

Behavioural Equivalences

Rocco De Nicola

Dipartimento di Sistemi ed Informatica
Università di Firenze

Process Algebras and Concurrent Systems

Behavioural Equivalence

Implementation

$$CM \stackrel{\text{def}}{=} \text{coin}.\overline{\text{coffee}}.CM$$

$$PR \stackrel{\text{def}}{=} \overline{\text{hello}}.\overline{\text{coin}}.\overline{\text{coffee}}.\overline{\text{drink}}.PR$$

$$UNI \stackrel{\text{def}}{=} (CM \mid PR) \setminus \{\text{coin}, \text{coffee}\}$$

Behavioural Equivalence

Implementation

$$CM \stackrel{\text{def}}{=} \text{coin}.\overline{\text{coffee}}.CM$$

$$PR \stackrel{\text{def}}{=} \overline{\text{hello}}.\overline{\text{coin}}.\overline{\text{coffee}}.\overline{\text{drink}}.PR$$

$$UNI \stackrel{\text{def}}{=} (CM \mid PR) \setminus \{\text{coin}, \text{coffee}\}$$

Specification

$$Spec \stackrel{\text{def}}{=} \overline{\text{hello}}.\tau.\tau.\overline{\text{drink}}.Spec$$

Behavioural Equivalence

Implementation

$$\begin{aligned}CM &\stackrel{\text{def}}{=} \text{coin}.\overline{\text{coffee}}.CM \\ PR &\stackrel{\text{def}}{=} \overline{\text{hello}}.\overline{\text{coin}}.\overline{\text{coffee}}.\overline{\text{drink}}.PR \\ UNI &\stackrel{\text{def}}{=} (CM \mid PR) \setminus \{\text{coin}, \text{coffee}\}\end{aligned}$$

Specification

$$Spec \stackrel{\text{def}}{=} \overline{\text{hello}}.\tau.\tau.\overline{\text{drink}}.Spec$$

Question

Are the processes *Uni* and *Spec* “behaviourally equivalent”?

$$Uni \equiv Spec$$

Goals

What should a reasonable behavioural equivalence satisfy?

- Abstract from states (consider only the behaviour – actions)
- Abstract from nondeterminism
- Abstract from internal behaviour

Goals

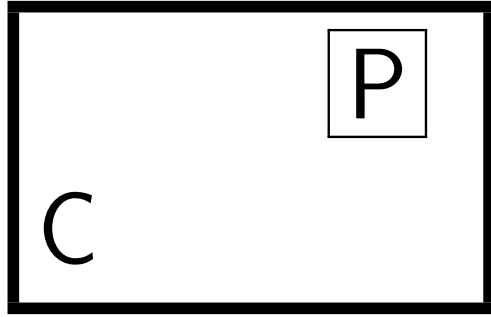
What should a reasonable behavioural equivalence satisfy?

- Abstract from states (consider only the behaviour – actions)
- Abstract from nondeterminism
- Abstract from internal behaviour

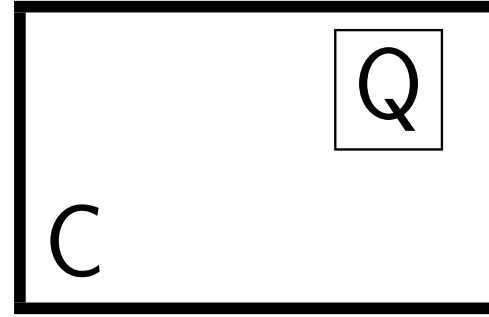
What else should a reasonable behavioural equivalence satisfy?

- **Reflexivity**: $P \equiv P$ for each process P
- **Transitivity**: $Spec_0 \equiv Spec_1 \equiv Spec_2 \equiv \dots \equiv Impl$ gives that
$$Spec_0 \equiv Impl$$
- **Symmetry**: $P \equiv Q$ iff $Q \equiv P$

