

# ARTG 5330

## Visualization Technologies

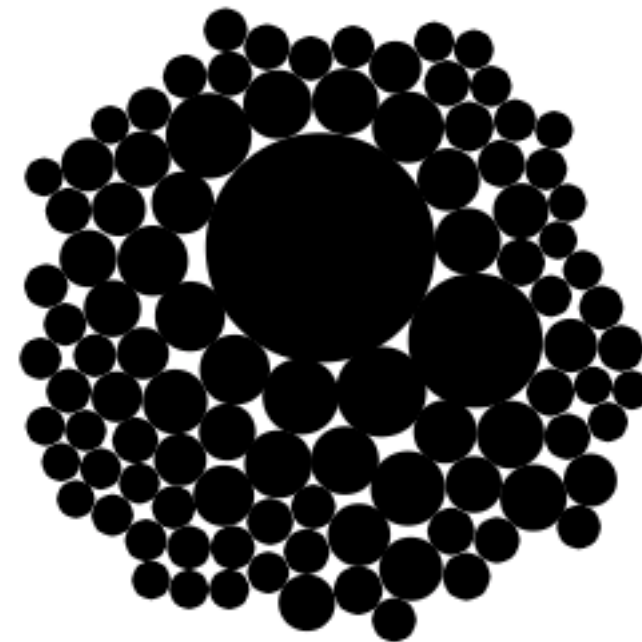
**Packed bubbles**

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College of Arts, Media and Design

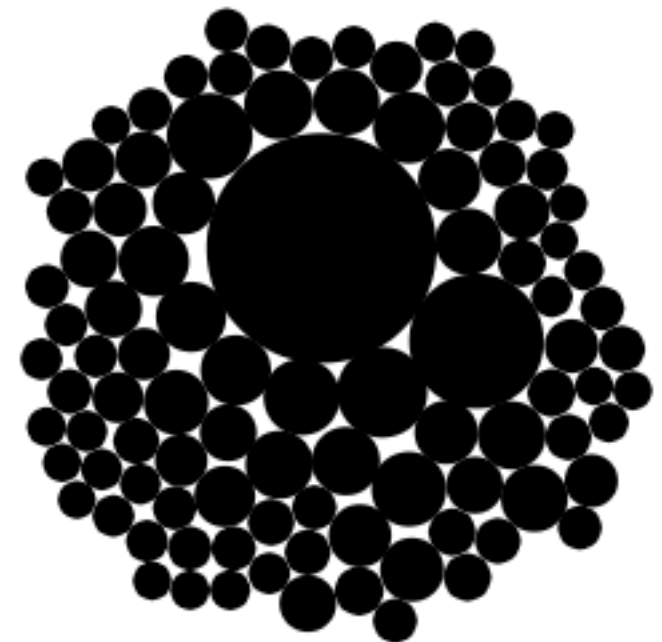
# Packed bubbles

1. Bubbles are attracted to the center
2. Bubbles collide with each other
3. Initial conditions are paramount



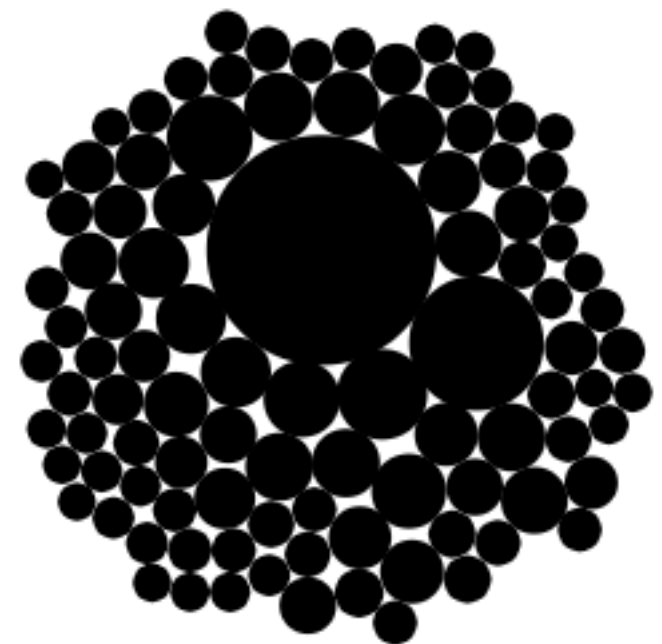
# Challenge: first take on interacting with packed bubbles

1. When the mouse is over a circle, it expands.
2. When the mouse exits the circle, it returns to its normal size.
3. When the circle attained its maximum size, it displays the name of the company.



