

RZ/A2M Group

RZ/A2M Software Package for GR-MANGO Quick Start Guide

1. Introduction

This is the Quick Start Guide for the RZ/A2M Software Package for GR-MANGO which works on GR-MANGO board by CORE CORPORATION and the operation of Renesas e² studio.

This document describes how to run each executable sample project included in the package.

2. Preparation

2.1 Tool

RZ/A2M Software Package for GR-MANGO can be used on the following environment. Please check your environment before continuing.

Tools:

- IDE: e² studio 2021-04 Windows 64-bit product version or later
Available from
<https://www.renesas.com/software-tool/rza2m-freertos-software-package>
- Tool Chain: GNU ARM Embedded Toolchain 6-2017-q2-update
This tool is bundled in the IDE above. Available from
<https://developer.arm.com/tools-and-software/open-source-software/developer-tools/gnu-toolchain/gnu-rm/downloads/6-2017-q2-update>

Refer to the following document for the details of installing e2 studio.

- [e2 studio Integrated Development Environment User's Manual: Getting Started](#)

Target Board:

GR-MANGO

ICE (In-circuit emulator):

On GR-MANGO environment, user do not need to prepare an ICE for programming and debugging.

GR-MANGO supports Arm Mbed DAPLink feature for rapid prototyping. DAPLink provides features below.

- ✓ drag-and-drop programming (MSC)
- ✓ a virtual serial port (CDC)
- ✓ CMSIS-DAP based debugging (HID)

For more detail of DAPLink specification, please refer following page.

<https://os.mbed.com/handbook/DAPLink>

Bootloader:

This package includes the bootloader as table data. If user would like to get the source code, please access following website.

<https://www.mx.com.tw/en-us/support/technical-documentation/Pages/Serial-NOR-Flash.aspx>

2.2 Virtual Serial Port Connection

Connect CN1 on the GR-MANGO board to a Windows™ PC, this provides a USB virtual serial port.

When the RZ/A2M SUB board is first connected, the PC will look for a suitable driver. This driver is installed during the installation process and the PC should automatically find and install it. The PC will report it is installing a driver and report a driver has been installed successfully. The COMx port number allocated to the virtual serial port can be confirmed in Windows™ Device Manager.

2.3 Serial Terminal

- Start a serial terminal program (such as PuTTY, HyperTerminal or Tera Term) using the following configuration:

Baud Rate: 115200

Data Bits: 8

Parity: None

Stop Bits: 1

Flow Control: None

COM Port: As shown in Windows™ Device Manager.

3. Trying sample application

3.1 Importing Software Package into IDE

This package is distributed as an archive file. Build project of this package can be imported into e² studio from the Project Import Menu. User can import the project to e² studio by the following procedure in this section.

- Obtain the package to use.
- Extract the contents of the package.
- Extract the individual projects to a short path.
- Launch e² studio from the start menu.
- Set the top directory which has each sample project sub-directory for the workspace directory. These 2 steps are shown in Figure 3-1.

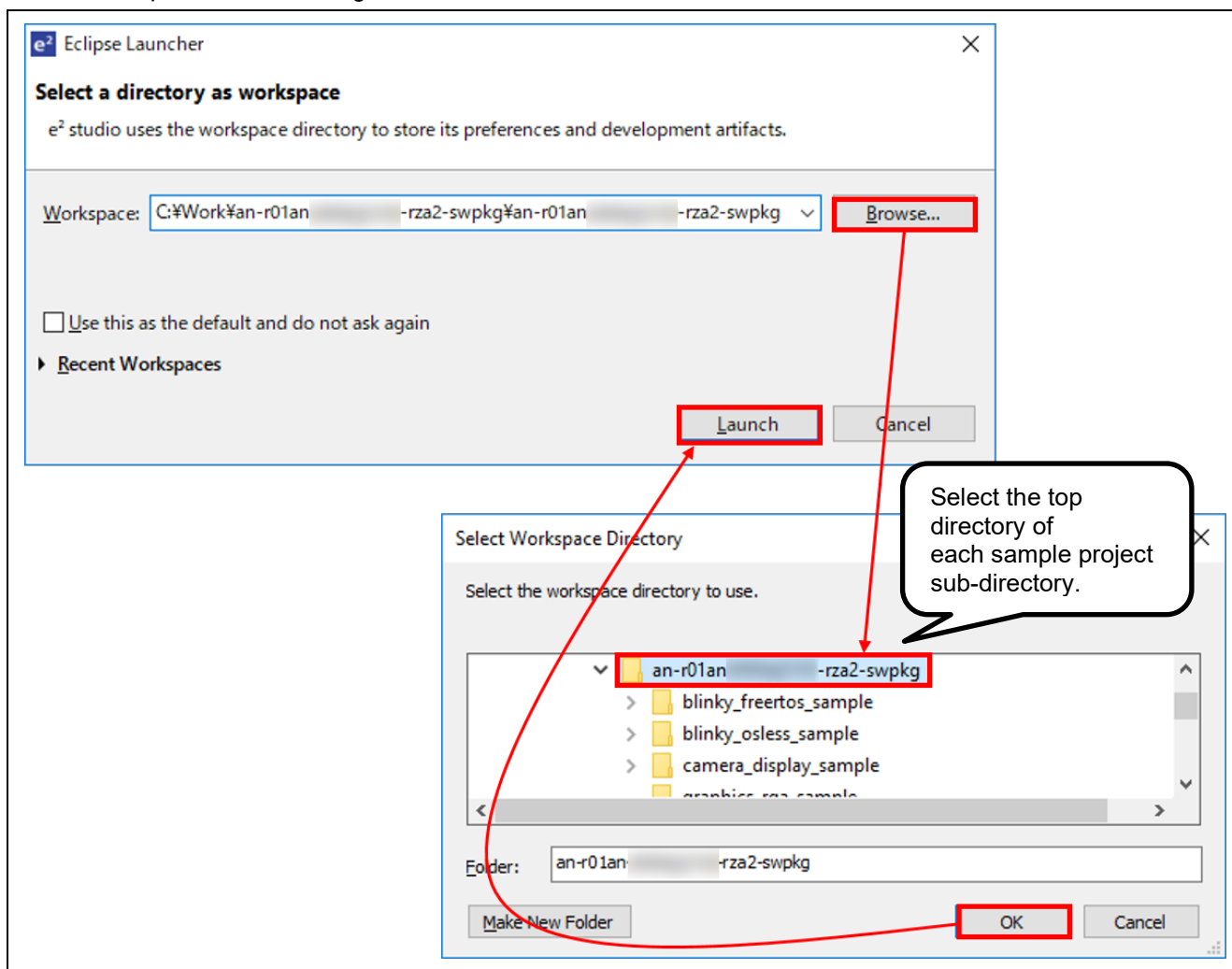


Figure 3-1 e2 studio launching

— In the e² studio welcome screen, click 'Workbench'. This is shown in Figure 3-2.

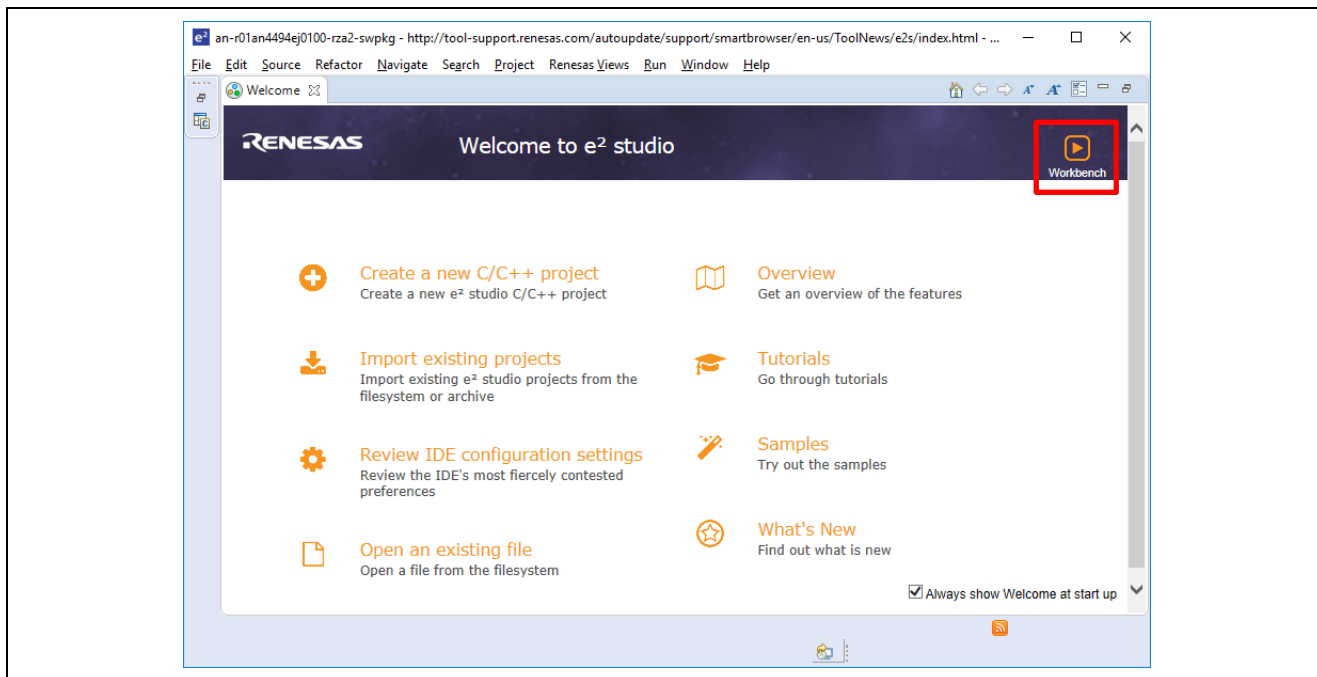


Figure 3-2 Position of 'Workbench' switch

— Right-click in the Project Explorer window and select 'Import'. This is shown in Figure 3-3.

