

VIII.1 The statistical description

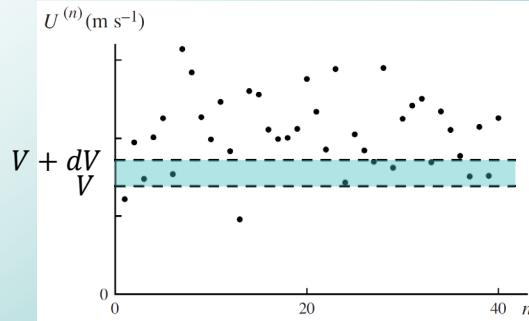
The random nature of turbulence

- Consistent with deterministic Navier-Stokes (NS) equations?
- Turbulent flow: Chaotic behavior of NS + perturbations in the state
- Random nature of turbulence: Every flow property $U(\vec{x}_0, t_0)$ can be regarded as a random variable.

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Random variables

- Consider a random variable U , e.g. $U = U_1(\vec{x}_0, t_0)$:



- The Probability Density Function (PDF) of U is defined as:

$$f(V)dV \equiv P\{V < U < V + dV\} \quad (8.1)$$

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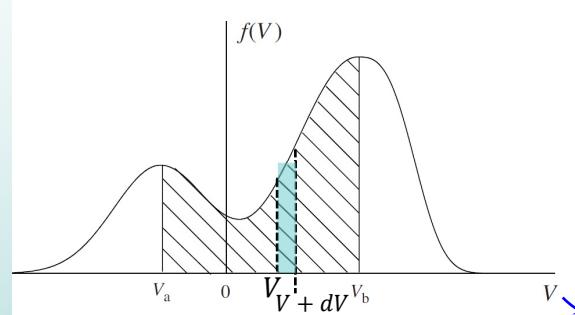
Probability

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VIII.1 The statistical description

Random variables

- PDF $f(V)dV \equiv P\{V < U < V + dV\}$ (8.1)



Sample space,
i.e., the probable
values of U

- Therefore;

$$P\{V_a < U < V_b\} = \int_{V_a}^{V_b} f(V)dV \quad (8.2)$$

$$\int_{-\infty}^{+\infty} f(V)dV = 1 \quad (8.3) \text{ (Normalization condition)}$$

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Random variables

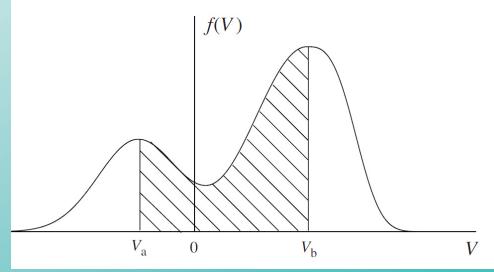
- The Cumulative Distribution Function (CDF):

$$F(V) = \int_{-\infty}^V f(V') dV' = P\{U < V\} \quad (8.2)'$$

- Therefore,

$$f(V) = \frac{dF(V)}{dV} \quad (8.2)''$$

$$\begin{aligned} P\{V_a < U < V_b\} &= \int_{V_a}^{V_b} f(V) dV = \\ &= \int_0^{V_b} f(V) dV - \int_0^{V_a} f(V) dV = \\ &= F(V_b) - F(V_a) \end{aligned} \quad (8.2)'''$$



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Random variables

- PDF

- contains a large amount of information: all one-point statistics (mean and moments)

- The mean (or expectation) of the random variable U :

$$\mu = \langle U \rangle = \int_{-\infty}^{+\infty} V f(V) dV \quad (8.4)$$

Probability of U being
in $V < U < V + dV$

- Simple example:

$$\langle U \rangle = \frac{3 + 5 + 5 + 6}{4} = \frac{1}{4} \times 3 + \frac{2}{4} \times 5 + \frac{1}{4} \times 6 = \sum_i P(V_i) V_i$$

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Random variables

- Corollary: If $Q = Q(U)$

$$\langle Q(U) \rangle = \int_{-\infty}^{+\infty} Q(V) f(V) dV \quad (8.4)'$$

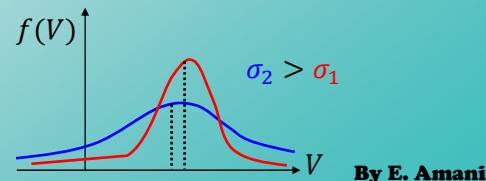
- The fluctuation of the random variable U is defined by:

$$u = U - \langle U \rangle \quad (8.5)$$

- The one-point statistics of the random variable U :

variance $\mu_2 = \sigma^2 = \int (V - \langle U \rangle)^2 f(V) dV = \langle (V - \langle U \rangle)^2 \rangle = \langle u^2 \rangle \quad (8.6)$

Standard deviation
or Root-Mean-Square (RMS)
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Random variables

- The one-point statistics of the random variable U :

nth central moment $\mu_n = \langle u^n \rangle = \int (V - \langle U \rangle)^n f(V) dV \quad (8.8)$

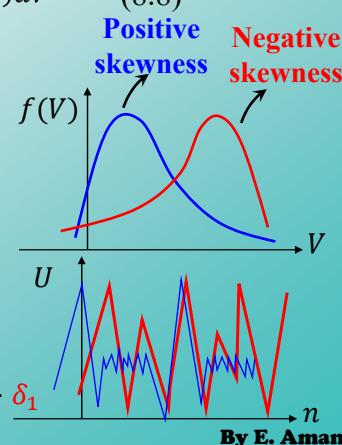
nth standardized moment $\hat{\mu}_n \equiv \frac{\mu_n}{\sigma^n}; n \geq 3 \quad (8.9)$

➤ Examples:

skewness $\hat{\mu}_3 = S = \frac{\mu_3}{\sigma^3} = \frac{\langle u^3 \rangle}{\langle u^2 \rangle^{3/2}} \quad (8.10)$

flatness or kurtosis $\hat{\mu}_4 = \delta = \frac{\mu_4}{\sigma^4} = \frac{\langle u^4 \rangle}{\langle u^2 \rangle^2} \quad (8.11)$

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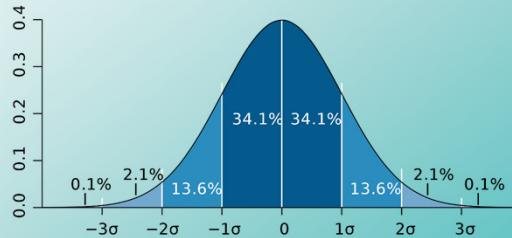
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Random variables

- Analytical PDFs

- Gaussian (or Normal) PDF

$$f(V) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(V-\mu)^2}{2\sigma^2}\right) \quad (8.12)$$



- Exercise: For the Gaussian PDF, $S = 0$ and $\delta = 3$.

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Joint random variables

- Joint statistical properties, e.g. $\langle uv \rangle$
- Consider two random variables U_1 and U_2 , e.g. $U_1 = U_1(\vec{x}_0, t_0)$ and $U_2 = U_2(\vec{x}_0, t_0)$, the joint PDF of U_1 and U_2 is defined:

$$f_{12}(V_1, V_2)dV_1dV_2 \equiv P\{V_1 < U_1 < V_1 + dV_1, V_2 < U_2 < V_2 + dV_2\} \quad (8.13)$$

- The normalization condition:

$$\iint f_{12}(V_1, V_2)dV_1dV_2 = 1 \quad (8.14)$$

- The relation with PDF of U_1 (marginal PDF):

$$\begin{aligned} \int f_{12}(V_1, V_2)dV_2 &= P\{V_1 < U_1 < V_1 + dV_1, \underbrace{-\infty < U_2 < +\infty}_{\text{sure event}}\}/dV_1 \\ &= P\{V_1 < U_1 < V_1 + dV_1\}/dV_1 = f_1(V_1) \end{aligned} \quad (8.15)$$

