

## Announcements:

HW1 : submit via gradescope

Quiz1 : next Wednesday 9/27 (linear algebra, probability, optimization)

Waitlist and section changes : today & tomorrow

## Outline

Recap. Const. Opt  
Probability

$$P^* = \min_x f(x) \\ \text{subject to } g_i(x) \leq 0 \quad \forall i \in \{1, \dots, m\}$$

Lagrangian:

$$\mathcal{L}(x, \lambda) = f(x) + \sum \lambda_i g_i(x) \quad (\lambda_i \geq 0 \ \forall i) \\ = f(x) + \underline{\lambda}^T g(x)$$

Dual function

$$F(\lambda) = \inf_x \mathcal{L}(x, \lambda)$$

ex:  $\inf_{x > 0} x = 0$       Infimum (inf) : Greatest lower bound.

Dual problem:  $\boxed{d^*} = \max_{\lambda \geq 0} F(\lambda)$

- $F(\lambda) \leq f(x^*)$  for any feasible  $x^*$   $\left( \min_{\substack{f(x) \leq b}} f(x) \right)$

$$\begin{aligned}
 F(\lambda) &= \inf_x f(x) + \lambda^\top g(x) \\
 &\leq f(x^*) + \lambda^\top g(x^*) \\
 &\leq f(x^*) \quad \Rightarrow \quad d^* \leq p^* \\
 &\quad \text{(equal if nice enough)}
 \end{aligned}$$

## Probability Terminology

Name	What it is	Common Symbols	What it means
Sample Space Event Space	Set Collection of subsets	$\Omega, S, \mathcal{F}, E$	"Possible outcomes." "The things that have probabilities.."
Probability Measure	Measure	$P, \pi$	Assigns probabilities to events.
Probability Space	A triple	$(\Omega, \mathcal{F}, P)$	

Remarks: may consider the event space to be the power set of the sample space (for a discrete sample space - more later). e.g., rolling a fair die:

$$\Omega = \{1, 2, 3, 4, 5, 6\}$$

$$\mathcal{F} = 2^\Omega = \{\{1\}, \{2\}, \dots, \{1, 2\}, \dots, \{1, 2, 3\}, \dots, \{1, 2, 3, 4, 5, 6\}, \emptyset\}$$

$$P(\{1\}) = P(\{2\}) = \dots = \frac{1}{6}$$
 (i.e., a fair die)

$$P(\{1, 3, 5\}) = \frac{1}{2}$$
 (i.e., half chance of odd result)

$$P(\{1, 2, 3, 4, 5, 6\}) = 1$$
 (i.e., result is "almost surely" one of the faces).

### Axioms

$$P(A) \geq 0 \quad \forall A \in \mathcal{F}$$

$$P(\emptyset) = 0$$

$$P(\bigcup_i A_i) = \sum_{i=1}^n P(A_i) \quad \text{for disjoint events } A_i : i \in \{1, \dots, n\}$$

### Probability Mass Function (PMF)      discrete R.V.)

$$f_X(x) \rightarrow P(X=x)$$

$$\text{Eg. } P(X=x_i) = \theta_i \geq 0 \quad \sum_{i=1}^n \theta_i = 1$$

$$\mathbb{E} g(X) = \sum_x g(x) f_X(x)$$

## Cumulative Distribution Function (CDF)

$$F_X(x) = P(X \leq x)$$

## Probability Density Function (cont RVS)

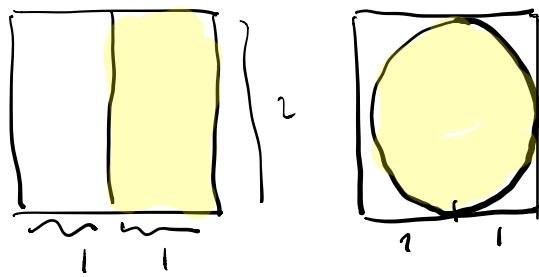
$$f_X(x) = \frac{d}{dx} F_X(x) \quad \text{e.g. Uniform } f(x) = \frac{1}{b-a} \mathbf{1}_{(a,b)}(x)$$

Gaussian

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$N(\mu, \sigma^2)$$

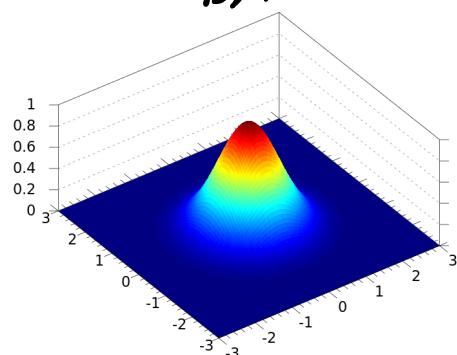
Uniform:



$$\text{Probability: } \frac{1}{2}$$

$$\frac{\pi}{2 \cdot 2}$$

- a) Integration
- b) Monte Carlo



## Multivariate Gaussian

$$\underline{X} = (X_1, \dots, X_n) \text{ is M.V.}$$

Gaussian distributed if

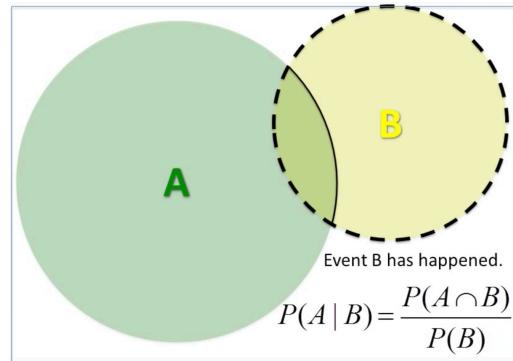
$$f_x(x_1, \dots, x_n) = \frac{1}{\sqrt{(2\pi)^n \cdot \det(\Sigma)}} \exp\left(-\frac{1}{2} \cdot (x-\mu)^\top \Sigma^{-1} (x-\mu)\right)$$

$\underline{\mu} = \mu_1, \dots, \mu_n$  mean (vector)

$\underline{\Sigma} \succeq 0$  (PSD) covariance (matrix)

### Conditional probability

$$P(B|A) = \frac{P(A \cap B)}{P(A)}$$



$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$

### Bayes Rule

### Independent R.V.s.

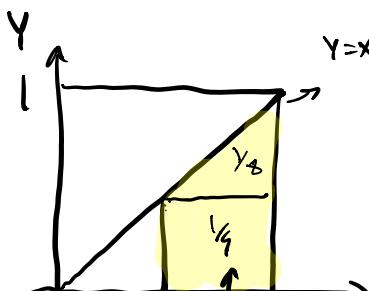
A and B are independent events if  $P(A \cap B) = P(A) \cdot P(B)$

X and Y independent R.V.s if  $P(X=x, Y=y) = P(X=x) \cdot P(Y=y)$

Processing the bigger number:

Observe X but not Y.  
in order to choose the bigger number will you pick X or Y?

X, Y uniform  $[0,1]$  independent



If  $X > \frac{1}{2}$  pick X  
 $X \leq \frac{1}{2}$  pick Y

... i.e., random  $X \leftrightarrow Y$

$$\begin{aligned}
 P(\text{win}) &= P\left( \underbrace{x > y_2}_{\text{1}} \wedge \underbrace{x > y}_{\text{2}} \right) + P(x < y_2 \wedge y > x) \\
 &= \frac{1}{4} + \frac{1}{8} + \frac{1}{4} + \frac{1}{8} \\
 &= 2 \cdot \frac{3}{8} = \frac{6}{8} = \frac{3}{4}
 \end{aligned}$$

### Classification

Consider random variables

$$\begin{aligned}
 x \in \mathbb{R}^d &\quad (\text{feature vector}) \\
 y \in \{1, \dots, K\} &\quad \text{class label}
 \end{aligned}$$

With joint distribution  $P_{XY}$

$$\begin{aligned}
 P_{XY} &= P_{X|Y} \cdot P_Y \\
 &\downarrow \quad \xrightarrow{\text{prior class distribution}} \\
 &\text{class conditional.}
 \end{aligned}$$

$$\pi_k = P_Y(Y=k) \quad k=1, \dots, K \quad (\text{discrete})$$

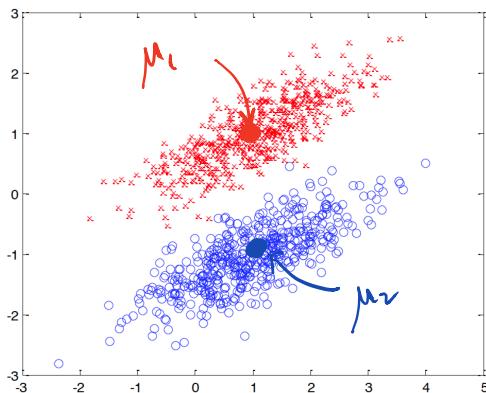
$P_{X|Y}$  discrete or continuous.

Ex:  $k=2, d=2$   $P_{X|Y}$  is Gaussian

$$x|y=1 \sim N(\mu_1, \Sigma)$$

$$x|y=2 \sim N(\mu_2, \Sigma)$$

$$\begin{aligned}
 \mu_1 &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \mu_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \Sigma = \begin{bmatrix} .9 & .4 \\ .4 & .3 \end{bmatrix} \quad \pi_1 = \pi_2 = \frac{1}{2}
 \end{aligned}$$



$$P_{XY} = P_{Y|X} P_X$$

↑ posterior distribution

- Naive Bayes:  $P_{X|Y=k}$  factorizes into independent factors.
- Linear Discriminant Analysis:  $P_{X|Y=k}$  is Multivariate Gaussian.
- Logistic Regression:  $P_{Y|X=x}$  is given by logistic probability model.

### Bayes Classifier

Given  $P_{XY}$  of  $(X, Y)$  what is the best possible classifier

Classifier is a function

$$f: \mathbb{R}^d \rightarrow \{1, \dots, K\}$$

Performance measure: Probability of error (risk)

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$$R(f) = P_{x,y}(f(x) \neq y)$$