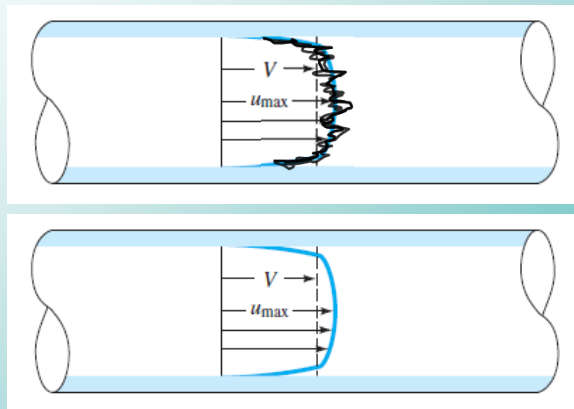


## Introduction

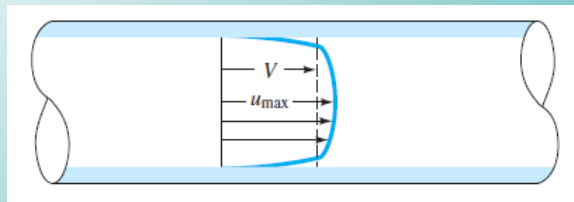
### The concept of averaging



## Introduction

### The concept of averaging

- The mean (averaged) velocity can be captured by a much **coarser grid** and much **lower computational cost (+)**
- Therefore, the governing equations of the mean properties (**RANS equations**) can be governed (the **goal** of this chapter) and solved.



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## Introduction

### The concept of averaging

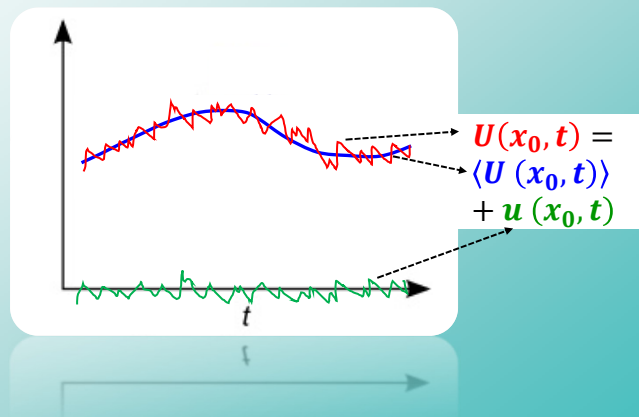
- The mean (averaged) velocity can be captured by a much **coarser grid** and much **lower computational cost (+)**
- Therefore, the governing equations of the mean properties (**RANS equations**) can be governed (the **goal** of this chapter) and solved.
- In **most engineering applications**, we seek to find the **mean properties**.
- Therefore, when a direct numerical simulation (**DNS**) is applied, the solution is averaged to find the mean flow.
- A question arises: **what is the benefit of DNS or LES? Or what is the limitation of RANS?**

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## III.1 Reynolds averaging

### Mean and fluctuation



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## III.1 Reynolds averaging

➡ Lecture Notes: 3.1

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### III.2 The decomposition of the kinetic energy

- The mean of kinetic energy can be decomposed into two parts:

$$(3.7) \quad \langle E(\vec{x}, t) \rangle = \left\langle \frac{1}{2} \vec{U} \cdot \vec{U} \right\rangle = \underbrace{\frac{1}{2} \langle \vec{U} \rangle \cdot \langle \vec{U} \rangle}_{\bar{E}(\vec{x}, t)} + \underbrace{\frac{1}{2} \langle \vec{u} \cdot \vec{u} \rangle}_{k(\vec{x}, t)}$$

$$\langle E(\vec{x}, t) \rangle = \bar{E}(\vec{x}, t) + k(\vec{x}, t) \quad (3.10)$$

Kinetic energy  
of the mean flow

Turbulent kinetic  
energy

$$\bar{E}(\vec{x}, t) = \frac{1}{2} \langle \vec{U} \rangle \cdot \langle \vec{U} \rangle \quad (3.11)$$

$$k(\vec{x}, t) = \frac{1}{2} \langle \vec{u} \cdot \vec{u} \rangle = \frac{1}{2} \langle u_i u_i \rangle = \frac{1}{2} \text{tr} \{ \langle u_i u_j \rangle \} \quad (3.12)$$

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### III.2 The decomposition of the kinetic energy

