Day 24

```
In [1]:
         import numpy as np
         import matplotlib.pyplot as plt
         import seaborn as sns
In [2]:
         sns.set_theme()
In [3]:
         ti = np.linspace(0,10,100001)
In [4]:
         def vin(ti): return(np.floor(2*ti)%2*-2+1)
In [5]:
         fig0, ax0 = plt.subplots()
         ax0.plot(ti, vin(ti))
Out[5]: [<matplotlib.lines.Line2D at 0x7ff9ad6b11d0>]
In [8]:
         # Runge-Kutta 4nd order
         def f(vout,t):
             return(1/.01*(vin(t)-vout))
         # define boundary conditions
         a = 0.0 # starting point
         b = 10.0 # ending point
         N = 100000 # number of points between a and b
         dt = (b-a)/N
         x = 0.0 # initial condition
         tpoints = np.arange(a, b, dt)
         xpoints = []
         for t in tpoints:
             xpoints.append(x)
             k1 = dt*f(x,t)
             k2 = dt*f(x+0.5*k1,t+0.5*dt)
             k3 = dt*f(x+0.5*k2,t+0.5*dt)
             k4 = dt*f(x+k3, t+dt)
             x = x + (k1+2*k2+2*k3+k4)/6
In [9]:
         fig1, ax1 = plt.subplots()
         ax1.plot(tpoints, vin(tpoints))
         ax1.plot(tpoints, xpoints)
Out[9]: [<matplotlib.lines.Line2D at 0x7ff9ac281358>]
```

Now do the above plot, but use a Sin wave, and rather than adjust RC, instead adjust the frequency of the wave. See how the low pass filter lets low frequencies go but stifles higher frequencies.

```
In [14]: # Runge-Kutta 4nd order

def vin(t):
    f = 1
        return(np.sin(2*np.pi*f*t))

def f(vout,t):
        return(1/0.01*(vin(t)-vout))

# define boundary conditions

a = 0.0 # starting point
b = 1.0 # ending point
```

```
N = 100000 # number of points between a and b
           dt = (b-a)/N
           x = 0.0 # initial condition
           tpoints = np.arange(a, b, dt)
           xpoints = []
           for t in tpoints:
                xpoints.append(x)
               k1 = dt*f(x,t)

k2 = dt*f(x+0.5*k1,t+0.5*dt)
                k3 = dt*f(x+0.5*k2,t+0.5*dt)
               k4 = dt*f(x+k3, t+dt)
                x = x + (k1+2*k2+2*k3+k4)/6
In [15]: fig2, ax2 = plt.subplots()
           ax2.plot(tpoints[:100], vin(tpoints[:100]))
ax2.plot(tpoints[:100], xpoints[:100])
Out[15]: [<matplotlib.lines.Line2D at 0x7ff9ac452e80>]
In [16]:
           plt.close('all')
```

Loading [MathJax]/extensions/Safe.js

In []: