Introduction to High Performance Scientific Computing

Autumn, 2016

Lecture 17

Imperial College

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Project Part 1

- · Random walks in 1-D
- · Consider equations of the form:

X(t+dt) = X(t) + F[X(t),dt]

- Here, X and F, are both random variables
- Simplest example: F = +/- dx based on flip of a coin → random walk

Compute several realizations, X1(t), X2(t),... XM(t) and then compute statistics over these M realizations

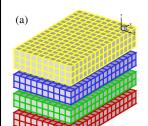
These statistics (the mean and stdev) will generally depend on time

Imperia collegandom walk on a network follows same idea

Send/Recv and domain decomposition

A parallel computation computes a potential field, f(x,y,z,t) on four

processors. P0, P1, P2, P3 solve for *f* in separate subdomains



How would you compute the gradient?

$$\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}\right)$$

- No problems with x and z directions
- But what about y?

Last time: Send/Recv A parallel computation computes a potential field, f(x,y,z,t) on four processors. P0, P1, P2, P3 solve for f in separate subdomains - Send and Recv must be paired: - If yellow sends to blue, blue must recv from yellow - Yellow and blue should not send to each other simultaneously - Instead: - Yellow → Blue - Blue - Green - Red - Red - Yellow (if periodic) - and then the reverse

Parallel differentiation example

Today

Solving the (steady) 2D heat equation

Heat equation

Task: Compute temperature distribution in a room

Governing equation: Heat equation (diffusion equation):

$$\frac{\partial T}{\partial t} = \alpha \nabla^2 T + S(\mathbf{x}, t)$$

$$T(\mathbf{x},t=0)=f(\mathbf{x})$$
 Initial condition

Here, S is a heat source. Boundary conditions should also be specified as appropriate.

Problem: given the source, initial condition, and boundary conditions, solve for the temperature distribution, $\mathsf{T}(\boldsymbol{x},t)$

1-D (steady) heat equation

First consider steady problem, e.g., S = S(x), a and b are constants:

$$rac{\partial^2 T}{\partial x^2} + S(x) = 0$$
 Poisson equation

Numerical method:
1. Discretize the derivative:

$$\frac{\partial^2 T}{\partial x^2} \approx \frac{T_{i+1} - 2T_i + T_{i-1}}{\Delta x^2}$$
 2nd_-order, centered scheme
$$x_i = i*\Delta x, \ i=0,1,2,...,N+1$$

$$x_i = i * \Delta x, \ i = 0, 1, 2, ..., N + 1$$

 $(N+1) * \Delta x = 1$

With boundary conditions: $T_0=T_a,\ T_N=T_b$

Programming example

Equation for T_i:
$$\frac{T_{i+1}-2T_i+T_{i-1}}{\Delta x^2}=-S_i$$

In matrix form: AT = b

- In 1-D, this is just a tridiagonal system of equations
- Easy to solve directly (with, say, DGTSV)

Jacobi iteration

- Basic idea: rewrite Ax=b as A₁x = A₂x + b
- Choose A₁ so that it is easy to invert, then solve iterative system:
- $A_1 x^{k+1} = A_2 x^k + b$
 - Requires guess, x⁰
- $\emph{Jacobi iteration}$: Choose \mathbf{A}_1 to be diagonal matrix (main diagonal of A):

$$\frac{T_{i+1}^{k-1} - 2T_i^k + T_{i-1}^{k-1}}{\Delta x^2} = -S_i$$

 $=rac{\Delta x^{2}}{2}S_{i}+rac{1}{2}\left(T_{i+1}^{k-1}+T_{i-1}^{k-1}
ight)$ Main algor

Main algorithm, easy to code

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Jacobi iteration in Fortran

- One Fortran trick: set variables to be dimension(0:N+1)
 - x(0)=0, x(N+1)=1, T(0)=a, T(N+1)=b
 - Then, easy to compute T_1 using:

$$T_i^k = \frac{\Delta x^2}{2} S_i + \frac{1}{2} \left(T_{i+1}^{k-1} + T_{i-1}^{k-1} \right)$$

