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**ECON2125/6012**

**Fedor Iskhakov**

**Aug 03, 2023**



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## Preliminary schedule

Week	Date	Topic	Notes
1	July 27	<i>Introduction</i>	Recorded lecture
2	Aug 3	<i>Univariate and bivariate optimization</i>	Tutorials start
3	Aug 10	<i>Elements of set theory and analysis</i>	
4	Aug 17	<i>Elements of linear algebra</i>	
Test		15%	Submit by Aug 23
5	Aug 24	<i>Elements of Probability</i>	
6	Aug 31	<i>Fundamentals of optimization</i>	
Test		15%	Submit by Sept 3
Break			2 weeks
7	Sept 21	<i>Unconstrained optimization</i>	
8	Sept 28	<i>Constrained optimization</i>	
Test		15%	Submit by Oct 4
9	Oct 5	<i>Practical session/invited speaker</i>	TBA
10	Oct 12	<i>Envelope and maximum theorems</i>	
11	Oct 19	<i>Dynamic optimization</i>	
12	Oct 26	<i>Revision</i>	
Exam		55%	During exam period

## ANU course pages

[Course Wattle page](#) Schedule, announcements, teaching team contacts, recordings, assignment, grades

[Course overview](#) [Class summary](#) General course description in ANU Programs and Courses



## WELCOME

Course title: “**Optimization for Economics and Financial Economics**”

- Elective second year course in the *Bachelor of Economics* program ECON2125
- Compulsory second math course in the *Master of Economics* program ECON6012

The two courses are identical in content and assessment, but final grades may be adjusted depending on your program.

### 1.1 Plan for this lecture

1. Organization
2. Administrative topics
3. Course content
4. Self-learning materials

### 1.2 Instructor

**Fedor Iskhakov** Professor of Economics at RSE

- Office: 1021 HW Arndt Building
- Email: [fedor.iskhakov@anu.edu.au](mailto:fedor.iskhakov@anu.edu.au)
- Web: [fedor.iskh.me](http://fedor.iskh.me)
- Contact hours: Thursday 9:30-11:30

### 1.3 Timetable

**Face-to-face:**

- Lectures: Thursday 15:30 — 17:30
- Location: **DNF Dunbar Lecture Theatre, Physics Bldg 39A**

**Online:**

- Echo-360 recordings on Wattle
- All notes and materials on [optim.iskh.me](http://optim.iskh.me)

Face-to-face is strictly preferred

## 1.4 Course web pages

- [Wattle](#) Schedule, announcements, teaching team contacts, recordings, assignment, grades
- [Online notes](#) Lecture notes, slides, assignment tasks
- Lecture slides should appear online the previous day before the lecture
- Details on assessment including the exam instructions will appear on Wattle

## 1.5 Tutorials

- Enrollments open on *Wattle*

Tutorial questions

- posted on the course website
- not assessed, help you learn and prepare

Tutorials start on week 2

## 1.6 Tutors

**Wending Liu**

- Email: [Wending.Liu@anu.edu.au](mailto:Wending.Liu@anu.edu.au)
- Room: 1018 HW Arndt Building
- Office hours: **Friday 1pm-3pm**

**Chien Yeh**

- Email: [Chien.Yeh@anu.edu.au](mailto:Chien.Yeh@anu.edu.au)
- Room: Room 2106, Copland Bld (24)
- Office hours: **Monday 2pm-4pm**

## 1.7 Prerequisites

See [Course overview](#) and [Class summary](#)

What you actually need to know:

- basic algebra
- basic calculus
- some idea of what a matrix is, etc.

≈ content of EMET1001/EMET7001 math course



## 1.8 Focus?

*Q:* Is this optimization or a general math-econ course?

*A:* A general course on mathematical modeling for economics and financial economics. Optimization will be an important and recurring theme.

## 1.9 Assessment

- 3 timed open book tests (15% each)
- Final exam (55%)

The three tests spread out through the semester will check the knowledge of the immediately preceding material. The final closed book in-person exam will cover the entire course.

## 1.10 Questions

1. Administrative questions: RSE admin
  - **Bronwyn Cammack** Senior School Administrator
  - Email: [enquiries.rse@anu.edu.au](mailto:enquiries.rse@anu.edu.au)
  - “I can not register for the tutorial group”
2. Content related questions: please, refer to the tutors
  - “I don’t understand why this function is convex”
3. Other questions: to Fedor
  - “I’m working hard but still can not keep up”
  - “Can I please have extra assignment for more practice”

## 1.11 Attendance

- Please, **do not** use email for *instructional* questions\Instead make use of the office hours
- Attendance of tutorials is *very highly* recommended  
You will make your life much easier this way
- Attendance of lectures is *highly* recommended  
But not mandatory

## 1.12 Comments for lectures notes/slides

- Cover exactly what you are required to know
- Code inserts are the exception, they are not assessable

In particular, you need to know:

- The definitions from the notes
- The facts from the notes
- How to apply facts and definitions

If a concept is not in the lecture notes, it is not assessable

## 1.13 Definitions and facts

The lectures notes/slides are full of definitions and facts.

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### Definition

Functions  $f : \mathbb{R} \rightarrow \mathbb{R}$  is called *continuous at  $x$*  if, for any sequence  $\{x_n\}$  converging to  $x$ , we have  $f(x_n) \rightarrow f(x)$ .

---

Possible exam question: “Show that if functions  $f$  and  $g$  are continuous at  $x$ , so is  $f + g$ .”

You should start the answer with the definition of continuity:

“Let  $\{x_n\}$  be any sequence converging to  $x$ . We need to show that  $f(x_n) + g(x_n) \rightarrow f(x) + g(x)$ . To see this, note that ...”

## 1.14 Facts

In the lecture notes/slides you will often see

---

### Fact

The only  $N$ -dimensional subset of  $\mathbb{R}^N$  is  $\mathbb{R}^N$ .

---

This means either:

- theorem
- proposition
- lemma
- true statement

All well known results. You need to remember them, have some intuition for, and be able to apply.

## 1.15 Note on Assessments

Assessable = definitions and facts + last year level math + a few simple steps of logic

Exams and tests will award:

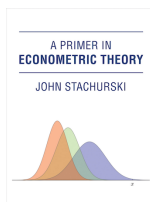
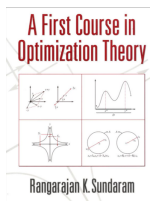
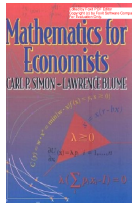
- Hard work
- Deeper understanding of the concepts

In each question there will be a *easy* path to the solution

## 1.16 Reading materials

**Primary reference:** lecture slides

**Books:**



- “Mathematics for Economists” (1994) by Simon, C. and L. Blume
- “A First Course in Optimization” (1996) Theory by Rangarajan Sundaram
- “A Primer in Econometric Theory” (2016) by John Stachurski

Readings are supplementary but will provide a more detailed explanation with additional examples.

- Each lecture will reference book chapters

## 1.17 Key points for the administrative part

- Tutorials start next week, **please register before the next lecture**
- Course content = what's in lecture notes/slides
- Lecture slides are available online and will be updated throughout the semester
- Optimization is a recurring theme but not the only topic

## 1.18 What you will learn in the course

- The lecture plan is on the course website [optim.iskh.me](https://optim.iskh.me) and [Class summary](#)
- See the list of topics on the left

Essentially:

### 1. **Mathematical foundations**

- elements of analysis
- elements of linear algebra
- elements of probability

### 2. **Optimization theory**

- when solution exists
- unconstrained optimization
- optimization with equality constraints
- optimization with inequality constraints

### 3. **Further topics**

- Parameterized optimization problems
- Optimization in dynamics

## 1.19 Further material and self-learning

- Each lecture will suggest some material for further reading and learning
- Today: **The Wason Selection Task** logical problem
- Mathematics relies on rules of logic
- Yet, for human brain applying mathematical logic may be difficult, and dependent on the domain

Please, watch the video and try to solve the puzzle yourself [youtu.be/iR97LBgpsl8](https://youtu.be/iR97LBgpsl8)

## UNIVARIATE AND BIVARIATE OPTIMIZATION

ECON2125/6012 Lecture 2 Fedor Iskhakov

### 2.1 Announcements & Reminders

- **Tutorials start tomorrow (Aug 4)**
- Register for tutorials on [Wattle](#) if you have not done so already
- Office hours of the tutors are updated:
  - **Wending Liu**
    - \* Email: [Wending.Liu@anu.edu.au](mailto:Wending.Liu@anu.edu.au)
    - \* Room: 1018 HW Arndt Building
    - \* Office hours: **Friday 1pm-3pm**
  - **Chien Yeh**
    - \* Email: [Chien.Yeh@anu.edu.au](mailto:Chien.Yeh@anu.edu.au)
    - \* Room: Room 2106, Copland Bld (24)
    - \* Office hours: **Monday 2pm-4pm**
- Reminder on how to ask questions:
  1. Administrative: RSE admin
  2. Content/understanding: tutors
  3. Other: to Fedor

### 2.2 Plan for this lecture

1. Motivation (math vs. computing)
2. Univariate optimization
3. Working with bivariate functions
4. Bivariate optimization

#### Supplementary reading:

- Simon & Blume: part 1 (revision)

- Sundaram: sections 1.1, 1.4, chapter 2, chapter 4

## 2.3 Computing

The *classic* way we do mathematics is pencil and paper

In 1944, Hans Bethe solved following problem *by hand*:

Will detonating an atom bomb ignite the atmosphere and thereby destroy life on earth?