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Joint random variables

- $f_1(V_1)$ is only a part of information contained in $f_{12}(V_1, V_2)$
- The one-point joint statistics of U_1 and U_2 :

$$\langle Q(U_1, U_2) \rangle = \int \int Q(V_1, V_2) f_{12}(V_1, V_2) dV_1 dV_2 \quad (8.16)$$

covariance
 $\text{cov}(U_1, U_2) = \langle u_1 u_2 \rangle = \int \int (V_1 - \langle U_1 \rangle)(V_2 - \langle U_2 \rangle) f_{12}(V_1, V_2) dV_1 dV_2$

Correlation coefficient
 $CC(U_1, U_2) = \frac{\langle u_1 u_2 \rangle}{(\langle u_1^2 \rangle \langle u_2^2 \rangle)^{1/2}} \quad (8.18)'$

- Exercise: Show that for $Q(U_1, U_2) = Q(U_1)$, Eq. (8.16) is simplified to Eq. (8.4)'.
- Exercise: Show that (Cauchy-Schwarz inequality):

$$|\langle u_1 u_2 \rangle| \leq (\langle u_1^2 \rangle \langle u_2^2 \rangle)^{1/2} \quad (8.19)$$

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 $-1 \leq CC \leq 1$

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Joint random variables

- Joint CDF:

$$F_{12}(V_1, V_2) = \int_{-\infty}^{V_2} \int_{-\infty}^{V_1} f_{12}(V'_1, V'_2) dV'_1 dV'_2 = P\{U_1 < V_1, U_2 < V_2\} \quad (8.15)'$$

$$f_{12}(V_1, V_2) = \frac{\partial^2}{\partial V_1 \partial V_2} F_{12}(V_1, V_2) \quad (8.15)''$$

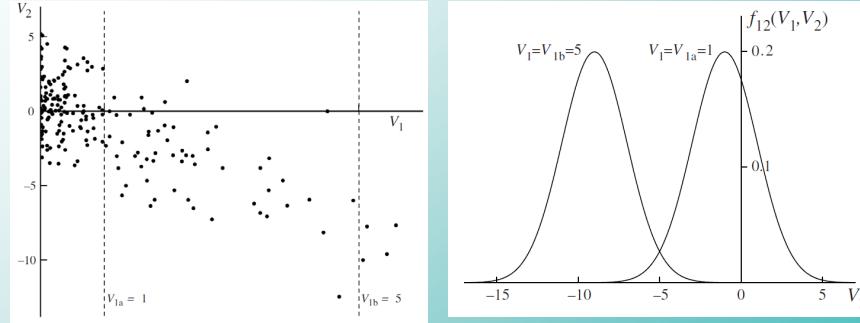
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Joint random variables

- Conditional PDF:



$$\begin{aligned} f_{2|1}(V_2|V_1)dV_2 &\equiv P\{V_2 < U_2 < V_2 + dV_2 | U_1 = V_1\} \\ &= \frac{P\{V_1 < U_1 < V_1 + dV_1, V_2 < U_2 < V_2 + dV_2\}}{P\{V_1 < U_1 < V_1 + dV_1\}} = \frac{f_{12}(V_1, V_2)dV_1dV_2}{f_1(V_1)dV_1} \\ &= \frac{f_{12}(V_1, V_2)}{f_1(V_1)}dV_2 \end{aligned}$$

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Joint random variables

- Conditional PDF:

$$f_{2|1}(V_2|V_1) = \frac{f_{12}(V_1, V_2)}{f_1(V_1)} \quad (8.20)$$

- Exercise:** Show that

$$\int_{-\infty}^{+\infty} f_{2|1}(V_2|V_1)dV_2 = 1 \quad (8.21)$$

- Conditional mean:

$$\langle Q(U_1, U_2) | U_1 = V_1 \rangle = \langle Q(U_1, U_2) | V_1 \rangle \equiv \int Q(V_1, V_2) f_{2|1}(V_2|V_1)dV_2 \quad (8.22)$$

- Exercise:** Show that

$$\langle Q(U_1) | U_1 = V_1 \rangle = Q(V_1) \quad (8.23)$$

$$\langle Q(U_1, U_2) \rangle = \int \langle Q(U_1, U_2) | V_1 \rangle f_1(V_1)dV_1 \quad (8.24)$$

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Joint random variables

- Independent random variables:

$$f_{2|1}(V_2|V_1) = f_2(V_2) \quad (8.25)$$

- Exercise: Show that for independent random variables

$$f_{12}(V_1, V_2) = f_1(V_1)f_2(V_2) \quad (8.26)$$

- If $\langle u_1 u_2 \rangle = 0$, U_1 and U_2 are said to be uncorrelated.

- Exercise: Independence vs. zero-correlation: Which property is followed given the other?

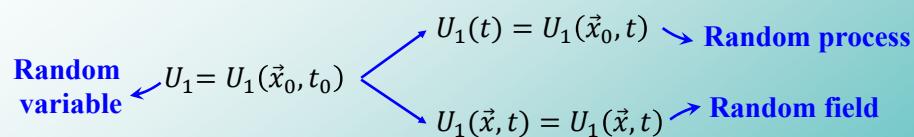
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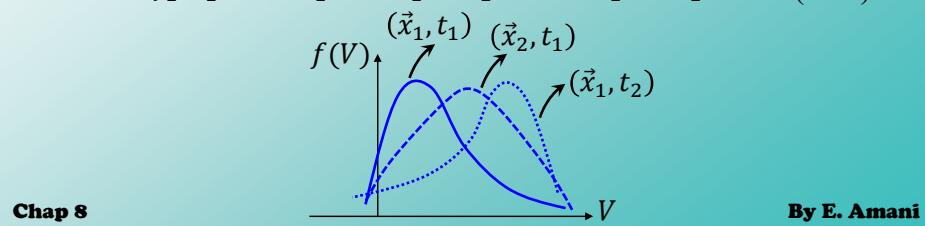
Random processes and random fields

- Extensions:



- All definitions can be extended straightforwardly, e.g.

$$f_1(V_1; \vec{x}, t) dV_1 \equiv P\{V_1 < U_1(\vec{x}, t) < V_1 + dV_1\} \quad (8.27)$$



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VIII.1 The statistical description

Random processes and random fields

- Example of one-point statistics:

$$U_1 = U_1(\vec{x}, t) \quad \left. \begin{array}{l} \\ \end{array} \right\} \langle u_1(\vec{x}, t) u_1(\vec{x}, t) \rangle \rightarrow \text{variance}$$

- Example of one-point joint statistics:

$$\begin{aligned} U_1 &= U_1(\vec{x}, t) \\ U_2 &= U_2(\vec{x}, t) \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \langle u_1(\vec{x}, t) u_2(\vec{x}, t) \rangle \rightarrow \text{covariance}$$

- Example of two-point or two-time joint statistics:

$$\begin{aligned} U_1 &= U_i(\vec{x}, t) \\ U_2 &= U_j(\vec{x} + \vec{r}, t) \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \langle u_i(\vec{x}, t) u_j(\vec{x} + \vec{r}, t) \rangle \rightarrow \text{(spatial)} \text{ autocovariance}$$

$$\begin{aligned} U_1 &= U_i(\vec{x}, t) \\ U_2 &= U_j(\vec{x}, t + s) \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \langle u_i(\vec{x}, t) u_j(\vec{x}, t + s) \rangle \rightarrow \text{(temporal)} \text{ autocovariance}$$

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VIII.2 PDF methods

Joint PDF of velocity

- State (or internal) space: 3 components of the fluid velocity field

$$U_i(\vec{x}, t) \quad \left. \begin{array}{l} \\ \end{array} \right\} \xrightarrow{\text{Joint PDF}} f(\vec{V}; \vec{x}, t) \quad \vec{V} = \{V_1, V_2, V_3\}$$

\searrow Eulerian PDF of velocity

- One-point velocity statistics:

$$\langle U_i(\vec{x}, t) \rangle = \int V_i f(\vec{V}; \vec{x}, t) d\vec{V} \quad \int (\) d\vec{V} \rightarrow \iiint (\) dV_1 dV_2 dV_3$$

$$\langle u_i u_j \rangle = \iiint (V_i - \langle U_i \rangle)(V_j - \langle U_j \rangle) f(\vec{V}; \vec{x}, t) d\vec{V}$$

