Outline

- Python Programming Setup
- Python Platforms for DL
- Introduction to Numpy
- Plotting with Matplotlib
- Preparing Data for Machine Learning
- Lab Assignment

Part 1: Python Programming Setup

Setting up Python Environment (Anaconda 3)

What is Anaconda?



Anaconda is a distribution of the Python and R for scientific computing

- Comes with >250 packages automatically installed
- >7500 additional open-source packages available
- Equipped with Jupyter Notebook
- Conda environment manager for easy maintenance of packages

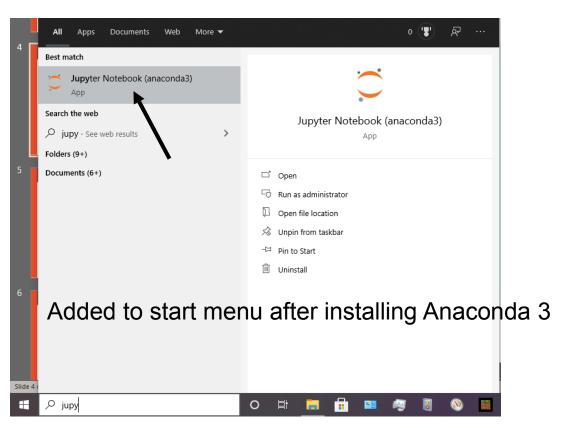
Setting up Python Environment (Anaconda 3)

Installing Anaconda 3 https://www.anaconda.com/products/individual



Starting up Jupyter Notebook (Anaconda3)

Windows

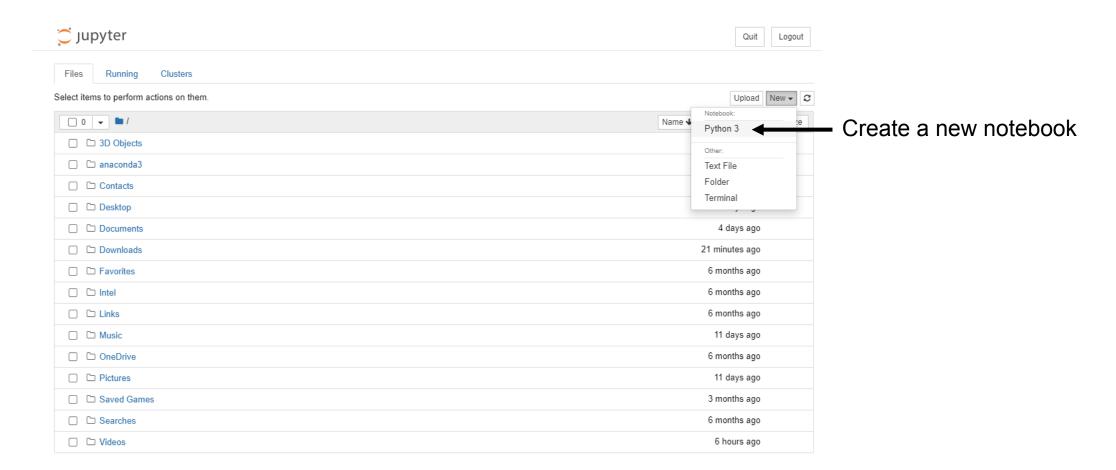


Mac/Linux

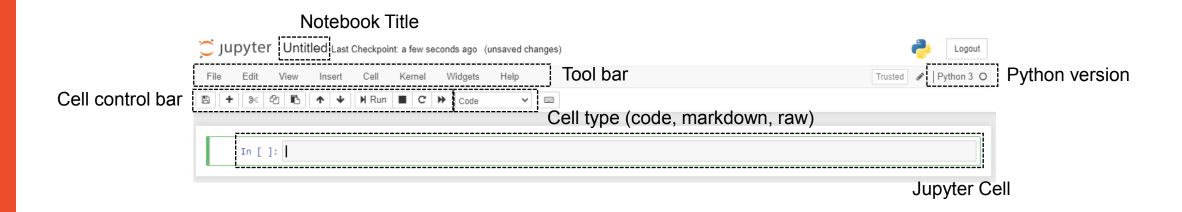
Start terminal

Type "jupyter notebook"

