4231 Homework 6

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Problem 1

Problem 23-4 on Page 641: Alternative minimum-spanning-tree algorithms. For each of the three algorithms, either give a counterexample or prove that it always outputs a minimum spanning tree. Make sure your proof is written clearly and concisely. Also there is no need to describe efficient implementations of these algorithms.

23-4

In this problem, we give pseudocode for three different algorithms. Each on takes a connected graph and a weight function as input and returns a set of edges T. For each algorithm, either prove that T is a minimum spanning tree or prove that T is not a minimum spanning tree. Also describe the most efficient implementation of each algorithm, whether or not it computes a minimum spanning tree.

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a. Maybe-MST-A(G, w)
    1: sort the edges into nonincreasing order of edge weights w
    2: T = E
    3: for each edge e, taken in nonincreasing order by weight do
          if T - \{e\} is a connected graph then
              T = T - \{e\}
    6: return T
b. Maybe-MST-B(G, w)
    1: T = \emptyset
    2: for each edge e, taken in arbitrary order do
          if T \cup \{e\} has no cycles then
              T = T \cup \{e\}
    5: return T
c. Maybe-MST-C(G, w)
    1: T = \emptyset
    2: for each edge e, taken in arbitrary order do
          T = T \cup \{e\}
          if T has a cycle c then
              let e' be a maximum-weight edge on c
              T = T - \{e'\}
    7: return T
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Problem 2

Problem 24-4 on Page 679: Gabow's scaling algorithm for single-source shortest paths.

24-4

Arbitrage is the use of discrepancies in currency exchange rates to transform one unit of a currency into more than one unit of the same currency. For example, suppose that 1 U.S. dollar buys 49 Indian rupees, 1 Indian rupee buys 2 Japanese yen, and 1 Japanese yen buys 0.0107 U.S. dollars. Then, by converting currencies, a trader can start with 1 U.S. dollar and buy $49 \times 2 \times 0.0107 = 1.0486$ U.S. dollars, thus turning a profit of 4.86 percent.

Suppose that we are given n currencies c_1, c_2, \ldots, c_n and an $n \times n$ table R of exchange rates, such that one unit of currency c_i buys R[i, j] units of currency c_j .

a. Give an efficient algorithm to determine whether or not there exists a sequence of currencies $\langle c_{i_1}, c_{i_2}, \dots, c_{i_k} \rangle$ such that

$$R[i_1, i_2] \cdot R[i_2, i_3] \cdot \cdot \cdot R[i_{k-1}, i_k] \cdot R[i_k, i_1] > 1$$

Analyze the running time of your algorithm.

 \boldsymbol{b} . Give an efficient algorithm to print out such a sequence if one exists. Analyze the running time of your algorithm.

Problem 3

Problem 25-2 on Page 706: Shortest paths in ϵ -dense graphs. Skip a). For a d-ary min-heap, INSERT takes time $O(\log_d n)$; EXTRACT-MIN takes time $O(d \cdot \log_d n)$; and DECREASE-KEY takes time $O(\log_d n)$. Check Chapter 6 and Problem 6-2 if you are interested in d-ary min-heaps. But for this problem, you may use these facts for free.

25-2

A graph G=(V,E) is ϵ -dense if $|E|=\Theta(V^{1+\epsilon})$ for some constant ϵ in the range $0<\epsilon\leq 1$. By using d-ary min-heaps (see Problem 6-2) in shortest-paths algorithms on ϵ -dense graphs, we can match the running times of Fibonacci-heap-based algorithms without using as complicated a data structure.

- **b.** Show how to compute shortest paths from a single source on an ϵ -dense directed graph G = (V, E) with no negative-weight edges in O(E) time. (*Hint:* Pick d as a function of ϵ .)
- c. Show how to solve the all-pairs shortest-paths problem on an ϵ -dense directed graph G = (V, E) with no negative-weight edges in O(VE) time.
- d. Show how to solve the all-pairs shortest-paths problem in O(VE) time on an ϵ -dense directed graph G = (V, E) that may have negative-weight edges but has no negative-weight cycles.

Problem 4

Problem 26.1 on Page 760: Escape problem.

26.1

An $n \times n$ **grid** is an undirected graph consisting of n rows and n columns of vertices, as shown in Figure 1. We denote the vertex in the ith row and the j th column by (i,j). All vertices in a grid have exactly four neighbors, except fo the boundary vertices, which are the points (i,j) for which i=1, i=n, j=1, or j=n.

Given $m \leq n^2$ starting points $(x_1, y_1), (x_2, y_2), \ldots, (x_m, y_m)$ in the grid, the **escape problem** is to determine whether or not there are m vertex-disjoint paths from the starting points to any m different points on the boundary. For example, the grid in Figure 1(a) has an escape, but the grid in Figure 1(b) does not.

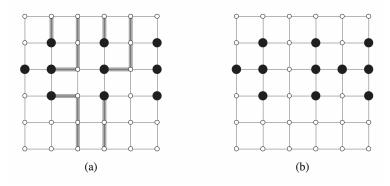


Figure 1: Grids for the escape problem. Starting points are black, and other grid vertices are white. (a) A grid with an escape, shown by shaded paths. (b) A grid with no escape.

- a. Consider a flow network in which vertices, as well as edges, have capacities. That is, the total positive flow entering any given vertex is subject to a capacity constraint. Show that determining the maximum flow in a network with edge and vertex capacities can be reduced to an ordinary maximum-flow problem on a flow network of comparable size.
- **b.** Describe an efficient algorithm to solve the escape problem, and analyze its running time.