Machine Learning CMPT 726

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2025-09-17

Linear Algebra and Calculus Review (cont'd)

Convex function:

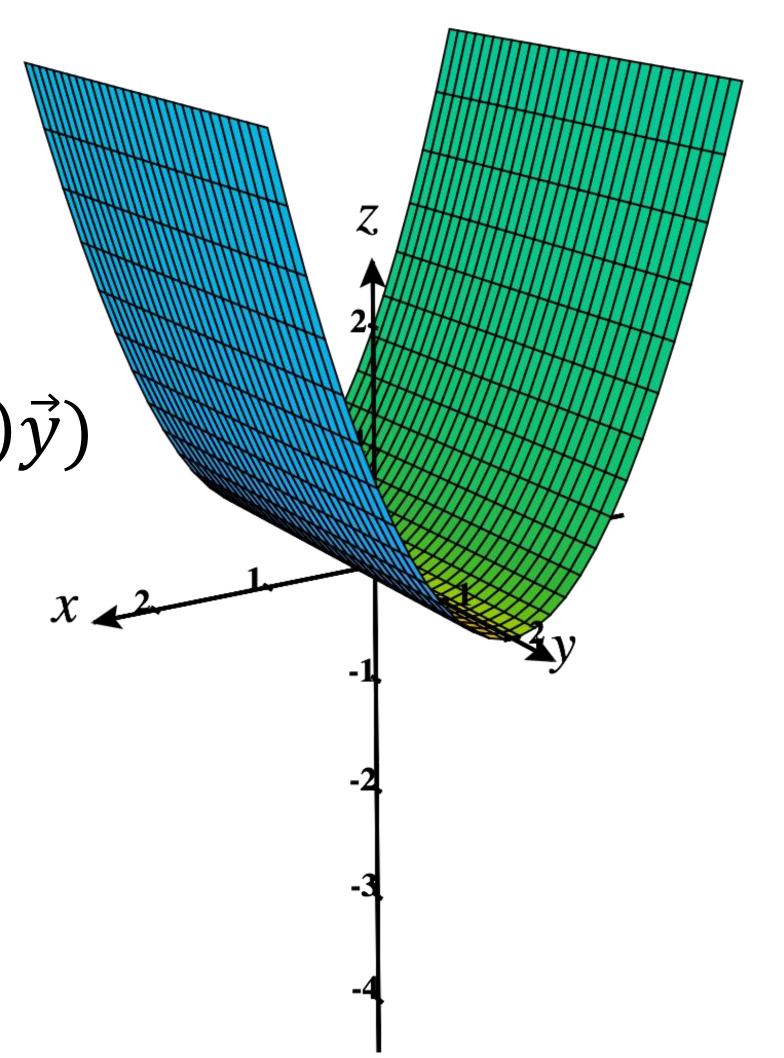
A line segment between **any** two points on the surface lies **on or above** the surface:

$$\alpha f(\vec{x}) + (1 - \alpha)f(\vec{y}) \ge f(\alpha \vec{x} + (1 - \alpha)\vec{y})$$

where $0 \le \alpha \le 1$

Or equivalently: Hessian of function is **positive semi-definite** everywhere, e.g.:

$$f(\vec{x}) = \vec{x}^{\mathsf{T}} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \vec{x} = x_1^2$$



Strictly convex function:

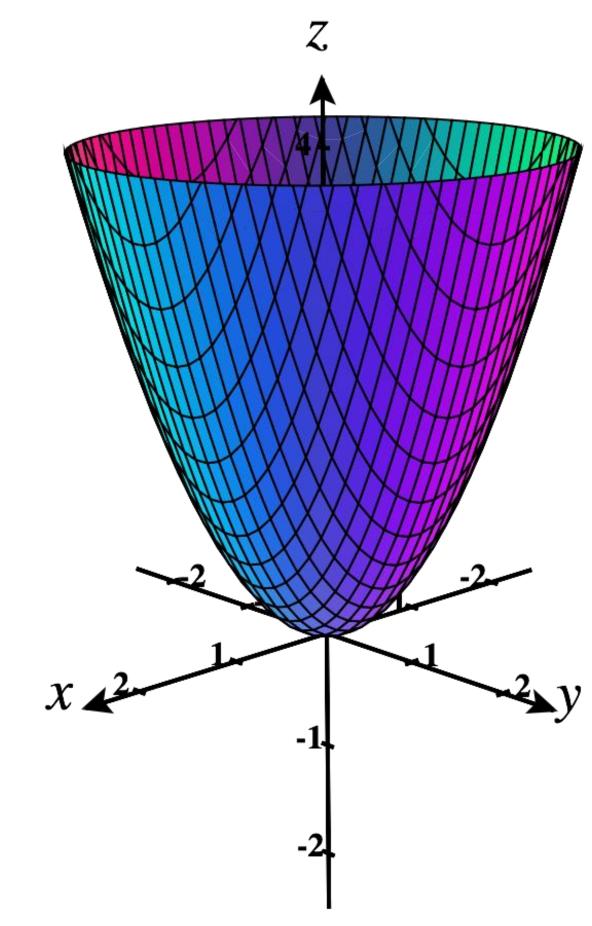
A line segment between **any** two points on the surface lies **above** the surface:

$$\alpha f(\vec{x}) + (1 - \alpha)f(\vec{y}) > f(\alpha \vec{x} + (1 - \alpha)\vec{y})$$

where $0 < \alpha < 1$

If the Hessian is positive definite everywhere, e.g.:

$$f(\vec{x}) = \vec{x}^{\mathsf{T}} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \vec{x} = x_1^2 + x_2^2$$



Then the function is strictly convex (but not the other way around!)

Concave function:

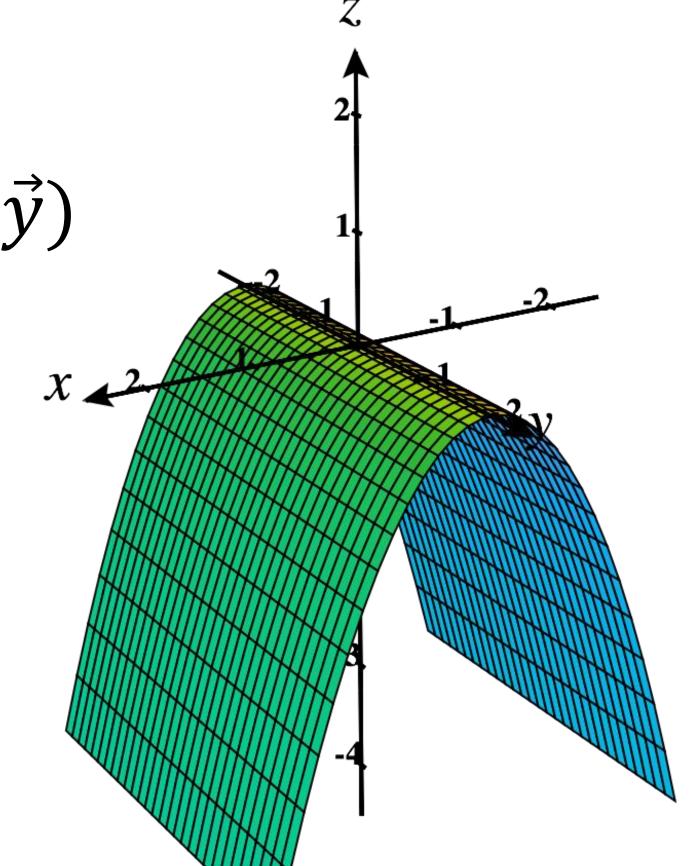
A line segment between **any** two points on the surface lies **on or below** the surface:

$$\alpha f(\vec{x}) + (1 - \alpha)f(\vec{y}) \le f(\alpha \vec{x} + (1 - \alpha)\vec{y})$$

where $0 \le \alpha \le 1$

Or equivalently: Hessian of function is **negative semi-definite** everywhere, e.g.:

$$f(\vec{x}) = \vec{x}^{\mathsf{T}} \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \vec{x} = -x_1^2$$



Strictly concave function:

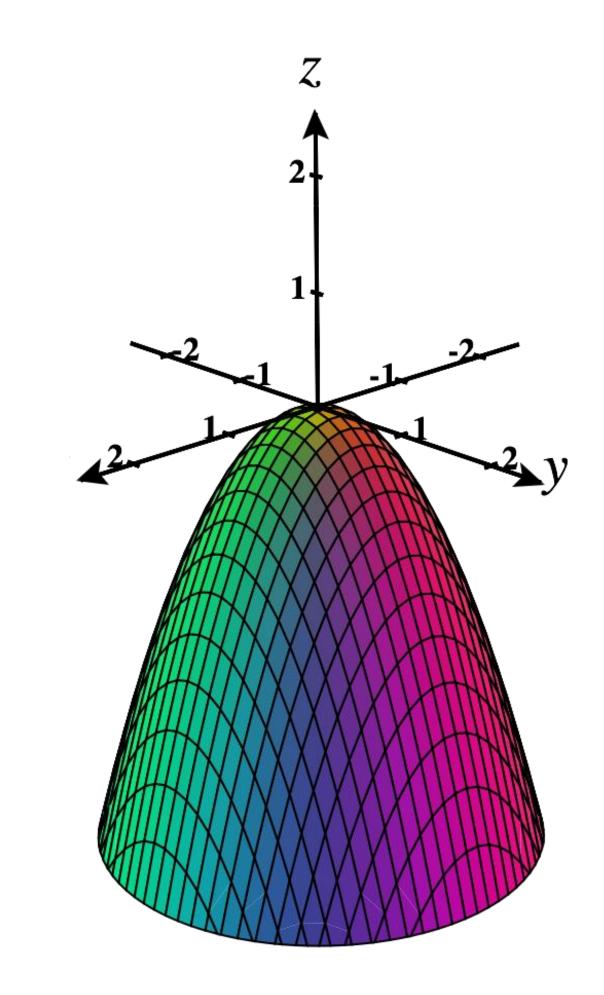
A line segment between **any** two points on the surface lies **below** the surface:

$$\alpha f(\vec{x}) + (1 - \alpha)f(\vec{y}) < f(\alpha \vec{x} + (1 - \alpha)\vec{y})$$

where $0 < \alpha < 1$

If the Hessian is negative definite everywhere, e.g.:

$$f(\vec{x}) = \vec{x}^{\mathsf{T}} \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \vec{x} = -x_1^2 - x_2^2$$



Then the function is strictly concave (but not the other way around!)

Jensen's Inequality

Definition of convex functions:

$$\alpha f(\vec{x}) + (1 - \alpha)f(\vec{y}) \ge f(\alpha \vec{x} + (1 - \alpha)\vec{y})$$
, where $0 \le \alpha \le 1$

Jensen's inequality generalizes this to convex combinations of many points:

$$\sum_{i=1}^{n} \alpha_i f(\vec{x}_i) \ge f\left(\sum_{i=1}^{n} \alpha_i \vec{x}_i\right), \text{ where } \alpha_i \ge 0 \ \forall i, \text{ and } \sum_{i=1}^{n} \alpha_i = 1$$

