Question 1. Simulation of a multi-compartment Hodgkin-Huxley model.

1.1 The Hodgkin-Huxley model for an active neurite with input current $I_e(j,t)$ for a single cylindrical compartment j is given by equations 1-12.

$$V' = \frac{V}{mV} \tag{1}$$

$$I_{e}(t) = C_{m} \frac{\mathrm{d}V_{j}'}{\mathrm{d}t} + g_{L}(V_{j}' - E_{L}) + g_{\mathrm{Na},j}(V_{j}' - E_{\mathrm{Na}}) + g_{\mathrm{K},j}(V_{j}' - E_{\mathrm{K}}) + g_{\mathrm{ax}}(V_{j}' - V_{j-1}') + g_{\mathrm{ax}}(V_{j}' - V_{j+1}')$$
 (2)

$$g_{Na,j} = \bar{g}_{Na} m_j^3 h_j, \quad g_{K,j} = \bar{g}_K n_j^4$$
 (3)

Sodium channels (not writing indices *j*):

$$\frac{\mathrm{d}\,m}{\mathrm{d}\,t} = \alpha_m \left(1 - m\right) - \beta_m m \tag{4}$$

$$\alpha_{m} = \begin{cases} 0.1 \frac{V' - 25}{1 - \exp\left(-\frac{V' - 25}{10}\right)} & V \neq 25mV \\ 1 & V = 25mV \end{cases}$$
 (5)

$$\beta_m = 4 \exp\left(-\frac{V'}{18}\right) \tag{6}$$

$$\frac{\mathrm{d}\,h}{\mathrm{d}\,t} = \alpha_h (1 - h) - \beta_h h \tag{7}$$

$$\alpha_h = 0.07 \exp\left(-\frac{V'}{20}\right) \tag{8}$$

$$\beta_h = \frac{1}{1 + \exp\left(-\frac{V' - 30}{10}\right)} \tag{9}$$

Potassium channel (not writing indices *j*):

$$\frac{\mathrm{d}\,n}{\mathrm{d}\,t} = \alpha_n (1-n) - \beta_n n \tag{10}$$

$$\alpha_n = \begin{cases} 0.01 \frac{V' - 10}{1 - \exp\left(-\frac{V' - 10}{10}\right)} & V \neq 10mV \\ 0.1 & V = 10mV \end{cases}$$
 (11)

$$\beta_n = 0.125 \exp\left(-\frac{V'}{80}\right) \tag{12}$$

The electrical and geometrical properties are

- $C_m = 1 \,\mu\text{F}$, membrane capacitance
- $E_{Na} = 115 \,\mathrm{mV}$, sodium equilibrium potential
- $E_K = -12 \,\mathrm{mV}$, potassium equilibrium potential
- $E_L = 10.6 \,\mathrm{mV}$, leak equilibrium potential
- $V(t=0) = 0 \,\mathrm{mV}$, initial (and equilibrium) membrane potential
- $\bar{g}_{Na} = 120 \,\mathrm{mS}$, maximum sodium channel conductance
- $\bar{g}_K = 36 \,\mathrm{mS}$, maximum potassium channel conductance

- $g_L = 0.3 \,\mathrm{mS}$, leak conductance
- $g_{ax} = 0.5 \,\mathrm{mS}$, axial conductance
- N = 100, number of compartments

Given the Hodgkin-Huxley model described above, we approximate the DEQs using the Forward Euler method and derive an equation for V(j,t) for an arbitrary compartment j. We assume that the first compartment is terminated as a 'sealed end' and the last compartment is terminated as a 'killed end', as shown in Figure 1.

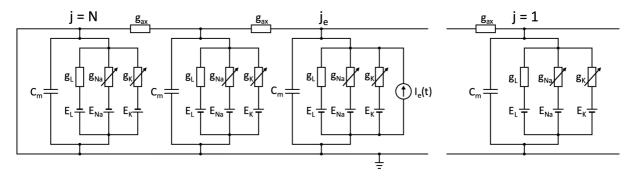


Figure 1: Circuit diagram of a multi-compartment Hodgkin-Huxley model. Compartment 1 is terminated as a 'sealed end' and compartment N is terminated as a 'killed end'. Note that the connection between compartment 1 and compartment j_e is not shown for simplicity.