Congruence

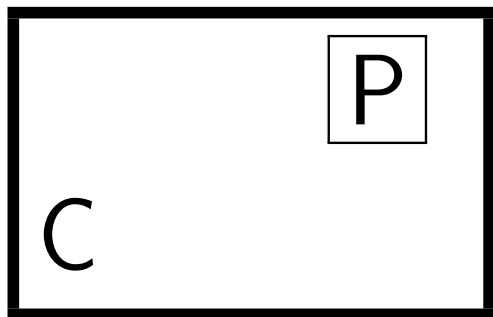


$C(P)$

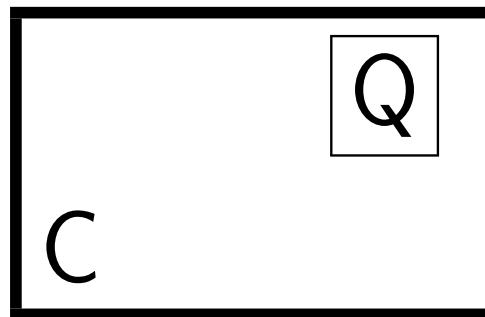


$C(Q)$

Congruence



$C(P)$

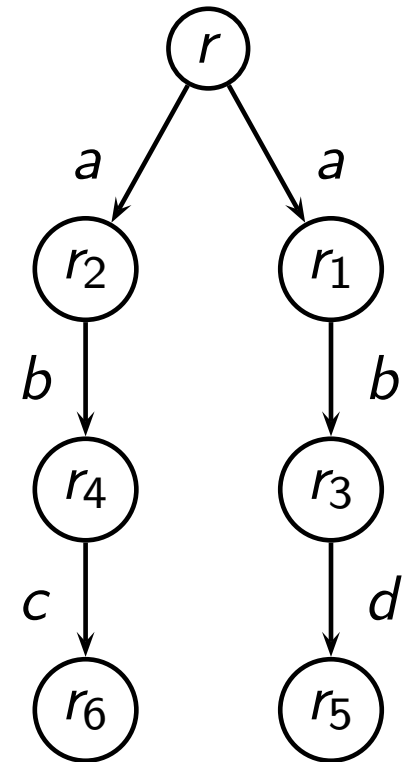
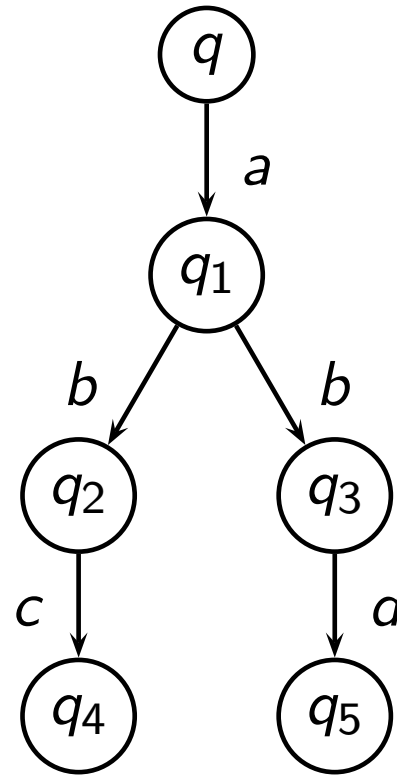
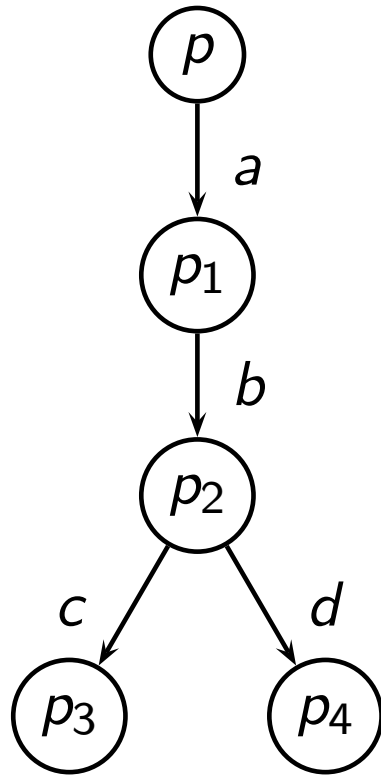


$C(Q)$

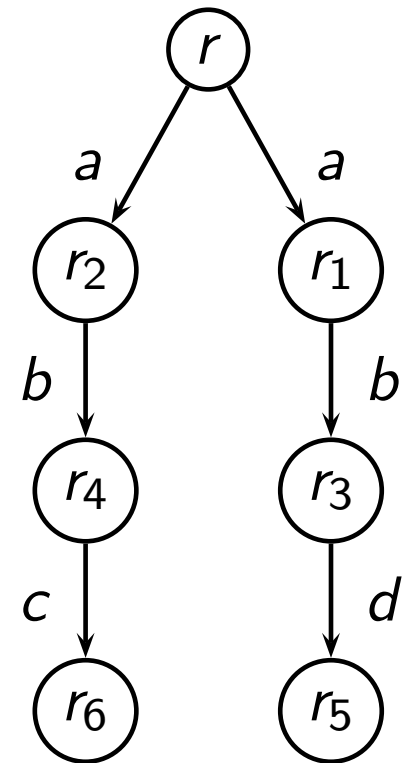
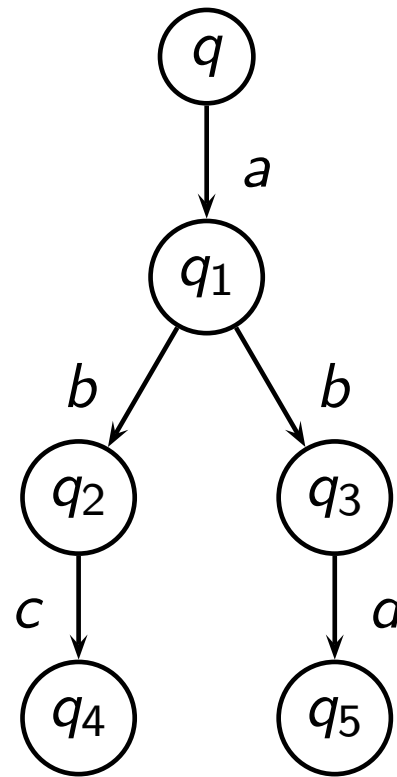
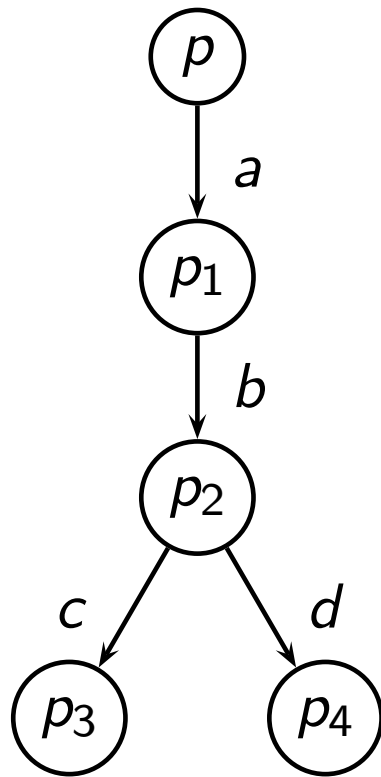
Congruence Property

$P \equiv Q$ implies that $C(P) \equiv C(Q)$

Behavioural Equivalences



Behavioural Equivalences



Problem: Are these three systems equivalent?

Traces/Language Equivalence

Let $\langle Q, A, \rightarrow \rangle$ be an LTS, with $q \in Q$ and $s \in A^*$.

Traces

- 1 s is a *trace* of q if there exists $q' \in Q$ s.t. $q \xrightarrow{s} q'$.
- 2 $T(q)$ represents the set of all traces of q

Traces/Language Equivalence

Let $\langle Q, A, \rightarrow \rangle$ be an LTS, with $q \in Q$ and $s \in A^*$.

