

# Notes on Inference Devices

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## 1 Notation and Definitions

Standard notation is taken from set theory and vector algebra. We clarify some notation specific to computation and inference devices.

### Computation and Turing Machines

- $\mathbb{B}^*$  The space of all finite bit strings.
- $\Lambda$  Symbol alphabet of a Turing Machine.
- $\sigma$  A symbol on a Turing Machine tape.
- $Q$  Set of finite states of a Turing Machine.
- $\Delta$  Transition function of a Turing Machine.
- $k$  Number of tapes of a Machine.
- $\eta$  Non-halting state of a Turing Machine.

### Inference Devices

- $U$  Set of possible histories of the universe.
- $u$  A history of the universe in  $U$ .
- $X$  Setup function of an ID that maps  $U \rightarrow X(U)$ . A binary question concerning  $\Gamma(u)$ .
- $x$  A binary question and a member of image  $X(U)$ .
- $Y$  Conclusion function of an ID that maps  $U \rightarrow \{-1, 1\}$ . A binary answer of an ID for  $X(u) = x$ .
- $y$  A single-valued answer, and member of image  $Y(U) = \{0, 1\}$ .
- $\Gamma$  A function of the actual values of a physical variable over  $U$ , equivalent to  $\Gamma(u) = S(t_i)(u)$ .
- $\gamma$  Possible value of a physical variable, a member of the image  $\Gamma(U)$ .
- $\delta$  Probe of any variable  $V$  parameterized by  $v \in V$  such that :

$$\delta_v(v') = \begin{cases} 1 & \text{if } v = v' \\ -1 & \text{otherwise} \end{cases}$$

- $\wp$  Set of probes over  $\Gamma(U)$ .

$\mathcal{D} = (X, Y)$  An inference device, consisting of functions  $X$  and  $Y$ .

$\bar{F}$  Inverse. Given a function  $F$  over  $U$ ,  $F^{-1} = \bar{F} \equiv \{\{u : F(u) = f\} : f \in F(U)\}$ .

> Weak inference: a device  $\mathcal{D}$  weakly infers  $\Gamma$  iff  $\forall \gamma \in \Gamma(U), \exists x \in X(U)$  s.t.  $\forall u \in U$ ,  
 $X(u) = x \implies Y(u) = \delta_\gamma(\Gamma(u))$ .

>> Strong inference: a device  $(X_1, Y_1)$  strongly infers a device  $(X_2, Y_2)$  iff  $\forall \delta \in \wp(Y_2)$   
and all  $x_2, \exists x_1$  such that  $X_1 = x_1 \implies X_2 = x_2, Y_1 = \delta(Y_2)$ .

## 2 Turing Machines

Arora and Barak denote a Turing Machine (TM) as  $T = (\Lambda, Q, \Delta)$  containing:

1. An *alphabet*  $\Lambda$  of a finite set of symbols that  $T$ 's tapes can contain. We assume that  $\Lambda$  contains a special blank symbol  $B$ , start symbol  $S$ , and the numbers 0 and 1.
2. A finite set  $Q$  of possible states that  $T$ 's register can be in. We assume that  $Q$  contains a special start state  $q_s$  and a special halt state  $q_h$ .
3. A transition function function  $\Delta : Q \times \Lambda^k \rightarrow Q \times \Lambda^{k-1} \times \{L, S, R\}^k$ , where  $k \geq 2$ , describing the rules  $T$  use in performing each step. The set  $\{L, S, R\}$  denote the actions *Left*, *Stay*, and *Right*, respectively.

Suppose  $T$  is in state  $q \in Q$  and  $(\sigma_1, \sigma_2, \dots, \sigma_k)$  are the symbols on the  $k$  tapes. Then  $\Delta(q, (\sigma_1, \dots, \sigma_k)) = (q', (\sigma'_2, \dots, \sigma'_k), z)$  where  $z \in \{L, S, R\}^k$  and at the next step the  $\sigma$  symbols in the last  $k - 1$  tapes will be replaced by the  $\sigma'$  symbols, the machine will be in state  $q$ , and the  $k$  heads will move *Left*, *Right* or *Stay*. This is illustrated in Figure 1.