[source](#)

These days we rarely calculate with actual numbers

Almost all calculations are done on computers

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### Example: numerical integration

$$\frac{1}{\sqrt{2\pi}} \int_{-2}^2 \exp\left\{-\frac{x^2}{2}\right\} dx$$

```
from scipy.stats import norm
from scipy.integrate import quad
phi = norm()
value, error = quad(phi.pdf, -2, 2)
print('Integral value =', value)
```

```
Integral value = 0.9544997361036417
```

---

### Example: Numerical optimization

$$f(x) = -\exp\left\{-\frac{(x-5.0)^4}{1.5}\right\} \rightarrow \min$$

```
from scipy.optimize import fminbound
import numpy as np
f = lambda x: -np.exp(-(x - 5.0)**4 / 1.5)
res = fminbound(f, -10, 10) # find approx solution
print('Minimum value is attained approximately at', res)
```

```
Minimum value is attained approximately at 4.999941901210501
```

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### Example: Visualization

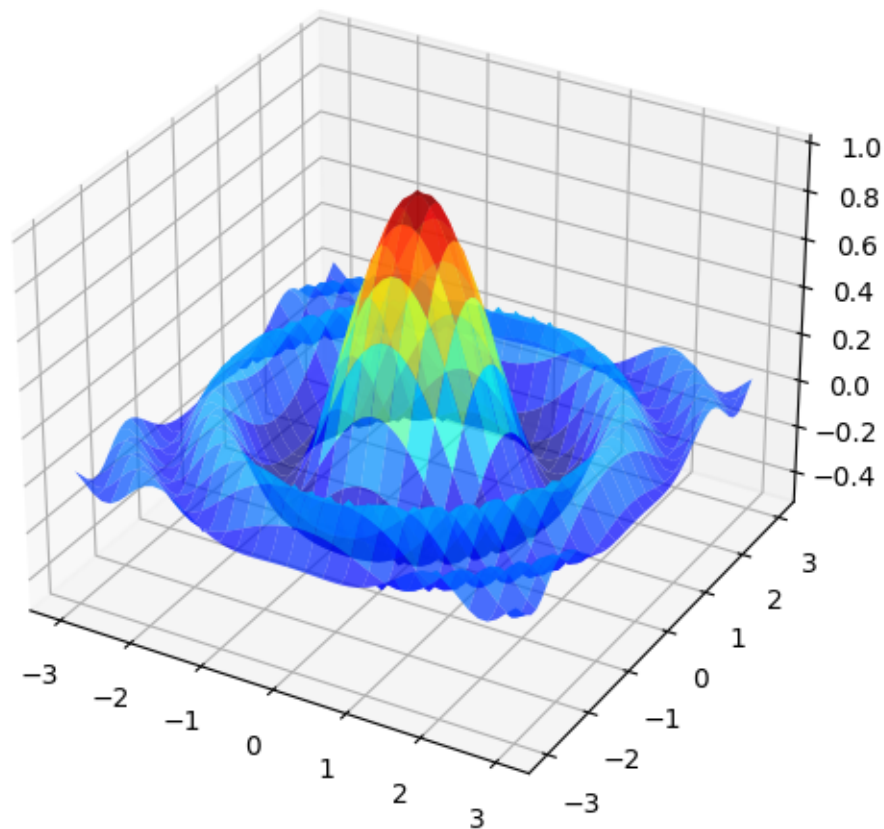
What does this function look like?

$$f(x, y) = \frac{\cos(x^2 + y^2)}{1 + x^2 + y^2}$$

```

import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d.axes3d import Axes3D
import numpy as np
from matplotlib import cm
f = lambda x, y: np.cos(x**2 + y**2) / (1 + x**2 + y**2)
xgrid = np.linspace(-3, 3, 50)
ygrid = xgrid
x, y = np.meshgrid(xgrid, ygrid)
fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')
ax.plot_surface(x,
               y,
               f(x, y),
               rstride=2, cstride=2,
               cmap=cm.jet,
               alpha=0.7,
               linewidth=0.25)
ax.set_zlim(-0.5, 1.0)
plt.show()

```



### Example: Symbolic calculations

Differentiate  $f(x) = (1 + 2x)^5$ .

Forgotten how? No problems, just ask a computer for *symbolic* derivative

---

```
import sympy as sp
x = sp.Symbol('x')
fx = (1 + 2 * x)**5
print("Derivative of", fx, "is", fx.diff(x))
```

```
Derivative of (2*x + 1)**5 is 10*(2*x + 1)**4
```

So if computers can do our maths for us, why learn maths?

The difficulty is

- giving them the right inputs and instructions
- interpreting what comes out

The skills we need are

- Understanding of fundamental concepts
- Sound deductive reasoning

**These are the focus of the course**

## 2.3.1 Computer Code in the Lectures

While computation is not a formal part of the course  
there will be little bits of code in the lectures to illustrate the kinds of things we can do.

- All the code will be written in the Python programming language
- It is not assessable

You might find value in actually running the code shown in lectures

If you want to do so please refer to **linked GitHub repository** in [optim.iskh.me](https://optim.iskh.me)

## 2.4 Univariate Optimization

Let  $f: [a, b] \rightarrow \mathbb{R}$  be a differentiable (smooth) function

- $[a, b]$  is all  $x$  with  $a \leq x \leq b$
- $\mathbb{R}$  is “all numbers”
- $f$  takes  $x \in [a, b]$  and returns number  $f(x)$
- derivative  $f'(x)$  exists for all  $x$  with  $a < x < b$

---

### Definition

A point  $x^* \in [a, b]$  is called a

- **maximizer** of  $f$  on  $[a, b]$  if  $f(x^*) \geq f(x)$  for all  $x \in [a, b]$
- **minimizer** of  $f$  on  $[a, b]$  if  $f(x^*) \leq f(x)$  for all  $x \in [a, b]$



**Example**

Let

- $f(x) = -(x - 4)^2 + 10$
- $a = 2$  and  $b = 8$

Then

- $x^* = 4$  is a maximizer of  $f$  on  $[2, 8]$
- $x^{**} = 8$  is a minimizer of  $f$  on  $[2, 8]$