Starting up Jupyter Notebook (Anaconda3)



Starting up Jupyter Notebook (Anaconda3)



For more information, visit https://www.dataquest.io/blog/jupyter-notebook-tutorial/

Part 2: Python Platforms for DL

Google Colaboratory

A free Jupyter notebook environment that runs in the cloud

- Saves in Google drive
- Github commit style code sharing with others
- Maximum runtime of 12hrs (Free version)
- Support GPU or TPU for hardware acceleration
- Pre-equipped with latest scientific packages (Numpy, Scipy, etc)

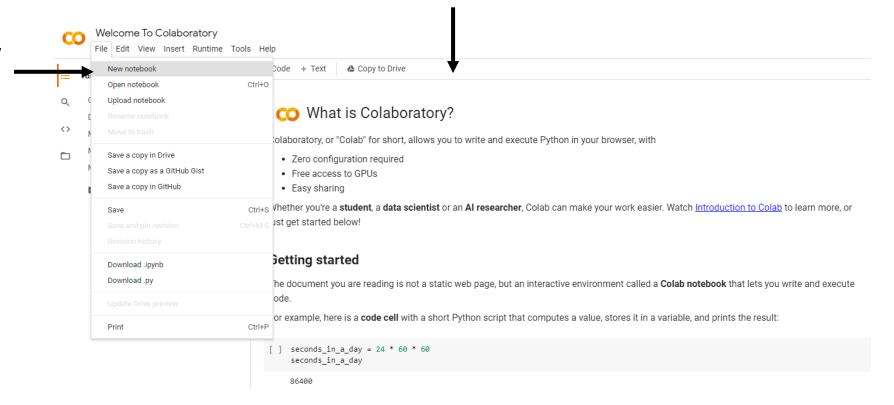


Google Colaboratory: Getting started

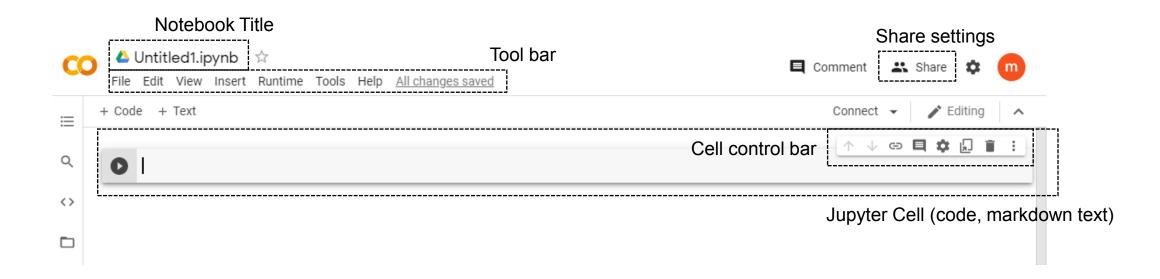
Tutorial to Colab

https://colab.research.google.com/notebooks/intro.ipynb

Create new Notebook



Google Colaboratory: Getting started



Google Cloud

Suite of cloud computing services offered by Google



- Offers AI Platform for deploying DL models
- Support Jupyter Notebook instances
- Provide instances with DL libraries
- Fully customizable hardware spec with state-of-the-art components
- Monthly charge for the service

https://towardsdatascience.com/get-deep-learning-on-google-cloud-platform-the-easy-way-53f74bab5ee9

Deep Learning Frameworks







Developed by Facebook

- Lots of modules that are easy to combine
- Easy to edit network
- Lots of pre-trained models
- Seamless integration into Python/Numpy framework

Developed by Google

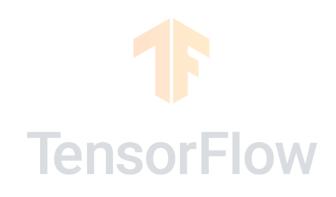
- Provides Tensorboard for visualization
- Uses its own session during training
- Great community support
- Tensorflow Lite can run models on mobile devices

Developed by Apache

- Supported by Amazon Web Service
- Supports many languages
- Fast and flexible for running DL algorithms
- Features advanced GPU support
- Popular among industrial projects

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Framework for this class

Part 3: Introduction to Numpy

What is Numpy?

Fundamental package for scientific computing in Python

- Provides multi-dimensional array object
- Provides assortment of mathematical routines for arrays
- Fast array operations through pre-compiled C
- Support vectorization of operations
- Seamlessly integrated with DL frameworks such as PyTorch, TensorFlow



Constructing Numpy arrays

From python lists

From Numpy commands

```
# Define number of each dimension
n1 = 3
n2 = 4
n3 = 5
# Zeros array
zeros 1d = np.zeros(n1)
zeros_2d = np.zeros((n1,n2))
zeros 3d = np.zeros((n1,n2,n3))
# Ones array
ones 1d = np.ones(n1)
ones_2d = np.ones((n1,n2))
ones 3d = np.ones((n1,n2,n3))
# Creating array using np.arange
arr arange = np.arange(0, 10, 1)
                                     # (start, stop, stepsize)
# Creating an array using np.linspace
arr_linspace = np.linspace(0, 9, 10) # (start, stop, # of bins)
```

Random arrays

```
# Random array

np.random.seed(10)  # Fixes the seed number so that random samplings always give same results

rand_arr = np.random.randn(n1, n2) # Random array sampled from standard normal distribution
```

Basic Matrix Operations in Numpy

Elementwise Addition – np.add()

Dot Product – np.dot()

Elementwise Subtraction – np.subtract()

Transpose – .T operative or np.transpose()

Elementwise Multiplication – np.multiply()

Elementwise Division – np.divide()

Elementwise Power – np.power()

Useful Numpy functions

Combining arrays

```
Concatenating arrays—np.concetenate()
Stacking arrays—np.stack() (Can add dimensions), np.hstack() (horizontal stack), np.vstack() (vertical stack)
```

Finding characteristic values of an array

Minimum, Maximum, Mean, Sum of array elements – np.min(), np.max(), np.mean(), np.sum()

Indexing an array

Indices of minimum and maximum element – np.argmin(), np.argmax()
Sorting the indices from low to high values – np.argsort()
Finding the indices that satisfy conditions – np.where()

Part 4: Plotting with Matplotlib

Basic plotting

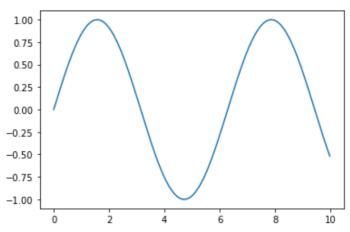
Import Matplotlib

#%matplotlib inline # If using local notebook runtime, allows you to display the plot inside the jupyter notebook #%matplotlib notebook # Alternatively, you can use this line instead for interactive plots

import matplotlib.pyplot as plt

Code

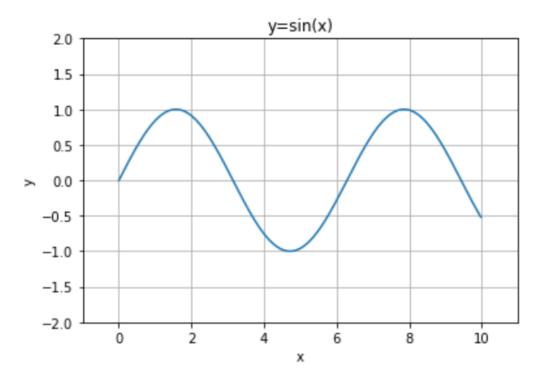
```
x = np.arange(0, 10, 1/32) # x axis data
y = np.sin(x) # y axis data
plt.plot(x, y) # plot the data
```