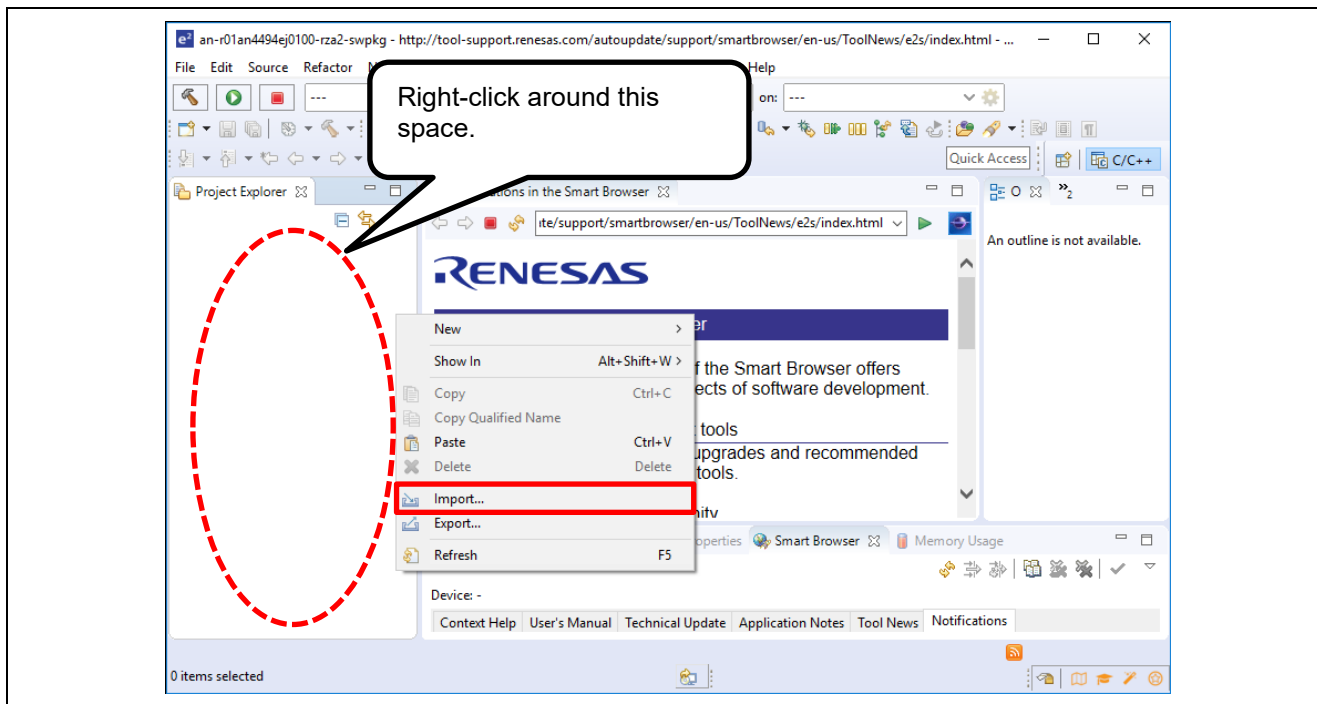


Figure 3-3 Selecting 'Import'

- Under 'Import' window, select General > Existing Projects into Workspace and click 'Next'. This is shown in Figure 3-4.

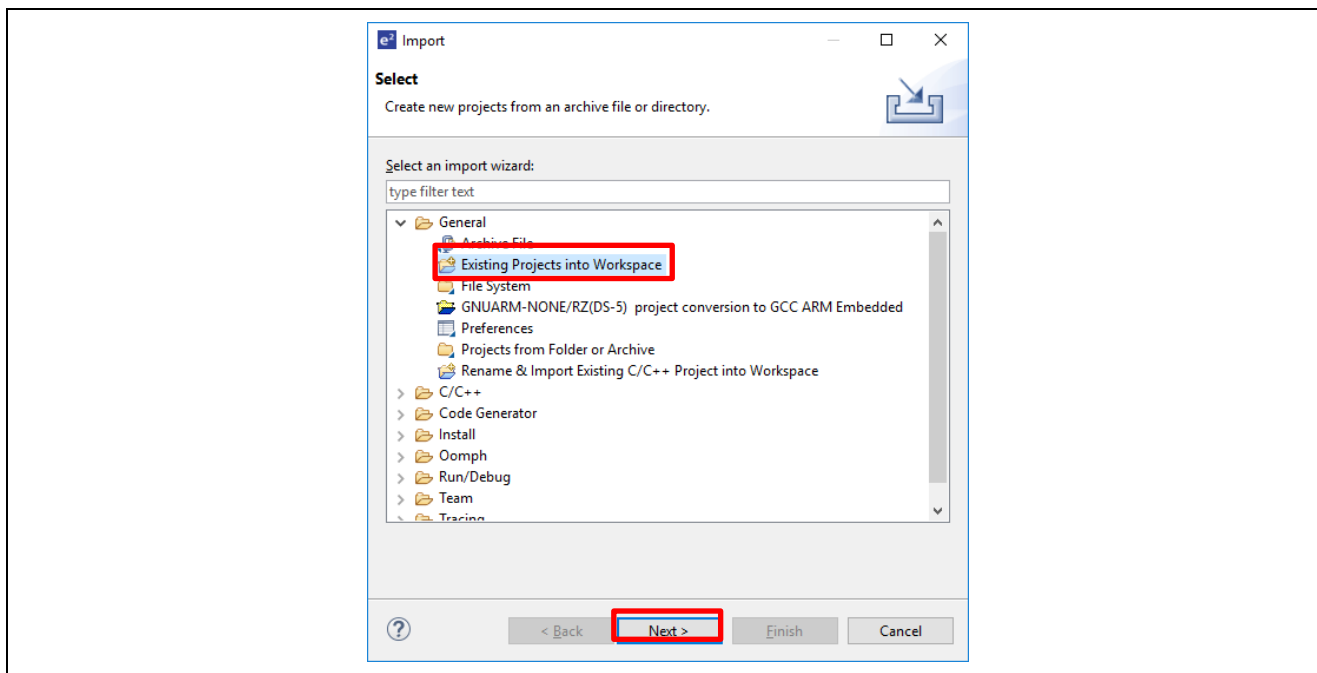


Figure 3-4 Menu of 'Import' window

- Select "Browse" at the right of "Select root directory:", and "Browse for Folder" dialog box will be appeared.
- Click "OK". These 2 steps are shown in Figure 3-5.

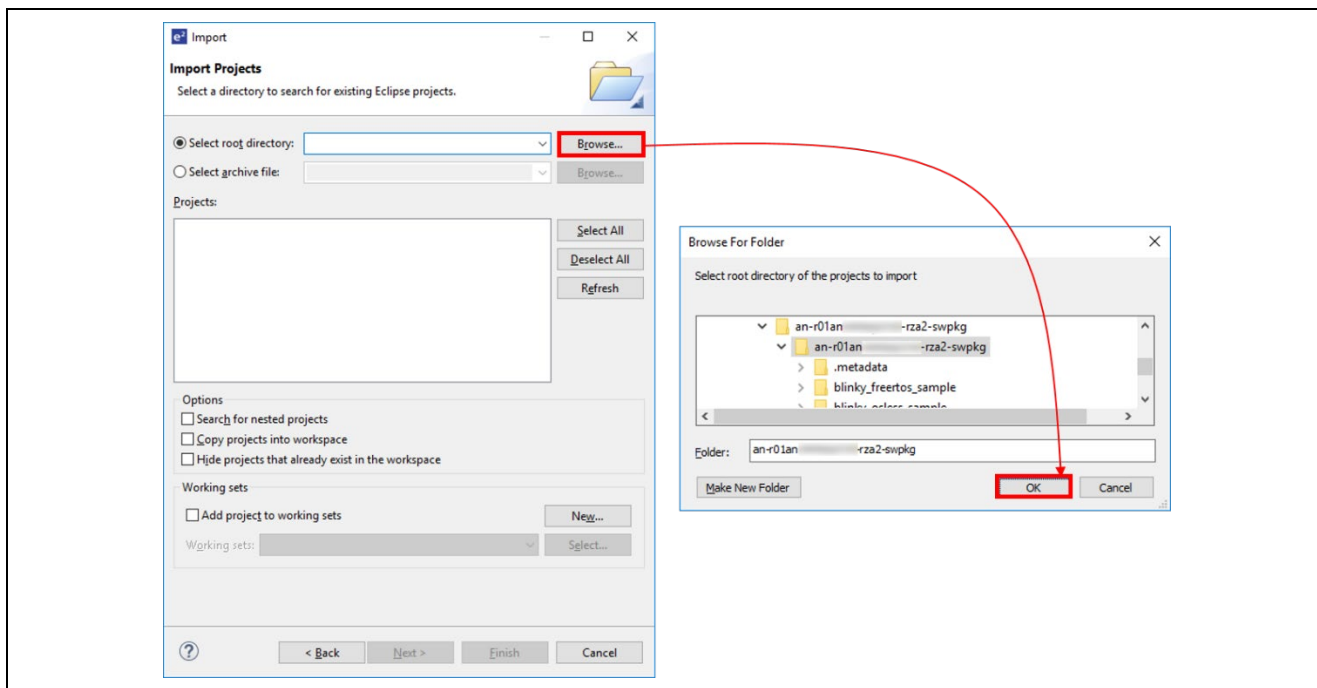


Figure 3-5 Select root directory

- Confirm your target project is checked, then click 'Finish'. This is shown in Figure 3-6.
(Note: Projects in Figure 3-6 are just sample. From here, please read the project name as your target project name.)

