ESP32-S2 Series

Datasheet

SoC with Xtensa® Single-Core 32-bit LX7 Microprocessor Supporting IEEE 802.11b/g/n (2.4 GHz Wi-Fi)

Including:

ESP32-S2

ESP32-S2FH2

ESP32-S2FH4

ESP32-S2FN4R2

ESP32-S2R2



About This Document

This document provides the specifications of ESP32-S2 series of SoCs.

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Product Overview

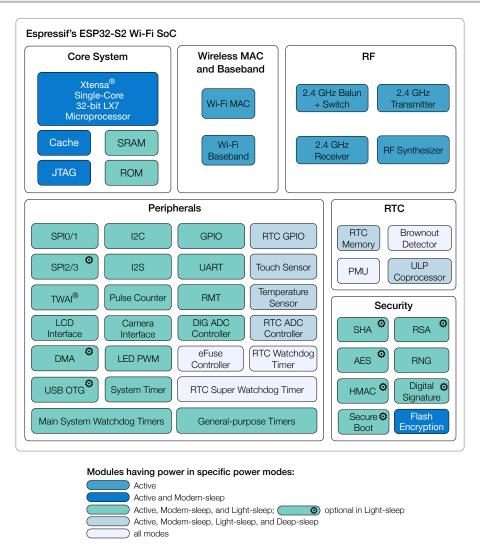


Figure 1: Block Diagram of ESP32-S2

ESP32-S2 series of SoC is a highly-integrated, low-power, 2.4 GHz Wi-Fi System-on-Chip (SoC) solution. With its state-of-the-art power and RF performance, this SoC is an ideal choice for a wide variety of application scenarios relating to Internet of Things (IoT), wearable electronics and smart home.

ESP32-S2 series of SoC includes a Wi-Fi subsystem that integrates a Wi-Fi MAC, Wi-Fi radio and baseband, RF switch, RF balun, power amplifier, low noise amplifier (LNA), etc. The chip is fully compliant with the IEEE 802.11b/g/n protocol and offers a complete Wi-Fi solution.

At the core of this chip is an Xtensa® 32-bit LX7 CPU

that operates at up to 240 MHz. The chip supports application development, without the need for a host MCU.

The on-chip memory includes 320 KB SRAM and 128 KB ROM. It also supports multiple external SPI/QSPI/OSPI flash and external RAM chips for more memory space.

ESP32-S2 series of SoC is designed for ultra-low-power applications with its multiple low-power modes. The ULP coprocessor can operate in ultra-low-power mode. The chip's featured fine-grained clock gating, dynamic voltage and frequency scaling, and adjustable power amplifier output power, contribute to an optimal trade-off

between communication range, data rate and power consumption.

The device provides a rich set of peripheral interfaces including SPI, I2S, UART, I2C, LED_PWM, LCD interface, camera interface, ADC, DAC, touch sensor, temperature sensor, as well as 43 GPIOs. It also includes a full-speed USB On-The-Go (OTG) interface to enable USB communication.

ESP32-S2 series of SoC has several dedicated hardware security features. Cryptographic accelerators are integrated for AES, SHA and RSA algorithms. Additional hardware security features are provided by the RNG, HMAC and Digital Signature modules as well as flash encryption and secure boot signature verification features. These features allow the device to meet stringent security requirements.

Features

Wi-Fi

- IEEE 802.11 b/g/n-compliant
- Supports 20 MHz, 40 MHz bandwidth in 2.4 GHz band
- Single-band 1T1R mode with data rate up to 150 Mbps
- WMM
- TX/RX A-MPDU, RX A-MSDU
- Immediate Block ACK
- Fragmentation and defragmentation

CPU and Memory

- Xtensa® single-core 32-bit LX7 microprocessor, up to 240 MHz
- CoreMark® score:
 - 1 core at 240 MHz: 472.73 CoreMark; 1.97
 CoreMark/MHz
- 128 KB ROM
- 320 KB SRAM

Advanced Peripheral Interfaces

- 43 × programmable GPIOs
- Digital interfaces:
 - 4 × SPI
 - 1 × I2S
 - 2 × I2C
 - 2 × UART
 - 1 × RMT (TX/RX)
 - LED PWM controller, up to 8 channels

- Automatic Beacon monitoring (hardware TSF)
- 4 × virtual Wi-Fi interfaces
- Simultaneous support for Infrastructure Station, SoftAP, and Promiscuous modes
 Note that when ESP32-S2 is in Station mode and performs a scan, the SoftAP channel will change along with the Station channel.
- Antenna diversity
- 802.11mc FTM
- 16 KB SRAM in RTC
- Embedded flash and PSRAM (see details in Chapter 1: ESP32-S2 Series Comparison)
- SPI/QSPI/OSPI supports multiple flash and external RAM chips
- Access to flash accelerated by cache
- Supports flash in-Circuit Programming (ICP)
 - 4 × pulse counters
 - 1 × full-speed USB OTG
 - 1 × DVP 8/16 camera interface, implemented using the hardware resources of I2S
 - 1 × LCD interface (8-bit serial RGB/8080/6800), implemented using the hardware resources of SPI2
 - 1 × LCD interface (8/16/24-bit parallel),

- implemented using the hardware resources of I2S
- DMA controller
- 1 × TWAI® controller compatible with ISO 11898-1 (CAN Specification 2.0)
- Analog interfaces:
 - 2 × 13-bit SAR ADCs, up to 20 channels
 - 2 × 8-bit DACs

Security

- Secure boot
- Flash encryption
- 4096-bit OTP, up to 1792 bits for users
- Cryptographic hardware acceleration:
 - AES-128/192/256 (FIPS PUB 197)

- 14 × touch sensing GPIOs
- 1 × temperature sensor
- Timers:
 - 1 × 64-bit general-purpose timer
 - 1 × 64-bit system timer
 - 3 × watchdog timers
 - 1 × super watchdog timer
 - 1 × XTAL32K watchdog timer
 - Hash (FIPS PUB 180-4)
 - RSA
 - Random Number Generator (RNG)
 - HMAC
 - Digital signature

Applications (A Non-exhaustive List)

- Generic Low-power IoT Sensor Hubs
- Generic Low-power IoT Data Loggers
- Cameras for Video Streaming
- Over-the-top (OTT) Devices
- USB Devices
- Speech Recognition
- Image Recognition
- Mesh Networks
- Home Automation
 - Light control
 - Smart plugs
 - Smart door locks
- Smart Buildings
 - Smart lighting
 - Energy monitoring
- Industrial Automation
 - Industrial wireless control
 - Industrial robotics

- Smart Agriculture
 - Smart greenhouses
 - Smart irrigation
 - Agriculture robotics
- Audio Applications
 - Internet music players
 - Live streaming devices
 - Internet radio players
 - Audio headsets
- Health Care Applications
 - Health monitoring
 - Baby monitors
- Wi-Fi-enabled Toys
 - Remote control toys
 - Proximity sensing toys
 - Educational toys
- Wearable Electronics
 - Smart watches

- Smart bracelets
- Retail & Catering Applications
 - POS machines
 - Service robots

- Touch Sensing Applications
 - Waterproof design
 - Distance sensing applications
 - Linear slider, wheel slider designs

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1.1 ESP32-S2 Series Nomenclature

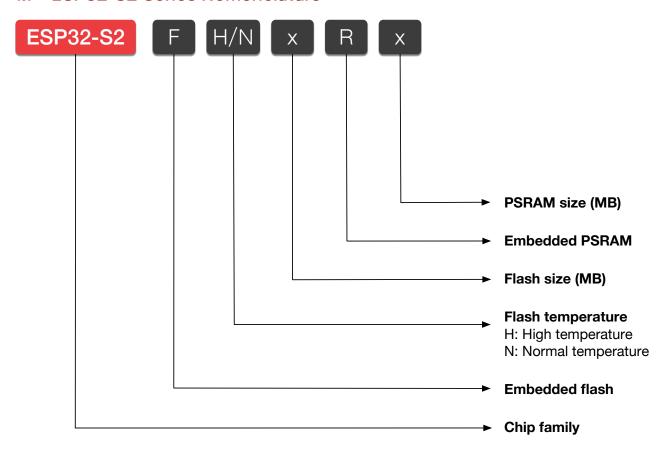


Figure 2: ESP32-S2 Series Nomenclature

1.2 Comparison

Table 1: ESP32-S2 Series Comparison

Ordering Code	Embedded Flash	Embedded PSRAM	Ambient Temperature (°C)
ESP32-S2	_	_	-40 ∼ 105
ESP32-S2FH2	2 MB	_	−40 ~ 105
ESP32-S2FH4	4 MB	_	−40 ~ 105
ESP32-S2FN4R2	4 MB	2 MB	-40 ∼ 85
ESP32-S2R2	_	2 MB	- 40 ∼ 85

Note:

• For junction temperature, please refer to Table 10.

2. Pin Definitions

2.1 Pin Layout

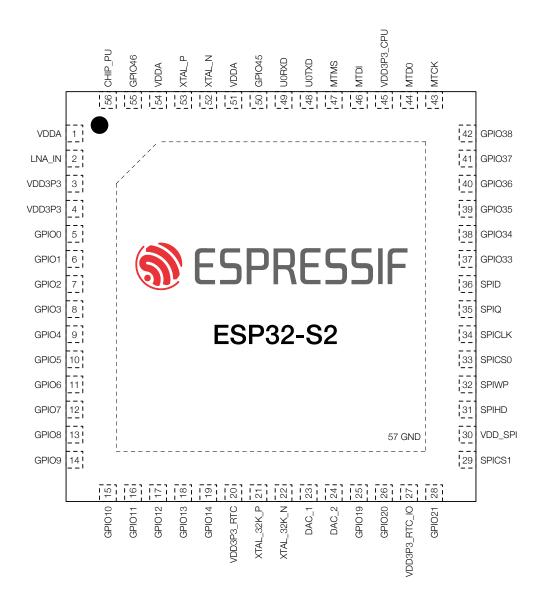


Figure 3: ESP32-S2 Pin Layout (Top View)

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2.2 Pin Description

Table 2: Pin Description

Name	No.	Туре	Power domain	Function					
VDDA	1	P_A	_	Analog power	supply				
LNA_IN	2	1/0	_	RF input and o	utput				
VDD3P3	3	P_A	_	Analog power	supply				
VDD3P3	4	P_A	_	Analog power	supply				
GPI00	5	I/O/T	VDD3P3_RTC_IO	RTC_GPIOO,	GPI00				
GPIO1	6	I/O/T	VDD3P3_RTC_IO	RTC_GPI01,	GPIO1,	TOUCH1,	ADC1_CHO		
GPI02	7	I/O/T	VDD3P3_RTC_IO	RTC_GPI02,	GPIO2,	TOUCH2,	ADC1_CH1		
GPIO3	8	I/O/T	VDD3P3_RTC_IO	RTC_GPIO3,	GPIO3,	TOUCH3,	ADC1_CH2		
GPIO4	9	I/O/T	VDD3P3_RTC_IO	RTC_GPIO4,	GPIO4,	TOUCH4,	ADC1_CH3		
GPI05	10	I/O/T	VDD3P3_RTC_IO	RTC_GPI05,	GPIO5,	TOUCH5,	ADC1_CH4		
GPI06	11	I/O/T	VDD3P3_RTC_IO	RTC_GPI06,	GPI06,	TOUCH6,	ADC1_CH5		
GPI07	12	I/O/T	VDD3P3_RTC_IO	RTC_GPI07,	GPIO7,	TOUCH7,	ADC1_CH6		
GPI08	13	I/O/T	VDD3P3_RTC_IO	RTC_GPI08,	GPIO8,	TOUCH8,	ADC1_CH7		
GPI09	14	I/O/T	VDD3P3_RTC_IO	RTC_GPI09,	GPIO9,	TOUCH9,	ADC1_CH8,	FSPIHD	
GPI010	15	I/O/T	VDD3P3_RTC_IO	RTC_GPI010,	GPI010,	TOUCH10,	ADC1_CH9,	FSPICSO,	FSPIIO4
GPIO11	16	I/O/T	VDD3P3_RTC_IO	RTC_GPIO11,	GPIO11,	TOUCH11,	ADC2_CHO,	FSPID,	FSPII05
GPIO12	17	I/O/T	VDD3P3_RTC_IO	RTC_GPI012,	GPI012,	TOUCH12,	ADC2_CH1,	FSPICLK,	FSPII06
GPIO13	18	I/O/T	VDD3P3_RTC_IO	RTC_GPI013,	GPIO13,	TOUCH13,	ADC2_CH2,	FSPIQ,	FSPII07
GPIO14	19	I/O/T	VDD3P3_RTC_IO	RTC_GPI014,	GPI014,	TOUCH14,	ADC2_CH3,	FSPIWP,	FSPIDQS
VDD3P3_RTC	20	P_A	_	Analog power	supply				
XTAL_32K_P	21	I/O/T	VDD3P3_RTC_IO	RTC_GPI015,	GPI015,	UORTS,	ADC2_CH4,	XTAL_32K_P	
XTAL_32K_N	22	I/O/T	VDD3P3_RTC_IO	RTC_GPI016,	GPI016,	UOCTS,	ADC2_CH5,	XTAL_32K_N	
DAC_1	23	I/O/T	VDD3P3_RTC_IO	RTC_GPIO17,	GPIO17,	U1TXD,	ADC2_CH6,	DAC_1	
DAC_2	24	I/O/T	VDD3P3_RTC_IO	RTC_GPI018,	GPI018,	U1RXD,	ADC2_CH7,	DAC_2,	CLK_OUT3
GPIO19	25	I/O/T	VDD3P3_RTC_IO	RTC_GPI019,	GPI019,	U1RTS,	ADC2_CH8,	CLK_OUT2,	USB_D-
GPI020	26	I/O/T	VDD3P3_RTC_IO	RTC_GPI020,	GPI020,	U1CTS,	ADC2_CH9,	CLK_OUT1,	USB_D+

