Gopal Sharma

Current Position

Current Position	
Postdoctoral Researcher , <i>The University of British Columbia</i> , Vancouver (with Dr. Kwang Moo Yi and Dr. Andrea Tagliasacchi)	2022 – Present
Education	
Ph.D. in Computer Science , <i>University of Massachusetts, Amherst</i> (3.86/4.00) Thesis: <i>Representation Learning for Shape Decomposition, By Shape Decomposition</i> Advisor: Dr. Subhransu Maji and Dr. Evangelos Kalogerakis	2016 – 2022
B.Tech. in Electrical Engineering, Indian Institute of Technology, Roorkee (8.6/10.0)	2012 – 2016
Work Experience	
Research Intern, <i>Nvidia</i> , Toronto (with Dr. Sanja Fidler and Dr. Kangxue Yin) Research Intern, <i>Adobe</i> , San Jose (with Dr. Radomír Měch and Dr. Siddhartha Chaudhuri) Research intern, <i>KAUST</i> (with Dr. Bernard Ghanem)	2021 2019 2015

Research Interests

Intersection of computer vision, computer graphics and machine learning, with emphasis on neural rendering (NeRFs and Gaussian Splatting) and Diffusion models.

Publications [Google Scholar: 0.5k+ citations and an h-index of 10]

2024

3D Gaussian Splatting as Markov Chain Monte Carlo Shakiba Kheradmand, Daniel Rebain, **Gopal Sharma**, Weiwei Sun, Jeff Tseng, Hossam Isack, Kar Abhishek, Andrea Tagliasacchi, and Kwang Moo Yi Arxiv 2024

Volumetric Rendering with Baked Quadrature Fields

Gopal Sharma, Daniel Rebain, Andrea Tagliasacchi, and Kwang Moo Yi

ECCV 2024

PointNeRF++: A multi-scale, point-based Neural Radiance Field Weiwei Sun, Eduard Trulls, Yang-Che Tseng, Sneha Sambandam, Gopal Sharma, Andrea Tagliasacchi, and Kwang Moo Yi ECCV 2024

Unsupervised Keypoints from Pretrained Diffusion Models
Eric Hedlin, Gopal Sharma, Shweta Mahajan, Xingzhe He, Hossam Isack, Abhishek Kar,
Helge Rhodin, Andrea Tagliasacchi, and Kwang Moo Yi
CVPR 2024 (Spotlight)

Accelerating Neural Field Training via Soft Mining
Shakiba Kheradmand, Daniel Rebain, **Gopal Sharma**, Hossam Isack, Kar Abhishek,
Andrea Tagliasacchi, and Kwang Moo Yi
CVPR 2024

2023.....

Unsupervised Semantic Correspondence Using Stable Diffusion

Eric Hedlin, **Gopal Sharma**, Shweta Mahajan, Hossam Isack, Abhishek Kar, Andrea Tagliasacchi, and Kwang Moo Yi

NeurIPS 2023

2022.....

PriFit: Learning to Fit Primitives Improves Few Shot Point Cloud Segmentation Gopal Sharma, Bidya Dash, Matheus Gadelha, Aruni RoyChowdhury, Marios Loizou, Evangelos Kalogerakis, Liangliang Cao, and Erik Learned-Miller Computer Graphics Forum 2022 (Oral)

MvDeCor: Multi-view Dense Correspondence Learning for Fine-grained 3D Segmentation Gopal Sharma, Kangxue Yin, Subhransu Maji, Evangelos Kalogerakis, Or Litany, and Sanja Fidler European Conference on Computer Vision 2022

Attention beats concatenation for conditioning neural fields

Daniel Rebain, Mark J Matthews, Kwang Moo Yi, **Gopal Sharma**, Dmitry Lagun, and Andrea Tagliasacchi

Transaction of Machine Learning Research 2022

Representation Learning for Shape Decomposition, By Shape Decomposition Gopal Sharma

PhD Thesis, University of Massachusetts Amherst 2022

2020

Label-efficient learning on point clouds using approximate convex decompositions
Matheus Gadelha, Aruni RoyChowdhury, **Gopal Sharma**, Evangelos Kalogerakis, Liangliang Cao, Erik Learned-Miller, Rui Wang, and Subhransu Maji
Computer Vision–ECCV 2020: 16th European Conference on Computer Vision 2020

ParSeNet: A Parametric Surface Fitting Network for 3D Point Clouds Gopal Sharma, Difan Liu, Evangelos Kalogerakis, Siddhartha Chaudhuri, and Radomír Měch ECCV: European Conference on Computer Vision 2020

2019.....

Search-guided, lightly-supervised training of structured prediction energy networks Amirmohammad Rooshenas, Dongxu Zhang, **Gopal Sharma**, and Andrew McCallum Advances in Neural Information Processing Systems 2019

Learning point embeddings from shape repositories for few-shot segmentation Gopal Sharma, Evangelos Kalogerakis, and Subhransu Maji 2019 International Conference on 3D Vision (3DV) 2019 (Oral)

2018

CSGNet: Neural shape parser for constructive solid geometry

Gopal Sharma, Rishabh Goyal, Difan Liu, Evangelos Kalogerakis, and Subhransu Maji Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition 2018

2016.....

Persistent aerial tracking system for uavs
Matthias Mueller, Gopal Sharma, Neil Smith, and Bernard Ghanem
2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2016

Invited Talks

0. Stable-Keypoints: Unsupervised learning of key points using Stable Diffusion Models, MathWorks	2024
1. MvDeCoR: Multi-view Dense Correspondence Learning for Fine-grained 3D Segmentation, Google	2022
Brain	
2. ParSeNet: A Parametric Surface Fitting Network for 3D Point Clouds, Invited talk at 3d Structure	2021
and Compositional Learning workshop. ICCV	
3. Fine-grained 3D shape co-segmentation via pixel-based contrastive learning, Nvidia Toronto	2021
4. Reinforcement learning for game programming, Game programming course at UMass Amherst	2021
5. Unity Machine Learning Agents, Game programming course at UMass Amherst	2020
6. CSGNet: Neural Shape Parser for Constructive Solid Geometry, New England Computer Vision	2018
Workshop, Harvard University	

Interns and Students

Eric Hedlin PhD student at UBC	2022 – present
Shakiba Kheradmand PhD student at UBC	2022 – present
Bidya Dash MSc student at UMass Amherst	2021
Rishabh Goyal Visiting intern at UMass Amherst	2017

Professional Activities

3DV Program Committee

2024

Reviewing

IEEE Conference on Computer Vision and Pattern Recognition (CVPR)

IEEE International Conference on Computer Vision (ICCV)

International Conference on the Constraint Programming, AI, and Operations Research (CPAIOR)

International Conference on Machine Learning (ICML)

Journal of Machine Learning Research (JMLR)

Neural Information Processing Systems (NeurIPS)

Transactions on Pattern Analysis and Machine Intelligence (TPAMI)

ECCV European Conference on Computer Vision

Symposium on Geometry Processing (SGP)

ACM SIGGRAPH

ACM Transactions on Graphics (TOG)

SIGGRAPH Asia

Honors & Awards

Co-written and awarded Huawei Research Grant 2024
MCM scholarship, Indian Institute of Technology, Roorkee 2012-2014
IMPPRS MS scholarship, International Max Planck Research Schools 2016

Skills

Programming Python, MATLAB, C++

Frameworks NumPy, Pandas, PyTorch, SciPy, TensorFlow

Toolbox Linux, emacs, org, git, tmux, zsh