

SR을 적용한 자동차 번호판 추정 향상



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주제

SR을 적용한 자동차 번호판 추정향상

개요

Object detection에서 SR의 필요성



자동차의 번호판은 차량을 식별할 수 있는 중요 정보를 담고 있습니다. 블랙박스 카메라의 화질이나 기상 상황, 도로 상황 등에 따라서 Object detection이 안되거나 잘못된 위치를 찾는 일이 발생합니다. Super Resolution을 통해서 Pre-processing 이후, Object Detection을 진행 시 더 높은 인식률과 정확도를 기대해볼 수 있다.

실험 및 결과

Base Code

- 데이터: Kaggle 'Car License Plate Detection'
- VGG16을 이용한 자동차 번호판 Detection

Dataset information

The number of images: 432장

Original Image Size: 500 x 268 size

Translated Image Size: 224x224크기로 Resize (VGGNet 모델 사용을 위해)



그림 1 - 기본 image

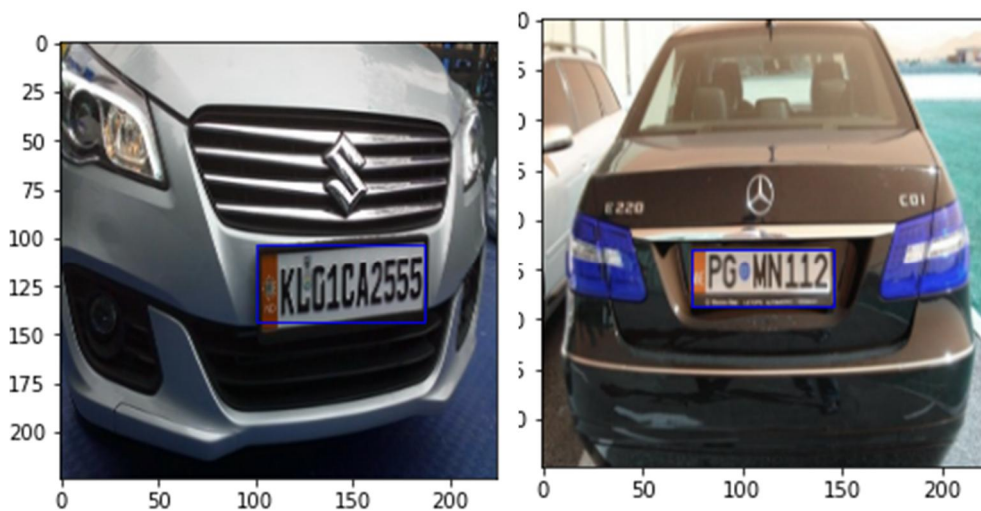


그림 2 - label box 좌표

Train_test_split

```
from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
X_train, X_val, y_train, y_val = train_test_split(X_train, y_train, test_size=0.1, random_state=1)
```

➔ 먼저, train과 test dataset을 8:2로 쪼갬다. 그리고 검증데이터를 얻기 위해서 train dataset을 9:1 비율로 쪼개서 데이터를 나눴다.

Model

```
1: from keras.models import Sequential
   from keras.layers import Dense, Flatten
   from keras.applications.vgg16 import VGG16

2: # Create the model
   model = Sequential()
   model.add(VGG16(weights="imagenet", include_top=False, input_shape=(IMAGE_SIZE, IMAGE_SIZE, 3)))
   model.add(Flatten())
   model.add(Dense(128, activation="relu"))
   model.add(Dense(128, activation="relu"))
   model.add(Dense(64, activation="relu"))
   model.add(Dense(4, activation="sigmoid"))

   model.layers[-6].trainable = False

   model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
vgg16 (Functional)	(None, 7, 7, 512)	14714588
flatten (Flatten)	(None, 25088)	0
dense (Dense)	(None, 128)	3211392
dense_1 (Dense)	(None, 128)	16512
dense_2 (Dense)	(None, 64)	8256
dense_3 (Dense)	(None, 4)	260

=====
Total params: 17,951,108
Trainable params: 3,236,420
Non-trainable params: 14,714,688
=====

➔ VGG16 모델을 사용

Hyperparameters

```
model.compile(loss='mean_squared_error', optimizer='adam', metrics=['accuracy'])

train = model.fit(X_train, y_train, validation_data=(X_val, y_val), epochs=50, batch_size=32, verbose=1)
```

Result