Jensen's Inequality

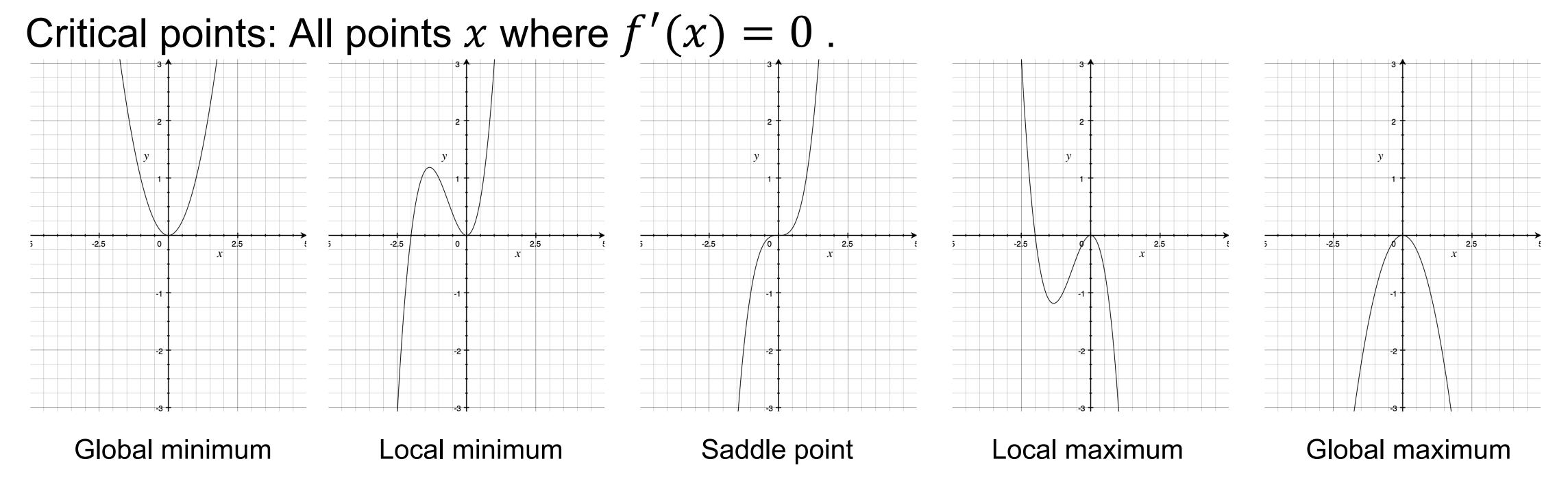
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Consider a univariate function $f: \mathbb{R} \to \mathbb{R}$ that is everywhere twice differentiable. How can we find the points where f is minimized or maximized?



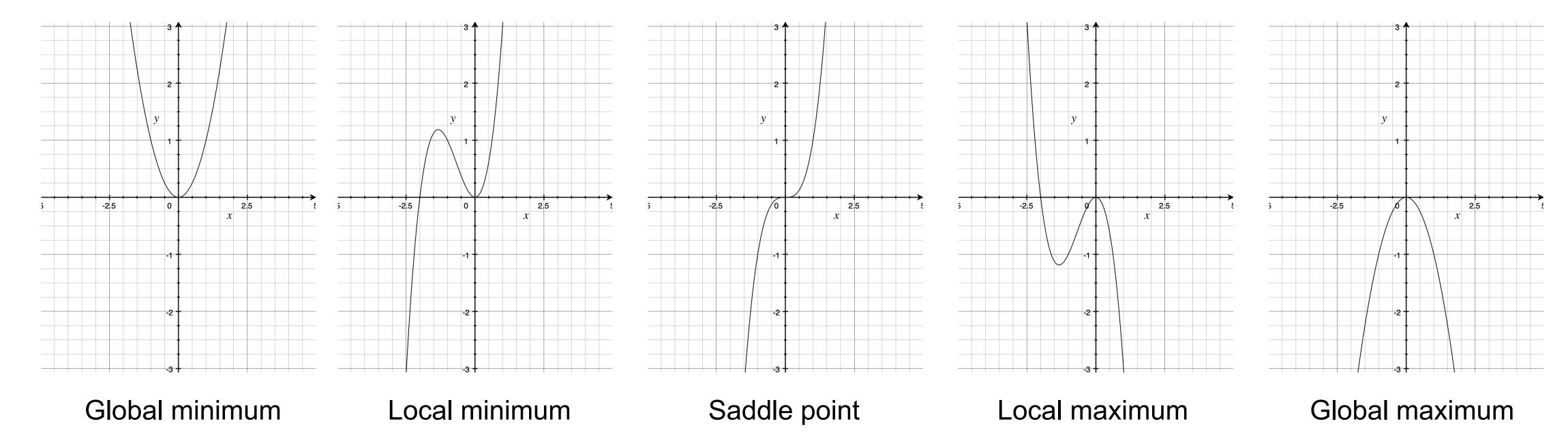
To differentiate these cases, we can check the second derivative at the critical points.