Labeling your plots

Code

```
plt.plot(x, y)
plt.title('y=sin(x)') # set the title
plt.xlabel('x') # set the x axis label
plt.ylabel('y') # set the y axis label
plt.xlim(-1, 11) # set the x axis range
plt.ylim(-2, 2) # set the y axis range
plt.grid() # enable the grid
```

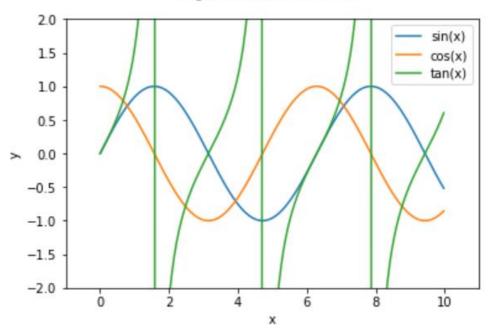


Multiple plots

Code

```
# Multiple Plots
# On same figure
x = np.arange(0, 10, 1/32) # x axis data
y1 = np.sin(x)
                         # y axis data 1
y2 = np.cos(x)
                        # y axis data 2
y3 = np.tan(x)
                         # y axis data 3
plt.figure(1)
                        # create figure 1
plt.plot(x, y1, label='sin(x)')
plt.plot(x, y2, label='cos(x)')
plt.plot(x, y3, label='tan(x)')
plt.xlabel('x')
plt.ylabel('y')
plt.xlim(-1, 11)
plt.ylim(-2, 2)
plt.suptitle('Trigonometric Functions')
plt.legend()
plt.show()
```

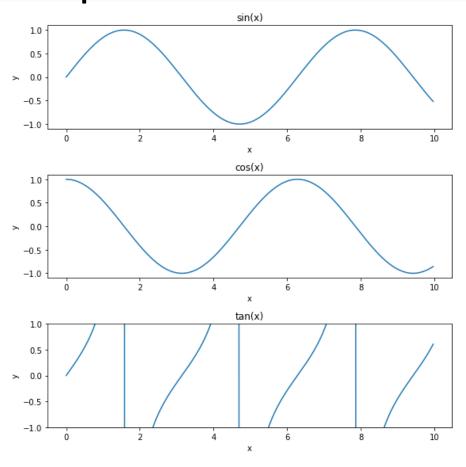




Creating subplots

Code

```
# Multiple Subplots
x = np.arange(0, 10, 1/32) # x axis data
                           # y axis data for subplot 1
y1 = np.sin(x)
y2 = np.cos(x)
                           # y axis data for subplot 2
                           # y axis data for subplot 3
y3 = np.tan(x)
fig = plt.figure(2,figsize=(8,8)) # create figure 2
                           # (number of rows, number of columns, current plot)
plt.subplot(311)
plt.plot(x, y1)
plt.title('sin(x)')
plt.xlabel('x')
plt.ylabel('y')
plt.subplot(312)
plt.plot(x, y2)
plt.title('cos(x)')
plt.xlabel('x')
plt.ylabel('y')
plt.subplot(313)
plt.plot(x, y3)
plt.title('tan(x)')
plt.xlabel('x')
plt.ylabel('y')
plt.ylim(-1, 1)
fig.tight_layout()
```



