

Using Genetic Algorithms in the Design of Two-phase Studies

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Outline

- 1 Background
- 2 Statistical Framework
- 3 Phase 2 Designs
- 4 Challenges of GAs
- 5 Future Work

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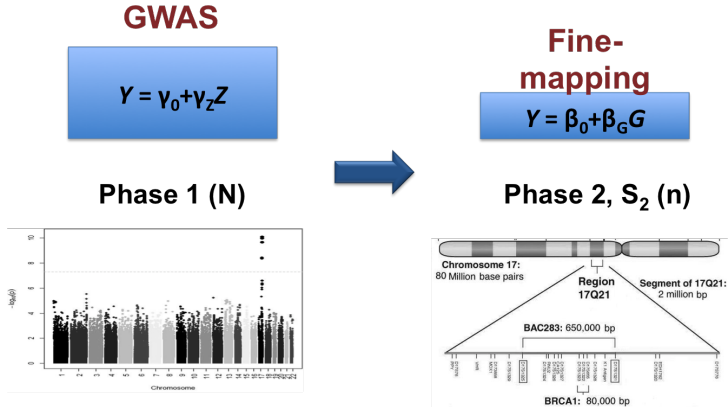
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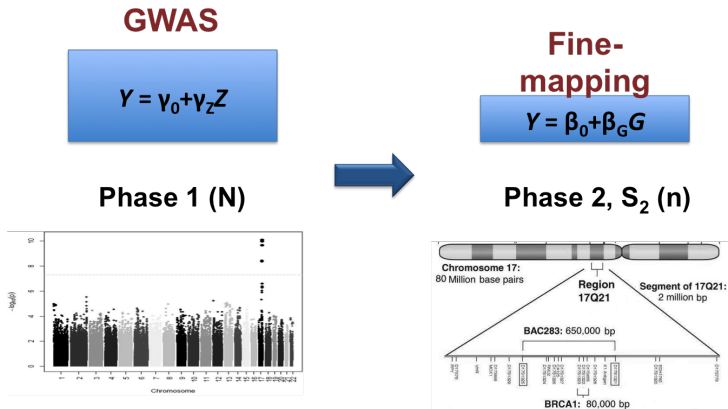
Costs of next-generation sequencing remain prohibitively expensive for large studies

Motivation: Two-phase Fine-mapping Studies



Y is an outcome of interest (quantitative trait, QT), Z is the lead SNP, and G is a (fine-mapped) sequence variant

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Aim: Identify designs that select informative individuals for S_2 data collection

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Regression via Maximum Likelihood Methods

The observed data likelihood is defined as:

$$L(\boldsymbol{\beta}, \boldsymbol{p}) \propto \prod_{i=1}^N \left[f_{\boldsymbol{\beta}}(y_i | g_i, z_i) p(g_i, z_i) \right]^{R_i} \left[\sum_{g \in \mathcal{G}} f_{\boldsymbol{\beta}}(y_i | g, z_i) p(g, z_i) \right]^{(1-R_i)} \quad (1)$$

$$= \prod_{i \in S_2} f_{\boldsymbol{\beta}}(y_i | g_i, z_i) p_{g_i, z_i} \prod_{i \in \bar{S}_2} \sum_{g \in \mathcal{G}} f_{\boldsymbol{\beta}}(y_i | g, z_i) p_{g, z_i} \quad (2)$$

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where

- $R_i = \mathbb{1}\{i \in S_2\}$ with $\mathbb{P}(R_i = 1 | y_i, z_i) = \pi(y_i, z_i; \psi)$, $\mathbf{R} = (R_1, \dots, R_N)'$, and $\sum_{i=1}^N R_i = n$.
- $f_{\beta}(y | g, z)$ is a member of the exponential family, focus on $Y | G = g, Z = z \sim \mathcal{N}(\beta_0 + \beta_1 g + \beta_2 z, \sigma^2)$ with $\boldsymbol{\beta} = (\beta_0, \beta_1, \beta_2)$.
- $p_{g,z}$ is the joint probability of $G = g$ and $Z = z$, $\mathbf{p} = \{p_{g,z}\}_{g \in \mathcal{G}, z \in \mathcal{Z}}$.
- \mathcal{G}, \mathcal{Z} are sets of uniquely observed values of G (in S_2) and Z (in $S_2 \cup \bar{S}_2$).
- \bar{S}_2 is the set of $N - n$ unselected subjects.