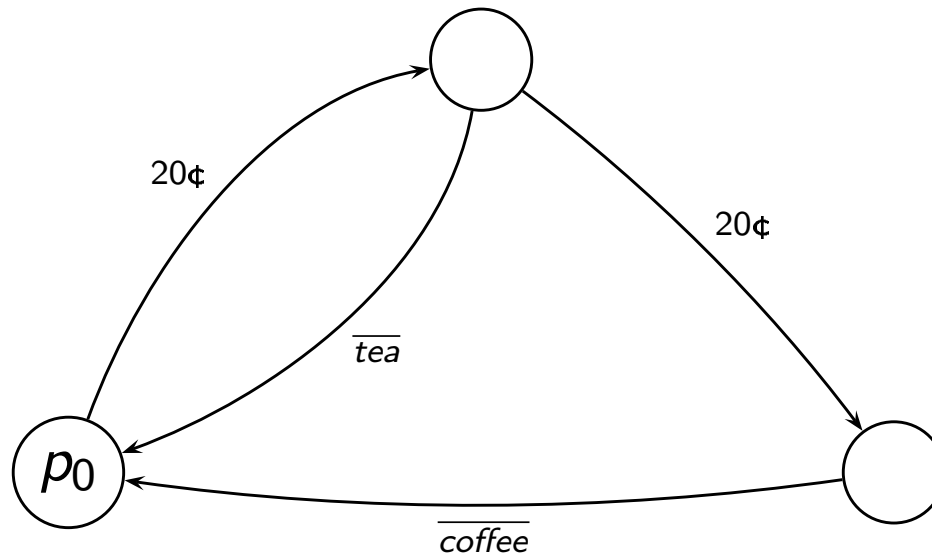
Traces

- 1 s is a *trace* of q if there exists $q' \in Q$ s.t. $q \xrightarrow{s} q'$.
- 2 $T(q)$ represents the set of all traces of q

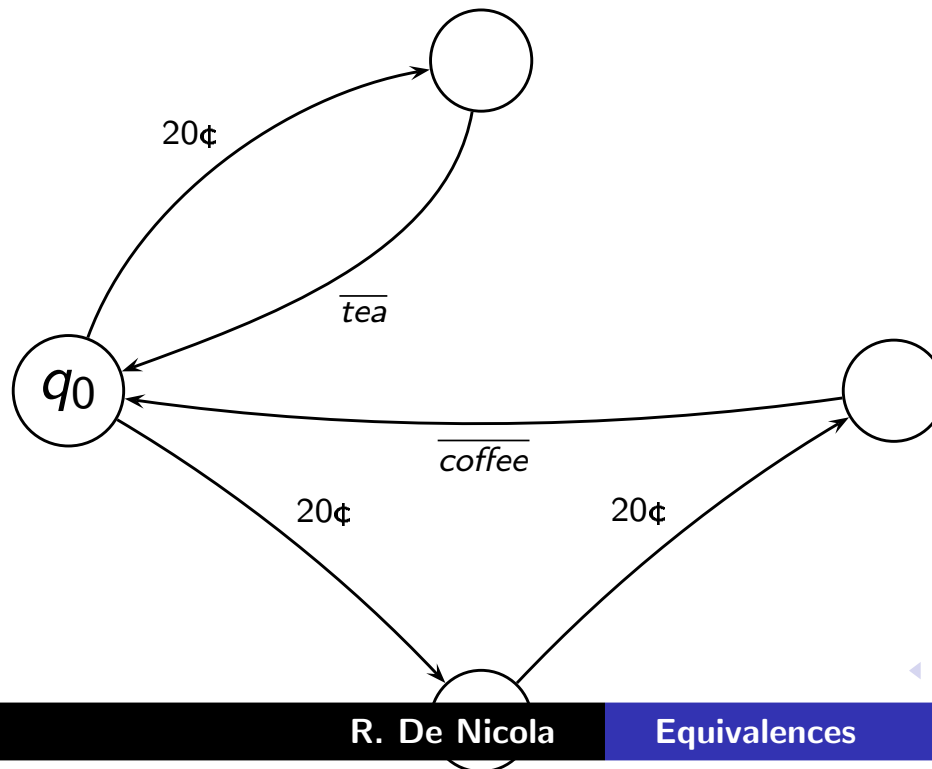
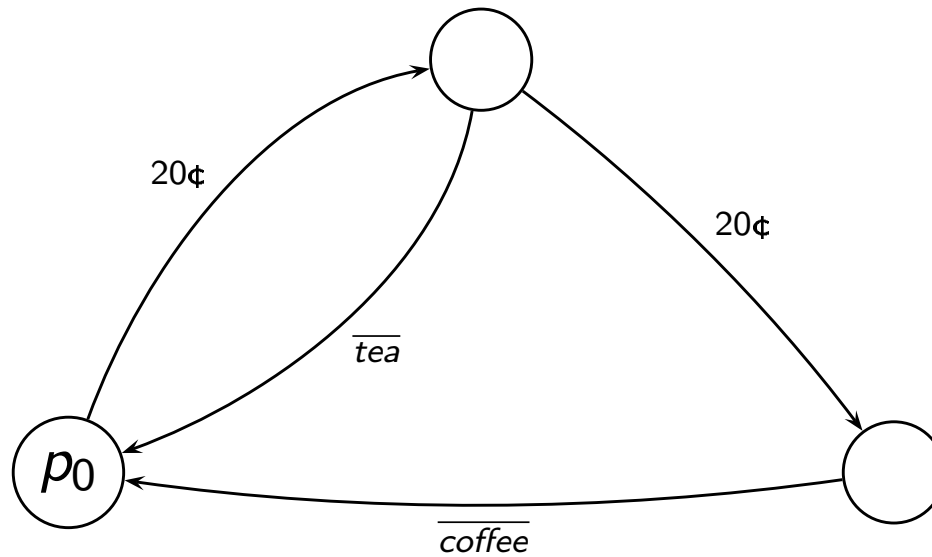
Traces Equivalence

Two states p e q are *trace equivalent*, written $p =_T q$, if $T(p) = T(q)$.

Two Traces Equivalent Systems



Two Traces Equivalent Systems



Bisimulation Relation

Strong Bisimulation

A relation $R \subseteq Q \times Q$ is *strong bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, the following holds:

- 1 for all $a \in A$ e $p' \in Q$, if $p \xrightarrow{a} p'$ then $q \xrightarrow{a} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;
- 2 for all $a \in A$ e $q' \in Q$, if $q \xrightarrow{a} q'$ then $p \xrightarrow{a} p'$ for some $p' \in Q$ such that $\langle p', q' \rangle \in R$.

