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Limits of Computation

II - Church-Turing Thesis

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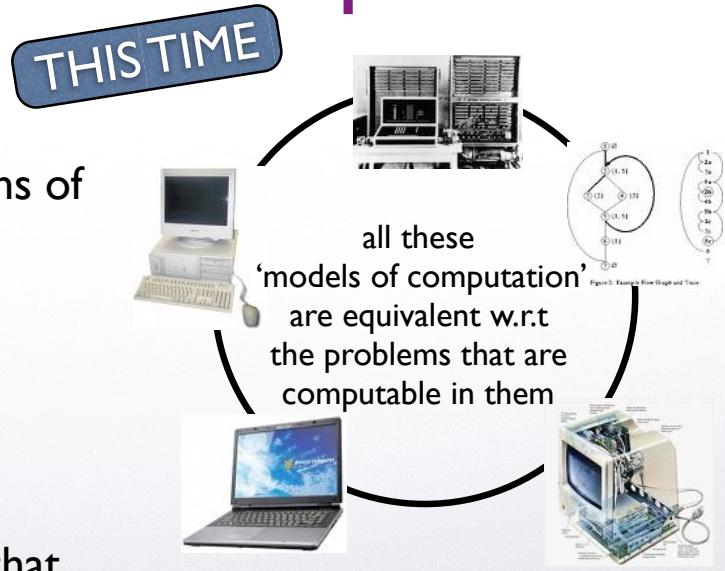
The story so far

- We have found problems that cannot be solved by a WHILE program (*Halting, Busy-Beaver, Tiling, Ambiguity of CFGs*, etc).
- But this does not mean yet they could not be solved by a different machine model (different definition of “effective procedure”).



More ‘notions of computation’

- Evidence for the
 - Church-Turing Thesis
- by looking at other notions of computation:
 - Register machines
 - Counter machines
 - Turing machines
 - Goto language
 - Cellular Automata
- and showing (or stating) that they are all equivalent.



Church-Turing Thesis

reasonable formalisations of the intuitive notion of effective computability

All *reasonable* computation models are equivalent.

no restrictions on memory size and execution time are assumed

So it does not matter what model we use.
It was alright to use WHILE.



We cannot prove this as it refers to informal entities (reasonable computation models). It is thus only a “thesis”. But we provide some evidence for it.



Models of computation

- Random Access Machines (register machines): RAM
- Turing machines: TM
- Counter machines: CM
- Flowchart language: GOTO
- Cellular Automata: CA
- While language: WHILE ✓
- Church's λ -Calculus (see course Comparative Prog. Languages)



Machine instructions

- TM, GOTO, CM, RAM have the following in common:
- A *program* is a sequence of instructions with labels
$$l_1:I_1; l_2:I_2; \dots l_n:I_n$$
- a *state* or *configuration* during execution of the program is of the form (ℓ, σ) where ℓ is the current instruction's label and σ is the “store” which varies from machine to machine.

WHILE does not have ‘machine flavour’, it’s more abstract

CA quite different



Semantic Framework for Machines

- definition of store
- function *Readin* producing initial store
- function *Readout* producing output
- description of semantics of the instructions,

$$p \vdash s \rightarrow s'$$

program p transits from
configuration s into s' in one step



Semantic Framework for machines

Definition (General framework for machine model semantics). Let p be a machine program with m instructions.