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VIII.2 PDF methods

PDF transport equation

- See appendix H of reference [1] for the details of derivation.
- Mathematics:

$$\frac{\partial f}{\partial t} + V_i \frac{\partial f}{\partial x_i} = -\frac{\partial}{\partial V_i} \left[f \left\langle \frac{D U_i}{D t} \middle| \boldsymbol{V} \right\rangle \right] \quad (8.28)$$

- Expressing the material derivative of the state variables
Using Navier-Stokes equations:

$$\frac{\partial f}{\partial t} + V_i \frac{\partial f}{\partial x_i} = \frac{1}{\rho} \frac{\partial \langle p \rangle}{\partial x_i} \frac{\partial f}{\partial V_i} - \frac{\partial}{\partial V_i} \left[f \left\langle v \nabla^2 U_i - \frac{1}{\rho} \frac{\partial p'}{\partial x_i} \middle| \boldsymbol{V} \right\rangle \right] \quad (8.29)$$

• or

$$\begin{aligned} \frac{\partial f}{\partial t} + V_i \frac{\partial f}{\partial x_i} &= v \nabla^2 f + \frac{1}{\rho} \frac{\partial \langle p \rangle}{\partial x_i} \frac{\partial f}{\partial V_i} + \frac{\partial^2}{\partial x_i \partial V_i} \left(f \left\langle \frac{p'}{\rho} \middle| \boldsymbol{V} \right\rangle \right) \\ &\quad + \frac{1}{2} \frac{\partial^2}{\partial V_i \partial V_j} \left[f \left\langle \frac{p'}{\rho} \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) - 2v \frac{\partial U_i}{\partial x_k} \frac{\partial U_j}{\partial x_k} \middle| \boldsymbol{V} \right\rangle \right]. \end{aligned} \quad (8.30)$$

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VIII.2 PDF methods

PDF transport equation

- Closure problem: The conditional means including the two-point velocity gradients or pressure fluctuation

$$\frac{\partial f}{\partial t} + V_i \frac{\partial f}{\partial x_i} = \frac{1}{\rho} \frac{\partial \langle p \rangle}{\partial x_i} \frac{\partial f}{\partial V_i} - \frac{\partial}{\partial V_i} \left[f \left\langle v \nabla^2 U_i - \frac{1}{\rho} \frac{\partial p'}{\partial x_i} \middle| \boldsymbol{V} \right\rangle \right] \quad (8.29)$$

$$\begin{aligned} \frac{\partial f}{\partial t} + V_i \frac{\partial f}{\partial x_i} &= v \nabla^2 f + \frac{1}{\rho} \frac{\partial \langle p \rangle}{\partial x_i} \frac{\partial f}{\partial V_i} + \frac{\partial^2}{\partial x_i \partial V_i} \left(f \left\langle \frac{p'}{\rho} \middle| \boldsymbol{V} \right\rangle \right) \\ &\quad + \frac{1}{2} \frac{\partial^2}{\partial V_i \partial V_j} \left[f \left\langle \frac{p'}{\rho} \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) - 2v \frac{\partial U_i}{\partial x_k} \frac{\partial U_j}{\partial x_k} \middle| \boldsymbol{V} \right\rangle \right]. \end{aligned} \quad (8.30)$$

- Note the dimension of the equation: $4+3=7$
- Modeling?
- Numerical solution? Monte Carlo (MC) method

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VIII.3 PDF modeling

Lagrangian point of view

- Lagrangian PDF

$$\left. \begin{array}{l} \vec{V}^+(t, \vec{Y}) \\ \vec{X}^+(t, \vec{Y}) \\ \vec{Y} = \vec{X}_0 \end{array} \right\} \xrightarrow[\text{on } \vec{Y}] {\substack{\text{Joint PDF of} \\ \vec{X}^+ \text{ and } \vec{V}^+ \\ \text{conditioned}}} f_L(\vec{V}, \vec{x}; t | \vec{Y}) \quad \text{Lagrangian PDF of fluid particle velocity}$$

- Relation between f_L and f [1]:

$$\int f_L(V, x; t | Y) dY = f(V; x, t). \quad (8.31)$$

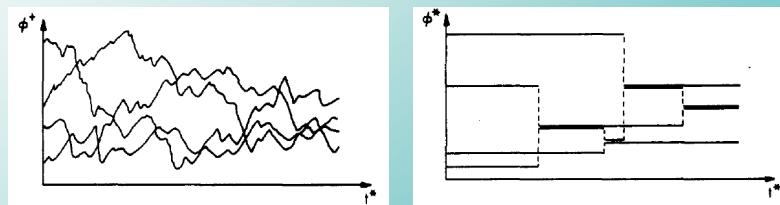
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VIII.3 PDF modeling

Lagrangian point of view

- Stochastic Processes (SPs) and Stochastic Differential Equations (SDEs) are suitable candidates for modeling Lagrangian fluid particle properties ($\phi^+(t, \vec{Y})$).
- Fluid particle ($\phi^+(t, \vec{Y})$) vs. stochastic particle ($\phi^*(t, \vec{Y})$):



- For PDF methods, the consistency is assured at the level of PDF

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VIII.4 Stochastic processes and calculus

The need to extend the ordinary calculus

- SDE vs. ODE and SP vs. deterministic function:

$$dU(t) = a[U(t), t] dt + b[U(t), t] dW(t),$$

- If $b \neq 0$, the above equation is a SDE and the solution, $U(t)$, is a SP.
- The second term requires special treatment with the knowledge of stochastic calculus

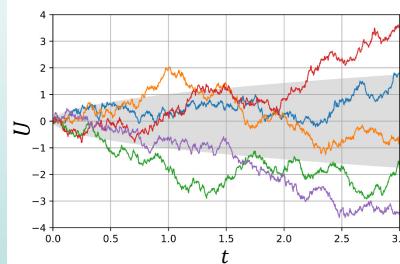
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VIII.4 Stochastic processes and calculus

Properties of SPs

- Sample path (trajectory): A realization of $U(t)$ vs. t



- N-point PDFs

- Increment:

$$\Delta_h U(t) \equiv U(t+h) - U(t). \quad (8.32)$$

Positive time interval

- Infinitesimal parameters:

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$$B_n(V, t) \equiv \lim_{h \downarrow 0} \frac{1}{h} \langle [\Delta_h U(t)]^n | U(t) = V \rangle, \quad (8.33)$$

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VIII.4 Stochastic processes and calculus

Classification of SPs

- Markov vs. non-Markov process:
 - N-point conditional PDF satisfies:

$$f_{N-1}(V_N; t_N | V_{N-1}, t_{N-1}, V_{N-2}, t_{N-2}, \dots, V_1, t_1) = f_1(V_N; t_N | V_{N-1}, t_{N-1}). \quad (8.34)$$

- Interpretation: The present is enough to predict the future (the information of the past is included in the present)
- Continuous-time vs. discrete-time processes.