Bisimulation Relation

Strong Bisimulation

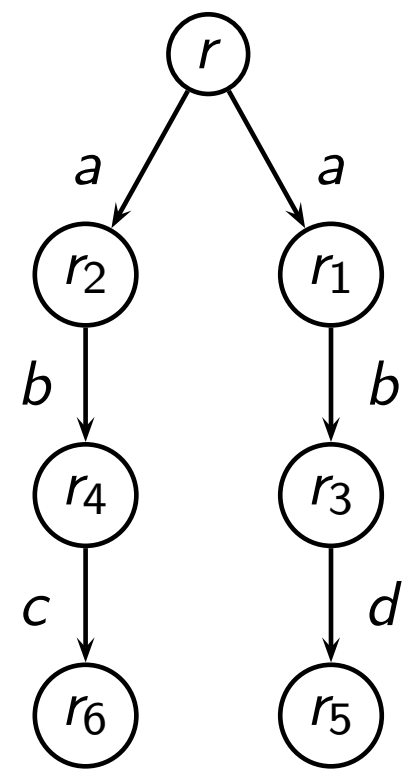
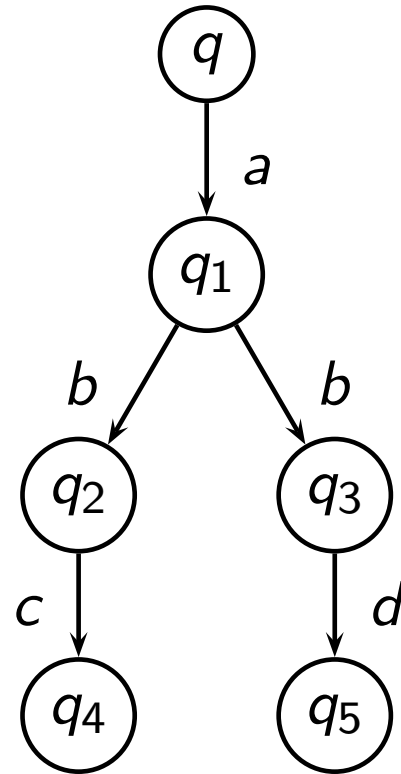
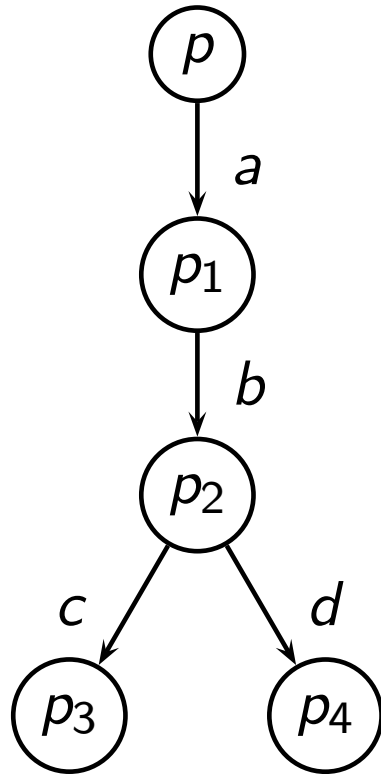
A relation $R \subseteq Q \times Q$ is *strong bisimulation* if, for any pair of states p, q such that $\langle p, q \rangle \in R$, the following holds:

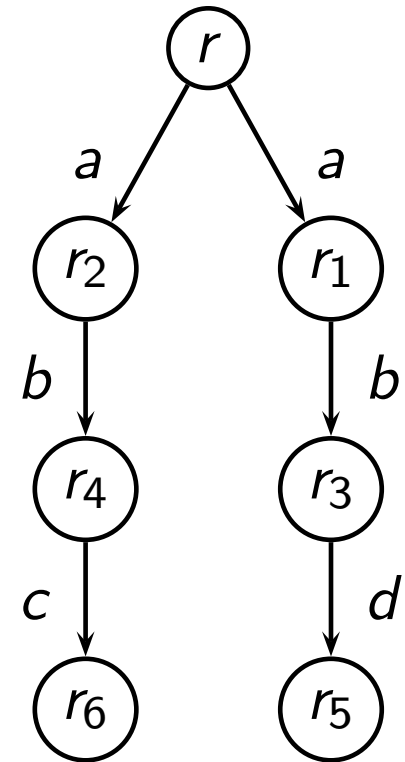
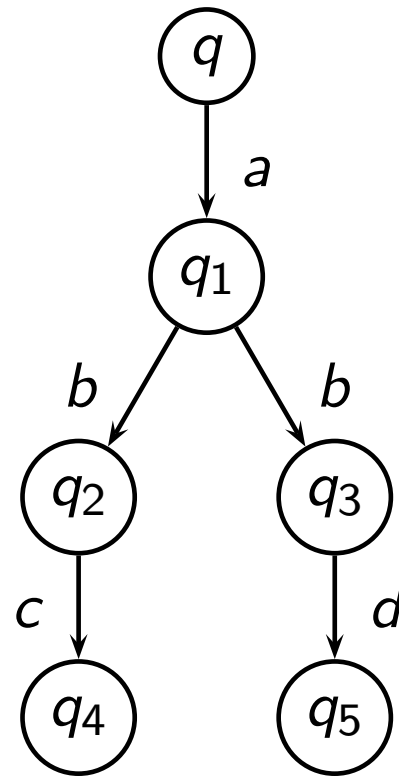
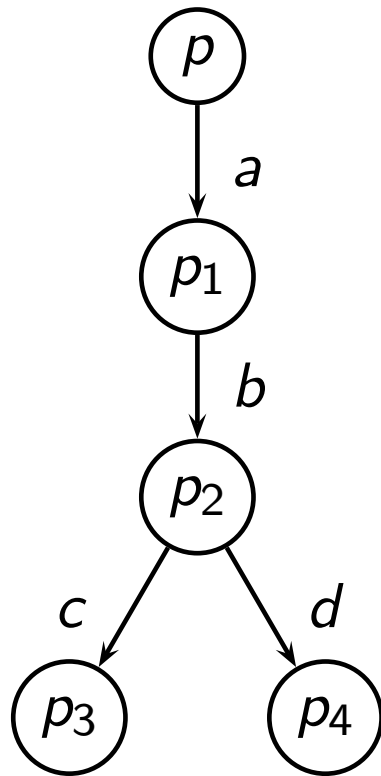
- 1 for all $a \in A$ e $p' \in Q$, if $p \xrightarrow{a} p'$ then $q \xrightarrow{a} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;
- 2 for all $a \in A$ e $q' \in Q$, if $q \xrightarrow{a} q'$ then $p \xrightarrow{a} p'$ for some $p' \in Q$ such that $\langle p', q' \rangle \in R$.

Bisimilarity

Two states $p, q \in Q$ are strongly *bisimilar*, written $p \sim q$, if there exists a strong bisimulation R such that $\langle p, q \rangle \in R$.