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Name	No.	Туре	Power domain	Function		
VDD3P3_RTC_IO	27	P_D	VDD3P3_RTC_IO	Input power su	ipply for RT	CIO
GPIO21	28	I/O/T	VDD3P3_RTC_IO	RTC_GPIO21,	GPIO21	
SPICS1	29	I/O/T	VDD_SPI	SPICS1,	GPI026	
VDD_SPI	30	P_D	_	Output power:	supply: 1.8	V or the same voltage as VDD3P3_RTC_IO
SPIHD	31	I/O/T	VDD_SPI	SPIHD,	GPIO27	
SPIWP	32	I/O/T	VDD_SPI	SPIWP,	GPI028	
SPICS0	33	I/O/T	VDD_SPI	SPICSO,	GPIO29	
SPICLK	34	I/O/T	VDD_SPI	SPICLK,	GPI030	
SPIQ	35	I/O/T	VDD_SPI	SPIQ,	GPIO31	
SPID	36	I/O/T	VDD_SPI	SPID,	GPI032	
GPIO33	37	I/O/T	VDD3P3_CPU / VDD_SPI	SPIIO4,	GPI033,	FSPIHD
GPIO34	38	I/O/T	VDD3P3_CPU / VDD_SPI	SPIIO5,	GPI034,	FSPICSO
GPIO35	39	I/O/T	VDD3P3_CPU / VDD_SPI	SPIIO6,	GPI035,	FSPID
GPIO36	40	I/O/T	VDD3P3_CPU / VDD_SPI	SPIIO7,	GPI036,	FSPICLK
GPIO37	41	I/O/T	VDD3P3_CPU / VDD_SPI	SPIDQS,	GPIO37,	FSPIQ
GPIO38	42	I/O/T	VDD3P3_CPU		GPI038,	FSPIWP
MTCK	43	I/O/T	VDD3P3_CPU	MTCK,	GPI039,	CLK_OUT3
MTDO	44	I/O/T	VDD3P3_CPU	MTDO,	GPI040,	CLK_OUT2
VDD3P3_CPU	45	P_D	_	Input power su	ipply for CP	PU IO
MTDI	46	I/O/T	VDD3P3_CPU	MTDI,	GPI041,	CLK_OUT1
MTMS	47	I/O/T	VDD3P3_CPU	MTMS,	GPI042	
UOTXD	48	I/O/T	VDD3P3_CPU	UOTXD,	GPI043,	CLK_OUT1
UORXD	49	I/O/T	VDD3P3_CPU	UORXD,	GPI044,	CLK_OUT2
GPIO45	50	I/O/T	VDD3P3_CPU	GPIO45		
VDDA	51	P_A	_	Analog power:	supply	
XTAL_N	52	_	_	External crystal	output	
XTAL_P	53	_	_	External crystal	input	
VDDA	54	P_A	_	Analog power :	supply	
GPIO46	55	I	VDD3P3_CPU	GPIO46		

Name	No.	Туре	Power domain	Function
				High: on, enables the chip.
CHIP_PU	56	I	VDD3P3_RTC_IO	Low: off, the chip powers off.
				Note: Do not leave the CHIP_PU pin floating.
GND	57	G	_	Ground

 \sim

Pin Definitions

Note:

- P: power pin; I: input; O: output; T: high impedance.
- Ports of embedded flash correspond to pins of ESP32-S2FH2 and ESP32-S2FH4 as follows:
 - CS# = SPICSO
 - DI = SPID
 - DO = SPIQ
 - CLK = SPICLK
 - WP# = SPIWP
 - HOLD# = SPIHD

Ports of embedded PSRAM correspond to pins of ESP32-S2FN4R2 and ESP32-S2R2 as follows:

- CE# = SPICS1
- SI/SIOO = SPID
- SO/SIO1 = SPIQ
- SCLK = SPICLK
- SIO2 = SPIWP
- SIO3 = SPIHD

These pins are not recommended for other uses.

- For the data port connection between ESP32-S2 and external flash, please refer to Section 3.4.2.
- Power supply for GPIO33, GPIO34, GPIO35, GPIO36 and GPIO37 is configurable to be either VDD3P3_CPU (default) or VDD_SPI.
- The pin function in this table refers only to some fixed settings and do not cover all cases for signals that can be input and output through the GPIO matrix. For more information on the GPIO matrix, please refer to Table 20.

2.3 Power Scheme

Digital pins of ESP32-S2 are divided into four different power domains:

- VDD3P3_RTC_IO
- VDD3P3_CPU
- VDD_SPI
- VDD3P3_RTC

VDD3P3_RTC_IO is the input power supply for RTC and CPU.

VDD3P3_CPU is the input power supply for CPU.

VDD_SPI can be an input power supply or an output power supply. VDD_SPI connects to the output of an internal LDO whose input is VDD3P3_RTC_IO. When VDD_SPI is connected to the same PCB net together with VDD3P3_RTC_IO, the internal LDO should be disabled.

VDD3P3_RTC is the input power supply for RTC analog.

The power scheme diagram is shown in Figure 4.

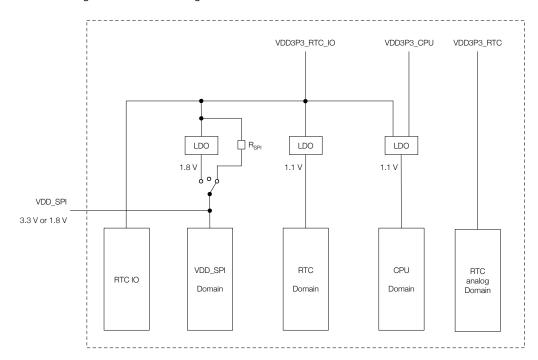


Figure 4: ESP32-S2 Power Scheme

The VDD_SPI voltage can be configured at 1.8 V using an internal LDO, or powered by VDD3P3_RTC_IO via R_{SPI} (nominal 3.3 V). Since ESP32-S2FH2, ESP32-S2FH4, ESP32-S2FN4R2, and ESP32-S2R2 come with both/either 3.3 V SPI flash and/or PSRAM, the VDD_SPI must be powered by VDD3P3_RTC_IO via R_{SPI} . The VDD_SPI can be powered off via software to minimize the current leakage of flash in the Deep-sleep mode.

Notes on CHIP_PU:

The illustration below shows the power-up and reset timing of ESP32-S2. Details about the parameters are listed in Table 3.

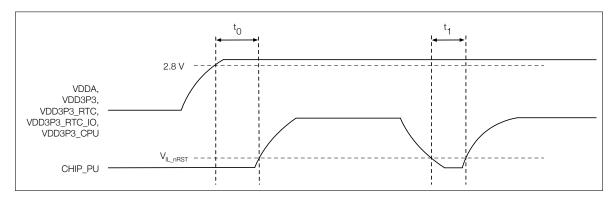


Figure 5: ESP32-S2 Power-up and Reset Timing

Table 3: Description of ESP32-S2 Power-up and Reset Timing Parameters

Parameters	Description	Min	Unit
+	Time between bringing up the VDDA, VDD3P3, VDD3P3_RTC,		
ι ₀	VDD3P3_RTC_IO and VDD3P3_CPU rails, and activating CHIP_PU.	50	μ S
+	Duration of CHIP_PU signal level < V_{IL_nRST} (refer to its value in Table 12 DC	50	μS
l ₁	Characteristics) to reset the chip.	50	

2.4 Strapping Pins

ESP32-S2 has three strapping pins:

- GPI00
- GPIO45
- GPI046

Software can read the values of corresponding bits from register "GPIO_STRAPPING".

During the chip's system reset (power-on-reset, RTC watchdog reset, brownout reset, analog super watchdog reset, and crystal clock glitch detection reset), the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down.

GPIO0, GPIO45 and GPIO46 are connected to the chip's internal weak pull-up/pull-down during the chip reset. Consequently, if they are unconnected or the connected external circuit is high-impedance, the internal weak pull-up/pull-down will determine the default input level of these strapping pins.

To change the strapping bit values, users can apply the external pull-down/pull-up resistances, or use the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32-S2.

After reset, the strapping pins work as normal-function pins.

Refer to Table 4 for a detailed boot-mode configuration of the strapping pins.

Table 4: Strapping Pins

VDD_SPI Voltage ^{1 2}					
Pin	Default	3.3 V	1.8 V		
GPIO45	Pull-down	0	1		
Booting Mode ³					
Pin	Default	SPI Boot	Download Boot		

GPI00	Pull-up	1	0			
GPI046	Pull-down	Don't-care	0			
Enabling/Disabling ROM Messages Print During Booting $^4\ ^5$						
Pin	Default	Enabled	Disabled			
GPIO46	Pull-down	See note 5	See note 5			

Note:

- 1. The functionality of strapping pin GPIO45 to select VDD_SPI voltage may be disabled by setting VDD_SPI_FORCE eFuse to 1. In such a case the voltage is selected with eFuse bit VDD_SPI_TIEH.
- 2. Since ESP32-S2FH2, ESP32-S2FH4, ESP32-S2FN4R2, and ESP32-S2R2 come with both/either 3.3 V SPI flash and/or PSRAM, VDD_SPI must be configured to 3.3 V.
- 3. The strapping combination of GPIO46 = 1 and GPIO0 = 0 is invalid and will trigger unexpected behavior.
- 4. ROM code can be printed over UOTXD (by default) or DAC_1, depending on the eFuse bit.
- 5. When eFuse UART_PRINT_CONTROL value is:
 - O, print is normal during boot and not controlled by GPIO46.
 - 1 and GPIO46 is 0, print is normal during boot; but if GPIO46 is 1, print is disabled.
 - 2 and GPIO46 is 0, print is disabled; but if GPIO46 is 1, print is normal.
 - 3, print is disabled and not controlled by GPIO46.

Regarding the timing requirements for the strapping pins, there are such parameters as setup time and hold time. For more information, see Table 5 and Figure 6.

Table 5: Description of Timing Parameters for the Strapping Pins

Parameter	Description	Min (ms)
+	Setup time is the time reserved for the power rails to stabilize be-	0
t_{SU}	fore the CHIP_PU pin is pulled high to activate the chip.	0
	Hold time is the time reserved for the chip to read the strapping	
t_H	pin values after CHIP_PU is already high and before these pins	3
	start operating as regular IO pins.	

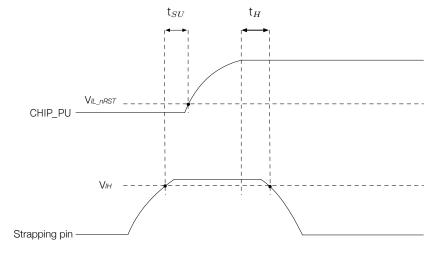


Figure 6: Visualization of Timing Parameters for the Strapping Pins

Functional Description 3.

This chapter describes the functions of ESP32-S2 series of SoCs.

CPU and Memory 3.1

3.1.1 CPU

ESP32-S2 contains one low-power Xtensa® 32-bit LX7 microprocessor with the following features:

- 7-stage pipeline that supports the clock frequency of up to 240 MHz
- 16/24-bit Instruction Set providing high code-density
- support for 32-bit multiplier and 32-bit divider
- unbuffered GPIO instructions
- support for 32 interrupts at six levels
- support for windowed ABI with 64 physical general registers
- support for trace function with TRAX compressor, up to 16 KB trace memory
- JTAG for debugging

For information about the Xtensa® Instruction Set Architecture, please refer to Xtensa® Instruction Set Architecture (ISA) Summary.