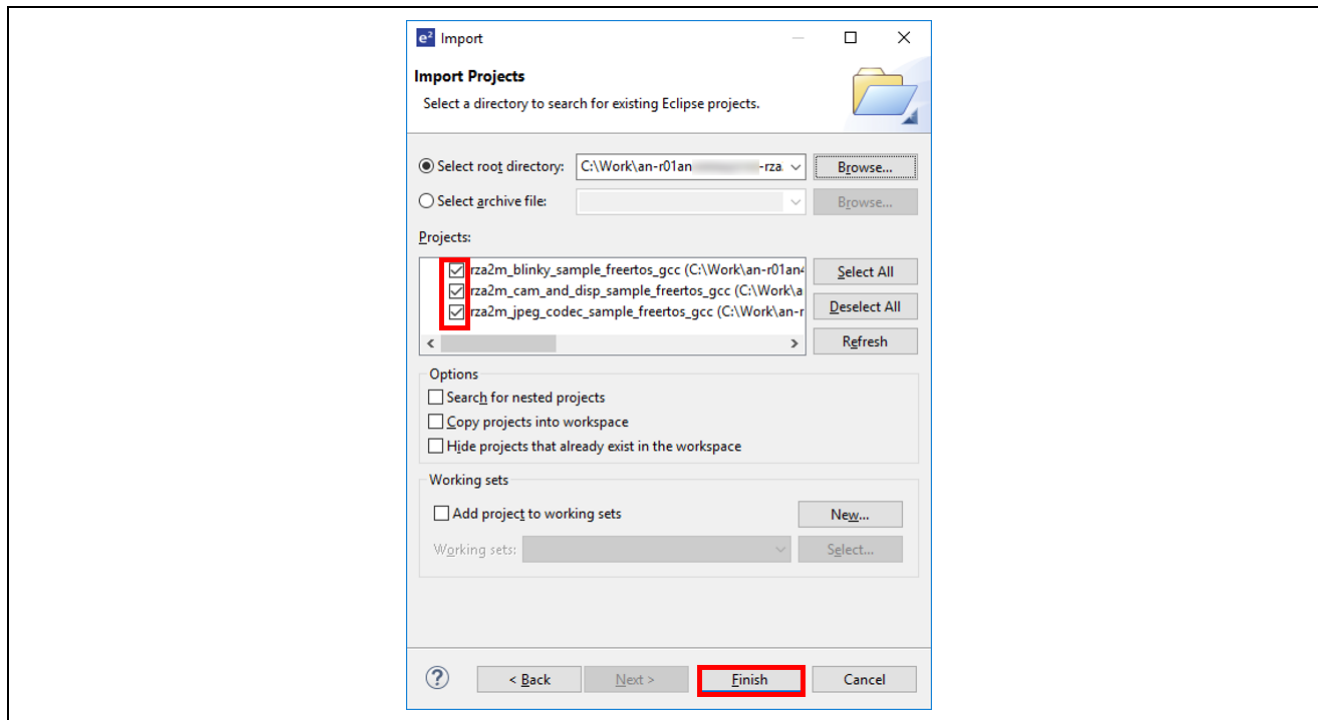


Figure 3-6 Import target project

- Now, target projects are imported, and user can see them in the Project Explorer window. This is shown in Figure 3-7.

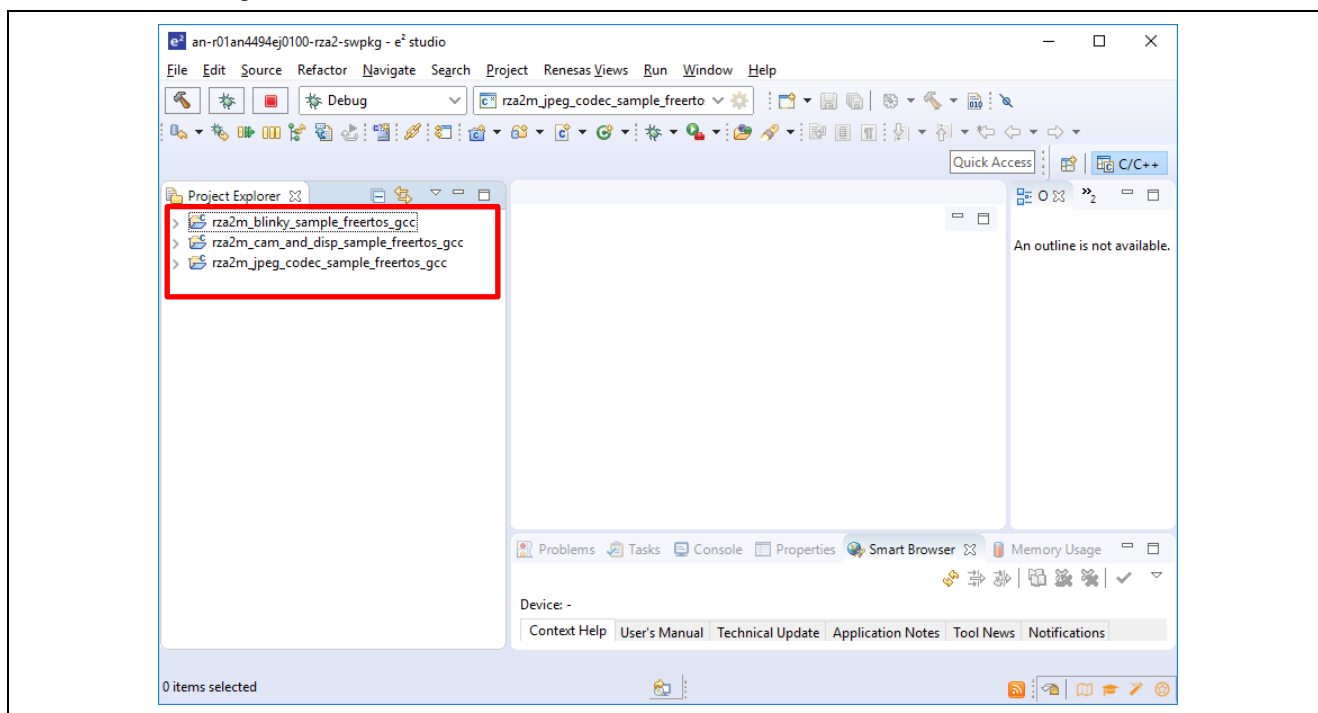


Figure 3-7 Confirmation on 'Project Explorer' window

3.2 Build and Download to target board

- Select your target project by left clicking on it, then click the arrow next to build button (hammer icon) and select 'HardwareDebug' from the drop-down menu. From next time, user can build the project by this Build button (hammer icon). This is shown in Figure 3-8.

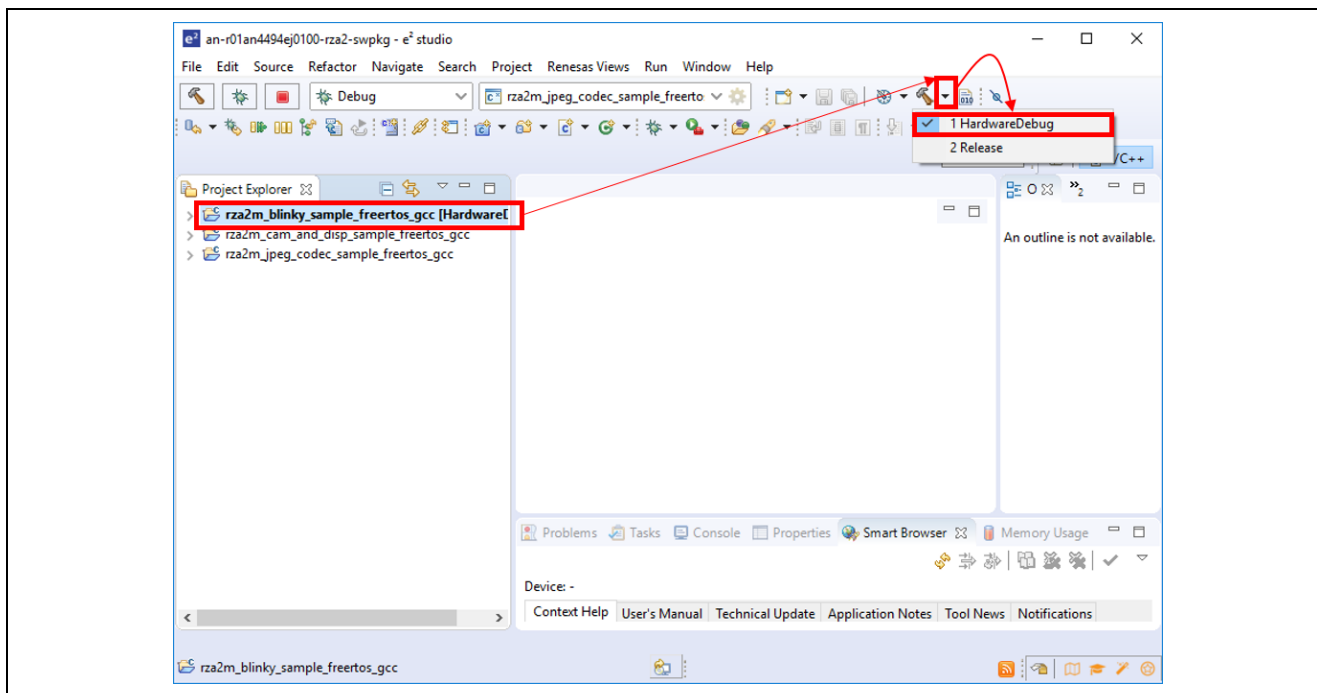


Figure 3-8 Build the target project

- e2 studio tool build the project, and the build status can be confirmed in Console window (Note: Please mind the length of your workspace path. If the path is too long, there is a possibility of build error.) This is shown in Figure 3-9.

