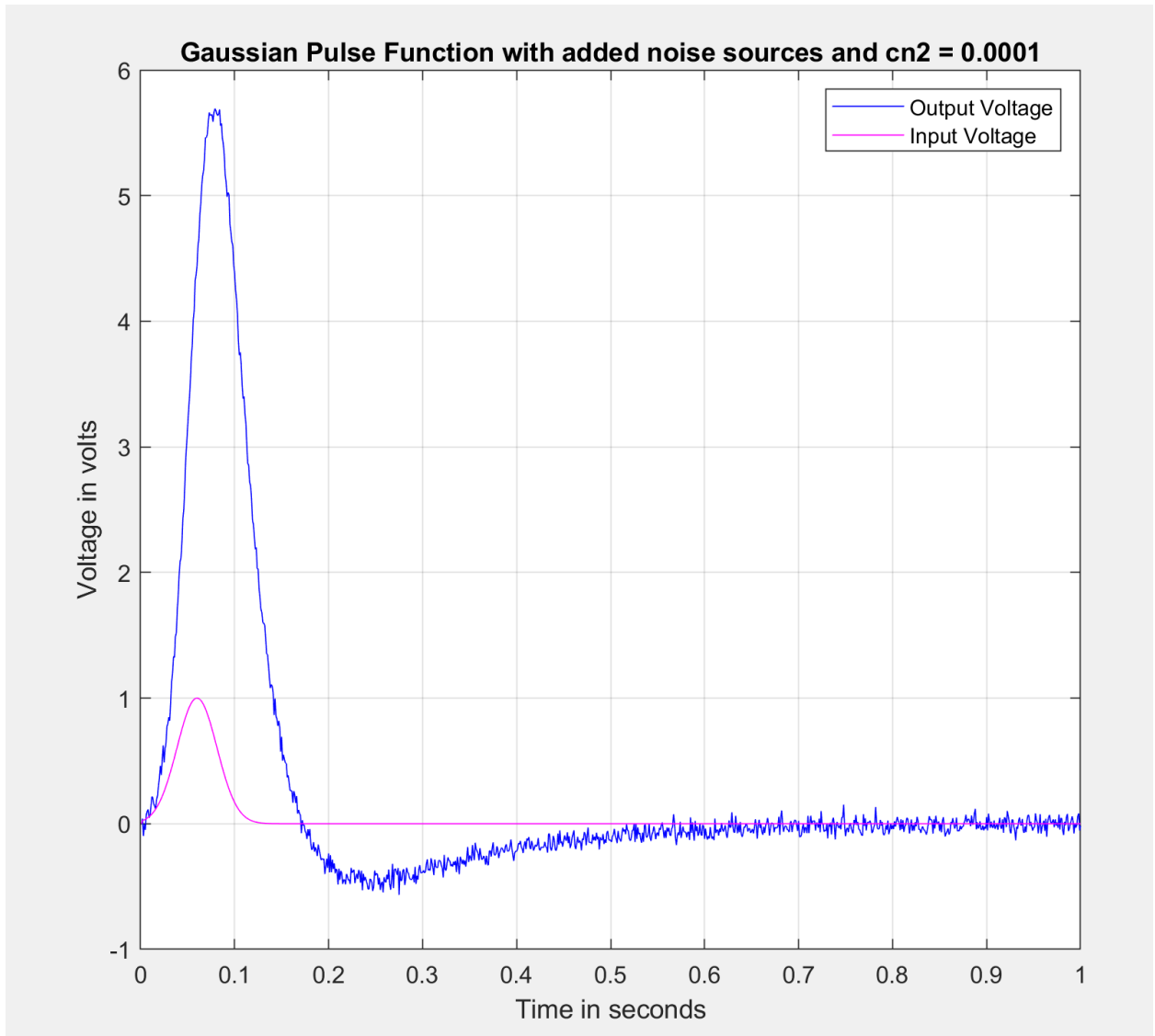


Figure 14: Gaussian Pulse function with added noise sources and $cn2=0.0001$

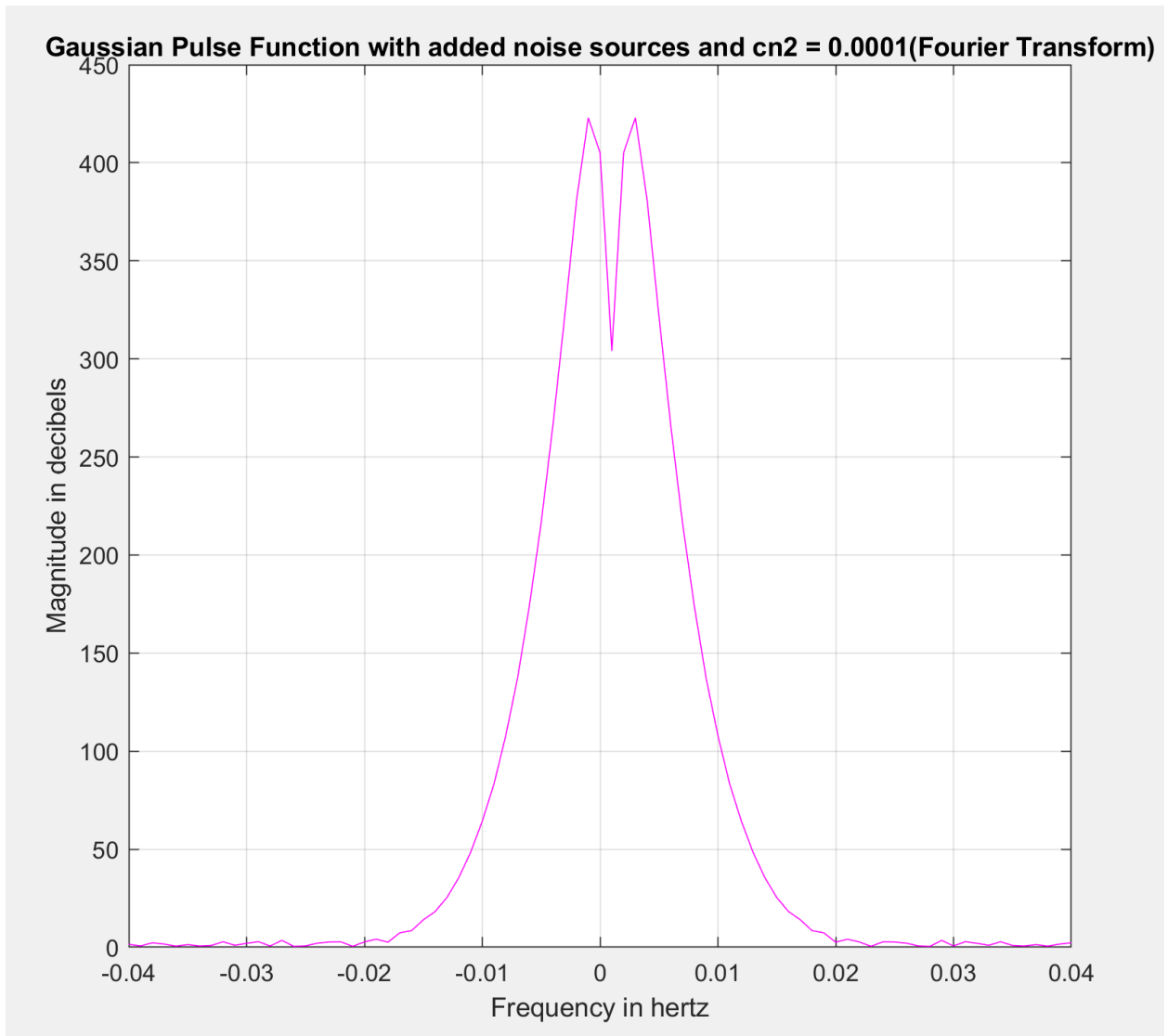


Figure 15: Gaussian Pulse Function with added noise sources and $cn2 = 0.0001$ fourier transform

