



HÁSKÓLINN Í REYKJAVÍK
REYKJAVÍK UNIVERSITY

Computer Graphics

T- 511 – TGRA

Final Exam

Teacher: Kári Halldórsson

Date: 23. November, 2018

Time: 14:00 - 17:00

Helping materials: non-programmable calculator

Name: LAUSNIR

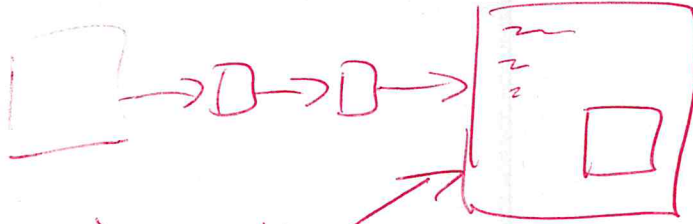
Kt.: _____

Answers can be given in English and/or Icelandic.

1. (10%) Rasterization

Describe the process of rasterization in OpenGL, considering the following questions:

- Where in the OpenGL pipeline does it occur, and what is its purpose?
- How does the algorithm work and what are its inputs?
- What values does it affect and which processes does it run?



- 1 Last in pipeline
- 1 Make pixels in framebuffer from vertex coordinates
- 2 Inputs : vertices of a polygon and linked data like varying
- * 3 Loops from min y to max y and in each scan line from min x to max x
 - 1 Linearly interpolates data like varying
 - 1 Runs fragment shader with those values
 - 1 uses output to set pixel values in frame buffer

2. (10%) Depth testing

Describe the process of depth testing in OpenGL.

What is the purpose of it?

What values are used and how, and where/when are they calculated?

How is the data processed between different parts of the calculations?

2 To display what is closer, regardless of drawing order

1 pseudo depth calculated for vertex
1 in projection

1 interpolated for each pixel
1 in rasterization

1 check if lower than z-buffer

1 then set color in frame buffer

1 and z in z-buffer

else

1 discard both.

3. (10%) Shaders

Describe the input and output of the OpenGL pipeline's two main shaders, considering the following questions:

What types of "global" variables can be defined in each shader?

How are the values of each type of variable affected?

What main output variable is set in each shader?

- 1 attribute variables

- 1 in vertex shader

- 1 when pipeline run, these are set from vertex lists and run automatically

- 1 uniform variables

- in both vertex and fragment shaders

- 1 set at any time by program.

- 1 varying variables

- 1 set in main() code of vertex shader

- 1 interpolated and set by rasterization before running fragment shader

- 1 gl_Position in vertex shader

- 1 gl_FragColor in fragment shader

4. (10%) Cohen-Sutherland Clipping

A clipping window has the following geometry:

Window(left, right, bottom, top) = (-16, 16, -9, 9)

A line with the following end points is drawn in the world:

P1: (22, 11)

P2: (10, 5)

Show how the Cohen-Sutherland clipping algorithm will clip these lines and what their final endpoints, if any, are. Show the coordinate values of P1 and P2 after each pass of the algorithm.

$$\begin{aligned} \Delta x &= 22 - 10 = 12 \\ \Delta y &= 11 - 5 = 6 \end{aligned}$$

Pass 1: code 1: 10 10 (or 0110 or etc.)
code 2: 00 00

P1 to right:

$$\begin{aligned} P1.y &= P1.y + (w.r - P1.x) \cdot \frac{\Delta y}{\Delta x} \\ &= 11 + (16 - 22) \cdot \frac{6}{12} \\ &= 11 - 6 \cdot \frac{1}{2} = 11 - 3 = \underline{8} \end{aligned}$$

$$P1.x = w.r = 16$$

$$P1 = (16, 8) \quad P2 = (10, 5)$$

Pass 2: code 1: 0000
code 2: 0000

TRIVIAL ACCEPT !!

5. (10%) Window-2-Viewport mapping

A second line is drawn into the same window as in the previous example (4. Cohen-Sutherland clipping). This line has the endpoints:

P1 = (-5, 7) & P2 = (12, -2)

In which pixels on a 1920x1080 viewport (bottom left corner (0,0)) will the line's endpoints be rendered?

$$A = \frac{1920}{16 - (-16)} = 60$$

$$B = \frac{1080}{9 - (-9)} = 60$$

$$C = 0 - 60 \cdot (-16) = 960$$

$$D = 0 - 60 \cdot (-9) = 540$$

P1 :

$$sx = 60 \cdot (-5) + 960 = 660$$

$$sy = 60 \cdot 7 + 540 = 960$$

$$P1 : \underline{(660, 960)}$$

P2 :

$$sx = 60 \cdot 12 + 960 = 1680$$

$$sy = 60 \cdot (-2) + 540 = 420$$

$$P2 : \underline{(1680, 420)}$$

6. (40%) Matrices and transformations

a) (10%)

A camera is set up to be positioned in $(-2, 3, 1)$

looking at the point $(1, -1, -1)$.