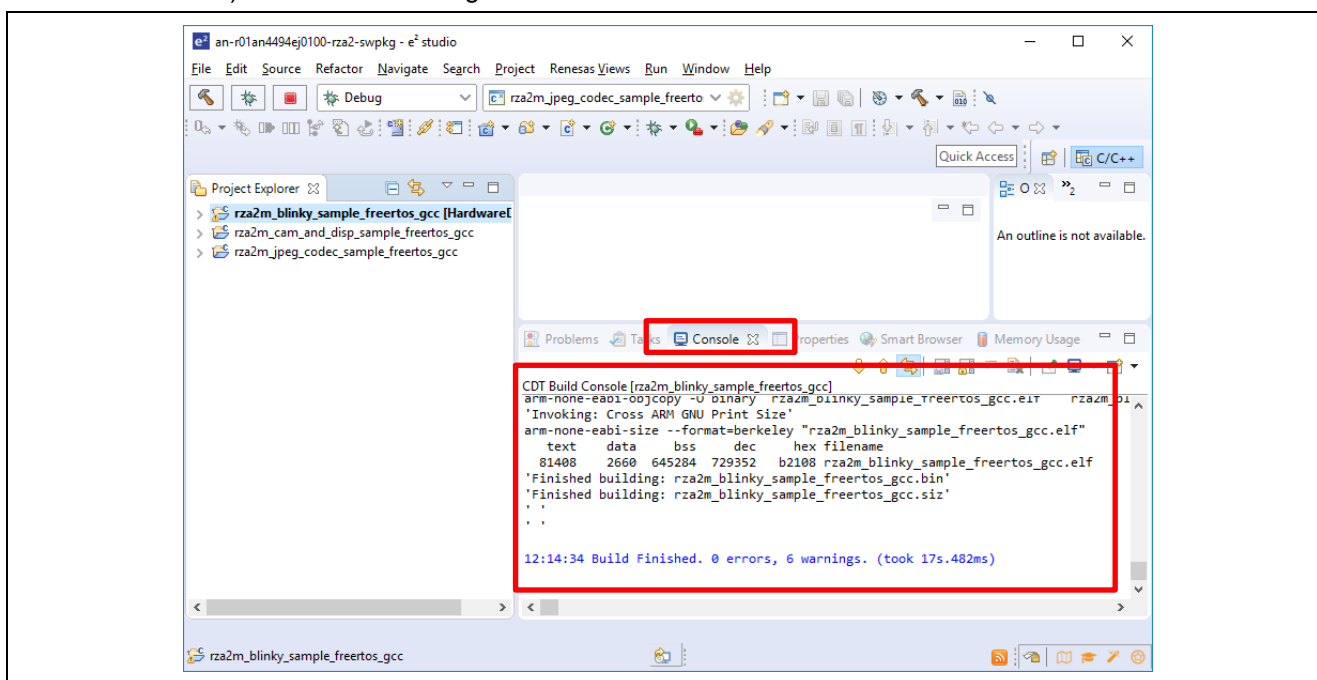
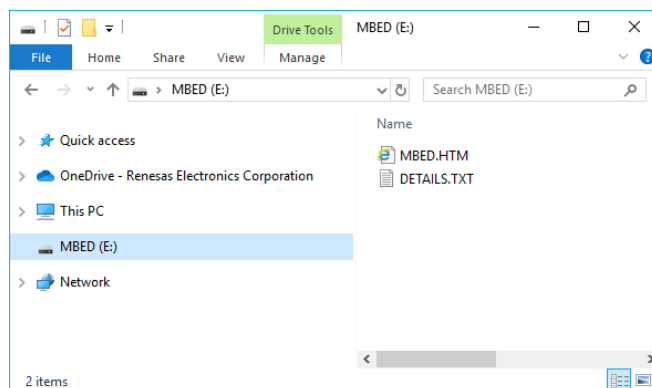


Figure 3-9 Confirmation build status

- After the build is completed, the binary format file is generated in the “HardwareDebug” directory of the target project. When connect the PC and GR-MANGO via USB cable, PC detects GR-MANGO as MBED drive. User can download the program by drag-and-drop the program binary file to MBED drive.



- Execute the program by push the reset button of GR-MANGO after download.

3.3 CMSIS-DAP based debugging

GR-MANGO supports ARM Mbed DAPLink feature and user can debug with OpenOCD.

Please refer page below to make out how to debug GR-MANGO with OpenOCD.

<https://os.mbed.com/teams/Renesas/wiki/How-to-debug-with-e2-studio>

4. Adding drivers and middleware

This section describes how to integrate drivers, middleware into the project which included in this package. In RZ/A2M Software Package for GR-MANGO, the drivers and middleware are managed as components, and the components can be added by e2 studio.

Refer the sample projects bundled in RZ/A2M Simple Applications Package for GR-MANGO(R01AN5595) for examples of usage of each driver and each middleware.

Refer [RZ/A2M Smart Configurator User's Guide: e² studio](#) (R20AN0583) for the usage of Smart Configurator. e.g.) how to install drivers and middleware to e2 studio.

4.1 Components and related sample projects

Following table shows the components used in each sample project:

Package	Component (Explanation)	Sample Program	sillex (Sillex Wi-Fi Libraries)	fatts (FatFS filesystem)	r_vdc (VDC6 driver)	r_usbf_cdc (USBF CDC driver)	r_usbf_basic (USBF basic driver)	r_usb1_msc (USBH ch1 MSC driver)	r_usb1_basic (USBH ch1 basic driver)	r_usb1_hcdc (USBH ch1 HID driver)	r_usb0_msc (USBH ch0 MSC driver)	r_usbh0_basic (USBH ch0 basic driver)	r_usbh0_hcdc (USBH ch0 HID driver)	r_ssif (SSIF driver)	r_sdhi_simplified (SDHI driver)	r_scifa (SCiFa driver)	r_rvapi (Video utility)	r_rtc (RTC driver)	r_rspi (RSPI driver)	r_riic (RIIC driver)	r_rga (Graphics Library "RGA")	r_ostm (OS timer driver)	r_mipi (MIPI driver)	r_lpm (LPM driver)	r_jcu (JCU driver)	r_octabus (Octabus driver)	r_gpt (GPT driver)	r_ether (Ethernet driver)	r_drp (DRP driver)	r_dmac (DMAC driver)	r_ceu (CEU driver)	r_chbuffer (Ring buffer)
simple applications	adc ^{*3}	✓														✓						✓										✓
	blinky_freertos ^{*1}	✓														✓						✓										✓
	blinky_osless ^{*2}	✓														✓						✓										✓
	cam_and_disp ^{*3}	✓														✓						✓										✓
	dmac_scifa ^{*3}	✓														✓						✓										✓
	drp_basic ^{*3}	✓														✓						✓										✓
	drp_dynamic1 ^{*3}	✓														✓						✓										✓
	drp_dynamic2 ^{*3}	✓														✓						✓										✓
	drp_dynamic3 ^{*3}	✓														✓						✓										✓
	drp_parallel ^{*3}	✓														✓						✓										✓
	drp_simple_isp_sample1 ^{*3}	✓														✓						✓										✓
	eeprom_riic ^{*3}	✓														✓						✓										✓
	ethernet ^{*3}	✓														✓						✓										✓
	fw_update_boot ^{*3}	✓														✓						✓										✓
	fw_update_sample ^{*3}	✓														✓						✓										✓
	gpt-pwm ^{*4}	✓														✓						✓										✓
	lpm ^{*4}	✓														✓						✓										✓
	jpeg_codec ^{*3}	✓														✓						✓										✓
	rtc ^{*4}	✓														✓						✓										✓
	sdhi_fat ^{*3} ^{*4}	✓														✓						✓										✓
	sprite_engine ^{*3}	✓														✓						✓										✓
	ssif ^{*3}	✓														✓						✓										✓
	touch_panel ^{*3}	✓														✓						✓										✓
	usbh_msc_fat ^{*3} ^{*4}	✓														✓						✓										✓
	usbh_hid ^{*3}	✓														✓						✓										✓
	usbf_cdc ^{*3} ^{*4}	✓														✓						✓										✓

	wifi_pmod_esp32 ^{*3}	✓	-	-	✓	-	-	-	✓	-	✓	✓	-	✓	-	-	✓	✓	-	-	-	-	-	-	-	-	✓	-	-
2d_barcode	2d_barcode ^{*3}	✓	-	-	✓	-	-	-	-	-	✓	✓	-	✓	-	-	✓	✓	-	-	-	-	-	-	-	-	✓	-	-
iris	iris ^{*3}	✓	-	-	✓	-	-	✓	-	-	✓	✓	-	✓	-	-	✓	✓	-	-	-	-	-	-	-	-	✓	-	-
graphics RG	graphics ^{*3}	✓	-	-	-	-	-	✓	-	-	✓	✓	✓	-	-	✓	✓	-	-	-	-	-	-	-	-	-	✓	-	-
Wi-Fi	wifi_sx_sdmac_eval ^{*3}	✓	-	-	-	-	✓	-	-	-	✓	-	✓	-	-	-	✓	✓	-	-	-	-	-	-	-	-	-	-	✓
	wifi_sx_sdmac ^{*3}	✓	-	-	✓	-	-	✓	✓	-	✓	✓	-	✓	-	-	✓	✓	✓	-	-	-	-	-	-	-	✓	-	✓

Note ✓ : Component is used.

- : Component is not included.

*1 : "rza2m_blinky_sample_freertos_gcc" is the name displayed in e² studio.

*2 : "rza2m_blinky_sample_osless_gcc" is the name displayed in e² studio.

*3 : "rza2m_[SampleProgram]_sample_freertos_gcc" is the name displayed in e² studio.

*4 : "rza2m_[SampleProgram]_sample_osless_gcc" is the name displayed in e² studio.

4.2 Importing Software Package into IDE

- Open the project tree of target project in the Project Explorer window of e2 studio, and double click .scfg file in the project.
- Select 'Components' tab and add the target component from 'Add component' button.
- After adding the target component, click 'Generate Code' button.

The steps above are shown in Figure 4-1.

With this, the component is added to the target project's folder, "(Project Folder)\generate\sc_drivers" and "(Project Folder)\settings\smartconfigurator". After adding the component, re-build the target project according to section 3.2.