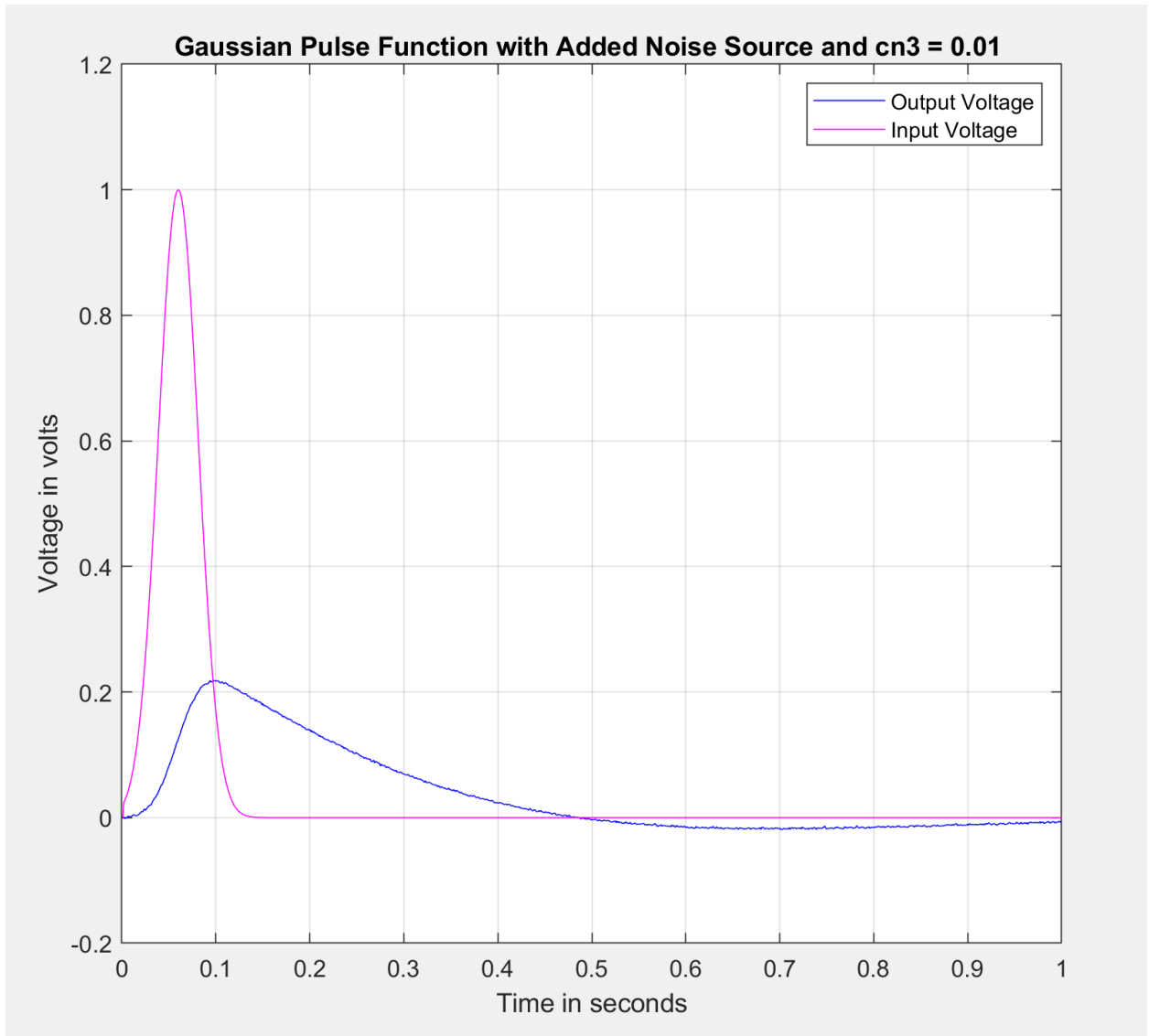


Figure 16: Gaussian Pulse function with added noise sources and $cn3=0.01$

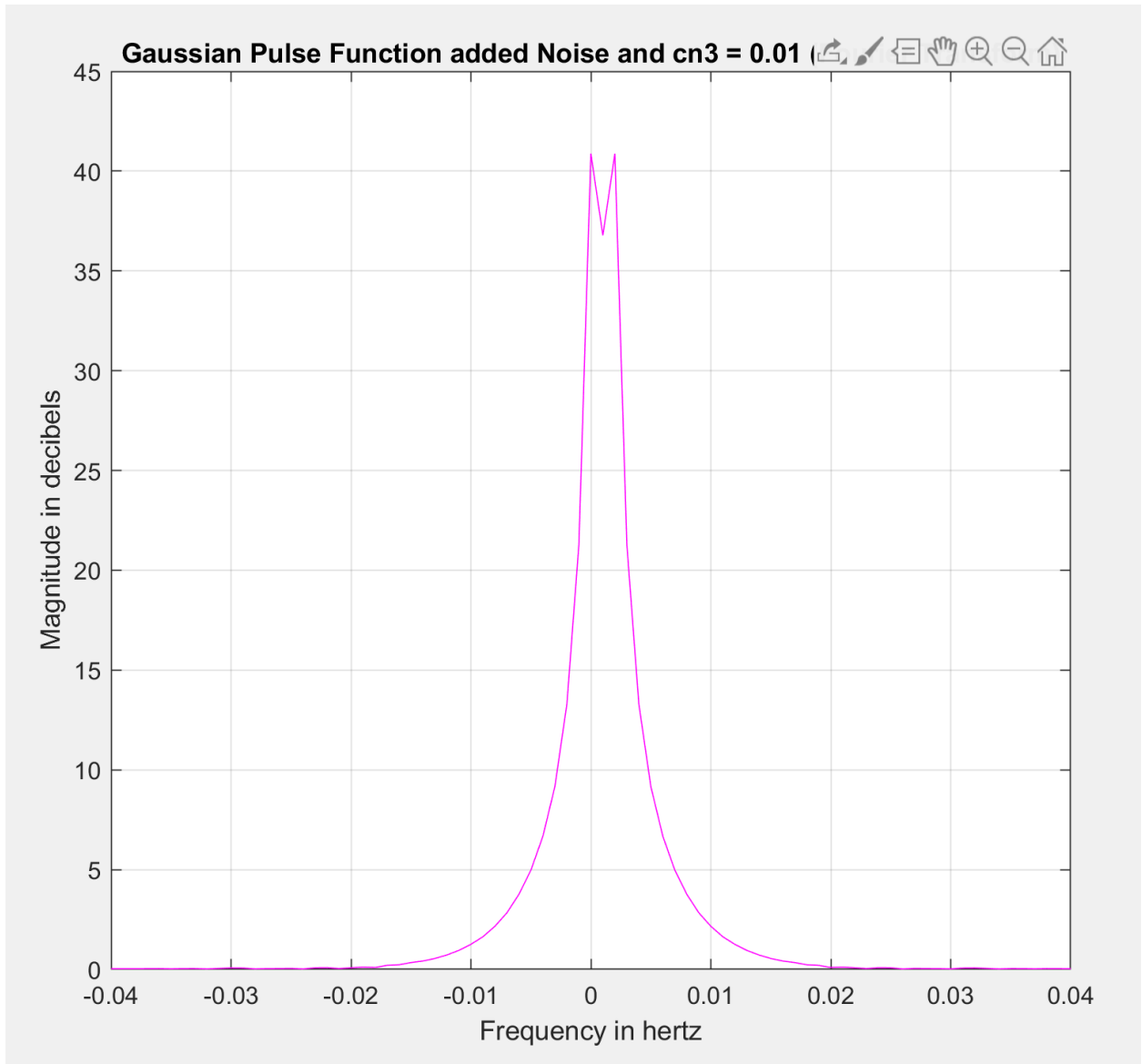


Figure 17: Gaussian Pulse function with added noise sources and $cn3=0.01$ fourier transform

We can conclude that as cn gets larger the bandwidth tends to get smaller.

