

VII.1 Numerics of spectral methods

Series expansion

- An infinite sequence of orthogonal functions $\{\phi_k\}$

$$f(x) = \sum_{k=-\infty}^{+\infty} \tilde{f}_k \phi_k \quad (7.1)$$

- Can the series be approximated by a few terms?
- Spectral accuracy: The k^{th} coefficient decays fast enough for $|k| \geq m$; m is not-a-very-large integer.
 - For periodic functions: Fourier series
 - For non-periodic functions: Chebyshev series, ...

VII.1 Numerics of spectral methods

The Fourier system

→ Lecture: 7.1.1

- Fourier series expansion:

$$Sf = \sum_{k=-\infty}^{+\infty} \tilde{f}_k \phi_k = \sum_{k=-\infty}^{+\infty} \tilde{f}_k e^{ikx} = f(x) \quad (7.5)$$

Wave number
 ↓
 Fourier coefficient Fourier mode

- Fourier transform:

$$\tilde{f}_k = \frac{1}{2\pi} \int_0^{2\pi} f(x) e^{-ikx} dx = \mathcal{F}\{f(x)\} \quad (7.6)$$

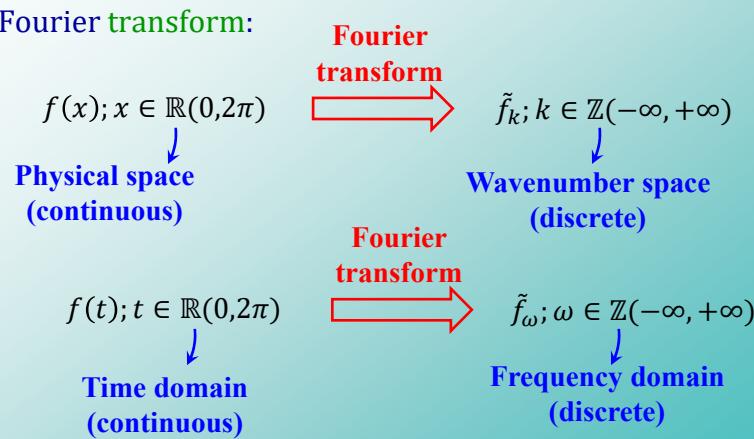
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VII.1 Numerics of spectral methods

The Fourier system

- Fourier transform:



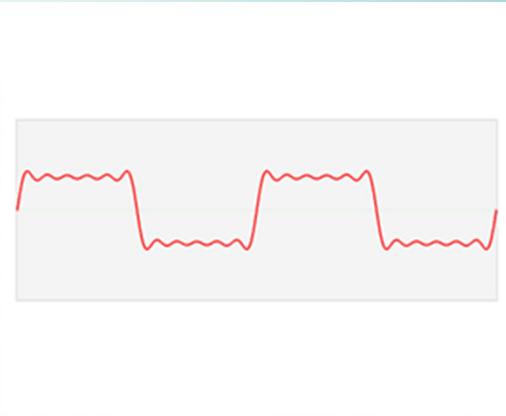
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The Fourier system

Fourier transform decomposes a function into different modes; waves of different wavenumbers and amplitudes. ►

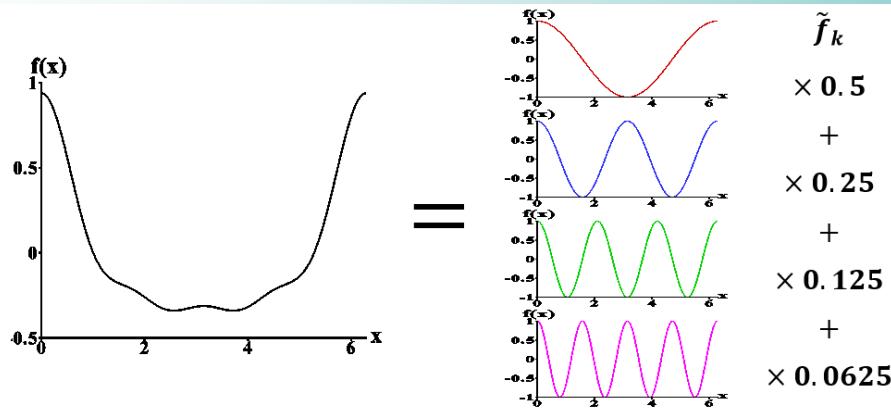


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The Fourier system



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The Fourier system

- An important property: If $f(x)$ is real-valued

$$\tilde{f}_{-k} = (\tilde{f}_k)^* \quad (7.7)$$

- Fourier cosine and sine transforms:

$$\begin{aligned}\tilde{a}_k &= \frac{1}{2\pi} \int_0^{2\pi} f(x) \cos(kx) dx \\ \tilde{b}_k &= \frac{1}{2\pi} \int_0^{2\pi} f(x) \sin(kx) dx\end{aligned}\quad (7.8)$$

- Relation between Fourier transforms:

$$\tilde{f}_k = \tilde{a}_k - i\tilde{b}_k \quad (7.9)$$

- For a **smooth** periodic function, the Fourier series expansion possesses the “spectral accuracy” property

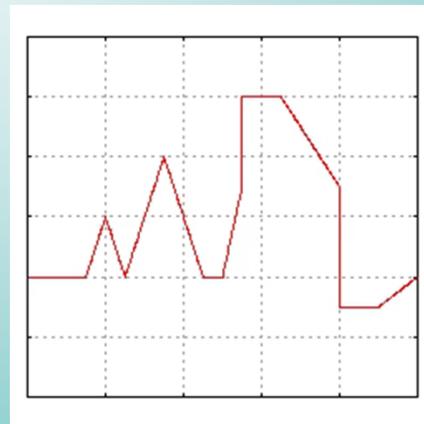
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VII.1 Numerics of spectral methods

The Fourier system

Fourier transform decomposes a function into different modes; waves of different wavenumbers and amplitudes. ►



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VII.1 Numerics of spectral methods

The Fourier system

- N^{th} -order truncated Fourier series:

$$P_N f = \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \tilde{f}_k e^{ikx} = f(x) + T_N \quad (7.10)$$

Truncation error

$$\tilde{f}_k = \frac{1}{2\pi} \int_0^{2\pi} f(x) e^{-ikx} dx = \mathcal{F}\{f(x)\}$$

- What if the values of $f(x)$ are known at discrete points (a computational grid) rather than $x \in \mathbb{R}(0,2\pi)$?