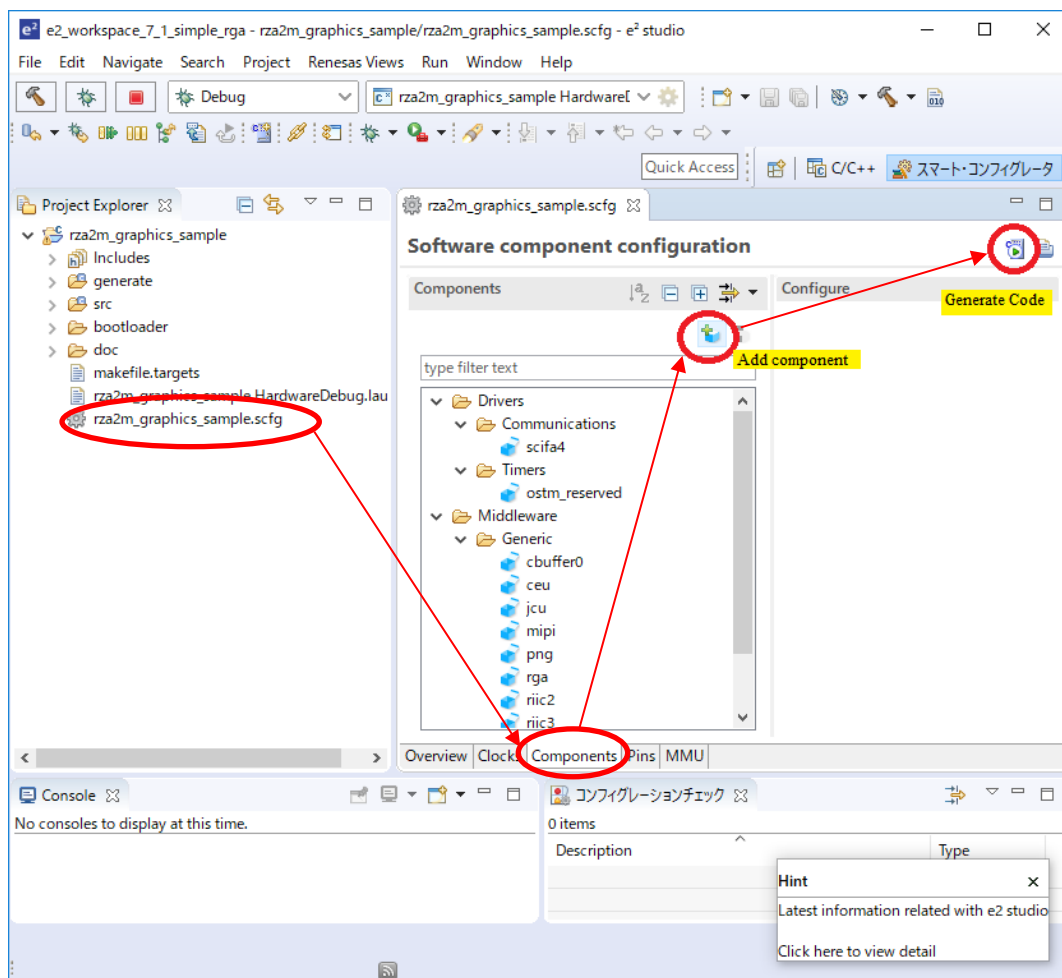


Figure 4-1 How to add components

4.3 How to integrate the new component

New component is integrated to a project by the following step

- Add component by the procedure shown in section 4.2.
- Configure the component by Smart Configurator.
- Generate the source code of the component.
- Confirm API functions or the name of header file declaring API functions from the document of the component.
- Confirm the project which uses the component and use the API function name or the header file name to find where the component is used.
- Implement the source code into a project by referring the source file using the component.

5. FreeRTOS awareness function

In this section it is shown that FreeRTOS awareness function of e2 studio.

This function supports displaying the list and the status of generated tasks, queues, and timer during break.

5.1 Adding FreeRTOS awareness function to e² studio

5.1.1 In the case of new e² studio installation or upgrading e² studio

- Launch e² studio installer. If e² studio has already been installed, select “Upgrade” or “Install”. This is shown in Figure 5-1.

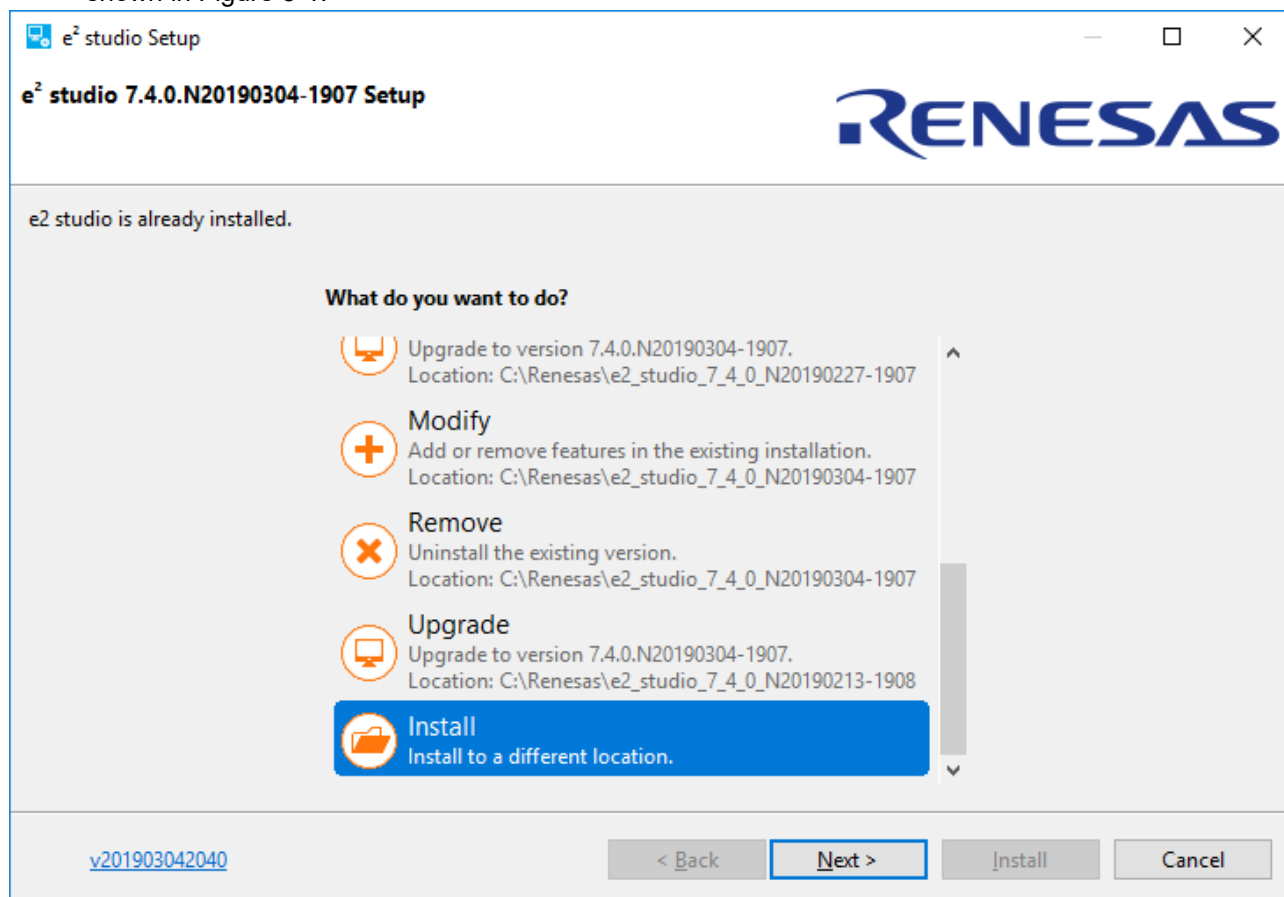


Figure 5-1 Adding FreeRTOS awareness function (new e² studio installation) 1

— Check “RZ” at “Device Families” stage of install wizard. This is shown in Figure 5-2.