Varying the timestep:

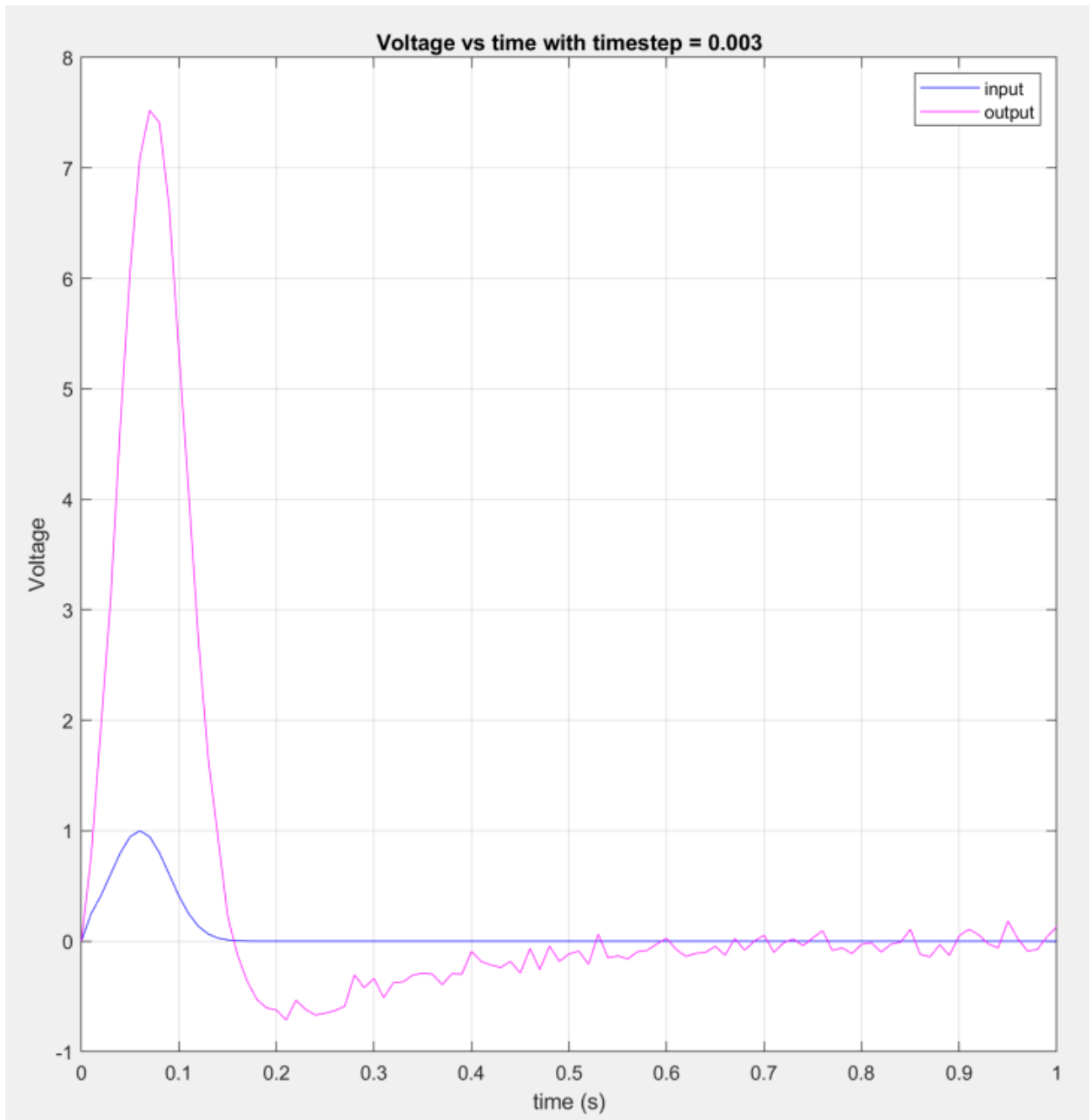


Figure 18: Plot when time step equals 0.003

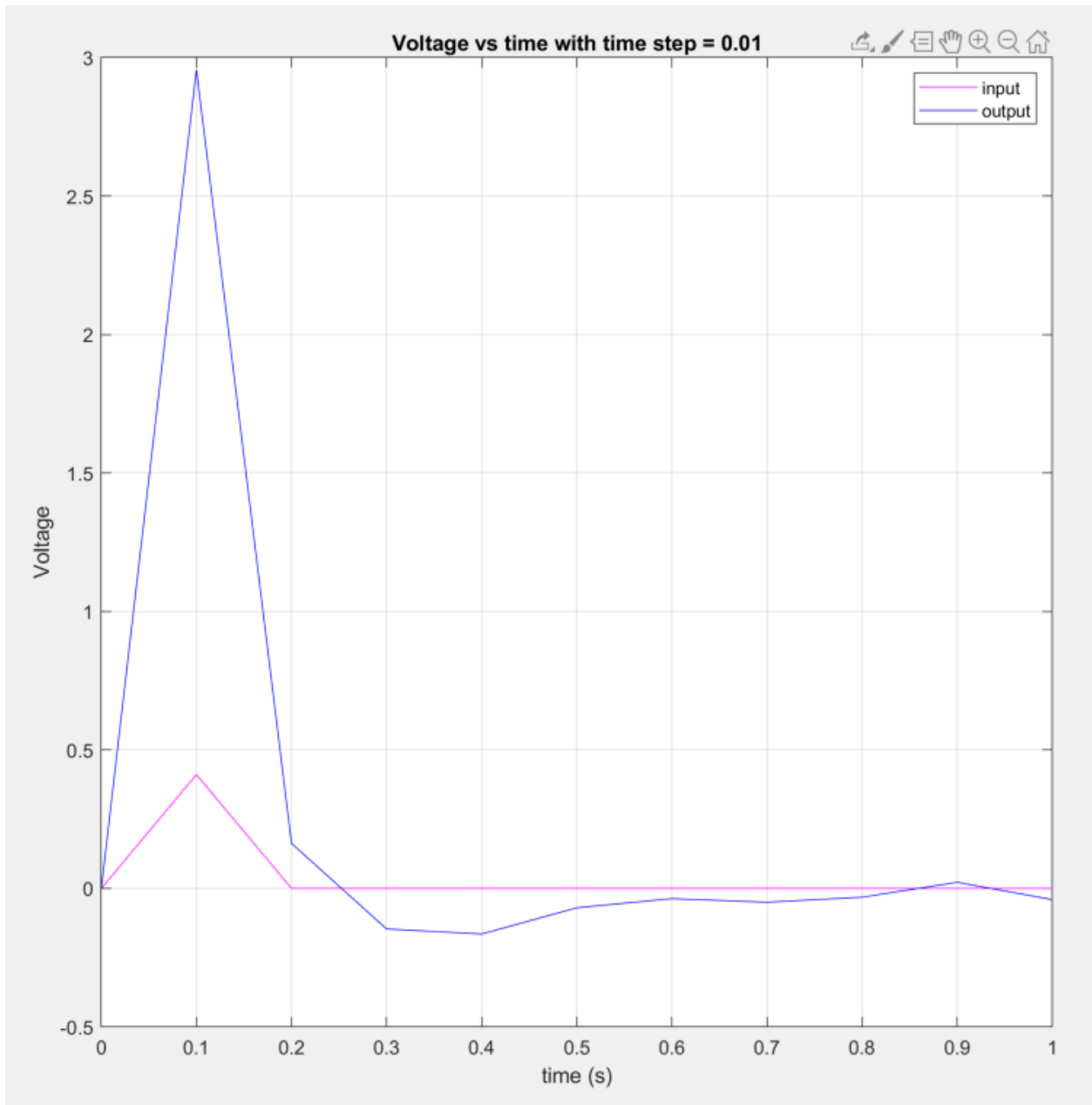


Figure19: Plot when timestep equals 0.01

What I seemed to have observed was that as the time step is increased the accuracy of the simulation decreases.

Non-Linearity:

In order to implement this in MATLAB we would need to add another matrix to represent or contain the equations for the non-linear elements. A column vector $B(V)$ would need to be added. When that has been added, because the system is

now non-linear it can't be solved by simple gaussian elimination and instead the newton Raphson numerical method would need to be used instead.

Appendix section:

```
clc
clear
clearvars
set(0,'DefaultFigureWindowSize','docked')
% Name:Jarikre Efe Jeffery
% Student Number: 101008461
% Part 3: Programming

G = zeros(6, 6);

%Resistances:
R1 = 1;
R2 = 2;
R3 = 10;
R4 = 0.1;
R0 = 1000;

%Conductances:
G1 = 1/R1;
G2 = 1/R2;
G3 = 1/R3;
G4 = 1/R4;
G0 = 1/R0;

%Additional Parameters:
a = 100;
Cval = 0.25;
L = 0.2;
vi = zeros(100, 1);
vo = zeros(100, 1);
v3 = zeros(100, 1);

G(1, 1) = 1;
G(2, 1) = G1; G(2, 2) = -(G1 + G2); G(2, 6) = -1;
```



```
G(3,3) = -G3; G(3,6) = 1;  
G(4,3) = -a*G3; G(4,4) = 1;  
G(5,5) = -(G4+G0); G(5,4) = G4;  
G(6,2) = -1; G(6,3) = 1;
```

```
C = zeros(6,6);
```

```
C(2,1) = Cval; C(2,2) = -Cval;  
C(6,6) = L;
```

```
F = zeros(6,1);  
v = 0;
```

```
for vin = -10:0.1:10  
    v = v + 1;  
    F(1) = vin;  
    Vm = G\F;  
    vi(v) = vin;  
    vo(v) = Vm(5);  
    v3(v) = Vm(3);  