```
test_loss, test_accuracy = model.evaluate(X_test, y_test, steps=int(100))

print("Test results \n Loss:", test_loss, '\n Accuracy', test_accuracy)
```

```
82/100 [=====>.....] - ETA: 0s - loss: 0.0070 - accuracy: 0.8293WARNING:
rupting training. Make sure that your dataset or generator can generate at least `steps_per
atches). You may need to use the repeat() function when building your dataset.
100/100 [=====] - 1s 6ms/step - loss: 0.0070 - accuracy: 0.8276
Test results
Loss: 0.006950060371309519
Accuracy 0.8275862336158752
```

➔ 약 82.7%의 정확도

Blur처리된 이미지

image



➔ 왼쪽 상단부터 오른쪽으로 순서대로 16x16 Blur, 8x8 Blur, 4x4 Blur, Basic image

Result

Blur Kernel Size	Loss	Accuracy
16x16	0.00912	70.1
8x8	0.00691	79.3
4x4	0.00666	80.4
Basic	0.00695	82.7

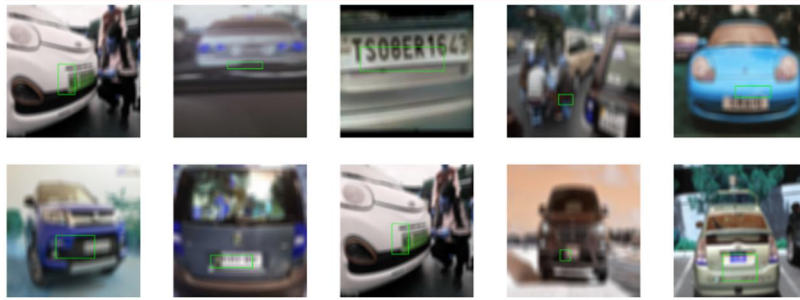


그림 3 - Blur 16x16



그림 4 - Basic

Super Resolution적용된 이미지 (BSRGAN)

Image



그림 5 - Basic image

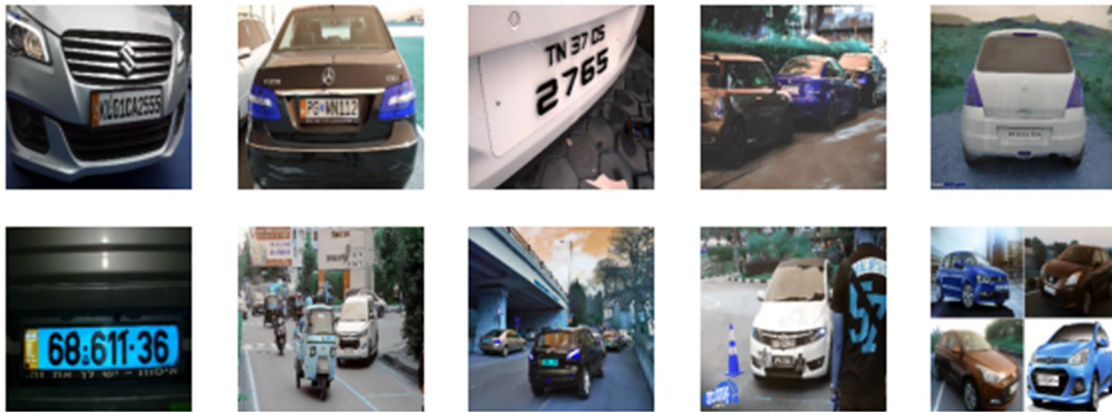


그림 6 - BSRGAN이 적용된 image

Test

1. BSRGAN을 적용한 이미지 학습 (base code, Apply-SR.html)
2. Weight Initialization(가중치 초기화) he_normal 사용 (Apply-SR-Copy.html)

```
# Create the model
model = Sequential()

model.add(VGG16(weights='imagenet', include_top=False, input_shape=(IMAGE_SIZE, IMAGE_SIZE, 3)))

model.add(Flatten())
model.add(Dense(128, activation='relu', kernel_initializer='he_normal'))
model.add(Dense(128, activation='relu', kernel_initializer='he_normal'))
model.add(Dense(64, activation='relu', kernel_initializer='he_normal'))
model.add(Dense(4, activation='sigmoid'))

model.layers[-6].trainable = False

model.summary()