# Brainstorm

- Which other types of interaction are suitable for this visualization model and data?
- What other visual variables can we use to depict data? (e.g. color)



# Data aggregation

**Aggregates data in a massive object such as**

```
{  
  Uber : total_usd,  
  Groupon : total_usd,  
  ...  
}
```

# Data aggregation

```
for (var r = 0; r < table.getRowCount(); r++){
    var cname = table.getString(r, "company_name");
    var invested = table.getString(r, "amount_usd");
    invested = parseInt(invested);
    if(!isNaN(invested)){
        if(aggregated.hasOwnProperty(cname)){
            aggregated[cname]=aggregated[cname]+invested;
        }else{
            aggregated[cname] = invested;
        }
    }
}
```

# Data aggregation

**Converts that object into an array of companies**

```
var aAggregated = [];  
Object.keys(aggreated).forEach(function(name_){  
    var company = {};  
    company.name = name_;  
    company.sum = aggreated[name_];  
    aAggregated.push(company);  
});
```

# Data aggregation

Sorts the array by USD amount

```
aAggregated.sort(function(companyA, companyB){  
    return companyB.sum - companyA.sum;  
});
```



# Creating particles

**Creates 100 particles from the array**

```
for(var i=0; i<100; i++){  
    var p = new Particle(aAggregated[i].name, aAggregated[i].sum);  
    particleSystem.push(p);  
}
```

# Creating particles

The area of the particle should signify the amount of the investment

```
/* in the constructor */  
this.radius = sqrt(sum)/4000;
```

```
/* in the draw function */  
ellipse(this.pos.x,  
        this.pos.y,  
        this.radius*2,  
        this.radius*2);
```

# Modifying particles

The position of a particle should be made public as it will need to be modified externally.

```
/* var pos  —————> this.pos */  
/* var vel  —————> this.vel */
```

# Create the attractor

**Creates a central attractor of strength 1**

```
var at = new Attractor(createVector(width/2, height/2), 1);  
attractors.push(at);
```

# Making uniform attraction forces

Attracts particles regardless of their distances.

```
attractors.forEach(function(A){
  var att = p5.Vector.sub(A.pos, this.pos);
  var distanceSq = att.magSq();
  if(distanceSq > 1){
    att.normalize();
    att.div(10);
    //att.mult(this.radius*this.radius/200);
    acc.add(att);
  }
}, this);
this.vel.add(acc);
this.pos.add(this.vel);
acc.mult(0);
```