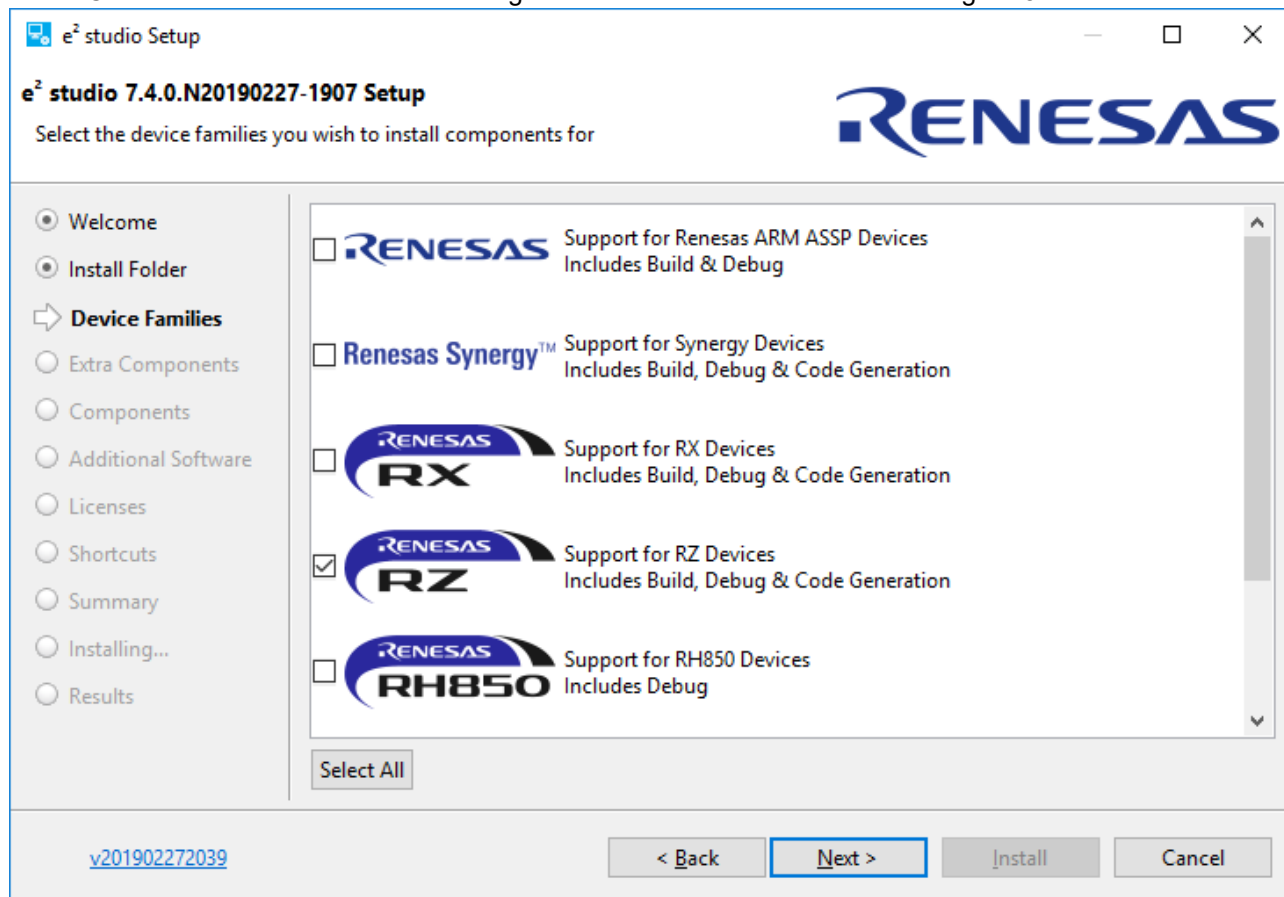


Figure 5-2 Adding FreeRTOS awareness function (new e² studio installation) 2

— Check “RTOS” at “Extra Components” stage of install wizard. This is shown in Figure 5-3.

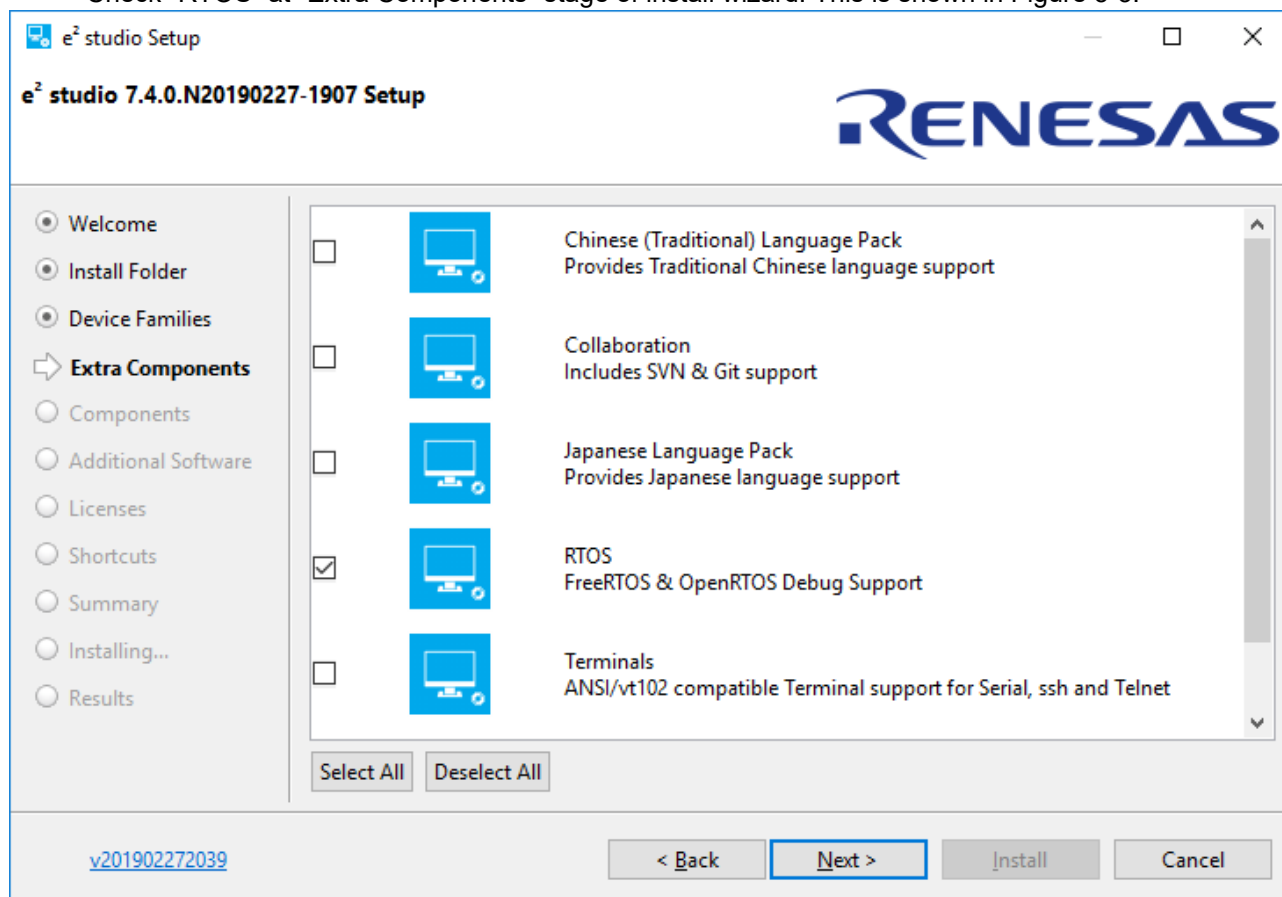


Figure 5-3 Adding FreeRTOS awareness function (new e² studio installation) 3

- Check “GCC ARM Embedded 6 2017q2” and “LibGen for GCC ARM Embedded” at “Additional Software” stage of install wizard. This is shown in Figure 5-4.

By setting up to here, FreeRTOS awareness function will be enabled.

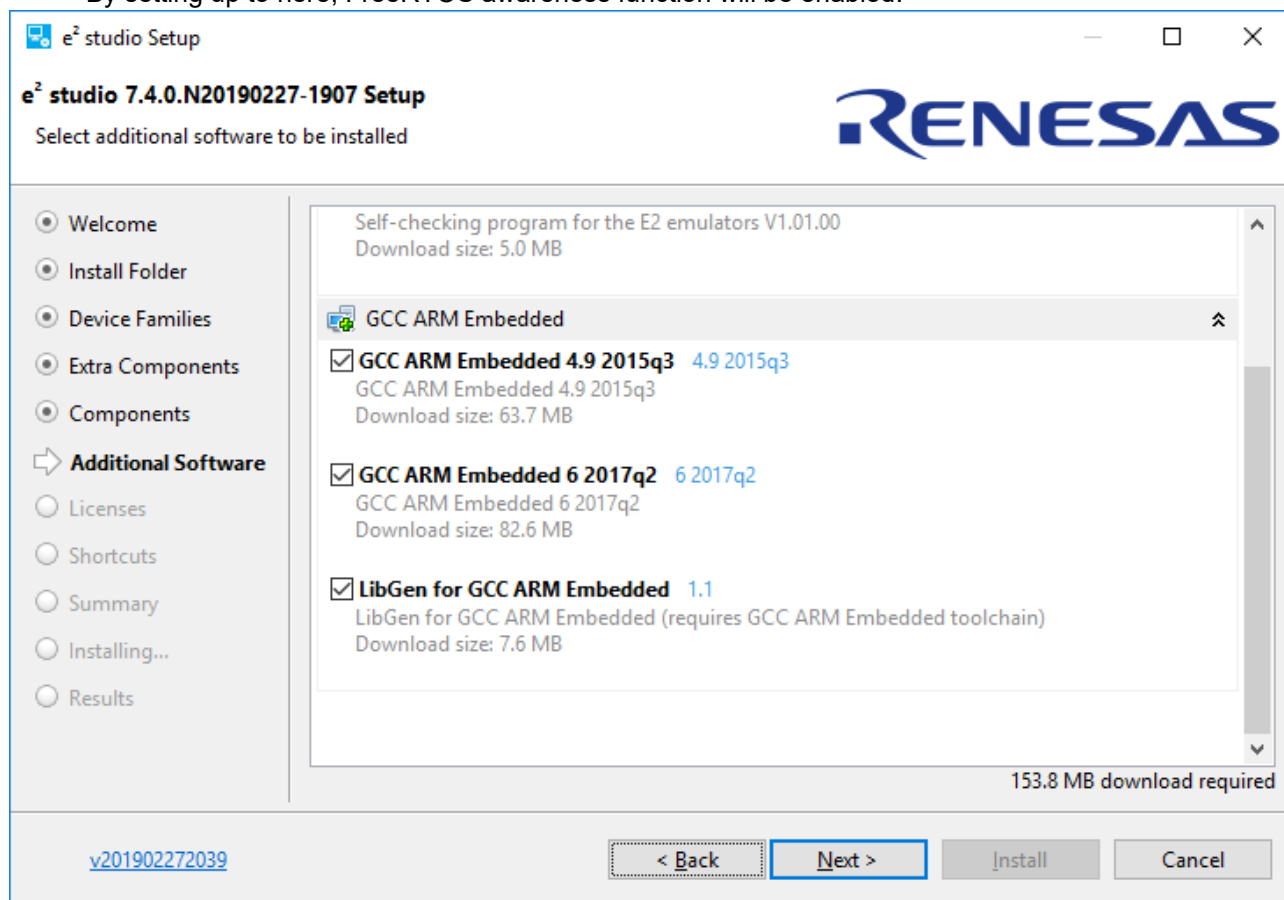


Figure 5-4 Adding FreeRTOS awareness function (new e² studio installation) 4

5.1.2 In the case that e² studio has already been installed

— Launch e² studio installer. And select “Modify”. This is shown in Figure 5-5.

