

# BCM63138/BCM63148/BCM4908/BCM63158 Dynamic Crossbar PHY Port Assignment

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## 1 Overview

In BCM63138/BCM63148/BCM4908/BCM63158 devices, some Ethernet ports are not connected to PHY interface directly, instead, these ports are connected to a crossbar switch that connects to many PHY interfaces. Up to and including release 5.02L.04, the crossbar PHY-to-port assignment is defined in boardparams, and cannot be changed at run-time.

Some customers require the flexibility of moving the PHY interface from one port to another during run-time. This run-time PHY port assignment feature is implemented in release 5.02L.05.

Different devices contain different combinations of number of ports on crossbar and number of PHY interfaces. Refer to Device Crossbar Connections for details.

#### 2 Commands

A new ethctl command, phy-crossbar, is added to support the run-time PHY Port assignment feature.

```
Usage: ethctl <interface> phy-crossbar [arguments...]
    phy-crossbar : Get/Move <interface> crossbar phys
    ethctl <interface> phy-crossbar [port <sub_port#>]
        [port <sub_port#>]: assign <sub_port#> to <interface>
    ethctl bcmsw phy-crossbar: list all port phy mapping
```

NOTE: Details of sub port# for different devices is documented in Device Crossbar Connections.

## 2.1 Show Current Port PHY Mapping

```
// 63138REF board example
// specify bcmsw as interface list all mapping
# ethctl bcmsw phy-crossbar
eth0: on crossbar with phy endpoint: 9 10
eth4: on crossbar with phy endpoint: 13

// specify interface not on crossbar get an error and list all mapping
# ethctl eth1 phy-crossbar
eth1: not connected to crossbar!
eth0: on crossbar with phy endpoint: 9 10
eth4: on crossbar with phy endpoint: 13

// specify interface on crossbar get a list of PHYs assigned to interface
# ethctl eth4 phy-crossbar
eth4: on crossbar with phy endpoint: 13
```

## 2.2 Reassign PHY Interface to a Different Port

```
// 63138REF board example
# ethctl eth4 phy-crossbar port 9
Phy endpoint 9 moved from eth0 to eth4
```

**NOTE:** Reassigning a PHY to new port requires bringing down both the source and destination interfaces. This command will print an error if interfaces are not brought down first.

## 2.3 Useful Helper Commands

// 63138REF board example

#### # echo list > /proc/driver/phy/cmd

PHY: proc cmd - list

=		===		===		==		==		===		==		-=-		=
	Id		State		Phy	I	Bus		Addr	-	Speed		Duplex		PHYID	
=		===		===		==:		==:		==:		==:		===		-
	0		Down		GPHY		GMII		0x0c						600d:85c0	
-	1		Up		SERDES		SERDES		0x06		1000 Mbps		Full		0000:0000	
	2		Up		GPHY		GMII		0x08		1000 Mbps		Full		600d:85c0	
	3		Down		GPHY		GMII		0x09						600d:85c0	
	4		Down		GPHY		GMII		0x0a						600d:85c0	
	5		Down		GPHY		GMII		0x0b						600d:85c0	
-	6		Down		I2C				0x0						0000:0000	
1=				===						===						-

#### # echo crossbars > /proc/driver/phy/cmd

PHY: proc cmd - crossbars

ı	=====	===					-=:				ı
İ	Id	-	activ	те		Phy		Bus	1	Addr	İ
1	0	=== 	====== I2-		 I	======		======			1
İ		İ	-E1	*	İ	GPHY	i	GMII	İ	0x0c	
		===			==				==:		
	1		IO-								
-			-E4			GPHY		GMII		0x0b	
			-E0	*		SERDES		SERDES		0x06	l
			-E0			I2C				0x00	l

## 3 Configuration Steps

- 1. Bring down both the source and destination interfaces (ports).
- 2. Reassign PHY to new interface.
- 3. Bring up both the source and destination interfaces (ports).