end
```

```
figure(1)  
plot(vi, vo);  
hold on;  
plot(vi, v3);  
title('VO and V3 for DC Sweep (Vin): -10 V to 10 V');  
xlabel('Vin (V)')  
ylabel('Vo (V)')  
grid on
```

```
vo2 = zeros(1000,1);  
W = zeros(1000,1);
```

```
Avlog = zeros(1000,1);
```

```
for freq = linspace(0,100,1000)  
    v = v+1;
```

```
Vm2 = (G+1j*freq*C)\F;  
W(v) = freq;  
vo2(v) = norm(Vm2(5));
```

```
Avlog(v) = 20*log10(norm(Vm2(5))/10);  
end
```

```
figure(3)  
plot(W, vo2)  
hold on;  
plot(W, Avlog)  
grid on  
title('Vo(w) dB (part C)')  
xlabel('w (rad)')  
ylabel('Av (dB)')
```

```
figure(4)  
semilogx(W,vo2)  
title('Vo(w) dB (part C)')  
xlabel('w (rad)')  
ylabel('Av (dB)')  
grid on
```

```
w = pi;  
CC = zeros(1000,1);  
GG = zeros(1000,1);
```

```
for i = 1:1000  
    crand = Cval + 0.05*randn();  
    C(2, 1) = crand;  
    C(2, 2) = -crand;  
    C(3, 3) = L;  
    Vm3 = (G+(1i*w*C))\F;  
    CC(i) = crand;  
    GG(i) = 20*log10(abs(Vm3(5))/10);  
end
```

```
figure(5)  
histogram(CC)  
grid on
```

```

figure(6)
grid on
hist(GG)

clc
clear
clearvars
set(0,'DefaultFigureWindowStyle','docked')
% Transient simulation
R1 = 1;
R2 = 2;
C = 0.25;
L = 0.2;
R3 = 10;
a = 100;
R4 = 0.1;
R0 = 1000;
G = zeros(7,7);
Cm = zeros(7,7);
% Conductance value
G(1,1) = 1;
G(2,1) = -1/R1;
G(2,2) = 1/R1 + 1/R2;
G(2,6) = 1;
G(3,3) = 1/R3;
G(3,6) = -1;
G(4,3) = 1/R3;
G(4,7) = -1;
G(5,4) = -1/R4;
G(5,5) = 1/R4 + 1/R0;
G(6,2) = 1;
G(6,3) = -1;
G(7,4) = 1;
G(7,7) = -a;
% Capacitance value
Cm(2,1) = -C;
Cm(2,2) = C;
Cm(6,6) = -L;
V1 = zeros(7,1);
V2 = zeros(7,1);

