

# DYNAMIC PARTIAL AWARENESS

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- ✦ Awareness is a pervasive form of ignorance:
- ✦ An agent is unaware of an object/event/statement/etc if it is *not on her radar screen*

Existing models have difficulties with:

- ❖ Awareness of Unawareness:

“I know I am unaware of current research in immunological oncology.”

- ❖ Partial Awareness:

“I am aware of bitcoin but do not fully understand it.”

- ❖ Growing Awareness:

“I just discovered quantum computing, and it makes me re-evaluate cyber security.”

## Why do we care?

- ❖ More realistic/nuanced representation of ignorance.
- ❖ Agents who reason about their own limitations, may take actions to temper exposure to unawareness
  - ❖ Motivate learning, preference for the well understood
- ❖ Has important implications in economic markets:
  - ❖ Incomplete contracting, over-confidence, context-dependent preferences, &c.

This talk:

1. Develop a formal model of partial awareness.
  - ❖ Modal logic extending Halpern Rego (2009, 2013).
2. Considers what happens when agents become more aware
  - ❖ How do the agent's beliefs change
  - ❖ Becoming aware is in-and-of-itself informative

The language has three building blocks:

1. objects
2. properties: unary predicates
3. concepts: Boolean combination of properties

In each state (possible world), each agent is aware of a subset of objects, properties, and concepts.

The logic also has two modalities:

- ❖  $A_i\varphi$ : agent  $i$  is **aware** of the formula  $\varphi$
- ❖  $K_i\varphi$ : agent  $i$  **explicitly knows** formula  $\varphi$ .
  - ❖ Read:  $\varphi$  is true at all possible worlds and  $A_i\varphi$

Suppose a quantum computer ( $Q$ ) is defined as a computer ( $C$ ) that possesses an additional “quantum property”  $QP$ .

$$Q := C \wedge QP$$

1. A *partially aware* agent is aware of  $Q$  but unaware of the specific Boolean combination of properties that characterizes it.
2. A *fully unaware* agent is unaware of even the concept of a quantum computer
3. A *fully aware* agent is aware of both the concept of a quantum computer and also what it means to be one, i.e., the properties  $C$  and  $QP$ .



We capture introspection via quantification (over both objects and properties).

$$\spadesuit K_i \left( \exists P \forall x (Q(x) \Leftrightarrow C(x) \wedge P(x) \wedge \neg A_i P(x)) \right)$$

- $\spadesuit$  Although the agent is unaware of  $QP$ , she knows something about  $Q$  (quantum computers): she knows that they're computers that satisfy some extra property  $P$ .

$$\spadesuit K_i \left( \forall P \forall x ((Q(x) \Leftrightarrow C(x) \wedge P(x)) \Rightarrow (P(x) \Rightarrow R(x))) \right)$$

- $\spadesuit$  She can even reason about this property.

So what is the limitation imposed by (partial) unawareness?

- ❖ “Shadow predicates” cannot be expressed.
- ❖ Limits information exchange.

## Syntax

The syntax of our logic has the following building blocks:

- ❖ A countable set  $\mathcal{O}$  of constant symbols, representing objects. Following Levesque (1990),  $\mathcal{O}$  consists of *standard names*  $d_1, d_2, \dots$ .
- ❖ A countably infinite set  $\mathcal{V}^{\mathcal{O}}$  of object variables, which range over objects.
- ❖ A countable set  $\mathcal{P}$  of unary predicate symbols.
- ❖ A countably infinite set  $\mathcal{V}^{\mathcal{P}}$  of predicate variables.
- ❖ A countable set  $\mathcal{C}$  of concept symbols.

If  $d \in \mathcal{O}$ ,  $x \in \mathcal{V}^{\mathcal{O}}$ ,  $P \in \mathcal{P}$ ,  $Y \in \mathcal{V}^{\mathcal{P}}$ , and  $C \in \mathcal{C}$ , then  $P(d)$ ,  $P(x)$ ,  $Y(d)$ ,  $Y(x)$ ,  $C(d)$ , and  $C(x)$  are *atomic formulas*.

