

## Uygulama 1

1-) Aşağıdaki formüllerin ters fonksiyonlarını kullanarak logaritmanın ve ya  
yanlışlarını.

$$a) \int \frac{1}{(1+x)^2} dx = \left[ \frac{-1}{1+x} + C \right] \stackrel{F}{=} (\text{Doğru})$$

herhangi bir  $f$  fonk. iin  $F'(x) = f(x)$  o. şekilde  $F(x)$  ters  
 $f'$  ye  $f$ 'nin ters fonksiyonu denir.

$$\int F'(x) dx = \int f(x) dx$$

$$f(x) = -\left(\frac{1}{1+x}\right)' + C \quad \text{olsun.}$$

$$F'(x) = +1 \cdot \left(\frac{1}{1+x}\right)^{-2}$$

$$b) \int \sec^2(\sqrt{x}-1) dx = \underbrace{\frac{1}{\sqrt{x}}}_{F(x)} \tan(\sqrt{x}-1) + C \quad (\text{Doğru}).$$

$$F(x) = \frac{1}{\sqrt{x}} \tan(\sqrt{x}-1) + C \Rightarrow F'(x) = \frac{1}{\sqrt{x}} \sec^2(\sqrt{x}-1) \cdot \cancel{\frac{1}{2x}}$$

$$c) \int \tan \theta \cdot \sec^2 \theta d\theta = \frac{\sec^3 \theta}{3} + C \quad (\text{Yanlış})$$

$$\cos^{-1} \theta$$

$$F'(x) = \frac{1}{\sqrt{x}} \cancel{\theta} \cdot \sec^2 \theta \cdot (\sec \theta)' \quad \left(\frac{1}{\cos \theta}\right)' = -1 \cdot C^{-2} \cdot (-\sin \theta) = -\frac{1}{\cos^2 \theta} \cdot (-\sin \theta)$$

$$= \sec^2 \theta \cdot \frac{(-\sin \theta)}{\cos^2 \theta} = \underline{\sin \theta \cdot \sec^4 \theta}.$$

$$d) \int \sqrt{2x+1} dx = \underbrace{\frac{1}{3} (\sqrt{2x+1})^3}_F(x) + C \quad (\text{Doğru})$$

$$F(x) = \frac{1}{3} ((2x+1)^{1/2})^3 + C = \frac{1}{3} (2x+1)^{3/2} + C$$

$$\Rightarrow F'(x) = \cancel{\frac{1}{3}} \cdot \cancel{\frac{3}{2}} (2x+1)^{1/2} \cdot \cancel{x} = (2x+1)^{1/2} = \sqrt{2x+1}$$

2-) Bir roket denge üzerinde  $20 \text{ m/s}^2$  lik bir sabit ilaveye sahip oluyor. Buğa göre 1 detik sonra hızı ne olur?

Hızın:  $v(t) = \alpha(t) = \frac{d v(t)}{dt} \rightarrow \text{Hız} \Rightarrow v(t) = \int \alpha(t) dt$

  $H(t) = v(t) = \frac{d r(t)}{dt} \rightarrow \text{Konum}$

$$\alpha(t) = 20 = \frac{d v(t)}{dt}$$

$$\Rightarrow \int 20 dt = \int \frac{d v(t)}{dt} dt = v(t)$$

$$\Rightarrow v(t) = 20t + C. \quad (\text{Robotin başlangıçtaki hızının } 0 \text{ old.})$$

gözle seen'e alınırsa

$$v(0) = 0 \quad \text{olduğundan} \quad 0 = 20 \cdot 0 + C \Rightarrow C = 0$$

$$v(t) = 20t$$

$$v(1 \text{ dk}) = v(60) = 20 \cdot 60 = 1200$$

3-) Bir parçacık  $a(t) = \sqrt{t} - \left(\frac{1}{\sqrt{t}}\right)$  i̇emesi ile hareket ediyor.  $t=0$  anında hızının  $v=4/3$  ve konumun  $r=-4/15$  old. varıştak parçacığın konumunu ve hızını veren fonk. elde ediniz.