```

```

V3 = zeros(7,1);
V_node1(1) = 0;
V_node2(1) = 0;
V_node3(1) = 0;
delta = 0.001;
A = (Cm/delta) + G;
F_index1 = zeros(7,1);
F_index2 = zeros(7,1);
F_index33 = zeros(7,1);
Vo_node1(1) = 0;
Vo_node2(1) = 0;
Vo_node3(1) = 0;

i = 1;
for j = delta:delta:1
    if j >= 0.03
        F_index1(1) = 3;
    end
    F_index2(1) = sin(2*pi*j/0.03);
    F_index33(1) = exp(-0.5*((j - 0.06)/0.03)^2);
    V1 = A\((Cm*V1/delta + F_index1);
    V2 = A\((Cm*V2/delta + F_index2);
    V3 = A\((Cm*V3/delta + F_index33);
    V_node1(i+1) = V1(1);
    V_node2(i+1) = V2(1);
    V_node3(i+1) = V3(1);
    Vo_node1(i+1) = V1(5);
    Vo_node2(i+1) = V2(5);
    Vo_node3(i+1) = V3(5);
    i = i+1;
end

figure(7)
plot(0:delta:1,V_node1,'b')
hold on
plot(0:delta:1,Vo_node1,'m')
title('Voltage vs time')
xlabel('time (s)')
ylabel('Voltage')
legend('input','output')

```

```

grid on
figure(8)
plot(0:delta:1,V_node2,'b')
hold on
plot(0:delta:1,Vo_node2,'m')
title('Voltage vs time')
xlabel('time (s)')
ylabel('Voltage')
legend('input','output')
grid on
figure(9)
plot(0:delta:1,V_node3,'b')
hold on
plot(0:delta:1,Vo_node3,'m')
title('Voltage vs time')
xlabel('time (s)')
ylabel('Voltage')
legend('input','output')
grid on

```

```

% Convert to frequency domain by taking the fourier transform
step_in = fft(V_node1); %fft -> Fast fourier transform
P_mag2_in = abs(step_in/1000);
P_1_in = P_mag2_in(1:1000/2+1);
P_1_in(2:end-1) = 2*P_1_in(2:end-1);
sample_f = (1/delta)*(0:(1000/2))/1000;
% Plot figure
figure(10)
plot(sample_f,P_1_in,'b')
step_out = fft(Vo_node1);
P2_out = abs(step_out/1000);
P1_out = P2_out(1:1000/2+1);
P1_out(2:end-1) = 2*P1_out(2:end-1);
sample_f = (1/delta)*(0:(1000/2))/1000;
hold on
plot(sample_f,P1_out,'m')
title('Frequency Content Step Input')
xlabel('Frequency (Hz)')
ylabel('Amplitude')
ylim([0 3])

```

```

legend('input','output')
grid on
% The fourier transform of the step input signal gives us a sinc function.
% This makes sense as we know that by taking the fourier transform of a step signal we
should get a sinc function.
% The High Frequency components are attenuated due to the fact that the filter
% is a low pass filter

```

```

step_in = fft(V_node2); %Take fourier transform
P_mag2_in = abs(step_in/1000);
P_1_in = P_mag2_in(1:1000/2+1);
P_1_in(2:end-1) = 2*P_1_in(2:end-1); % Calculate singel ended spectrum
figure(11)
plot(sample_f,P_1_in,'b')
grid on
step_out = fft(Vo_node2);
P2_out = abs(step_out/1000);
P1_out = P2_out(1:1000/2+1);
P1_out(2:end-1) = 2*P1_out(2:end-1);
hold on
plot(sample_f,P1_out,'m')
title('Frequency Content Sinusoidal Input')
xlabel('Frequency (Hz)')
ylabel('Amplitude')
ylim([0 3])
legend('input','output')
step_in = fft(V_node3); %Take fourier transform
P_mag2_in = abs(step_in/1000);
P_1_in = P_mag2_in(1:1000/2+1);
P_1_in(2:end-1) = 2*P_1_in(2:end-1); % Calculate singel ended spectrum
figure(12)
plot(sample_f,P_1_in,'b')
grid on
step_out = fft(Vo_node3);
P2_out = abs(step_out/1000);
P1_out = P2_out(1:1000/2+1);
P1_out(2:end-1) = 2*P1_out(2:end-1);
hold on
plot(sample_f,P1_out,'m')
title('Frequency Content Gaussian Input')

```

```
xlabel('Frequency (Hz)')
ylabel('Amplitude')
ylim([0 3])
legend('input','output')

clc
clearvars
set(0,'DefaultFigureWindowStyle','docked')
```

```
R1 = 1;
R2 = 2;
R3 = 10;
R4 = 0.1;
Ro = 1000;
C = 0.25;
L = 0.2;
a = 100;
cn1 = 0.00001;
cn2 = 0.0001;
cn3 = 0.01;
```

```
C1(1,:)=[C -C 0 0 0 0 0 0];
C1(2,:)=[-C C 0 0 0 0 0 0];
C1(3,:)=[0 0 cn1 0 0 0 0 0];
C1(4,:)=[0 0 0 0 0 0 0 0];
C1(5,:)=[0 0 0 0 0 0 0 0];
C1(6,:)=[0 0 0 0 0 -L 0 0];
C1(7,:)=[0 0 0 0 0 0 0 0];
C1(8,:)=[0 0 0 0 0 0 0 0];
```