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VII.1 Numerics of spectral methods

Discrete Fourier series

➡ Lecture Notes: 7.1.2

- The discrete Fourier series:

$$I_N f(x_j) = \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \hat{f}_k e^{ikx_j} = f(x_j) = f_j \quad j = 0, 1, 2, \dots, N-1 \quad (7.12)$$

↓
Discrete Fourier coefficient

- The Discrete Fourier Transform (DFT):

$$\hat{f}_k = \frac{1}{N} \sum_{j=0}^{N-1} f_j e^{-ikx_j} = \mathcal{F}_N\{f_j\} \quad k = -\frac{N}{2}, \dots, \frac{N}{2}-1 \quad (7.15)$$

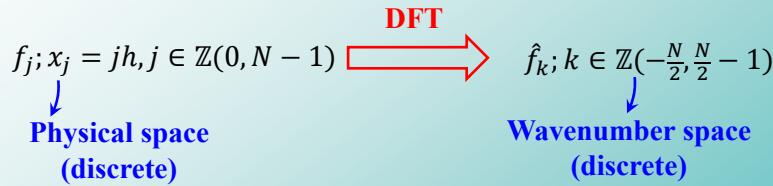
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Discrete Fourier series

- DFT:



- An important property: If $f(x)$ is real-valued

$$\hat{f}_{-k} = (\hat{f}_k)^* \quad (7.16)$$

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VII.1 Numerics of spectral methods

Discrete Fourier series

- Extension to general case of period length L :

- #### ➤ Base function definition:

$$\phi(x) = e^{i\frac{(2\pi)}{L}kx} \quad (7.17)$$

- It can be shown that all previous relations are valid, replacing π with L , and k with $\left(\frac{2\pi}{L}\right)k$.

- For instance, in Eq. (7.12):

$$x_j = jh = j \left(\frac{L}{N} \right);$$

$$f_j = \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \hat{f}_k e^{i\left(\frac{2\pi}{L}\right)kj\left(\frac{L}{N}\right)} = \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \hat{f}_k e^{ik\overbrace{\left(\frac{2\pi}{N}\right)j}}$$

Like when $x_j \in \mathbb{R}(0, 2\pi)$

This is why DFT is attractive

subroutines do not get L

Like when $x_i \in \mathbb{R}(0,2\pi)$

Like when $x_j \in \mathbb{R}(0, \angle\pi)$

$$\cdot \cdot \cdot \underbrace{a_n}_{\sim (2\pi)};$$

$$\hat{f}_k e^{ik\left(\frac{2\pi}{N}\right)j}$$

$$f_k e^{\imath \kappa(\frac{N}{N}) j}$$

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Discrete Fourier series

- Extension to general case of period length L :
 - Eqs. (7.12) and (7.15) are valid for the period length L
 - For derivatives of f , a modification is required as will be shown later
- DFT requires $O(N^2)$ operations
- In practice, a more efficient algorithm, called Fast Fourier Transform (FFT), is incorporated in computations that reduces the computational cost to $O(N \log_2 N)$
- Suggested reading: [3] (sections 6.1-6.3)

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Aliasing

Aliasing error

- Image processing
 - moiré pattern



Reducing resolution



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Aliasing

Aliasing error

- Image processing
 - moiré pattern

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Aliasing

Aliasing error

- Numerical analysis
 - The discrete representation induces another error, called the aliasing error:

$$\begin{aligned} P_N f &= Sf + T_N \\ &= f(x) \quad \text{Truncation error} \end{aligned}$$

$$I_N f = P_N f + R_N = Sf + T_N + R_N \quad (7.18)$$

↙ Aliasing error

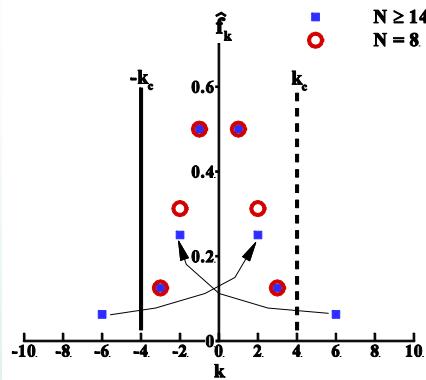
Lecture Notes: 7.1.4

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$$f(x) = \cos x + \frac{1}{2} \cos 2x + \frac{1}{4} \cos 3x + \frac{1}{8} \cos 6x$$



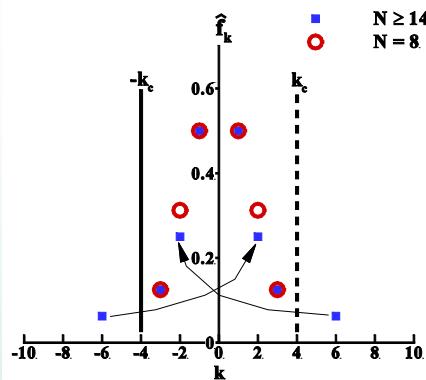
▲ Discrete Fourier coefficients of $f(x)$ on $N = 8$ grid and on a grid with $N \geq 14$.

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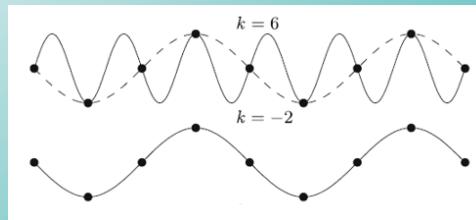
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$$f(x) = \cos x + \frac{1}{2} \cos 2x + \frac{1}{4} \cos 3x + \frac{1}{8} \cos 6x$$

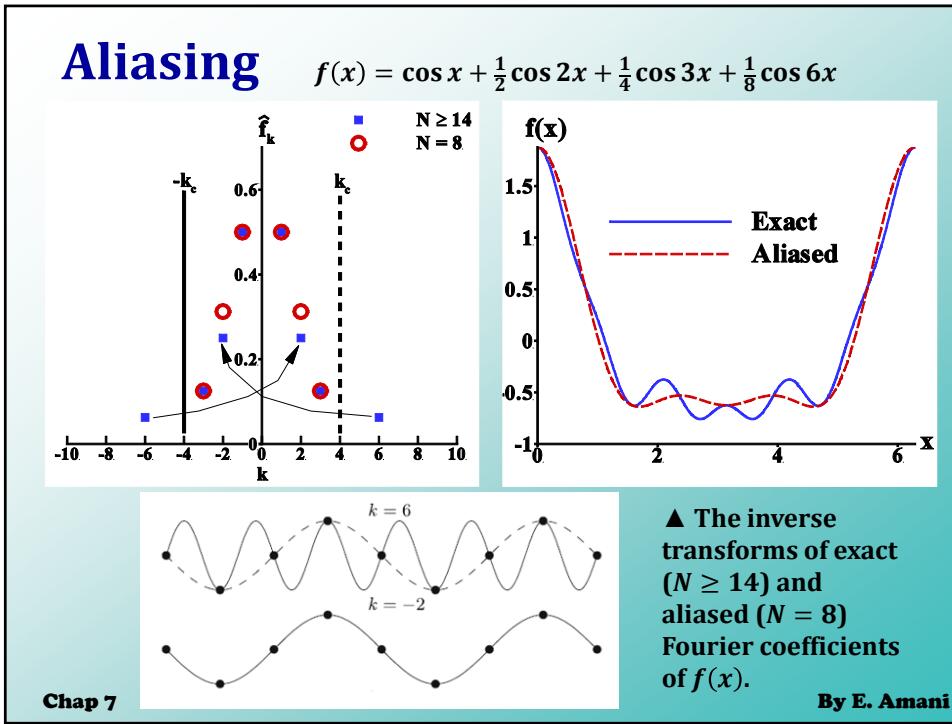


on $N = 8$ grid, the modes $k = 6$ and $k = -2$ are indistinguishable. ►



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Aliasing

Aliasing error

- The aliasing error is of N^{th} order and can be omitted in the conventional discretization schemes
- In spectral discretization, the aliasing error can contaminate the solution in the presence of non-linear terms and have to be controlled.
- In general, all modes k' ($|k'| > \frac{N}{2}$) alias the mode k ($|k| \leq \frac{N}{2}$) where:

$$k' + mN = k; \quad m = \pm 1, \pm 2, \dots$$

- Proof: See file "chap7-proofs.pdf"
- In the previous example:

$$-6 + 1 \times 8 = 2$$

$$+6 + (-1) \times 8 = -2$$

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Aliasing

Discrete Fourier transform of a product

- The simplest non-linear case: $H(x) = f(x)g(x)$
- Example: Consider $f(x) = \sin(2x)$ and $g(x) = \sin(3x)$ on a grid $N = 8$.