If f''(x) > 0, local/global minimum

If f''(x) < 0, local/global maximum

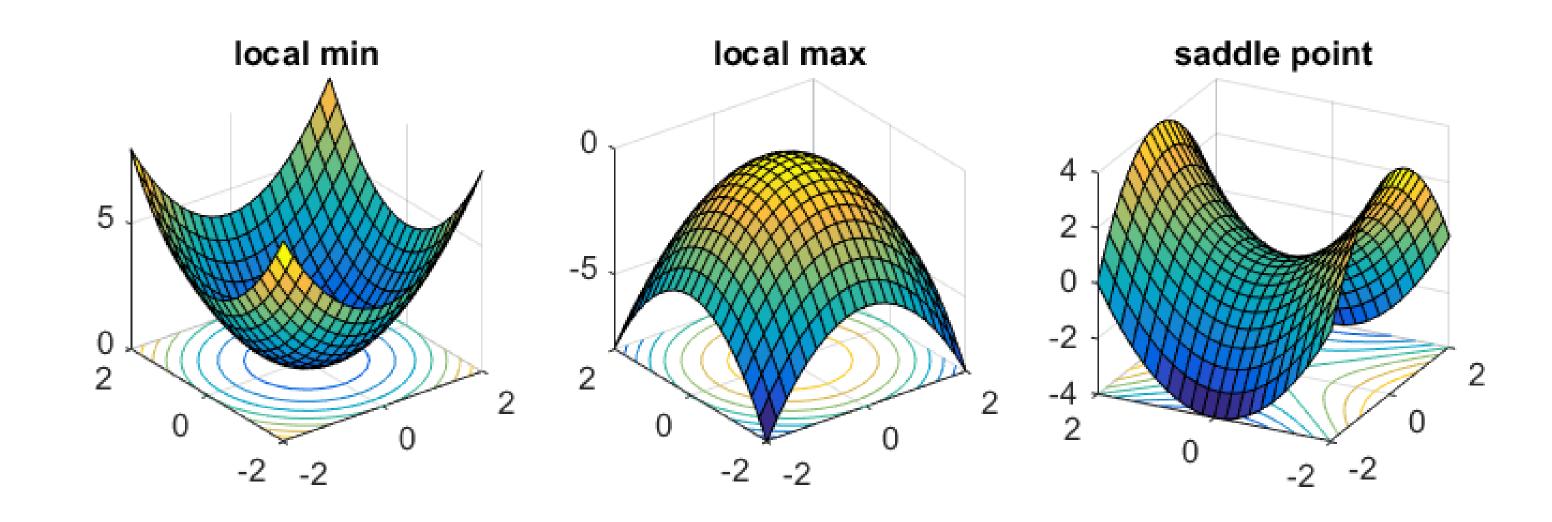
If f''(x) = 0, could be a local/global minimum, a local/global maximum, or a saddle point

Hard to distinguish local and global minima/maxima in general



Consider a multivariate function $f: \mathbb{R}^n \to \mathbb{R}$ that is everywhere twice differentiable. How can we find the points where f is minimized or maximized?

Critical points: All points \vec{x} where $\frac{\partial f}{\partial \vec{x}}(\vec{x}) = \vec{0}$.