The approximated DEQ for voltage response of compartment j into which current is injected looks as shown below

$$V'_{j}(t + \Delta t) = V'_{j}(t) + \frac{\Delta t}{C_{m}} \left(I_{e}(t) + g_{L} \left(E_{L} - V'_{j}(t) \right) + \bar{g}_{Na} m_{j}^{3}(t) h_{j}(t) \left(E_{Na} - V'_{j}(t) \right) + \bar{g}_{K} n_{j}^{4}(t) \left(E_{K} - V'_{j}(t) \right) + g_{ax} \left(V'_{j-1}(t) - V'_{j}(t) \right) + g_{ax} \left(V'_{j+1}(t) - V'_{j}(t) \right) \right)$$

Following Homework 4, voltage response for compartment i where 0 < i < j is

$$V_{i}'(t + \Delta t) = V_{i}'(t) + \frac{\Delta t}{C_{m}} \left(g_{L} \left(E_{L} - V_{i}'(t) \right) + \bar{g}_{Na} m_{i}^{3}(t) h_{i}(t) \left(E_{Na} - V_{i}'(t) \right) + \bar{g}_{K} n_{i}^{4}(t) \left(E_{K} - V_{i}'(t) \right) + g_{ax} \left(V_{i-1}'(t) - V_{i}'(t) \right) + g_{ax} \left(V_{i+1}'(t) - V_{i}'(t) \right) \right)$$

As for compartment i where j < i < N, we have

$$V'_{i}(t + \Delta t) = V'_{i}(t) + \frac{\Delta t}{C_{m}} \left(g_{L} \left(E_{L} - V'_{i}(t) \right) + \bar{g}_{Na} m_{i}^{3}(t) h_{i}(t) \left(E_{Na} - V'_{i}(t) \right) + \bar{g}_{K} n_{i}^{4}(t) \left(E_{K} - V'_{i}(t) \right) + g_{ax} \left(V'_{i+1}(t) - V'_{i}(t) \right) + g_{ax} \left(V'_{i-1}(t) - V'_{i}(t) \right) \right)$$

As regards the termini, membrane potential for compartment j = N is set to 0 and for compartment j = 1 we assume no axial current flowing out, and hence all membrane potential difference is due to current flowing through the membrane

$$V_1'(t + \Delta t) = V_1'(t) + \frac{\Delta t}{C_m} \left(+ g_L \left(E_L - V_1'(t) \right) + \bar{g}_{Na} m_1^3(t) h_1(t) \left(E_{Na} - V_1'(t) \right) + \bar{g}_K n_1^4(t) \left(E_K - V_1'(t) \right) + g_{ax} \left(V_2'(t) - V_1'(t) \right) \right)$$

For the approximations of m, h, n gating variables please refer to Homework 4.

1.2 Now, we turn on simulating the above model for an input current $I_e(j,t)$

$$I_e(j,t) = \begin{cases} 0, & (t < t_e) \lor (t_s \leqslant t) \lor (j \neq j_e) \\ I_0, & (t_e \leqslant t < t_s) \land (j = j_e) \end{cases}$$

with $j_e=14$, $t_e=60\,\mathrm{ms}$, $t_s=260\,\mathrm{ms}$ and different amplitudes $I_0=6\,\mu\mathrm{A}$, $I_0=8\,\mu\mathrm{A}$, $I_0=15\,\mu\mathrm{A}$, and $I_0=20\,\mu\mathrm{A}$. The results of this simulation appear in Figures 2, 3, 4, 5.