3.1.2 Internal Memory

ESP32-S2's internal memory includes:

- 128 KB of ROM: for booting and core functions
- 320 KB of on-chip SRAM: for data and instructions, running at a configurable frequency of up to 240 MHz.
- RTC FAST Memory: 8 KB of SRAM in RTC. It can be accessed by the main CPU. It can retain data in Deep-sleep mode.
- RTC SLOW Memory: 8 KB of SRAM in RTC. It can be accessed by the main CPU or the co-processor. It can retain data in Deep-sleep mode.
- 4 Kbit of eFuse: 1792 bits are reserved for user data, such as encryption key and device ID.
- Embedded flash and PSRAM: see details in Chapter 1: ESP32-S2 Series Comparison

For more information, please refer to Chapter System and Memory in ESP32-S2 Technical Reference Manual.

3.1.3 External Flash and RAM

ESP32-S2 supports multiple external QSPI/OSPI flash and RAM chips. It also supports hardware encryption/decryption based on XTS-AES to protect developers' programs and data in flash and RAM.

The external flash and RAM can be mapped into the CPU instruction memory space and read-only data memory space. The RAM can also be mapped into the CPU data memory space. Up to 1 GB of external flash and RAM can be supported.

Through high-speed caches, ESP32-S2 can support the following mappings at the same time.

• Up to 7.5 MB of instruction memory space can be mapped at a time into flash and RAM. If more than 3.5 MB are mapped, cache performance may be slightly reduced due to the CPU's pipeline characteristics.

- Up to 4 MB of read-only data memory space can be mapped into flash or RAM as individual 64 KB blocks. 8-bit, 16-bit and 32-bit reads are supported.
- Up to 10.5 MB of read-write data memory space can be mapped into RAM as individual 64 KB blocks. 8-bit, 16-bit and 32-bit reads and writes are supported. Blocks from this 10.5 MB space can also be mapped into flash, for read operations only.

Note:

After ESP32-S2 is initialized, firmware can customize the mapping of external RAM or flash into the CPU address space.

For more information, please refer to Chapter <u>System and Memory</u> in *ESP32-S2 Technical Reference Manual*.

3.1.4 Address Mapping Structure

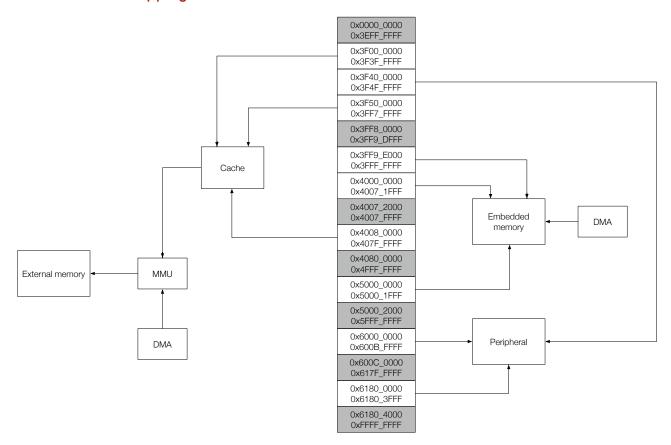


Figure 7: Address Mapping Structure

Note:

The memory space with gray background is not available for use.

3.1.5 Cache

ESP32-S2 has independent instruction Cache and data Cache that have the following features:

- configurable size of 8 KB or 16 KB
- 4-way set associative

- block size of 16 bytes or 32 bytes
- pre-load function
- lock function
- support for critical word first and early restart

System Clocks 3.2

For more information, please refer to Chapter Reset and Clock in ESP32-S2 Technical Reference Manual.

3.2.1 CPU Clock

The CPU clock has four possible sources:

- external 40 MHz crystal clock
- internal 8 MHz oscillator
- PLL clock
- audio PLL clock

The application can select the clock source from the external crystal clock source, the PLL clock, the audio PLL clock, or the internal 8 MHz oscillator. The selected clock source drives the CPU clock directly, or after division, depending on the application.

Note:

ESP32-S2 is unable to operate without an external crystal clock.

3.2.2 RTC Clock

The RTC slow clock has three possible sources:

- external low-speed (32 kHz) crystal clock
- internal RC oscillator (typically about 90 kHz, and adjustable)
- internal 31.25 kHz clock (derived from the internal 8 MHz oscillator divided by 256)

The RTC fast clock has two possible sources:

- external divide-by-4 crystal clock
- internal divide-by-N oscillator of 8 MHz

The RTC slow clock is used for RTC counter, RTC watchdog and low-power controller; while the RTC fast clock for RTC peripherals and sensing controllers.

3.2.3 Audio PLL Clock

The audio clock is generated by the low-noise fractional-N PLL.

Analog Peripherals

For more information, please refer to Chapter On-Chip Sensors and Analog Signal Processing in ESP32-S2 Technical Reference Manual.

3.3.1 Analog-to-Digital Converter (ADC)

ESP32-S2 integrates two 13-bit SAR ADCs and supports measurements on 20 channels (analog-enabled pins). The ULP-coprocessor in ESP32-S2 is also designed to measure voltage. The ULP can operate while the main CPU is in Deep-sleep mode, which lowers the total power consumption. By using threshold settings, and / or via other triggers or events, we can interrupt the CPU from the sleep state.

The ADCs can be configured to measure voltage on up to 20 pins.

For ADC characteristics, please refer to Table 13.

Digital-to-Analog Converter (DAC)

ESP32-S2 has two 8-bit DAC channels that convert two digital signals into two analog voltage signal outputs. The two DAC channels support independent conversions. The design structure is composed of integrated resistor strings and a buffer. This dual DAC supports VDD3P3_RTC_IO power supply as input voltage reference.

3.3.3 Temperature Sensor

The temperature sensor generates a voltage that varies with temperature. The voltage is internally converted via an ADC into a digital value.

The temperature sensor has a range of -20 °C to 110 °C. It is designed primarily to sense the temperature changes inside the chip. The temperature value depends on factors like microcontroller clock frequency or I/O load. Generally, the chip's internal temperature is higher than the ambient operating temperature.

Touch Sensor

ESP32-S2 has 14 capacitive-sensing GPIOs, which detect variations induced by touching or approaching the GPIOs with a finger or other objects. The low-noise nature of the design and the high sensitivity of the circuit allow relatively small pads to be used. Arrays of pads can also be used, so that a larger area or more points can be detected. The touch sensing performance can be further enhanced by the waterproof design and digital filtering feature. The 14 capacitive-sensing GPIOs are listed in Table 6.

Note:

ESP32-S2 Touch Sensor has not passed the Conducted Susceptibility (CS) test for now, and thus has limited application scenarios.

Table 6: Capacitive-Sensing GPIOs Available on ESP32-S2

Capacitive-sensing signal name	Pin name
TOUCH1	GPI01
TOUCH2	GPI02
TOUCH3	GPI03
TOUCH4	GPIO4
TOUCH5	GPI05
TOUCH6	GPI06
TOUCH7	GPI07
TOUCH8	GPI08
TOUCH9	GPI09
TOUCH10	GPIO10

Capacitive-sensing signal name	Pin name
TOUCH11	GPIO11
TOUCH12	GPI012
TOUCH13	GPIO13
TOUCH14	GPI014

Digital Peripherals 3.4

General Purpose Input / Output Interface (GPIO)

ESP32-S2 has 43 GPIO pins which can be assigned various functions by programming the appropriate registers. Some GPIOs can be used both for digital signals but also for analog functions, such as ADC, DAC and touch sensing.

All GPIOs can be configured as internal pull-up or pull-down, or set to high impedance, except for GPIO46, which is fixed to pull-down. When configured as an input, the input value can be read by software through the register. The input can also be set to edge-trigger or level-trigger to generate CPU interrupts. Except for GPIO46 (input only), all digital IO pins are bi-directional, non-inverting and tristate, including input and output buffers with tristate control. These pins can be multiplexed with other functions, such as the UART, SPI, etc. For low-power operations, the GPIOs can be set to hold their states.

For more information, please refer to Chapter IO MUX and GPIO Matrix (GPIO, IO_MUX) in ESP32-S2 Technical Reference Manual.

3.4.2 Serial Peripheral Interface (SPI)

ESP32-S2 features four SPI interfaces (SPIO, SPI1, SPI2 and SPI3). SPIO and SPI1 can only be configured to operate in SPI memory mode; SPI2 can be configured to operate in SPI memory and general-purpose SPI modes; SPI3 can only be configured to operate in general-purpose SPI mode.

• SPI Memory mode

In SPI memory mode, SPIO, SPI1 and SPI2 interface with external SPI memory. Data are transferred in unit of byte. Up to 8-line STR/DDR reads and writes are supported. The clock frequency is configurable to a maximum of 80 MHz in STR mode and a maximum of 40 MHz in DDR mode.

• SPI2 General-purpose SPI (GP-SPI) mode

When SPI2 acts as a general-purpose SPI, it can operate in master and slave modes. The master mode supports 2-line full-duplex communication and 1-/2-/4-/8-line half-duplex communication. The slave mode supports 2-line full-duplex communication and 1-/2-/4-line half-duplex communication. The host's clock frequency is configurable. Data are transferred in unit of byte. The clock polarity (CPOL) and phase (CPHA) are also configurable. The SPI2 interface supports DMA.

- In 2-line full-duplex communication mode, the host's clock frequency is configurable to 80 MHz at most, and the slave's clock frequency to 40 MHz at most. Four modes of SPI transfer format are supported.
- In 1-/2-/4-/8-line half-duplex communication mode, the host's clock frequency is configurable to 80 MHz at most and the four modes of SPI transfer format are supported.
- In 1-/2-/4-line half-duplex communication mode, the slave's clock frequency is configurable to 40 MHz at most, and the four modes of SPI transfer format are also supported.

• SPI3 General-purpose SPI (GP-SPI) mode

As a general-purpose SPI interface, SPI3 can operate in master and slave modes, in 2-line full-duplex and 1-line half-duplex communication modes. The host's clock frequency is configurable. Data are transferred in unit of byte. The clock polarity (CPOL) and phase (CPHA) are also configurable. The SPI3 interface supports DMA.

- In 2-line full-duplex communication mode, the host's clock frequency is configurable to a maximum

of 80 MHz, and the slave's clock frequency to 40 MHz at most. Four modes of SPI transfer format are supported.

- In 1-line half-duplex communication mode, the host's clock frequency is configurable to a maximum of 80 MHz, and the slave's clock frequency to 40 MHz at most. The four modes of SPI transfer format are supported.

The mapping between SPI bus signals and GPIO pins is shown in Table 7:

Table 7: Mapping of SPI Signal Buses and Chip Pins

Standard SPI		Extended SPI			
Full-Duplex	Half-Duplex	Chip Pad Signals			
SPI Signal Bus	SPI Signal Bus	Pin Functions	SPI Signal Bus	FSPI Signal Bus	SPI3 Signal Bus
MOSI	MOSI	D	SPID	FSPID	SPI3_D
MISO	(MISO)	Q	SPIQ	FSPIQ	SPI3_Q
CS	CS	CS	SPICSO ~ 1	FSPICSO ~ 5	SPI3_CS0 ~ 2
CLK	CLK	CLK	SPICLK	FSPICLK	SPI3_CLK
-	-	WP	SPIWP	FSPIWP	-
-	-	HD	SPIHD	FSPIHD	SPI3_HD
-	-	CD	-	FSPICD	SPI3_CD
-	-	DQS	SPIDQS	FSPIDQS	SPI3_DQS
-	-	104 ~ 7	SPIIO4 ~ 7	FSPIIO4 ~ 7	-
-	-	VSYNC	-	FSPI_VSYNC	-
-	-	HSYNC	-	FSPI_HSYNC	-
-	-	DE	-	FSPI_DE	-

In most cases, the data port connection between ESP32-S2 and external flash is as follows:

SPI 8-line mode:

- SPID (SPID) = 100
- SPIQ (SPIQ) = IO1
- SPIWP (SPIWP) = IO2
- SPIHD (SPIHD) = IO3
- GPI033 = I04
- GPIO34 = IO5
- GPI035 = I06
- GPI036 = I07
- GPIO37 = DQS

SPI 4-line mode:

- SPID (SPID) = 100
- SPIQ (SPIQ) = IO1
- SPIWP (SPIWP) = IO2
- SPIHD (SPIHD) = IO3

SPI 2-line mode:

- SPID (SPID) = IOO
- SPIQ (SPIQ) = IO1

SPI 1-line mode:

- SPID (SPID) = DI
- SPIQ (SPIQ) = DO
- SPIWP (SPIWP) = WP#
- SPIHD (SPIHD) = HOLD#

For more information, please refer to Chapter <u>SPI Controller (SPI)</u> in *ESP32-S2 Technical Reference Manual*.

3.4.3 LCD Interface

SPI2 supports parallel 8-bit RGB, I8080 and Moto6800 interfaces. I2S supports 8/16/24-bit parallel interface (8080).