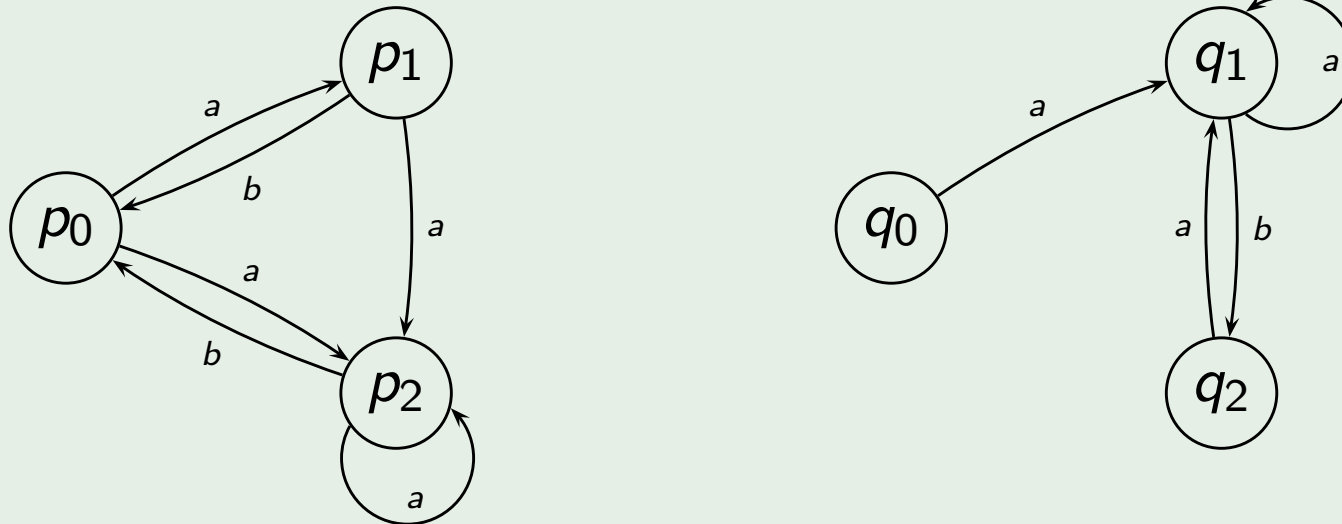
$$\sim = \bigcup \{R \mid R \text{ is a strong bisimulation}\}$$



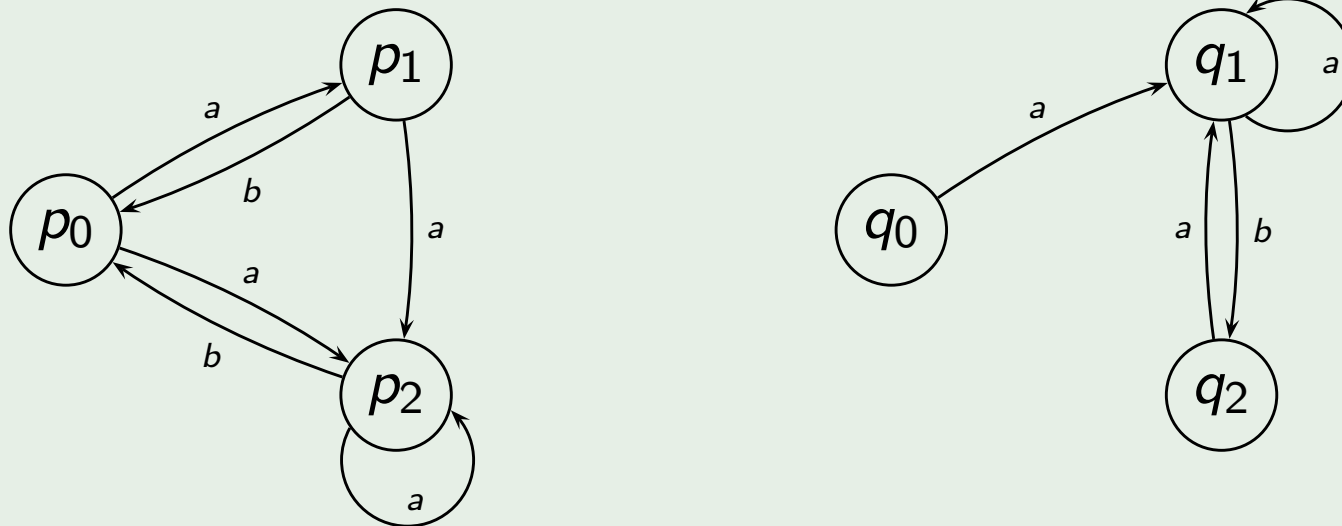


These three systems are not bisimulation equivalent

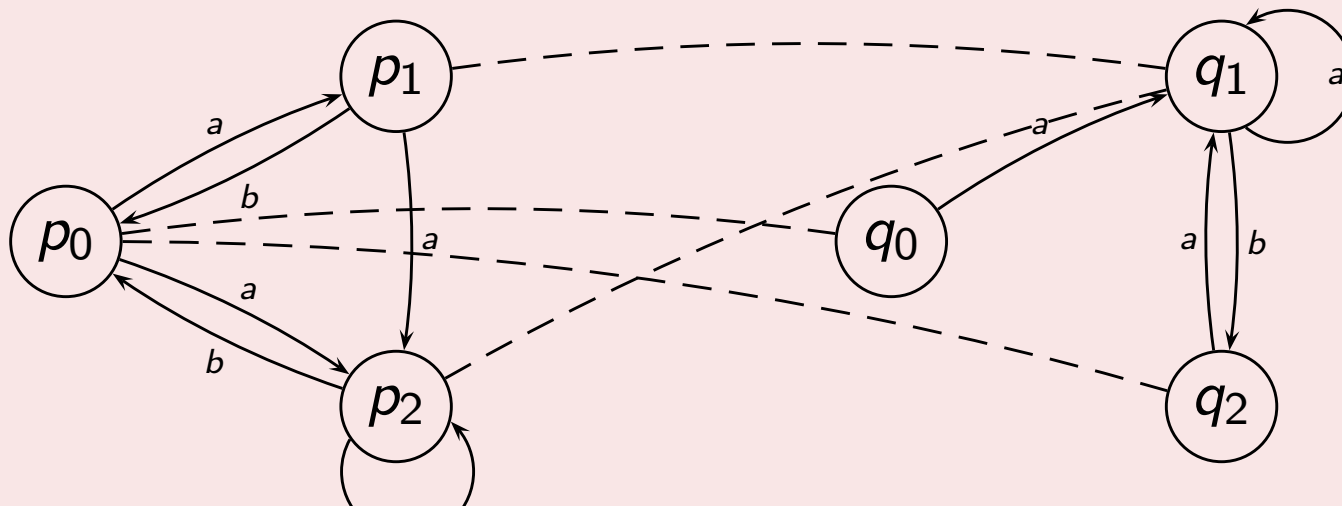
Two bisimilar Systems



Two bisimilar Systems



$R \triangleq \{ \langle p_0, q_0 \rangle, \langle p_0, q_2 \rangle, \langle p_1, q_1 \rangle, \langle p_2, q_1 \rangle \}$ is a strong bisimulation