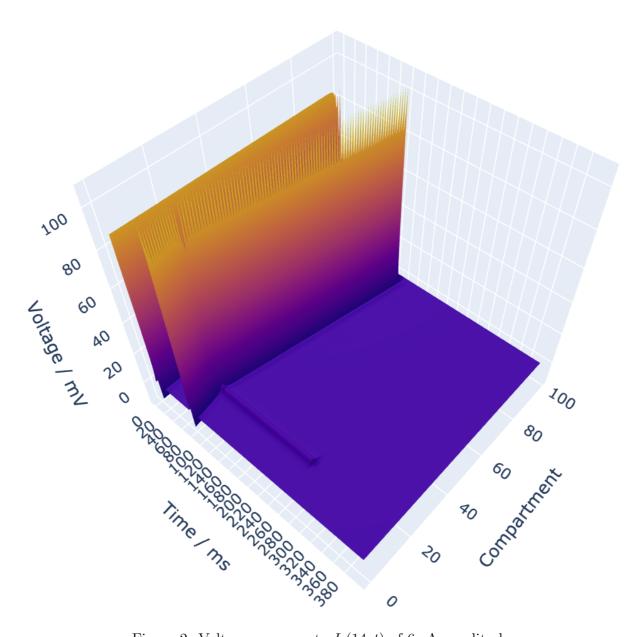


Figure 2: Voltage response to $I_e(14,t)$ of $6\,\mu\mathrm{A}$ amplitude.

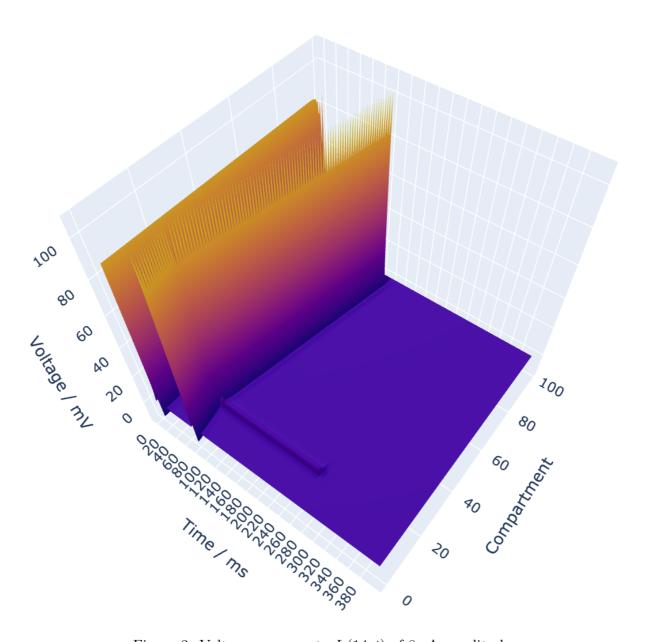


Figure 3: Voltage response to $I_e(14,t)$ of $8\,\mu\mathrm{A}$ amplitude.

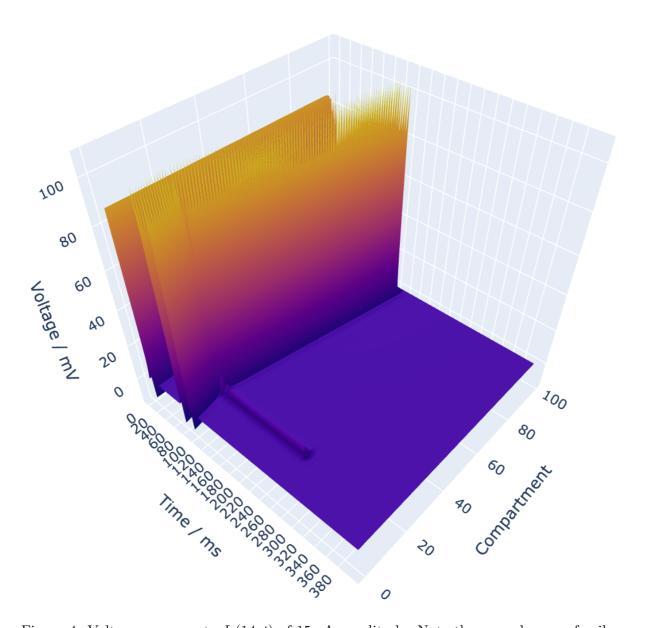


Figure 4: Voltage response to $I_e(14,t)$ of $15\,\mu\mathrm{A}$ amplitude. Note the second wave of spikes.