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 - Nonparametric part models the joint probability between Z and G (p).
- Maximum likelihood estimates are obtained via the EM algorithm.
- The variance-covariance matrix (VCM) is computed via the Louis' method (1982).
- Main interest lies in testing for $H_0 : \beta_1 = 0$ vs $H_A : \beta_1 \neq 0$.

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Outcome/Covariate - Dependent Sampling

Let $R_i = \mathbb{1}\{i \in S_2\}$ and

$$\mathbb{P}(R_i = 1|Z_i, Y_i, G_i) = \mathbb{P}(R_i = 1|Z_i, Y_i) = \pi_i, \quad i = 1, \dots, N \quad (\text{Missing at random})$$

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Marginal sampling:

$$\mathbb{P}(R_i = 1|Z_i, Y_i) = \begin{cases} \pi(Z_i) & \text{covariate-dependent} \\ \pi(Y_i) & \text{outcome-dependent} \end{cases}$$

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Joint sampling:

$$\mathbb{P}(R_i = 1|Z_i, Y_i) = \pi(Z_i, Y_i)$$

For the lead SNP (Z) sampling, strata are naturally defined by the number of copies of the minor allele.

To operationalize the outcome sampling, we discretize Y into a K strata variable Y_{st} , (T_1, \dots, T_K) using pre-specified cut-offs (C_1, \dots, C_{K-1}) .

A First Approach

Let N be the phase 1 sample size and n be the phase 2 sample size ($N > n$)

$Z \backslash Y_{st}$
0
1
2
M_Y

Phase 1 data			
T_1	\dots	T_K	M_Z
N_{01}	\dots	N_{0K}	$N_{0\cdot}$
N_{11}	\dots	N_{1K}	$N_{1\cdot}$
N_{21}	\dots	N_{2K}	$N_{2\cdot}$
$N_{\cdot 1}$	\dots	$N_{\cdot K}$	N

Phase 2 design			
T_1	\dots	T_K	M_Z
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where

$$n_{I_z, I_y} = \# \{i : Z_i \in I_z, Y_i \in I_y\}$$

is the number of subjects to be allocated in each stratum for the joint sampling design.

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Q: How to allocate samples for the phase 2 design?

Heuristic designs

Strata are defined using Y and Z (observed at phase 1)

Y , the QT, is discretized into a $K = 3$ strata variable Y_{st} (T_1, T_2, T_3)

Z , the lead SNP, is defined by the number of copies of the minor allele (0, 1, 2)

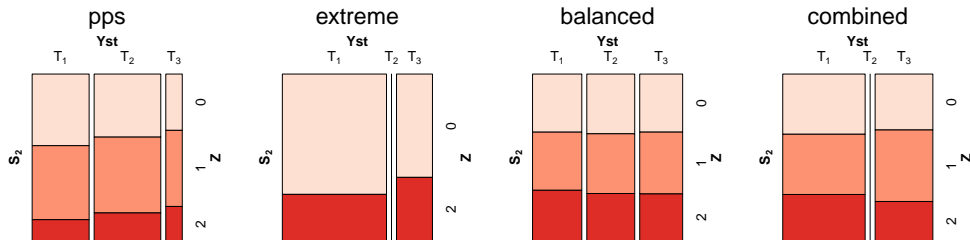


Figure: Heuristic designs when $n \approx N/2$, $Y \sim \mathcal{N}(2, 2.25)$, minor allele frequency (MAF) for Z , $q_Z = 0.3$

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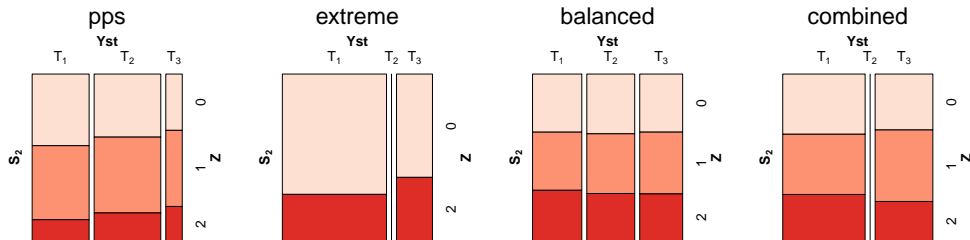


Figure: Heuristic designs when $n \approx N/2$, $Y \sim \mathcal{N}(2, 2.25)$, minor allele frequency (MAF) for Z , $q_Z = 0.3$

Q: Is there a better way to find phase 2 designs given a fixed n ?

