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B. proof (3D):

$$\vec{x}(u,v) = x(u,v)\hat{i} + y(u,v)\hat{j} + z(u,v)\hat{k} \quad t \rightarrow \text{is implied}$$

$$\left\{ \begin{array}{l} \vec{x}_u = \frac{\partial \vec{x}}{\partial u} \\ \vec{x}_v = \frac{\partial \vec{x}}{\partial v} \end{array} \right. \quad \begin{array}{l} (1.B3) \\ (2.B3) \end{array}$$

$$\hat{n} = \frac{\vec{x}_u \times \vec{x}_v}{|\vec{x}_u \times \vec{x}_v|} \quad (3.B3)$$

$$\left\{ \begin{array}{l} \hat{n} \rightarrow (3.B3) \\ \hat{t} = d\hat{x}_e(s) / ds \quad \vec{x}_e: \text{tangent} \\ \hat{p} = \hat{t} \times \hat{n} \end{array} \right. \quad \begin{array}{l} \text{to edge} \\ (4.B3) \end{array}$$

For volume fixed operation
 $\vec{\nabla} - \hat{n}(\hat{n} \cdot \vec{\nabla})$

surface $\vec{\nabla}_s \equiv (\underline{I} - \hat{n}\hat{n}) \cdot \vec{\nabla} \quad (5.B3)$

surface identity tensor $I_s \equiv \underline{I} - \hat{n}\hat{n} \quad (6.B3)$

$$I_s \cdot \vec{A} = \vec{A}_s \quad (7.B3) \rightarrow \underline{I}_s \cdot \vec{A}_s = 0, \underline{I}_s \cdot \vec{A}_n = 0$$

more general $\vec{\nabla}_s$ definition for both surface and volume fields

Consider a non-orthogonal curvilinear coordinates [Frenet]

and a surface $\vec{x}(q^\alpha, t)$ $\alpha=1 \rightarrow q^1=u$ 2D
 $\alpha=1,2 \rightarrow q^1=u, q^2=v$ 3D

$$\vec{g}_\alpha = \frac{\partial \vec{x}}{\partial q^\alpha}, g_{\alpha\beta} = \vec{g}_\alpha \cdot \vec{g}_\beta, g = |g_{\alpha\beta}|, g^{\alpha\beta} = g_{\alpha\beta}^{-1}, dS = \sqrt{g} d\vec{q}^\alpha$$

Corariant base vector $\underline{g} = [g_{\alpha\beta}]$ determinant Counter covariant metric tensor surface element

$$\vec{\nabla}_s \equiv g^{\alpha\beta} \vec{g}_\alpha \frac{\partial}{\partial q^\beta} \xrightarrow[3D]{(A.27)[1]} (q^\alpha=u) \quad g^{\alpha\beta} = 1, \vec{g}_\alpha = \hat{t} \rightarrow \vec{\nabla}_s = \hat{t} \frac{\partial}{\partial u}$$

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$$K = K_1 + K_2 = - \underbrace{\nabla_s \cdot \hat{n}}_{\downarrow \text{proof}} = - \nabla \cdot \hat{n} \quad (\text{B.B3})$$

$$\nabla_s \cdot \hat{n} = [(I - \hat{n}\hat{n}) \cdot \nabla] \cdot \hat{n} = \nabla \cdot \hat{n} - \underbrace{\hat{n}^T (I \cdot \nabla) \cdot \hat{n}}_{(\text{D.77})} = \nabla \cdot \hat{n} \quad \square$$

The surface tension tensor (\underline{T}_s^σ) is defined as
 (like stress tensor $\underline{\sigma} \cdot \hat{n}$ = force per unit surface of \hat{n})

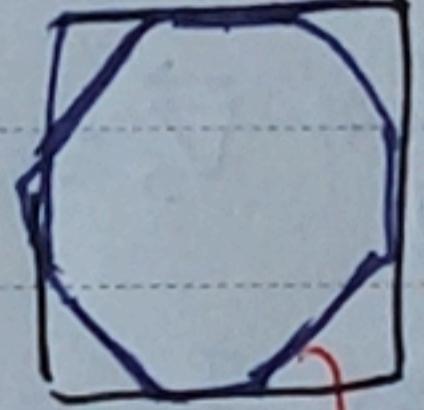
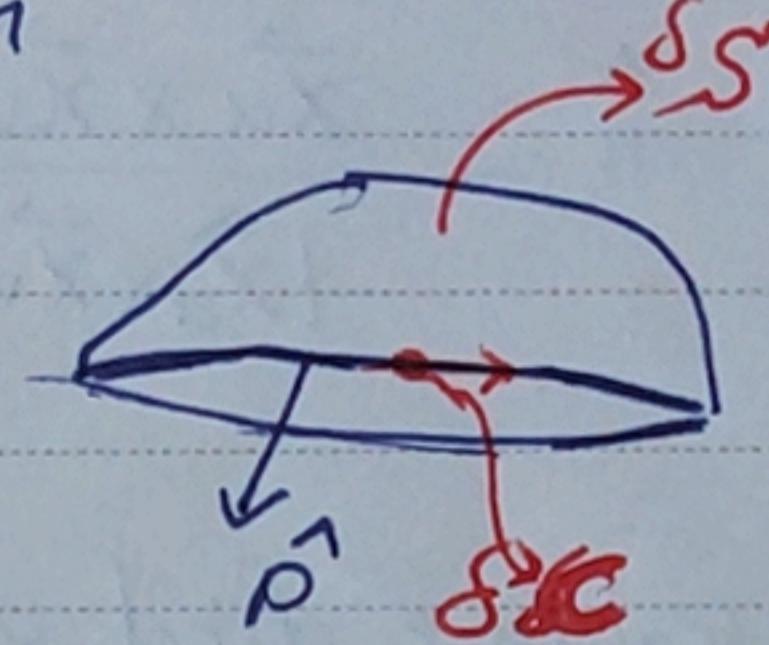
$$\underline{T}_s^\sigma \cdot \hat{P} \equiv \sigma \hat{P} \quad (\text{9.B3})$$