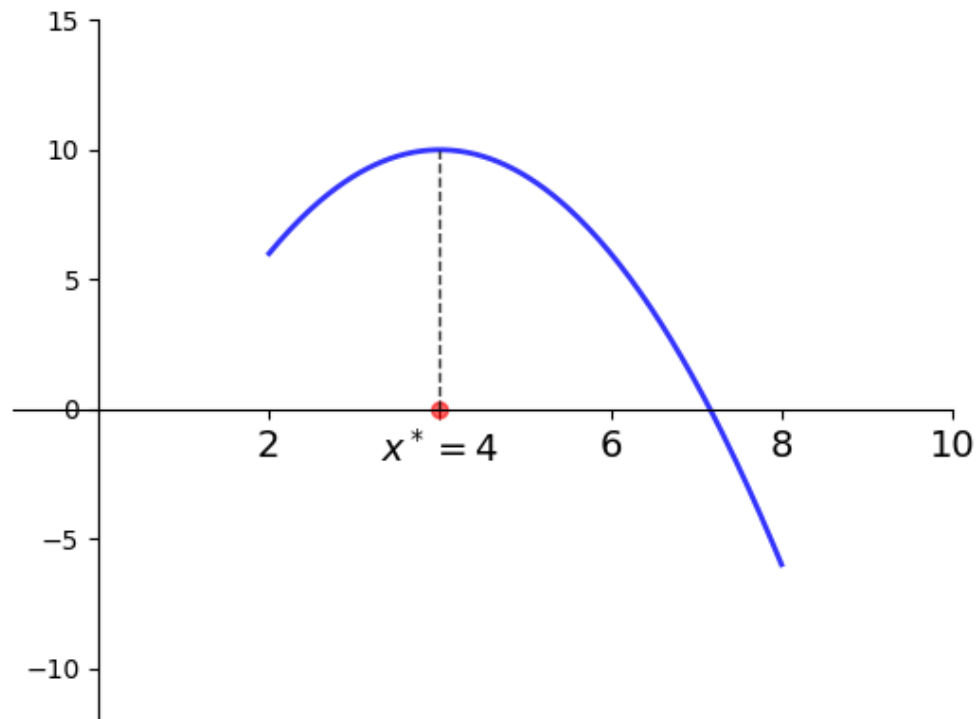


Fig. 2.1: Maximizer on  $[a, b] = [2, 8]$  is  $x^* = 4$

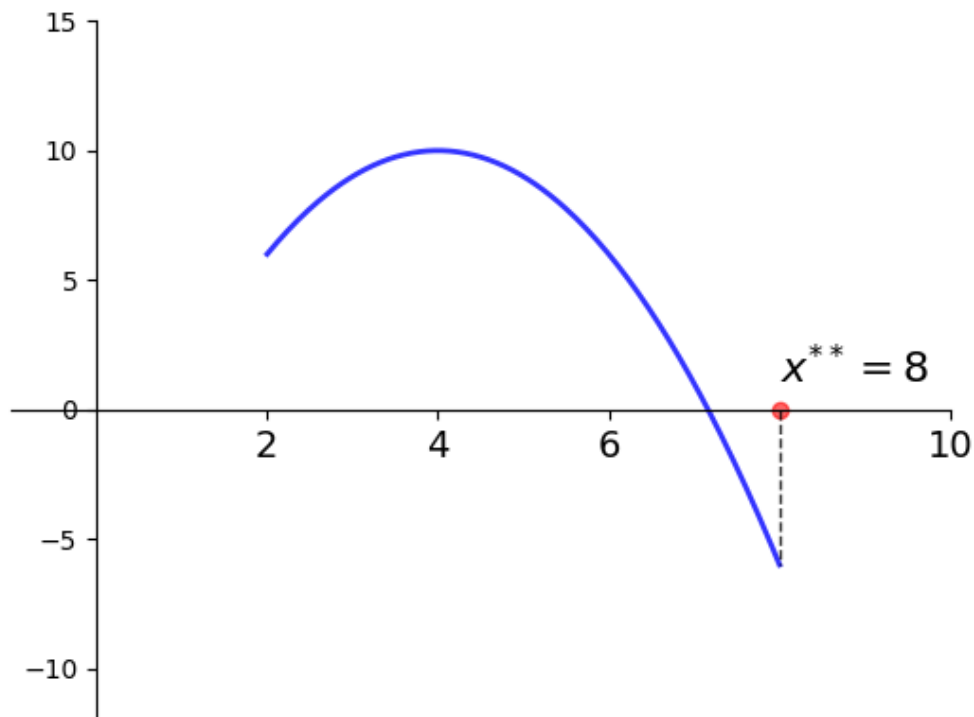


Fig. 2.2: Minimizer on  $[a, b] = [2, 8]$  is  $x^{**} = 8$

The set of maximizers/minimizers can be

- empty
- a singleton (contains one element)
- infinite (contains infinitely many elements)

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**Example: infinite maximizers**

$f: [0, 1] \rightarrow \mathbb{R}$  defined by  $f(x) = 1$   
has infinitely many maximizers and minimizers on  $[0, 1]$

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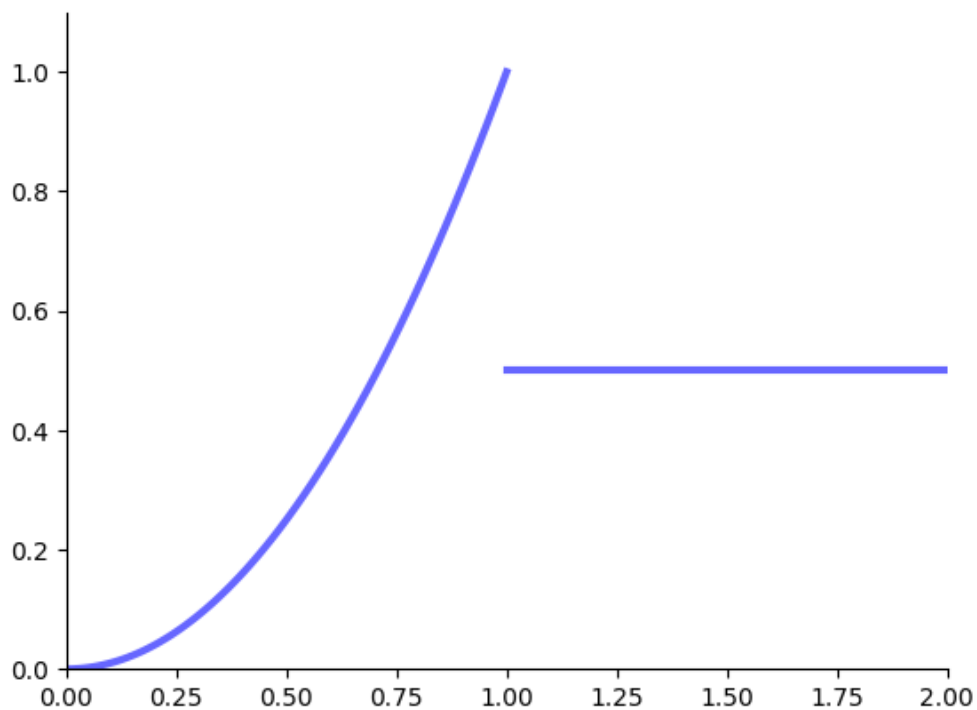


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**Example: no maximizers**

The following function has no maximizers on  $[0, 2]$

$$f(x) = \begin{cases} x^2 & \text{if } x < 1 \\ 1/2 & \text{otherwise} \end{cases}$$

Fig. 2.3: No maximizer on  $[0, 2]$ **Definition**

Point  $x$  is called **interior** to  $[a, b]$  if  $a < x < b$

The set of all interior points is written  $(a, b)$

We refer to  $x^* \in [a, b]$  as

- **interior maximizer** if both a maximizer and interior
- **interior minimizer** if both a minimizer and interior

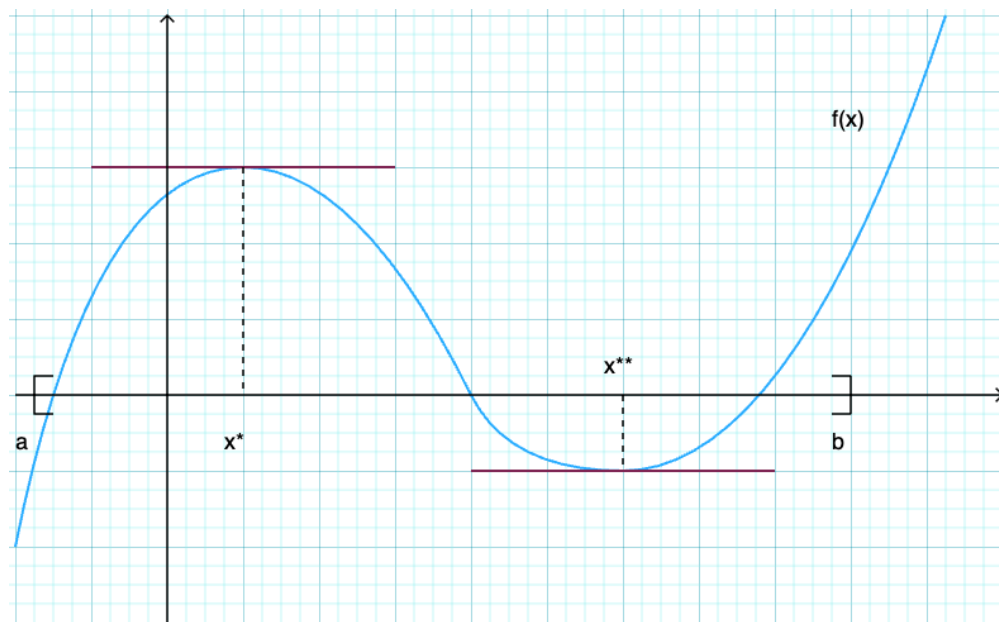
## 2.5 Finding optima

**Definition**

A **stationary point** of  $f$  on  $[a, b]$  is an interior point  $x$  with  $f'(x) = 0$

**Fact**

If  $f$  is differentiable and  $x^*$  is either an interior minimizer or an interior maximizer of  $f$  on  $[a, b]$ , then  $x^*$  is stationary

Fig. 2.4: Both  $x^*$  and  $x^{**}$  are stationary

Sketch of proof, for maximizers:  $f'(x^*) = \lim_{h \rightarrow 0} \frac{f(x^*+h) - f(x^*)}{h}$  (by def.)  $\Rightarrow f(x^* + h) \approx f(x^*) + f'(x^*)h$  for small  $h$

If  $f'(x^*) \neq 0$  then exists small  $h$  such that  $f(x^* + h) > f(x^*)$

Hence interior maximizers must be stationary — otherwise we can do better

$\Rightarrow$  any interior maximizer stationary

$\Rightarrow$  set of interior maximizers  $\subset$  set of stationary points

$\Rightarrow$  maximizers  $\subset$  stationary points  $\cup \{a\} \cup \{b\}$

Usage:

1. Locate stationary points
2. Evaluate  $y = f(x)$  for each stationary  $x$  and for  $a, b$
3. Pick point giving largest  $y$  value

Minimization: same idea

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### Example

Let's solve  $\max_{-2 \leq x \leq 5} f(x)$  where  $f(x) = x^3 - 6x^2 + 4x + 8$  Steps