# Making collisions

**It is a constraint based problem, where the constraint is that no circle can be juxtaposed to any other.**

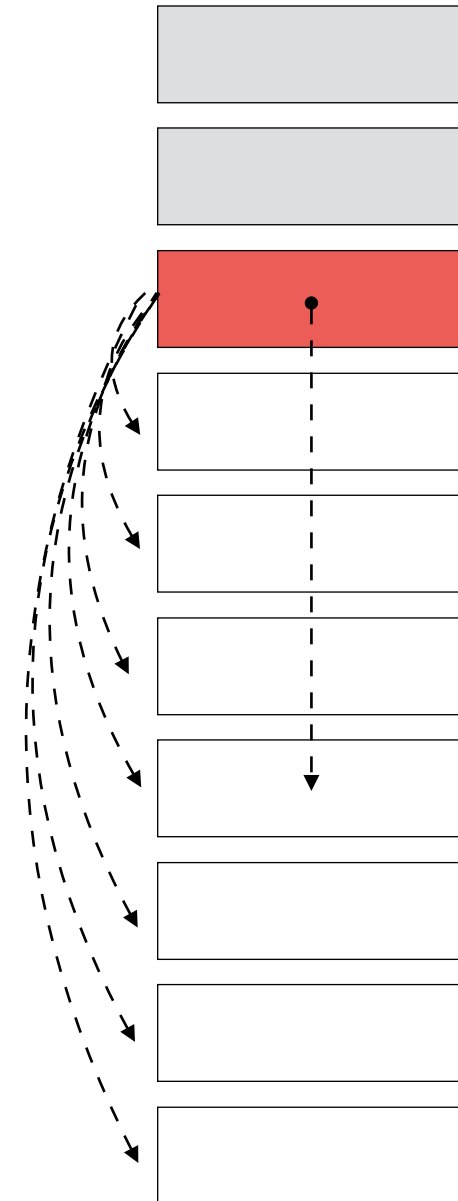
# Making collisions

**Circles will be compared in pairs, and if the constraints are not met, the system is modified in order to attain some of these constraints.**

# Making collisions

## Pair-wise comparison

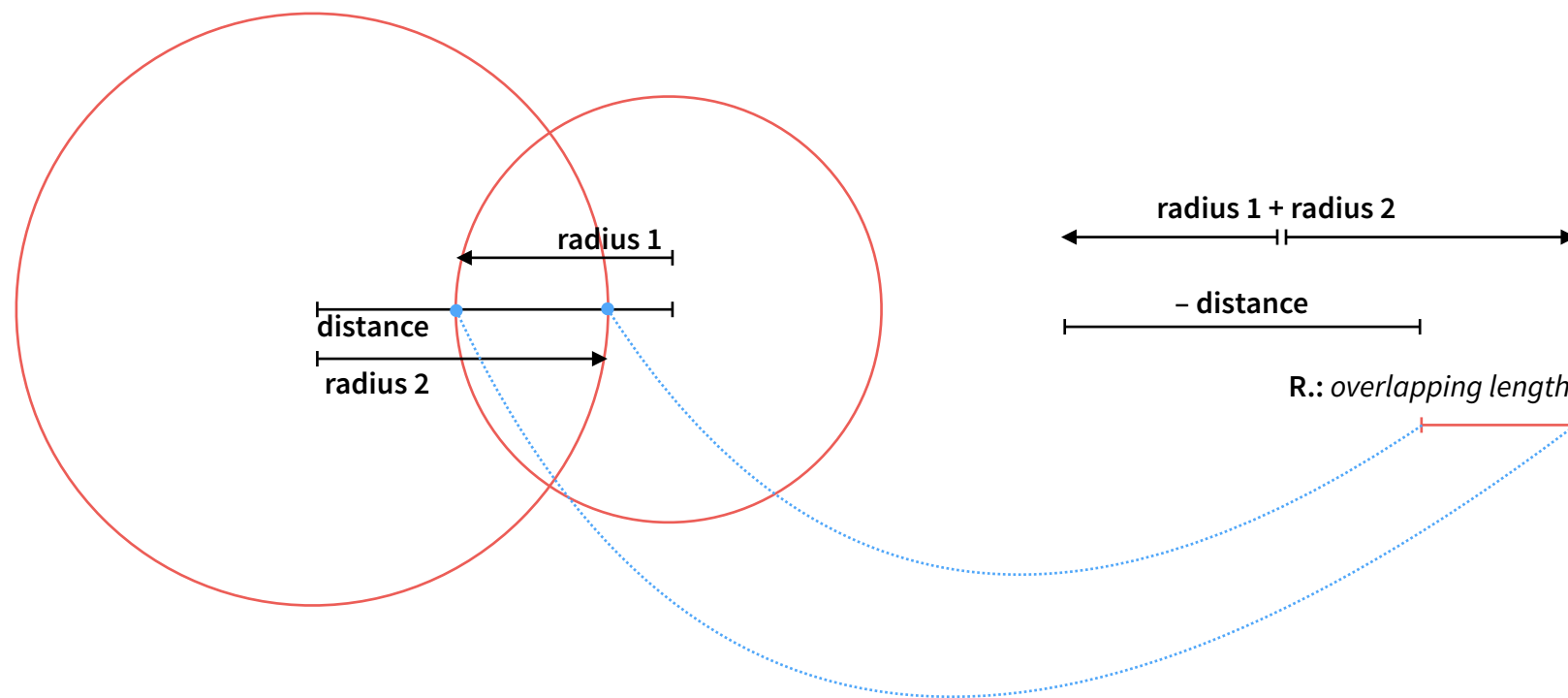
```
for(var i=0; i<particleSystem.length-1; i++){  
  for(var j=i+1; j<particleSystem.length; j++){  
    var pa = particleSystem[i];  
    var pb = particleSystem[j];  
    ...  
  }  
}
```





