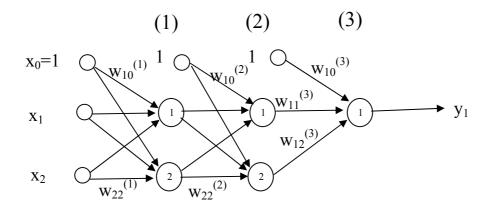
Example: Backpropagation Algorithm

Consider the following Multilayer Perceptrons:



Each neuron has an unipolar sigmoid activation fn:

$$\varphi(v) = \frac{1}{1 + e^{-av}}$$

Let a=1, $\varphi'(v) = \varphi(v)(1 - \varphi(v))$

For a given training sample, $\{\mathbf{x},d_1\}$:

Forward pass:

Compute
$$v_j^{(s)} = \sum_{i=0}^{n_{s-1}} x_i^{(s-1)} w_{ji}^{(s)}$$

 $x_{out,j}^{(s)} = \varphi(v_j^{(s)})$
for layer 1, 2, 3 (i.e. s=1,2,3)

Backward pass:

For output layer,

$$\delta_1^{(3)} = (d_1 - y_1) \varphi'(v_1^{(3)})$$
$$= (d_1 - y_1) y_1 (1 - y_1)$$

where d_1 is the desired value corresponding to the input ${\boldsymbol x}$

For hidden layers,

$$\delta_{1}^{(2)} = \varphi'(v_{1}^{(2)}) \sum_{h=1}^{1} w_{h1}^{(3)} \delta_{h}^{(3)}$$

$$= x_{out,1}^{(2)} (1 - x_{out,1}^{(2)}) w_{11}^{(3)} \delta_{1}^{(3)}$$

$$\delta_{2}^{(2)} = \varphi'(v_{2}^{(2)}) \sum_{h=1}^{1} w_{h2}^{(3)} \delta_{h}^{(3)}$$

$$= x_{out,2}^{(2)} (1 - x_{out,2}^{(2)}) w_{12}^{(3)} \delta_{1}^{(3)}$$

$$\delta_{1}^{(1)} = \varphi'(v_{1}^{(1)}) \sum_{h=1}^{2} w_{h1}^{(2)} \delta_{h}^{(2)}$$

$$= x_{out,1}^{(1)} (1 - x_{out,1}^{(1)}) (w_{11}^{(2)} \delta_{1}^{(2)} + w_{21}^{(2)} \delta_{2}^{(2)})$$

$$\delta_{2}^{(1)} = \varphi'(v_{2}^{(1)}) \sum_{h=1}^{2} w_{h2}^{(2)} \delta_{h}^{(2)}$$

$$= x_{out,2}^{(1)} (1 - x_{out,2}^{(1)}) (w_{12}^{(2)} \delta_{1}^{(2)} + w_{22}^{(2)} \delta_{2}^{(2)})$$

Then wt update rules are:

$$\Delta w_{10}^{(3)} = \eta \delta_{1}^{(3)}, \Delta w_{11}^{(3)} = \eta \delta_{1}^{(3)} x_{out,1}^{(2)}, \Delta w_{12}^{(3)} = \eta \delta_{1}^{(3)} x_{out,2}^{(2)}$$

$$\Delta w_{10}^{(2)} = \eta \delta_{1}^{(2)}, \Delta w_{11}^{(2)} = \eta \delta_{1}^{(2)} x_{out,1}^{(1)}, \Delta w_{12}^{(2)} = \eta \delta_{1}^{(2)} x_{out,2}^{(1)}$$

$$\Delta w_{20}^{(2)} = \eta \delta_{2}^{(2)}, \Delta w_{21}^{(2)} = \eta \delta_{2}^{(2)} x_{out,1}^{(1)}, \Delta w_{22}^{(2)} = \eta \delta_{2}^{(2)} x_{out,2}^{(1)}$$

$$\Delta w_{10}^{(1)} = \eta \delta_{1}^{(1)}, \Delta w_{11}^{(1)} = \eta \delta_{1}^{(1)} x_{1}, \Delta w_{12}^{(1)} = \eta \delta_{1}^{(1)} x_{2}$$

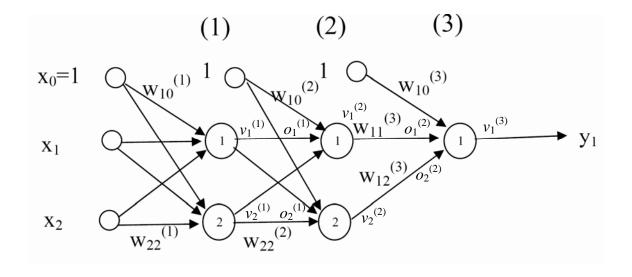
$$\Delta w_{20}^{(1)} = \eta \delta_{2}^{(1)}, \Delta w_{21}^{(1)} = \eta \delta_{2}^{(1)} x_{1}, \Delta w_{22}^{(1)} = \eta \delta_{2}^{(1)} x_{2}$$

Above wt update is for a single training pattern (corresponding to a learning step).

After a learning step is finished, next training pattern is submitted and the learning step is repeated.