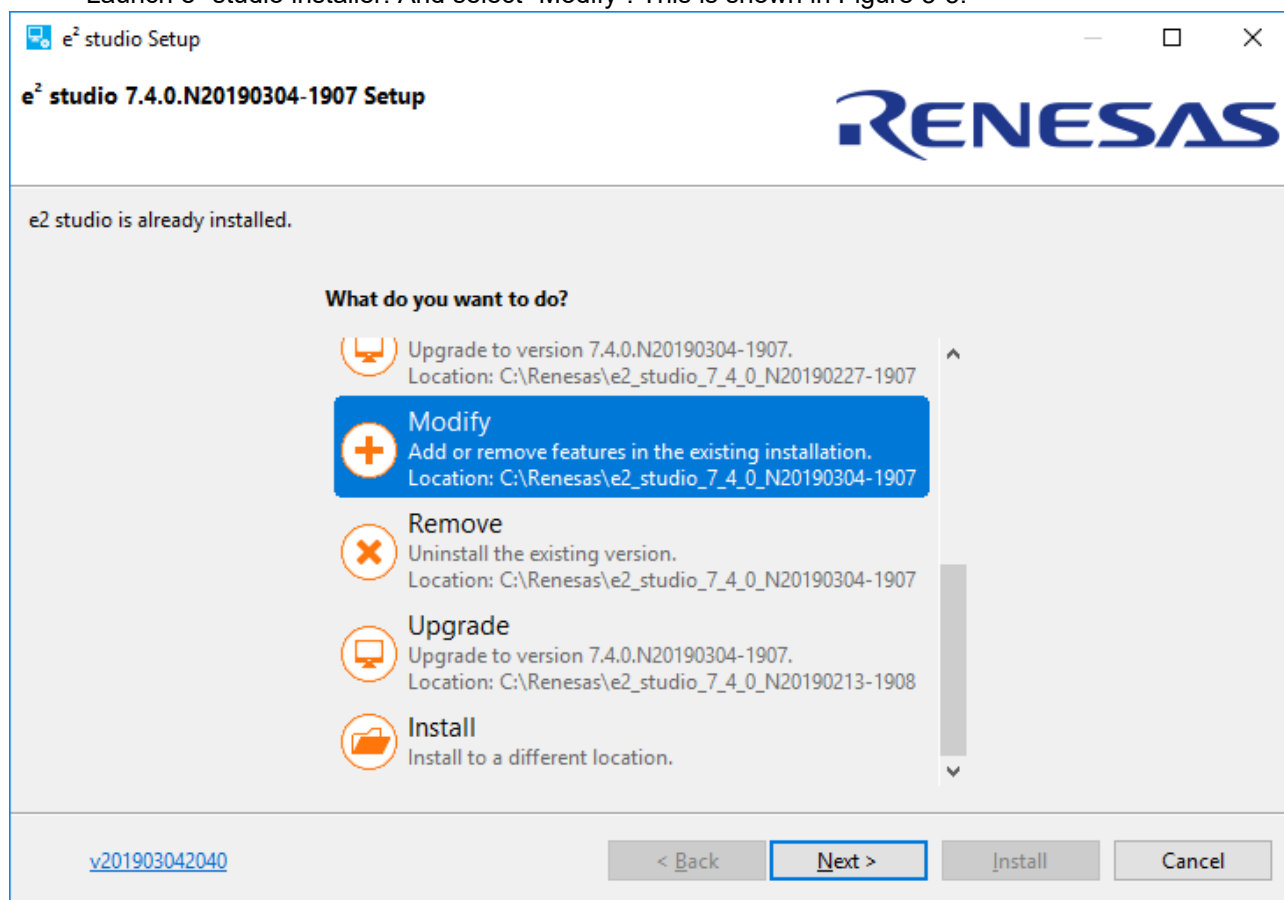


Figure 5-5 Adding FreeRTOS awareness function (to existing e² studio) 1

— Check “Renesas RTOS Debug Views” at “Components” stage of install wizard. This is shown in Figure 5-6.

By setting up to here, FreeRTOS awareness function will be enabled.

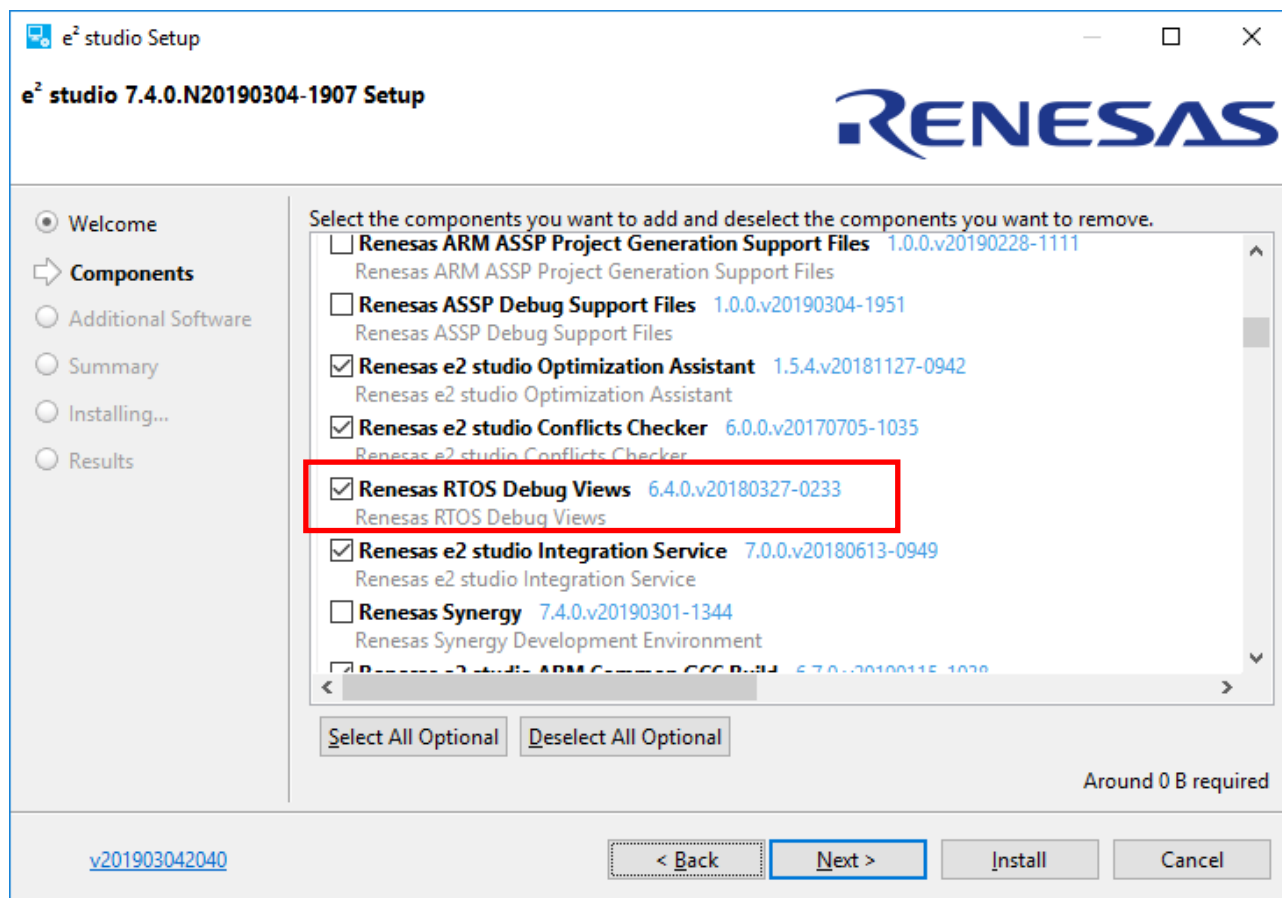


Figure 5-6 Adding FreeRTOS awareness function (to existing e² studio) 2

5.2 How to launch FreeRTOS awareness function

1. Download the program using FreeRTOS to your board.
2. Run the downloaded program.
3. Suspend (break) the running program.
4. Select “Window” menu – “Show view” – “Other”. This is shown in Figure 5-7.