Optimality in Two-Phase Studies

Let $\theta = (\beta^t, \mathbf{p}^t)^t$, under regularity conditions, the limiting distribution of $\hat{\theta}$ follows asymptotically:

$$\sqrt{N}(\hat{\theta} - \theta) \sim \mathcal{N}(0, \mathbb{J}(\Phi)^{-1}),$$

where $\Phi = (\theta^t, \psi^t)^t$, and

- ψ is a parameter determining $\pi(y_i, z_i; \psi) = \mathbb{P}(R_i = 1 | y_i, z_i; \psi)$, and
- $\mathbb{J}(\Phi)$ is the expected information matrix.

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Following experimental design literature, different optimality criteria, $\Lambda(\cdot)$, can be investigated:

A-optimality: minimizes trace of VCM, i.e. $\Lambda[\mathbb{J}(\Phi)] = \sum \text{diag}(\mathbb{J}(\Phi)^{-1})$

D-optimality: minimizes determinant of VCM, i.e. $\Lambda[\mathbb{J}(\Phi)] = \det(\mathbb{J}(\Phi)^{-1})$

Parameter-specific: minimizes the entry of the VCM corresponding to β_1 , i.e.

$$\Lambda[\mathbb{J}(\Phi)] = [\mathbb{J}(\Phi)^{-1}]_{\beta_1, \beta_1}$$

The Optimization Problem

We want to identify a design that satisfies the following optimization problem:

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or similarly

$$\min \Lambda [\mathbb{J}(\Phi)] \quad \text{subject to} \quad \mathbb{P}(\mathbf{R} = 1 | \mathbf{Y}, \mathbf{Z}) = \frac{n}{N}.$$

Designs via Lagrange Multipliers

Aims to optimize the stratum-specific selection probabilities by minimizing the following expression

$$\Lambda [\mathbb{J}(\Phi)] + \lambda N^{-1} \left(\sum_{k,j \in Y_{st}, Z} \pi_{kj}(\psi) N_{kj} - n \right)$$

where λ is a Lagrange multiplier (LM) that accounts for the budget constraint and N_{kj} is the phase 1 stratum size.

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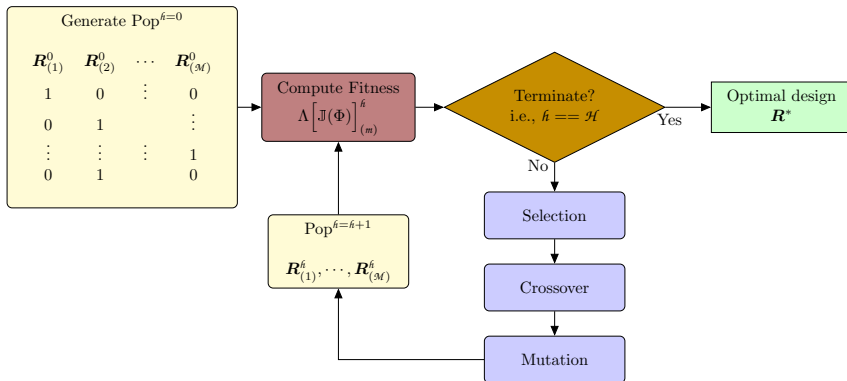
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Notes:

- $\theta = (\beta^t, \mathbf{p}^t)^t$ are design quantities, i.e. need to be specified a priori
- Provides a set of optimal sampling fractions π_{kj}^* for each stratum
- A phase 2 subsample is drawn given $\boldsymbol{\pi}^* = (\pi_{10}^*, \dots, \pi_{K2}^*)$