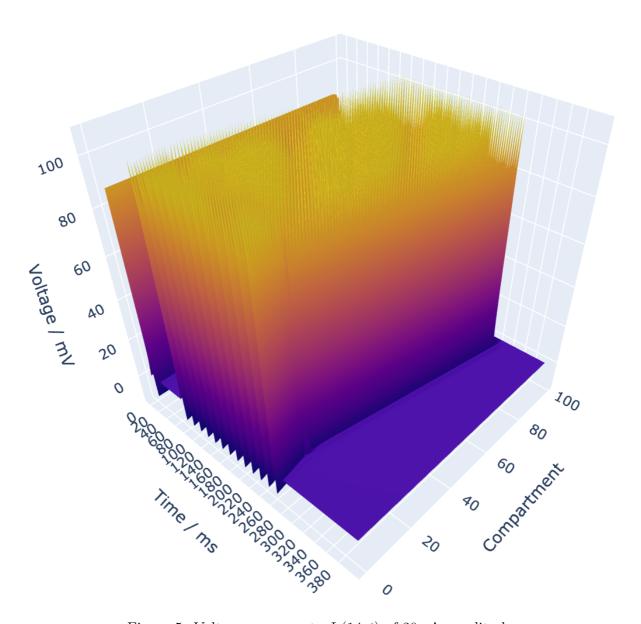


Figure 5: Voltage response to $I_e(14,t)$ of $20\,\mu\mathrm{A}$ amplitude.

HH

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[]: import numpy as np
   import matplotlib.pyplot as plt
   from scipy.signal import find_peaks
   import plotly.graph_objects as go
   %matplotlib inline
[]: def threshold_detect(signal):
       peaks, _ = find_peaks(signal, prominence=1)
       return peaks
[]: class Neuron:
       def __init__(self, E_m, C_m, E_na, E_k, E_l, g_na, g_k, g_l):
           self.E_m = E_m
           self.C_m = C_m
           self.E_na = E_na
           self.E_k = E_k
           self.E_1 = E_1
           self.g_na = g_na
           self.g_k = g_k
           self.g_1 = g_1
       def _update_gating(self, V_t, dt, m_t, h_t, n_t):
           '''Update gating variables'''
           beta_m = 4*np.exp(-V_t/18)
           beta_h = 1/(1 + np.exp(-(V_t - 30)/10))
           beta_n = 0.125*np.exp(-V_t/80)
           if V_t == 25:
               alpha_m = 1
               alpha_m = 0.1*((V_t - 25)/(1 - np.exp(-(V_t - 25)/10)))
           alpha_h = 0.07*np.exp(-V_t/20)
           if V_t == 10:
               alpha_n = 0.1
           else:
               alpha_n = 0.01*((V_t - 10)/(1 - np.exp(-(V_t - 10)/10)))
```

```
m_t1 = m_t + dt*(alpha_m*(1 - m_t) - beta_m*m_t)
   h_t1 = h_t + dt*(alpha_h*(1 - h_t) - beta_h*h_t)
   n_t1 = n_t + dt*(alpha_n*(1 - n_t) - beta_n*n_t)
   return m_t1, h_t1, n_t1
def _plot_response(self, V, t_e, t_s, dt, save_fig=False):
    '''Plot 2D responses'''
   figure = plt.figure(figsize=(9, 5))
   plt.grid(alpha=0.4)
   xi = np.arange(0, len(V), 1)*dt
   plt.plot(xi, V)
   plt.axhline(y=0, color='k', linestyle='--', alpha=0.4)
   plt.axvline(x=t_e, color='r', linestyle='--', alpha=0.4)
   plt.axvline(x=t_s, color='r', linestyle='--', alpha=0.4)
   plt.xlabel('Time / ms', fontsize=15)
   plt.ylabel('Voltage / mV', fontsize=15)
   plt.xticks(fontsize = 10)
   plt.yticks(fontsize = 10)
    if save_fig:
        plt.savefig('Figure.png')
    return
def _plot_response_3D(self, V, dt, save_fig=False):
    '''Plot 3D responses'''
   vals = np.arange(0, V.shape[1], 2000)
   ticks = vals*dt
   layout = go.Layout(scene = dict(
                        xaxis = dict(
                            title = 'Time / ms',
                            tickmode = 'array',
                            tickvals = vals,
                            ticktext = ticks),
                        yaxis title='Compartment',
                        zaxis_title='Voltage / mV'),
                        width=700.
                        margin=dict(r=20, b=10, l=10, t=10))
    fig = go.Figure(data=go.Surface(z=V), layout=layout)
    fig.show()
    if save_fig:
```