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VIII.4 Stochastic processes and calculus

Diffusion process

- A branch of continuous-time Markov processes
- Properties:

- Continuous trajectory

$$\lim_{h \downarrow 0} \frac{1}{h} P\{|\Delta_h U(t)| > \epsilon | U(t) = V\} = 0. \quad (8.35)$$

- The drift coefficient exists:

$$a(V, t) \equiv B_1(V, t), \quad (8.36)$$

- The diffusion coefficient exists:

$$b(V, t)^2 \equiv B_2(V, t), \quad (8.37)$$

$$\begin{aligned} \langle [\Delta_h U(t)]^2 / h \rangle \\ \langle [\Delta_h U(t)/h]^2 \rangle \rightarrow \infty \end{aligned}$$

↓
Not differentiable

- Other infinitesimal parameters are:

$$B_n(V, t) = 0, \quad \text{for } n \geq 3. \quad (8.38) \quad \text{anywhere}$$

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VIII.4 Stochastic processes and calculus

Diffusion process

- It can be shown that
 - The diffusion SP is the solution of the following SDE called the **generalized Langevin equation**:

$$dU(t) = a[U(t), t] dt + b[U(t), t] dW(t), \quad (8.39)$$

The Wiener SP: The elementary diffusion SP

- The conditional PDF evolves with the Fokker-Planck or forward Kolmogorov equation

$$\frac{\partial}{\partial t} f_1(V; t | V_1, t_1) = -\frac{\partial}{\partial V} [a(V, t) f_1(V; t | V_1, t_1)] + \frac{1}{2} \frac{\partial^2}{\partial V^2} [b(V, t)^2 f_1(V; t | V_1, t_1)]. \quad (8.40)$$

- The marginal PDF evolves with:

$$\frac{\partial}{\partial t} f(V; t) = -\frac{\partial}{\partial V} [a(V, t) f(V; t)] + \frac{1}{2} \frac{\partial^2}{\partial V^2} [b(V, t)^2 f(V; t)]. \quad (8.41)$$

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VIII.4 Stochastic processes and calculus

Diffusion process

- It can be shown that

$$\frac{\partial}{\partial t} f(V; t) = -\frac{\partial}{\partial V} [a(V, t) f(V; t)] + \frac{1}{2} \frac{\partial^2}{\partial V^2} [b(V, t)^2 f(V; t)]. \quad (8.41)$$

- The diffusion term interpretation:

$$\frac{\partial f}{\partial t} = \frac{\partial^2}{\partial v^2} (Df)$$

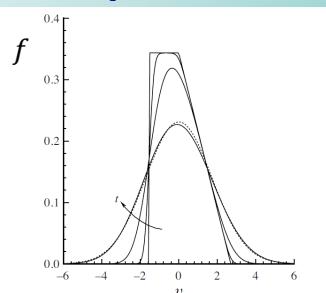


Fig. 12.1. The effect of diffusion on the shape of the PDF: the solutions to Eq. (12.29) for $Dt = 0, 0.02, 0.2$, and 1 . The dashed line is the Gaussian with the same mean (0) and variance (3) as those of the PDF at $Dt = 1$.

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VIII.4 Stochastic processes and calculus

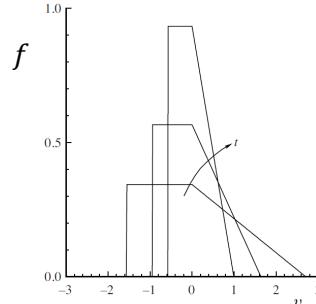
Diffusion process

- It can be shown that

$$\frac{\partial}{\partial t} f(V; t) = -\frac{\partial}{\partial V} [a(V, t)f(V; t)] + \frac{1}{2} \frac{\partial^2}{\partial V^2} [b(V, t)^2 f(V; t)]. \quad (8.41)$$

- The drift term interpretation:

$$\frac{\partial f}{\partial t} = -\frac{\partial}{\partial v} \left(\frac{v}{T_L} f \right)$$



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Fig. 12.2. Solutions (Eq. (12.34)) to Eq. (12.32) for $t/T_L = 0, \frac{1}{2}, 1$.

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VIII.4 Stochastic processes and calculus

Diffusion process

- It can be shown that

- The moments evolve with:

$$\frac{d}{dt} \langle U(t) \rangle = \langle a[U(t), t] \rangle. \quad (8.42)$$

$$\frac{d}{dt} \langle U(t)^2 \rangle = 2 \langle U(t) a[U(t), t] \rangle + \langle b[U(t), t]^2 \rangle. \quad (8.43)$$

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VIII.4 Stochastic processes and calculus

Diffusion process

- The Wiener process

- The simplest diffusion process:

$$a(V, t) = 0, \quad b(V, t)^2 = 1. \quad (8.44)$$

- Some important properties:

$$f_1(V; t|V_1, t_1) = \frac{1}{\sqrt{2\pi(t-t_1)}} \exp\left(-\frac{\frac{1}{2}(V-V_1)^2}{t-t_1}\right), \quad (8.45)$$

$$\Delta_h W(t) \stackrel{D}{=} \mathcal{N}(0, h). \quad (8.46)$$

$$\begin{aligned} \text{(i)} \quad & \langle W(t_2) - W(t_1) \rangle = 0, \\ \text{(ii)} \quad & \langle [W(t_2) - W(t_1)]^2 \rangle = \text{var}[W(t_2) - W(t_1)] = t_2 - t_1, \\ \text{(iii)} \quad & W(t_2) - W(t_1) \stackrel{D}{=} \mathcal{N}(0, t_2 - t_1), \end{aligned} \quad (8.47)$$

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VIII.4 Stochastic processes and calculus

Stochastic calculus

- Stochastic integral

$$dU(t) = a[t, U(t)]dt + b[t, U(t)]dW(t) \quad (8.48)$$

$$U(t) - U(t_0) = \int_{t_0}^t a[t, U(t)]dt + \int_{t_0}^t b[t, U(t)]dW(t) \quad (8.49)$$

$$I = \int_{t_0}^t b[t, U(t)]dW(t) \quad (8.50)$$

- Ordinary calculus: Riemann-Stieltjes definition

$$I = \lim_{N \rightarrow \infty} I_N = \lim_{N \rightarrow \infty} \sum_{i=1}^N b[\tau_i, U(\tau_i)][W(t_{i+1}) - W(t_i)]; \tau_i \in [t_i, t_{i+1}] \quad (8.51)$$

Converges but depends on the choice of τ_i in $[t_i, t_{i+1}]$

- Different choices are possible, the most commonly used one

Chap 8 is called Ito calculus

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VIII.4 Stochastic processes and calculus

Ito calculus

- Stochastic integral definition ($\tau_i = t_i$):

$$I = \lim_{N \rightarrow \infty} I_N = \lim_{N \rightarrow \infty} \sum_{i=1}^N b[t_i, U(t_i)][W(t_{i+1}) - W(t_i)] \quad (8.52)$$

➢ Example: Using (8.47)(ii) $((dW)^2 \sim dt)$, it can be shown that

$$\int_0^t W(t)dW(t) = \frac{1}{2}W^2(t) - \frac{1}{2}t \quad (8.53)$$

extra term

- Ito lemma (extended chain rule): If $dU = adt + bdW$ and $g(t, x)$ is a differentiable function

$$dg(t, U(t)) = \frac{\partial g}{\partial t} dt + \left(\frac{\partial g}{\partial x} \right) (adt + bdW) + \frac{1}{2} \frac{\partial^2 g}{\partial x^2} b^2 dt \quad (8.54)$$

extra term

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VII.5 Modeling

Stationary isotropic turbulence

- $\langle U_i \rangle = 0$ and U_1^+, U_2^+ , and U_3^+ are independent and evolve with the same model, i.e. the Langevin model:

$$\frac{dX^*(t)}{dt} = U^*(t). \quad dU^*(t) = -U^*(t) \frac{dt}{T_L} + \left(\frac{2\sigma^2}{T_L} \right)^{1/2} dW(t), \quad (8.55)$$

- The simplest stationary diffusion process called Ornstein-Uhlenbeck (OU) process with

$$dU(t) = a[U(t), t] dt + b[U(t), t] dW(t),$$

$$a(V, t) = -\frac{V}{T_L},$$

$$b(V, t)^2 = \frac{2\sigma^2}{T_L},$$

$$U(0) \stackrel{D}{=} \mathcal{N}(0, \sigma^2),$$

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VII.5 Modeling

Stationary isotropic turbulence

- It can be shown that appendix J [1]:
 - The solution to its Fokker-Planck equation:

$$\frac{\partial f_L^*}{\partial t} = \frac{1}{T_L} \frac{\partial}{\partial V} (V f_L^*) + \frac{\sigma^2}{T_L} \frac{\partial^2 f_L^*}{\partial V^2}. \quad f_L^*(V; t_1 | V_1, t_1) = \delta(V - V_1). \quad (8.56)$$

is:

$$f_L(V; t | V_1, t_1) = \mathcal{N}[V_1 e^{-(t-t_1)/T_L}, \sigma^2 (1 - e^{-2(t-t_1)/T_L})], \quad (8.57)$$

$$\rho(s) = e^{-|s|/T_L}. \quad (8.58)$$

$$T_L \equiv \int_0^\infty \rho(s) ds. \quad (8.59)$$

$$D_L^*(s) \equiv \langle [U^*(t+s) - U^*(t)]^2 \rangle = \frac{2\sigma^2}{T_L} s, \quad \text{for } s \ll T_L, \quad (8.60)$$