For more information, please refer to Chapter <u>SPI Controller (SPI)</u> and Chapter <u>I2S Controller (I2S)</u> in *ESP32-S2 Technical Reference Manual.*

3.4.4 Universal Asynchronous Receiver Transmitter (UART)

ESP32-S2 has two UART interfaces, i.e., UARTO, UART1, which provide asynchronous communication (RS232 and RS485) and IrDA support, communicating at a speed of up to 5 Mbps. UART provides hardware management of the CTS and RTS signals and software flow control (XON and XOFF). All of the interfaces can be accessed by the DMA controller or directly by the CPU.

For more information, please refer to Chapter <u>UART Controller (UART)</u> in *ESP32-S2 Technical Reference Manual*.

3.4.5 I2C Interface

ESP32-S2 has two I2C bus interfaces which can serve as I2C master or slave, depending on the user's configuration. The I2C interfaces support:

- standard mode (100 Kbit/s)
- fast mode (400 Kbit/s)
- up to 5 MHz (constrained by SDA pull-up strength)
- 7-bit/10-bit addressing mode
- dual addressing mode

Users can program command registers to control I2C interfaces, so that they have more flexibility.

For more information, please refer to Chapter <u>I2C Controller (I2C)</u> in *ESP32-S2 Technical Reference Manual*.

3.4.6 I2S Interface

ESP32-S2 includes a standard I2S interface. It can operate in master or slave mode, in full-duplex and half-duplex communication modes, and can be configured to operate with an 8-/16-/24-/32-bit resolution as an input or output channel. BCK clock frequency, from 10 kHz up to 40 MHz, is supported.

The I2S interface has a dedicated DMA controller. PCM interface is supported.

For more information, please refer to Chapter I2S Controller (I2S) in ESP32-S2 Technical Reference Manual.

3.4.7 Camera Interface

ESP32-S2 supports one 8 or 16-bit DVP image sensor, with clock frequency of up to 40 MHz. The camera interface is implemented by using the hardware resources of I2S.

For more information, please refer to Chapter I2S Controller (I2S) in ESP32-S2 Technical Reference Manual.

3.4.8 Infrared Remote Controller

The infrared remote controller supports four channels of infrared remote transmission and reception. By programming the pulse waveform, it supports various infrared and other single wire protocols. Four channels share a 256 × 32-bit block of memory to store the transmitting or receiving waveform.

For more information, please refer to Chapter Remote Control Peripheral (RMT) in ESP32-S2 Technical Reference Manual.

3.4.9 Pulse Counter

The pulse counter captures pulse and counts pulse edges through multiple modes. It has four channels, each of which captures four signals at a time. The four input signals include two pulse signals and two control signals.

For more information, please refer to Chapter Pulse Count Controller (PCNT) in ESP32-S2 Technical Reference Manual.

3.4.10 LED PWM Controller

The LED PWM controller can generate eight independent channels. The LED PWM controller:

- can generate digital waveforms with configurable periods and duties. The accuracy of duty can be up to 18 bits within a 1 ms period.
- has multiple clock sources, including APB clock and external crystal clock.
- can operate when the CPU is in Light-sleep mode.
- supports gradual increase or decrease of duty cycle, which is useful for the LED RGB color-gradient generator.

For more information, please refer to Chapter LED PWM Controller (LEDC) in ESP32-S2 Technical Reference Manual.

3.4.11 DMA Controller

ESP32-S2 includes a DMA controller that allows peripheral-to-memory and memory-to-memory data transfer at a high speed. It has the following features:

- AHB bus architecture
- Half-duplex and full-duplex mode
- Programmable length of data to be transferred in bytes
- INCR burst transfer when accessing internal RAM

- Access to an address space of 320 KB at most in internal RAM
- Access to an address space of 10.5 MB at most in external RAM
- High-speed data transfer using DMA

For more information, please refer to Chapter DMA Controller (DMA) in ESP32-S2 Technical Reference Manual.

3.4.12 Full-speed USB OTG

ESP32-S2 features a full-speed USB OTG interface which is compliant with the USB 2.0 specification (Note that it does not support the faster 480 Mbit/s high-speed transfer mode). It has the following features:

- software-configurable endpoint settings and suspend/resume
- support for dynamic FIFO sizing
- support for session request protocol (SRP) and host negotiation protocol (HNP)
- a full-speed USB PHY integrated in the chip

For more information, please refer to Chapter USB On-The-Go (USB) in ESP32-S2 Technical Reference Manual.

3.4.13 TWAI® Controller

ESP32-S2 has a TWAI® controller with the following features:

- compatible with ISO 11898-1 protocol (CAN Specification 2.0)
- standard frame format (11-bit ID) and extended frame format (29-bit ID)
- bit rates from 1 Kbit/s to 1 Mbit/s
- multiple modes of operation: Normal, Listen Only, and Self-Test
- 64-byte receive FIFO
- special transmissions: single-shot transmissions and self reception
- acceptance filter (single and dual filter modes)
- error detection and handling: error counters, configurable error interrupt threshold, error code capture, arbitration lost capture

For more information, please refer to Chapter Two-wire Automotive Interface (TWAI) in ESP32-S2 Technical Reference Manual.

3.5 Radio and Wi-Fi

The ESP32-S2 radio consists of the following blocks:

- 2.4 GHz receiver
- 2.4 GHz transmitter
- Bias and regulators
- Balun and transmit-receive switch
- Clock generator

3.5.1 2.4 GHz Receiver

The 2.4 GHz receiver demodulates the 2.4 GHz RF signal to quadrature baseband signals and converts them to the digital domain with two high-resolution, high-speed ADCs. To adapt to varying signal channel conditions, RF filters, Automatic Gain Control (AGC), DC offset cancelation circuits and baseband filters are integrated with ESP32-S2.

3.5.2 2.4 GHz Transmitter

The 2.4 GHz transmitter modulates the quadrature baseband signals to the 2.4 GHz RF signal, and drives the antenna with a high-powered Complementary Metal Oxide Semiconductor (CMOS) power amplifier. The use of digital calibration further improves the linearity of the power amplifier.

Additional calibrations are integrated to cancel any radio imperfections, such as:

- carrier leakage
- I/Q amplitude/phase matching
- baseband nonlinearities
- RF nonlinearities
- antenna matching

These built-in calibration routines reduce the cost, time, and specialized equipment required for product testing, and certification.

3.5.3 Clock Generator

The clock generator produces quadrature clock signals of 2.4 GHz for both the receiver and the transmitter. All components of the clock generator are integrated into the chip, including all inductors, varactors, filters, regulators and dividers.

The clock generator has built-in calibration and self-test circuits. Quadrature clock phases and phase noise are optimized on-chip with patented calibration algorithms which ensure the best performance of the receiver and the transmitter.

3.5.4 Wi-Fi Radio and Baseband

The ESP32-S2 Wi-Fi radio and baseband support the following features:

- 802.11b/g/n
- 802.11n MCSO-7 that supports 20 MHz and 40 MHz bandwidth
- 802.11n MCS32
- 802.11n 0.4 μ s guard-interval
- single stream, data rate up to 150 Mbps
- STBC RX (Single spatial stream)
- adjustable transmitting power
- antenna diversity

ESP32-S2 supports antenna diversity with an external RF switch. One or more GPlOs control the RF switch and select the best antenna to minimize the effects of channel imperfections.

3.5.5 Wi-Fi MAC

ESP32-S2 implements the full 802.11 b/g/n Wi-Fi MAC protocol. It supports the Basic Service Set (BSS) STA and SoftAP operations under the Distributed Control Function (DCF). Power management is handled automatically with minimal host interaction to minimize the active-duty period.

The ESP32-S2 Wi-Fi MAC applies low-level protocol functions automatically. They are as follows:

- 4 × virtual Wi-Fi interfaces
- simultaneous Infrastructure BSS Station mode/SoftAP mode/Promiscuous mode
- RTS protection, CTS protection, Immediate Block ACK
- fragmentation and defragmentation
- TX/RX A-MPDU, RX A-MSDU
- TXOP
- WMM
- CCMP, TKIP, WAPI, WEP, BIP
- automatic beacon monitoring (hardware TSF)
- 802.11mc FTM

3.5.6 Networking Features

Users are provided with libraries for TCP/IP networking, ESP-MESH networking, and other networking protocols over Wi-Fi. TLS 1.0, 1.1 and 1.2 support is also provided.

3.6 RTC and Low-Power Management

3.6.1 Power Management Unit (PMU)

With the use of advanced power-management technologies, ESP32-S2 can switch between different power modes.

- Active mode: CPU and chip radio are powered on. The chip can receive, transmit, or listen.
- Modem-sleep mode: The CPU is operational and the clock speed can be reduced. The Wi-Fi baseband and radio are disabled, but Wi-Fi connection can remain active.
- Light-sleep mode: The CPU is paused. The RTC peripherals, as well as the ULP co-processor are running. Any wake-up events (MAC, host, RTC timer, or external interrupts) will wake up the chip. Wi-Fi connection can remain active.
- Deep-sleep mode: Only the RTC memory and RTC peripherals are powered on. Wi-Fi connection data are stored in the RTC memory. The ULP co-processor is functional.
- Hibernation mode: The internal 8-MHz oscillator and ULP co-processor are disabled. The RTC recovery
 memory is powered down. Only one RTC timer on the slow clock and certain RTC GPIOs are active. The
 RTC timer or the RTC GPIOs can wake up the chip from the Hibernation mode.

For power consumption in different power modes, please refer to Table 4.6.2.

For more information, please refer to Chapter <u>Low-Power Management (RTC_CNTL)</u> in *ESP32-S2 Technical Reference Manual*.

3.6.2 Ultra-Low-Power Co-processor

The ULP co-processor is designed as a simplified, low-power replacement of CPU in sleep modes. It can be also used to supplement the functions of the CPU in normal working mode. The ULP co-processor and RTC memory remain powered on during the Deep-sleep mode. Hence, the developer can store a program for the ULP co-processor in the RTC slow memory to access RTC GPIO, RTC peripheral devices, RTC timers and internal sensors during the Deep-sleep mode.

ESP32-S2 has two ULP co-processors, with one based on RISC-V instruction set architecture (ULP-RISC-V) and the other on finite state machine (ULP-FSM). The clock of the co-processor is the internal 8 MHz oscillator.

ULP-RISC-V has the following features:

- support for RV32IMC instruction set
- thirty-two 32-bit general-purpose registers
- 32-bit multiplier and divider
- support for interrupts
- boot by the CPU, its dedicated timer, or RTC GPIO

ULP-FSM has the following features:

- support for common instructions including arithmetic, jump, and program control instructions
- support for on-board sensor measurement instructions
- boot by the CPU, its dedicated timer, or RTC GPIO

Note that these two co-processors cannot work simultaneously.

For more information, please refer to Chapter <u>ULP Coprocessor (ULP)</u> in *ESP32-S2 Technical Reference Manual*.

3.7 Timers and Watchdogs

3.7.1 64-bit Timers

There are four general-purpose timers embedded in ESP32-S2. They are all 64-bit generic timers which are based on 16-bit prescalers and 64-bit auto-reload-capable up/down-timers.

The timers' features are summarized as follows:

- a 16-bit clock prescaler, from 1 to 65536
- a 64-bit time-base counter programmable to be incrementing or decrementing
- able to read real-time value of the time-base counter
- halting and resuming the time-base counter
- programmable alarm generation
- timer value reload (Auto-reload at alarm or software-controlled instant reload)
- level and edge interrupt generation

For more information, please refer to Chapter <u>Timer Group (TIMG)</u> in *ESP32-S2 Technical Reference Manual*.

3.7.2 Watchdog Timers

The ESP32-S2 contains three watchdog timers: one in each of the two timer groups (called Main System Watchdog Timers, or MWDT) and one in the RTC Module (called the RTC Watchdog Timer, or RWDT). Each watchdog timer allows for four separately configurable stages and each stage can be programmed to take one of three (or four for RWDT) actions upon expiry, unless the watchdog is fed or disabled. The actions upon expiry are: interrupt, CPU reset, core reset and system reset. Only RWDT can trigger a system reset that will reset the entire digital circuits, which is the main system including the RTC itself. A timeout value can be set for each stage individually.

During the flash boot process, RWDT and the first MWDT are enabled automatically in order to detect and recover from booting errors.

Watchdog timers have the following features:

- four stages, each with a programmable timeout value. Each stage can be configured and enabled/disabled separately
- one of three/four (for MWDTs/ RWDT) possible actions (interrupt, CPU reset, core reset and system reset) available upon expiry of each stage
- 32-bit expiry counter
- write protection, to prevent RWDT and MWDT configuration from being altered inadvertently
- flash boot protection If the boot process from an SPI flash does not complete within a predetermined period of time, the watchdog will reboot the entire main system.

For more information, please refer to Chapter Watchdog Timers (WDT) in ESP32-S2 Technical Reference Manual.

