

EMS Tunneling server / client build process on Ubuntu 20.04

Building localproxy (Tunneling server)

```
1 sudo apt update
2 sudo apt upgrade
3 sudo apt install git zlib1g wget cmake libssl-dev
4 git clone https://github.com/eguanatech/aws-iot-securetunneling-localproxy.git
5 git checkout imx6-eguna
6 wget https://github.com/boostorg/boost/releases/download/boost-1.81.0/boost-1.81.0.tar.gz
7 tar xzvf boost-1.81.0.tar.gz
8 cd boost-1.81.0
9 ./bootstrap.sh
10 sudo ./b2 install link=static
11 cd ..
12 wget https://github.com/protocolbuffers/protobuf/releases/download/v3.17.3/protobuf-all-3.17.3.tar.gz
13 tar xzvf protobuf-all-3.17.3.tar.gz
14 cd protobuf-3.17.3
15 mkdir build
16 cd build
17 cmake ../cmake
18 make
19 sudo make install
20 cd ../../
21 git clone --branch v2.13.6 https://github.com/catchorg/Catch2.git
22 cd Catch2
23 mkdir build
24 cd build
25 cmake ../
26 make
27 sudo make install
28 cd ../../
29 mkdir build
30 cd build
31 cmake ../
32 make
```

You can find the built image [localproxy](#) and [localproxytest](#) at the bin folder. (i.e. aws-iot-securetunneling-localproxy/build/bin/).

[localproxytest](#) is the unit test suite that AWS team created, [localproxy](#) is the proxy server we need for tunneling.

The script I wrote for the proxy server is located at /home/ikayzo/Downloads/tunnel.sh. You can modify it if you need to.

Building aws-iot-device-client (Tunneling client on EMS)

```
1 sudo apt update
2 sudo apt install software-properties-common build-essential g++-arm-linux-gnueabi gcc-arm-linux-gnueabi
  gdb-multiarch
3 git clone https://github.com/eguanatech/aws-iot-device-client.git
4 cd aws-iot-device-client
5 git checkout master
6 mkdir build
7 cd build
```

```
8 wget --ca-certificate=/etc/ssl/certs/ca-certificates.crt https://www.openssl.org/source/openssl-1.1.1n.tar.gz
9 tar -xvzf openssl-1.1.1n.tar.gz
10 export INSTALL_DIR=/usr/lib/arm-linux-gnueabihf
11 cd openssl-1.1.1n
12 ./Configure linux-generic32 shared \
13     --prefix=$INSTALL_DIR --openssldir=$INSTALL_DIR/openssl \
14     --cross-compile-prefix=/usr/bin/arm-linux-gnueabihf-
15 make depend
16 make
17 sudo make install
18 cd ../
19 cmake -DCMAKE_TOOLCHAIN_FILE=./cmake-toolchain/Toolchain-armhf.cmake ../
20 cmake --build . --target aws-iot-device-client
21 cmake --build . --target test-aws-iot-device-client
```

You can find the built image [aws-iot-device-client](#) at the build folder(aws-iot-device-client/build/) and [test-aws-iot-device-client](#) at the bin folder(aws-iot-device-client/build/test/). Since the image is cross-compiled with the arm toolchain these images won't be able to run on our host machine(x86). You need to scp these image to the EMC to run them.

After you build the aws-iot-device-client, copy this image to the yocto project and replace existing one(egear-manifest/source/meta-aws/recipes-iot/aws-iot-device-client/files/aws-iot-device-client). Build the yocto project after that. By doing this your Yocto image will include the latest version of device client you built.