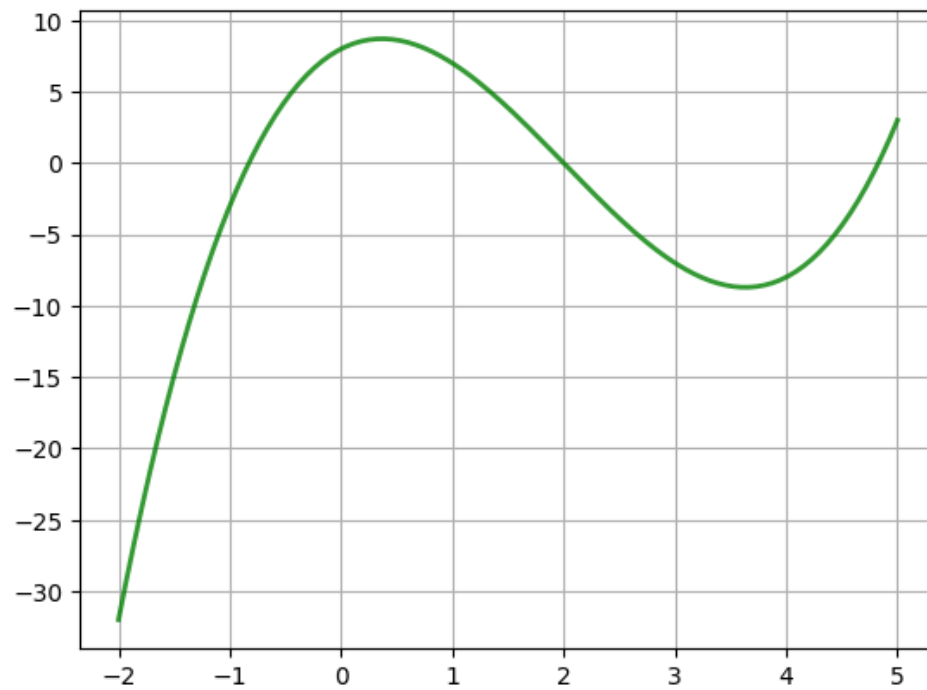
- Differentiate to get  $f'(x) = 3x^2 - 12x + 4$
  - Solve  $3x^2 - 12x + 4 = 0$  to get stationary  $x$
  - Discard any stationary points outside  $[-2, 5]$
  - Eval  $f$  at remaining points plus end points  $-2$  and  $5$
  - Pick point giving largest value
-

```

from sympy import *
x = Symbol('x')
points = [-2, 5]
f = x**3 - 6*x**2 + 4*x + 8
fp = diff(f, x)
spoints = solve(fp, x)
points.extend(spoints)
v = [f.subs(x, c).evalf() for c in points]
maximizer = points[v.index(max(v))]
print("Maximizer =", str(maximizer), '=', maximizer.evalf())

```

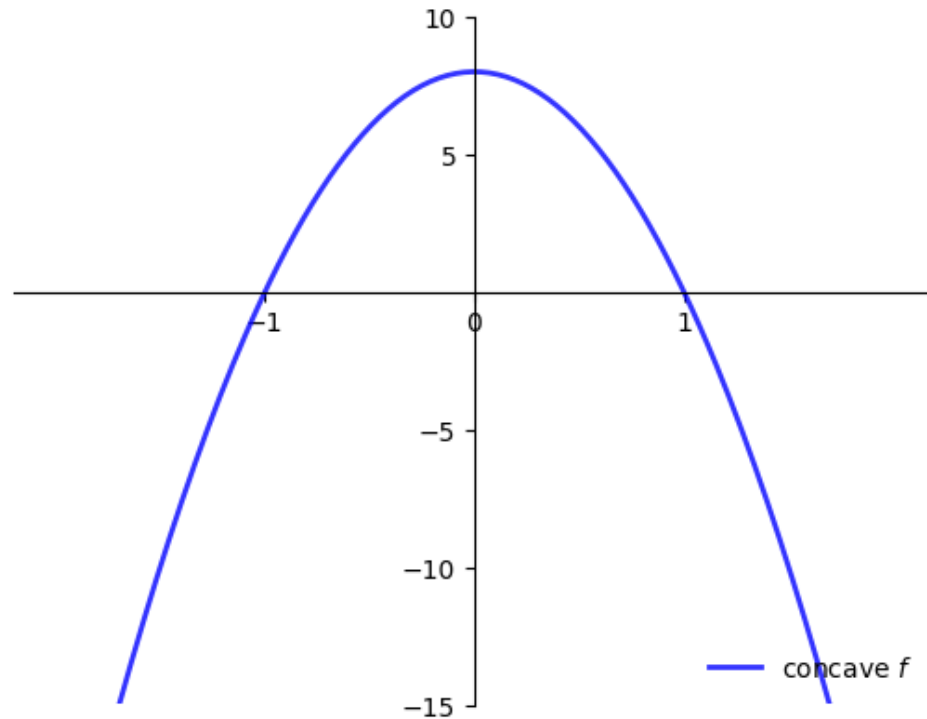
```
Maximizer = 2 - 2*sqrt(6)/3 = 0.367006838144548
```



## 2.6 Shape Conditions and Sufficiency

When is  $f'(x^*) = 0$  sufficient for  $x^*$  to be a maximizer?

One answer: When  $f$  is concave



(Full definition deferred)

---

**Sufficient conditions for *concavity* in one dimension**

Let  $f: [a, b] \rightarrow \mathbb{R}$

- If  $f''(x) \leq 0$  for all  $x \in (a, b)$  then  $f$  is concave on  $(a, b)$
- If  $f''(x) < 0$  for all  $x \in (a, b)$  then  $f$  is **strictly** concave on  $(a, b)$

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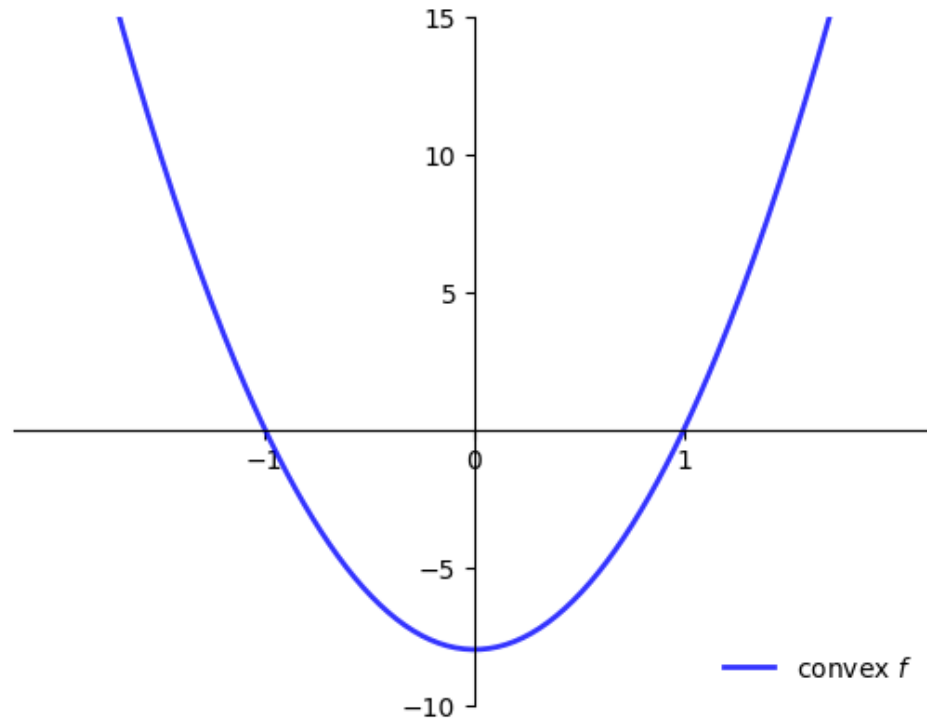
**Example**

- $f(x) = a + bx$  is concave on  $\mathbb{R}$  but not strictly
- $f(x) = \log(x)$  is strictly concave on  $(0, \infty)$

---

When is  $f'(x^*) = 0$  sufficient for  $x^*$  to be a minimizer?

One answer: When  $f$  is convex



(Full definition deferred)

### Sufficient conditions for *convexity* in one dimension

Let  $f: [a, b] \rightarrow \mathbb{R}$

- If  $f''(x) \geq 0$  for all  $x \in (a, b)$  then  $f$  is convex on  $(a, b)$
- If  $f''(x) > 0$  for all  $x \in (a, b)$  then  $f$  is **strictly** convex on  $(a, b)$

### Example

- $f(x) = a + bx$  is convex on  $\mathbb{R}$  but not strictly
- $f(x) = x^2$  is strictly convex on  $\mathbb{R}$

## 2.6.1 Sufficiency and uniqueness with shape conditions

### Fact

For maximizers:

- If  $f: [a, b] \rightarrow \mathbb{R}$  is concave and  $x^* \in (a, b)$  is stationary then  $x^*$  is a maximizer
- If, in addition,  $f$  is strictly concave, then  $x^*$  is the unique maximizer

### Fact

For minimizers:

- If  $f: [a, b] \rightarrow \mathbb{R}$  is convex and  $x^* \in (a, b)$  is stationary then  $x^*$  is a minimizer
  - If, in addition,  $f$  is strictly convex, then  $x^*$  is the unique minimizer
- 

### Example

A price taking firm faces output price  $p > 0$ , input price  $w > 0$

Maximize profits with respect to input  $\ell$

$$\max_{\ell \geq 0} \pi(\ell) = pf(\ell) - w\ell,$$

where the production technology is given by

$$f(\ell) = \ell^\alpha, 0 < \alpha < 1.$$

---

Evidently

$$\pi'(\ell) = \alpha p \ell^{\alpha-1} - w,$$

so unique stationary point is

$$\ell^* = (\alpha p / w)^{1/(1-\alpha)}$$

Moreover,

$$\pi''(\ell) = \alpha(\alpha - 1)p\ell^{\alpha-2} < 0$$

for all  $\ell \geq 0$  so  $\ell^*$  is unique maximizer.