Basic Properties of Strong Bisimilarity

Theorem

\sim is an equivalence relation (reflexive, symmetric and transitive)

Basic Properties of Strong Bisimilarity

Theorem

\sim is an equivalence relation (reflexive, symmetric and transitive)

Theorem

\sim is the largest strong bisimulation

Basic Properties of Strong Bisimilarity

Theorem

\sim is an equivalence relation (reflexive, symmetric and transitive)

Theorem

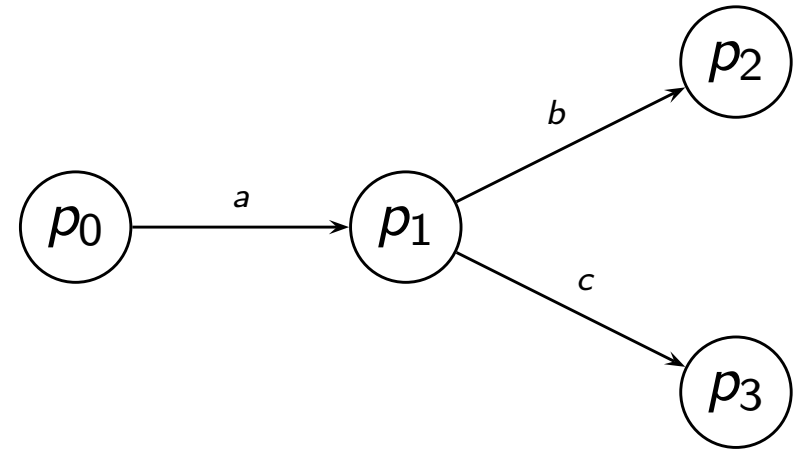
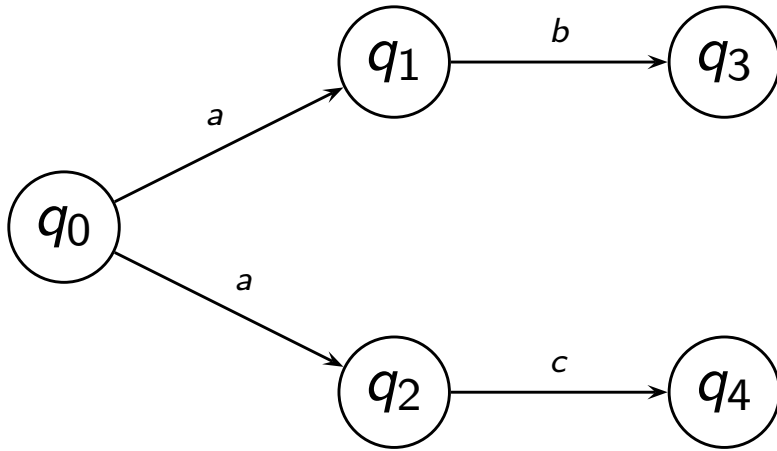
\sim is the largest strong bisimulation

Theorem

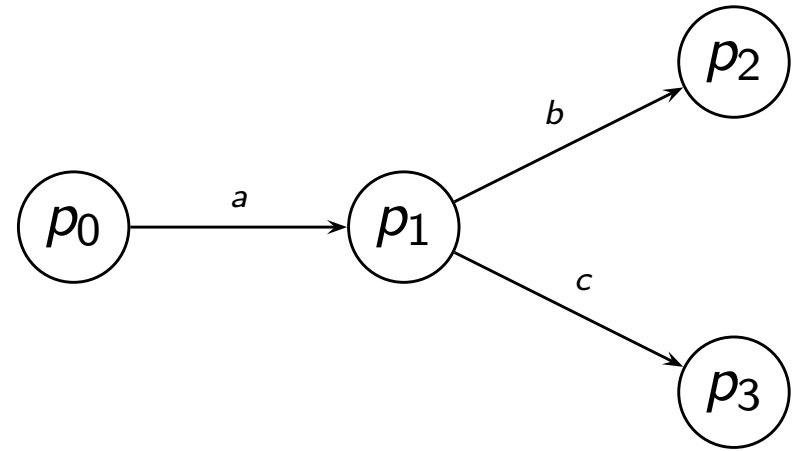
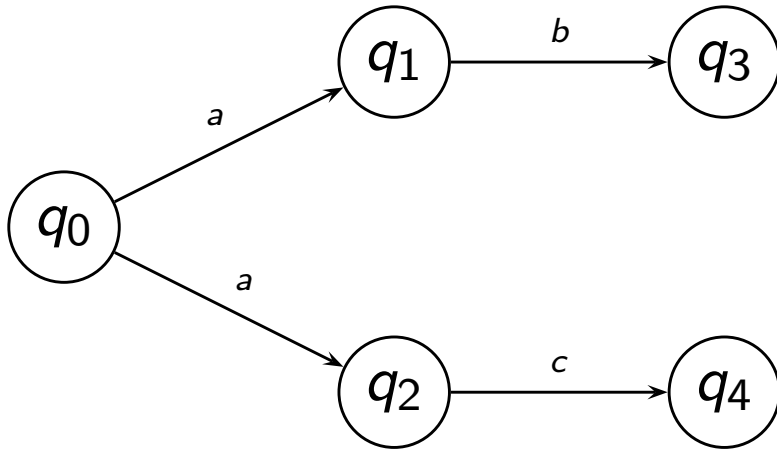
$s \sim t$ if and only if for each $a \in \text{Act}$:

- if $s \xrightarrow{a} s'$ then $t \xrightarrow{a} t'$ for some t' such that $s' \sim t'$
- if $t \xrightarrow{a} t'$ then $s \xrightarrow{a} s'$ for some s' such that $s' \sim t'$.