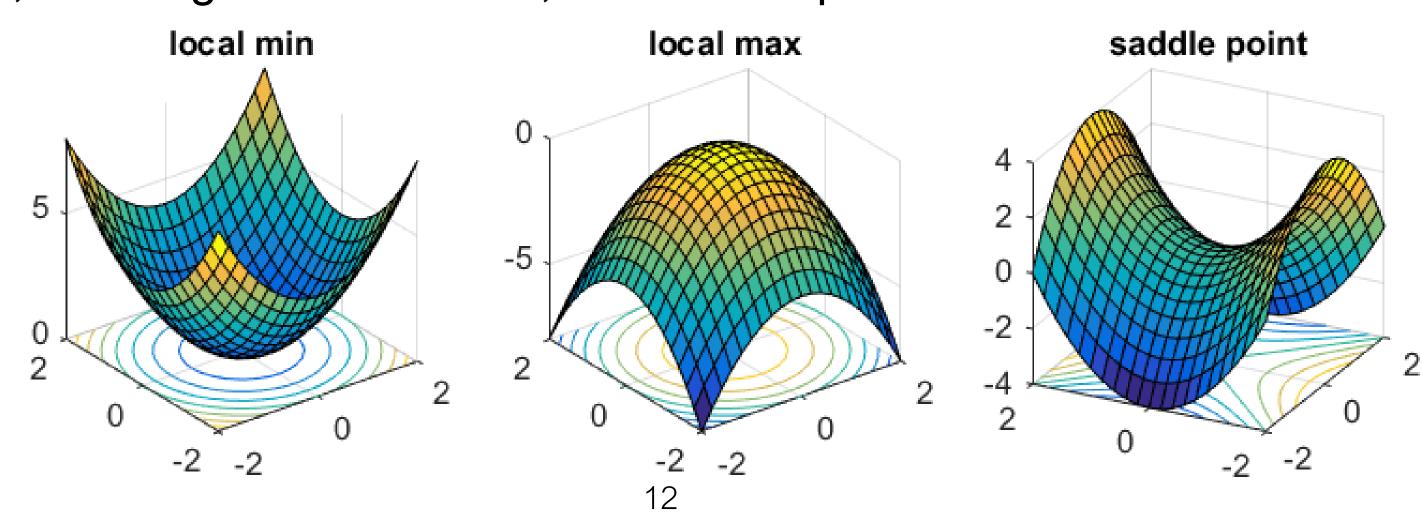
To differentiate these cases, we can check the Hessian evaluated at the critical points.

If
$$\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^T}(\vec{x}) > 0$$
 (positive definite), local/global minimum

If
$$\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^T}(\vec{x}) < 0$$
 (negative definite), local/global maximum

If
$$\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^T}(\vec{x})$$
 is indefinite, saddle point

If $\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^{\mathsf{T}}}(\vec{x}) \geq 0$ (positive semi-definite) or $\frac{\partial^2 f}{\partial \vec{x} \partial \vec{x}^{\mathsf{T}}} f(\vec{x}) \leq 0$ (negative semi-definite), could be a local/global minimum, a local/global maximum, or a saddle point



Global Optimality and Convexity/Concavity

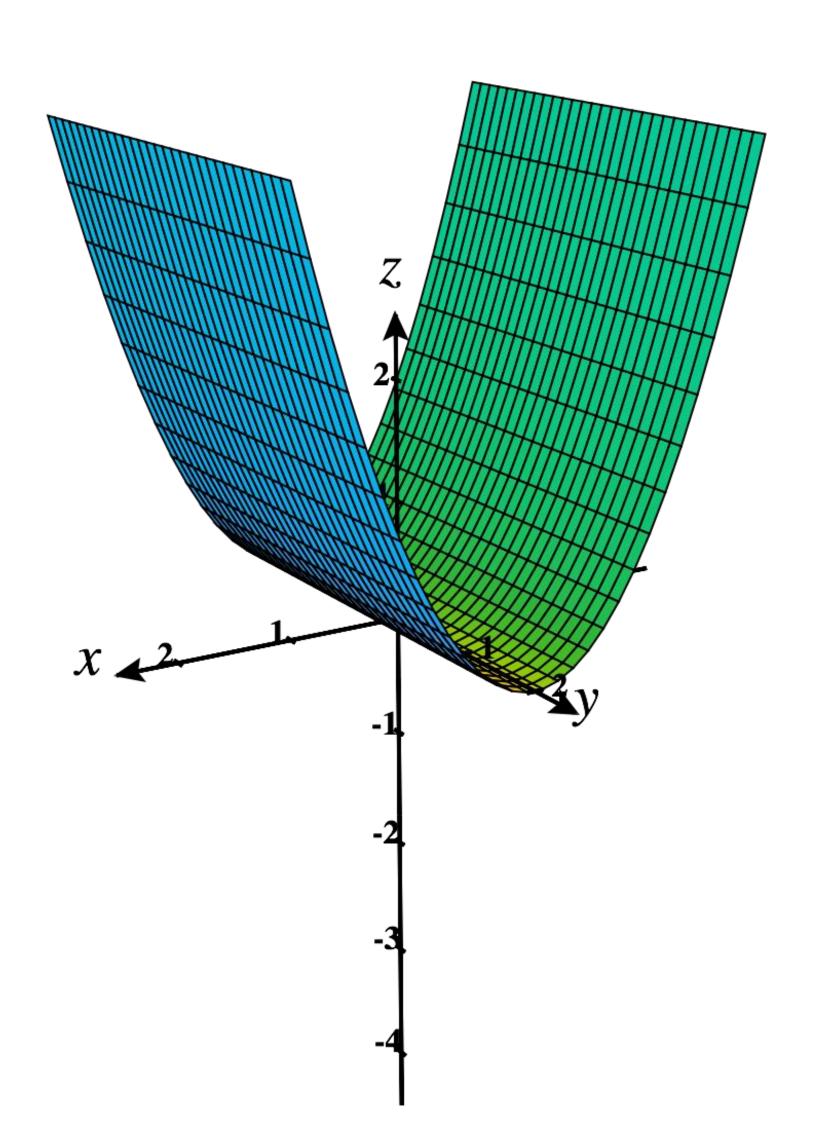
Recall: it is hard to distinguish local optima (that are not global optima) from global optima.