C1

```
C2(1,:)=[C -C 0 0 0 0 0 0];
C2(2,:)=[-C C 0 0 0 0 0 0];
C2(3,:)=[0 0 cn2 0 0 0 0 0];
C2(4,:)=[0 0 0 0 0 0 0 0];
C2(5,:)=[0 0 0 0 0 0 0 0];
C2(6,:)=[0 0 0 0 0 -L 0 0];
C2(7,:)=[0 0 0 0 0 0 0 0];
C2(8,:)=[0 0 0 0 0 0 0 0];
```

C2

```
C3(1,:)=[C -C 0 0 0 0 0 0];
C3(2,:)=[-C C 0 0 0 0 0 0];
C3(3,:)=[0 0 cn3 0 0 0 0 0];
C3(4,:)=[0 0 0 0 0 0 0 0];
C3(5,:)=[0 0 0 0 0 0 0 0];
C3(6,:)=[0 0 0 0 0 -L 0 0];
C3(7,:)=[0 0 0 0 0 0 0 0];
C3(8,:)=[0 0 0 0 0 0 0 0];
```

C3

```
G(1,:)=[1 -1 0 0 0 0 0 1];
G(2,:)=[-1 1.5 0 0 0 1 0 0];
G(3,:)=[0 0 0.1 0 0 -1 0 0];
G(4,:)=[0 0 0 10 -10 0 1 0];
G(5,:)=[0 0 0 -10 10.0010 0 0 0];
G(6,:)=[0 1 -1 0 0 -L 0 0];
G(7,:)=[0 0 -10 1 0 0 0 0];
G(8,:)=[1 0 0 0 0 0 0 0];
```

G

```
F = [
    0 ;
    0 ;
    0 ;
    0 ;
    0 ;
    0 ;
    0 ;
    0 ;
    0 ;
];
```

% Given these values from lab manual

delta = 0.001;

standard_deviation = 0.03;

d = 0.06;


```

m = 1;
c_s = zeros(1,1000);
f_l = zeros(8,1,1000);

for i=1:1:1000
    f_l(8,1,i) = exp(-((i*delta - d)/standard_deviation)^2);
    f_l(3,1,i) = -0.001*randn;
    c_s(i) = f_l(3,1,i);
end

VL_1 = zeros(8,1,1000);
VL_2 = zeros(8,1,1000);
VL_3 = zeros(8,1,1000);

for i = 2:1:1000
    index1 = C1/delta + G;
    index2 = C2/delta + G;
    index3 = C3/delta + G;

    VL_1(:,i) = index1*(C1*VL_1(:,i-1)/delta + f_l(:,i));
    VL_2(:,i) = index2*(C1*VL_2(:,i-1)/delta + f_l(:,i));
    VL_3(:,i) = index3*(C1*VL_3(:,i-1)/delta + f_l(:,i));
end

VoL_1(1,:) = VL_1(5,1,:);
ViL_1(1,:) = VL_1(1,1,:);

VoL_2(1,:) = VL_2(5,1,:);
ViL_2(1,:) = VL_2(1,1,:);

VoL_3(1,:) = VL_3(5,1,:);
ViL_3(1,:) = VL_3(1,1,:);

figure(13)
plot((1:1000).*delta, VoL_1(1,:), 'b')
hold on
plot((1:1000).*delta, ViL_1(1,:), 'm')
title('Gaussian Pulse Function with added noise sources and cn1 = 0.00001')

```

```

xlabel('Time (s)')
ylabel('Voltage (v)')
grid on
legend('Output Voltage','Input Voltage')
hold off

```

```

figure(14)
histogram(c_s)
title('Noise Source Histogram')
grid on
xlabel('Current in amperes')

```

```

figure(15)
FF = abs(fftshift(fft(VoL_1(1,:))));
plot(((1:length(FF))/1000)-0.5,FF,'b')
xlabel('Frequency in hertz')
ylabel('Magnitude in decibels')
grid on
xlim([-0.04 0.04])
title('Gaussian Pulse Function with added noise sources and cn1 = 0.00001(Fourier Transform)')

```

% CN 2 -----

```

figure(16)
plot((1:1000).*delta, VoL_2(1,:), 'b')
hold on
plot((1:1000).*delta, ViL_2(1,:), 'm')
title('Gaussian Pulse Function with added noise sources and cn2 = 0.0001')
xlabel('Time in seconds')
ylabel('Voltage in volts')
grid on
legend('Output Voltage','Input Voltage')
hold off

```

```

figure(17)
FF = abs(fftshift(fft(VoL_2(1,:))));
plot(((1:length(FF))/1000)-0.5,FF, 'm')
xlabel('Frequency in hertz')
ylabel('Magnitude in decibels')

```

```

grid on
xlim([-0.04 0.04])
title('Gaussian Pulse Function with added noise sources and cn2 = 0.0001(Fourier Transform)')

```

```

figure(18)
plot((1:1000).*delta, VoL_3(1,:), 'b')
hold on
plot((1:1000).*delta, ViL_3(1,:), 'm')
title('Gaussian Pulse Function with Added Noise Source and cn3 = 0.01 ')
xlabel('Time in seconds')
ylabel('Voltage in volts')
grid on
legend('Output Voltage', 'Input Voltage')
hold off