## 2.7 Functions of two variables

Let's have a look at some functions of two variables

- How to visualize them
  - Slope, contours, etc.
- 

### Example: Cobb-Douglas production function

Consider production function

$$f(k, \ell) = k^\alpha \ell^\beta$$
$$\alpha \geq 0, \beta \geq 0, \alpha + \beta < 1$$

Let's graph it in two dimensions.

---

Like many 3D plots it's hard to get a good understanding

Let's try again with contours plus heat map

In this context the contour lines are called *isoquants*

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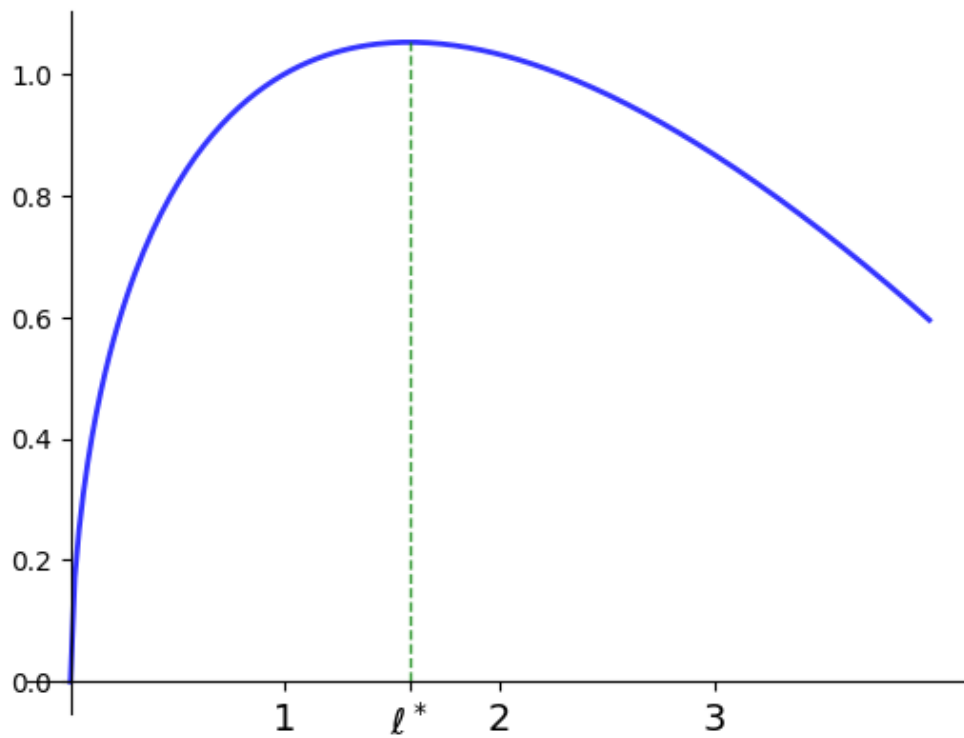


Fig. 2.5: Profit maximization with  $p = 2$ ,  $w = 1$ ,  $\alpha = 0.6$ ,  $\ell^* = 1.5774$

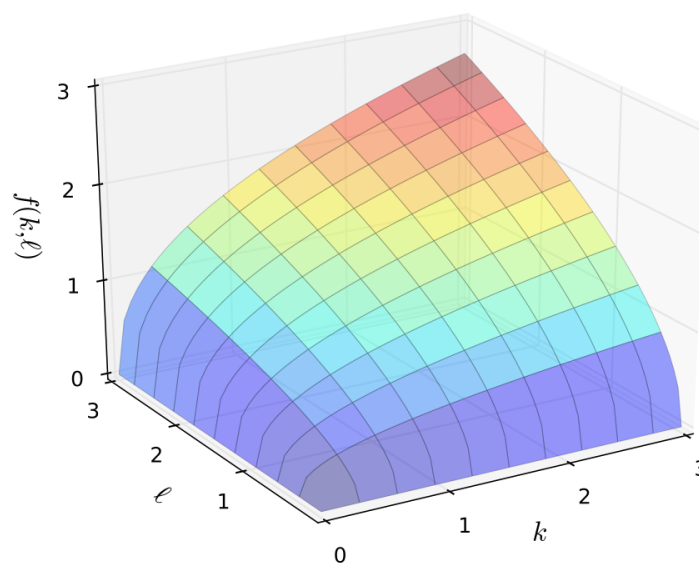


Fig. 2.6: Production function with  $\alpha = 0.4$ ,  $\beta = 0.5$  (a)

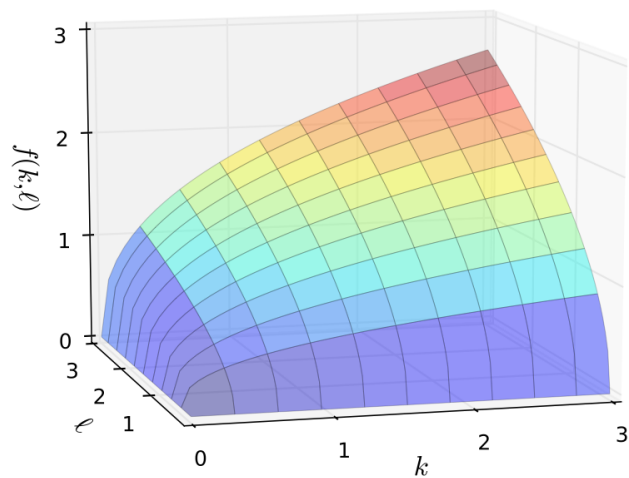


Fig. 2.7: Production function with  $\alpha = 0.4, \beta = 0.5$  (b)

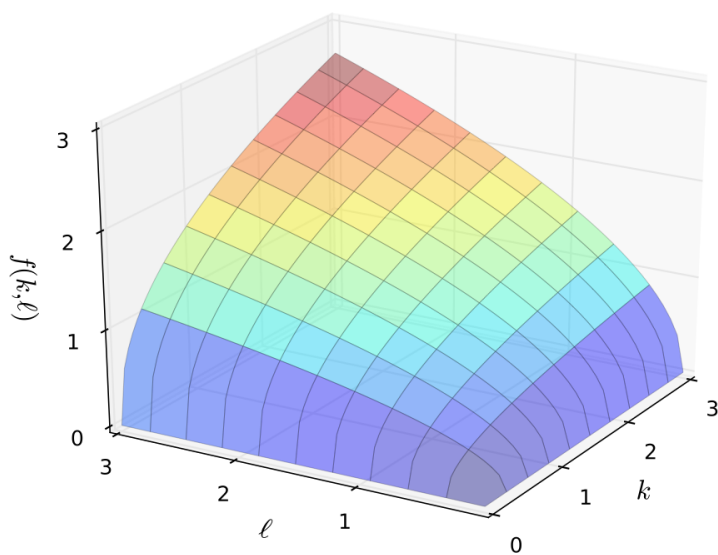


Fig. 2.8: Production function with  $\alpha = 0.4, \beta = 0.5$  (c)

