

# **Conservation of mass (continuity)**

• For a general control volume

$$\frac{Dm_s}{Dt} = 0 \quad (1.7) \qquad B = m \longrightarrow b \equiv \frac{dB}{dm} = \frac{dm}{dm} = 1$$

$$(7.6) \qquad Dm_s = \frac{d}{dt} \int_{\mathcal{V}_{\sigma}} \rho b d\mathcal{V} + \int_{A} \rho b (\vec{V} - \vec{V}_{\sigma}) . \vec{n} dA = 0$$

$$(1.7) \qquad (1.7)$$

$$\longrightarrow \underbrace{\frac{d}{dt} \iiint_{\mathcal{U}_{\sigma}} \rho d\mathcal{U}}_{\mathcal{U}_{\sigma}} + \underbrace{\oiint_{A} \rho \vec{V}_{r}. \vec{n} dA}_{=0} = 0 \quad (2.7) \quad \frac{dm_{\sigma}}{dt} + \sum_{\text{out}} \dot{m} - \sum_{\text{in}} \dot{m} = 0$$

Rate of change of mass in the control flowrate from the volume control surface

• For a fixed Control Volume (C.V.)  $(\vec{V}_{\sigma} = 0)$ 

$$\frac{\partial}{\partial t} \iiint_{\mathcal{U}_{\sigma}} \rho d\mathcal{U} + \oiint_{A} \rho \vec{V} \cdot \vec{n} dA = 0 \quad (3.7)$$

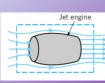
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# **Conservation of mass (continuity)**

- Simplified forms
  - 1. For a fixed C.V. in a steady flow:

$$\frac{\partial}{\partial t} \iiint_{\mathcal{V}_{\sigma}} \rho d\mathcal{V} = \iiint_{\mathcal{V}_{\sigma}} \frac{\partial \rho}{\partial t} d\mathcal{V} = 0$$

$$\oint_{A} \rho \vec{V} \cdot \vec{n} dA = 0 \qquad (4.7) \qquad \sum_{\text{out}} \dot{m} = \sum_{\text{in}} \dot{m}$$



3. For an incompressible flow (and single-phase):

$$\overbrace{\rho = cte}^{(2.7)} \rho \frac{d}{dt} \iiint_{\mathcal{U}_{\sigma}} d\mathcal{U} + \rho \oiint_{A} \vec{V}_{r} \cdot \vec{n} dA = 0 \longrightarrow \frac{d\mathcal{U}_{\sigma}}{dt} + \oiint_{A} \vec{V}_{r} \cdot \vec{n} dA = 0$$
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$$\sum_{\text{out}} Q - \sum_{\text{in}} Q \longrightarrow_{\text{By E. Amani}} (4.7)^{"}$$

# **Conservation of mass (continuity)**

- Simplified forms
  - 4. For a moving, non-deforming C.V. and an incompressible flow (in the C.V.-attached reference frame)

$$\underbrace{(4.7)^{"}}_{A} \oint_{A} \vec{V}_{r} \cdot \vec{n} dA = 0 \quad (5.7) \quad \sum_{\text{out}} Q = \sum_{\text{in}} Q$$

5. For a 1D inlet or outlet normal to the flow

$$\dot{m} = \iint \rho \vec{V_r} \cdot \vec{n} dA = \rho V_r A$$
  $Q = \iint \vec{V_r} \cdot \vec{n} dA = V_r A$ 

Note: It can be shown that Eqs. (4.7)" and (5.7) also valid for incompressible multiphase flows  $(D\rho/Dt = 0 \text{ instead of } \rho = cte)$ .

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# **Conservation of mass (continuity)**

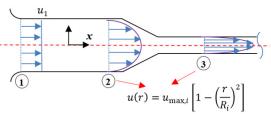
#### Sample problem

A steady-state incompressible flow develops in a pipe system. The velocity profiles are shown at three different sections. Determine the maximum velocity at sections 2 and 3 as a function of the inlet velocity,  $u_1$ , and pipe sizing  $(R_1 = R_2 = 2R_3)$ . The flow is assumed parallel, in the x direction.