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VII.5 Modeling

Stationary isotropic turbulence

- Expressing T_L in terms of k and ε :
 - According to Kolmogorov 2nd-hypothesis:

$$D_L(s) = C_0 \varepsilon s, \quad \text{for } \tau_\eta \ll s \ll T_L, \quad (8.61)$$

From Eqs. (8.60) and (8.61)

$$T_L^{-1} = \frac{C_0 \varepsilon}{2\sigma^2} = \frac{3}{4} C_0 \frac{\varepsilon}{k}. \quad \sigma^2 = \frac{2}{3} k \quad (8.62)$$

$$dU^*(t) = -\frac{3}{4} C_0 \frac{\varepsilon}{k} U^*(t) dt + (C_0 \varepsilon)^{1/2} dW(t). \quad (8.63)$$

- Exercise: Using Eq. (8.43) show that

$$\frac{dk}{dt} = 0$$

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VII.5 Modeling

More general models

- The Simplified Langevin Model (SLM)
 - Extending Eq. (8.63) to 3D inhomogeneous flow

Mean pressure gradient effect To have $\frac{dk}{dt} = \varepsilon$
instead of $\frac{dk}{dt} = 0$

$$\begin{aligned} dU_i^*(t) = & -\frac{1}{\rho} \frac{\partial \langle p \rangle}{\partial x_i} dt - \left(\frac{1}{2} + \frac{3}{4} C_0 \right) \frac{\varepsilon}{k} (U_i^*(t) - \langle U_i \rangle) dt \\ & + (C_0 \varepsilon)^{1/2} dW_i(t), \quad \langle U_i \rangle \neq 0 \end{aligned} \quad (8.64)$$

- Exercise: Using Eq. (8.42) and (8.43) show that

$$\frac{dk}{dt} = \varepsilon$$

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VII.5 Modeling

More general models

- The Generalized Langevin Models (GLMs)

- Extending the drift term in Eq. (8.64)

$$dU_i^*(t) = -\frac{1}{\rho} \frac{\partial \langle p \rangle}{\partial x_i} dt + G_{ij}(U_j^*(t) - \langle U_j \rangle) dt + (C_0 \varepsilon)^{1/2} dW_i(t), \quad (8.65)$$

- For SLM:

$$G_{ij} = -\left(\frac{1}{2} + \frac{3}{4} C_0\right) \frac{\varepsilon}{k} \delta_{ij}, \quad (8.66)$$

$$\frac{dX^*(t)}{dt} = U^*(t). \quad (8.65)'$$

- The corresponding Fokker-Planck equations

$$\frac{\partial f_L^*}{\partial t} = -V_i \frac{\partial f_L^*}{\partial x_i} + \frac{1}{\rho} \frac{\partial f_L^*}{\partial V_i} \frac{\partial \langle p \rangle}{\partial x_i} - G_{ij} \frac{\partial}{\partial V_i} [f_L^* (V_j - \langle U_j \rangle)] + \frac{1}{2} C_0 \varepsilon \frac{\partial^2 f_L^*}{\partial V_i \partial V_i}, \quad (8.67)$$

$$\frac{\partial f^*}{\partial t} + V_i \frac{\partial f^*}{\partial x_i} - \frac{1}{\rho} \frac{\partial f^*}{\partial V_i} \frac{\partial \langle p \rangle}{\partial x_i} = -G_{ij} \frac{\partial}{\partial V_i} [f^* (V_j - \langle U_j \rangle)] + \frac{1}{2} C_0 \varepsilon \frac{\partial^2 f^*}{\partial V_i \partial V_i}. \quad (8.68)$$

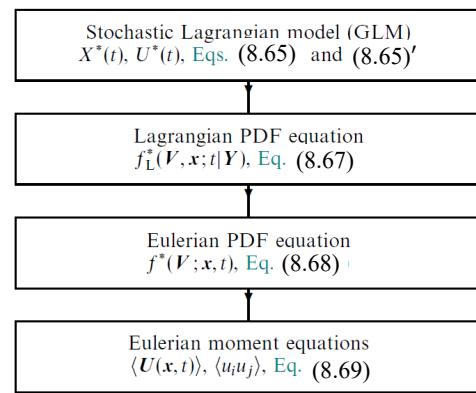
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VII.5 Modeling

More general models

- The Generalized Langevin Models (GLMs)
 - Realizable Reynolds stress models can be derived starting from the SDE or PDF transport equations



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VII.5 Modeling

More general models

- The Generalized Langevin Models (GLMs)
 - Realizable Reynolds stress models can be derived starting from the SDE or PDF transport equations

$$\frac{\bar{D}}{\bar{D}t} \langle u_i u_j \rangle + \frac{\partial}{\partial x_k} \langle u_i u_j u_k \rangle = \mathcal{P}_{ij} + G_{ik} \langle u_j u_k \rangle + G_{jk} \langle u_i u_k \rangle + C_0 \varepsilon \delta_{ij}. \quad (8.69)$$

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VII.5 Numerical solution

Monte Carlo (MC) method

- Given a particle property U at time t_i
- The particle property at time $t_{i+1} = t_i + \Delta t_i$ is computed by integrating a SDE of the general form:

$$dU(t) = a[U(t), t] dt + b[U(t), t] dW(t), \quad (8.70)$$

- Different discretized form of this SDE can be proposed using Ito-Taylor expansion [Sauer,6]
- For detailed derivation see reference [7]
- Knowing U of all particles at time t_{i+1} , the Eulerian statistics of U including its one-point Eulerian PDF can be computed on an Eulerian grid

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VII.5 Numerical solution

SDE discretization

$$dU(t) = a[U(t), t] dt + b[U(t), t] dW(t),$$

- Euler-Maruyama Method:

$$U(t_{i+1}) = U(t_i) + a[t_i, U(t_i)]\Delta t_i + b[t_i, U(t_i)]\Delta W_i \quad (8.71)$$

$$\Delta W_i = W(t_{i+1}) - W(t_i) = \zeta_i \sqrt{\Delta t_i}; \zeta_i \in \mathcal{N}(0,1) \quad (8.72)$$

- Simplified to explicit Euler for ODEs

- The order of convergence:

- Strong: 0.5 (or 1 if $b[t_i, U] = b(t)$)
- Weak: 1

- convergence of order m :

- Strong:

$$\lim_{\Delta t \rightarrow 0} \langle |U(t) - U_{\Delta t}(t)| \rangle = \lim_{\Delta t \rightarrow 0} \mathcal{O}(\Delta t^m) = 0 \quad (8.73)$$

- Weak: (for all polynomials $f(x)$)

$$\lim_{\Delta t \rightarrow 0} |\langle f[U(t)] \rangle - \langle f[U_{\Delta t}(t)] \rangle| = \lim_{\Delta t \rightarrow 0} \mathcal{O}(\Delta t^m) = 0 \quad (8.74)$$

