

# Building Smart Drones with ESP 8266 and Arduino | MENTOR MEETING

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2<sup>nd</sup> October, 2019 | Time: 06:00 PM – 07:00 PM | Meeting location: Zoom Meeting

## Type of Meeting:

Video Conference

## Attendees:

**Mentor:** Dr. Duo Chen

## Team Members:

Thati, Sravika

Patel, Binal

Mohammed, Ehteshamuddin

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## AGENDA

**Time allotted:** 06:00 PM – 07:00 PM

**Agenda topic:** *Assembling and communication of the Drone*

## Minutes:

- **Question and Answer:**

1. **Binal:** Do we need to use Telemetry?

**Answer:** Yes, because we need a communication.

2. **Sravika:** We can also communicate Drone with the phone through the ESP 8266, right?

**Answer:** Yes, it's another way to communicate. Wi-Fi module allows you to communicate with a small amount of range.

3. **Dr. Chen:** What language you are using to program ESP 8266?

**Sravika:** Using C programming language. Dr. Chen replied that he uses LUA for programming.

4. **Binal:** Can we use Java?

**Answer:** C is preferred to control the micro controllers. If you want to use other languages use python but not Java as it is a high-level language it might get complicated.

**5. Ehtheshamuddin:** If we use wifi module to communicate, Is that okay?

**Answer:** It's okay

**6. Ehtheshamuddin:** How to connect Arduino Nano and ArduPilot?

**Answer:** There are two ways for the communication: either use Arduino Nano or ArduPilot. If we use ArduPilot then communication occurs using Telemetry or Remote Controller.

**Conclusion:** Detail discussion occurred on the different ways to communicate the drone with Smart phone. Conversation ended with the conclusion to make drone using ArduPilot with the Telemetry or Remote Controller.

**Future Action Items:**

- Connect the telemetry and GPS module to the ArduPilot.
- Start to build communication between the Drone and Smartphone.
- Watch videos about Calibration of drone.
- Start calibrating the components and programming.

**Deadline:** 15<sup>th</sup> October, 2019