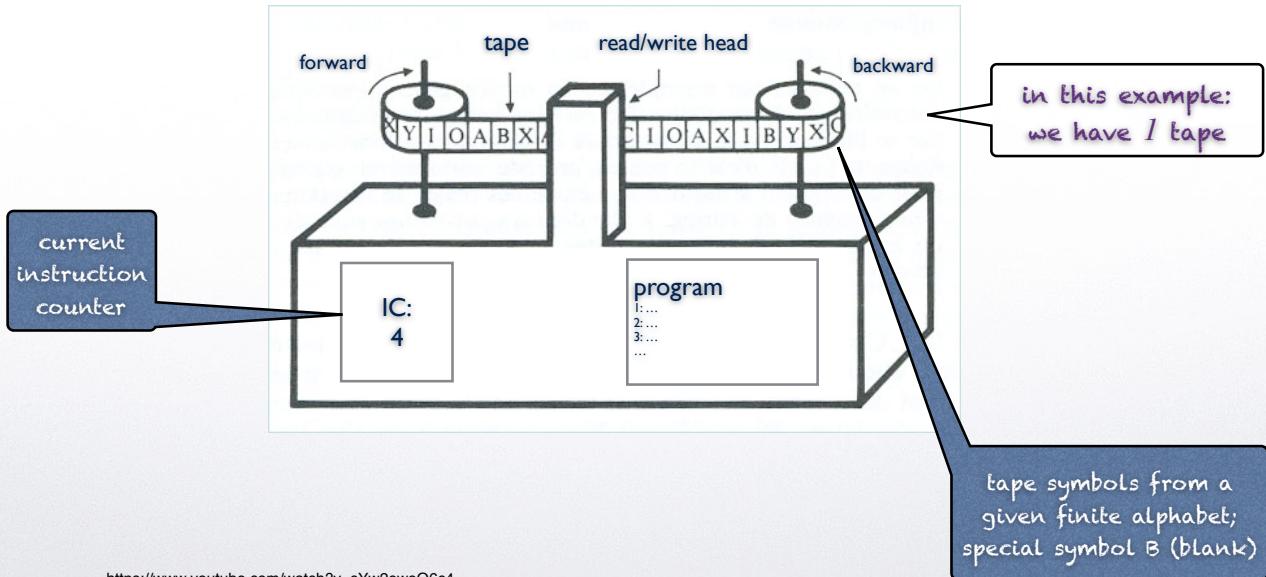
$$\llbracket p \rrbracket(d) = e \text{ iff } \sigma_0 = \text{Readin}(d) \quad \text{and} \\ p \vdash (1, \sigma_0) \rightarrow^* (m+1, \sigma) \quad \text{and} \\ e = \text{Readout}(\sigma)$$

$p \vdash s \rightarrow^* s'$ "many-step" operational semantics for machine language, zero, one, or several steps of the "one-step" semantics

We will now show how semantics of other languages/machines are an instance of this framework.



Turing Machine



Turing Machine

j is number of tape

presented in a way to fit our machine model

instruction	explanation
right _j	move right
left _j	move left
write _j S	write S
if _j S goto ℓ_1 else ℓ_2	conditional jump (read)

we have k tapes

Store (= Tapes)

$(L_1 \underline{S_1} R_1, L_2 \underline{S_2} R_2, \dots L_k \underline{S_k} R_k)$

L_i, R_i are strings of symbols

$\underline{}$ denotes position of
read/write head



Turing Machine

Readin (input)

$Readin(x) = (\underline{B}x, \underline{B}, \underline{B}, \dots, \underline{B})$

Readout (output)

$Readout(\underline{L}_1 \underline{S}_1 \underline{R}_1, \underline{L}_2 \underline{S}_2 \underline{R}_2, \dots, \underline{L}_k \underline{S}_k \underline{R}_k) = Prefix(R_1)$

where $Prefix(R_1 R_2) = R_1$ provided that R_1 does not contain any blank symbols

One-step operational semantics for **1-tape** machine (no subscripts)

ℓ -th instruction

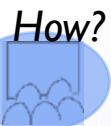
- $p \vdash (\ell, LSS'R) \rightarrow (\ell + 1, LSS'R)$ if $p(\ell) = \text{right}$
- $p \vdash (\ell, LS) \rightarrow (\ell + 1, LSB)$ if $p(\ell) = \text{right}$
- $p \vdash (\ell, LS' SR) \rightarrow (\ell + 1, LS' SR)$ if $p(\ell) = \text{left}$
- $p \vdash (\ell, SR) \rightarrow (\ell + 1, BSR)$ if $p(\ell) = \text{left}$
- $p \vdash (\ell, LSR) \rightarrow (\ell + 1, LS'R)$ if $p(\ell) = \text{write } S'$
- $p \vdash (\ell, LSR) \rightarrow (\ell_1, LSR)$ if $p(\ell) = \text{if } S \text{ goto } \ell_1 \text{ else } \ell_2$
- $p \vdash (\ell, LS'R) \rightarrow (\ell_2, LS'R)$ if $p(\ell) = \text{if } S \text{ goto } \ell_1 \text{ else } \ell_2 \text{ and } S \neq S'$



GOTO

instruction	explanation
$X := \text{nil}$	assign nil
$X := Y$	assign variable
$X := \text{hd } Y$	assign hd Y
$X := \text{tl } Y$	assign tl Y
$X := \text{cons } Y Z$	assign cons $Y Z$
$\text{if } X \text{ goto } \ell_1 \text{ else } \ell_2$	conditional jump

goto (unconditional
jump)
can be expressed as well



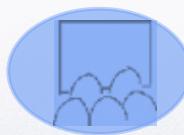
- uses the tree data type we know from WHILE
- does only permit operations on variables
- if X tests whether X is not nil and then jumps according to a label
- store as for WHILE, ReadIn and Readout like WHILE semantics of programs.