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VII.5 Numerical solution

SDE discretization

- Weak 2nd-Order Runge-Kutta:

$$\begin{aligned} U(t_{i+1}) = & U(t_i) + \frac{1}{2}\{a[U^1(t_{i+1})] + a[U(t_i)]\}\Delta t_i + \\ & \frac{1}{4}\{b[U^+(t_{i+1})] + b[U^-(t_{i+1})] + 2b[U(t_i)]\}\Delta W_i + \\ & \frac{1}{4}\{b[U^+(t_{i+1})] - b[U^-(t_{i+1})]\}(\Delta W_i^2 - \Delta t_i)/\sqrt{\Delta t_i} \end{aligned} \quad (8.75)$$

$$\begin{aligned} U^1(t_{i+1}) &= U(t_i) + a[U(t_i)]\Delta t_i + b[U(t_i)]\Delta W_i \\ U^+(t_{i+1}) &= U(t_i) + a[U(t_i)]\Delta t_i + b[U(t_i)]\sqrt{\Delta t_i} \\ U^-(t_{i+1}) &= U(t_i) + a[U(t_i)]\Delta t_i - b[U(t_i)]\sqrt{\Delta t_i} \end{aligned} \quad (8.76)$$

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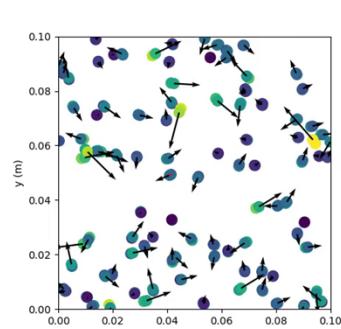
Hands-on practice

- HW#6:**

- Using “pyPDF.py” for 2D stationary isotropic turbulence
- SDE integration

$$\frac{dX^*(t)}{dt} = U^*(t). \quad dU^*(t) = -U^*(t)\frac{dt}{T_L} + \left(\frac{2\sigma^2}{T_L}\right)^{1/2} dW(t), \quad (8.55)$$

- MC computation for one grid cell with N_p particles per cell

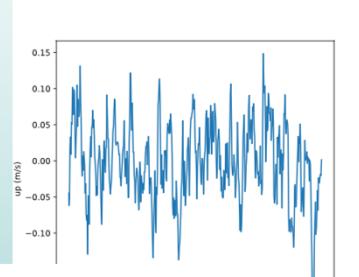


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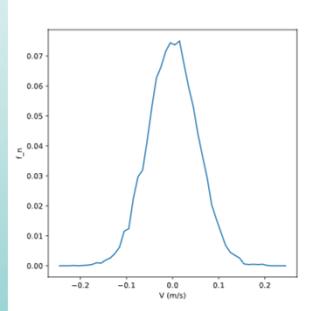
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Hands-on practice

- **HW#6:**
 - Trajectory of $U(t)$ process



- PDF of $U(t)$



- Isotropic decaying turbulence?

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VII.6 Case study

Case study# 2

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An efficient PDF calculation of flame temperature and major species in turbulent non-premixed flames

E. Amani, M.R.H. Nobari*

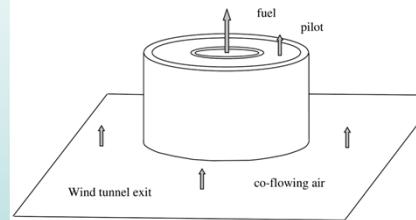
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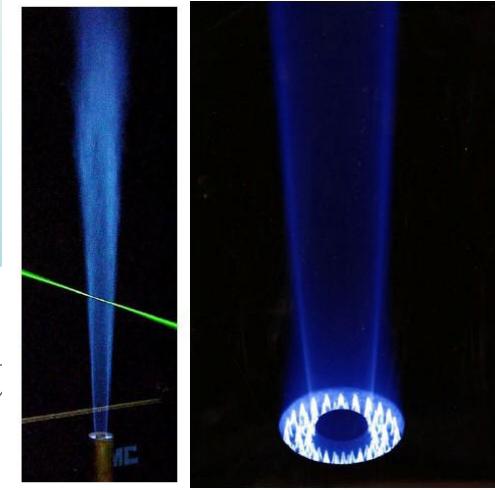
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VII.6 Case study

Test case: Sandia Flame D



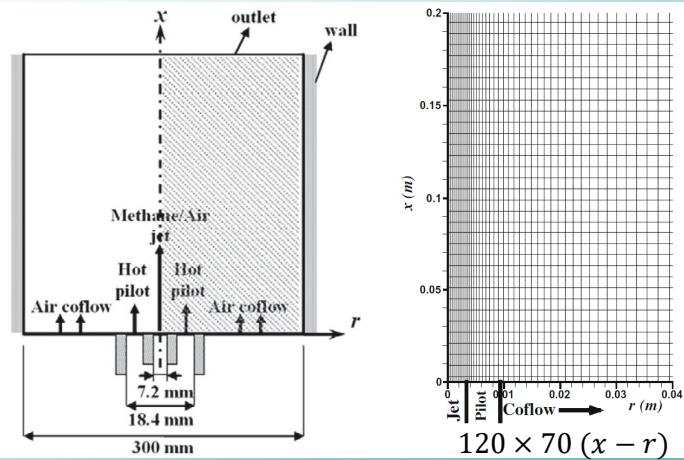
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VII.6 Case study

Computational geometry and grid



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VII.6 Case study

Modeling: RANS

- Mass:

$$\frac{\partial \bar{\rho}}{\partial t} + \frac{\partial \bar{\rho} \tilde{u}_j}{\partial x_j} = 0$$

Reynolds
stresses

- Momentum ($i=1, 2, 3$):

$$\frac{\partial \bar{\rho} \tilde{u}_i}{\partial t} + \frac{\partial \bar{\rho} \tilde{u}_j \tilde{u}_i}{\partial x_j} = - \frac{\partial \bar{\rho} u_i' u_j''}{\partial x_j} + \frac{\partial \bar{\tau}_{ij}}{\partial x_j}$$

- Species (N species with $k=1, \dots, N$):

$$\frac{\partial \bar{\rho} \tilde{Y}_n}{\partial t} + \frac{\partial \bar{\rho} \tilde{u}_j \tilde{Y}_n}{\partial x_j} = - \frac{\partial \bar{\rho} u_j'' Y_n''}{\partial x_j} - \frac{\partial \bar{J}_j^n}{\partial x_j} - \bar{\omega}_n \quad n = 1, \dots, N$$

- Total enthalpy ($h_t = h + u_i u_i / 2$):

$$\frac{\partial \bar{\rho} \tilde{h}}{\partial t} + \frac{\partial \bar{\rho} \tilde{u}_j \tilde{h}}{\partial x_j} = - \frac{\partial \bar{\rho} u_j'' h''}{\partial x_j} + \frac{\partial \bar{J}_j^h}{\partial x_j} - \sum_{n=1}^N h_{ref,n} \bar{\omega}_n$$

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VII.6 Case study

Modeling: PDF

- Velocity-composition space

$$\underline{U} = (U_1, U_2, U_3)$$

$$\underline{\phi} = (Y_1, Y_2, \dots, Y_N, T)$$

- State vector $\Rightarrow (\underline{U}(\underline{x}, t), \underline{\phi}(\underline{x}, t))$
- State sample space: Velocity-Composition space $\Rightarrow (\underline{V}, \underline{\psi})$
- One-point one-time joint PDF: $f_{u\phi}(\underline{V}, \underline{\psi})$

- Statistics:

$$\begin{aligned} \langle Q(\underline{U}, \underline{\phi}) \rangle &= \iint Q(\underline{V}, \underline{\psi}) f_{u\phi}(\underline{V}, \underline{\psi}) d\underline{V} d\underline{\psi} \\ Q &= \langle Q \rangle + Q' \end{aligned}$$

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VII.6 Case study

Modeling: PDF

$$\begin{aligned}
 & \rho(\underline{\psi}) \frac{\partial f}{\partial t} + \rho(\underline{\psi}) V_j \frac{\partial f}{\partial x_j} + (\rho(\underline{\psi}) g_j - \frac{\partial \langle p \rangle}{\partial x_j}) \frac{\partial f}{\partial V_j} + \frac{\partial}{\partial \psi_\alpha} [\rho(\underline{\psi}) S_\alpha(\underline{\psi}) f] \\
 &= \frac{\partial}{\partial V_j} \left[\left\langle -\frac{\partial \tau_{ij}}{\partial x_j} + \frac{\partial p'}{\partial x_j} | \underline{V}, \underline{\psi} \rangle \right\rangle f \right] + \frac{\partial}{\partial \psi_\alpha} \left[\left\langle \frac{\partial J_i^\alpha}{\partial x_i} | \underline{V}, \underline{\psi} \rangle \right\rangle f \right] \\
 &\quad \underbrace{\qquad\qquad\qquad}_{\text{Viscous stresses and fluctuating pressure gradient}} \quad \underbrace{\qquad\qquad\qquad}_{\text{Molecular diffusion}}
 \end{aligned}$$