Convexity/concavity is a sufficient (but not necessary) condition for every local optimum to be a global optimum.

In a **convex** function:

Every critical point is a local minimum.

Every local minimum is a global minimum.



Global Optimality and Convexity/Concavity

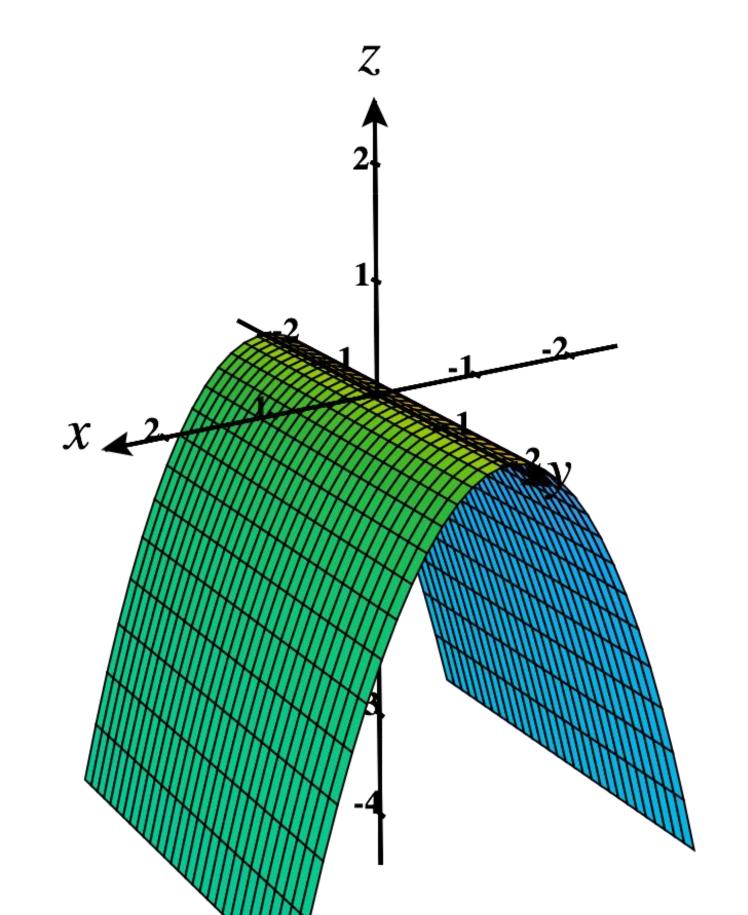
Recall: it is hard to distinguish local optima (that are not global optima) from global optima.

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In a **concave** function:

Every critical point is a local maximum.

Every local maximum is a global maximum.