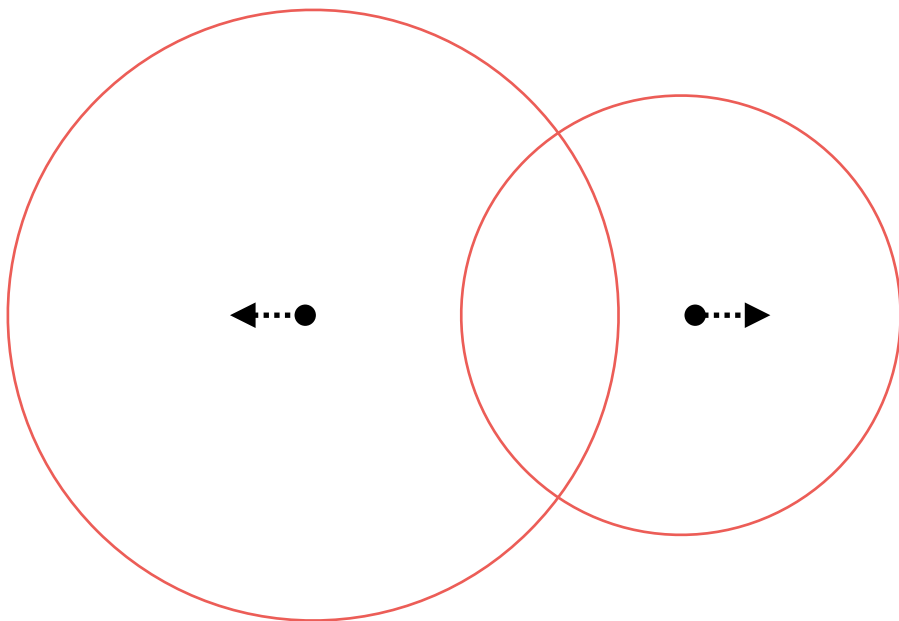
# Making collisions

Adjusting the positions for each pair of particles consists of pushing each particle away from the other in a distance that nullifies their overlapping length.