```
fig.write_image("fig1.png")
       return
  def simulate(self, I_t, dt, time, t_e=None, t_s=None, plot=True, __
⇔save_fig=False):
       num_time_bins = int(time/dt)
       V_t = 0
       V_course = np.zeros(num_time_bins)
       m_t = 0
       h_t = 0
       n_t = 0
       for i in np.arange(0, int(time/dt), 1):
           if t_e:
               if (i*dt) < t_e:</pre>
                   I = I_t[0]
               elif t_e \le (i*dt) and (i*dt) < t_s:
                   I = I t[1]
               else:
                   I = I_t[2]
           else:
               I = I_t
           m_t, h_t, n_t = self._update_gating(V_t, m_t, h_t, n_t)
           leak = self.g_l*(V_t - self.E_l)
           sod = self.g_na*(m_t**3)*h_t*(V_t - self.E_na)
           pot = self.g_k*(n_t**4)*(V_t - self.E_k)
           V_{course}[i] = V_t + (dt/self.C_m)*(I - leak - sod - pot)
           V_t = V_course[i]
       if plot:
           self._plot_response(V_course, t_e, t_s, dt, save_fig=save_fig)
       return V_course
  def simulate_multi_compartment(self, N, j, g_ax, I_t,
                                  dt, time, t_e=None, t_s=None, plot=True, __
⇔save_fig=False):
       num_time_bins = int(time/dt)
       V_t = np.zeros(N)
```