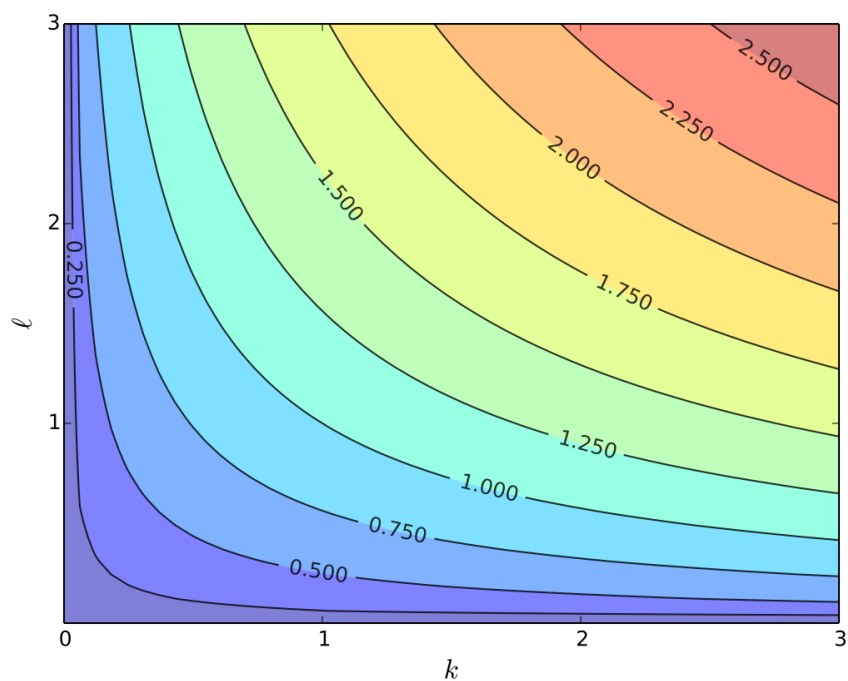


Fig. 2.9: Production function with  $\alpha = 0.4$ ,  $\beta = 0.5$ , contours

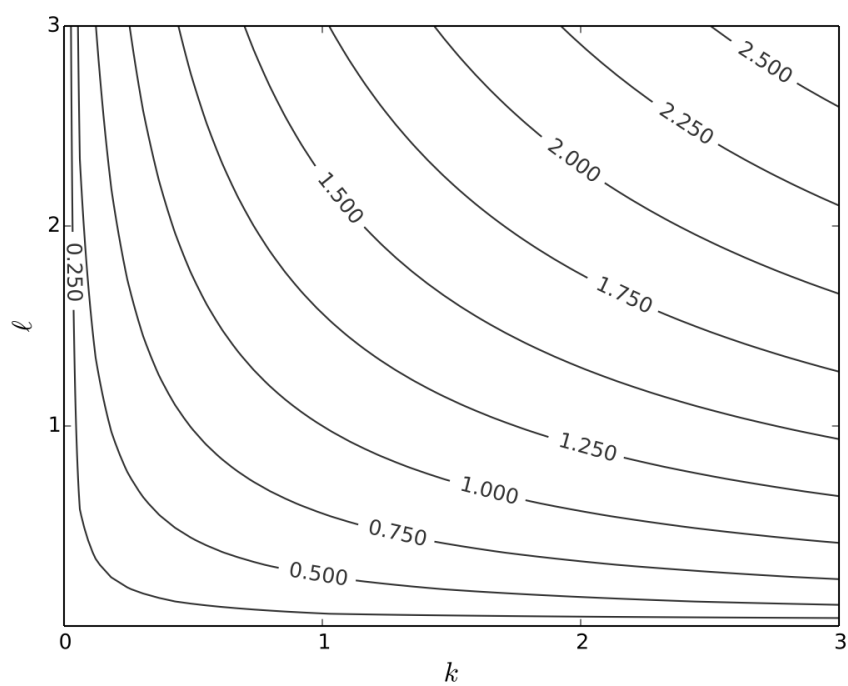


Fig. 2.10: Production function with  $\alpha = 0.4$ ,  $\beta = 0.5$

Can you see how  $\alpha < \beta$  shows up in the slope of the contours?

We can drop the colours to see the numbers more clearly

---

### Example: log-utility

Let  $u(x_1, x_2)$  be “utility” gained from  $x_1$  units of good 1 and  $x_2$  units of good 2

We take

$$u(x_1, x_2) = \alpha \log(x_1) + \beta \log(x_2)$$

where

- $\alpha$  and  $\beta$  are parameters
  - we assume  $\alpha > 0, \beta > 0$
  - The log functions mean “diminishing returns” in each good
- 

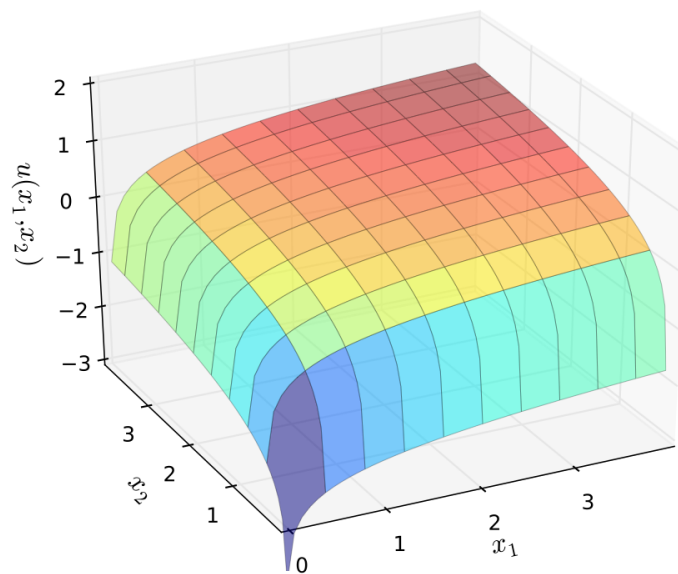


Fig. 2.11: Log utility with  $\alpha = 0.4, \beta = 0.5$

Let's look at the contour lines

For utility functions, contour lines called *indifference curves*

---

### Example: quasi-linear utility

$$u(x_1, x_2) = x_1 + \log(x_2)$$

- Called quasi-linear because linear in good 1

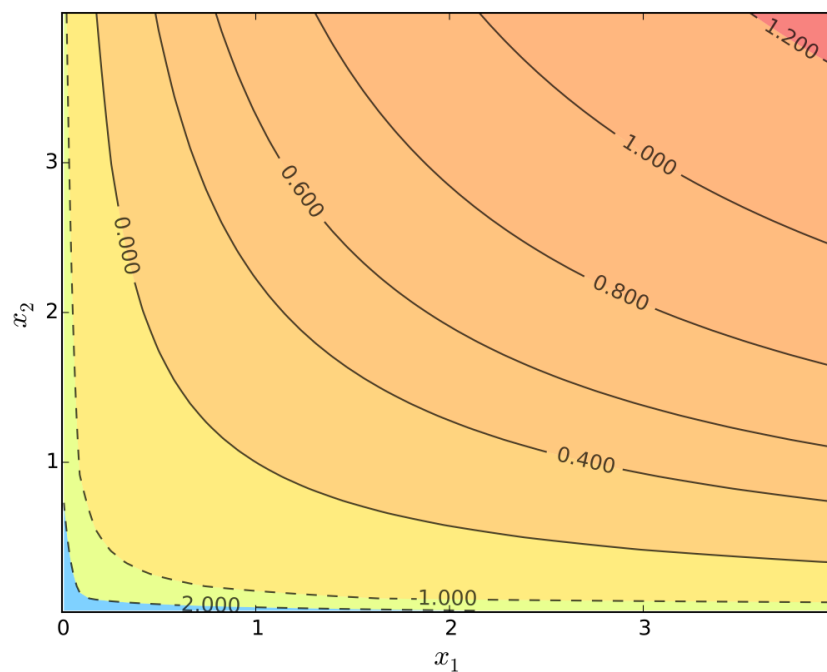


Fig. 2.12: Indifference curves of log utility with  $\alpha = 0.4$ ,  $\beta = 0.5$

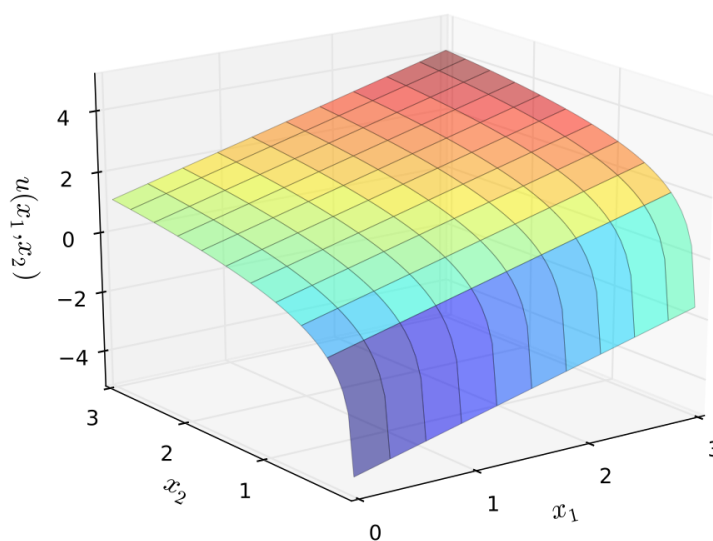


Fig. 2.13: Quasi-linear utility

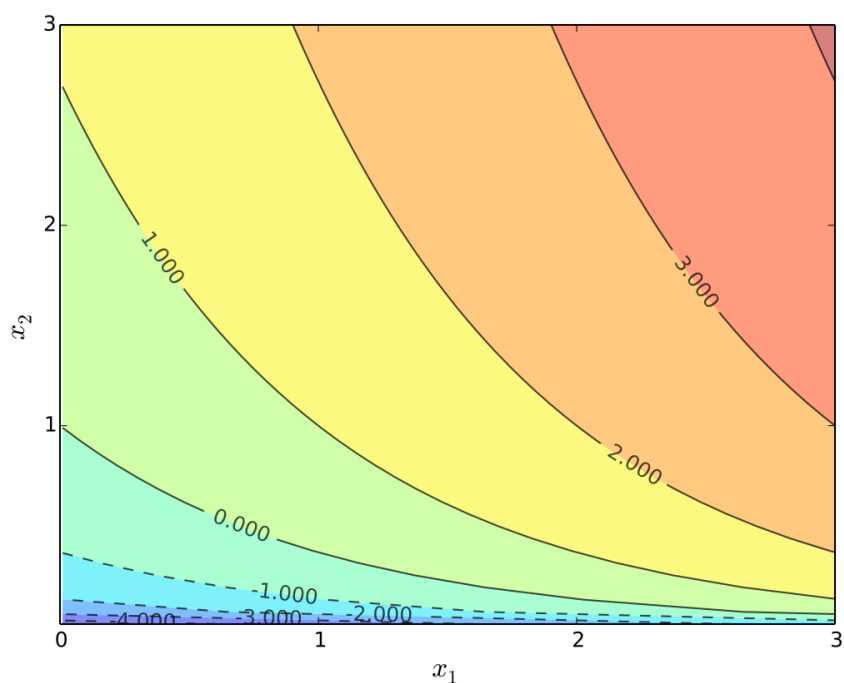


Fig. 2.14: Indifference curves of quasi-linear utility

---

**Example: quadratic utility**

$$u(x_1, x_2) = -(x_1 - b_1)^2 - (x_2 - b_2)^2$$

Here

- $b_1$  is a “satiation” or “bliss” point for  $x_1$
- $b_2$  is a “satiation” or “bliss” point for  $x_2$