Part 5: Working with data

Loading dataset

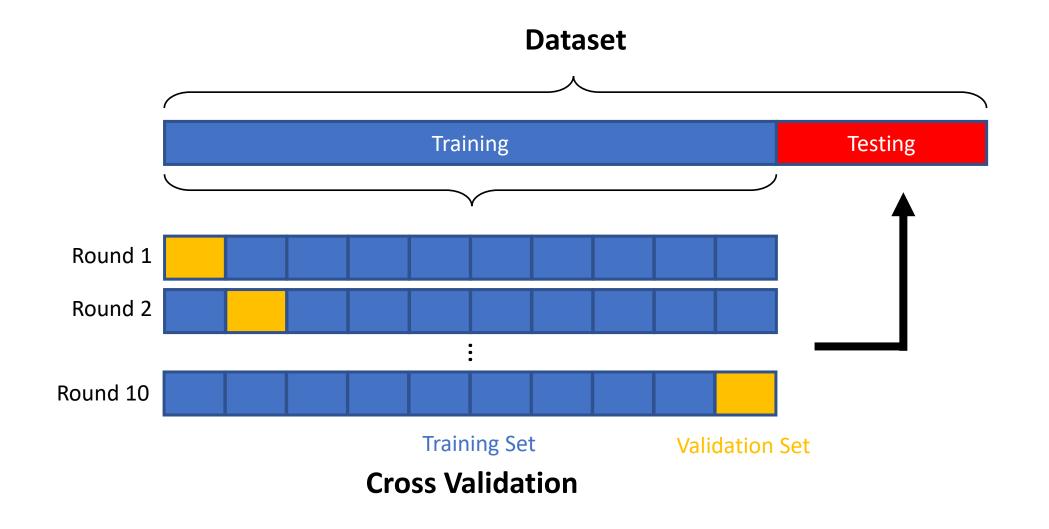
```
import pandas as pd
import sklearn

# Import necessary modules
from sklearn.linear_model import LogisticRegressionCV

diabetes = pd.read_csv('diabetes.csv') # Read the dataset with pandas diabetes.head() # Display the head of the data
```

	Pregnancies	Glucose	BloodPressure	${\bf Skin Thickness}$	Insulin	ВМІ	${\bf Diabetes Pedigree Function}$	Age	Outcome
0	6	148	72	35	0	33.6	0.627	50	1
1	1	85	66	29	0	26.6	0.351	31	0
2	8	183	64	0	0	23.3	0.672	32	1
3	1	89	66	23	94	28.1	0.167	21	0
4	0	137	40	35	168	43.1	2.288	33	1

Dividing dataset into Train, Validation, Test



Logistic Regression using Scikit-Learn

Scaling the dataset

Define Training and Testing sets

Use cross validation to train
model = LogisticRegressionCV(cv=10).fit(X_train, Y_train)
result = model.score(X_test, Y_test)
print("Accuracy: %.2f%" % (result*100))

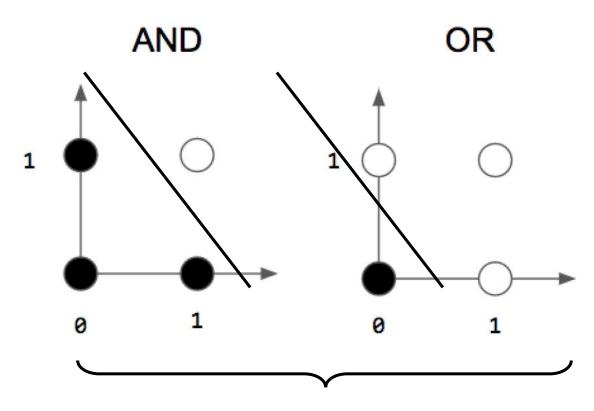
Perform Logistic Validation with CV

Accuracy: 78.79%

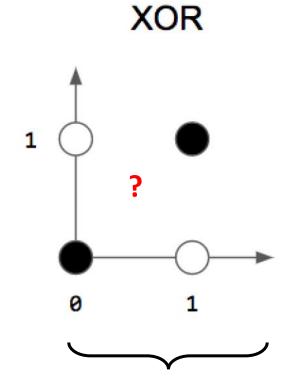
Lab Assignment:

Implement Neural Network for XOR gate with Numpy

XOR Problem



Linearly separable



NOT Linearly separable

Loading dataset into Numpy array

Using Pandas

```
# XOR table

# Using Pandas
import pandas as pd

XOR_table = pd.read_csv('XOR_table.csv')
XOR_table
```