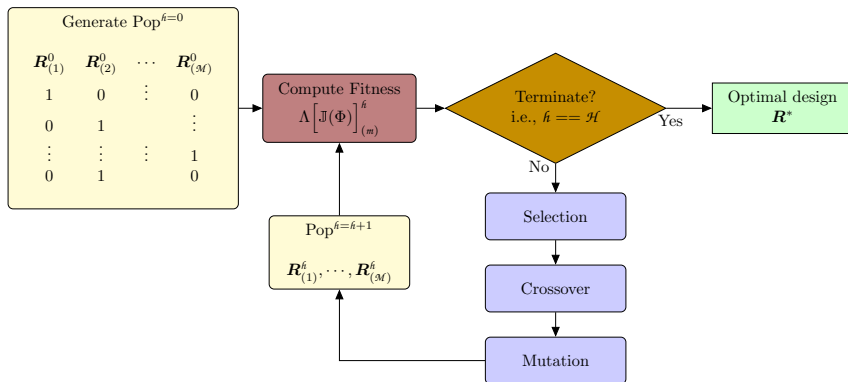
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Notes:

- Suitable for discrete optimization in large search spaces (2^N).
- The budget constraint is accounted for via fixed-size subset selection.
- Hyper-parameter tuning is needed.

Rank-based Designs

Grounded in theoretical findings, these designs achieve a phase 2 sample size by selecting an equal number of subjects from each of the top and bottom rankings of the following quantities:

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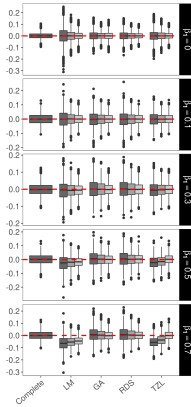
TZL: Tao-Zeng-Lin's scaled residuals design. Tao et al. (2020) showed that scaling the residuals by $\text{Var}(G|Z)^{1/2}$ (unknown at design stage) yields a design with minimum variance under the score test, i.e. $\beta_1 = o(1)$.

Characteristics of the Studied Designs

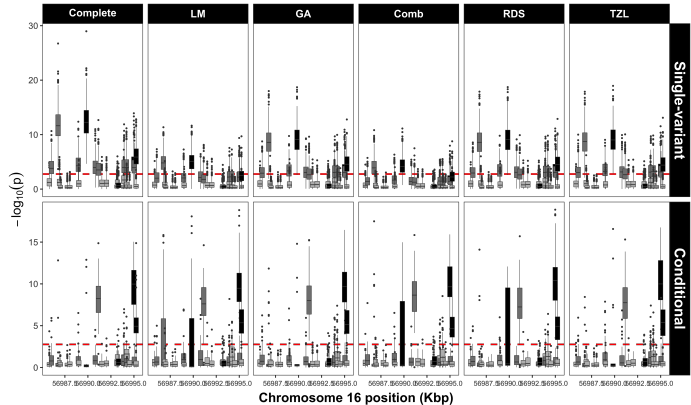
Feature	Design				
	Heuristic	LM	GA	ODS/RDS	TZL
Design quantities β , p need to be specified	×	✓	✓	×	✓
Subject to sampling variability	✓	✓	×	×	×
Computationally intensive	×	×	✓	×	×
Depends on strata definition	✓	✓	×	×	×

Simulation results in realistic scenario

- GA demonstrates less estimation bias compared to TZL.
- GA shows comparable power to TZL when $\text{Var}(G|Z)$ is misspecified.