**Lecture Notes** 

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# The (linear) momentum equation

For a general control volume

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$$\sum \vec{F}_{\sigma} = \frac{d}{dt} \iiint_{\mathcal{V}_{\sigma}} \vec{V} \rho d\mathcal{V} + \oiint_{A} \vec{V} (\rho \vec{V}_{r}. \vec{n}) dA \qquad (10.7)$$

Resultant external force acting on the control volume

Rate of change of momentum in the control volume control surface

Net momentum outflowrate from the control surface

- Simplified forms
  - 1. For an inertial C.V. (moving with a constant velocity)

$$\underbrace{\vec{V} - \vec{V}_r}_{\vec{V}} = \frac{10.7}{\vec{V}_r} \sum_{\vec{V}_r} \vec{F}_{\sigma} = \frac{1}{dt} \iiint_{\vec{U}_{\sigma}} \vec{V}_r \rho d\vec{U} + \iint_{\vec{V}_r} \vec{V}_r (\rho \vec{V}_r, \vec{n}) d\vec{A} \qquad (11.7)$$

Exercise: For an inertial C.V. both Eqs. (10.7) and (11.7) are valid. Therefore, the right-hand-side of these equations should be equal. Show this equality with the aid

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# The (linear) momentum equation

- **Simplified forms** 
  - For an inertial C.V. and a steady flow in the C.V.attached reference frame

Non-deforming
$$\frac{d}{dt}\iiint_{\mathcal{V}_{\sigma}}\vec{V}_{r}\rho d\mathcal{V} = \iiint_{\mathcal{V}_{\sigma}}\frac{d}{dt}[\rho(\vec{V}-\vec{V}_{\sigma})]d\mathcal{V}$$

$$\sum \vec{F}_{\sigma} = \oiint_{A}\vec{V}_{r}(\rho\vec{V}_{r}.\vec{n})dA \qquad (12.7)$$

3. For 1D inlets and outlets:

$$\sum \vec{F}_{\sigma} = \frac{d\vec{P}_{\sigma}}{dt} + \sum_{\text{out}} \dot{m}\vec{V} - \sum_{\text{in}} \dot{m}\vec{V}$$

$$\sum \vec{F}_{\sigma} = \frac{d\vec{P}_{\sigma,r}}{dt} + \sum_{\text{out}} \dot{m}\vec{V}_{r} - \sum_{\text{in}} \dot{m}\vec{V}_{r}$$
(10.7)

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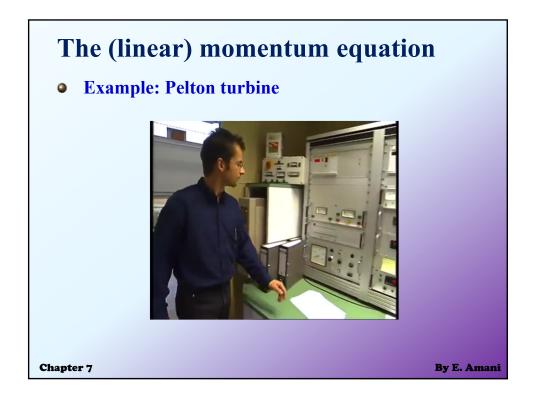
# The (linear) momentum equation

