

# Lab4, 70

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**Variant:** *70*

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```
[1]: import numpy as np
import networkx as nx
import matplotlib.pyplot as plt

from queue import Queue
```

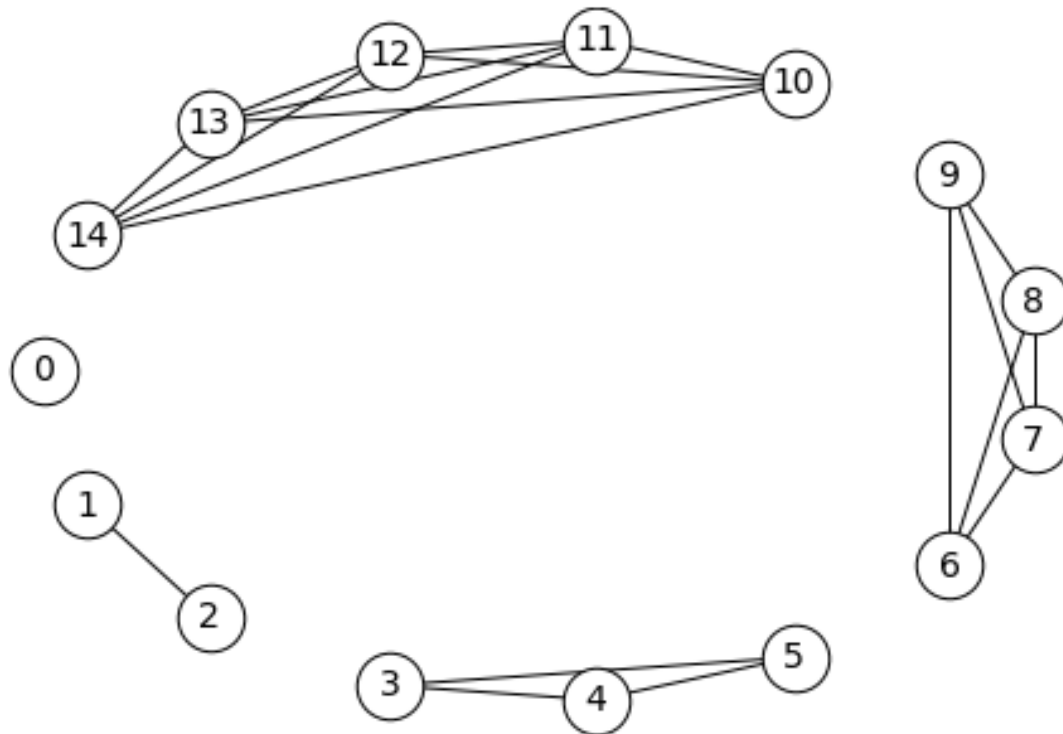
```
[2]: FILE_PATH = "./graph.txt"

N = 15
V = 20
K = 5

SIZES = {'node_size': 2000, 'font_size': 25, 'width': 3}
BASE_COLORS = {'font_color': 'black', 'node_color': 'white', 'with_labels': 1
               ↪ True}
BLACK = {'edgecolors': 'black', 'edge_color': 'black'} | BASE_COLORS
```

```
[3]: g = nx.read_adjlist(FILE_PATH, nodetype=int, create_using=nx.Graph)
```

```
[4]: nx.draw_shell(g, **BLACK, node_size=700, font_size=14)
```



```
[5]: def circle_n(n, start_index=0, radius=1, x_shift=0, y_shift=0):
    """
    Build circle positions for graph

    Parameters
    n : int
        Number of nodes

    start_index : int
        Number of first numerical label

    radius : float
        Circle radius

    x_shift : float
        Shift the figure along the x coordinate

    y_shift : float
        Shift the figure along the y coordinate

    Returns
    dict
```

*Dictionary with labels as keys and pairs of x and y coordinates as values*

```

"""
fi = 2 * np.pi / n
start_rad = np.pi*0.5

return {
    start_index+i : np.array((
        np.cos(-i*fi + start_rad) + x_shift,
        np.sin(-i*fi + start_rad) + y_shift)
    ) * radius
    for i in range(n)
}

def completed_components_pos(n, k, components_distance, radius=1):
    res_pos = dict()
    for i in range(k):
        v_in_comp = i+1
        x_shift = (radius*2+components_distance)*i

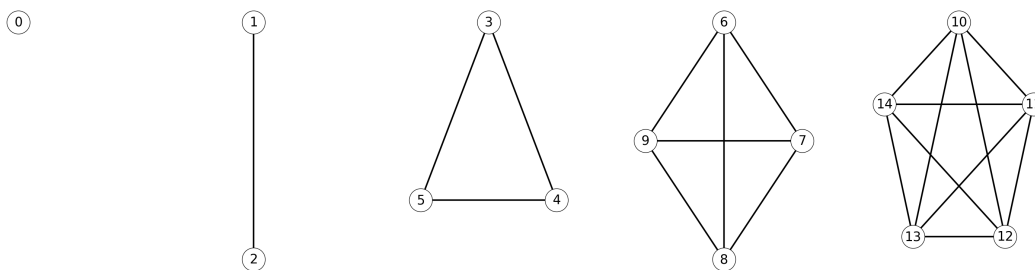
        res_pos |= circle_n(i+1, start_index=v_in_comp*(v_in_comp-1) // 2,
                             radius=radius, x_shift=x_shift)
    return res_pos

```