Dissatisfaction increases with deviations from the bliss points

## 2.8 Bivariate Optimization

Consider  $f: I \rightarrow \mathbb{R}$  where  $I \subset \mathbb{R}^2$

The set  $\mathbb{R}^2$  is all  $(x_1, x_2)$  pairs

---

**Definition**

A point  $(x_1^*, x_2^*) \in I$  is called a **maximizer** of  $f$  on  $I$  if

$$f(x_1^*, x_2^*) \geq f(x_1, x_2) \quad \text{for all } (x_1, x_2) \in I$$

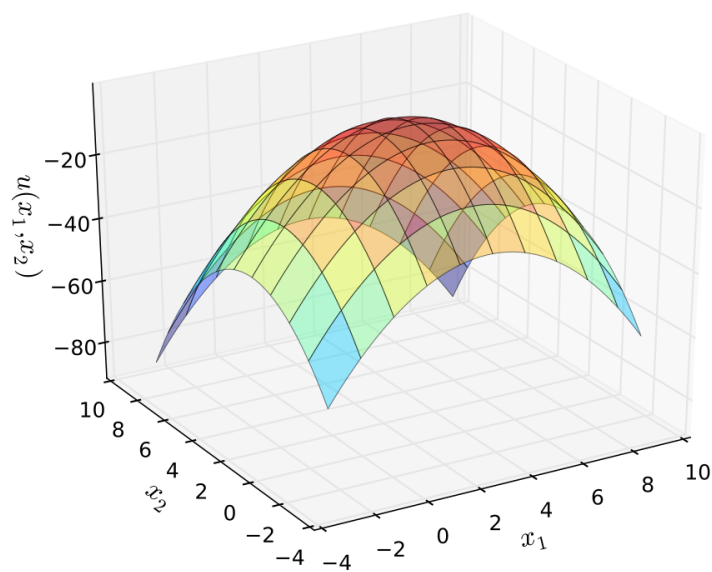


Fig. 2.15: Quadratic utility with  $b_1 = 3$  and  $b_2 = 2$

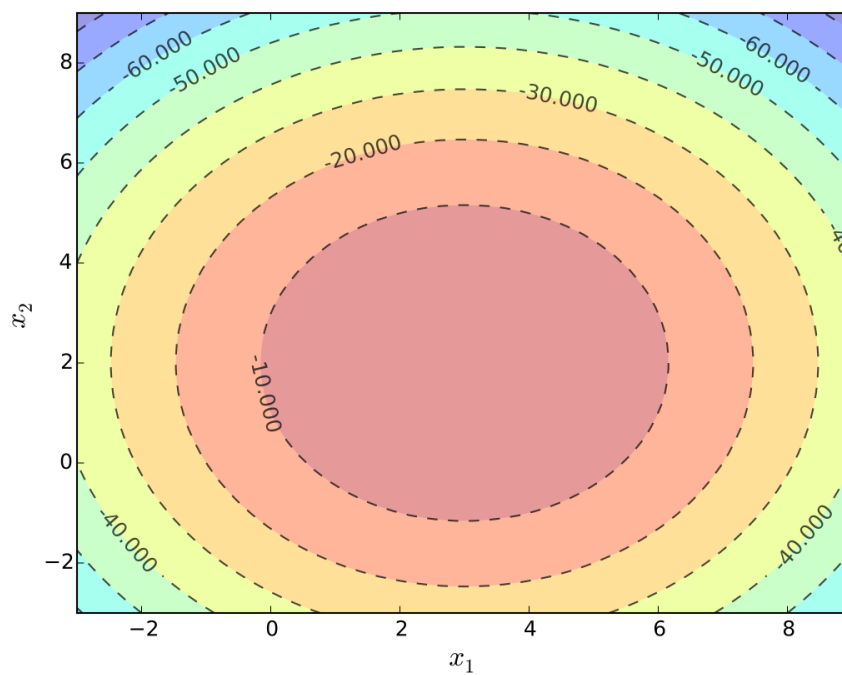


Fig. 2.16: Indifference curves quadratic utility with  $b_1 = 3$  and  $b_2 = 2$

**Definition**

A point  $(x_1^*, x_2^*) \in I$  is called a **minimizer** of  $f$  on  $I$  if  $f(x_1^*, x_2^*) \leq f(x_1, x_2)$  for all  $(x_1, x_2) \in I$

---

When they exist, the partial derivatives at  $(x_1, x_2) \in I$  are

$$f_1(x_1, x_2) = \frac{\partial}{\partial x_1} f(x_1, x_2)$$
$$f_2(x_1, x_2) = \frac{\partial}{\partial x_2} f(x_1, x_2)$$

---

**Example**

When  $f(k, \ell) = k^\alpha \ell^\beta$ ,

$$f_1(k, \ell) = \frac{\partial}{\partial k} f(k, \ell) = \frac{\partial}{\partial k} k^\alpha \ell^\beta = \alpha k^{\alpha-1} \ell^\beta$$

---

**Definition**

An interior point  $(x_1, x_2) \in I$  is called **stationary** for  $f$  if

$$f_1(x_1, x_2) = f_2(x_1, x_2) = 0$$

---

**Fact**

Let  $f: I \rightarrow \mathbb{R}$  be a continuously differentiable function. If  $(x_1^*, x_2^*)$  is either

- an interior maximizer of  $f$  on  $I$ , or
- an interior minimizer of  $f$  on  $I$ ,

then  $(x_1^*, x_2^*)$  is a stationary point of  $f$

---

Usage, for maximization:

1. Compute partials
  2. Set partials to zero to find  $S$  = all stationary points
  3. Evaluate candidates in  $S$  and boundary of  $I$
  4. Select point  $(x_1^*, x_2^*)$  yielding highest value
- 

**Example**

$$f(x_1, x_2) = x_1^2 + 4x_2^2 \rightarrow \min \quad \text{s.t.} \quad x_1 + x_2 \leq 1$$

---

Setting

$$f_1(x_1, x_2) = 2x_1 = 0 \quad \text{and} \quad f_2(x_1, x_2) = 8x_2 = 0$$

---



gives the unique stationary point  $(0, 0)$ , at which  $f(0, 0) = 0$

On the boundary we have  $x_1 + x_2 = 1$ , so

$$f(x_1, x_2) = f(x_1, 1 - x_1) = x_1^2 + 4(1 - x_1)^2$$

**Exercise:** Show right hand side  $> 0$  for any  $x_1$

Hence minimizer is  $(x_1^*, x_2^*) = (0, 0)$

## 2.8.1 Nasty secrets

Solving for  $(x_1, x_2)$  such that  $f_1(x_1, x_2) = 0$  and  $f_2(x_1, x_2) = 0$  can be hard

- System of nonlinear equations
- Might have no analytical solution
- Set of solutions can be a continuum

---

### Example

(Don't) try to find all stationary points of

$$f(x_1, x_2) = \frac{\cos(x_1^2 + x_2^2) + x_1^2 + x_1}{2 + p(-x_1^2) + \sin^2(x_2)}$$


---

Also:

- Boundary is often a continuum, not just two points
- Things get even harder in higher dimensions

On the other hand:

- Most classroom examples are chosen to avoid these problems
- Life is still pretty easy if we have concavity / convexity
- Clever tricks have been found for certain kinds of problems

## 2.9 Second Order Partial

Let  $f: I \rightarrow \mathbb{R}$  and, when they exist, denote

$$f_{11}(x_1, x_2) = \frac{\partial^2}{\partial x_1^2} f(x_1, x_2)$$

$$f_{12}(x_1, x_2) = \frac{\partial^2}{\partial x_1 \partial x_2} f(x_1, x_2)$$

$$f_{21}(x_1, x_2) = \frac{\partial^2}{\partial x_2 \partial x_1} f(x_1, x_2)$$

$$f_{22}(x_1, x_2) = \frac{\partial^2}{\partial x_2^2} f(x_1, x_2)$$

**Example: Cobb-Douglas technology with linear costs**

If  $\pi(k, \ell) = pk^\alpha \ell^\beta - w\ell - rk$  then

$$\pi_{11}(k, \ell) = p\alpha(\alpha - 1)k^{\alpha-2}\ell^\beta$$

$$\pi_{12}(k, \ell) = p\alpha\beta k^{\alpha-1}\ell^{\beta-1}$$

$$\pi_{21}(k, \ell) = p\alpha\beta k^{\alpha-1}\ell^{\beta-1}$$

$$\pi_{22}(k, \ell) = p\beta(\beta - 1)k^\alpha \ell^{\beta-2}$$

---

**Fact**

If  $f: I \rightarrow \mathbb{R}$  is twice continuously differentiable at  $(x_1, x_2)$ , then  $f_{12}(x_1, x_2) = f_{21}(x_1, x_2)$

---

**Exercise:** Confirm the results in the exercise above.

## 2.10 Shape conditions in 2D

Let  $I$  be an “open” set (only interior points – formalities next week)

Let  $f: I \rightarrow \mathbb{R}$  be twice continuously differentiable

The function  $f$  is strictly **concave** on  $I$  if, for any  $(x_1, x_2) \in I$

1.  $f_{11}(x_1, x_2) < 0$
2.  $f_{11}(x_1, x_2) f_{22}(x_1, x_2) > f_{12}(x_1, x_2)^2$

The function  $f$  is strictly **convex** on  $I$  if, for any  $(x_1, x_2) \in I$

1.  $f_{11}(x_1, x_2) > 0$
2.  $f_{11}(x_1, x_2) f_{22}(x_1, x_2) > f_{12}(x_1, x_2)^2$

When is stationarity sufficient?