Model: "sequential"
-----
Layer (type)                Output Shape              Param #
-----
vgg16 (Functional)          (None, 7, 7, 512)         14714688
flatten (Flatten)            (None, 25088)              0
dense (Dense)                (None, 128)                3211392
dense_1 (Dense)              (None, 128)                16512
dense_2 (Dense)              (None, 64)                 8256
dense_3 (Dense)              (None, 4)                  260
-----
Total params: 17,951,108
Trainable params: 3,236,420
Non-trainable params: 14,714,688
-----

model.compile(loss='mean_squared_error', optimizer='adam', metrics=['accuracy'])

train = model.fit(X_train, y_train, validation_data=(X_val, y_val), epochs=50, batch_size=32, verbose=1)
```

➔ 단순 가중치 초기화 he_normal을 적용

3. Batch Size 64 + Epoch 증가 + EarlyStopping 적용 (Apply-SR-Copy2.html)

```
# Create the model
model = Sequential()
model.add(VGG16(weights='imagenet', include_top=False, input_shape=(IMAGE_SIZE, IMAGE_SIZE, 3)))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dense(128, activation='relu'))
model.add(Dense(64, activation='relu'))
model.add(Dense(4, activation='sigmoid'))

model.layers[-6].trainable = False

model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
vgg16 (Functional)	(None, 7, 7, 512)	14714688
flatten (Flatten)	(None, 25088)	0
dense (Dense)	(None, 128)	3211392
dense_1 (Dense)	(None, 128)	16512
dense_2 (Dense)	(None, 64)	8256
dense_3 (Dense)	(None, 4)	260

=====
 Total params: 17,951,108
 Trainable params: 3,236,420
 Non-trainable params: 14,714,688
 =====

```
model.compile(loss='mean_squared_error', optimizer='adam', metrics=['accuracy'])
```

```
from keras.callbacks import EarlyStopping
```

```
early_stopping = EarlyStopping(patience = 50)
```

```
train = model.fit(X_train, y_train, validation_data=(X_val, y_val), epochs=1000, batch_size=64, verbose=1, callbacks = [early_stopping])
```

Result

Type	Loss	Accuracy
Basic	0.00695	82.7
BSRGAN 적용	0.00626	85.5
Weight Initialization	0.00667	88.5
Batch Size + Epoch + EarlyStopping	0.00618	88.5

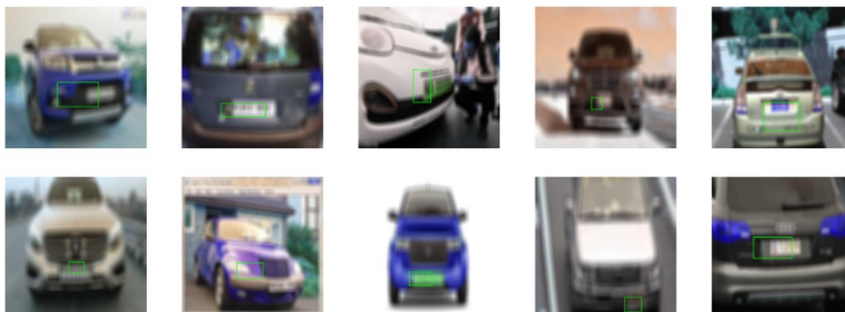


그림 5 - blur16x16 image

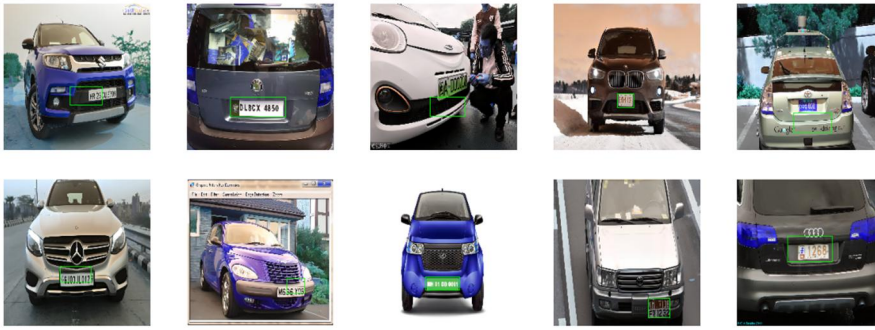


그림 6 - BSRGAN 적용 후 image

A case of trying but bad results

1. Optimizer 수정 (RMSProp, RAdam, NAdam, SGD 등)
2. Loss Function 수정
3. Dropout, Batch Normalized 기법 적용
4. 모델 수정 (Layer 층 추가, activation function 수정 등)

참고 자료

<https://www.kaggle.com/datasets/andrewmvd/car-plate-detection>

<https://www.kaggle.com/code/mclikmb4/vehicle-license-plate-detection-vgg16>

<https://github.com/kairess/BSRGAN>

<https://velog.io/@heaseo/BSRGAN-Designing-a-Practical-Degradation-Model-for-Deep-Blind-Image-Super-Resolution>