- Averaging kinetic energy transport equation, Eq. (2.17):

$$\underbrace{\left\langle \frac{DE}{Dt} \right\rangle}_{(3.6)} + \underbrace{\vec{\nabla} \cdot \left\langle \frac{p\vec{U}}{\rho} - 2\nu \underline{S} \cdot \vec{U} \right\rangle}_{\vec{T}} = -2\nu \underbrace{\langle \underline{S} : \underline{S} \rangle}_{(3.7)} \quad (3.7)$$

$$\frac{\bar{D}\langle E \rangle}{\bar{D}t} + \vec{\nabla} \cdot \langle \vec{u} e \rangle$$

$$\frac{\bar{D}\langle E \rangle}{\bar{D}t} + \vec{\nabla} \cdot [\langle \vec{u} e \rangle + \langle \vec{T} \rangle] = -\bar{\varepsilon} - \varepsilon \quad (3.13)$$

$$\bar{\varepsilon} = 2\nu \langle \underline{S} : \underline{S} \rangle \quad (3.14) \quad \text{: dissipation due to the mean flow}$$

$$\varepsilon = 2\nu \langle \underline{s} : \underline{s} \rangle \quad (3.15) \quad \text{: turbulent dissipation}$$

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### III.2 The decomposition of the kinetic energy

- **Knowing:**

$$\langle \underline{s} \rangle = \left\langle \frac{1}{2} [(\vec{\nabla} \vec{U})^T + \vec{\nabla} \vec{U}] \right\rangle = \frac{1}{2} [(\vec{\nabla} \langle \vec{U} \rangle)^T + \vec{\nabla} \langle \vec{U} \rangle] \quad (3.16)$$

$$\underline{s} = \underline{s} - \langle \underline{s} \rangle = \frac{1}{2} [(\vec{\nabla} \vec{u})^T + \vec{\nabla} \vec{u}] \quad (3.17)$$

$$\vec{\nabla} \cdot \underline{s} = \frac{1}{2} \nabla^2 \vec{U} \quad (3.17)'$$

$$\vec{\nabla} \cdot \underline{\Omega} = -\frac{1}{2} \nabla^2 \vec{U} \quad (3.17)''$$

⇒ **Proof: Appendix**

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### III.2 The decomposition of the kinetic energy

- **Taking the dot product of  $\langle \vec{U} \rangle$  and mean momentum equation, Eq. (3.4)' (**Proof: appendix**):**

$$\frac{\overline{D}\bar{E}}{\overline{D}t} + \vec{\nabla} \cdot \left[ \langle \vec{U} \rangle \cdot \langle \vec{u}\vec{u} \rangle + \frac{\langle p \rangle \langle \vec{U} \rangle}{\rho} - 2\nu \langle \vec{U} \rangle \cdot \langle \underline{s} \rangle \right] = \underbrace{\langle \vec{u}\vec{u} \rangle : \vec{\nabla} \langle \vec{U} \rangle}_{-\mathcal{P}} - \bar{\varepsilon} \quad (3.18)$$

$$\mathcal{P} = -\langle \vec{u}\vec{u} \rangle : \vec{\nabla} \langle \vec{U} \rangle = -\langle u_i u_j \rangle \frac{\partial \langle U_i \rangle}{\partial x_j} \quad (3.19)$$

- **Exercise: Subtracting Eq. (3.18) from Eq. (3.13), show that:**

$$\frac{\overline{D}k}{\overline{D}t} + \vec{\nabla} \cdot \left[ \frac{1}{2} \langle \vec{u}\vec{u} \cdot \vec{u} \rangle + \frac{\langle p' \vec{u} \rangle}{\rho} - 2\nu \langle \vec{u} \cdot \underline{s} \rangle \right] = \mathcal{P} - \varepsilon \quad (3.21)$$

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### III.2 The decomposition of the kinetic energy

$$\frac{\overline{D}\bar{E}}{\overline{D}t} + \vec{\nabla} \cdot \left[ \langle \vec{U} \rangle \cdot \langle \vec{u}\vec{u} \rangle + \frac{\langle p \rangle \langle \vec{U} \rangle}{\rho} - 2\nu \langle \vec{U} \rangle \cdot \langle \underline{S} \rangle \right] = -\mathcal{P} - \bar{\varepsilon} \quad (3.18)$$

$$\frac{\overline{D}k}{\overline{D}t} + \vec{\nabla} \cdot \left[ \frac{1}{2} \langle \vec{u}\vec{u} \cdot \vec{u} \rangle + \frac{\langle p' \vec{u} \rangle}{\rho} - 2\nu \langle \vec{u} \cdot \underline{S} \rangle \right] = \mathcal{P} - \varepsilon \quad (3.21)$$

$$\mathcal{P} = -\langle u_i u_j \rangle \frac{\partial \langle U_i \rangle}{\partial x_j} \quad (3.19)$$

- Experiment:  $\mathcal{P}$  is **almost** always a positive quantity (**Production of turbulent kinetic energy**).
- The action of the **mean velocity gradients** working against the Reynolds stresses
- Removes energy from the mean flow and **transfers** it to the fluctuating field

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## Homework

- HW#2:
  - The **derivation** of some important relations
  - A practice on working with **tensorial** as well as **suffix** notation

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