**Fact**

If  $f$  is differentiable and strictly concave on  $I$ , then any stationary point of  $f$  is also a unique maximizer of  $f$  on  $I$

---

**Fact**

If  $f$  is differentiable and strictly convex on  $I$ , then any stationary point of  $f$  is also a unique minimizer of  $f$  on  $I$

---

**Example: unconstrained maximization of quadratic utility**

$$u(x_1, x_2) = -(x_1 - b_1)^2 - (x_2 - b_2)^2 \rightarrow \max_{x_1, x_2}$$

---

Intuitively the solution is  $x_1^* = b_1$  and  $x_2^* = b_2$

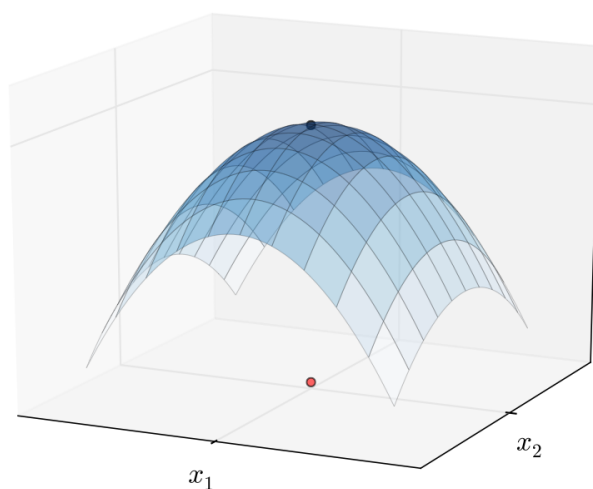


Fig. 2.17: Maximizer of a concave function

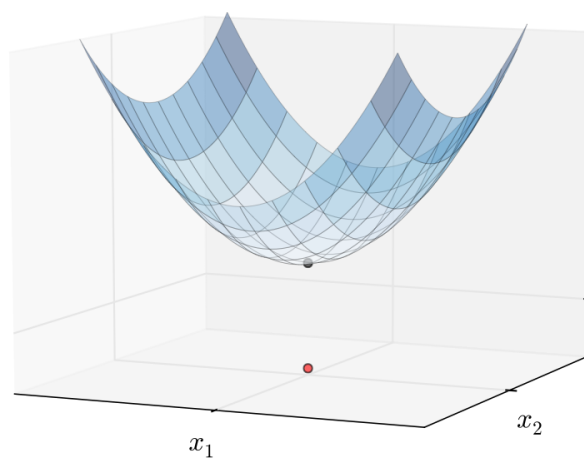


Fig. 2.18: Minimizer of a convex function

Analysis above leads to the same conclusion

First let's check first order conditions (F.O.C.)

$$\frac{\partial}{\partial x_1} u(x_1, x_2) = -2(x_1 - b_1) = 0 \implies x_1 = b_1$$

$$\frac{\partial}{\partial x_2} u(x_1, x_2) = -2(x_2 - b_2) = 0 \implies x_2 = b_2$$

How about (strict) concavity?

Sufficient condition is

1.  $u_{11}(x_1, x_2) < 0$
2.  $u_{11}(x_1, x_2)u_{22}(x_1, x_2) > u_{12}(x_1, x_2)^2$

We have

- $u_{11}(x_1, x_2) = -2$
- $u_{11}(x_1, x_2)u_{22}(x_1, x_2) = 4 > 0 = u_{12}(x_1, x_2)^2$

---

**Example: Profit maximization with two inputs**

$$\pi(k, \ell) = pk^\alpha \ell^\beta - w\ell - rk \rightarrow \max_{k, \ell}$$

where  $\alpha, \beta, p, w$  are all positive and  $\alpha + \beta < 1$

---

Derivatives:

- $\pi_1(k, \ell) = p\alpha k^{\alpha-1} \ell^\beta - r$
- $\pi_2(k, \ell) = p\beta k^\alpha \ell^{\beta-1} - w$
- $\pi_{11}(k, \ell) = p\alpha(\alpha-1)k^{\alpha-2} \ell^\beta$
- $\pi_{22}(k, \ell) = p\beta(\beta-1)k^\alpha \ell^{\beta-2}$
- $\pi_{12}(k, \ell) = p\alpha\beta k^{\alpha-1} \ell^{\beta-1}$

First order conditions: set

$$\begin{aligned}\pi_1(k, \ell) &= 0 \\ \pi_2(k, \ell) &= 0\end{aligned}$$

and solve simultaneously for  $k, \ell$  to get

$$\begin{aligned}k^* &= [p(\alpha/r)^{1-\beta}(\beta/w)^\beta]^{1/(1-\alpha-\beta)} \\ \ell^* &= [p(\beta/w)^{1-\alpha}(\alpha/r)^\alpha]^{1/(1-\alpha-\beta)}\end{aligned}$$

**Exercise:** Verify

Now we check second order conditions, hoping for strict concavity

What we need: for any  $k, \ell > 0$

1.  $\pi_{11}(k, \ell) < 0$
2.  $\pi_{11}(k, \ell)\pi_{22}(k, \ell) > \pi_{12}(k, \ell)^2$

**Exercise:** Show both inequalities satisfied when  $\alpha + \beta < 1$

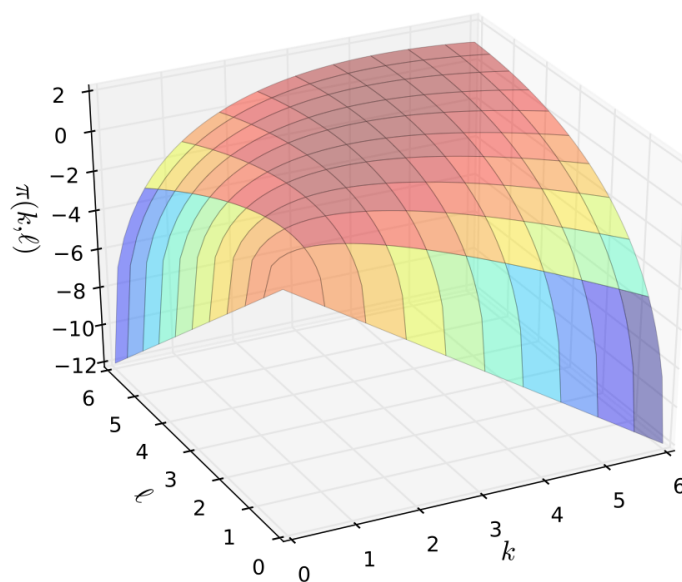


Fig. 2.19: Profit function when  $p = 5$ ,  $r = w = 2$ ,  $\alpha = 0.4$ ,  $\beta = 0.5$

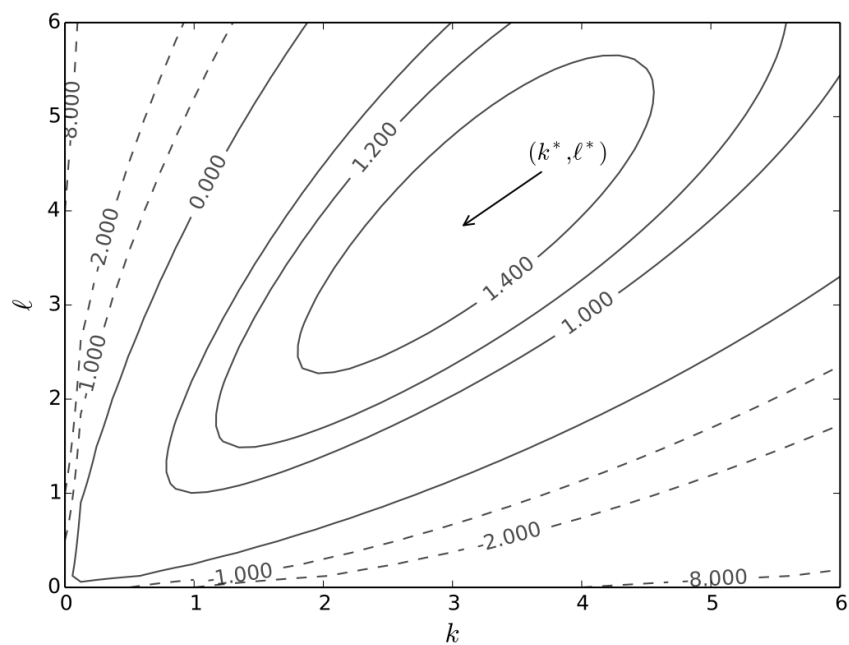


Fig. 2.20: Optimal choice,  $p = 5$ ,  $r = w = 2$ ,  $\alpha = 0.4$ ,  $\beta = 0.5$



## ELEMENTS OF SET THEORY AND ANALYSIS

COMING SOON





## ELEMENTS OF LINEAR ALGEBRA

COMING SOON



## ELEMENTS OF PROBABILITY

COMING SOON



## FUNDAMENTALS OF OPTIMIZATION

COMING SOON



## UNCONSTRAINED OPTIMIZATION

COMING SOON





## CONSTRAINED OPTIMIZATION

COMING SOON



## PRACTICAL SESSION

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## ENVELOPE AND MAXIMUM THEOREMS

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CHAPTER  
**TWELVE**

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**REVISION**

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