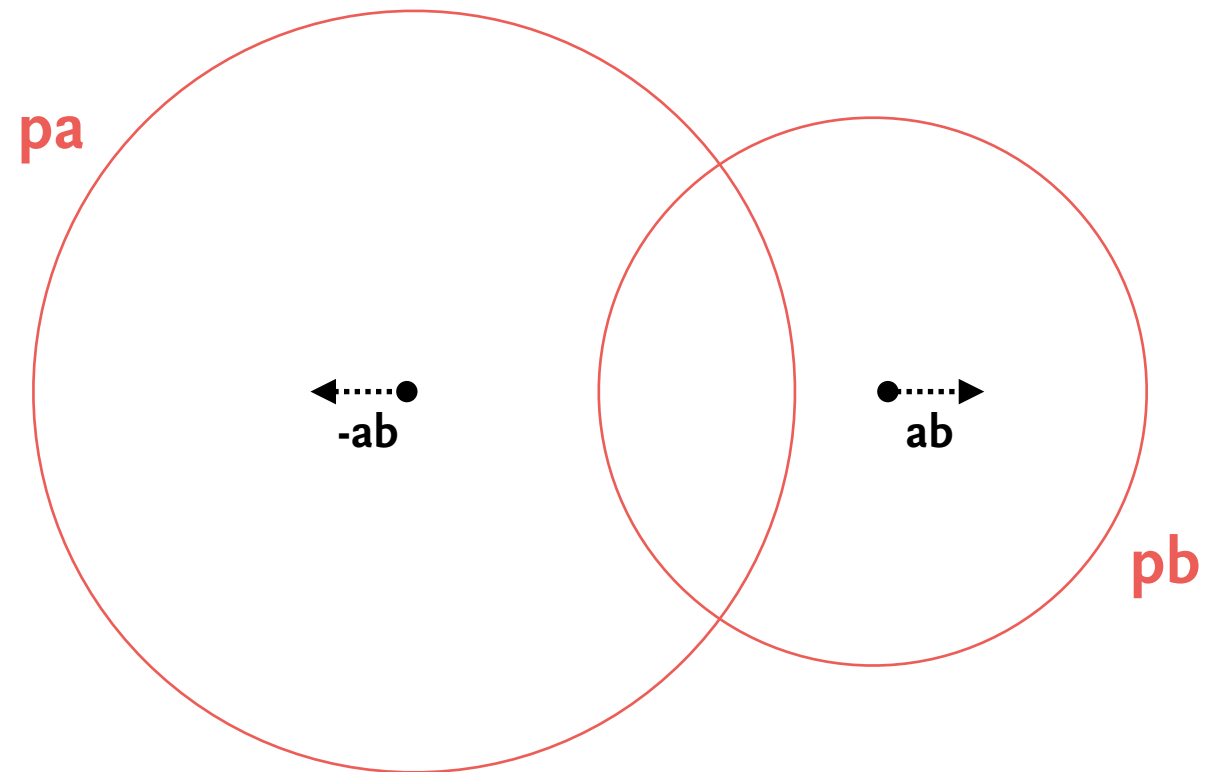
# Making collisions

In the end it should result into two vectors that shift the positions of each particle in opposing directions, having each of these vectors a length that is half of the total overlapping length.



# Making collisions

```
var pa = particleSystem[i];  
var pb = particleSystem[j];  
var ab = p5.Vector.sub(pb.pos, pa.pos);  
var distSq = ab.magSq();  
if(distSq <= sq(pa.radius + pb.radius)){  
  var dist = sqrt(distSq);  
  var overlap = (pa.radius + pb.radius) - dist;  
  ab.div(dist); //ab.normalize();  
  ab.mult(overlap*0.5);  
  pb.pos.add(ab);  
  ab.mult(-1);  
  pa.pos.add(ab);  
}
```



# Making collisions – relaxation

```
for(var STEPS = 0; STEPS<3; STEPS++){  
  for(var i=0; i<particleSystem.length-1; i++){  
    for(var j=i+1; j<particleSystem.length; j++){  
      var pa = particleSystem[i];  
      var pb = particleSystem[j];  
      var ab = p5.Vector.sub(pb.pos, pa.pos);  
      var distSq = ab.magSq();  
      if(distSq <= sq(pa.radius + pb.radius)){  
        var dist = sqrt(distSq);  
        var overlap = (pa.radius + pb.radius) - dist;  
        ab.div(dist); //ab.normalize();  
        ab.mult(overlap*0.5);  
        pb.pos.add(ab);  
        ab.mult(-1);  
        pa.pos.add(ab);  
      }  
    }  
  }  
}
```

# Making collisions – dumping

```
for(var STEPS = 0; STEPS<3; STEPS++){  
    for(var i=0; i<particleSystem.length-1; i++){  
        for(var j=i+1; j<particleSystem.length; j++){  
            (...)  
            if(distSq <= sq(pa.radius + pb.radius)){  
                (...)  
  
                pa.vel.mult(0.97);  
                pb.vel.mult(0.97);  
            }  
        }  
    }  
}
```

# Initial conditions

**Arrange circles radially while making bigger circles stay the center of the canvas, and the smallest in the periphery.**

```
var tempAng = random(TWO_PI);  
this.pos = createVector(cos(tempAng), sin(tempAng));  
this.pos.div(this.radius);  
this.pos.mult(1000);  
this.pos.set(this.pos.x + width/2, this.pos.y + height/2);
```