```
V_course = np.zeros((N, num_time_bins))
                     m_t = np.zeros(N)
                     h_t = np.zeros(N)
                     n_t = np.zeros(N)
                     right = np.array([i for i in range(1, j)][::-1])
                     left = np.array([i for i in range((j+1), (N-1))])
                     for i in np.arange(0, int(time/dt), 1):
                                  if t_e:
                                              if (i*dt) < t_e:</pre>
                                                          I = I_t[0]
                                              elif t_e \le (i*dt) and (i*dt) < t_s:
                                                          I = I_t[1]
                                              else:
                                                          I = I_t[2]
                                  else:
                                              I = I_t
                                 m_t[j], h_t[j], n_t[j] = self._update_gating(V_t[j], dt, m_t[j],_u
\rightarrowh_t[j], n_t[j])
                                 V_{course[j, i]} = V_{t[j]} + (dt/self.C_m)*(I + self.g_l*(self.E_l - U))
\rightarrow V_t[j]
                                                                                                                                                                      + self.g_na*np.
\rightarrowpower(m_t[j], 3)*h_t[j]*(self.E_na - V_t[j])
                                                                                                                                                                      + self.g_k*np.
\rightarrowpower(n_t[j], 4)*(self.E_k - V_t[j])
                                                                                                                                                                      + g_ax*(V_t[j-1] -__
→V_t[j])
                                                                                                                                                                      + g_ax*(V_t[j+1] -_u
→V_t[j]))
                                  V_t[j] = V_course[j, i]
                                 for r in right:
                                              m_t[r], h_t[r], n_t[r] = self._update_gating(V_t[r], dt,__
\rightarrowm_t[r], h_t[r], n_t[r])
                                              V_{course}[r, i] = V_{t}[r] + (dt/self.C_m)*(self.g_l*(self.E_l - C_m))*(self.g_l*(self.E_l - C_m))*(self.g_l*(s
\rightarrowV_t[r])
                                                                                                                                                                      + self.g_na*np.
\rightarrowpower(m_t[r], 3)*h_t[r]*(self.E_na - V_t[r])
                                                                                                                                                                     + self.g_k*np.
\rightarrowpower(n_t[r], 4)*(self.E_k - V_t[r])
                                                                                                                                                                      + g_ax*(V_t[r-1] -__
\rightarrow V_t[r]
```

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+ g_ax*(V_t[r+1] -__
               \rightarrowV_t[r]))
                                                              V_t[r] = V_course[r, i]
                                                 for 1 in left:
                                                              m_t[1], h_t[1], n_t[1] = self._update_gating(V_t[1], dt,_u)
              \rightarrowm_t[1], h_t[1], n_t[1])
                                                              V_{course[1, i]} = V_{t[1]} + (dt/self.C_m)*(self.g_1*(self.E_1 - U_1))
              \rightarrowV_t[1])
                                                                                                                                                                                           + self.g_na*np.
               \rightarrowpower(m_t[1], 3)*h_t[1]*(self.E_na - V_t[1])
                                                                                                                                                                                           + self.g_k*np.
              \rightarrowpower(n_t[1], 4)*(self.E_k - V_t[1])
                                                                                                                                                                                           + g_ax*(V_t[l+1] -_
              \rightarrowV_t[1])
                                                                                                                                                                                           + g_ax*(V_t[l-1] -__
              →V_t[1]))
                                                              V_t[1] = V_course[1, i]
                                                  c = 0
                                                  m_t[c], h_t[c], n_t[c] = self._update_gating(V_t[c], dt, m_t[c],__
              \rightarrowh_t[c], n_t[c])
                                                  V_{course[c, i]} = V_{t[c]} + (dt/self.C_m)*(self.g_l*(self.E_l - U_s))
              \rightarrow V_t[c]
                                                                                                                                                                              + self.g_na*np.power(m_t[c],_
              \rightarrow3)*h_t[c]*(self.E_na - V_t[c])
                                                                                                                                                                             + self.g_k*np.power(n_t[c],_
              \rightarrow 4)*(self.E_k - V_t[c])
                                                                                                                                                                              + g_ax*(V_t[c+1] - V_t[c]))
                                                 V_t[c] = V_course[c, i]
                                                  c = (N-1)
                                                       m_t[c], h_t[c], n_t[c] = self.\_update\_gating(V_t[c], dt, m_t[c], local terms of the self.\_update\_gating(V_t[c], dt, m_t[c], dt, m_t[c], local terms of t
              \hookrightarrow h_t[c], n_t[c]
                                                 V_{course[c, i]} = 0
                                                 V_t[c] = V_course[c, i]
                                     if plot:
                                                  self._plot_response_3D(V_course, dt, save_fig=save_fig)
                                    return V_course
[]: E_m = 0
           C_m = 1
           E na = 115
           E_k = -12
```

```
E_1 = 10.6
   g_na = 120
   g_k = 36
   g_1 = 0.3
   a = Neuron(E_m, C_m, E_na, E_k, E_l, g_na, g_k, g_l)
[]: | I = [0, 8, 0]
   t_e = 50
   t_s = 300
   dt = 0.01 \#ms
   time = t_s+100 \#ms
   v = a.simulate(I, dt, time, t_e, t_s, save_fig=False)
[]: I = np.arange(0, 20, 0.25)
   dt = 0.01 \#ms
   time = 800 \#ms
   v = np.zeros((len(I), int(time/dt)))
   for c in range(len(I)):
       v[c, :] = a.simulate(I[c], dt, time, plot=False, save_fig=False)
[ ]: r = []
   for i in range(v.shape[0]):
       trace = v[i, 20000:]
       x = threshold_detect(trace)
       r.append(np.float(len(x))/np.float(0.6))
[]: figure = plt.figure(figsize=(9, 5))
   plt.grid(alpha=0.4)
   plt.xlabel('Applied current / tA', fontsize=15)
   plt.ylabel('Firing rate / s^-1', fontsize=15)
   plt.plot(I, r)
   # plt.scatter(I, r, marker='x', alpha=0.6)
   # plt.savefig('Firing_rate.png')
[]: N = 100
   j = 14
   g_ax = 0.5
   I = [0, 20, 0]
   t_e = 60
   t_s = 260
   dt = 0.01 \#ms
   time = 400 \text{ #ms}
   a.simulate_multi_compartment(N, j, g_ax, I, dt, time, t_e, t_s)
[]:
```