- Mean pressure \Rightarrow Poisson equation

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Modeling: PDF

- Velocity-composition PDF

$$\begin{aligned}
 & \rho(\underline{\psi}) \frac{\partial f}{\partial t} + \rho(\underline{\psi}) V_j \frac{\partial f}{\partial x_j} + (\rho(\underline{\psi}) g_j - \frac{\partial \langle p \rangle}{\partial x_j}) \frac{\partial f}{\partial V_j} + \frac{\partial}{\partial \psi_\alpha} [\rho(\underline{\psi}) S_\alpha(\underline{\psi}) f] \\
 &= \frac{\partial}{\partial V_j} \left[\left\langle -\frac{\partial \tau_{ij}}{\partial x_j} + \frac{\partial p'}{\partial x_j} | \underline{V}, \underline{\psi} \rangle \right\rangle f \right] + \frac{\partial}{\partial \psi_\alpha} \left[\left\langle \frac{\partial J_i^\alpha}{\partial x_i} | \underline{V}, \underline{\psi} \rangle \right\rangle f \right]
 \end{aligned}$$

- Exercise: What are the corresponding SDEs for $\vec{X}^*(t)$, $\vec{U}^*(t)$, and $\vec{\phi}^*(t)$? (Consult reference [1])

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VII.6 Case study

Modeling: Composition PDF

- PDF for scalar variables
- State space $\underline{\phi} = (Y_1, Y_2, \dots, Y_N, T)$
- Statistics:

$$\langle Q(\underline{\phi}) \rangle = \int_{-\infty}^{+\infty} Q(\underline{\psi}) f_{\underline{\phi}}(\underline{\psi}; \vec{x}, t) d\underline{\psi}$$

$$\langle S_\alpha \rangle \quad \langle \phi'_\alpha \phi'_\beta \rangle \quad \checkmark$$

$$\langle u'_i \phi'_\alpha \rangle \quad \langle u'_i u'_j \rangle \quad \times$$

- Navier-Stokes equations for $\langle \vec{U} \rangle$ and $\langle p \rangle$
- LES or RANS

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Modeling: Composition PDF

$$\frac{\partial \tilde{f}_\phi}{\partial t} + \tilde{U}_i \frac{\partial \tilde{f}_\phi}{\partial x_i} + \frac{1}{\langle \rho \rangle} \frac{\partial}{\partial x_i} [\langle \rho \rangle \langle u_i | \psi \rangle \tilde{f}_\phi] = -\frac{\partial}{\partial \psi_\alpha} \left[\left\langle \frac{\partial J_i^\alpha}{\partial x_i} | \psi \right\rangle \tilde{f}_\phi \right] - \frac{\partial}{\partial \psi_\alpha} [\tilde{f}_\phi S_\alpha(\psi)]$$

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Modeling: Composition PDF

$$\frac{\partial \tilde{f}_\phi}{\partial t} + \tilde{U}_i \frac{\partial \tilde{f}_\phi}{\partial x_i} - \frac{1}{\langle \rho \rangle} \frac{\partial}{\partial x_i} \left[\Gamma_t \frac{\partial \tilde{f}_\phi}{\partial x_i} \right] = - \frac{\partial}{\partial \psi_\alpha} \left[\left\langle \frac{\partial J_i^\alpha}{\partial x_i} | \psi \right\rangle \tilde{f}_\phi \right] - \frac{\partial}{\partial \psi_\alpha} \left[\tilde{f}_\phi S_\alpha(\psi) \right]$$

Curl's model
LIEM
,...

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Modeling: Composition PDF

$$\frac{\partial \tilde{f}_\phi}{\partial t} + \tilde{U}_i \frac{\partial \tilde{f}_\phi}{\partial x_i} - \frac{1}{\langle \rho \rangle} \frac{\partial}{\partial x_i} \left[\Gamma_t \frac{\partial \tilde{f}_\phi}{\partial x_i} \right] = E(\bar{\psi}; \bar{x}, t) - \frac{\partial}{\partial \psi_\alpha} \left(\tilde{f}_\phi S_\alpha(\psi) \right)$$

Micro-mixing

Reaction

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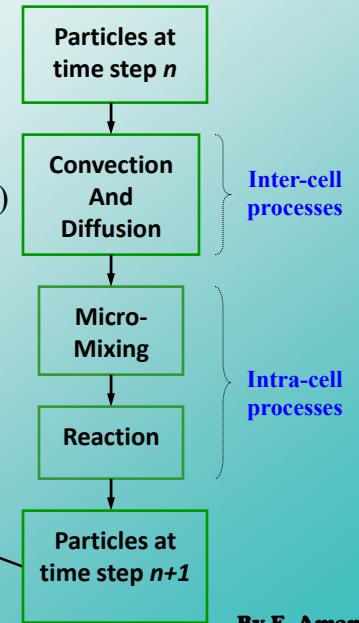
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VII.6 Case study

Numerics

- Fractional step algorithm
- A grid of computational cells
- There are N_ℓ particles in each cell (\vec{x}_ℓ, t)
- Each particle has a value $\phi^{(n)}$
- Statistics in each cell at each time are calculated from the particles presented in that cell at the given time

$$\langle \phi_\alpha \rangle(\vec{x}_\ell, t) = \frac{1}{N_\ell} \sum_{n=1}^{N_\ell} \phi_\alpha^{(n)}(\vec{x}_\ell, t) + \text{statistical error}$$



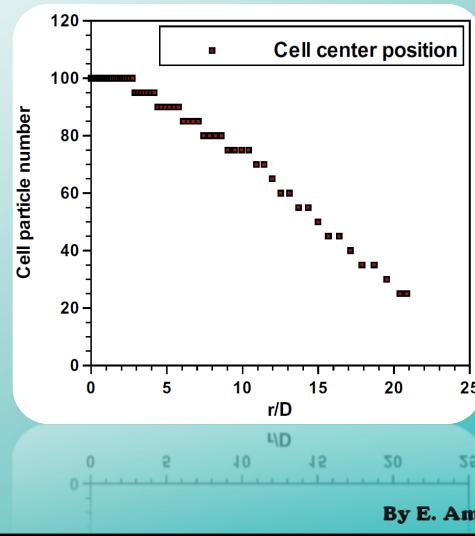
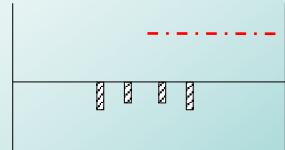
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Numerics