```

```

figure(19)
FF = abs(fftshift(fft(VoL_3(1,:))));
plot(((1:length(FF))/1000)-0.5, FF, 'm')
xlabel('Frequency in hertz')
ylabel('Magnitude in decibels')
grid on
xlim([-0.04 0.04])
title('Gaussian Pulse Function added Noise and cn3 = 0.01 (Fourier Transform)')
% Varying timestep
%Varying timestep:
clc
clear
clearvars
set(0, 'DefaultFigureWindowStyle', 'docked')
R1 = 1;
R2 = 2;
C = 0.25;
L = 0.2;
R3 = 10;
a = 100;
R4 = 0.1;
R0 = 1000;

G = zeros(7,7);

```

```

C_mat = zeros(7,7);
G(1,1) = 1;
G(2,1) = -1/R1;
G(2,2) = 1/R1 + 1/R2;
G(2,6) = 1;
G(3,3) = 1/R3;
G(3,6) = -1;
G(4,3) = 1/R3;
G(4,7) = -1;
G(5,4) = -1/R4;
G(5,5) = 1/R4 + 1/R0;
G(6,2) = 1;
G(6,3) = -1;
G(7,4) = 1;
G(7,7) = -a;
C_mat(2,1) = -C;
C_mat(2,2) = C;
C_mat(6,6) = -L;

```

```

G
C_mat

```

```

F = zeros(7,1);
V = zeros(7,1);

```

```

%Circuit with noise
In = 0.001; % as provided in assignment manual
Cn = 0.00001; % as provided in assignment manual
C_mat(3,3) = Cn;
G
C_mat

```

```

delta = 0.001;
A_transpse = C_mat/delta + G;

```

```

F = zeros(7,1);
V = zeros(7,1);
Vo_index(1) = 0;
Vi_index(1) = 0;

```

```

ii = 1;
for t = delta:delta:1
    F(1) = exp(-0.5*((t - 0.06)/0.03)^2);
    F(3) = ln*normrnd(0,1);
    V = A_transpse\'(C_mat*V/delta + F);
    Vi_index(ii + 1) = F(1);
    Vo_index(ii + 1) = V(5);
    ii = ii + 1;
end

X_input = fft(Vi_index);
P2_input = abs(X_input/1000);
P1_input = P2_input(1:1000/2+1);
P1_input(2:end-1) = 2*P1_input(2:end-1);
f = (1/delta)*(0:(1000/2))/1000;

X_output = fft(Vo_index);
P2_output = abs(X_output/1000);
P1_output = P2_output(1:1000/2+1);
P1_output(2:end-1) = 2*P1_output(2:end-1);
f = (1/delta)*(0:(1000/2))/1000;

C_sml = C_mat;
C_med = C_mat;
C_big = C_mat;
C_sml(3,3) = 0;
C_med(3,3) = 0.001;
C_big(3,3) = 0.1;
V_sml = zeros(7,1);
V_med = zeros(7,1);
V_big = zeros(7,1);
Vo_sml(1) = 0;
Voutput_med(1) = 0;
Vout_big(1) = 0;
Vi_index(1) = 0;
ii = 1;
for t = delta:delta:1
    F(1) = exp(-0.5*((t - 0.06)/0.03)^2);
    F(3) = ln*normrnd(0,1);
    V_sml = (C_sml/delta + G)\(C_sml*V_sml/delta + F);

```

```

V_med = (C_med/delta + G)\(C_med*V_med/delta + F);
V_big = (C_big/delta + G)\(C_big*V_big/delta + F);
Vo_sml(ii + 1) = V_sml(5);
Voutput_med(ii + 1) = V_med(5);
Vout_big(ii + 1) = V_big(5);
Vi_index(ii + 1) = F(1);
ii = ii + 1;
end

```

```

delta1 = 0.01;
Vinput_SmlStep(1) = 0;
Voutput_SmlStep(1) = 0;
V = zeros(7,1);
ii = 1;
for t = delta1:delta1:1
    F(1) = exp(-0.5*((t - 0.06)/0.03)^2);
    F(3) = ln*normrnd(0,1);
    V = (C_mat/delta1 + G)\(C_mat*V/delta1 + F);
    Voutput_SmlStep(ii + 1) = V(5);
    Vinput_SmlStep(ii + 1) = F(1);
    ii = ii + 1;
end

```

```

delta2 = 0.1;
Vinput_bigStep(1) = 0;
Voutput_bigStep(1) = 0;
V = zeros(7,1);
ii = 1;
for t = delta2:delta2:1
    F(1) = exp(-0.5*((t - 0.06)/0.03)^2);
    F(3) = ln*normrnd(0,1);
    V = (C_mat/delta2 + G)\(C_mat*V/delta2 + F);
    Voutput_bigStep(ii + 1) = V(5);
    Vinput_bigStep(ii + 1) = F(1);
    ii = ii + 1;
end

```

```

figure(20)
plot(0:delta1:1,Vinput_SmlStep,'b')
hold on

```

```
plot(0:delta1:1,Voutput_SmlStep,'m')
title('Voltage vs time with timestep = 0.003')
xlabel('time (s)')
ylabel('Voltage')
legend('input','output')
grid on
```

```
figure(21)
plot(0:delta2:1,Vinput_bigStep,'m')
hold on
plot(0:delta2:1,Voutput_bigStep,'b')
title('Voltage vs time with time step = 0.01')
xlabel('time (s)')
ylabel('Voltage')
legend('input','output')
grid on
```