➢ Each function is represented on $N = 8$ grid without aliasing:

$$|k| = 2 < \frac{8}{2} = 4: \hat{f}_k = \begin{cases} -i/2 & ; k = 2 \\ +i/2 & ; k = -2 \\ 0 & ; \text{otherwise} \end{cases}$$

$$|k| = 3 < \frac{8}{2} = 4: \hat{g}_k = \begin{cases} -i/2 & ; k = 3 \\ +i/2 & ; k = -3 \\ 0 & ; \text{otherwise} \end{cases}$$

➢ Using the trigonometric relation:

$$H(x) = f(x)g(x) = \sin(2x)\sin(3x) = 0.5[\cos(x) - \cos(5x)]$$

➢ The product cannot be presented on $N = 8$ grid and generates aliasing error. $|k| = 5 > \frac{8}{2} = 4$

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Discrete Fourier transform of a product

- The convolution sum (proof: "chap7-proofs.pdf"):

$$\hat{H}_m = \sum_{\substack{k=-\frac{N}{2} \\ |m-k|\leq \frac{N}{2}}}^{\frac{N}{2}-1} \hat{f}_k \hat{g}_{m-k} \quad m = -\frac{N}{2}, \dots, \frac{N}{2} - 1 \quad (7.22)$$

- Needs $O(N^2)$ operations
- More efficient algorithms?

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Aliasing

Pseudo-spectral transform – padding method

- Requires $O(N \log_2 N)$ operations
- Uses more grid points $M = 3N/2$ temporarily to avoid aliasing
- Philosophy: Using a finer grid, allowing the high wavenumbers generated by the non-linearity to appear and not to alias the modes with $|k| \leq N/2$. Then, these high wavenumbers are filtered out.
- Steps:

1. Transform \hat{f}_k and \hat{g}_k to physical space on M grid nodes using inverse FFT:

$$M = 2N: \quad -\frac{M}{2}, \dots, -\frac{N}{2}, \dots, \frac{N}{2} - 1, \dots, \frac{M}{2} - 1 \quad \xrightarrow{\text{Inverse FFT}} \quad f_j, g_j \quad j = 0, 1, \dots, M - 1$$

$\hat{f}_k = \hat{g}_k = 0$ $\hat{f}_k = \hat{g}_k = 0$

(Nyquist is set to zero)

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Pseudo-spectral transform – padding method

- Requires $O(N \log_2 N)$ operations
- Uses more grid points $M = 3N/2$ temporarily to avoid aliasing
- Steps:
 1. Transform \hat{f}_k and \hat{g}_k to physical space on M grid nodes using inverse FFT
 2. Compute H_j on the fine grid:

$$H_j = f_j g_j \quad ; j = 0, 1, \dots, M - 1$$

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Pseudo-spectral transform – padding method

- Requires $O(N \log_2 N)$ operations
- Uses more grid points $M = 3N/2$ temporarily to avoid aliasing
- Steps:
 1. Transform \hat{f}_k and \hat{g}_k to physical space on M grid nodes using inverse FFT
 2. Compute H_j on the fine grid
 3. Compute \hat{H}_k using FFT:

$$\begin{array}{ccc} H_j & \xrightarrow{\text{FFT}} & \hat{H}_k \\ j = 0, 1, \dots, M-1 & & k = -\frac{M}{2}, \dots, \frac{M}{2}-1 \end{array}$$

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Aliasing

Pseudo-spectral transform – padding method

- Requires $O(N \log_2 N)$ operations
- Uses more grid points $M = 3N/2$ temporarily to avoid aliasing
- Steps:
 1. Transform \hat{f}_k and \hat{g}_k to physical space on M grid nodes using inverse FFT
 2. Compute H_j on the fine grid
 3. Compute \hat{H}_k using FFT
 4. Keep \hat{H}_k on the coarse grid and discard the others:

$$\hat{H}_k: k = -\frac{M}{2}, \dots, -\frac{N}{2}, \dots, \frac{N}{2}-1, \dots, \frac{M}{2}-1$$

Now these frequencies include aliasing error
(discarded)

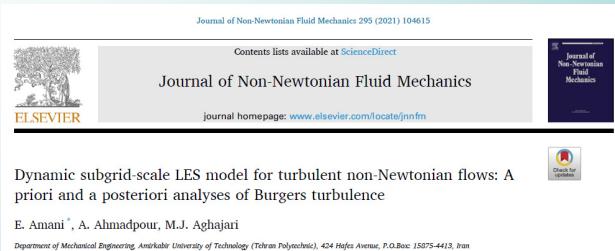
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DeAliasing of non-linear terms

- DNS of turbulent power-law fluid flows



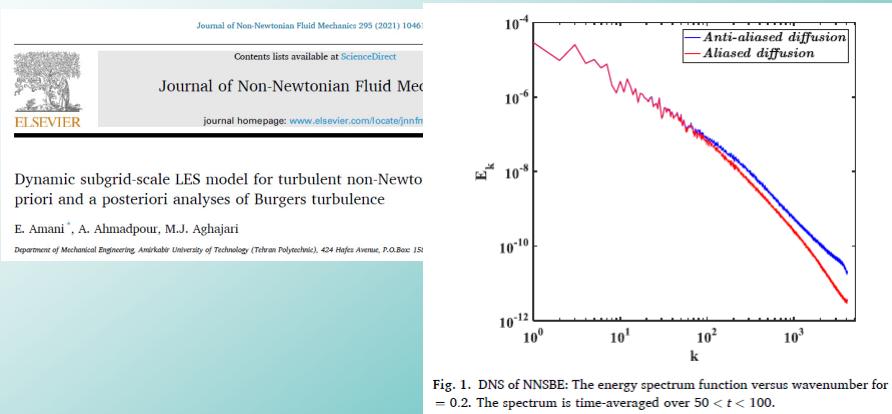
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DeAliasing of non-linear terms

- DNS of turbulent power-law fluid flows



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VII.1 Numerics of spectral methods

Transform of derivatives

 **Lecture Notes: 7.1.7**

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VII.1 Numerics of spectral methods