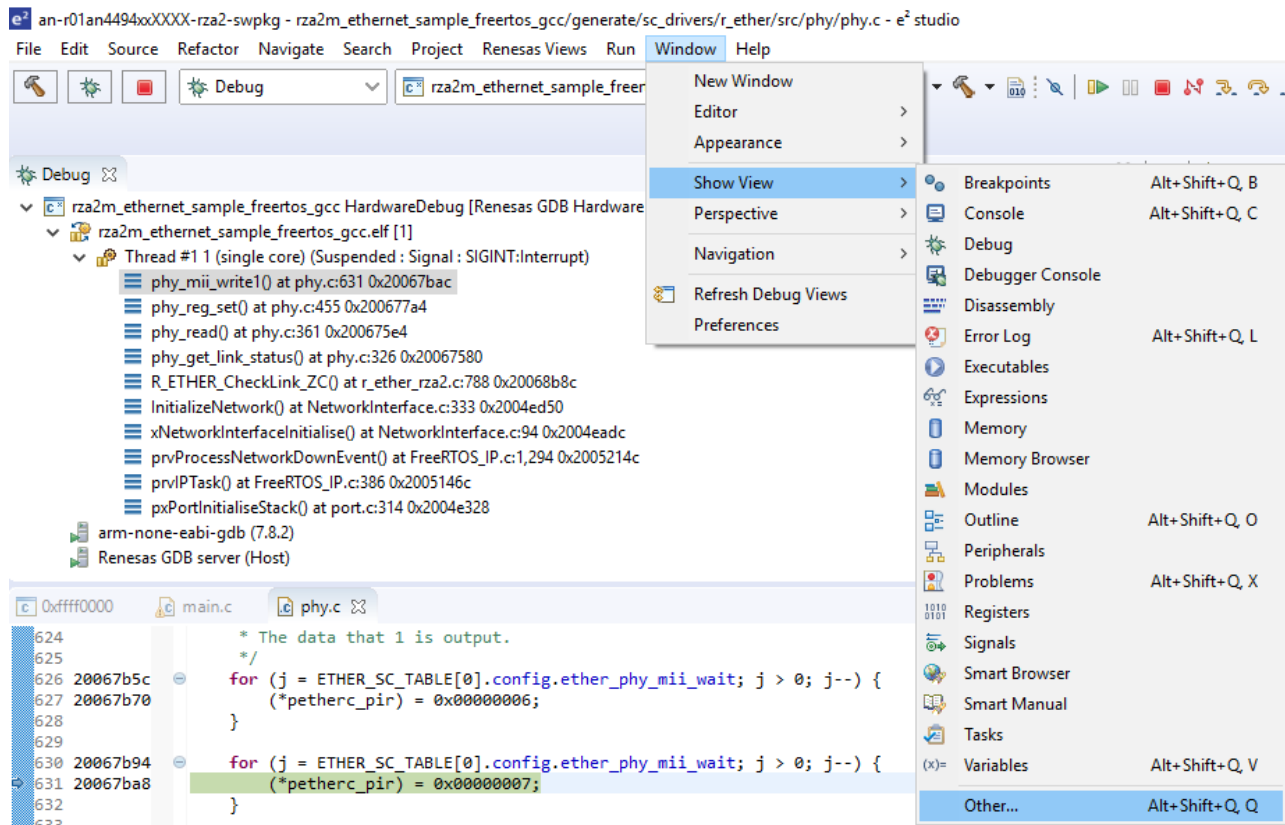


Figure 5-7 Launching FreeRTOS awareness function, step 4

5. Select “Queue Table” under “OpenRTOS Viewer”. And Press “Open”. This is shown in Figure 5-8.
6. After the same procedure, select “Task Table” under “OpenRTOS Viewer”. And Press “Open”.
7. After the same procedure, select “Timer Table” under “OpenRTOS Viewer”. And Press “Open”.

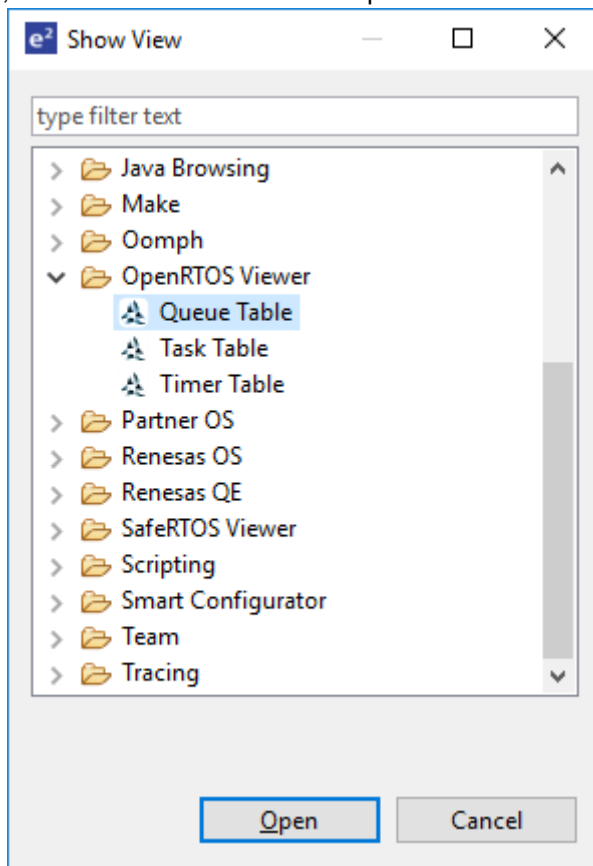


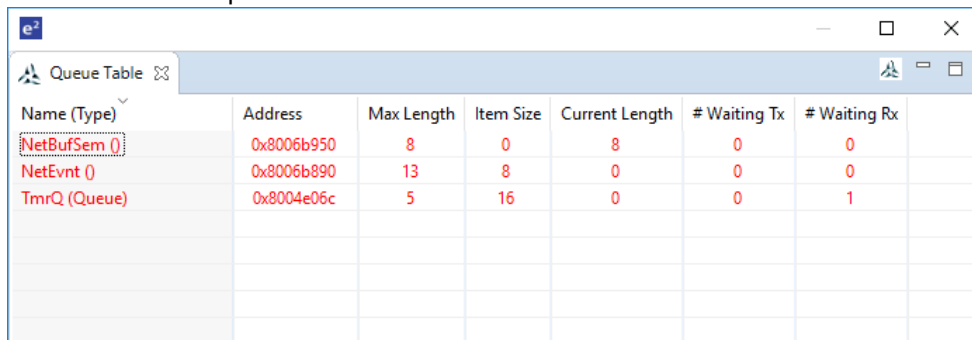
Figure 5-8 Launching FreeRTOS awareness function, step 5,6, and 7

8. Status of FreeRTOS will be shown.

Figure 5-9 shows the example of Queue Table view.

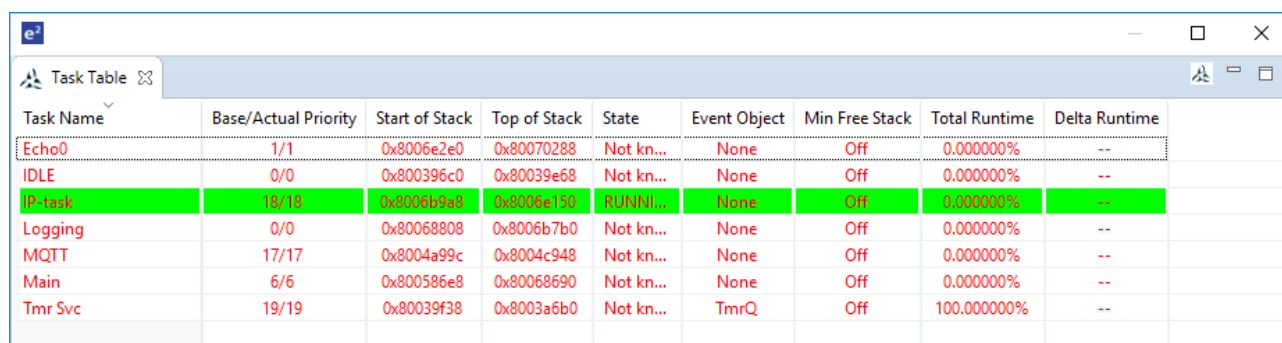
Figure 5-10 shows the example of Task Table view.

Figure 5-11 shows the example of Timer Table view.



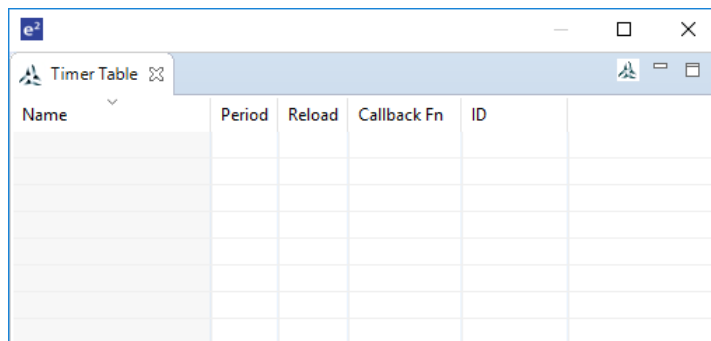
Name (Type)	Address	Max Length	Item Size	Current Length	# Waiting Tx	# Waiting Rx
NetBufSem ()	0x8006b950	8	0	8	0	0
NetEvt ()	0x8006b890	13	8	0	0	0
TmrQ (Queue)	0x8004e06c	5	16	0	0	1

Figure 5-9 FreeRTOS awareness function (Queue Table)



Task Name	Base/Actual Priority	Start of Stack	Top of Stack	State	Event Object	Min Free Stack	Total Runtime	Delta Runtime
Echo0	1/1	0x8006e2e0	0x80070288	Not kn...	None	Off	0.000000%	--
IDLE	0/0	0x800396c0	0x80039e68	Not kn...	None	Off	0.000000%	--
IP-task	18/18	0x8006b9a8	0x8006e150	RUNNI...	None	Off	0.000000%	--
Logging	0/0	0x80068808	0x8006b7b0	Not kn...	None	Off	0.000000%	--
MQTT	17/17	0x8004a99c	0x8004c948	Not kn...	None	Off	0.000000%	--
Main	6/6	0x800586e8	0x80068690	Not kn...	None	Off	0.000000%	--
Tmr Svc	19/19	0x80039f38	0x8003a6b0	Not kn...	TmrQ	Off	100.000000%	--

Figure 5-10 FreeRTOS awareness function (Task Table)



Name	Period	Reload	Callback Fn	ID

Figure 5-11 FreeRTOS awareness function (Timer Table)

6. Support

Online technical support and information is available at <https://www.renesas.com>

Technical Contact Details

America: techsupport.america@renesas.com

Europe& global: <https://www.renesas.com/eu/en/support/contact.html>

Japan: <https://www.renesas.com/eu/ja/contact-us>

Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Sep. 30, 2020	—	First edition issued
1.01	May. 31, 2021	P11	Add applications included in the package JCU sample program Sprite Engine sample Ethernet sample program DMAC-SCIFA sample program Low power consumption sample program SDHI FAT sample program USBF CDC sample program USBH MSC FAT sample program USBH HID sample program RTC counter sample program GPT-PWM sample program Firmware Update sample program

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity.

Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

Notice

1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation or any other use of the circuits, software, and information in the design of your product or system. Renesas Electronics disclaims any and all liability for any losses and damages incurred by you or third parties arising from the use of these circuits, software, or information.
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