Cryptographic Hardware Accelerators

ESP32-S2 is equipped with hardware accelerators of general algorithms, such as AES (FIPS PUB 197), ECB/CBC/OFB/CFB/CTR (NIST SP 800-38A), GCM (NIST SP 800-38D), SHA (FIPS PUB 180-4), and RSA, which support independent arithmetic, such as large-number multiplication and large-number modular multiplication. The maximum operation length for RSA and large-number modular multiplication is 4096 bits. The maximum operand length for large-number multiplication is 2048 bits.

Physical Security Features 3.9

- Transparent external flash and RAM encryption (AES-XTS) with software inaccessible key prevents unauthorized readout of user application code or data.
- Secure Boot feature uses a hardware root of trust to ensure only signed firmware (with RSA-PSS signature) can be booted.
- HMAC module can use a software inaccessible MAC key to generate SHA-HMAC signatures for identity verification, as well as other uses.
- Digital Signature module can use a software inaccessible secure key to generate MAC signatures for identity verification.

Peripheral Pin Configurations 3.10

Table 8: Peripheral Pin Configurations

Interface	Signal	Pin	Function
ADC	ADC1_CHO	GPI01	Two 13-bit SAR ADCs
ADC1	ADC1_CH1	GPIO2	
	ADC1_CH2	GPIO3	
	ADC1_CH3	GPIO4	
	ADC1_CH4	GPI05	
	ADC1_CH5	GPIO6	
	ADC1_CH6	GPI07	
	ADC1_CH7	GPI08	
	ADC1_CH8	GPI09	
	ADC1_CH9	GPIO10	
	ADC2_CHO	GPIO11	
	ADC2_CH1	GPIO12	
	ADC2_CH2	GPIO13	
	ADC2_CH3	GPIO14	
	ADC2_CH4	XTAL_32K_P	
	ADC2_CH5	XTAL_32K_N	
	ADC2_CH6	DAC_1	
	ADC2_CH7	DAC_2	
	ADC2_CH8	GPIO19	
	ADC2_CH9	GPI020	
DAC	DAC_1	DAC_1	Two 8-bit DACs
	DAC_2	DAC_2	
Touch sensor	TOUCH1	GPIO1	Capacitive touch sensors
	TOUCH2	GPIO2	
	TOUCH3	GPIO3	
	TOUCH4	GPIO4	
	TOUCH5	GPIO5	
	TOUCH6	GPI06	
	TOUCH7	GPI07	
	TOUCH8	GPIO8	
	TOUCH9	GPIO9	
	TOUCH10	GPIO10	
	TOUCH11	GPIO11	
	TOUCH12	GPIO12	
	TOUCH13	GPIO13	
	TOUCH14	GPIO14	
JTAG	MTDI	MTDI	JTAG for software debugging
	MTCK	MTCK	
	MTMS	MTMS	
	MTDO	MTDO	
UART	UORXD_in	Any GPIO pins	Two UART channels with hardware flow-control

Interface	Signal	Pin	Function
	UOCTS_in		
	UODSR_in		
	UOTXD_out		
	UORTS_out		
	UODTR_out		
	U1RXD_in		
	U1CTS_in		
	U1TXD_out		
	U1RTS_out		
12C	I2CEXTO_SCL_in	Any GPIO pins	Two I2C channels in slave or master mode
	I2CEXTO_SDA_in		
	I2CEXT1_SCL_in		
	I2CEXT1_SDA_in		
	I2CEXTO_SCL_out		
	I2CEXTO_SDA_out		
	I2CEXT1_SCL_out		
	I2CEXT1_SDA_out		
LED PWM	ledc_ls_sig_out0~7	Any GPIO pins	8 independent channels, 80 MHz clock/RTC
			clock/XTAL clock. Duty accuracy: 18 bits
128	12S0I_DATA_in0~15	Any GPIO pins	Stereo input and output from/to the audiocodec;
	I2SOO_BCK_in		parallel LCD data output; parallel camera data
	12S00_WS_in		input
	I2SOI_BCK_in		
	12S0I_WS_in		
	I2SOI_H_SYNC		
	I2SOI_V_SYNC		
	I2SOI_H_ENABLE		
	I2SOO_BCK_out		
	I2SOO_WS_out		
	I2SOI_BCK_out		
	I2SOI_WS_out		
	I2SOO_DATA_out0~23		
Infrared Remote	RMT_SIG_INO~3	Any GPIO pins	Four channels for an IR transceiver of
controller	RMT_SIG_OUTO~3		various waveforms
SPIO/1	SPICLK_out	SPICLK	Support Standard SPI, Dual SPI, QSPI, QPI,
	SPICSO_out	SPICS0	OSPI, and OPI. Support STR and DDR modes.
	SPICS1_out	SPICS1	Support interface with external flash and RAM
	SPID_in/out	SPID	
	SPIQ_in/out	SPIQ	
	SPIWP_in/out	SPIWP	
	SPIHD_in/out	SPIHD	
	SPID4_in/out	GPIO33	
	SPID5_in/out	GPIO34	
	SPID6_in/out	GPIO35	
	SPID7_in/out	GPIO36	

Interface	Signal	Pin	Function
	SPIDQS_in/out	GPIO37	
SPI2	FSPICLK_in/out	Any GPIO pins	Cupports CDI that any interfere with LCD and
	FSPICSO_in/out		Supports SPI that can interface with LCD and
	FSPICS1 ~ 5_out		other external devices. Supports the following
	FSPID_in/out		features:
	FSPIQ_in/out		Both master and slave modes Four modes of SDI transfer formet.
	FSPIWP_in/out		Four modes of SPI transfer format Configurable SPI transfer format
	FSPIHD_in/out		Configurable SPI frequency 20 byte FIFO or DMA bytes
	FSPIIO4 ~ 7_in/out		72-byte FIFO or DMA buffer Supports Standard SDL Dual SDL OSDL ODL
	FSPIDQS_out		Supports Standard SPI, Dual SPI, QSPI, QPI,
	FSPICD_out		OSPI, and OPI. Supports STR and DDR modes.
	FSPI_VSYNC_out		Supports interface with external flash and RAM
	FSPI_HSYNC_out		
	FSPI_DE_out		
SPI3	SPI3_CLK_in/out	Any GPIO pins	Supports Standard SPI, with the following
	SPI3_CSO_in/out		features:
	SPI3_CS1_out		Both master and slave modes
	SPI3_CS2_out		Four modes of SPI transfer format
	SPI3_D_in/out		Configurable SPI frequency;
	SPI3_Q_in/out		72-byte FIFO or DMA buffer.
	SPI3_HD_in/out		
	SPI3_DQS_out		
	SPI3_CD_out		
Pulse counter	pcnt_sig_ch0_in0	Any GPIO pins	Captures pulse and counts pulse edges in
	pcnt_sig_ch1_in0		multiple different modes
	pcnt_ctrl_ch0_in0		
	pcnt_ctrl_ch1_in0		
	pcnt_sig_ch0_in1		
	pcnt_sig_ch1_in1		
	pcnt_ctrl_ch0_in1		
	pcnt_ctrl_ch1_in1		
	pcnt_sig_ch0_in2		
	pcnt_sig_ch1_in2		
	pcnt_ctrl_ch0_in2		
	pcnt_ctrl_ch1_in2		
	pcnt_sig_ch0_in3		
	pcnt_sig_ch1_in3		
	pcnt_ctrl_ch0_in3		
	pcnt_ctrl_ch1_in3		
USB OTG	D-	GPIO19	Full-speed USB OTG
	D+	GPIO20	
TWAI	twai_rx	Any GPIO pins	Compatible with ISO 11898-1 protocol
	twai_tx		
1	twai_bus_off_on	1	

3 Functional Description

Interface	Signal	Pin	Function
	twai_clkout		

Note:

• GPIO46 is input-only and can not be used for output function.

Electrical Characteristics 4.

4.1 **Absolute Maximum Ratings**

Stresses beyond the absolute maximum ratings listed in the table below may cause permanent damage to the device. These are stress ratings only, and do not refer to the functional operation of the device.

Table 9: Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit
VDDA, VDD3P3, VDD3P3_RTC,	Voltage applied to power supply	-0.3	3.6	\/
VDD3P3_CPU, VDD_SPI, VDD3P3_RTC_IO	pins per power domain	-0.3	3.0	V
	Cumulative IO output current	1800		mA
T_{STORE}	Storage temperature	-40	150	°C

Recommended Operating Conditions

Table 10: Recommended Operating Conditions

Symbol	Parameter	Min	Тур	Max	Unit
VDDA, VDD3P3,	Voltage applied to power supply pins per power domain	2.8	3.3	3.6	V
VDD3P3_RTC	voltage applied to power supply pills per power domain	2.0	3.3	ა.0	V
VDD_SPI (working as		1.0	2.2	3.6	V
input power supply) ¹		1.8	3.3	3.0	V
VDD3P3_RTC_IO ²	_	3.0	3.3	3.6	V
VDD3P3_CPU ³	Voltage applied to power supply pin	2.8	3.3	3.6	V
$ V_{UDD} ^4$	Current delivered by external power supply	0.5	_	_	Α
T_J	Junction temperature	-40	_	125	°C

Note:

- 1. Please refer to Power Scheme, section 2.3, for more information.
- 2. When VDD_SPI is used to drive peripherals, VDD3P3_RTC_IO should comply with the peripherals' specifications. For more information, please refer to Table 11.
- 3. To write eFuse, VDD3P3_CPU should not be higher than 3.3 V.
- 4. When using a single-power supply, the recommended output current is 500 mA or more.

4.3 VDD_SPI Output Characteristics

Table 11: VDD_SPI Output Characteristics

Symbol	Parameter	Тур	Unit
R_{SPI}	On-resistance in 3.3 V mode	5	Ω
$ _{SPI}$	Output current in 1.8 V mode	40	mΑ

Note:

In real-life applications, when VDD_SPI works in 3.3 V output mode, VDD3P3_RTC_IO may be affected by R_{SPI} . For example, when VDD3P3_RTC_IO is used to drive an external 3.3 V flash, it should comply with the following specifications:

VDD3P3_RTC_IO > VDD_flash_min + I_flash_max* R_{SPI}

Among which, VDD_flash_min is the minimum operating voltage of the flash, and I_flash_max the maximum current.

For more information, please refer to Power Scheme, section 2.3.

4.4 DC Characteristics (3.3 V, 25 °C)

Table 12: DC Characteristics (3.3 V, 25 °C)

Symbol	Parameter	Min	Тур	Max	Unit
C_{IN}	Pin capacitance	_	2	_	pF
V_{IH}	High-level input voltage	0.75 × VDD ¹	_	VDD ¹ + 0.3	V
V_{IL}	Low-level input voltage	-0.3	_	0.25 × VDD ¹	V
$ I_{IH} $	High-level input current	_	_	50	nA
_{IL}	Low-level input current	_	_	50	nA
V_{OH}^2	High-level output voltage	$0.8 \times VDD^1$	_	_	V
V_{OL}^2	Low-level output voltage	_	_	0.1 × VDD ¹	V
	High-level source current (VDD 1 = 3.3 V, V $_{OH}$		40		mA
$ _{OH}$	>= 2.64 V, PAD_DRIVER = 3)	_	40	_	IIIA
	Low-level sink current (VDD1 = 3.3 V, V_{OL} =		28		mA
$ I_{OL} $	0.495 V, PAD_DRIVER = 3)	_	20	_	IIIA
R_{PU}	Pull-up resistor	_	45	_	kΩ
R_{PD}	Pull-down resistor	_	45	_	kΩ
V_{IH_nRST}	Chip reset release voltage	0.75 × VDD ¹	_	VDD ¹ + 0.3	V
V_{IL_nRST}	Chip reset voltage	-0.3	_	0.25 × VDD ¹	V

Note:

- 1. VDD is the I/O voltage for a particular power domain of pins.
- 2. V_{OH} and V_{OL} are measured using high-impedance load.

4.5 ADC Characteristics

Table 13: ADC Characteristics

Parameter	Description	Min	Max	Unit
DNL (Differential nonlinearity) ²	RTC controller; ADC connected to an	– 7	7	LSB
DNE (Differential Horilineanty)	external 100 nF capacitor; DC signal input;	-/	/	LOD
INL (Integral nonlinearity)	ambient temperature at 25 °C;	-12	10	LSB
inc (integral northleanty)	Wi-Fi off	-12	12	LOD

Note:

- 1. When reading voltages greater than 2450 mV, ADC accuracy will be worse than that in the table above.
- 2. To get better DNL results, users can sample multiple times and apply a filter, or calculate the average value.
- 3. kSPS means kilo samples-per-second.
- 4. MSPS means million samples-per-second.

Current Consumption Characteristics 4.6

4.6.1 RF Current Consumption in Active Mode

The current consumption measurements are taken with a 3.3 V supply at 25 °C of ambient temperature at the RF port. All transmitters' measurements are based on a 100% duty cycle.