It has an up vector $(0, 1, 0)$.

Find the values for the camera's coordinate frame, clearly showing each of the four parts of the coordinate frame and what they are.

$$\begin{aligned} n &= \text{eye-center} = (-2, 3, 1) - (1, -1, -1) = (-3, 4, 2) \\ u &= \text{up} \times n = (2, 0, 3) \\ v &= n \times u = (12, 13, -8) \end{aligned} \quad \left| \begin{aligned} |n| &= \sqrt{29} \\ |u| &= \sqrt{13} \\ |v| &= \sqrt{377} \end{aligned} \right.$$

Coordinate frame:

$$\text{eye} = (-2, 3, 1)$$

$$u = \frac{1}{\sqrt{13}} \cdot (2, 0, 3)$$

$$v = \frac{1}{\sqrt{377}} \cdot (12, 13, -8)$$

$$n = \frac{1}{\sqrt{29}} \cdot (-3, 4, 2)$$

MUST

NORMALIZE!

b) (5%)

Show how this coordinate frame would commonly be represented in a matrix. What matrix is this and what are its values in this particular case?

$$-eye \cdot u = \frac{2 \cdot 2 + 0 - 1 \cdot 3}{\sqrt{13}} = \frac{1}{\sqrt{13}}$$

$$-eye \cdot v = \frac{2 \cdot 12 - 3 \cdot 13 - 1 \cdot (-8)}{\sqrt{377}} = \frac{-7}{\sqrt{377}}$$

$$-eye \cdot n = \frac{2 \cdot (-3) - 3 \cdot 4 - 1 \cdot 2}{\sqrt{29}} = \frac{-20}{\sqrt{29}}$$

VIEW MATRIX:

$$\begin{bmatrix} \frac{2}{\sqrt{13}}^{0,55} & 0^0 & \frac{3}{\sqrt{13}}^{0,83} & \frac{1}{\sqrt{13}}^{0,28} \\ \frac{12}{\sqrt{377}}^{0,62} & \frac{13}{\sqrt{377}}^{0,67} & \frac{-8}{\sqrt{377}}^{-0,41} & \frac{-7}{\sqrt{377}}^{-0,36} \\ \frac{-3}{\sqrt{29}}^{-0,56} & \frac{4}{\sqrt{29}}^{0,74} & \frac{2}{\sqrt{29}}^{0,37} & \frac{-20}{\sqrt{29}}^{-3,7} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

c) (10%)

The camera should have a field of view of 120° , an aspect ratio of 16:9, a near plane at 1 and a far plane at 10. Find the exact values for a matrix that calculates this camera.

Which matrix in your shader should be set to these values?

$$\text{top} = N \cdot \tan\left(\frac{\text{fovy}}{2}\right) = 1 \cdot \tan(60^\circ) = 1,732$$

$$\text{bottom} = -\text{top} = -1,732$$

$$\text{right} = \text{top} \cdot \text{ratio} = 1,732 \cdot \frac{16}{9} = 3,079$$

$$\text{left} = -\text{right} = -3,079$$

Projection ?

$$\begin{bmatrix} \frac{2 \cdot 1}{3,079 - (-3,079)} & 0,32 & 0 & 0 \\ 0 & \frac{2 \cdot 1}{1,732 - (-1,732)} & 0 & 0 \\ 0 & 0 & \frac{-(10 + 1)}{10 - 1} & \frac{-2 \cdot 10 \cdot 1}{10 - 1} \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

d) (10%)

Vertex data should be drawn into a coordinate frame that has been first scaled double in all dimensions, then rotated by 30° about the z-axis and finally translated by (2, 4, 7).

Represent this coordinate frame in a matrix. Which matrix would this commonly be?

$$\begin{matrix} 1 & & 2 & & 1 \\ & \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} & \cdot & \begin{bmatrix} 0,866 & -0,5 & 0 & 0 \\ 0,5 & 0,866 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} & \cdot & \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 7 \\ 0 & 0 & 0 & 1 \end{bmatrix} \\ & & & & & \\ 2 & & & & 2 \\ = & \begin{bmatrix} 1,732 & -1,0 & 0 & -0,536 \\ 1,0 & 1,732 & 0 & 8,928 \\ 0 & 0 & 2 & 14 \\ 0 & 0 & 0 & 1 \end{bmatrix} & & &
 \end{matrix}$$

MODEL MATRIX ²