Higher dimensions

- $f(x, y)$ which is periodic in x or y is treated like before, the dependence on the other variable is implied.
- $f(x, y)$ which is periodic in both x and y (two-time Fourier transforming):

$$f_{m,l} = f(x_m, y_l) = \sum_{k_1=-\frac{N_1}{2}}^{\frac{N_1}{2}-1} \sum_{k_2=-\frac{N_2}{2}}^{\frac{N_2}{2}-1} \hat{f}_{k_1, k_2} e^{ik_1 x_m} e^{ik_2 y_l} \quad m = 0, 1, \dots, N_1 - 1 \\ l = 0, 1, \dots, N_2 - 1 \quad (7.27)$$

$$\hat{f}_{k_1, k_2} = \frac{1}{N_1 N_2} \sum_{m=0}^{N_1-1} \sum_{l=0}^{N_2-1} f_{m,l} e^{-ik_1 x_m} e^{-ik_2 y_l} \quad k_1 = -\frac{N_1}{2}, \dots, \frac{N_1}{2} - 1 \\ k_2 = -\frac{N_2}{2}, \dots, \frac{N_2}{2} - 1 \quad (7.28)$$

- For real-valued f :

$$\hat{f}_{-k_1, -k_2} = (\hat{f}_{k_1, k_2})^* \quad (7.29) \quad \text{By E. Amani}$$

VII.1 Numerics of spectral methods

Higher dimensions

- In three dimensions, and for a vector quantity:

$$\vec{f}(\vec{x}) = \sum_{\vec{k}} \hat{f}_{\vec{k}} e^{i\vec{k}\cdot\vec{x}} \quad (7.30)$$

$$\begin{aligned} \vec{x} &= (x_1, x_2, x_3) = x_i \hat{e}_i \\ \vec{k} &= (k_1, k_2, k_3) = k_i \hat{e}_i \quad (7.31) \\ \sum_{\vec{k}} &\rightarrow \sum_{k_1} \sum_{k_2} \sum_{k_3} \end{aligned}$$

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VII.1 Numerics of spectral methods

Numerical solution of differential equations

- Linear advection-diffusion equation:

 [Lecture Notes: 7.1.8](#)

- Non-linear Burgers equation

 [Lecture Notes: 7.1.9](#)

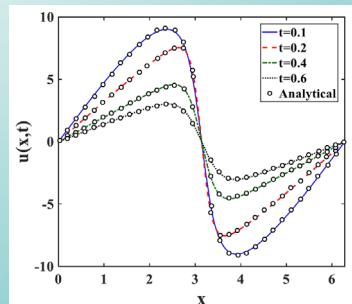
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Hands-on practice

• HW#5:

- Using “pyBurgers.py” and python FFT packages for numerical analysis
- Solving linear and non-linear equations using spectral methods
- Comparing spectral and conventional 2nd- and 4th-order finite difference solutions



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Project#2: *A posteriori* study

1D Stochastic Forced Burgers Equation (1DFSBE)

- Energy spectrum (you can do Q11)

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VII.2 Spectral description of turbulence

Fourier series representation

- The velocity field is periodic in a box of length $L > L_{11}$:

$$\vec{U}(\vec{x}, t) = \vec{U}(\vec{x} + \vec{N}L, t)$$

 Integer vector

$$\vec{N} = n_1 \hat{e}_1 + n_2 \hat{e}_2 + n_3 \hat{e}_3 = n_i \hat{e}_i$$

- Using Eqs. (7.5) and (7.30)

$$\vec{U}(\vec{x}, t) = \sum_{\vec{k}} \vec{U}(\vec{k}, t) e^{i\vec{k}\cdot\vec{x}} \quad (7.44)$$

$$\vec{x} = x_i \hat{e}_i \quad \vec{k} = \frac{2\pi}{L} \vec{N} = \frac{2\pi}{L} n_i \hat{e}_i, n_i = 0, \pm 1, \dots, \pm \infty \quad (7.45)$$

 Wavenumber vector $k = |\vec{k}|$

- Note: In section VII.2, the notation \tilde{U} is used instead of \vec{U} , to be consistent with reference [1]

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VII.2 Spectral description of turbulence

Fourier series representation

- Note: For non-periodic cases, the wavenumber space becomes continuous:

$$L \rightarrow \infty; \Delta k = k_{i,n+1} - k_{i,n} = \frac{2\pi}{L} \rightarrow 0$$

- The volume-averaging operator over the cube $0 \leq x_i \leq L$:

$$\langle \vec{f}(\vec{x}) \rangle_L = \frac{1}{L^3} \int_0^L \int_0^L \int_0^L \vec{f}(\vec{x}) dx_1 dx_2 dx_3 \quad (7.46)$$

- The orthogonality property:

$$\langle e^{i\vec{k}\cdot\vec{x}} e^{-i\vec{k}'\cdot\vec{x}} \rangle_L = \delta_{\vec{k}, \vec{k}'} \quad (7.47)$$

- Exercise: Using Eq. (7.4) (replacing 2π with L) verify Eq. (7.47)

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VII.2 Spectral description of turbulence

Fourier series representation

- Using the orthogonality property, Eq. (7.47), the Fourier coefficients are obtained as:

$$\vec{U}(\vec{k}, t) \equiv \mathcal{F}_L\{\vec{U}(\vec{x}, t)\} = \left\langle \vec{U}(\vec{x}, t) e^{-i\vec{k}\cdot\vec{x}} \right\rangle_L = \frac{1}{L^3} \iiint_0^L \vec{U}(\vec{x}, t) e^{-i\vec{k}\cdot\vec{x}} dx_1 dx_2 dx_3 \quad (7.48)$$

- Hereafter, the dependence on t is implied.

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VII.2 Spectral description of turbulence

Fourier series representation

- Exercise:** Prove the following relations:

$$\hat{A}(\vec{k}) \equiv \mathcal{F}_L\{\vec{A}(\vec{x})\} \quad \vec{A} \rightarrow \text{Scalar, vector, or tensor}$$

$$\hat{A}(-\vec{k}) \equiv \hat{A}^*(\vec{k}) \quad \text{Each component of } \hat{A}^* \text{ is the complex conjugate of the same component of } \hat{A}$$

$$\mathcal{F}_L\left\{\frac{\partial \hat{A}(\vec{x})}{\partial x_j}\right\} = ik_j \hat{A}(\vec{k})$$

$$\mathcal{F}_L\{\vec{\nabla} \cdot \hat{A}(\vec{x})\} = i\vec{k} \cdot \hat{A}(\vec{k}) \quad \mathcal{F}_L\{\vec{\nabla} \times \hat{A}(\vec{x})\} = i\vec{k} \times \hat{A}(\vec{k})$$

$$\mathcal{F}_L\{\nabla^2 \hat{A}(\vec{x})\} = -k^2 \hat{A}(\vec{k}) \quad \mathcal{F}_L\{\vec{\nabla} \hat{A}(\vec{x})\} = i\vec{k} \hat{A}(\vec{k})$$

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VII.2 Spectral description of turbulence

The Navier-Stokes equations in the Fourier space

→ **Lecture Notes: 7.2.2**

The kinetic energy of Fourier modes

→ **Lecture Notes: 7.2.3**

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VII.2 Spectral description of turbulence