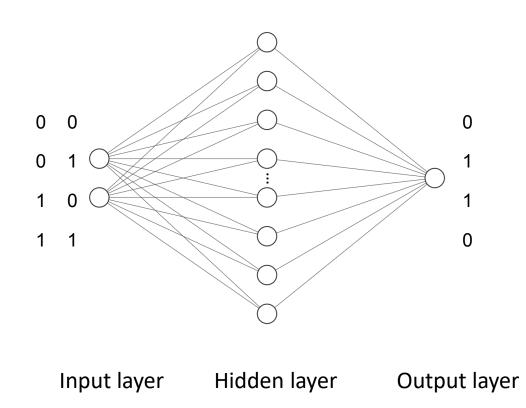
x1 x2 y 0 0 0 0 1 0 1 1 2 1 0 1 3 1 1 0

Converting data into Numpy array

```
XOR_table = XOR_table.values
X = XOR_table[:, :2]
targets = XOR_table[:, -1].reshape(-1,1)
print(X) # Input data
print(targets) # Output targets
[[0 0]]
 [0 1]
 [1 0]
 [1 1]]
[[0]]
 [1]
 [1]
 [0]]
```

Solving XOR with a neural network

```
# Define dimensions on input, hidden and output layers
input dim, hidden dim, output dim =
# Define learning rate
learning rate=
# Define a hidden layer
W1=
# Define an output layer
W2=
# Define sigmoid activation function
for i in range(10000):
  # Forward pass: compute predicted y
  # Compute and print loss
  # Backprop to compute gradients of w1 and w2 with respect to L2-norm loss
  # Update weights
  # Save loss to an array
```



Solving XOR with a neural network (Forward Pass)

Feed Forward Eqns

$$z = \sigma(W_1x + b_1)$$

$$y = \sigma(W_2\sigma(W_1x + b_1) + b_2)$$

$$y = \sigma(W_2z + b_2)$$

Activation (sigmoid)

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

L2-Loss Function

$$J = \sum_{i=1}^{N} (y-t)^2$$

y = predicted output

t = Target output

Solving XOR with a neural network (Backward Pass)

Derivative of Activation

$$\frac{d(\sigma(x))}{dx} = \frac{1}{1 + e^{-x}} * \left(1 - \frac{1}{1 + e^{-x}}\right) \qquad \frac{\frac{\partial J}{\partial W_2}}{\frac{\partial J}{\partial y}} = \frac{\partial J}{\partial y} \frac{\frac{\partial y}{\partial W_2}}{\frac{\partial W_2}{\partial y}} = \sigma(W_2 z)$$

$$= \sigma(x) \left(1 - \sigma(x)\right) \qquad \frac{\partial y}{\partial W_2} = \sigma(W_2 z)$$

Gradient of J w.r.t. W_2

$$egin{align} rac{\partial J}{\partial W_2} &= rac{\partial J}{\partial y} rac{\partial y}{\partial W_2} \ rac{\partial J}{\partial y} &= 2(y-t) \ rac{\partial y}{\partial W_2} &= \sigma(W_2z+b_2)(1-\sigma(W_2z+b_2))z \ rac{\partial J}{\partial W_2} &= 2(y-t)y(1-y)z \ \end{pmatrix}$$

Gradient of J w.r.t. W_1

$$egin{aligned} rac{\partial J}{\partial W_1} &= rac{\partial J}{\partial y} rac{\partial y}{\partial z} rac{\partial z}{\partial W_1} \ rac{\partial J}{\partial y} &= 2(y-t) \ rac{\partial y}{\partial z} &= \sigma(W_2z+b_2)(1-\sigma(W_2z+b_2))W_2 \ rac{\partial z}{\partial W_1} &= \sigma(W_1x+b_1)(1-\sigma(W_1z+b_1))x \ rac{\partial J}{\partial W_1} &= 2(y-t)y(1-y)W_2z(1-z)x \end{aligned}$$

Update rule for W_2

$$W_2 = W_2 - lpha rac{\partial J}{\partial W_2}$$
 $W_2 = W_2 - lpha 2(y-t)y(1-y)z$

Update rule for W_1

$$W_1 = W_1 - \alpha \frac{\partial J}{\partial W_1}$$

$$W_1 = W_1 - \alpha 2(y-t)y(1-y)W_2z(1-z)x$$