**Figure 1. The transition function  $\Delta$  for a  $k$ -tape Turing Machine**

| $(q, (\sigma_1, \dots, \sigma_k))$ |                               |          |                  | $(q', (\sigma'_2, \dots, \sigma'_k), z)$ |          |                             |          |              |
|------------------------------------|-------------------------------|----------|------------------|--|----------|-----------------------------|----------|--------------|
| Input<br>symbol                    | Work/output<br>symbol<br>read | ...      | Current<br>state | New<br>work/output<br>tape symbol        | ...      | Move<br>work/output<br>tape | ...      | New<br>state |
| $\vdots$                           | $\vdots$                      | $\ddots$ | $\vdots$         | $\vdots$                                 | $\ddots$ | $\vdots$                    | $\ddots$ | $\vdots$     |
| $\sigma_1$                         | $\sigma_i$                    | $\ddots$ | $q$              | $\sigma'_i$                              | $\ddots$ | $z_i$                       | $\ddots$ | $q'$         |
| $\vdots$                           | $\vdots$                      | $\ddots$ | $\vdots$         | $\vdots$                                 | $\ddots$ | $\vdots$                    | $\ddots$ | $\vdots$     |

*Remark:*  $\Lambda$  can be reduced to  $\mathbb{B} = \{0, 1\}$  and  $k$  can be reduced to 1 without loss of computational power. Then, any Turing Machine can be expressed as a partial recursive function mapping  $\mathbb{B}^* \rightarrow \mathbb{B}^* \cup \eta$ , where  $\eta$  is the undefined non-halting output. Since  $|\mathbb{B}^* \times \mathbb{B}^* \cup \eta| = |\mathbb{N} \times \mathbb{N}| = |\mathbb{N}|$ , the set of all Turing Machines is countably infinite.

### 3 Inference of Turing Machines

**Theorem** *Every Turing Machine can be weakly inferred by an inference device.*

**Proof** Recall the definition of weak inference:

$$\mathcal{D} > \Gamma \text{ iff } \forall \gamma \in \Gamma(U), \exists x \in X(U) \text{ such that } \forall u \in U, X(u) = x \implies Y(u) = \delta_\gamma(\Gamma(u))$$

Preliminaries:

We want to define a countably infinite  $U$ ,  $X(U)$ , so that an inference device can weakly infer a countably infinite  $\Gamma = \{b \in \mathbb{B}^*, T_1(b)\}$ .  $x \in X(U)$  can be informally phrased as: "For this input string  $b$ , what is  $T_1(p)$ ? Then the inference device must be able to answer correctly, for either of the probes for  $\gamma_i$ .

Working definition of weak inference:  $\forall \gamma_i, \forall \delta_{\gamma_i}, \exists x : \forall u \in X^{-1}(x), Y(u) = \delta_{\gamma_i}(u)$

Take  $U$  to be the integers. The hard part is mapping  $U$  to  $(p, T_1(p))$ . The mapping must be injective, i.e. there must be some  $u$  for each  $(p, T_1(p))$  tuple.

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Let  $U := \mathbb{N}$ . Let  $X : U \rightarrow \mathbb{B}^*$  be the lexicographic mapping of integers to binary bit strings.

**Theorem** *Every Turing Machine can be strongly inferred by an inference device.*

**Proof** Recall the definition of strong inference:

$$(X_1, Y_1) >> (X_2, Y_2) \text{ iff } \forall \delta \in \wp(Y_2) \text{ and all } x_2, \exists x_1 \text{ such that } X_1 = x_1 \implies X_2 = x_2, Y_1 = \delta(Y_2)$$

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Let  $U := \mathbb{N}$ . Define  $S : U \rightarrow \mathbb{B}^*$  to be the lexicographic mapping of integers to binary bit strings and  $T : U \rightarrow \mathbb{B}^* \times \mathbb{B}^* \cup \eta$  as a function that maps  $u$  to the Cartesian product of the space of bits strings with all possible outputs from any Turing machine.

We want to construct an inference device  $(X, Y)$  such that  $(X, Y) >> (S, T)$ . We need to show that for all probes for  $T$  and for all values of  $s \in S$  there exist some  $x \in X$  such that  $x$  forces  $s$  and forces  $y$  to equal  $\delta(T)$ .

Let  $X : U \rightarrow \mathbb{B}^*$  be the lexicographic mapping of integers to binary bits strings such that 1 is alphabetically before 0. Then  $X(u) = x \text{ iff } S(u) = s$ .

Now we want to construct a  $Y$  that correctly answers  $\delta(Y_2)$  for all probes and for all  $s$  when  $X = x$ .