Core part of code (see jacobi1s.f90):

do k1=1,kmax

Tnew(1:n) = S(1:n)*dx2f + 0.5d0*(T(0:n-1) + T(2:n+1)) !Jacobi

deltaT(k1) = maxval(abs(Tnew(1:n)-T(1:n))) !compute relative error

T(1:n)=Tnew(1:n) !update variable

if (deltaT(k1)<tol) exit !check convergence criterion
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Parallel Jacobi

Let's now parallelize the solver with OpenMP

- Look for loops that can be parallelized
- Look for vectorized operations that can be converted to loops that can be parallelized

Parallel:

let:
 dmax=0.d0
!Somp parallel do reduction(max:dmax)
do i1=1,n
 Tnew(i1) = S(i1)*dx2f + 0.5d0*(T(i1-1) + T(i1+1))
 dmax = max(dmax,abs(Tnew(i1)-T(i1)))
end do
!Somp end parallel do
deltaT(k1) = dmax

$$\boxed{ \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + S(x,y) = 0 \quad \text{Poisson equation} }$$

2-D (steady) heat equation

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + S(x,y) = 0 \quad \text{ Poisson equation}$$

Numerical method: 1. Discretize the derivative:

2-D (steady) heat equation

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + S(x,y) = 0 \quad \text{ Poisson equation}$$

Numerical method: 1. Discretize the derivative:

$$\begin{pmatrix} \frac{\partial^2 T}{\partial x^2} \end{pmatrix}_{i,j} \approx \frac{\overset{\cdot}{T_{i+1,j}} - 2T_{i,j} + T_{i-1,j}}{\Delta x^2}$$

$$\begin{pmatrix} \frac{\partial^2 T}{\partial y^2} \end{pmatrix}_{i,j} \approx \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\Delta y^2}$$

$$\Delta x = \Delta y = \Delta$$
 2nd-order, centered scheme

With boundary conditions: $T(x=0,y)=L(y),\ T(x=1,y)=R(y)$ $T(x,y=0) = D(x), \ T(x,y=1) = U(x)$

Numerical method:

Discretize the derivative:

$$\begin{pmatrix} \left(\frac{\partial^2 T}{\partial x^2}\right)_{i,j} \approx \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\Delta x^2} \\ \left(\frac{\partial^2 T}{\partial y^2}\right)_{i,j} \approx \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\Delta y^2} \\ \Delta x = \Delta y = \Delta$$
 2nd-order, centered scheme

Final equation:

$$\frac{T_{i+1,j} + T_{i,j+1} - 4T_{i,j} + T_{i-1,j} + T_{i,j-1}}{\Delta^2} = -S_i$$

$$x_i = i * \Delta, i = 0, 1, 2, ..., N + 1$$

 $y_j = j * \Delta, j = 0, 1, 2, ..., N + 1$

With b.c.'s imposed at i=0, i=N+1 and j=0, j=N+1

2-D (steady) heat equation

We now have system of n² linear equations, AT = B:

$$A = \begin{bmatrix} M & I & 0 & 0 & 0 & \dots & 0 \\ I & M & I & 0 & 0 & \dots & 0 \\ 0 & I & M & I & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & I & M & I \\ 0 & \dots & 0 & 0 & 0 & I & M \end{bmatrix} \bullet \text{ 1D: A was tridiagonal}$$

$$\bullet \text{ Mis a n x n tridiagonal matrix}$$

$$\bullet M \text{ is a n x n tridiagonal matrix}$$

$$M = \begin{bmatrix} -4 & 1 & 0 & 0 & 0 & \dots & 0 \\ 1 & -4 & 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & -4 & 1 & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 & -4 & 1 \\ 0 & \dots & 0 & 0 & 0 & 1 & -4 \end{bmatrix}$$