The energy spectrum function

- Theoretical turbulence literature: Integral Fourier transform

$$\vec{U}(\vec{k}) \equiv \mathcal{F}\{\vec{U}(\vec{x})\} = \frac{1}{(2\pi)^3} \iiint_{-\infty}^{+\infty} \vec{U}(\vec{x}) e^{-i\vec{k} \cdot \vec{x}} d\vec{x} \quad (7.71)$$

$$\vec{U}(\vec{x}) = \mathcal{F}^{-1}\{\vec{U}(\vec{k})\} = \iiint_{-\infty}^{+\infty} \vec{U}(\vec{k}) e^{i\vec{k} \cdot \vec{x}} d\vec{k} \quad (7.72)$$

- Non-periodic function, continuous real-valued wavenumber component k_i

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VII.2 Spectral description of turbulence

The energy spectrum function

- For flow in a finite domain $D \in L^3$, both \mathcal{F} and \mathcal{F}_L can be defined.
- \mathcal{F} is usually used in theoretical discussions
- \mathcal{F}_L is usually used in numerical calculations
- The relation between \mathcal{F} and \mathcal{F}_L (proof: Lesieur, Turbulence in fluids, section 5.1):

$$\text{continuous} \quad \vec{U}(\vec{k}) = \sum_{\vec{k}'} \delta(\vec{k} - \vec{k}') \vec{U}(\vec{k}') \quad (7.72)' \\ \mathcal{F}\{\vec{U}(\vec{x})\} \quad \text{discrete} \quad \mathcal{F}_L\{\vec{U}(\vec{x})\}$$

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VII.2 Spectral description of turbulence

The energy spectrum function

- A unified energy spectrum function for periodic and non-periodic cases:

$$E(k) = \sum_{\vec{k}'} \delta(k' - k) \hat{E}(\vec{k}') \quad (7.80)'$$

- It can be shown that (proof: "chap7-proofs.pdf"):

Velocity spectrum function $\phi_{ij}(\vec{k}) \equiv \mathcal{F}\{R_{ij}(\vec{r})\} = \sum_{\vec{k}'} \delta(\vec{k} - \vec{k}') \hat{R}_{ij}(\vec{k}') \quad (7.73)'$

$$E(k) = \iiint_{-\infty}^{+\infty} \frac{1}{2} \phi_{ii}(\vec{k}') \delta(k' - k) d\vec{k}' \quad (7.81)$$

$$k = \int_0^\infty E(k) dk \quad (7.82) \quad \varepsilon = \int_0^\infty 2\nu k^2 E(k) dk \quad (7.83)$$

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VII.2 Spectral description of turbulence

Kolmogorov spectra

- The first similarity hypothesis (for scales $l \ll l_0 \sim \eta$ or $l < l_{EI} \sim \frac{1}{6}L_{11}$):



$$E(k) = f(k, \varepsilon, v); \quad k \gg k_0 = \frac{2\pi}{l_0} \text{ or } k > k_{EI} = \frac{2\pi}{l_{EI}}$$

- Exercise: knowing $\eta = (\nu^3/\varepsilon)^{1/4}$ and using a dimensional analysis, show that:

$$E(k) = (\varepsilon v^5)^{1/4} \varphi(k\eta) \quad k > k_{EI} \quad (7.91) \quad \text{or} \quad E(k) = \varepsilon^{2/3} k^{-5/3} \psi(k\eta) \quad k > k_{EI} \quad (7.92)$$

Kolmogorov spectrum function

compensated Kolmogorov spectrum function

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$$\psi(k\eta) = (k\eta)^{5/3} \varphi(k\eta)$$

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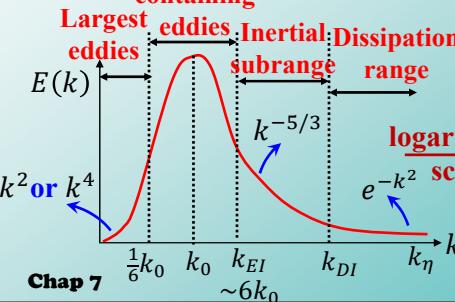
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Kolmogorov spectra

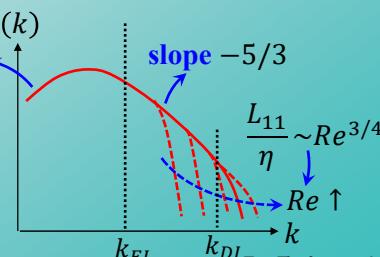
- The second similarity hypothesis (for scales $l_0 \ll l \ll \eta$ or $60\eta \sim l_{DI} < l < l_{EI}$):



Kolmogorov constant experiment: $E(k) = C \varepsilon^{2/3} k^{-5/3}$ (7.93) $k_0 \ll k \ll k_\eta = \frac{2\pi}{\eta}$ or $k_{EI} < k < k_{DI} = \frac{2\pi}{l_{DI}}$



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VII.2 Spectral description of turbulence

Kolmogorov spectra

- Pao's model spectrum:

$$E(k) = f_L(kL) C \varepsilon^{2/3} k^{-5/3} f_\eta(k\eta) \quad (7.94)$$

$$f_L(kL) = \left(\frac{kL}{[(kL)^2 + c_L]^{1/2}} \right)^{\frac{5}{3} + p_0} ; p_0 = 2 \text{ or } 4$$

$c_L = 6.78$

$$f_\eta(k\eta) = \exp(-\beta(k\eta)^{4/3}) \quad ; \beta = \frac{3}{2} C$$

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VII.3 LES in spectral space

Spectral representation of filtering

- Comparing Eq. (6.1) and Eq. (D.15) (appendix D [1]):

$$\mathcal{F}_L \{ \vec{\bar{U}}(\vec{x}) \} \xrightarrow{\text{Transfer function}} \widehat{\vec{U}}(\vec{k}) = \widehat{G}(\vec{k}) \widehat{\vec{U}}(\vec{k}) \xrightarrow{\mathcal{F}_L} \mathcal{F}_L \{ \vec{U}(\vec{x}) \} \quad (7.95)$$

$$\widehat{G}(\vec{k}) = L^3 \mathcal{F}_L \{ G(\vec{r}) \} = \iiint_0^L G(\vec{r}) e^{-i\vec{k} \cdot \vec{r}} d\vec{r}$$

- Note that:

$$\widehat{G}(0) = \iiint_0^L G(\vec{r}) d\vec{r} = 1 \quad (7.96)$$

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VII.3 LES in spectral space

Filter types

- The sharp spectral (cut-off) filter:

$$\hat{G}(\vec{k}) = H(k_c - |\vec{k}|) \quad (7.97)$$

Cut-off
wavenumber

- Isotropic
- Filter width: Number of modes

$$k_c = \frac{2\pi N_c}{L} = \pi \frac{N_c}{L} = \frac{\pi}{\Delta} \rightarrow \Delta = \frac{\pi}{k_c}$$