Table 14: Current Consumption Depending on RF Modes

Mode	Descrip	Description	
		802.11b, 20 MHz, 1 Mbps, @19.5 dBm	310
	TV	802.11g, 20 MHz, 54 Mbps, @15 dBm	220
	1 1 1	802.11n, 20 MHz, MCS7, @13 dBm	200
		802.11n, 40 MHz, MCS7, @13 dBm	160
	DV1	802.11b/g/n, 20 MHz	63
	802.11n, 40 MHz	68	

Note:

The current consumption figures for in RX mode are for cases when the peripherals are disabled and the CPU idle.

4.6.2 Current Consumption in Other Modes

The measurements below are applicable to ESP32-S2, ESP32-S2FH2, and ESP32-S2FH4. Since ESP32-S2FN4R2 and ESP32-S2R2 are embedded with PSRAM, their current consumption might be higher.

Table 15: Current Consumption in Modem-sleep Mode

	CPU Frequency		Тур		
Mode (MHz)		Description	All Peripherals Clocks	All Peripherals Clocks	
	(IVITZ)		Disabled (mA)	Enabled (mA) ¹	
240 Modem-sleep ^{2,3} 160 80	CPU is idle	20.0	28.0		
	240	CPU is running	23.0	32.0	
	160	CPU is idle	14.0	21.0	
	100	CPU is running	16.0	24.0	
	80	CPU is idle	10.5	18.4	
		CPU is running	12.0	20.0	

¹ In practice, the current consumption might be different depending on which peripherals are enabled.

² In Modem-sleep mode, Wi-Fi is clock gated.

³ In Modem-sleep mode, the consumption might be higher when accessing flash. For a flash rated at 80 Mbit/s, in SPI 2-line mode the consumption is 10 mA.

Table 16: Current Consumption in Low-Power Modes

Mode	Description		Typ (μ A)
Light-sleep ¹	VDD_SPI and Wi-Fi are powered down, and all GPIOs are high-impedance		750
	The ULP co-processor	ULP-FSM	170
	is powered on ²	ULP-RISC-V	190
Deep-sleep	ULP sensor-monitored pattern ³		22
	RTC timer + RTC memor	У	25
	RTC timer only		20
Power off	CHIP_PU is set to low le	vel, the chip is powered off	1

¹ In Light-sleep mode, with all related SPI pins pulled up, the current consumption of the embedded PSRAM is 140 μ A. Chip variants with embedded PSRAM include ESP32-S2FN4R2 and ESP32-S2R2.

4.7 Reliability Qualifications

Table 17: Reliability Qualifications

Test Item	Test Conditions	Test Standard
HTOL (High Temperature Operating Life)	125 °C, 1000 hours	JESD22-A108
ESD (Electro-Static	HBM (Human Body Mode) ¹ ± 2000 V	JS-001
Discharge Sensitivity)	CDM (Charge Device Mode) ² ± 500 V	JS-002
Latch up	Current trigger ± 200 mA	JESD78
Laterrup	Voltage trigger 1.5 × VDD $_{max}$	JESD/O
Preconditioning	Bake 24 hours @125 °C Moisture soak (level 3: 192 hours @30 °C, 60% RH) IR reflow solder: 260 + 0 °C, 20 seconds, three times	J-STD-020, JESD47, JESD22-A113
TCT (Temperature Cycling Test)	-65 °C / 150 °C, 500 cycles	JESD22-A104
uHAST (Highly Accelerated Stress Test, unbiased)	130 °C, 85% RH, 96 hours	JESD22-A118
HTSL (High Temperature Storage Life)	150 °C, 1000 hours	JESD22-A103
LTSL (Low Temperature Storage Life)	- 40 °C, 1000 hours	JESD22-A119

^{1.} JEDEC document JEP155 states that 500 V HBM allows safe manufacturing with a standard ESD control process.

² During Deep-sleep, when the ULP co-processor is powered on, peripherals such as GPIO and I2C are able to operate.

³ The "ULP sensor-monitored pattern" refers to the mode where the ULP coprocessor or the sensor works periodically. When touch sensors work with a duty cycle of 1%, the typical current consumption is 22 μ A.

^{2.} JEDEC document JEP157 states that 250 V CDM allows safe manufacturing with a standard ESD control process.

4.8 Wi-Fi Radio

4.8.1 Transmitter Characteristics

Table 18: Transmitter Characteristics

Parameter	Rate	Тур	Unit
TX Power	11b, 1 Mbps	19.5	dBm
	11b, 11 Mbps	19.5	
	11g, 6 Mbps	18	
	11g, 54 Mbps	15	
	11n, HT20, MCS0	18	
	11n, HT20, MCS7	13	
	11n, HT40, MCS0	18	
	11n, HT40, MCS7	13	

4.8.2 Receiver Characteristics

Table 19: Receiver Characteristics

Parameter	Rate	Тур	Unit
RX Sensitivity	1 Mbps	-97	dBm
	2 Mbps	-95	
	5.5 Mbps	-93	
	11 Mbps	-88	
	6 Mbps	-92	
	9 Mbps	-91	
	12 Mbps	-89	
	18 Mbps	-87	
	24 Mbps	-84	
	36 Mbps	-80	
	48 Mbps	-76	
	54 Mbps	-75	
	11n, HT20, MCS0	-92	
	11n, HT20, MCS1	-88	
	11n, HT20, MCS2	-85	
	11n, HT20, MCS3	-83	
	11n, HT20, MCS4	-79	
	11n, HT20, MCS5	-75	
	11n, HT20, MCS6	-74	
	11n, HT20, MCS7	-72	
	11n, HT40, MCS0	-89	
	11n, HT40, MCS1	-86	
	11n, HT40, MCS2	-83	
	11n, HT40, MCS3	-80	
	11n, HT40, MCS4	-76	
	11n, HT40, MCS5	-72	

Parameter	Rate	Тур	Unit
	11n, HT40, MCS6	-71	
	11n, HT40, MCS7	-69	
RX Maximum Input Level	11b, 1 Mbps	5	dBm
	11b, 11 Mbps	5	
	11g, 6 Mbps	5	
	11g, 54 Mbps	0	
	11n, HT20, MCS0	5	
	11n, HT20, MCS7	0	
	11n, HT40, MCS0	5	
	11n, HT40, MCS7	0	
Adjacent Channel Rejection	11b, 11 Mbps	35	dB
	11g, 6 Mbps	31	
	11g, 54 Mbps	14	
	11n, HT20, MCS0	31	
	11n, HT20, MCS7	13	
	11n, HT40, MCS0	19	
	11n, HT40, MCS7	8	

5. Package Information

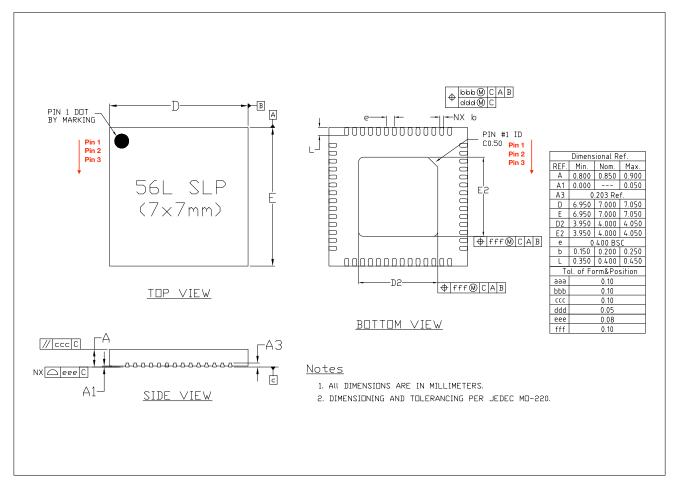


Figure 8: QFN56 (7×7 mm) Package, for Variants Excluding ESP32-S2FN4R2

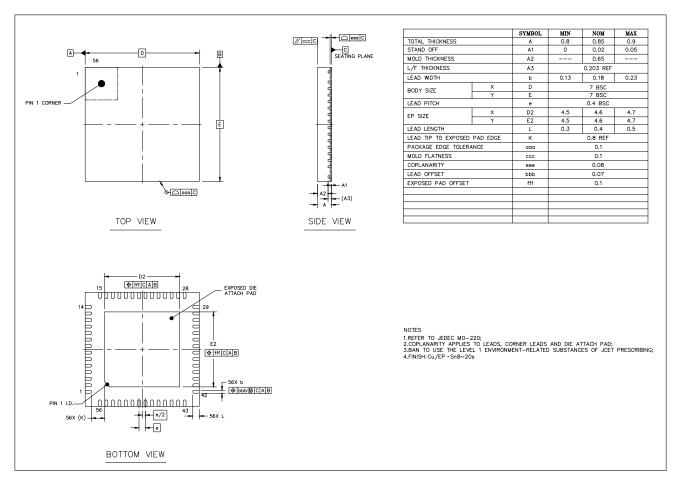


Figure 9: QFN56 (7×7 mm) Package, for ESP32-S2FN4R2

Note:

- The two packages only vary in EPAD size;
- The pins of the chip are numbered in an anti-clockwise direction from Pin 1 in the top view;
- For the source file of recommended PCB land pattern (dxf), you can view it with Autodesk Viewer;
- For information about tape, reel, and product marking, please refer to Espressif Chip Packaging Information.

6. Related Documentation and Resources

Related Documentation

- ESP32-S2 Technical Reference Manual Detailed information on how to use the ESP32-S2 memory and peripherals.
- ESP32-S2 Hardware Design Guidelines Guidelines on how to integrate the ESP32-S2 into your hardware product.
- Certificates

https://espressif.com/en/support/documents/certificates

ESP32-S2 Product/Process Change Notifications (PCN)

https://espressif.com/en/support/documents/pcns?keys=ESP32-S2

ESP32-S2 Advisories – Information on security, bugs, compatibility, component reliability.
 https://espressif.com/en/support/documents/advisories?keys=ESP32-S2

 Documentation Updates and Update Notification Subscription https://espressif.com/en/support/download/documents

Developer Zone

- ESP-IDF Programming Guide for ESP32-S2 Extensive documentation for the ESP-IDF development framework.
- ESP-IDF and other development frameworks on GitHub.

https://github.com/espressif

• ESP32 BBS Forum – Engineer-to-Engineer (E2E) Community for Espressif products where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.

https://esp32.com/

• The ESP Journal - Best Practices, Articles, and Notes from Espressif folks.

https://blog.espressif.com/

• See the tabs SDKs and Demos, Apps, Tools, AT Firmware. https://espressif.com/en/support/download/sdks-demos

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Appendix A – ESP32-S2 Pin Lists