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2-D (steady) heat equation

We now have system of n^2 linear equations, AT = B:

$$T = \begin{bmatrix} T_{11} \\ T_{21} \\ \vdots \\ T_{n1} \\ T_{12} \\ \vdots \\ T_{n2} \\ \vdots \\ T_{1n} \\ \vdots \\ T_{nn} \\ \vdots \\ T_{1n} \\ \vdots \\ T_{nn} \end{bmatrix} \quad B = \begin{bmatrix} S_{11}\Delta^2 - T_{01} - T_{10} \\ S_{21}\Delta^2 - T_{20} \\ \vdots \\ S_{n1}\Delta^2 - T_{n0} - T_{n+1,1} \\ S_{12}\Delta^2 - T_{02} \\ \vdots \\ S_{n2}\Delta^2 - T_{n+1,2} \\ \vdots \\ S_{n1}\Delta^2 - T_{n+1,1} \\ \vdots \\ S_{n1}\Delta^2 - T_{n+1,1} \\ \vdots \\ S_{nn}\Delta^2 - T_{n+1,n} - T_{n,n+1} \end{bmatrix}$$

Boundary conditions appear in appropriate elements of $\ensuremath{\mathsf{B}}$

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We now have system of n² linear equations, AT = B

- Direct solution of n x n matrix: O(n³) operations (LU decomposition of A + back-substitution with B)
- We have n^2 x n^2 matrix, so on 100 x 100 grid, matrix is 1e4 x 1e4 and contains 1e8 elements (in double precision, that's 800 mb!)
- So, in 2D (and 3D) direct solution becomes expensive and memory-intensive

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2-D (steady) heat equation

We now have system of n^2 linear equations, AT = B

- Direct solution of n x n matrix: O(n³) operations (LU decomposition of A + back-substitution with B)
- We have n^2 x n^2 matrix, so on 100 x 100 grid, matrix is 1e4 x 1e4 and contains 1e8 elements (in double precision, that's 800 mb!)
- So, in 2D (and 3D) direct solution becomes expensive and memory-intensive
- But the matrix, A, is sparse, so iterative method will only need to store O(n²) elements (rather than n⁴)
- A good iterative method (SOR, conjugate gradient, multigrid) will be faster as well
- Jacobi iteration is inefficient, but a good starting point for looking at iterative methods

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2-D (steady) heat equation

Jacobi iteration:

$$T_{i,j}^{k+1} = \frac{\Delta^2}{4} S_i + \frac{1}{4} \left(T_{i+1,j}^k + T_{i,j+1}^k + T_{i-1,j}^k + T_{i,j-1}^k \right)$$

- New temperature = Source contribution + average of surrounding temperatures
- How do we convert 1D code → 2D?

Jacobi iteration:

$$T_{i,j}^{k+1} = \frac{\Delta^2}{4} S_i + \frac{1}{4} \left(T_{i+1,j}^k + T_{i,j+1}^k + T_{i-1,j}^k + T_{i,j-1}^k \right)$$

New temperature = Source contribution + average of surrounding temperatures

- How do we convert 1D code → 2D?
- Dlan
 - 1. Need 2D variables: x, y, S, T
- 2. Intialize 2D field and apply boundary conditions
- 3. During iterations, average in two dimensions rather than one

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2-D (steady) heat equation

Final problem: Use Jacobi iteration to find T(x,y) on unit square with fixed temperature on boundaries and prescribed source, S(x,y)

T=U

T=L

T(x,y)=?

T=D

T=R

Jacobi iteration in Fortran

1D:

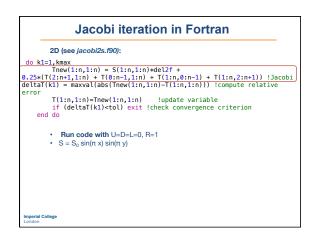
do k1=1,kmax

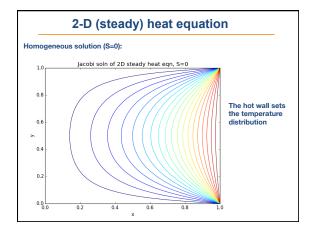
 $deltaT(k1) = maxval(abs(Tnew(1:n)-T(1:n))) \ ! compute \ relative \ error \\$

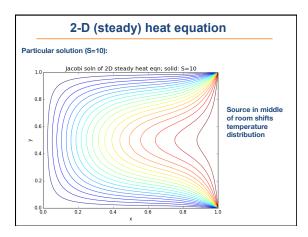
T(1:n)=Tnew(1:n) !update variable

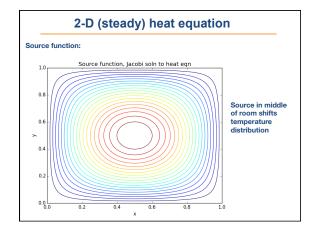
if (deltaT(k1)<tol) exit !check convergence criterion

end do









Parallelize with OpenMP:

- Essentially the same as in 1D
- Parallel loop iterates across rows of A
- Reduction of deltaT to check for convergence

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2-D (steady) heat equation

dmax=0.d0
!\$omp parallel do reduction(max:dmax)
do i1=1,n
 Tnew(i1) = \$\(\)(i1) * dx2f + 0.5d0*(T(i1-1) + T(i1+1))\)
 dmax = max(dmax,abs(Tnew(i1)-T(i1)))
end do
!\$omp end parallel do
deltaT(k1) = dmax
if (deltaT(k1) < tol) exit !check convergence criterion
!\$omp parallel do
do i1=1,n
 T(i1) = Tnew(i1)
end do
!\$omp end parallel do</pre>

2-D (steady) heat equation 2D (see jacobi2s_omp.f90):

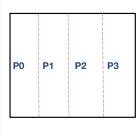
2-D (steady) heat equation

- Moving from 1D serial to 2D parallel (with OpenMP) is straightforward
- Much more difficult if solving equations directly
- What about MPI?

2-D (steady) heat equation

What is best domain decomposition?

If we have four processors, can try:



2-D (steady) heat equation What is best domain decomposition? If we have four processors, can try: Then, parallelization is essentially same as differentiation example: · Loop across rows P0 **P1 P2 P3** At "boundary" rows, send/recv data needed to compute second derivative Reduce max(|deltaT|) 2-D (steady) heat equation What is best domain decomposition? If we have four processors, can try: But is the 1D decomposition the best? · Want to minimize communication P0 P1 **P2 P3** M "layers": of a n x n grid:(M-1)*n boundary points 2-D (steady) heat equation What is best domain decomposition? If we have four processors, can also try: But is the 1D decomposition the best? P0 **P1** · Want to minimize communication M "boxes": of a n x n grid: Each interior box has 2n/sqrt(M) boundary points **P2 P3** Total: 2n*(sqrt(M)-1) boundary points

2₋1	D (steady)	heat equation		
What is best doma				
If we have four pro				
no nato toa. pro		7		
P0	P1	But is the 1D decomposition the best? Want to minimize communication		
P2	P3	M "boxes": of a n x n grid: Each box has 2n/sqrt(M) boundary points		
		Total: 2n*(sqrt(M) -1) boundary points		
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2-1	D (steady)	heat equation		
MPI provides tools for creating and managing complex "topologies"				
For example, to	create a 4 x 3 "grid	" of processes:		
call MPI_cart_create(MPI_COMM_WORLD, ndirns, dirns, periods, reorder, new_comm, ierr)				
with: ndims = 2, dim	n: ndims = 2, dims = (/4,3/), periods = (/.false.,/.true/), reorder = .false.			
Here, periods set	Here, periods sets periodic boundary conditions along the three columns			
			-	
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2-1	D (steady)	heat equation		
		I managing complex "topologies"		
For example, to				
call MPI_Cart_c	call MPI_Cart_create(MPI_COMM_WORLD, ndims, dims, periods, reorder, new_comm, ierr)			
with: ndims = 2, dim	ns = (/4,3/), periods =	= (/.false.,/.true/), reorder = .false.		
Here, periods set	ts periodic bounda	ry conditions along the three columns		
Other useful con MPI_Cart_co	nmands with the no			
MPI_Cart_rank: given (i,j), provides id (0, 1, 2,, numprocs)				
horizontal or ver	tical direction	es id of neighboring processes in		

2-D (steady) heat equation		
Most useful: MPI_Cart_shift: provides id of neighboring processes in horizontal or vertical direction Use to set up send/recv sequences needed for exchanging boundary		
data. How to decide on process grid dimensions?		
MPI_Dims_create: dim 0		
Given number number of processes and dimensions, outputs process grid (0,0) (1,0) (3,0) (3,0)		
Dimensions (4,3 in picture →) • e.g. 400 x 300 grid points:		
4 x 3 process grid with 100 x 100 points on each grid		
2 (0,2) (1,2) (3,2) (3,2)		
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