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Filter types

◀ Table 13.2 [1],
filters formula in
physical space

Name	Filter function	Transfer function
General	$G(r)$	$\hat{G}(\kappa) \equiv \int_{-\infty}^{\infty} e^{i\kappa r} G(r) dr$
Box	$\frac{1}{\Delta} H(\frac{1}{2}\Delta - r)$	$\frac{\sin(\frac{1}{2}\kappa\Delta)}{\frac{1}{2}\kappa\Delta}$
Gaussian	$\left(\frac{6}{\pi\Delta^2}\right)^{1/2} \exp\left(-\frac{6r^2}{\Delta^2}\right)$	$\exp\left(-\frac{\kappa^2\Delta^2}{24}\right)$
Sharp spectral	$\frac{\sin(\pi r/\Delta)}{\pi r}$	$H(\kappa_c - \kappa),$ $\kappa_c \equiv \pi/\Delta$
Cauchy	$\frac{a}{\pi\Delta[(r/\Delta)^2 + a^2]}, \quad a = \frac{\pi}{24}$	$\exp(-a\Delta \kappa)$
Pao		$\exp\left(-\frac{\pi^{2/3}}{24}(\Delta \kappa)^{4/3}\right)$

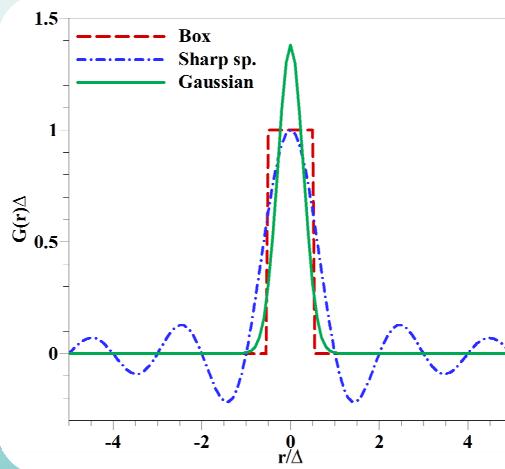
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VII.3 LES in spectral space

Filter types

Representation of filters in physical space. Solid line: Gaussian filter, dashed line: box filter, dash-dotted: sharp spectral filter.►

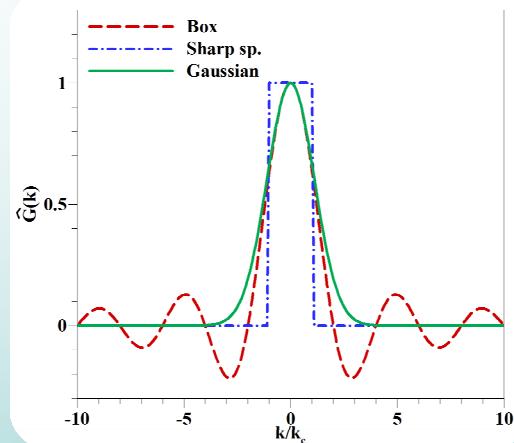


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VII.3 LES in spectral space

Filter types



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◀ Representation of filters in spectral space. Solid line: Gaussian filter, dashed line: box filter, dash-dotted: sharp spectral filter.

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VII.3 LES in spectral space

The filtered fluctuations and energy spectrum:

- Remember Resolved part Similarly

$$u_i \equiv U_i - \langle U_i \rangle \quad \bar{u}_i \equiv \bar{U}_i - \langle \bar{U}_i \rangle \quad (6.19)$$

$$R_{ij}(\vec{r}) \equiv \langle u_i(\vec{x}) u_j(\vec{x} + \vec{r}) \rangle \quad R_{ij}^R(\vec{r}) \equiv \langle \bar{u}_i(\vec{x}) \bar{u}_j(\vec{x} + \vec{r}) \rangle \quad (6.20)$$

$$\hat{R}_{ij}(\vec{k}) \equiv \mathcal{F}_L\{R_{ij}(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle \quad \hat{R}_{ij}^R(\vec{k}) \equiv \mathcal{F}_L\{R_{ij}^R(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle \quad (7.97)'$$

$$\phi_{ij}(\vec{k}) \equiv \mathcal{F}\{R_{ij}(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle \quad \phi_{ij}^R(\vec{k}) \equiv \mathcal{F}\{R_{ij}^R(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle$$

$$\hat{E}(\vec{k}) = \frac{1}{2} \hat{R}_{ii}(\vec{k}) \quad \hat{E}^R(\vec{k}) = \frac{1}{2} \hat{R}_{ii}^R(\vec{k}) \quad (7.97)''$$

$$E(k) = \sum_{\vec{k}'} \delta(k' - k) \hat{E}(\vec{k}') \quad E^R(k) = \sum_{\vec{k}'} \delta(k' - k) \hat{E}^R(\vec{k}') \quad (7.97)'''$$

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In Ref. [1], E^R is denoted by \bar{E}

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VII.3 LES in spectral space

The filtered fluctuations and energy spectrum:

- Remember Resolved part Similarly

$$u_i \equiv U_i - \langle U_i \rangle \quad \bar{u}_i \equiv \bar{U}_i - \langle \bar{U}_i \rangle \quad (6.19)$$

$$R_{ij}(\vec{r}) \equiv \langle u_i(\vec{x}) u_j(\vec{x} + \vec{r}) \rangle \quad R_{ij}^R(\vec{r}) \equiv \langle \bar{u}_i(\vec{x}) \bar{u}_j(\vec{x} + \vec{r}) \rangle \quad (6.20)$$

$$\hat{R}_{ij}(\vec{k}) \equiv \mathcal{F}_L\{R_{ij}(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle \quad \hat{R}_{ij}^R(\vec{k}) \equiv \mathcal{F}_L\{R_{ij}^R(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle \quad (7.97)'$$

$$\phi_{ij}(\vec{k}) \equiv \mathcal{F}\{R_{ij}(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle \quad \phi_{ij}^R(\vec{k}) \equiv \mathcal{F}\{R_{ij}^R(\vec{r})\} = \langle \hat{u}_i^*(\vec{k}) \hat{u}_j(\vec{k}) \rangle$$

$$\hat{E}(\vec{k}) = \frac{1}{2} \hat{R}_{ii}(\vec{k}) \quad \hat{E}^R(\vec{k}) = \frac{1}{2} \hat{R}_{ii}^R(\vec{k}) \quad (7.97)''$$

$$E(k) = \sum_{\vec{k}'} \delta(k' - k) \hat{E}(\vec{k}') \quad E^R(k) = \sum_{\vec{k}'} \delta(k' - k) \hat{E}^R(\vec{k}') \quad (7.97)'''$$

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 $k^R = \frac{1}{2} \langle \bar{u}_i \bar{u}_i \rangle = \int_0^\infty E^R(k) dk \quad (7.99)''$

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VII.3 LES in spectral space

The filtered fluctuations and energy spectrum:

- Exercise: For homogeneous flow and homogeneous filters, show that:

$$\hat{R}_{ij}^R(\vec{k}) = |\hat{G}(\vec{k})|^2 \hat{R}_{ij}(\vec{k}) = \hat{G}^2(\vec{k}) \hat{R}_{ij}(\vec{k}) \quad (7.98)^{(5)}$$

and for isotropic filter:

$$E^R(k) = \hat{G}^2(k) E(k) \quad (7.99)'$$

- Remember:

$$k^{SFS} = k - k^R \quad (6.50)$$

- Exercise: Show that:

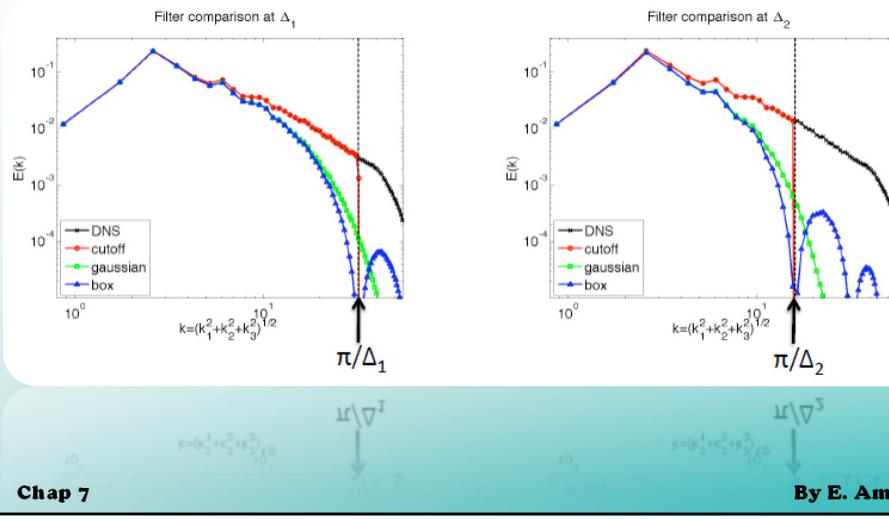
$$k^{SFS} = \int_0^\infty (1 - \hat{G}^2(k)) E(k) dk \quad (7.99)^{(4)}$$

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VII.3 LES in spectral space

Filtered energy spectrum



VII.3 LES in spectral space

Filtered equations

- Remember: Assuming a periodic velocity field of period length length L :

$$\frac{d\vec{U}(\vec{k})}{dt} + \nu k^2 \vec{U}(\vec{k}) = -\underline{P} \cdot \vec{G} \quad (7.57)$$

$$\underline{P} = \underline{I} - \frac{\vec{k}\vec{k}}{k^2} \quad (7.52) \quad (7.55)$$

$$\vec{G} = -i\vec{k} \cdot \sum_{\vec{k}'} \vec{U}(\vec{k}') \vec{U}(\vec{k} - \vec{k}') = -i\vec{k} \cdot \sum_{\vec{k}'} \sum_{\vec{k}''} \delta_{\vec{k}, \vec{k}' + \vec{k}''} \vec{U}(\vec{k}') \vec{U}(\vec{k}'')$$

- The pressure variable is removed and the continuity equation is decoupled in the spectral space
- Filtering in spectral space: The multiplication of Eq. (7.57) by the transfer function

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VII.3 LES in spectral space

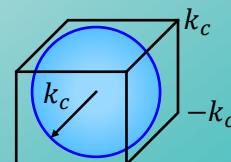
Filtered equations

- Assuming the isotropic sharp spectral filter $\hat{G}(\vec{k}) = H(k_c - k)$:

Closure problem ← Triad Interaction (TI)

$$\left\{ \begin{array}{l} \left(\frac{d}{dt} + \nu k^2 \right) \hat{U}_j(\vec{k}) = -ik_l P_{jk}(\vec{k}) \underbrace{\sum_{\vec{k}'} \sum_{\vec{k}''} \delta_{\vec{k}, \vec{k}' + \vec{k}''} H(k_c - k) \hat{U}_k(\vec{k}') \hat{U}_l(\vec{k}'')}_{\text{Closure problem } \leftarrow \text{Triad Interaction (TI)}}; \\ k_i = \frac{2\pi}{L} n_i, n_i = 0, \pm 1, \dots, -\frac{N_c}{2}, n_1^2 + n_2^2 + n_3^2 \leq N_c^2 = \left(\frac{L}{\pi} k_c \right)^2 \quad (7.100a) \end{array} \right.$$

$$\hat{U}_j(\vec{k}) = 0; \text{ otherwise} \quad (7.100b)$$



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VII.3.3 SGS modeling

The filtered rate of strain

- The filtered rate of strain tensor:

$$\bar{s}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) \quad (7.101)$$

- The characteristic rate of strain:

$$\bar{s} = (2\bar{s}_{ij}\bar{s}_{ij})^{1/2} \quad (7.102)$$

- Note: For isotropic turbulence $\bar{u}_i = \bar{U}_i$ and $\bar{s}_{ij} = \bar{S}_{ij}$.

- Remember, Eq. (3.15) and (7.83):

$$\varepsilon = 2\nu \langle s_{ij}s_{ij} \rangle \cong \int_0^\infty 2\nu k^2 E(k) dk \quad \langle \varepsilon_f \rangle \equiv 2\nu \langle \bar{s}_{ij}\bar{s}_{ij} \rangle \cong \int_0^\infty 2\nu k^2 E^R(k) dk \quad (7.103)$$

$$\langle \bar{s}^2 \rangle \equiv 2\langle \bar{s}_{ij}\bar{s}_{ij} \rangle \cong 2 \int_0^\infty k^2 E^R(k) dk = 2 \int_0^\infty k^2 \hat{G}^2(k) E(k) dk \quad (7.104)$$

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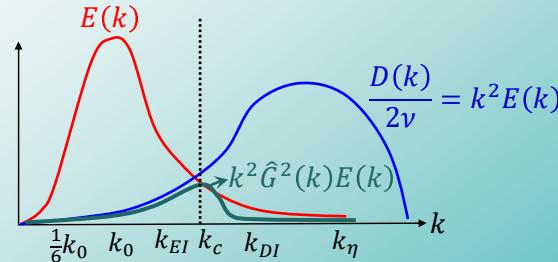
Isotropic filter

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VII.3.3 SGS modeling

The filtered rate of strain

$$\langle \bar{s}^2 \rangle \equiv 2\langle \bar{s}_{ij}\bar{s}_{ij} \rangle \cong 2 \int_0^\infty k^2 E^R(k) dk = 2 \int_0^\infty k^2 \hat{G}^2(k) E(k) dk \quad (7.104)$$



- Therefore, the contributions to $\langle \bar{s}^2 \rangle$ are predominantly from wavenumbers around k_c .
- Assuming high Re, and k_c being in the inertial subrange, Eq. (7.104) can be approximated by $E(k)$ in this range, Eq. (7.93)

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VII.3.3 SGS modeling

The filtered rate of strain

$$\langle \bar{s}^2 \rangle \sim 2 \int_0^\infty k^2 \hat{G}^2(k) [C \varepsilon^{2/3} k^{-5/3}] dk = a_f C \varepsilon^{2/3} \Delta^{-4/3} \quad (7.105)$$

