


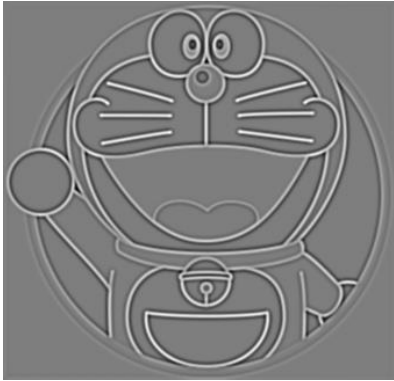






# Computer Vision HW1 Report

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## Part 1.

- Visualize the DoG images of 1.png.

	DoG Image (threshold = 5)		DoG Image (threshold = 5)
DoG1-1.png		DoG2-1.png	
DoG1-2.png		DoG2-2.png	
DoG1-3.png		DoG2-3.png	
DoG1-4.png		DoG2-4.png	

- Use three thresholds (2, 5, 7) on 2.png and describe the difference.

Threshold	Image with detected keypoints on 2.png
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2			
5			
7			

(describe the difference)

Threshold 是 2 的時候有很多在文字、盤子邊緣的點，往 threshold 越大變越少，而且留下來的 keypoint 與周圍顏色差距比較大（灰白對比黑白）




## Part 2.

- Report the cost for each filtered image.

Gray Scale Setting	Cost (1.png)	Gray Scale Setting	Cost (2.png)
cv2.COLOR_BGR2GRAY	1207799	cv2.COLOR_BGR2GRAY	183850
$R*0.0+G*0.0+B*1.0$	1439568	$R*0.1+G*0.0+B*0.9$	77883
$R*0.0+G*1.0+B*0.0$	1305961	$R*0.2+G*0.0+B*0.8$	86023
$R*0.1+G*0.0+B*0.9$	1393620	$R*0.2+G*0.8+B*0.0$	188019
$R*0.1+G*0.4+B*0.5$	1279697	$R*0.4+G*0.0+B*0.6$	128341
$R*0.8+G*0.2+B*0.0$	1127913	$R*1.0+G*0.0+B*0.0$	110862

- Show original RGB image / two filtered RGB images and two grayscale images with highest and lowest cost.


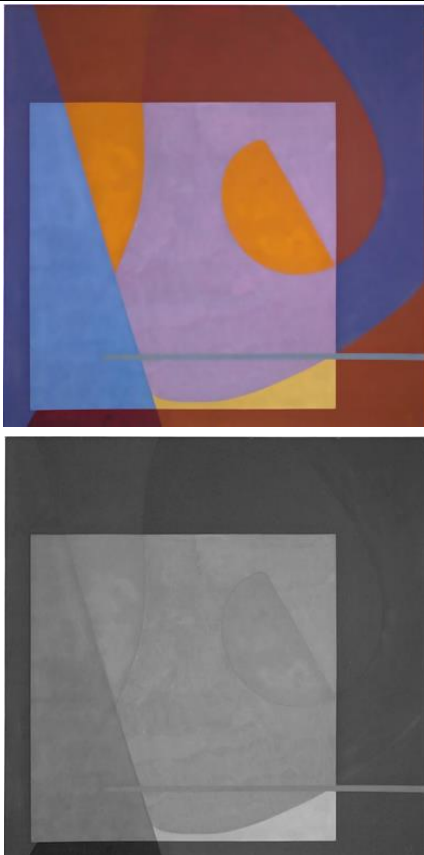
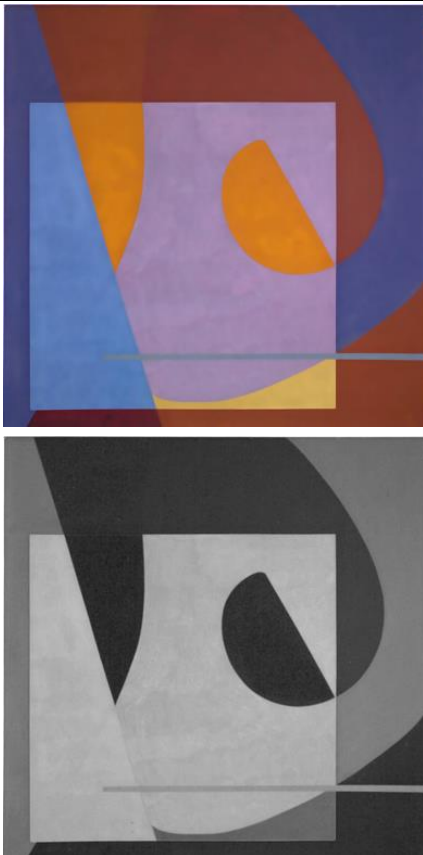
Original RGB image (1.png)	Filtered <u>RGB image</u> and	Filtered <u>RGB image</u> and
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	Grayscale image of Highest cost	Grayscale image of Lowest cost
		

(Describe the difference between those two grayscale images)

Highest cost: 葉子本身與草地黑白差距小，做出來的 image 邊緣較模糊（葉子的斑點看不太清楚）

Lowest cost: 葉子本身與草地黑白差距大，做出來的 image 邊緣較清楚，保留較多細節

Original RGB image (2.png)	Filtered <u>RGB image</u> and <u>Grayscale image</u> of Highest cost	Filtered <u>RGB image</u> and <u>Grayscale image</u> of Lowest cost
		

(Describe the difference between those two grayscale images)

Highest cost: 相鄰色塊黑白差距小，中間橘紫顏色看起來差不多，做出來的 image 邊緣較模糊

Lowest cost: 相鄰色塊黑白差距大，做出來的 image 邊緣較清楚

- **Describe how to speed up the implementation of bilateral filter.**

- 我在自己的電腦上測試的結果：

- JBF.so:1.3 sec

- My result: 0.87~0.93 sec

- 一開始是用 `for (r, c) in (row, column)` 的形式來算每個 pixel 的值，spatial kernel 用查表的，range kernel 用算的，大約是 8 秒。

- 後來把 range kernel 也改用查表呼叫，大約是 3 秒。

- 到此時我發現我是做

- `for (r, c) in (row, column):`

- `output[r, c] = spatial[r, c] ... range[r, c] ... image[r, c] / spatial[r, c] ... range[r, c]`

類似於這種取值方式，就覺得應該可以改成全部一起算。

- 改成先得到一個 kernel matrix (是 spatial kernel 跟 range kernel 相乘的結果)，`shape = (r, c, window, window)`，以 sample 為例是 `(314, 314, 19, 19)`。

跟 original image 的 `sliding window(314, 314, 19, 19, 3)` 去做 element wise 相乘再加起來得到原公式的分子。

就只是把原本查表的方法改成包進 `(314, 314)` 的矩陣做運算，不使用 `for (r, c) in (row, column)` 來加速，沒用到新的數學方法或定理，只是要花很多時間解決 array shape, broadcast 等問題。