

Building Smart Drones with ESP 8266 and Arduino | TEAM MEETING

Date: 4th October 2019

Time: 4.00 pm – 9.00 pm

Meeting location: Delta, UHCL

Type of Meeting:

In- Person

Attendees:

Thati, Sravika

Patel, Binal

Mohammed, Ehtheshamuddin

AGENDA TOPICS

Time allotted: 4:00 PM – 9:00 PM |

Agenda topic: *Assembling and communication of the Drone*

Minutes:

- Completed Architectural Design document.
- Completed Mid presentation of the project.
- Purchased Telemetry and OTG connector.
- Continued to assemble the components of the drone.
- Researched about calibration of the components.
- Discussed about the ways to communicate with the Drone.
- Scheduled and uploaded the Team meeting report on the website and the weekly report on the Blackboard.
- Watched tutorials and videos on how to assemble and calibrate components of the drone.

Future Action Items:

- Connect the telemetry and GPS module to the ArduPilot.
- Start to build communication between the Drone and Smartphone.
- Watch videos about Calibration of drone.
- Start calibrating the components and programming.

Deadline:

15th October 2019