## 3.1 Example: on BCM963138REF board

#### Initial configuration:

```
eth0: <Int sw port: 0> <Logical : 00> MAC : 02:10:18:34:99:01
        Chip Physical Port 10, Cross Bar Port 1, PHY_ID <0x0007f00c:0x0c:GPHY >
        Chip Physical Port 9, Cross Bar Port 0, PHY_ID <0x06180006:0x06:SERDES >
eth1: <Ext sw port: 0> <Logical : 08> PHY_ID <0x0007f008:0x08:GPHY> MAC:02:10:18:34:99:01
eth2: <Ext sw port: 1> <Logical : 09> PHY_ID <0x0007f009:0x09:GPHY> MAC:02:10:18:34:99:01
eth3: <Ext sw port: 2> <Logical : 10> PHY_ID <0x0007f00a:0x0a:GPHY> MAC:02:10:18:34:99:01
eth4: <Ext sw port: 3> <Logical : 11> MAC : 02:10:18:34:99:01
        Chip Physical Port 13, Cross Bar Port 4, PHY_ID <0x0007f00b:0x0b:GPHY >

# ethct1 bcmsw phy-crossbar
eth0: on crossbar with phy endpoint: 9 10
eth4: on crossbar with phy endpoint: 13
```

## 3.2 Moving Subport 9 SerDes PHY from eth0 to eth4

```
// step 1: bring down eth0 and eth4
# ifconfig eth4 down
device eth4 left promiscuous mode
br0: port 4(eth4.0) entered disabled state
# ifconfig eth0 down
eth0 (Int switch port: 0) (Logical Port: 0) (phyId: 6) Link DOWN.
// step 2: assign subport 9 to eth4
# ethctl eth4 phy-crossbar port 9
Phy endpoint 9 moved from eth0 to eth4
// step 3: bring up eth0 and eth4
# ifconfig eth0 up
IPv6: ADDRCONF(NETDEV UP): eth0: link is not ready
# ifconfig eth4 up
IPv6: ADDRCONF(NETDEV UP): eth4: link is not ready
device eth4 entered promiscuous mode
IPv6: ADDRCONF(NETDEV_UP): eth4.0: link is not ready
eth4 (Ext switch port: 3) (Logical Port: 11) (phyId: 6) Link UP at 1000 mbps full duplex
IPv6: ADDRCONF(NETDEV_CHANGE): eth4: link becomes ready
IPv6: ADDRCONF(NETDEV CHANGE): eth4.0: link becomes ready
br0: port 4(eth4.0) entered forwarding state
br0: port 4(eth4.0) entered forwarding state
// optional showing current PHY port mapping
# ethctl bcmsw phy-crossbar
eth0: on crossbar with phy endpoint: 10
eth4: on crossbar with phy endpoint: 9 13
```

#### 3.3 Limitations

The PHY interface connecting directly to peer MAC (MAC-to-MAC) connection cannot be reassigned at run-time. To support these connections, significant code change is required.

Only boardparams-defined PHY interfaces on the crossbar, and defined ports on the crossbar, can participate in run-time PHY port assignment.

On the BCM63138 device, GPHY3 (subport 13) can only be not used, or assigned to SF2 port 3.

## **4 Device Crossbar Connections**

#### 4.1 BCM63138

**Table 1: Direct Connections** 

Switch - Port	PHY Interface
SF2 (external) -port 0	GPHY0
SF2 (external) -port 1	GPHY1
SF2 (external) -port 2	GPHY2
SF2 (external) -port 5	RGMII1
SF2 (external) –port 7	RGMII2

Table 2: 3x5 Crossbar

Three Internal Endpoints (Ports)	Switch - Port
10	SF2 (external) – port 3
l1	SF2 (external) – port 4
12	Runner (internal) – port 0 (WAN)
Five External Endpoints (PHYs)	Interface
E0 (subport 9)	Active Ethernet
E1 (subport 10)	GPHY4
E2 (subport 11)	RGMII3
E3 (subport 12)	MII/TMII/RvMII/RGMII
E4 (subport 13)	GPHY3

## 4.2 BCM63148

#### **Table 3: Direct Connections**

Switch - Port	PHY Interface	
SF2 (external) –port 0	GPHY0	
SF2 (external) –port 1	GPHY1	
SF2 (external) –port 2	GPHY2	
SF2 (external) –port 3	GPHY3	
SF2 (external) –port 5	RGMII1	
SF2 (external) –port 7	RGMII2	