Sample Program

```
1: if X goto 2 else 6;  
2: Y := hd X;  
3: R := cons Y R;  
4: X := tl X;  
5: if R goto 1 else 1;  
6: X := R;
```

GOTO programs not as readable
as WHILE programs



What does it compute?



Semantics of GOTO (cont'd)

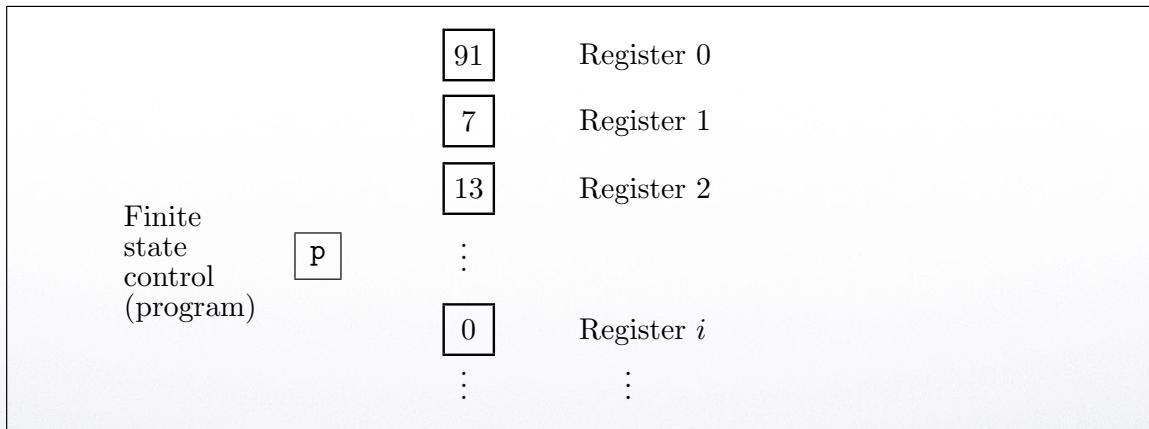
store σ (sigma) where variable X
is assigned value nil

ℓ -th instruction

$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := \text{nil}])$	if $p(\ell) = X := \text{nil}$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := \sigma(Y)])$	if $p(\ell) = X := Y$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := d])$	if $p(\ell) = X := \text{hd } Y$ and $\sigma(Y) = \langle d.e \rangle$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := \text{nil}])$	if $p(\ell) = X := \text{hd } Y$ and $\sigma(Y) = \text{nil}$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := e])$	if $p(\ell) = X := \text{tl } Y$ and $\sigma(Y) = \langle d.e \rangle$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := \text{nil}])$	if $p(\ell) = X := \text{tl } Y$ and $\sigma(Y) = \text{nil}$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := \langle d.e \rangle])$	if $p(\ell) = X := \text{cons } Y Z$ and $\sigma(Y) = d$ and $\sigma(Z) = e$
$p \vdash (\ell, \sigma) \rightarrow (\ell_1, \sigma)$	if $p(\ell) = \text{if } X \text{ goto } \ell_1 \text{ else } \ell_2$ and $\sigma(X) \neq \text{nil}$
$p \vdash (\ell, \sigma) \rightarrow (\ell_2, \sigma)$	if $p(\ell) = \text{if } X \text{ goto } \ell_1 \text{ else } \ell_2$ and $\sigma(X) = \text{nil}$



RAM model



- uses *arbitrarily many* registers containing *arbitrarily big* numbers.