Dependence on
filter type Dependence on
filter width

$$a_f = 2 \int_0^\infty (k \Delta)^{1/3} \hat{G}^2(k) \Delta dk \quad (7.106)$$

- Exercise: Using the appropriate relations for $\hat{G}(k)$, show that:

$$a_f = \begin{cases} 6.90 & ; \text{for sharp spectral filter} \\ 7.10 & ; \text{for Gaussian filter} \end{cases} \quad (7.107)$$

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VII.3.3 SGS modeling

Determining the Smagorinsky constant

- Assuming isotropic turbulence, high Re, and the filter width in the inertial subrange:

$$\begin{aligned} \varepsilon \sim \langle \mathcal{P}_r \rangle &= \langle -\tau_{ij}^r \bar{S}_{ij} \rangle = \langle 2\nu_r \bar{S}_{ij} \bar{S}_{ij} \rangle = \langle \nu_r \bar{S}^2 \rangle = l_s^2 \langle \bar{S}^3 \rangle \longrightarrow \\ &\text{Eq. (6.40)} \qquad \qquad \qquad \text{Eq. (6.48)} \\ l_s &= \left(\frac{\varepsilon}{\langle \bar{S}^3 \rangle} \right)^{1/2} = \frac{\varepsilon^{1/2}}{\langle \bar{S}^2 \rangle^{3/4}} \left(\frac{\langle \bar{S}^2 \rangle^{3/4}}{\langle \bar{S}^3 \rangle^{1/2}} \right) \end{aligned} \quad (7.110)$$

- Assuming $\langle \bar{S}^2 \rangle$ from the approximation (7.105) and

$$\langle \bar{S}^3 \rangle \sim \langle \bar{S}^2 \rangle^{3/2} : \quad l_s = \frac{\Delta}{(Ca_f)^{4/3}} \quad (7.111) \longrightarrow$$

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$$C_S = \frac{l_s}{\Delta} = (Ca_f)^{-4/3} \quad (7.112)$$

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VII.3.3 SGS modeling

Determining the Smagorinsky constant

- For the sharp spectral filter, $a_f = 6.90$, and $C \sim 1.5$:

$$C_S = (Ca_f)^{-4/3} \approx 0.17 \quad (7.112)'$$

- Recommended values:

$$C_S \sim 0.1 - 0.17 \rightarrow C_{DS} \sim C_S^2 \sim 0.01 - 0.03$$

- Exercise:** Compare these values with the value obtained for the dynamic Smagorinsky constant for the **1DFSBE** in project#2.

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VII.3.3 SGS modeling

Modeling in spectral space

- The closure problem: Triad Interaction

$$TI = \sum_{\vec{k}'} \sum_{\vec{k}''} \delta_{\vec{k}, \vec{k}' + \vec{k}''} H(k_c - k) \hat{U}_k(\vec{k}') \hat{U}_l(\vec{k}'') = \mathcal{F}_L\{\overline{U_k U_l}\} \quad (7.113)$$

- Another reason for the superiority of Germano's decomposition:

- **Exercise:** Assuming sharp spectral filter ($\bar{U} = \bar{U}$), Eq. (6.61) is simplified to:

vs. $\overline{U_i U_j} \equiv \overline{\bar{U}_i \bar{U}_j} + \tau_{ij}^k, \tau_{ij}^k = \overline{\bar{U}_i \bar{U}_j'} + \overline{\bar{U}_j \bar{U}_i'} + \overline{\bar{U}_i' \bar{U}_j'} \quad (7.114)$

$\overline{U_i U_j} \equiv \bar{U}_i \bar{U}_j + \tau_{ij}^R \quad (6.30)$

- $\overline{U_i U_j}$ contains no wavenumber $k > k_c$

- $\bar{U}_i \bar{U}_j$ contains wavenumbers $k_c < k < 2k_c$

- τ_{ij}^R should cancel out wavenumbers $k_c < k < 2k_c$ with the data available for $k < k_c$, a toll order! This issue is removed by

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modeling τ_{ij}^k , see Eq. (7.114)

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VII.3.3 SGS modeling

Modeling in spectral space

- The closure problem: Triad Interaction (TI)

$$TI = \sum_{\vec{k}'} \sum_{\vec{k}''} \delta_{\vec{k}, \vec{k}' + \vec{k}''} H(k_c - k) \hat{U}_k(\vec{k}') \hat{U}_l(\vec{k}'') = \mathcal{F}_L \{ \overline{\hat{U}_k \hat{U}_l} \} \quad (7.113)$$

- Indirect approach: Using a SGS model in physical space for $\overline{\hat{U}_k \hat{U}_l}$ and Fourier transform the result, like in "pyBurgers.py"
- Direct approach: Modeling TI directly in the spectral space

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VII.3.3 SGS modeling

Direct SGS modeling in the spectral space

- Using decomposition Eq. (7.114) in Eq. (7.100a):

$$\left(\frac{d}{dt} + \nu k^2 \right) \hat{U}_j(\vec{k}) = \underbrace{F_j^<(\vec{k})}_{\substack{\text{Resolved} \\ \text{TI}}} + \underbrace{F_j^>(\vec{k})}_{\substack{\text{Unresolved} \\ \text{TI}}} \quad (7.115)$$

$\mathcal{F}_L \{ \overline{\hat{U}_k \hat{U}_l} \}$

$$F_j^<(\vec{k}) = -ik_l P_{jk}(\vec{k}) \underbrace{\sum_{\substack{\vec{k}', \vec{k}'' \\ (\vec{k}', \vec{k}'' < k_c)}} \delta_{\vec{k}, \vec{k}' + \vec{k}''} H(k_c - k) \hat{U}_k(\vec{k}') \hat{U}_l(\vec{k}'')}_{\mathcal{F}_L \{ \tau_{ij}^k \}} \quad (7.116)$$

$$F_j^>(\vec{k}) = -ik_l P_{jk}(\vec{k}) \underbrace{\sum_{\substack{\vec{k}', \vec{k}'' \\ (\max(\vec{k}', \vec{k}'') \geq k_c)}} \delta_{\vec{k}, \vec{k}' + \vec{k}''} H(k_c - k) \hat{U}_k(\vec{k}') \hat{U}_l(\vec{k}'')}_{\mathcal{F}_L \{ \tau_{ij}^k \}} \quad (7.117)$$

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VII.3.3 SGS modeling

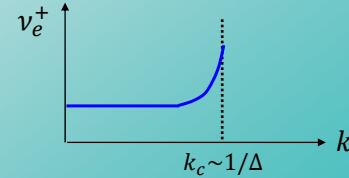
Direct SGS modeling in the spectral space

- Using a direct spectral model, e.g., spectral eddy-viscosity model for $F_j^>(\vec{k})$:

$$F_j^>(\vec{k}) = -\nu_e k^2 \hat{U}_j(\vec{k}) \quad (7.118)$$

$$\nu_e = \nu_e^+ \sqrt{\frac{E(k_c)}{k_c}} \quad (7.119)$$

$$\nu_e^+ = C^{-3/2} \{a + b \exp[-d(k_c/k)^p]\} \quad (7.120)$$



➤ Model constants: For 3D flows:

$$C = 1.5, a = 0.441, b = 15.2, d = 3.03, p = 1 \quad (7.121)$$