A.1. IO MUX

IO_MUX

Power Supply Pin	Analog Pin	Digital Pin	Power Domain	Analog Function0	Analog Function1	RTC_GPIO	Digital Function0	Туре	Digital Function1	Туре	Digital Function2	Туре	Digital Function3	Туре	Digital Function4	Type	Drive Strength (Default)	At Reset	After Rese
VDDA																			
LNA_IN																			
VDD3P3																			
VDD3P3		GPIO0	VDD3P3_RTC_IO			RTC_GPI00	GPIO0	I/O/T	GPI00	I/O/T							2'd2	oe=0. ie=1. wpu	0 - 4
		GPIO1	VDD3P3_RTC_IO	TOUCH1	ADC1_CH0	RTC_GPI00	GPIO1	I/O/T	GPIO1	I/O/T							2'd2	oe=0, ie=1, wpu	oe=0, ie=
		GPIO2	VDD3P3_RTC_IO	TOUCH2	ADC1_CH0	RTC_GPI02	GPIO2	I/O/T	GPIO2	I/O/T							2'd2	oe=0, ie=1	oe=0, ie=
		GPIO3	VDD3P3_RTC_IO	TOUCH3	ADC1_CH2	RTC_GPIO3	GPIO3	I/O/T	GPIO3	I/O/T							2'd2	oe=0, ie=1	oe=0. ie=
		GPIO4	VDD3P3_RTC_IO	TOUCH4	ADC1_CH3	RTC_GPIO4	GPIO4	I/O/T	GPIO4	I/O/T							2'd2	oe=0, ie=1	oe=0, ie=
		GPIO5	VDD3P3_RTC_IO	TOUCH5	ADC1_CH4	RTC_GPIO5	GPIO5	I/O/T	GPI05	I/O/T							2'd2	oe=0, ie=0	oe=0, ie=
		GPIO6	VDD3P3_RTC_IO	TOUCH6	ADC1_CH5	RTC_GPI06	GPIO6	I/O/T	GPI06	I/O/T							2'd2	oe=0, ie=0	oe=0, ie=
		GPIO7	VDD3P3_RTC_IO	TOUCH7	ADC1_CH6	RTC_GPI07	GPIO7	I/O/T	GPIO7	I/O/T							2'd2	oe=0, ie=0	oe=0, ie=
		GPIO8	VDD3P3_RTC_IO	TOUCH8	ADC1_CH7	RTC_GPI08	GPIO8	I/O/T	GPI08	I/O/T							2'd2	oe=0, ie=0	oe=0, ie
		GPIO9	VDD3P3_RTC_IO	TOUCH9	ADC1_CH8	RTC_GPI09	FSPIHD	11/O/T	GPIO9	I/O/T					FSPIHD	11/O/T	2'd2	oe=0, ie=0	oe=0, ie
		GPIO10	VDD3P3_RTC_IO	TOUCH10	ADC1_CH9	RTC_GPIO10	FSPICS0	11/O/T	GPIO10	I/O/T	FSPIIO4	11/O/T			FSPICS0	11/O/T	2'd2	oe=0, ie=0	oe=0, ie:
		GPIO11	VDD3P3_RTC_IO	TOUCH11	ADC2_CH0	RTC_GPIO11	FSPID	11/O/T	41.16.1		FSPIIO5	11/O/T			FSPID	11/O/T	2'd2	oe=0, ie=0	oe=0, ie:
		GPIO12	VDD3P3_RTC_IO	TOUCH12	ADC2_CH1	RTC_GPIO12	FSPICLK	11/O/T	GPIO12	I/O/T	FSPII06	11/O/T			FSPICLK	11/O/T	2'd2	oe=0, ie=0	oe=0, ie=
		GPIO13	VDD3P3_RTC_IO	TOUCH13	ADC2_CH2	RTC_GPIO13		11/O/T	GPIO13	I/O/T	FSPIIO7	11/O/T			FSPIQ	11/O/T	2'd2	oe=0, ie=0	oe=0, ie
		GPIO14	VDD3P3_RTC_IO	TOUCH14	ADC2_CH3	RTC_GPIO14	FSPIWP	I1/O/T	GPIO14	I/O/T	FSPIDQS	I1/O/T			FSPIWP	11/O/T	2'd2	oe=0, ie=0	oe=0, ie
VDD3P3_RTC		10011 maid =	LEBRADA DEG. :-	1001 001 -	4800 OUT	pro oper:	001015	110.07	000010	110.5							0.00		
		XTAL_32K_P XTAL_32K_N	VDD3P3_RTC_IO VDD3P3_RTC_IO	XTAL_32K_P XTAL_32K_N	ADC2_CH4 ADC2_CH5	RTC_GPIO15		I/O/T	GPIO15	I/O/T	UORTS	0		-			2'd2 2'd2	oe=0, ie=0 oe=0, ie=0	oe=0, ie
		DAC_1	VDD3P3_RTC_IO	DAC_1	ADC2_CHS ADC2_CH6	RTC_GPIO16	GPIO17	I/O/T	GPIO16 GPIO17	I/O/T	U1TXD	0					2'd2	oe=0, ie=0	oe=0, ie
		DAC_1 DAC_2	VDD3P3_RTC_IO	DAC_1	ADC2_CH6 ADC2_CH7	RTC_GPI017	GPIO17 GPIO18	I/O/T	GPIO17 GPIO18	I/O/T	U1RXD	II II	CLK_OUT3	0			2'd2	oe=0, ie=0	oe=0, ie
		GPIO19	VDD3P3_RTC_IO	USB_D-	ADC2_CH8	RTC_GPIO19	GPIO19	I/O/T	GPIO19	I/O/T	U1RTS	0	CLK_OUT2	0			2'd2	oe=0, ie=0	oe=0, ie
		GPIO20	VDD3P3_RTC_IO		ADC2_CH9	RTC_GPIO20		I/O/T	GPI020	I/O/T	U1CTS	11	CLK_OUT1	0			2'd2	oe=0, ie=0	oe=0, ie
VDD3P3 RTC IO				000_01										-					00 0110
		GPIO21	VDD3P3_RTC_IO			RTC_GPI021	GPIO21	I/O/T	GPIO21	I/O/T							2'd2	oe=0, ie=0	oe=0, ie
		SPICS1	VDD_SPI				SPICS1	11/O/T	GPIO26	I/O/T							2'd2	oe=0, ie=1, wpu	oe=1, ie
VDD_SPI																			
		SPIHD	VDD_SPI				SPIHD	11/O/T	GPIO27	I/O/T							2'd2	oe=0, ie=1, wpu	oe=0, ie:
		SPIWP	VDD_SPI				SPIWP	11/O/T	GPIO28	I/O/T							2'd2	oe=0, ie=1, wpu	oe=0, ie:
		SPICS0	VDD_SPI				SPICS0	11/O/T	GPIO29	I/O/T							2'd2	oe=0, ie=1, wpu	oe=1, ie
		SPICLK	VDD_SPI				SPICLK	11/O/T	GPIO30	I/O/T							2'd2	oe=0, ie=1, wpu	oe=1, ie
		SPIQ	VDD_SPI				SPIQ	11/O/T	GPIO31	I/O/T							2'd2	oe=0, ie=1, wpu	oe=0, ie
		SPID	VDD_SPI				SPID	11/O/T	GPIO32	I/O/T							2'd2	oe=0, ie=1, wpu	oe=0, ie
		GPIO33	VDD3P3_CPU / VDD_SPI				GPIO33	I/O/T	GPIO33	I/O/T	FSPIHD	11/O/T			SPIIO4	11/O/T	2'd2	oe=0, ie=0	oe=0, ie
			VDD3P3_CPU /																
		GPIO34	VDD_SPI				GPIO34	I/O/T	GPIO34	I/O/T	FSPICS0	I1/O/T			SPII05	11/O/T	2'd2	oe=0, ie=0	oe=0, ie
		GPIO35	VDD3P3_CPU /				GPIO35	I/O/T	GPIO35	I/O/T	ESPID	11/O/T			SPIIO6	11/O/T	2°d2	oe=0, ie=0	oe=0, ie
		GFIO33	VDD_SPI				GFIOOD	DO/ I	GFIOOO	DOV1	TOPID	11/0/1			GF1100	11/0/1	2 02	06-0, 16-0	UG-U, IG
		GPIO36	VDD3P3_CPU / VDD SPI				GPIO36	I/O/T	GPIO36	I/O/T	FSPICLK	11/O/T			SPIIO7	11/O/T	2'd2	oe=0, ie=0	oe=0, ie
			VDD3P3_CPU /							-									
		GPIO37	VDD_SPI				GPIO37	I/O/T	GPIO37	I/O/T	FSPIQ	I1/O/T			SPIDQS	11/O/T	2'd2	oe=0, ie=0	oe=0, ie
		GPIO38	VDD3P3_CPU				GPIO38	I/O/T	GPIO38	I/O/T	FSPIWP	I1/0/T			GPIO38	I/O/T	2'd2	oe=0, ie=0	oe=0, ie
		MTCK	VDD3P3_CPU				MTCK	H	GPIO39	I/O/T	CLK_OUT3	0					2'd2	oe=0, ie=0	oe=0, ie
		MTDO	VDD3P3_CPU				MTDO	O/T	GPIO40	I/O/T	CLK_OUT2	0					2'd2	oe=0, ie=0	oe=0, ie
VDD3P3_CPU																			
		MTDI	VDD3P3_CPU				MTDI	11	GPI041	I/O/T	CLK_OUT1	0					2'd2	oe=0, ie=0	oe=0, ie
		MTMS	VDD3P3_CPU				MTMS	10	GPIO42	I/O/T	0111 015						2'd2	oe=0, ie=0	oe=0, ie
		UOTXD	VDD3P3_CPU				UOTXD	0	GPIO43 GPIO44	I/O/T	CLK_OUT1	0					2'd2 2'd2	oe=0, ie=1, wpu	oe=1, ie
			VDD3P3_CPU								CLK_OUT2	U						oe=0, ie=1, wpu	oe=0, ie
VDDA		GPIO45	VDD3P3_CPU			-	GPIO45	I/O/T	GPIO45	I/O/T		-					2'd2	oe=0, ie=1, wpd	oe=0, ie
VDUA	VTAL N								-										
	XTAL_N XTAL_P																		
VDDA	AIAL_F																		
VDDA		GPIO46	VDD3P3 CPU				GPIO46	1	GPIO46									oe=0, wpd, ie=1	ne=0 w
	CHIP PU	2,1040	VDD3P3_RTC_IO				311040	-	211040	Ė								mpu, 10-1	50-0, W

- Notes:

 Power supply for GPIO33, GPIO34, GPIO35, GPIO36 and GPIO37 is configurable to be either VDD3P3_CPU (default) or VDD_SPI.

 SPIHD, SPIWP, SPICSO, SPICLK, SPIQ, SPID pins of ESP32-S2FH2 and ESP32-S2FH4 are connected to embedded flash and not recommended for other uses.

 wpu: weak pull-up

 wpd: weak pull-dup

 ie: input enable

 oe: output enable

 Each column about digital "Function" is accompanied by a column about "Type". Please see the following explanations for the meanings of "type" with respect to each "function" they are associated with. For each "Function-N", "type" signifies:

 I: input only, If a function other than "Function-N" is assigned, the input signal of "Function-N" is always "1".

 II: input only, If a function other than "Function-N" is assigned, the input signal of "Function-N" is always "1".

 II: input only, If a function other than "Function-N" is assigned, the input signal of "Function-N" is always "0".

 O: output only, If a function other than "Function-N" is assigned, the input signal of "Function-N" is always "0".

 O: coutput only, If a function other than "Function-N" is assigned, the input signal of "Function-N" is always "0".

 O: coutput only, If a function other than "Function-N" is assigned, the input signal of "Function-N" is always "0".

 O: coutput only, If a function other than "Function-N" is assigned, the input signal of "Function-N" is always "0".

A.2. GPIO Matrix

Table 20: GPIO_Matrix

		Default	Same input		
Signal		value if	signal from IO		Output enable of
No.	Input signals	unassigned*	MUX core	Output signals	output signals
0	SPIQ_in	0	yes	SPIQ_out	SPIQ_oe
1	SPID_in	0	yes	SPID_out	SPID_oe
2	SPIHD_in	0	yes	SPIHD_out	SPIHD_oe
3	SPIWP_in	0	yes	SPIWP_out	SPIWP_oe
4	-	-	-	SPICLK_out_mux	SPICLK_oe
5	-	-	-	SPICSO_out	SPICSO_oe
6	-	-	-	SPICS1_out	SPICS1_oe
7	SPID4_in	0	yes	SPID4_out	SPID4_oe
8	SPID5_in	0	yes	SPID5_out	SPID5_oe
9	SPID6_in	0	yes	SPID6_out	SPID6_oe
10	SPID7_in	0	yes	SPID7_out	SPID7_oe
11	SPIDQS_in	0	yes	SPIDQS_out	SPIDQS_oe
14	UORXD_in	0	yes	UOTXD_out	1'd1
15	UOCTS_in	0	yes	UORTS_out	1'd1
16	UODSR_in	0	no	UODTR_out	1'd1
17	U1RXD_in	0	yes	U1TXD_out	1'd1
18	U1CTS_in	0	yes	U1RTS_out	1'd1
21	U1DSR_in	0	no	U1DTR_out	1'd1
23	I2SOO_BCK_in	0	no	I2SOO_BCK_out	1'd1
25	I2S00_WS_in	0	no	I2SOO_WS_out	1'd1
27	I2SOI_BCK_in	0	no	I2SOI_BCK_out	1'd1
28	12S0I_WS_in	0	no	I2SOI_WS_out	1'd1
29	I2CEXTO_SCL_in	1	no	I2CEXTO_SCL_out	I2CEXTO_SCL_oe
30	I2CEXTO_SDA_in	1	no	I2CEXTO_SDA_out	I2CEXTO_SDA_oe
39	pcnt_sig_ch0_in0	0	no	gpio_wlan_prio	1'd1
40	pcnt_sig_ch1_in0	0	no	gpio_wlan_active	1'd1
41	pcnt_ctrl_ch0_in0	0	no	-	1'd1
42	pcnt_ctrl_ch1_in0	0	no	-	1'd1
43	pcnt_sig_ch0_in1	0	no	-	1'd1
44	pcnt_sig_ch1_in1	0	no	-	1'd1
45	pcnt_ctrl_ch0_in1	0	no	-	1'd1
46	pcnt_ctrl_ch1_in1	0	no	-	1'd1
47	pcnt_sig_ch0_in2	0	no	-	1'd1
48	pcnt_sig_ch1_in2	0	no	-	1'd1
49	pcnt_ctrl_ch0_in2	0	no	-	1'd1
50	pcnt_ctrl_ch1_in2	0	no	-	1'd1
51	pcnt_sig_ch0_in3	0	no	-	1'd1
52	pcnt_sig_ch1_in3	0	no	-	1'd1

0'		Default	Same input		Outrout analyte of
Signal	lament alamata	value if	signal from IO	Outrot siemele	Output enable of
No.	Input signals	unassigned*	MUX core	Output signals	output signals
53	pcnt_ctrl_ch0_in3	0	no	-	1'd1
54	pcnt_ctrl_ch1_in3	0	no	-	1'd1
64	usb_otg_iddig_in	0	no	-	1'd1
65	usb_otg_avalid_in	0	no	-	1'd1
66	usb_srp_bvalid_in	0	no	usb_otg_idpullup	1'd1
67	usb_otg_vbusvalid_in	0	no	usb_otg_dppulldown	1'd1
68	usb_srp_sessend_in	0	no	usb_otg_dmpulldown	1'd1
69	-	-	-	usb_otg_drvvbus	1'd1
70	-	-	-	usb_srp_chrgvbus	1'd1
71	-	-	-	usb_srp_dischrgvbus	1'd1
72	SPI3_CLK_in	0	no	SPI3_CLK_out_mux	SPI3_CLK_oe
73	SPI3_Q_in	0	no	SPI3_Q_out	SPI3_Q_oe
74	SPI3_D_in	0	no	SPI3_D_out	SPI3_D_oe
75	SPI3_HD_in	0	no	SPI3_HD_out	SPI3_HD_oe
76	SPI3_CSO_in	0	no	SPI3_CSO_out	SPI3_CSO_oe
77	-	-	-	SPI3_CS1_out	SPI3_CS1_oe
78	-	-	-	SPI3_CS2_out	SPI3_CS2_oe
79	-	-	-	ledc_ls_sig_out0	1'd1
80	-	-	-	ledc_ls_sig_out1	1'd1
81	-	-	-	ledc_ls_sig_out2	1'd1
82	-	-	-	ledc_ls_sig_out3	1'd1
83	rmt_sig_in0	0	no	ledc_ls_sig_out4	1'd1
84	rmt_sig_in1	0	no	ledc_ls_sig_out5	1'd1
85	rmt_sig_in2	0	no	ledc_ls_sig_out6	1'd1
86	rmt_sig_in3	0	no	ledc_ls_sig_out7	1'd1
87	-	_	_	rmt_sig_out0	1'd1
88	-	_	_	rmt_sig_out1	1'd1
89	-	_	_	rmt_sig_out2	1'd1
90	-	-	-	rmt_sig_out3	1'd1
95	I2CEXT1_SCL_in	1	no	I2CEXT1_SCL_out	I2CEXT1_SCL_oe
96	I2CEXT1_SDA_in	1	no	I2CEXT1_SDA_out	I2CEXT1_SDA_oe
100		-	-	gpio_sd0_out	1'd1
101	-	_	_	gpio_sd0_out	1'd1
102	-	_	_	gpio_sd2_out	1'd1
103	-		_	gpio_sd3_out	1'd1
104			_	gpio_sd4_out	1'd1
105	-		_	gpio_sd5_out	1'd1
106		_	_	gpio_sd5_out	1'd1
100	-		_	gpio_sdo_out	1'd1
108 109	FSPICLK_in FSPIQ_in	0	yes yes	FSPICLK_out_mux FSPIQ_out	FSPICLK_oe FSPIQ_oe

		Default	Same input		
Signal		value if	signal from IO		Output enable of
No.	Input signals	unassigned*	MUX core	Output signals	output signals
110	FSPID_in	0	yes	FSPID_out	FSPID_oe
111	FSPIHD_in	0	yes	FSPIHD_out	FSPIHD_oe
112	FSPIWP_in	0	yes	FSPIWP_out	FSPIWP_oe
113	FSPIIO4_in	0	yes	FSPIIO4_out	FSPIIO4_oe
114	FSPIIO5_in	0	yes	FSPIIO5_out	FSPIIO5_oe
115	FSPII06_in	0	yes	FSPII06_out	FSPIIO6_oe
116	FSPII07_in	0	yes	FSPII07_out	FSPII07_oe
117	FSPICSO_in	0	yes	FSPICSO_out	FSPICSO_oe
118	-	-	-	FSPICS1_out	FSPICS1_oe
119	-	-	-	FSPICS2_out	FSPICS2_oe
120	-	-	-	FSPICS3_out	FSPICS3_oe
121	-	-	-	FSPICS4_out	FSPICS4_oe
122	-	-	-	FSPICS5_out	FSPICS5_oe
123	twai_rx	1	no	twai_tx	1'd1
124	-	-	-	twai_bus_off_on	1'd1
125	-	-	-	twai_clkout	1'd1
126	-	-	-	SUBSPICLK_out_mux	SUBSPICLK_oe
127	SUBSPIQ_in	0	yes	SUBSPIQ_out	SUBSPIQ_oe
128	SUBSPID_in	0	yes	SUBSPID_out	SUBSPID_oe
129	SUBSPIHD_in	0	yes	SUBSPIHD_out	SUBSPIHD_oe
130	SUBSPIWP_in	0	yes	SUBSPIWP_out	SUBSPIWP_oe
131	-	-	-	SUBSPICSO_out	SUBSPICSO_oe
132	-	-	-	SUBSPICS1_out	SUBSPICS1_oe
133	-	-	-	FSPIDQS_out	FSPIDQS_oe
134	-	-	-	FSPI_HSYNC_out	FSPI_HSYNC_oe
135	-	-	-	FSPI_VSYNC_out	FSPI_VSYNC_oe
136	-	-	-	FSPI_DE_out	FSPI_DE_oe
137	-	-	-	FSPICD_out	FSPICD_oe
139	-	-	-	SPI3_CD_out	SPI3_CD_oe
140	-	-	-	SPI3_DQS_out	SPI3_DQS_oe
143	I2SOI_DATA_in0	0	no	I2SOO_DATA_outO	1'd1
144	I2SOI_DATA_in1	0	no	I2SOO_DATA_out1	1'd1
145	I2SOI_DATA_in2	0	no	I2SOO_DATA_out2	1'd1
146	I2SOI_DATA_in3	0	no	I2SOO_DATA_out3	1'd1
147	I2SOI_DATA_in4	0	no	I2SOO_DATA_out4	1'd1
148	I2SOI_DATA_in5	0	no	I2SOO_DATA_out5	1'd1
149	I2SOI_DATA_in6	0	no	I2SOO_DATA_out6	1'd1
150	I2SOI_DATA_in7	0	no	I2SOO_DATA_out7	1'd1
151	I2SOI_DATA_in8	0	no	I2SOO_DATA_out8	1'd1
152	I2SOI_DATA_in9	0	no	I2SOO_DATA_out9	1'd1
153	I2SOI_DATA_in10	0	no	I2SOO_DATA_out10	1'd1

		Default	Same input		
Signal		value if	signal from IO		Output enable of
No.	Input signals	unassigned*	MUX core	Output signals	output signals
154	I2SOI_DATA_in11	0	no	I2SOO_DATA_out11	1'd1
155	I2SOI_DATA_in12	0	no	I2SOO_DATA_out12	1'd1
156	I2SOI_DATA_in13	0	no	I2SOO_DATA_out13	1'd1
157	I2SOI_DATA_in14	0	no	I2SOO_DATA_out14	1'd1
158	I2SOI_DATA_in15	0	no	I2SOO_DATA_out15	1'd1
159	-	-	-	I2SOO_DATA_out16	1'd1
160	-	-	-	I2SOO_DATA_out17	1'd1
161	-	-	-	I2SOO_DATA_out18	1'd1
162	-	-	-	I2SOO_DATA_out19	1'd1
163	-	-	-	I2SOO_DATA_out20	1'd1
164	-	-	-	I2SOO_DATA_out21	1'd1
165	-	-	-	I2SOO_DATA_out22	1'd1
166	-	-	-	I2SOO_DATA_out23	1'd1
167	SUBSPID4_in	0	yes	SUBSPID4_out	SUBSPID4_oe
168	SUBSPID5_in	0	yes	SUBSPID5_out	SUBSPID5_oe
169	SUBSPID6_in	0	yes	SUBSPID6_out	SUBSPID6_oe
170	SUBSPID7_in	0	yes	SUBSPID7_out	SUBSPID7_oe
171	SUBSPIDQS_in	0	yes	SUBSPIDQS_out	SUBSPIDQS_oe
193	I2SOI_H_SYNC	0	no	-	1'd1
194	I2SOI_V_SYNC	0	no	-	1'd1
195	I2SOI_H_ENABLE	0	no	-	1'd1
215	-	-	-	ant_sel0	1'd1
216	-	-	-	ant_sel1	1'd1
217	-	-	-	ant_sel2	1'd1
218	-	-	-	ant_sel3	1'd1
219	-	-	-	ant_sel4	1'd1
220	-	-	-	ant_sel5	1'd1
221	-	-	-	ant_sel6	1'd1
222	-	-	-	ant_sel7	1'd1
223	sig_in_func_223	0	no	sig_in_func223	1'd1
224	sig_in_func_224	0	no	sig_in_func224	1'd1
225	sig_in_func_225	0	no	sig_in_func225	1'd1
226	sig_in_func_226	0	no	sig_in_func226	1'd1
227	sig_in_func_227	0	no	sig_in_func227	1'd1
235	pro_alonegpio_in0	0	no	pro_alonegpio_out0	1'd1
236	pro_alonegpio_in1	0	no	pro_alonegpio_out1	1'd1
237	pro_alonegpio_in2	0	no	pro_alonegpio_out2	1'd1
238	pro_alonegpio_in3	0	no	pro_alonegpio_out3	1'd1
239	pro_alonegpio_in4	0	no	pro_alonegpio_out4	1'd1
240	pro_alonegpio_in5	0	no	pro_alonegpio_out5	1'd1
241	pro_alonegpio_in6	0	no	pro_alonegpio_out6	1'd1

		Default	Same input		
Signal		value if	signal from IO		Output enable of
No.	Input signals	unassigned*	MUX core	Output signals	output signals
242	pro_alonegpio_in7	0	no	pro_alonegpio_out7	1'd1
251	-	-	-	clk_i2s_mux	1'd1

Revision History

Date	Version	Release notes
2024.02	V1.6	 Added Table Description of Timing Parameters for the Strapping Pins and Figure Visualization of Timing Parameters for the Strapping Pins; Added references to the Technical Reference Manual in Chapter 3 <i>Functional Description</i>; Added cumulative IO current to Table Absolute Maximum Ratings.
2022.12	V1.5	 Delete feature "Supports external power amplifier"; Added a note about Xtensa® Instruction Set Architecture (ISA) Summary in Section 3.1.1 CPU; Added the package diagram for ESP32-S2FN4R2 in Chapter 5 Package Information.
2022.09	V1.4	 Updated Figure Block Diagram of ESP32-S2 to show power modes; Added CoreMark score in Features; Added a note about external crystal clock in Section 3.2.1 CPU Clock; Added Table Mapping of SPI Signal Buses and Chip Pins; Added Section 3.4.11 DMA Controller; Added the clock of ULP coprocessor in Section 3.6.2 Ultra-Low-Power Co-processor; Added note 3 to Table Recommended Operating Conditions; Updated Section 4.6 Current Consumption Characteristics; Replaced "chip family" with "chip series" following Espressif's taxonomy; Updated Section "Learning Resources" and renamed to "Related Documentation and Resources"; Other updates to wording.
2021.06	V1.3	 Added chip variant ESP32-S2R2; Updated Table 17 Reliability Qualifications; Added the link to recommended PCB land pattern in Chapter 5 Package Information; Added Chapter 6 Related Documentation and Resources; Other minor updates.
2021.02	V1.2	 Added chip variant ESP32-S2FN4R2; Added information about TWAI® Controller; Updated operating temperature to ambient temperature in Table 1

Date	Version	Release notes
2020.09	V1.1	 Added chip variant ESP32-S2FH2□ESP32-S2FH4; Added Chapter 1 ESP32-S2 Series Comparison.
2020.06	V1.O	 Modified the second note under Table 4 Strapping Pins; Modified the frequency of internal RC oscillator in Section 3.2.2 RTC Clock from 150 kHz to 90 kHz; Renamed RISCV to RISC-V and ULP-RISCV to ULP-RISC-V in Section 3.6.2 Ultra-Low-Power Co-processor; Modified a few figures in Table 4.6.2 Current Consumption in Other Modes; Added a note about V_{OH} and V_{OL} under Table 12 DC Characteristics (3.3 V, 25 °C); Added Table 17 Reliability Qualifications; Other small changes.
2019.11	VO.4	Updated Section 3.6.2 Ultra-Low-Power Co-processor; Updated Section 3.7 Timers and Watchdogs; Updated Table 20 GPIO_Matrix; Added documentation feedback hyperlink; Fixed formatting issues; Other small changes.
2019.08	v0.3	Overall update.
2019.06	v0.2	Updated Figure 4 ESP32-S2 Power Scheme; Updated Section 2.4 Strapping Pins; Updated Figure 7 Address Mapping Structure; Updated Section 4 Electrical Characteristics.
2019.04	v0.1	Preliminary release.



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