#### Table 4: 2x4 Crossbar

Two Internal Endpoints (ports)	Switch - Port
10	SF2 (external) – port 4
11	Runner (internal) – port 0 (WAN)
Four External Endpoints (PHYs)	Interface
E0 (subport 9)	Active Ethernet
E1 (subport 10)	GPHY4
E2 (subport 11)	RGMII3
E3 (subport 12)	MII/TMII/RvMII/RGMII

## 4.3 BCM4908

#### **Table 5: Direct Connections**

Switch - Port	PHY Interface
SF2 (external) –port 0	GPHY0
SF2 (external) –port 1	GPHY1
SF2 (external) -port 2	GPHY2
SF2 (external) –port 3	GPHY3

#### Table 6: 2x3 Crossbar

Two Internal Endpoints (ports)	Switch - Port
10	SF2 (external) – port 7
l1	Runner (internal) – port 3 (WAN)
Three External Endpoints (PHYs)	Interface
E0 (subport 9)	SerDes
E1 (subport 10)	GPHY4
E2 (subport 11)	MII/RvMII/RGMII

## 4.4 BCM63158

#### **Table 7: Direct Connections**

Switch - Port	PHY Interface
SF2 (external) –port 0	GPHY0
SF2 (external) –port 1	GPHY1
SF2 (external) –port 2	GPHY2
SF2 (external) -port 3	GPHY3

#### Table 8: 3x4 Crossbar

Three Internal Endpoints (Ports)	Switch - Port
10	SF2 (external) – port 4
[1]	SF2 (external) – port 6
12	Runner (internal) – XPORT1 (WAN)
Four External Endpoints (PHYs)	Interface
E0 (subport 9)	SerDes
E1 (subport 10)	GPHY4
E2 (subport 11)	RGMII0
E3 (subport 12)	RGMII1

## **5 Example Initial Configuration**

Using BCM4908 device selecting E1 (subport 10) GPHY4 between I1 Runner-port3 (WAN) and I0 SF2-port7 (LAN).

#### Scenario 1: Initially assigning GPHY4 to WAN (eth0) port

In this case, SF2-port7 (eth5) has no PHY endpoint initially. Following is a sample boardparms.c definition.

```
{bp ucPhyType0,
                       .u.uc = BP ENET NO PHY}, // Runner
                       .u.us = BP ENET CONFIG MMAP},
 {bp usConfigType,
                         .u.uc = 0x1e,
 {bp ucPhyAddress,
 {bp ulPortMap,
                         .u.ul = 0x9,
 {bp_ulCrossbarPhyId,
                         .u.ul = (BCM94908 PHY BASE + 0x04) | (ADVERTISE ALL GMII |
PHY ADV CFG VALID) },
 /* use the WAN LED from runner */
 {bp_usSpeedLed100, .u.us = BP_SERIAL_GPIO_22_AH},
 {bp_usSpeedLed1000, u.us = BP_SERIAL_GPIO_23_AH},
                         .u.us = BP SERIAL GPIO 21 AH},
 {bp usLinkLed,
 switch
                       .u.ul = 0x8f),
 {bp ulPortMap,
 {bp ulPhyId0,
                         .u.ul = (BCM94908 PHY BASE + 0x00) | (ADVERTISE ALL GMII |
PHY ADV CFG VALID) },
 .u.us = BP_SERIAL_GPIO_26_AH},
 {bp ulPhyId1,
                         .u.ul = (BCM94908 PHY BASE + 0x01) | (ADVERTISE ALL GMII |
PHY ADV CFG VALID) },
                       .u.us = BP_SERIAL_GPIO_2_AH},
.u.us = BP_SERIAL_GPIO_3_AH},
.u.us = BP_SERIAL_GPIO_27_AH},
 {bp_usSpeedLed100,
 {bp usSpeedLed1000,
 {bp usLinkLed,
 {bp ulPhyId2,
                         .u.ul = (BCM94908 PHY BASE + 0x02) | (ADVERTISE ALL GMII |
PHY ADV CFG VALID) },
 {bp_usSpeedLed100,
                         .u.us = BP SERIAL GPIO 4 AH},
                        .u.us = BP_SERIAL_GPIO_5_AH},
 {bp_usSpeedLed1000,
                        .u.us = BP_SERIAL_GPIO 28 AH},
 {bp usLinkLed,
 {bp ulPhyId3,
                         .u.ul = (BCM94908 PHY BASE + 0x03) | (ADVERTISE ALL GMII |
PHY ADV CFG VALID) },
 {bp usSpeedLed100,
                        .u.us = BP SERIAL GPIO 6 AH},
 {bp_usSpeedLed1000,
                         .u.us = BP SERIAL GPIO 7 AH},
                       .u.us = BP SERIAL GPIO 29 AH},
 {bp usLinkLed,
 {bp ulPhyId7, .u.ul = BP PHY ID NOT SPECIFIED}, ← no crossbar PHY endpoint
```