■ 540 ■ 1250 ■ 2500



■ Causal ■ Hitchhiker ■ Non-causal

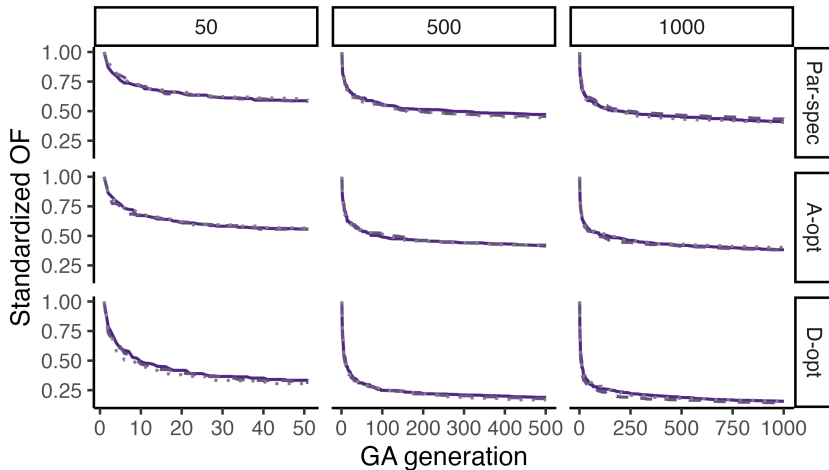
Summary

- The proposed GA designs can be more powerful than heuristic designs and comparable to rank-based designs.
- Similar results for GA over different MAFs, LDs and sample sizes (N, n).
- GA achieves power similar to complete data with half sequencing info.
- GA can be implemented across a variety of models.
- Implementation available at github.com/egosv/twoPhaseGAS.

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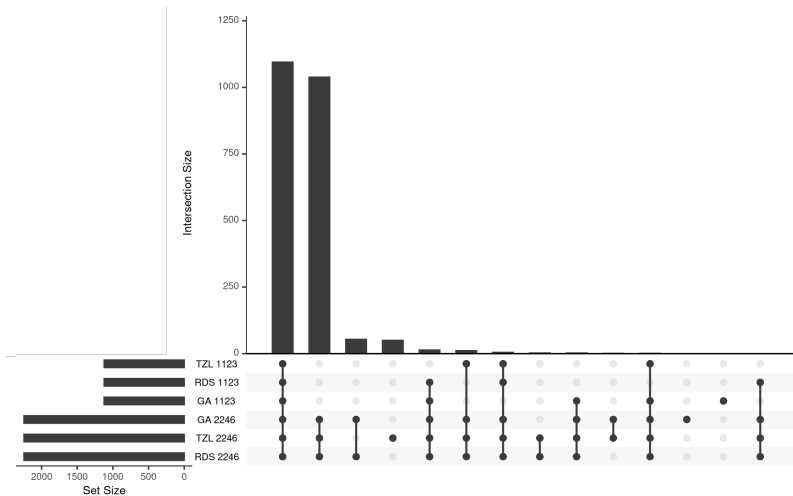
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Convergence



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Solution Uniqueness



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High-dimensional Covariate Settings

Let $\mathbf{Z} \in \mathbb{R}^p$ be a high-dimensional covariate vector, with observed likelihood:

$$L(\boldsymbol{\beta}, \boldsymbol{\gamma}) = \prod_{i=1}^N \left\{ f_{\boldsymbol{\beta}}(Y_i | G_i, \mathbf{Z}_i) h_{\boldsymbol{\gamma}}(G_i, \mathbf{Z}_i) \right\}^{R_i} \times \left\{ \int f_{\boldsymbol{\beta}}(Y_i | g, \mathbf{Z}_i) h_{\boldsymbol{\gamma}}(g, \mathbf{Z}_i) \mathrm{d}g \right\}^{1-R_i},$$

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the optimization problem becomes:

$$\begin{aligned} \min \quad & -\log L(\boldsymbol{\beta}, \boldsymbol{\gamma}, \mathbf{R}) + \Lambda \left[\mathbb{J}(\boldsymbol{\beta}, \boldsymbol{\gamma}, \mathbf{R})^{-1} \right] \\ \text{subject to} \quad & \sum_{i=1}^N R_i = n, \quad \sum_{j=2}^{p+2} c_{1j} \mathbb{1}(\beta_j) \leq C_1, \quad \sum_{j=2}^{p+2} c_{2j} \mathbb{1}(\gamma_j) \leq C_2, \end{aligned}$$

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here

- $\mathbb{1}(\cdot)$ is the indicator function denoting whether the j th parameter is to be selected,
- c_{kj} , $k = 1, 2; j = 2, \dots, p + 2$ represent covariate-specific costs, and
- C_k , $k = 1, 2$, are budget constraints for the parameters in f and h .

Alternative Optimization Methods

- Dynamic Programming (knapsack problem)
- Simulated Annealing
- Estimation of Distribution Algorithms

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Thank you for listening!

Questions?