

# Meeting summaries DRL project

## Meeting 1: 27.07.2022, 12 pm

### About the Idea:

- Why not use the fMRI data? Because it is not publicly available
- Three approaches, start with one and then do the other ones later if we need more

### Approach 1 (start)

Train agent on games and compare salience maps

-> should be relatively easy (not so much risk)

-> Leon S. send material from Tensorflow about salience maps, we might need to optimise it

-> then everything in place for approach 2

### Approach 2:

Give agent information about human gaze and compare learning to the normal one from before

-> also relatively easy

### Approach 3:

Create more human like vision for the agent

E.g. restricting the view or blurring the image

LeonS: more experimental & risk

Ideas: having one model deciding what to do and where to go next, vs. Two models

-> blurring difficult because the mask would have to be differentiable

-> discuss that with Leon S. if we are there in the project

### Decision on which game

Start with game with good performance in comparisons in other papers (e.g. rainbow DQN)

### DQN implementation:

1. Using existing Rainbow DQN implementation
  1. Stable baselines has good ones
  2. Need Approach 1 and 2 for a good project
  3. Choose carefully a good working implementation that we can understand

2. Implementing it ourselves
  1. Approach 1 might be enough for a good grade
  2. Rainbow what is reasonable
  3. Something with advantages (because they are already checking where the network is looking?)
  4. Noisy networks not necessary
- Give feedback on that decision via Email

### Workload:

Maybe it is easier to do more different approaches and then not so deeply.

## Meeting 2: 08.08.22, 12 pm

Leon S. you sadly did not attend the meeting, so this features only our decisions.

### DQN implementation:

- We will further improve and test it
- Implementing prioritised experience replay
- Changing some hyperparameters

### Saliency:

- It is okay to use external code for calculations, because there is still enough to implement
- Different methods are going to be compared
- Scale the big q-values maybe with softmax to be able to compute the calculations (otherwise np.exp overflow)

### Gaze Prediction:

- Scale heatmaps down to 0-1?
- How to stack the frames most efficiently?

### How to use Tensorboard:

- Also works during training
- Command: `tensorboard --logdir path`

## Meeting 3: 11.08.22, 12 pm

### Saliency maps suggestions:

- If performs bad, maybe the bias in the middle is not good in information gain
- Compare scores of our dqn with the performance of old basic dqn papers
- MNIST classifier, to check if the saliency methods are working

### Risks approach 3,

if it does not work, these might be the causes :

- Deepq stuff -> misuse part of the q-surface -> need a large delay to solve that
- DQN always trained on old data
- Idea Leon L: with another target network to environment for blurring

### Writing together:

- Toodonotes -> write in parallel, review what the others did by writing a comment, or telling others what you are doing in a comment
- Do a general structure at the beginning so you know what goes where

## Meeting 4: 13.09.22, 11 pm

### Deadline extension:

Because we tried to have a meeting for a week already and the training of our model takes a lot of time (after the first there are 2 more to train) we asked for a deadline extension.

### Buffer improvements:

- Do not use normal system memory as runtime memory, because it will be super slow
- Size down the images to uint8
- Buffer should be 4x the batch size already loaded (we already have 8 x)
- Lossless compression algorithm?
- Better use sparse arrays, who only save nonzero values, because the whole background is black

### Parameters:

- Try to go in a direction and see how good at beginning of training, because we do not have time for a grid search
- 6 times more training than sampling (as we have) sounds reasonable

### Prioritised replay:

What to do with new samples?

- Directly use them once or give them a high value
- TD error of 0-100 (as we have) is too big, maybe normalise the rewards for better training

### Saliency:

- Try binary comparison
- Try correlation
- Use 4 different frames
- Use scaling instead of blurring after creating saliency not for every pixel
- Human might look in the future, DQN in the present
- Write down precisely what we did at the end
- Also try with integrated gradients