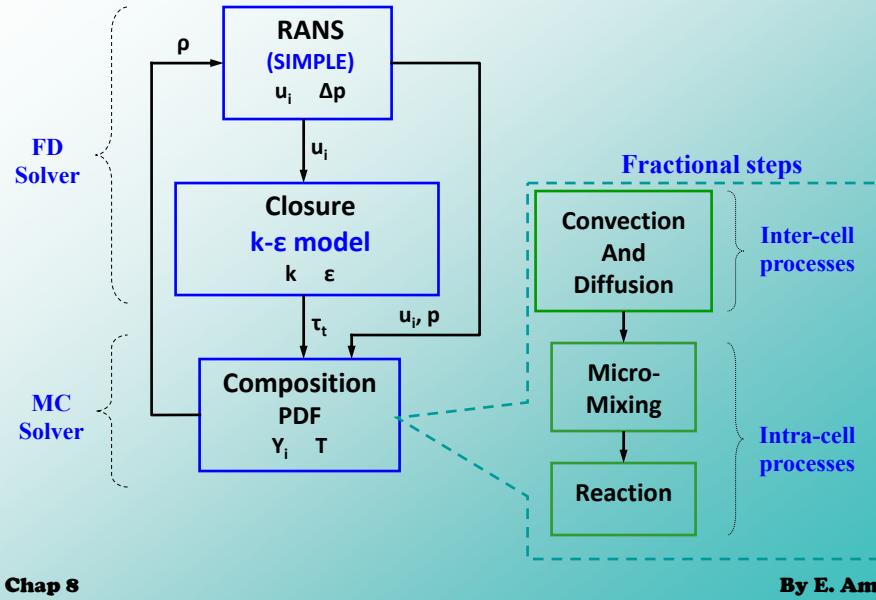
- Particles per cell



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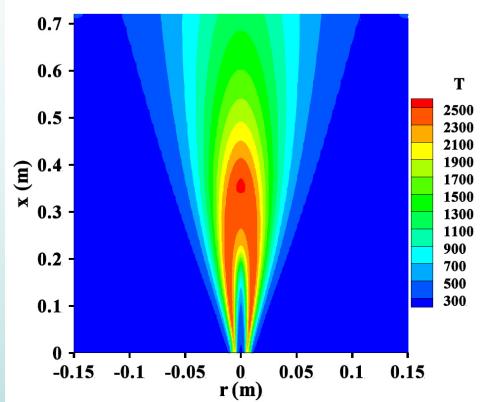
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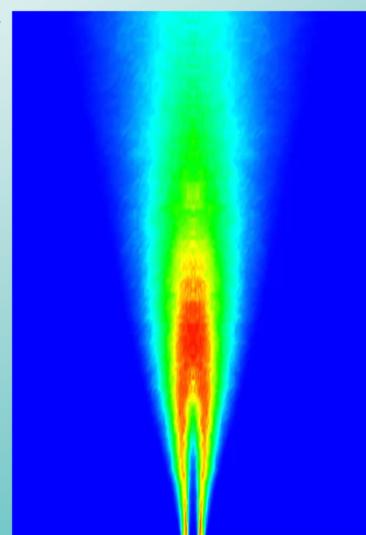
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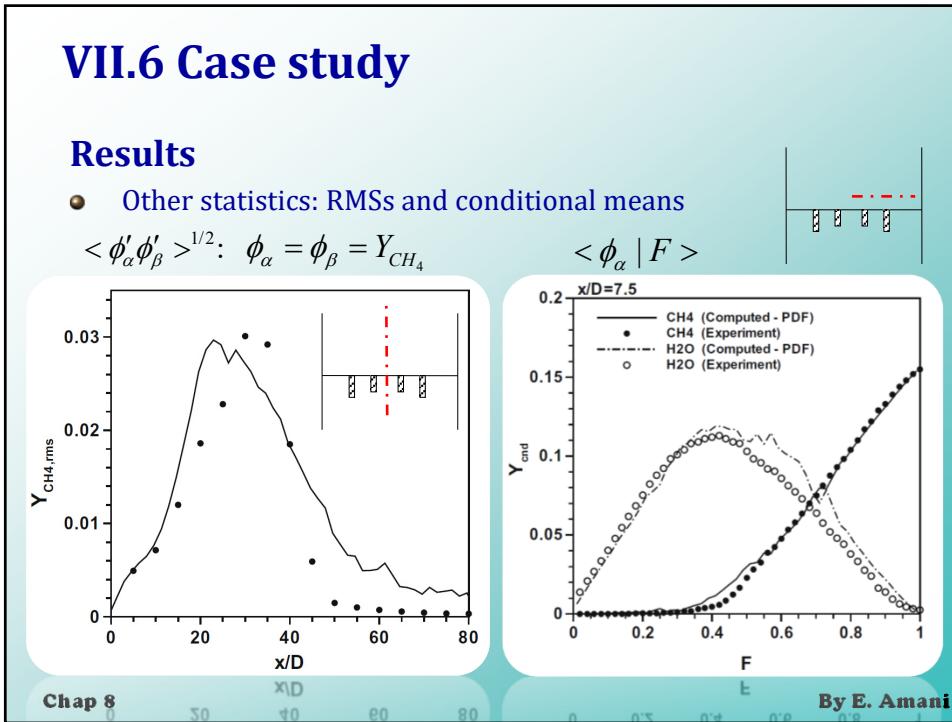
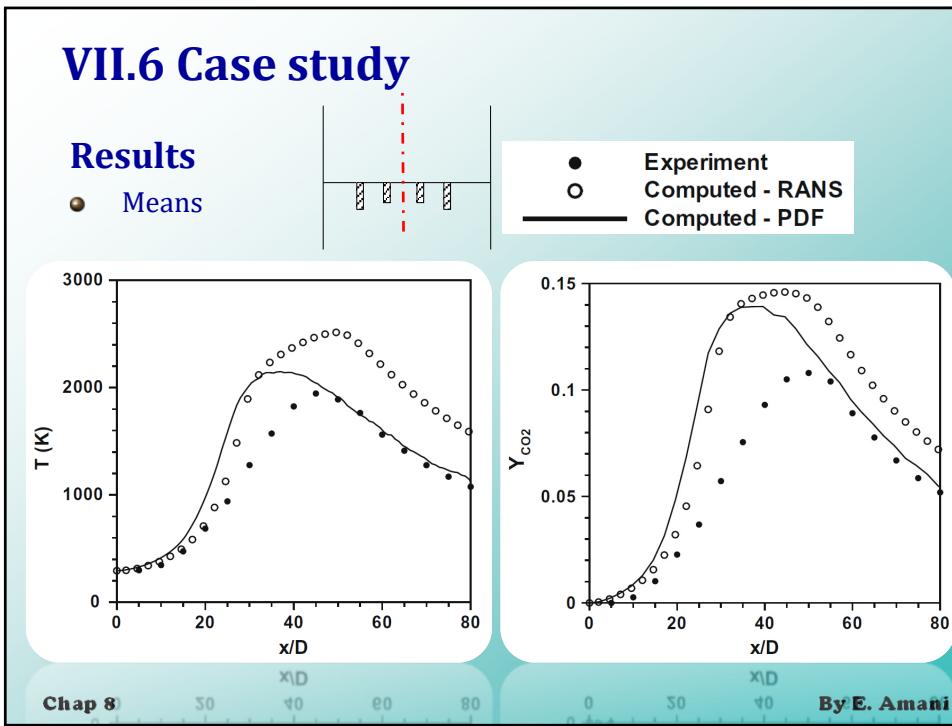
Results

▼ RANS



PDF ►

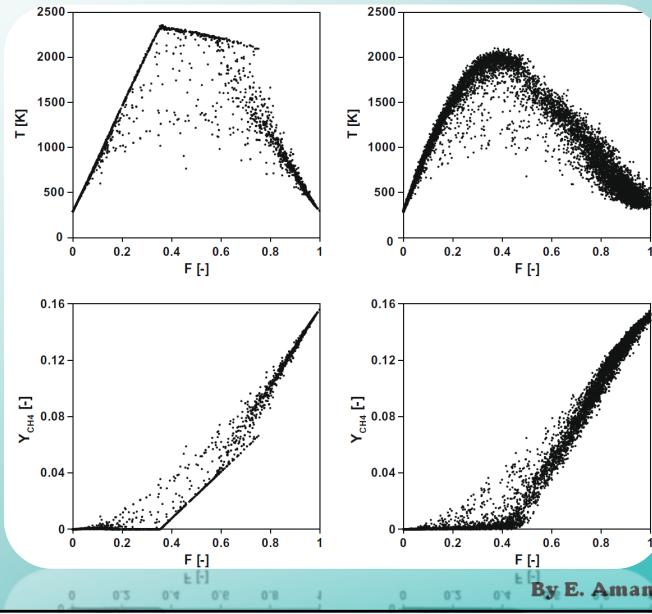




VII.6 Case study

Results

- Scatter plots



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