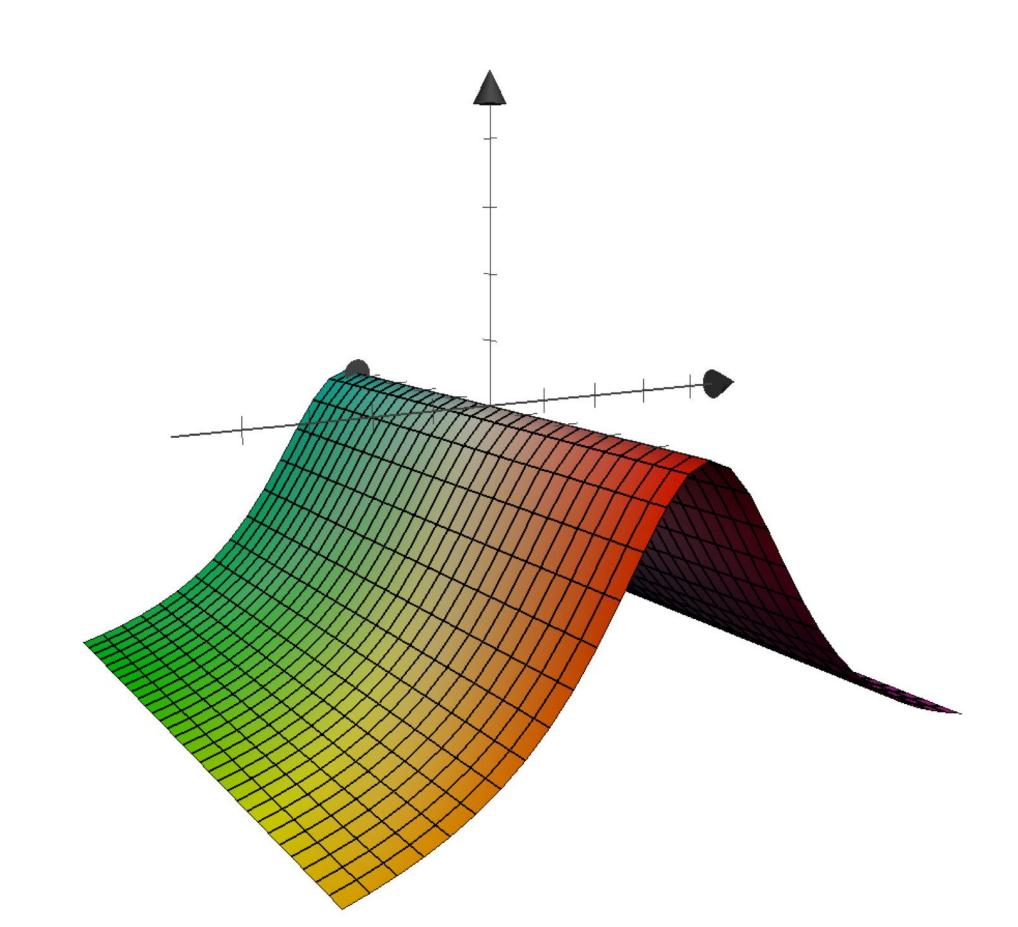


Global Optimality and Convexity/Concavity

Recall: it is hard to distinguish local optima (that are not global optima) from global optima.

Convexity/concavity is a sufficient (but not necessary) condition for every local optimum to be a global optimum.

Note: There are non-concave functions where every local maximum is a global maximum.



Example

- $f(x) = x^4$: $f''(0) = 0 \Rightarrow$ positive semidefinite Hessian
 - 0 is a local minimum
 - (Hessian is also negative semidefinite)
- $f(x) = -x^4$: $f''(0) = 0 \Rightarrow$ negative semidefinite Hessian
 - 0 is a local maximum
 - (Hessian is also positive semidefinite)

Lipschitz Continuity

A function $f: \mathbb{R}^n \to \mathbb{R}$ is L-Lipschitz if for all $\vec{x}_1, \vec{x}_2,$ $|f(\vec{x}_1) - f(\vec{x}_2)| \le L||\vec{x}_1 - \vec{x}_2||_2$

Intuitively, an L-Lipschitz function cannot grow too quickly.

An everywhere differentiable function is L-Lipschitz if and only if $\left\| \frac{\partial f}{\partial \vec{x}} (\vec{x}) \right\| \leq L$