Our language  $\mathcal{L}(\mathcal{O}, \mathcal{P}, \mathcal{C})$  is the closure under

- conjunction and negation
- quantification over objects and over unary predicates,
  - if  $\varphi$  is a formula,  $x \in \mathcal{V}^{\mathcal{O}}$ , and  $Y \in \mathcal{V}^{\mathcal{P}}$ , then so are  $\forall x\varphi$  and  $\forall Y\varphi$ .
- the modal operators  $A_1, \dots, A_n$  and  $K_1, \dots, K_n$ ,
  - representing awareness and (explicit) knowledge.
  - if  $\varphi$  is a formula, then so are  $A_i\varphi$  and  $K_i\varphi$ .

# Semantics

- ❖  $\Omega$  of possible *states*.
- ❖ each state  $\omega$  is associated with a language. Formally, there is a function  $\Phi$  on states such that  $\Phi(\omega) = (\mathcal{O}_\omega, \mathcal{P}_\omega, \mathcal{C}_\omega)$
- ❖ we take the domain  $D$  to be the standard names in  $\mathcal{O}$ .
- ❖ a binary relation  $\mathcal{K}_i$  on states; states  $i$  considers possible.
- ❖ an awareness set  $\mathcal{A}_i(\omega) \subseteq \Phi(\omega)$ , the symbols  $i$  is aware of.

An interpretation  $I$ : for each state  $\omega$ , we have a function  $I_\omega$ :

- ✧ taking  $\mathcal{O}$  to elements of the domain  $D$ , standard names are mapped to themselves, so that  $I_\omega(d_i) = d_i$ .
- ✧  $\mathcal{P}$  to subsets of  $D$ ,
- ✧  $\mathcal{C}$  to  $\mathcal{L}^{bc}(\Phi(\omega))$ , Boolean combinations of properties (i.e., predicates).

The truth of a sentences at a state  $\omega$  in

$$M = (\Omega, D, \Phi, \mathcal{A}_1 \dots, \mathcal{A}_n, \mathcal{K}_1, \dots, \mathcal{K}_n, I)$$

are defined as usual .

Of interest:

- ✧  $(M, \omega) \models C(d)$  iff  $(M, \omega) \models C_\omega^I(d)$ ,
- ✧  $(M, \omega) \models \forall Y \varphi$  iff  $(M, \omega) \models \varphi[Y/\psi]$ , where  $\psi \in \mathcal{L}^{bc}$
- ✧  $(M, \omega) \models A_i \varphi$  iff  $\varphi \in \mathcal{L}(\mathcal{A}_i(\omega))$ ,
- ✧  $(M, \omega) \models K_i \varphi$  iff  $(M, \omega) \models A_i \varphi$  and  $(M, \omega') \models \varphi$  for all  $\omega' \in \mathcal{K}_i(\omega)$ .

We assume agents know what they are aware of:

• if  $(\omega, \omega') \in \mathcal{K}_i$ , then  $\mathcal{A}_i(\omega) = \mathcal{A}_i(\omega')$

and  $\mathcal{K}_i$  is an equivalence relation, and thus partitions the states in  $\Omega$ .



Why different languages at different states? Otherwise:

$$(\neg K_i \neg \forall P(A_i P(d))) \Rightarrow K_i \forall P(A_i P(d))$$

Because different languages at different states:

- ✧  $\varphi$  is true at  $\omega$  only if it is expressible at  $\omega$ .

- ✧ Non-standard notion of validity:

- ✧  $\varphi$  is *valid* in  $M$  if  $(M, \omega) \models \varphi$  for all  $\omega \in \Omega$  such that  $\varphi \in \mathcal{L}(\Phi(\omega))$ .

How do beliefs change as awareness changes?