```

[6]: plt.figure(figsize=(30, 7), dpi=100)
     nx.draw(g, pos=completed_components_pos(N, K, 1), **(BLACK|SIZES))

```



```

[7]: for component_nodes in nx.connected_components(g):
     subgraph = g.subgraph(component_nodes)
     eccentricities = nx.eccentricity(subgraph)
     n_nodes = subgraph.number_of_nodes()
     start_index = n_nodes * (n_nodes-1) // 2

     plt.figure(figsize=(3, 3), dpi=100)

```

```

    nx.draw(subgraph, pos=circle_n(n_nodes, start_index=start_index), **BLACK,
↪node_size=400, font_size=12)
    plt.show()

    print("Count of nodes:", subgraph.number_of_nodes())
    print("Count of edges:", subgraph.number_of_edges())
    print("Node", "Degree", "Eccentricity", sep="\t")

    for node in component_nodes:
        print(node, end="\t")
        print(g.degree(node), end="\t")
        print(eccentricities[node])

    print()
    print()

```

①

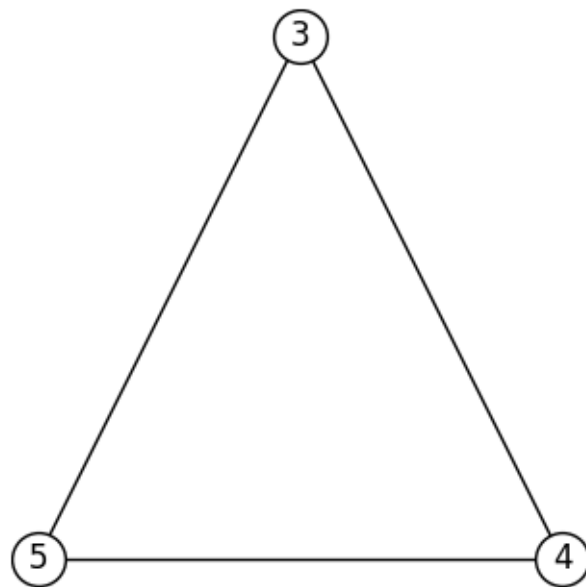
```

Count of nodes: 1
Count of edges: 0
Node    Degree  Eccentricity
0       0       0

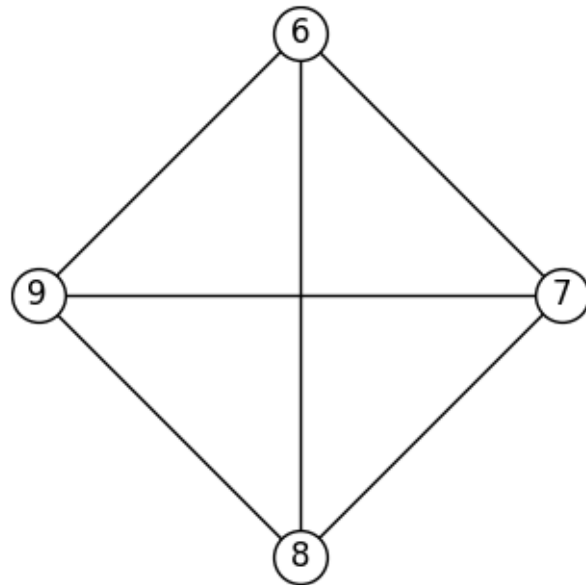
```



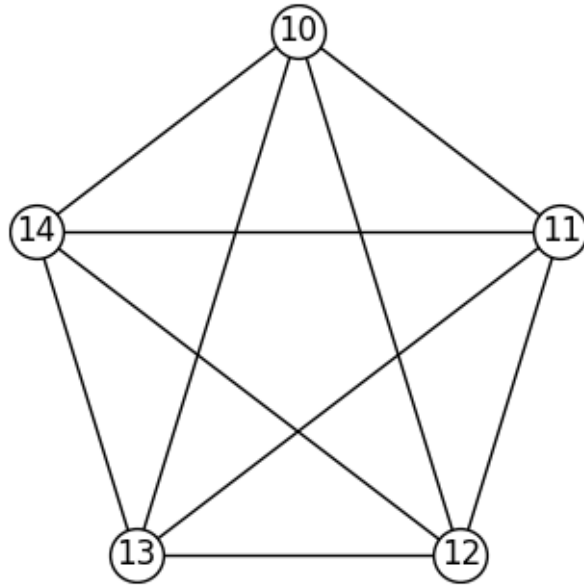
Count of nodes: 2  
Count of edges: 1  
Node    Degree    Eccentricity  
1       1       1  
2       1       1



Count of nodes: 3  
 Count of edges: 3  
 Node      Degree    Eccentricity  
 3          2          1  
 4          2          1  
 5          2          1



Count of nodes: 4  
 Count of edges: 6  
 Node      Degree    Eccentricity  
 8          3          1  
 9          3          1  
 6          3          1  
 7          3          1



Count of nodes: 5  
 Count of edges: 10

Node	Degree	Eccentricity
10	4	1
11	4	1
12	4	1
13	4	1
14	4	1