Until all the patterns in the training set have been exhausted → One epoch

Example: Solve the XOR problem using the following network architecture:

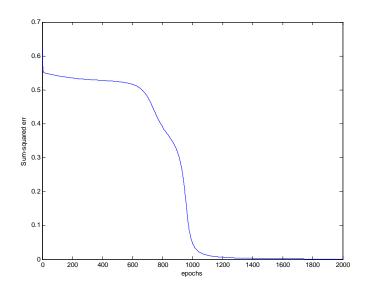


The input vector consists of 4 patterns,

$$x_1 = [0 \ 0]^T, x_2 = [1 \ 0]^T, x_3 = [1 \ 1]^T, x_4 = [0, \ 1]^T;$$

which corresponds to the desired vector of: $\mathbf{d} = [0, 1, 0, 1]^T$;

For randomly initialized weights and a learning rate of 0.8, the learning stops when the sum-squared err is less than 0.001 or the number of epochs reaches 2000. The convergence is shown in the figure below.



In this case, the output obtained is given as: $y = [0.0219, 0.9769, 0.0239, 0.9768]^T$ After training, the weight matrix of each layer (1, 2, 3) is as follows,

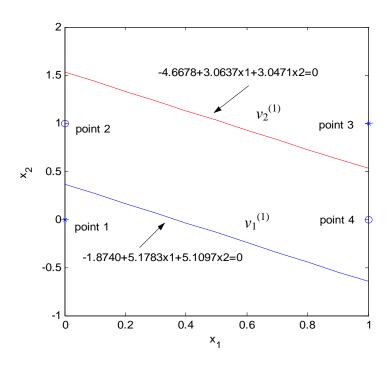
$$\mathbf{w}^{(1)} = \begin{bmatrix} \text{bias} \\ -1.87 & 5.17 & 5.10 \\ -4.66 & 3.06 & 3.04 \end{bmatrix}$$

$$\mathbf{w}^{(2)} = \begin{bmatrix} \text{bias} \\ -1.06 & 3.69 & -5.29 \\ 2.53 & -4.67 & 3.54 \end{bmatrix}$$

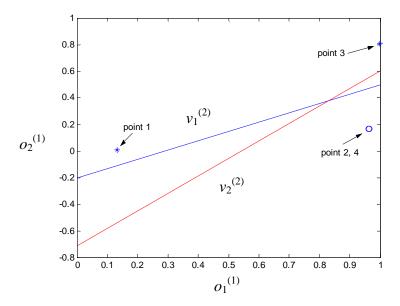
$$\mathbf{w}^{(3)} = [-0.36, 6.49, -6.5147]$$

Therefore the decision lines for the first hidden layer are:

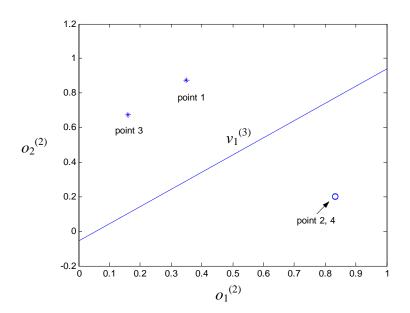
$$-1.87 + 5.17 \cdot x_1 + 5.10 \cdot x_2 = 0$$
 and $-4.66 + 3.06 \cdot x_1 + 3.04 \cdot x_2 = 0$.



The decision lines for the second hidden layer are:



And the decision line for the output layer is:



Source codes in Matlab ************

clear all; close all;

X=[0 1 1 0;0 0 1 1];

```
X = [ones(1,4);X];
d=[0\ 1\ 0\ 1];
H1=2;H2=2;
No=1;
W1=2*(rand(H1,3)-rand(H1,3));
W2=2*(rand(H2,H1+1)-rand(H2,H1+1));
W3=2*(rand(No,H2+1)-rand(No,H2+1));
err=1;
epoch=1;
yit=0.96;
while (err>0.001) & (epoch<2000)
  err=0;
for iter=1:4
%% begin forward process
for i=1:H1
  V1(i) = W1(i,:)*X(:,iter);
  O1(i) = logsig(V1(i));
end
for i=1:H2
  V2(i)=W2(i,:)*[1;O1'];
  O2(i) = logsig(V2(i));
end
%%output layer
for i=1:No
  V3(i)=W3(i,:)*[1;O2'];
  Y(i,iter) = logsig(V3(i));
end
%%end forward process
%% begin backward pass
for i=1:No
  De3(i)=(d(iter)-Y(i,iter))*Y(i,iter)*(1-Y(i,iter));
end
for i=1:H2
  De2(i)=O2(i)*(1-O2(i))*W3(:,i+1)*De3;
end
for i=1:H1
  De1(i)=O1(i)*(1-O1(i))*(De2*W2(:,i+1));
%% end backward pass
```

```
%% weights update
W3=W3+yit*De3*[1;O2']';
for i=1:H2
    W2(i,:)=W2(i,:)+yit*De2(i)*[1;O1']';
end
for i=1:H1
    W1(i,:)=W1(i,:)+yit*De1(i)*X(:,iter)';
end
err=err+0.5*(d(iter)-Y(iter))^2;
end %% end of one epoch
Err(epoch)=err;
epoch=epoch+1;
end
Y
plot(Err)
```