(S)RAM instruction set

S_{uccessor}RAM is like RAM but without binary operations

instruction	explanation
$X_i := 0$	reset register value
$X_i := X_i + 1$	increment register value
$X_i := X_i - 1$	decrement register value
$X_i := X_j$	move register value
$X_i := <X_j>$ <i>indirect addressing</i>	move content of register addressed by X_j
$<X_i> := X_j$	move into register addressed by X_i
if $X_i = 0$ goto ℓ_1 else ℓ_2	conditional jump
available only in RAM	
$X_i := X_j + X_k$	addition of register values
$X_i := X_j * X_k$	multiplication of register values

- data type of *natural numbers*
- angle brackets $< >$ *indirect addressing*
- if-goto-else tests whether X is 0 and then jumps accordingly.



Semantics SRAM

$\text{SRAM-store} = \{ \sigma \mid \sigma : IN \rightarrow IN \}$

$\text{Readin}(x) = \{0:x, 1:0, 2:0, \dots\}$ Input in register X0

$\text{Readout}(\sigma) = \sigma(0)$ From register X0

$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := \sigma(i) + 1])$	if $p(\ell) = \text{Xi} := \text{Xi} + 1$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := \sigma(i) - 1])$	if $p(\ell) = \text{Xi} := \text{Xi} - 1$ and $\sigma(i) > 0$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := 0])$	if $p(\ell) = \text{Xi} := \text{Xi} - 1$ and $\sigma(i) = 0$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := \sigma(j)])$	if $p(\ell) = \text{Xi} := \text{Xj}$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := 0])$	if $p(\ell) = \text{Xi} := 0$
$p \vdash (\ell, \sigma) \rightarrow (\ell_1, \sigma)$	if $p(\ell) = \text{if } \text{Xi} = 0 \text{ goto } \ell_1 \text{ else } \ell_2 \text{ and } \sigma(\text{Xi}) = 0$
$p \vdash (\ell, \sigma) \rightarrow (\ell_2, \sigma)$	if $p(\ell) = \text{if } \text{Xi} = 0 \text{ goto } \ell_1 \text{ else } \ell_2 \text{ and } \sigma(\text{Xi}) \neq 0$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := \sigma(\sigma(j))])$	if $p(\ell) = \text{Xi} := \langle \text{Xj} \rangle$
$p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[\sigma(i) := \sigma(j)])$	if $p(\ell) = \langle \text{Xi} \rangle := \text{Xj}$



Counter Machine CM

$I ::= \text{Xi} := \text{Xi} + 1 \mid \text{Xi} := \text{Xi} - 1 \mid \text{if } \text{Xi}=0 \text{ goto } \ell \text{ else } \ell'$

- Counter machines are much simpler than register machines.
- They contain several registers, called *counters* as they can only be incremented or decremented and tested for zero.
- 2CM is like CM but with 2 counters only.
- Semantics as for register machines.



Cellular Automata CA

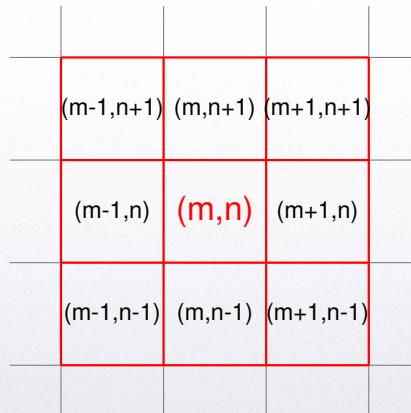
we just focus one specific version the famous 2-dimensional CA called (Conway's) **Game of Life**



John Conway (Cambridge Mathematician)

neighbourhood of (m,n)
= 8 cells

the value of a cell
changes every "time
tick" and the new value
is determined only by
the values of the
neighbourhood cells



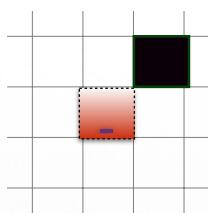
cell lattice (grid)

each cell
contains 0 or 1



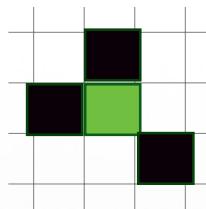
Rules of Game of Life

alive = 1 (solid line/filled)
dead = 0 (no colour)



