Introduction to High Performance Scientific Computing

Autumn, 2016

Lecture 10

Today

- A few comments on Fortran
- F2Py with fortran modules
- Timing Fortran code
- Networks

- Do not attempt to guess Fortran syntax! look it up instead
- Do not develop Fortran code in Python using f2py get a Fortranonly code working first
- Test code (compile and run) after adding a few (4-5) lines of code.
 Don't write 100 lines and then test!
- Lecture 7: code structure, variable types, loops, if-then, subroutines
- Lecture 8: allocatable arrays, functions modules
- Lecture 9: Lapack, f2py

Debugging code

- If the compiler is giving you a series of errors, look at the topmost error message. It will include a line number
- If the code runs but crashes with a segmentation fault: probably a problem with array indices (e.g. trying to access the 12th element of a dimension(11) array
- If you can't tell where the code is crashing, add print statements, e.g. print *, 1 --some code- print *, 2
 When the code is run, if the 1 prints to screen but not the 2, you know where the problem is.
- If the code runs, but gives the wrong answer, add print statements outputting values of variables, try a small problem size where you know what values the variables can take

- Modules consist of:
 - 1. Module variables
 - 2. Module sub-programs
- Module variables are "available" throughout the module
 - They do not need to be declared
 - They do not need to be provided as input/output in the subprogram header
- Module variables and module sub-programs are also "available" in any program or sub-program that uses the module
- A module by itself doesn't do anything
 - There should be a "main" program which uses it
 - You can compile a module by itself: gfortran -c module.f90
 - But to generate an executable, you need a <u>program</u>: gfortran -o program.exe module.f90 program.f90
 When re-compiling, first remove the previous .mod file

Compiling code that uses lapack routines:

```
$ gfortran -c program.f90
$ gfortran -o program.exe program.o -llapack
or
```

\$ gfortran -o program.exe program.f90 -llapack

Similarly, with f2py:

\$ f2py -llapack -c program.f90 -m module_name

- F2Py will recognize subroutines and functions in modules
- What about variables?
 - Try f2py with circle module from last week (f2pymodule_circle.f90)

```
$ f2py -c f2pymodule_circle.f90 -m cmod
```

```
In [10]: import cmod
In [11]: cmod.<tab>
cmod.circle cmod.so
```

Need to look at cmod.circle

Need to look at *cmod.circle*:

```
In [12]: cmod.circle?
Docstring:
'd'-scalar
initialize_pi()
Wrapper for ``initialize_pi``.
circumference = circumference(radius)
Wrapper for ``circumference``.
Parameters
radius : input float
Returns
circumference: float
                             And similar info for "area"
area = area(radius)
```

How do we access variables and methods in cmod.circle?

Can initialize pi in python:

```
In [9]: cmod.circle.pi
Out[9]: array(0.0)
In [10]: cmod.circle.pi = pi
In [11]: cmod.circle.pi
Out[11]: array(3.141592653589793)
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Can also initialize allocatable arrays, see f2pymodule_circle_array.f90:

```
!module for computing circumference, area, and "mass" of circle
module circle
   implicit none
   real(kind=8) :: pi
   real(kind=8), allocatable, dimension(:) :: weights,mass
   save
subroutine compute_mass(radius,mass)
    !compute mass = weights*area
    implicit none
    real(kind=8), intent(in) :: radius
    real(kind=8), intent(out) :: mass(:)
    mass = weights*area(radius)
end subroutine compute_mass
```

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- 3. Initialize variables:

```
In [15]: cmoda.circle.pi=pi
In [16]: cmoda.circle.weights=arange(5)
In [17]: cmoda.circle.pi,cmoda.circle.weights
Out[17]: (array(3.141592653589793), array([ 0., 1., 2., 3., 4.]))
```

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- 1. Compile with f2py: \$ f2py -c f2pymodule_circle_array.f90 -m cmoda
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Out[17]: (array(3.141592653589793), array([ 0., 1., 2., 3., 4.]))
```

4. Compute mass:

```
In [18]: cmoda.circle.compute_mass(2.0)
In [19]: cmoda.circle.mass
Out[19]: array([ 0. , 12.56637061, 25.13274123, 37.69911184, 50.26548246])
```

Finite difference methods

- Finite difference methods are a standard approach for numerical differentiation.
- They form the basis for a wide variety of methods used to solve partial differential equations
- See online supplementary class notes: Notes on numerical differentiation with finite difference methods

Unix time command

Can use time to obtain timing info for any unix command:

```
$ time ./midpoint.exe
N= 512000
sum= 3.1415926535901515
error= 3.5837999234900053E-013
real 0m0.015s
user 0m0.010s
sys 0m0.003s
```

- real is approximately the wall-clock time
- user is time spent executing the program
- sys is time spent on system tasks required by program

- Unix time doesn't tell you how much time different parts of program take
- system_clock and cpu_time gives wall time and cpu time between two points in code
- See midpoint_time.f90:

```
!timing variables
    real(kind=8) :: cpu_t1,cpu_t2,clock_time
    integer(kind=8) :: clock_t1,clock_t2,clock_rate
```

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```
!timing variables
       real(kind=8) :: cpu t1,cpu t2,clock time
       integer(kind=8) :: clock t1,clock t2,clock rate
    call system clock(clock t1)
    call cpu time(cpu t1)
       !loop over intervals computing each interval's contribution to
   integral
   ... Midpoint quadrature ...
    call cpu time(cpu t2)
    print *, 'elapsed cpu time (seconds) =',cpu_t2-cpu_t1
    call system clock(clock t2,clock rate)
    print *, 'elapsed wall time (seconds)= ',
                              dble(clock t2-clock t1)/dble(clock rate)
Imperial College
London
```

- Unix time doesn't tell you how much time different parts of program take
- system_clock and cpu_time gives wall time and cpu time between two points in code
- See midpoint_time.f90:

```
$ ./midpoint_t.exe
elapsed cpu time (seconds) = 8.62399999999999997E-003
elapsed wall time (seconds) = 9.12799966E-03
N = 512000
sum = 3.1415926535901515
error = 3.5837999234900053E-013
```

Can place timing commands throughout code to find bottlenecks

- Also, often have a theoretical estimate of how cost scales with problem size
- A method may require O(N) (or O(NIn₂N) or O(N²)) operations
- But does your implementation of the algorithm match theory?
- How do compiler optimizations affect performance?
- Carefully timing code while varying the problem size can help answer these questions

Networks

Examples of significant networks include:

Social networks

World-wide web

Internet

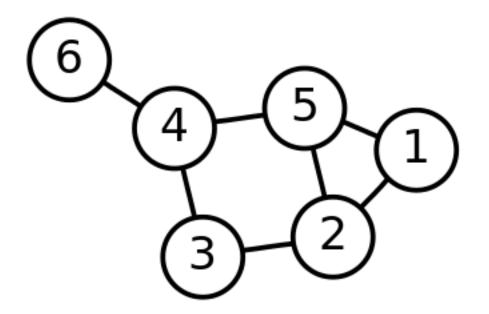
Air transportation network

Cellular network

The science of networks is an important, rapidly growing field

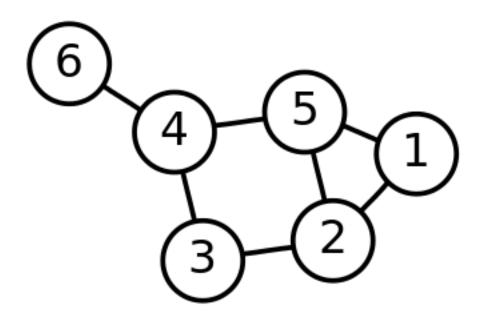
- A network has N nodes and L links between nodes
- Each node has a label, e.g. 1, 2, ..., N
- Then a link between node i and j can be represented simply as (i, j)

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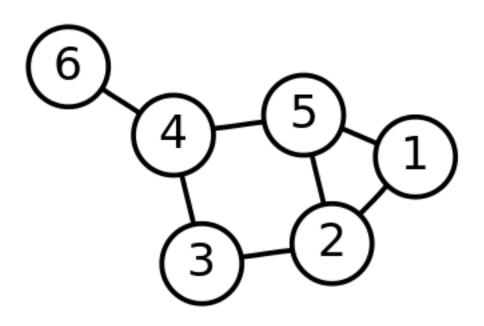
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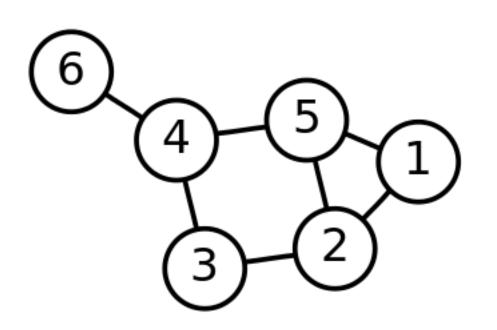
Can also represent connected portions of graph with edge list:

Example: 6 nodes, 7 lines Node one has two edges: (1,2) and (1,5)

The graph can be represented by the *adjacency matrix*, A A_{ij}=1 if there is link between nodes i and j

$$\begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$$

A is symmetric.



The *degree* of a node is the number of is the total number of links connected to it:

$$q_1 = 2, q_5 = 3, ...$$

The degree distribution, P(q) is particularly important. P(q) is the fraction of nodes in the graph with degree = q

$$P(1) = 1/6, P(2) = 2/6, P(3) = 3/6$$

Homework 3: You will work with a simple model for growing networks.