- ❖ Becoming aware of  $\varphi$  is informative
- ❖ Ex. playing a game with an irrational opponent
  - ❖ Become aware of a new rule (without knowing what the rule specifies)
  - ❖ More likely the opponent is rational

The state space  $\Omega$  is God's state-space. The 'objective' view of the world.

But the agent's view is limited by her own language.

An event  $E \subseteq \Omega$  is  $\omega$ -**conceivable** if there is a sentence  $\varphi$  such that

1. The agent is aware of  $\varphi$  at  $\omega$ .
2.  $\varphi$  is true exactly on  $E$ .

Under basic regularity conditions

$$\Sigma_\omega = \{E \subseteq \Omega \mid E \text{ is } \omega\text{-conceivable}\}$$

is a  $\sigma$ -algebra on  $\Omega$ .

A modeler can obtain a subjective probability  $\pi \in \Delta(\Omega, \Sigma_\omega)$

- ✦ Use bets on the truth of  $\varphi$  (usual decision theory).
- ✦ Only consider sentences the agent is already aware of.
- ✦ The support of  $\pi$  is  $\mathcal{K}(\omega)$ .

Now what happens when the agent becomes more aware, e.g., of a new property  $P$ .

- ❖ Her language gets richer
  - ❖ Implies: She might be able to differentiate new states
- ❖ She learns that she used to be unaware of whatever she discovered
  - ❖ Implies: she might condition her beliefs

Formally: becoming aware of  $\varphi$  changes the model from  $M$  to  $M^{[\varphi]}$ :

- The 'physical' properties of the states do not change:  
 $\Omega = \Omega^{[\varphi]}$ , and  $P(d)$  is true at  $\omega$  if and only if it is true at  $\omega^{[\varphi]}$ .
- The agent becomes aware of all the symbols in  $\varphi$

$$\mathcal{A}^{[\varphi]}(\omega) = \mathcal{A}(\omega) \cup \text{SYM}(\varphi)$$

- The agent learns she was unaware of  $\varphi$ :

$$\mathcal{K}^{[\varphi]}(\omega^{[\varphi]}) = \mathcal{K}(\omega) \cap \{\omega \mid \text{the agent could have been unaware of } \varphi\}$$



Say  $\pi_0$  is ex-ante probability and  $\pi_1$  is ex-post (the agent becomes aware of  $\varphi$ ):

- ✧  $\Sigma_\omega \subseteq \Sigma_\omega^{[\varphi]}$  (can differentiate new states)
- ✧  $\text{supp}(\pi_1) \subseteq \text{supp}(\pi_0)$  ('condition' her beliefs).

Bayes' rule states  $\pi_1(E) = \frac{\pi_0(E \cap \text{supp}(\pi_1))}{\pi_0(\text{supp}(\pi_1))}$ , but what if  $\text{supp}(\pi_1) \not\subseteq \Sigma_\omega$ ?

## Theorem.

If for all  $E, E' \in \Sigma_\omega$  with  $E, E' \subseteq \text{supp}(\pi_1)$ , we have

$$\frac{\pi_0(E)}{\pi_0(E')} = \frac{\pi_1(E)}{\pi_1(E')}$$

and  $\pi_0(E) \leq \pi_1(E)$  then it is as if  $\pi_1$  is a conditional distribution of  $\pi_0$ .

- There exists a  $\pi^* \in \Delta(\Omega, \Sigma_\omega^{[\varphi]})$  such that  $\pi^*$  is an extension of  $\pi_0$  and

$$\pi_1(E) = \frac{\pi^*(E \cap \text{supp}(\pi_1))}{\pi^*(\text{supp}(\pi_1))}$$

Hence the model:

- ✦ Allows for growing awareness to change beliefs about previously describable events
  - ✦ Has testable predictions
- ✦ This is in juxtaposition to Karni and Viero (2015) and Dominiak and Tserenjigmid (2019)