```
[8]: def _get_key_by_best_result(dictionary, estimator=lambda x: x):
      keys = list(dictionary.keys())

      best_key = keys[0]
      best_res = estimator(dictionary[best_key])

      for i in range(1, len(keys)):
          key = keys[i]

          if estimator(dictionary[key]) > best_res:
              best_key = key
              best_res = estimator(dictionary[key])
      return best_key

def bfs(graph, start_node):
    """
```

*Find paths from selected vertex to all other*

*Parameters*

*graph : networkx.Graph*

*Connected graph in which the search will be performed.*

*start\_node : int*

*Label of starting node*

*Returns*

*dict*

*Dictionary with vertex labels as keys and chain of vertices as path\_*

*→ from start node to other*

*"""*

```
nodes = dict.fromkeys(graph.nodes, None)
```

```
nodes[start_node] = [start_node]
```

```
queue = []
```

```
visited = []
```

```
queue.append(start_node)
```

```
visited.append(start_node)
```

```
while queue:
```

```
    curr_node = queue.pop(0)
```

```
    for neighbor_node in graph.neighbors(curr_node):
```

```
        if neighbor_node not in visited:
```

```
            nodes[neighbor_node] = nodes[curr_node] + [neighbor_node]
```

```
            visited.append(neighbor_node)
```

```
            queue.append(neighbor_node)
```

```
return nodes
```

```
def diameter(graph):
```

```
    """
```

*Find the diameter of connected graph*

*Parameters*

*graph : networkx.Graph*

*Connected graph in which the search will be performed.*

*Returns:*

*list*

*Chain of connected nodes.*

```
    """
```

```
    eccentricities = nx.eccentricity(graph)
```



```

start_node = _get_key_by_best_result(eccentricities, lambda x: x)
paths = bfs(graph, start_node)
path_key = _get_key_by_best_result(paths, lambda x: len(x))
return paths[path_key]

def nodes_to_chain_edges(nodes):
    """
    Convert list of connected nodes to list of edges

    Parameters
    nodes : list
        List of connected nodes

    Returns
    list
        List of edges
    """
    edges = []
    for i in range(len(nodes)-1):
        edges.append((nodes[i], nodes[i+1]))
    return edges

```

```

[9]: diameter_nodes = []
diameter_edges = []

for component_nodes in nx.connected_components(g):
    subgraph = g.subgraph(component_nodes)
    current_diameter_nodes = diameter(subgraph)
    diameter_nodes += current_diameter_nodes
    diameter_edges += nodes_to_chain_edges(current_diameter_nodes)

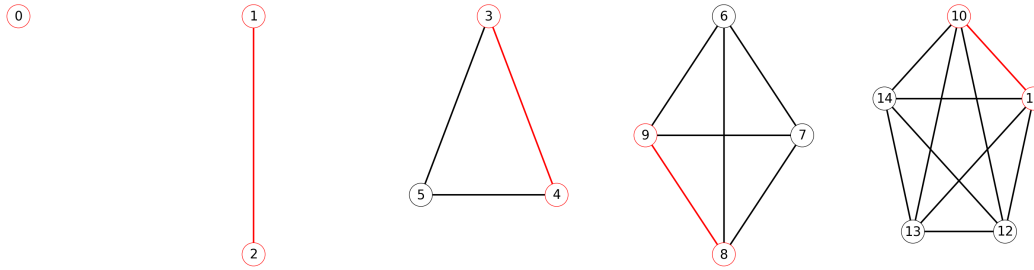
diam_border_colors = ["red" if node in diameter_nodes else "black" for node in
    ↪g.nodes]
diam_edge_colors = ["red" if (u, v) in diameter_edges or (v, u) in
    ↪diameter_edges else "black"
    for u, v in g.edges]

```

```

[10]: plt.figure(figsize=(30, 7), dpi=100)
nx.draw(g, pos=completed_components_pos(N, K, 1), **(BASE_COLORS|SIZES),
    edgecolors=diam_border_colors, edge_color=diam_edge_colors)

```



```
[11]: tree_edges = set()

for component_nodes in nx.connected_components(g):
    subgraph = g.subgraph(component_nodes)
    start_node = list(subgraph.nodes)[0]
    current_tree = nx.bfs_tree(subgraph, source=start_node)
    current_tree_edges = current_tree.edges()
    tree_edges.update(current_tree_edges)

tree_edge_colors = ["red" if (u, v) in tree_edges or (v, u) in tree_edges else
                    ↪"black"
                    for u, v in g.edges]
```

```
[12]: plt.figure(figsize=(30, 7), dpi=100)
nx.draw(g, pos=completed_components_pos(N, K, 1), **(BASE_COLORS|SIZES),
        edgecolors="black", edge_color=tree_edge_colors)
```