Gözleme:  $a(t) = \underbrace{\frac{dv(t)}{dt}}_{v} = \sqrt{t} - \frac{1}{\sqrt{t}} = t^{1/2} - t^{-1/2}$

$$\Rightarrow v(t) = \int \sqrt{t} - t^{-1/2} dt = \int \sqrt{t} dt - \int \left(\frac{1}{\sqrt{t}}\right) dt$$

$$= \underbrace{\frac{2}{3} t^{3/2}}_{v} - 2 t^{1/2} + C$$

$v(0) = 4/3 \Rightarrow 4/3 = \frac{2}{3} \cdot 0^{3/2} - 2 \cdot 0^{1/2} + C$

$\Rightarrow 4/3 = C$

$v(t) = \frac{2}{3} t^{3/2} - 2 t^{1/2} + 4/3 \quad (v(t) = \frac{dr(t)}{dt} \rightarrow \text{konum})$

$\Rightarrow r(t) = \int \left( \frac{2}{3} t^{3/2} - 2 t^{1/2} + 4/3 \right) dt$

Ödev  $\downarrow$

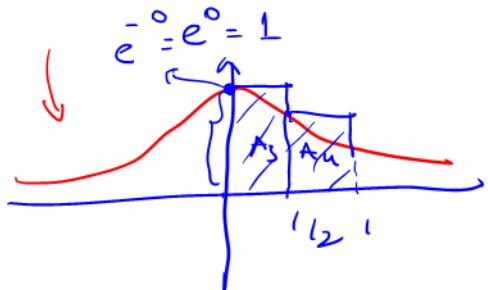
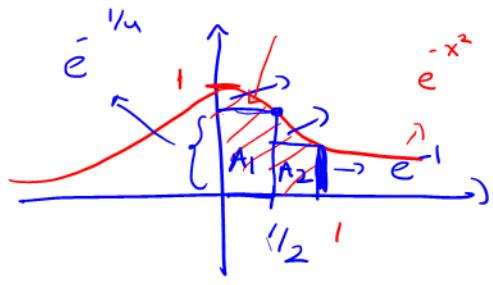
 $= \frac{4}{15} t^{5/2} - \frac{4}{3} t^{3/2} + \frac{4}{3} t + \tilde{C} \rightarrow -4/15$

$r(0) = -4/15 \Rightarrow \tilde{C} = -4/15$

İşlem:  $\frac{1}{2} \left\{ e^{-1/4} + e^1 \right\} \leq \int_0^1 e^{-x^2} dx \leq \frac{1}{2} \left\{ 1 + e^{-1/4} \right\}$  old.

İspatlayınız.

Gözleme:  $\int e^{-x^2} dx$  integralinin sonucunu elementer yollarla elde etmek mümkün değildir.



$$A_1 + A_2 \leq \int_{-1}^1 e^{-x^2} dx \leq A_3 + A_4$$

$$A_1 = \frac{1}{2} \cdot e^{-1/4}, \quad A_2 = \frac{1}{2} \cdot e^{-1}$$

$$A_3 = \frac{1}{2} \cdot 1, \quad A_4 = \frac{1}{2} \cdot e^{-1/4}$$

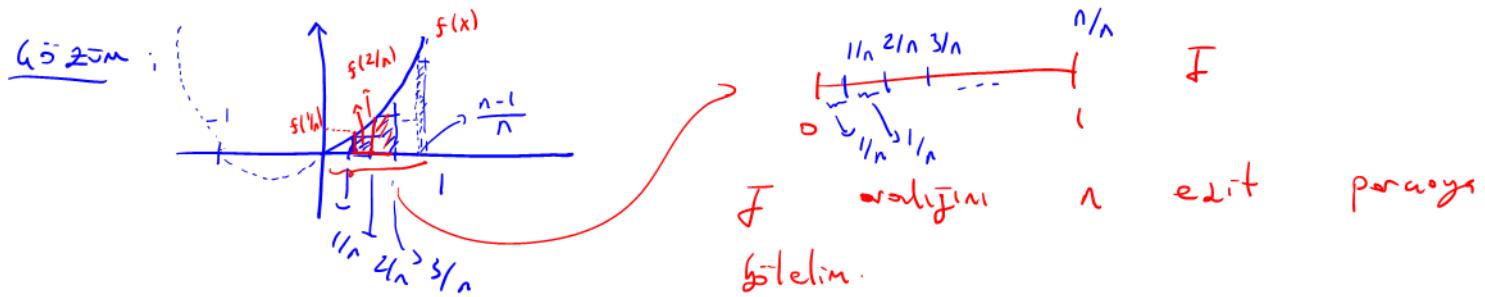
$$A_1 + A_2 = \frac{1}{2} \left\{ e^{-1/4} + e^{-1} \right\} \checkmark$$