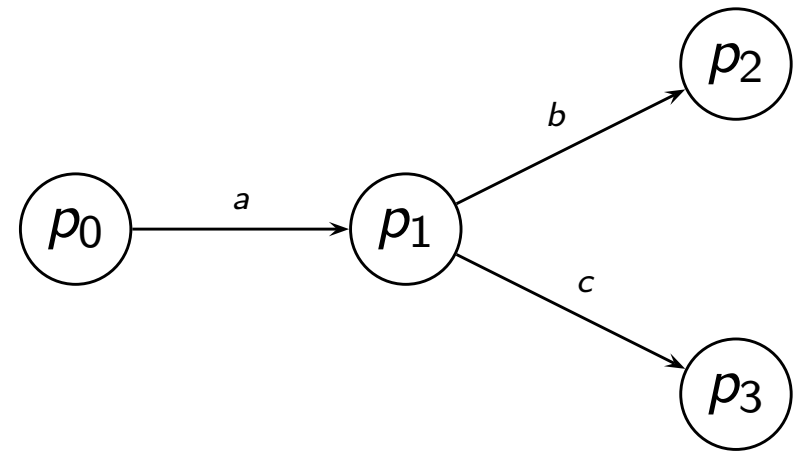
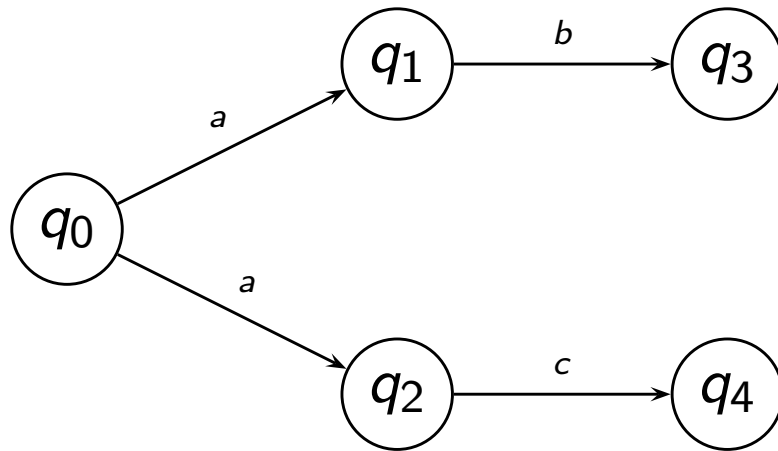
Two Systems that are not bisimilar



Two Systems that are not bisimilar

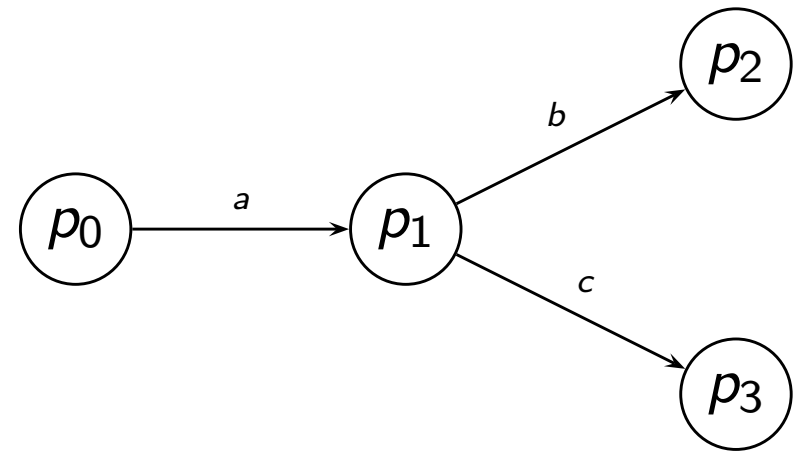
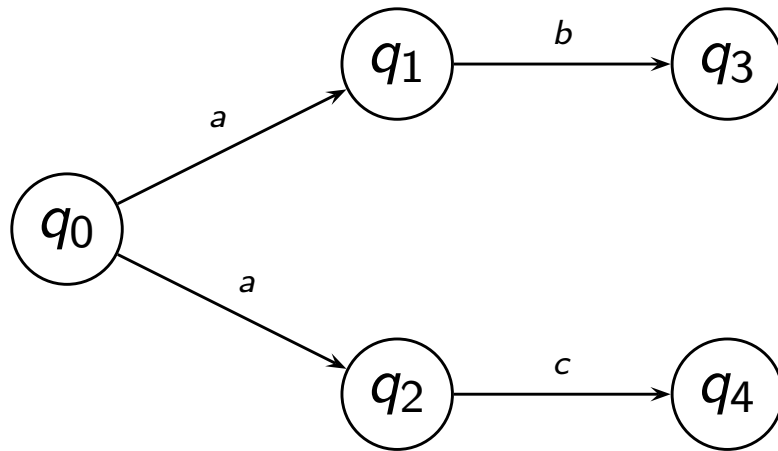


Two Systems that are not bisimilar



- States p_0 and q_0 are not strongly bisimilar.
- If they were equivalent, also states p_1 e q_1 , had to be so.

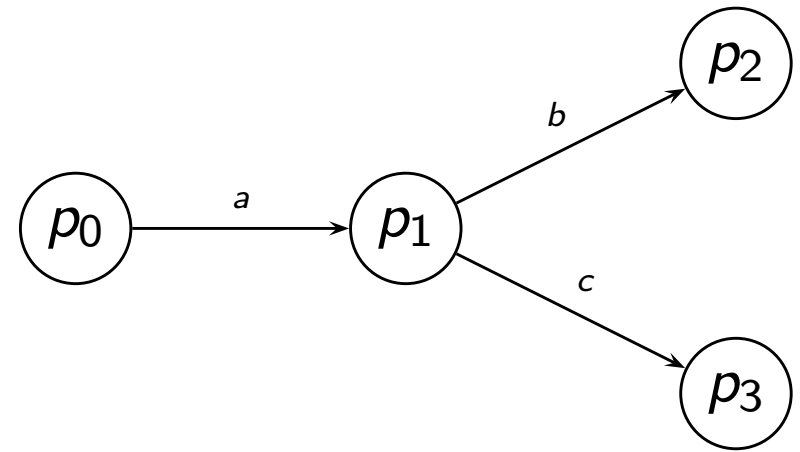
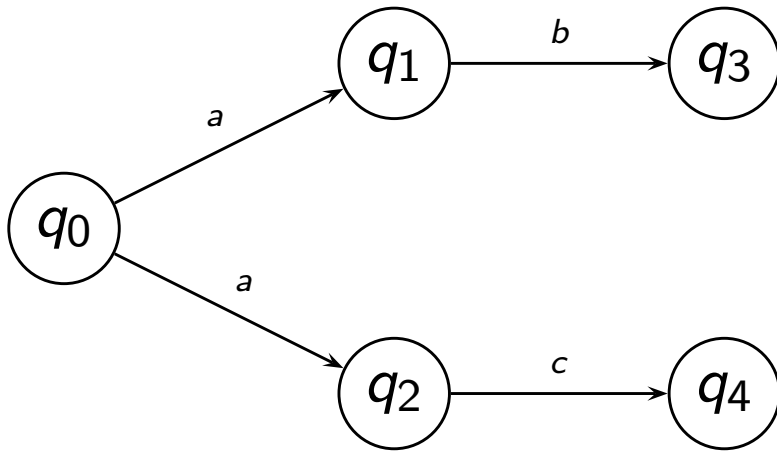
Two Systems that are not bisimilar