#### During run-time, GPHY4 can be re-assigned to eth5 by:

```
# ifconfig eth5 down; ifconfig eth0 down
# ethctl eth5 phy-crossbar port 10
# ifconfig eth5 up; ifconfig eth0 up
```

#### Scenario 2: Initially assigning GPHY4 to LAN (eth5) port

```
eth0: <Int sw port: 3> <Logical : 03> MAC : 02:10:18:34:44:01
eth1: <Ext sw port: 0> <Logical : 08> PHY_ID <0x0007f008:0x08:GPHY> MAC:02:10:18:34:44:01
eth2: <Ext sw port: 1> <Logical : 09> PHY_ID <0x0007f009:0x09:GPHY> MAC:02:10:18:34:44:01
eth3: <Ext sw port: 2> <Logical : 10> PHY_ID <0x0007f00a:0x0a:GPHY> MAC:02:10:18:34:44:01
eth4: <Ext sw port: 3> <Logical : 11> PHY_ID <0x0007f00b:0x0b:GPHY> MAC:02:10:18:34:44:01
eth5: <Ext sw port: 7> <Logical : 15> MAC : 02:10:18:34:44:01
Chip Physical Port 10, Cross Bar Port 1, PHY ID <0x0007f00c:0x0c:GPHY>
```

In this case, runner-port3 (eth0) has no PHY endpoint initially. Following is a sample boardparms.c definition.

```
.u.uc = BP_ENET_NO_PHY}, // Runner
.u.us = BP_ENET_CONFIG_MMAP},
.u.uc = 0x1e},
 {bp ucPhyType0,
 {bp usConfigType,
 {bp_ucPhyAddress,
 {bp ulPortMap,
                     .u.ul = 0x9,
                     .u.ul = GMII DIRECT | EXTSW CONNECTED},
 {bp ulPhyId0,
 {bp usLinkLed,
                     .u.us = BP SERIAL GPIO 21 AH},
 switch
 {bp ulPortMap,
                     .u.ul = 0x8f),
 {bp ulPhyId0,
                     .u.ul = (BCM94908 PHY BASE + 0x00) | (ADVERTISE ALL GMII |
PHY ADV CFG VALID) },
 .u.ul = (BCM94908 PHY BASE + 0x01) | (ADVERTISE ALL GMII |
 {bp ulPhyId1,
PHY ADV CFG_VALID) },
 .u.ul = (BCM94908 PHY BASE + 0x02) | (ADVERTISE ALL GMII |
 {bp ulPhyId2,
PHY ADV CFG VALID) },
 .u.ul = (BCM94908 PHY BASE + 0x03) | (ADVERTISE ALL GMII |
 {bp ulPhyId3,
PHY ADV CFG VALID) },
               .u.us = BP_SERIAL_GPIO_6_AH},
.u.us = BP_SERIAL_GPIO_7_AH},
 {bp_usSpeedLed100,
 {bp usSpeedLed1000,
                     .u.us = BP_SERIAL_GPIO_29_AH},
 {bp_usLinkLed,
 {bp_ulPhyId7,
                  .u.ul = BP_PHY_ID_NOT_SPECIFIED},
                .u.ul = 10},
.u.ul = (BCM94908_PHY_BASE + 0x04) | (ADVERTISE_ALL_GMII |
 {bp ulCrossbar,
 {bp ulCrossbarPhyId,
PHY ADV CFG VALID) },
```

#### During run-time, GPHY4 can be re-assigned to eth0 by:

- # ifconfig eth5 down; ifconfig eth0 down
- # ethctl eth0 phy-crossbar port 10
- # ifconfig eth5 up; ifconfig eth0 up

# **Revision History**

# **April 16, 2018**

Initial release

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