$$A_3 + A_4 = \frac{1}{2} \left\{ 1 + e^{-1/4} \right\} \checkmark \text{ bulunur ve}$$

bölgece işaret tamamlandı.

5-) Belirli integralin tanminini kullanarak

$$\int_0^1 (x^2 + x) dx \quad \text{int. hesaplayınız.}$$



$$A = \frac{1}{n} \cdot f\left(\frac{1}{n}\right) + \frac{1}{n} f\left(\frac{2}{n}\right) + \dots + \frac{1}{n} f\left(\frac{n-1}{n}\right)$$

$$= \frac{1}{n} \left\{ \sum_{k=1}^{n-1} f\left(\frac{k}{n}\right) \right\}$$

$$\Rightarrow \int_0^1 f(x) dx = \int_0^1 (x^2 + x) dx = \lim_{n \rightarrow \infty} \frac{1}{n} \left\{ \sum_{k=1}^{n-1} f\left(\frac{k}{n}\right) \right\}$$

$$= \lim_{n \rightarrow \infty} \frac{1}{n} \left\{ \sum_{k=1}^{n-1} \left( \frac{k}{n} \right)^2 + \frac{k}{n} \right\}$$

$$= \lim_{n \rightarrow \infty} \frac{1}{n} \left\{ \sum_{k=1}^{n-1} \frac{k^2}{n^2} + \frac{n-1}{2} \frac{k}{n} \right\}$$

$$= \lim_{n \rightarrow \infty} \frac{1}{n} \left[ \sum_{k=1}^{n-1} \frac{k^2}{2} + \frac{n-1}{n^2} \sum_{k=1}^{n-1} k \right] \xrightarrow{(n-1) \cdot n} \frac{1}{2}$$

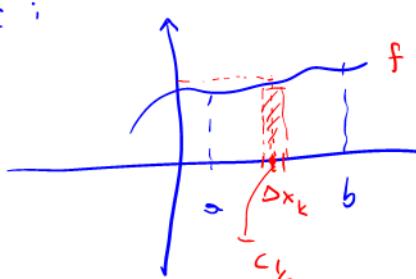
$$\sum_{k=1}^n k^2 = 1^2 + 2^2 + 3^2 + \dots + n^2 = \frac{n \cdot (n+1) \cdot (2n+1)}{6} \quad \left. \begin{array}{l} \text{Ödev: Bu erthizin ispatini} \\ \text{arasturun.} \end{array} \right\}$$

$$\begin{aligned} &= \lim_{n \rightarrow \infty} \frac{1}{n^3} \cdot \left[ \frac{(n-1) \cdot (n) \cdot (2n+1)}{6} \right] + \frac{1}{n^2} \cdot \frac{(n-1) \cdot n}{2} \\ &= \frac{1}{3} + \frac{1}{2} = \frac{5}{6}. \end{aligned}$$

6-) Aşağıdaki limiti belirli integral ile ifade ediniz.

$$A = \lim_{n \rightarrow \infty} \sum_{k=1}^n \frac{\frac{k-1+2n}{k-1+n} \cdot \left( \frac{1}{n} \right)}{c_k}$$

hözüm:



$$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{k=1}^n f(c_k) \cdot \Delta x_k$$

$$\frac{\frac{k-1+2n}{k-1+n}}{c_k} = \frac{n \left\{ \frac{k-1}{n} + 2 \right\}}{n \left\{ \frac{k-1}{n} + 1 \right\}} = \frac{\frac{k-1}{n} + 2}{\frac{k-1}{n} + 1}, \quad \frac{k-1}{n} = c_k$$

$$\frac{1}{n} = \Delta x_k$$

$$= \frac{c_k + 2}{c_k + 1}$$

$$f(x) := \frac{x+2}{x+1} \quad \text{fonk.- formülyüm.}$$

$$A = \lim_{n \rightarrow \infty} \sum_{k=1}^n f(c_k) \cdot \Delta x_k = \int_a^b f(x) dx$$

