## **COMP PROJECT:**

# **Liver Tumor Segmentation**

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# Agenda

- 1. Project Idea
- 2. Background
- 3. Methods
- 4. Performance measurement
- 5. Originality
- 6. Live demo



## **Project Idea**

• Participate at Liver Tumor Segmentation (LiTS) Challenge <a href="https://competitions.codalab.org/competitions/17094#learn\_the\_details">https://competitions.codalab.org/competitions/17094#learn\_the\_details</a>

#### **Minimum:**

- Beat 100st place
- Detect:
  - lesions with dice score of 60%
  - liver with dice score of 90%
  - tumor burden with RMSE 0.04

#### Ideal:

- Beat the current 1<sup>st</sup> place
- Detect:
  - lesions with dice score of 80%
  - liver with dice score of 97%
  - tumor burden with RMSE 0.02



## **Background**

#### **Dataset:**

- LiTS-Challenge Dataset (training and test data)
  - https://drive.google.com/drive/folders/0B0vscETPGI1-Q1h1WFdEM2FHSUE
  - https://drive.google.com/drive/folders/0B0vscETPGI1-NDZNd3puMIZiNWM

### Paper:

- U-net, <a href="https://arxiv.org/abs/1505.04597">https://arxiv.org/abs/1505.04597</a>
- Deep learning and level set approach for liver and tumor segmentation from CT scans,

https://aapm.onlinelibrary.wiley.com/doi/epdf/10.1002/acm2.13003

#### Code:

- U-net applied on <u>3D-IRCADb</u>, <a href="https://github.com/zhaohandd/Unet-liverCT">https://github.com/zhaohandd/Unet-liverCT</a>
- U-net applied on LiTS
  - <u>https://www.kaggle.com/arunasna/liver-segmentation-with-fastai-v2/notebook</u>
  - https://github.com/FelixGruen/tensorflow-u-net

### **Methods**

#### **Data Processing:**

- Convert given NIfTI to another format
- Liver Detection:
  - Median filtering
  - Intensity windowing
- Tumor Detection:
  - edge enhancing diffusion (EED) filtering
  - Intensity windowing

### **Semantic Segmentation:**

- Fully Convolutional Network-based
  - U-net and its family, <a href="https://github.com/ShawnBIT/UNet-family">https://github.com/ShawnBIT/UNet-family</a>



### **Performance measurement**

- Overall segmentation accuracy
  - Dice score for liver and lesion segmentation
- Tumour Detection
  - Root-mean-square error (RMSE) for tumour burden
- Training and running time
  - Does not need to be real time



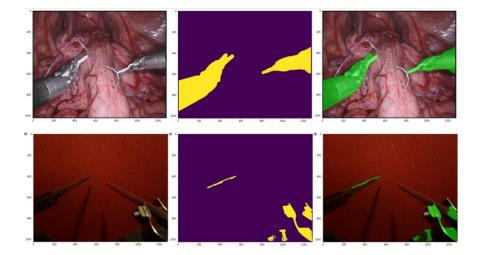
## **Originality**

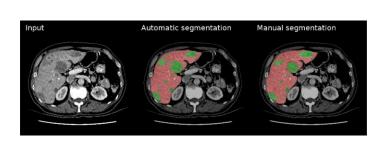
Not doing something new, rather trying to improve previous work



# Live-demo

6.





• <a href="https://github.com/ternaus/robot-surgery-segmentation">https://github.com/ternaus/robot-surgery-segmentation</a>