force per unit length of C

$$\hat{P} = \underline{I}_s \cdot \hat{P} \xrightarrow{(\text{9.B3})} \underline{T}_s^\sigma = \sigma \underline{I}_s \quad (\text{10.B3})$$

parallel to S

SDT: $\vec{F} = \underline{T}_s^\sigma$
 surface divergence theorem



$$\vec{F}_\sigma = \int_{\partial S} \vec{f}_\sigma dS = \oint_C \underline{T}_s^\sigma \cdot \hat{P} dC \xrightarrow{\text{surface divergence theorem}} \int_S \nabla_s \cdot \underline{T}_s^\sigma dS + \int_S k \underline{T}_s^\sigma \cdot \hat{n} dS$$

$$\begin{aligned} & \int_S \underline{T}_s^\sigma \cdot \hat{n} dS = \sigma (I - \hat{n}\hat{n}) \cdot \hat{n} \\ & = \sigma (\hat{n} - \hat{n}) \\ & = 0 \end{aligned}$$

surface divergence theorem [7] (A.36), [temen]

$$\int_S \nabla_s \cdot \vec{F} dS = \oint_C \vec{F} \cdot \hat{P} dC - \int_S k \vec{F} \cdot \hat{n} dS$$

(10.B3)

$$\vec{f}_\sigma = \nabla_s \cdot \underline{T}_s^\sigma = \nabla_s \cdot (\sigma \underline{I}_s) = \sigma \underbrace{\nabla_s \cdot \underline{I}_s}_{K \hat{n}} + \underbrace{\nabla_s \sigma \cdot \underline{I}_s}_{\vec{N} \cdot \underline{T}_s^\sigma} \quad \square$$

↓ proof

$$\text{SVD } \vec{F} = \underline{I}_s \quad \int_S \nabla_s \cdot \vec{I}_s dS = \oint_C \underbrace{\vec{I}_s \cdot \hat{P} dC}_{\hat{P}} - \int_S k \vec{I}_s \cdot \hat{n} dS \xrightarrow{(\text{7.B3})} \nabla_s \cdot \vec{I}_s = k \hat{n}$$

[7] (A.38) $\int k \hat{n} dS$

$$\vec{N} \cdot \underline{I}_s = \underline{I}_s \cdot \vec{N}$$

and finally, to show that $\nabla_s \cdot \underline{T}_s^\sigma = \vec{N} \cdot \underline{T}_s^\sigma$:

$$\nabla_s \cdot \underline{T}_s^\sigma = [(I - \hat{n}\hat{n}) \cdot \nabla] \cdot (\sigma \underline{I}_s) = \nabla \cdot (\sigma \underline{I}_s) - \hat{n}^T (\hat{n} \cdot \nabla) \cdot \sigma \underline{I}_s \xrightarrow{(\text{D.82})} \nabla \cdot \underline{I}_s - \frac{1}{2} \hat{n}^T \nabla \hat{n} \xrightarrow{(\text{D.77})} \frac{1}{2} (\hat{n} \cdot \hat{n}) \underline{I}_s$$

Subject :

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Date $\vec{T}_s \xrightarrow{\sigma} \text{symmetric}$

(D-73)

$$\vec{F}_G = (\vec{\nabla} \cdot \vec{T}_s^\sigma) \delta_s = \vec{\nabla} \cdot (\vec{T}_s^\sigma \delta_s) - \underbrace{\vec{T}_s^\sigma \cdot \vec{\nabla} \delta_s}_{\sigma \underline{I}_s \cdot \vec{\nabla} \delta_s} = \vec{\nabla} \cdot (\vec{T}_s \delta_s)$$



Similarly,

$$\vec{\nabla}_s \cdot \vec{T}_s^\sigma \delta_s = \vec{\nabla}_s \cdot (\vec{T}_s^\sigma \delta_s) - \vec{T}_s^\sigma \cdot \cancel{\vec{\nabla}_s \delta_s} = \vec{\nabla}_s \cdot (\vec{T}_s^\sigma \delta_s)$$