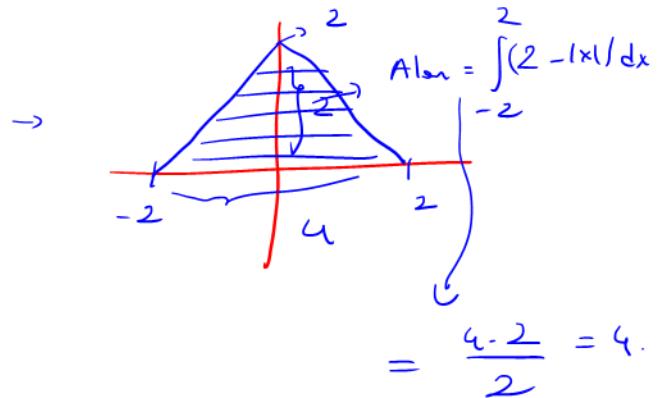
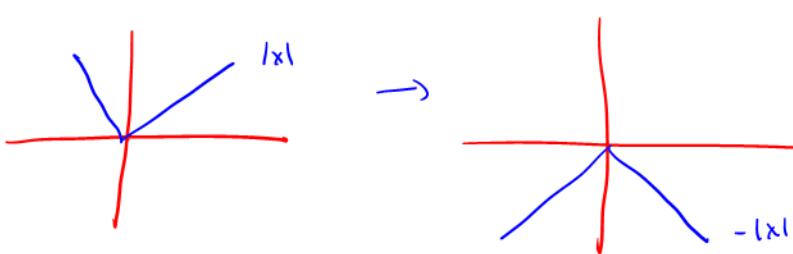
F-) İntegralin geometrik tanımı kılavuz

a-)  $\int_{-2}^2 (2 - |x|) dx$  ve  $\int_{-1}^1 (1 + \sqrt{1-x^2}) dx$  heraplayınız.

Ödev.

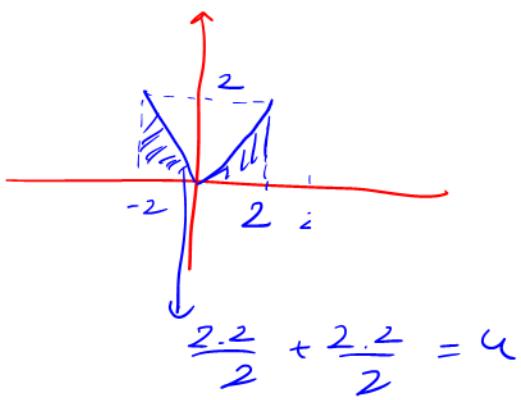
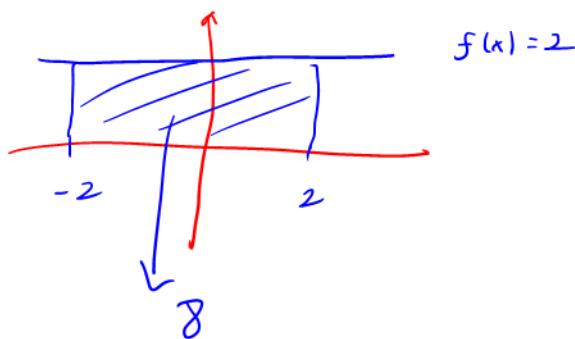
452cm : a-1

1. yol;  $f(x) := 2 - |x|$  fonk.- formülyüm.



2. yol; İntegralin toplanabilir özellilikini kullanınız

$$\int_{-2}^2 (2 - |x|) = \int_{-2}^2 2 - \int_{-2}^2 |x|$$



$$\Rightarrow 8 - 4 = 4.$$