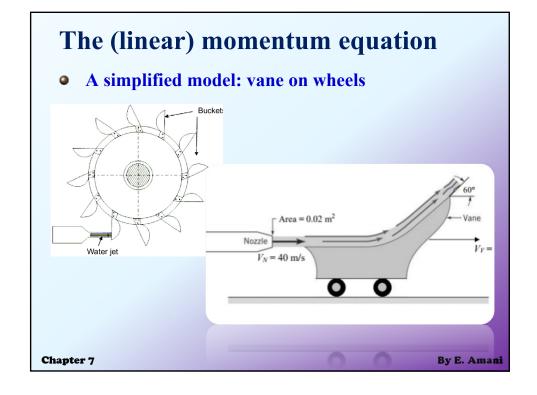
**Example: Pelton turbine** 

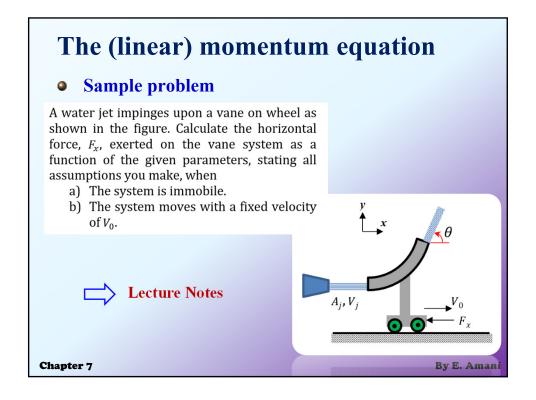


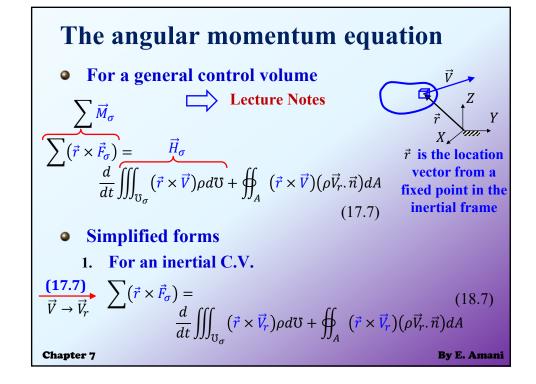
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# The angular momentum equation

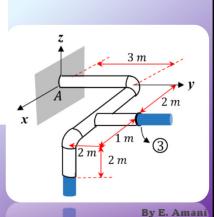
#### Sample problem

The piping system shown in the figure has been attached to the structure at section A. Water flows steadily in the system. The water flow rate and pressure at section A are  $Q_A=0.01\,m^3/s$  and  $p_A=300\,kPa$ . Calculate the resultant force and moment exerted from the water and piping system on the wall structure. Water outflow at section 3 is  $Q_3=0.004\,m^3/s$ , the internal pipe cross-sectional area is  $A_{in}=2580\,mm^2$ , the specific weight of the system (pipe and water) per unit length of pipes is  $W'=300\,N/m$ , and  $\rho_{water}=1000\,kg/m^3$ .



**Lecture Notes** 

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#### The (linear) momentum equation

Using a noninertial reference frame



$$\sum \vec{F}_{\sigma} - \iiint_{\mathcal{U}_{\sigma}} \left[ \ddot{\vec{R}} + 2\vec{\omega} \times \vec{V}_{rel} + \dot{\vec{\omega}} \times \vec{r}_{rel} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{rel}) \right] \rho d\mathcal{U}$$

$$= \frac{d}{dt} \iiint_{\mathcal{U}_{\sigma}} \vec{V}_{rel} \rho d\mathcal{U} + \oiint_{A} \vec{V}_{rel} (\rho \vec{V}_{r}. \vec{n}) dA \qquad (14.7)$$

$$\vec{V}_{rel} = \vec{V}_{XYZ} - (\dot{\vec{R}} + \vec{\omega} \times \vec{r}_{rel}) \qquad \vec{V}_{r} = \vec{V}_{XYZ} - \vec{V}_{\sigma}$$

- Simplified forms (noninertial reference frame)
  - 1. For a nondeforming (rigid-body-like moving) C.V. and the C.V.-attached local reference frame

$$\vec{V}_{rel} = \vec{V}_r$$

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#### The (linear) momentum equation

- Simplified forms (noninertial reference frame)
  - 2. For a nondeforming C.V. in a linear motion (uniform  $\ddot{R}$  and  $\vec{\omega} = \dot{\vec{\omega}} = 0$ ) and the C.V.-attached local reference frame

$$\iiint_{\mathbb{U}_{\sigma}} \ddot{\vec{R}} \rho d\mathbb{U} = \ddot{\vec{R}} \iiint_{\mathbb{U}_{\sigma}} \rho d\mathbb{U} = \ddot{\vec{R}} m_{\sigma} \quad \longrightarrow$$

$$\sum \vec{F}_{\sigma} - m_{\sigma} \ddot{\vec{R}} = \frac{d}{dt} \iiint_{\mathcal{U}_{\sigma}} \vec{V}_{r} \rho d\mathcal{U} + \oint_{A} \vec{V}_{r} (\rho \vec{V}_{r}. \vec{n}) dA$$
 (15.7)

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# The angular momentum equation

• Using a noninertial reference frame

• Exercise: Show that

$$\sum (\vec{r}_{rel} \times \vec{F}_{\sigma}) - \sum_{\vec{v}} (\vec{r}_{rel} \times \vec{F}_{\sigma}) - \sum_{\vec{v}} (\vec{r}_{rel} \times \vec{V}_{rel}) \rho d\vec{v} = \frac{d}{dt} \iiint_{\vec{v}} (\vec{r}_{rel} \times \vec{V}_{rel}) \rho d\vec{v} + \iint_{\vec{v}} (\vec{r}_{rel} \times \vec{V}_{rel}) (\rho \vec{V}_{r}.\vec{n}) dA$$
(21.7)

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