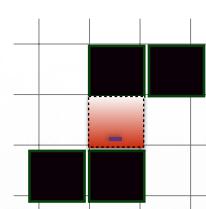
Underpopulation

die if fewer
than two neighbours
are alive



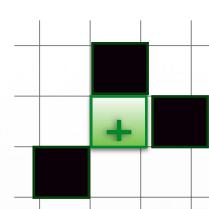
Survival

survive (stay alive)
if two or three
neighbours are
alive



Overcrowding

die if more
than three
neighbours
are alive



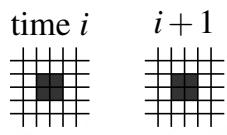
Reproduction

become alive if
exactly three
neighbours
are alive

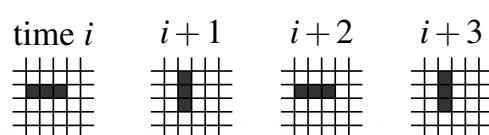


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Patterns of Game of Life

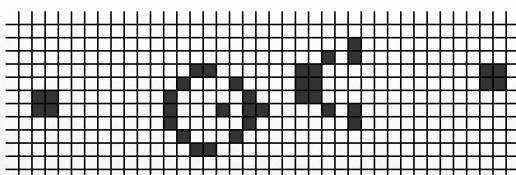


static



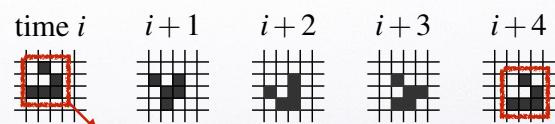
<https://www.youtube.com/watch?v=OrCTmfQWCmQ>

oscillating (dynamic)



<https://www.youtube.com/watch?v=GrlO5RJ76D0>

productive:
Gosling's Glider Gun



one-cell diagonal movement
of glider (dynamic)



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Cellular Automata

- Fun, but can they compute in our sense?
- Yes, one has to:
 - encode input as starting grid
 - result if a predefined cell changes its state to a predefined “accepting state”
 - “accepting state” must be left alone in further grid changes.



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Robustness of Computability

Church-Turing Thesis



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Robustness of Computability

- We justify the Church-Turing thesis ...
- ... by showing that all the above notions of computation are equivalent to WHILE.
- Proof technique:
 - compile one program of language X into an equivalent one of language Y ...
 - ... if X is not a sub-language of Y anyway.
 - compose compilers appropriately to avoid having to write n^2 compilers:



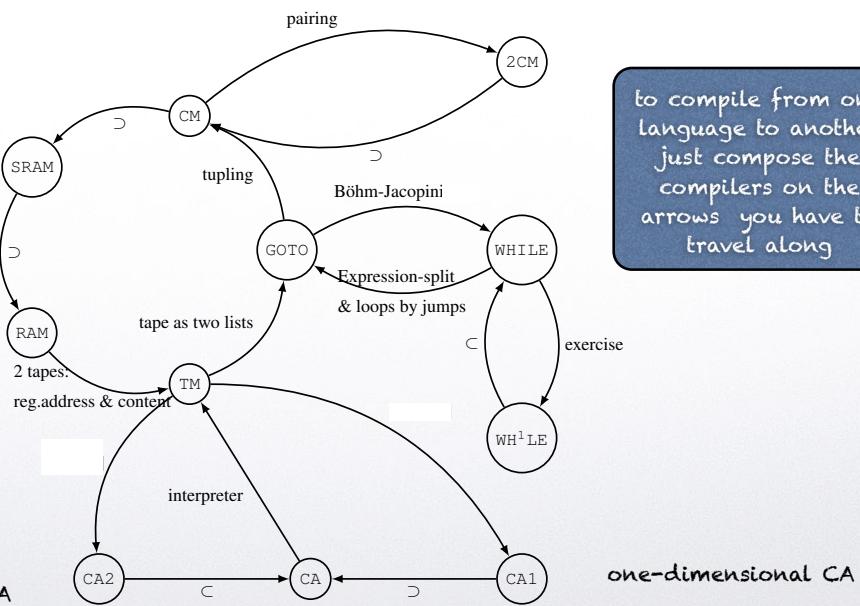
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Diagram of Equivalences

The label of each arrow is either c if one language is included in the other or the name/idea of the required compilation.

Details of compilations
in N. Jones' book,
Chapter 8, exercises.

two-dimensional CA



to compile from one language to another just compose the compilers on the arrows you have to travel along

one-dimensional CA

<https://www.youtube.com/watch?v=My8AsV7bA94>

<https://www.youtube.com/watch?v=xP5-ileKXE8>



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END

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Next time:
Moving on to Complexity.
How do we measure time usage?