- States p_0 and q_0 are not strongly bisimilar.
- If they were equivalent, also states p_1 e q_1 , had to be so.
- There is no strong bisimulation R that contains $\langle p_1, q_1 \rangle$.
- The c -transition from p_1 cannot be simulated by q_1 .

How to Show Nonbisimilarity?

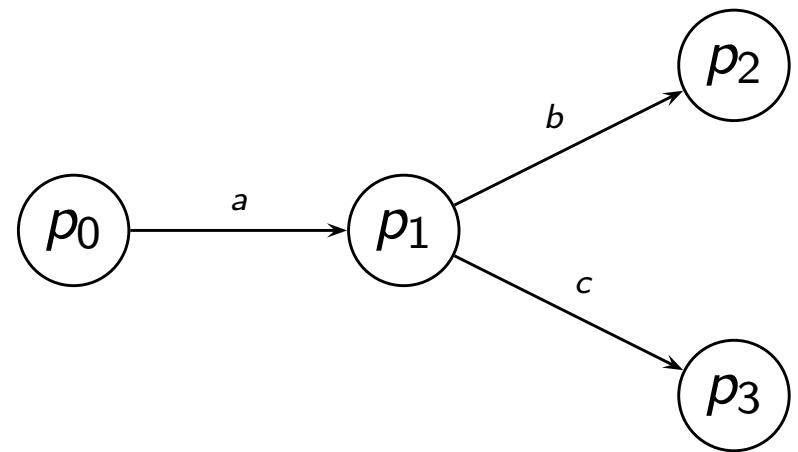
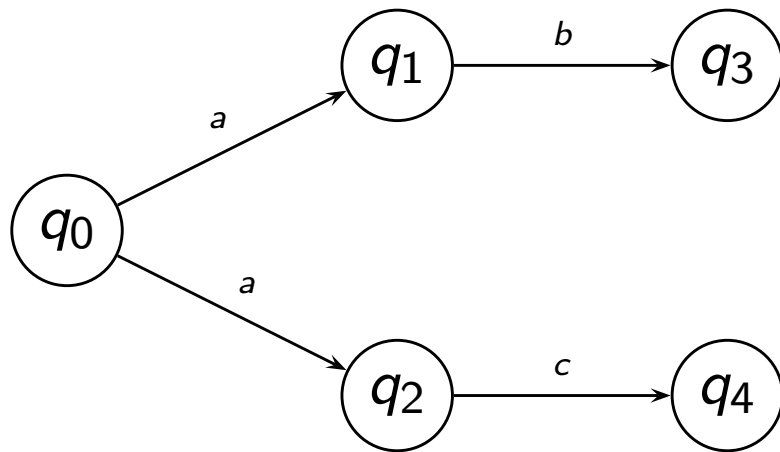
Given:



How to prove that $p_0 \not\sim q_0$:

How to Show Nonbisimilarity?

Given:

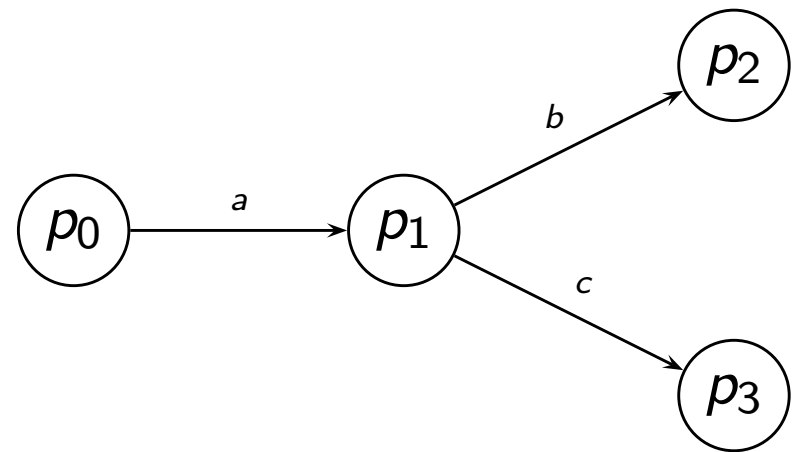
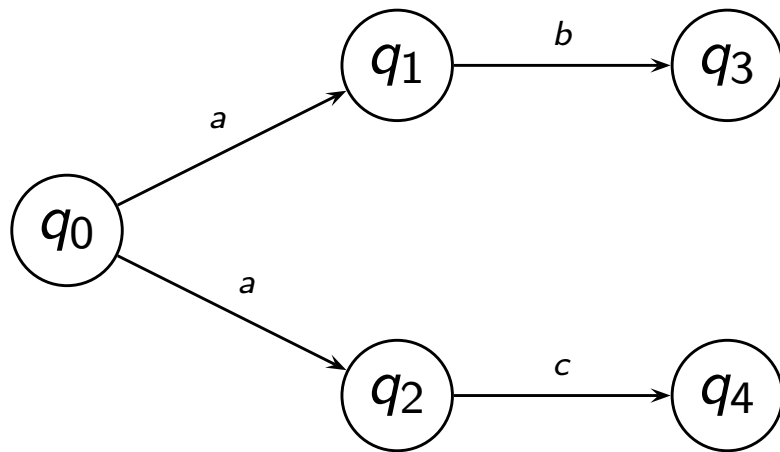


How to prove that $p_0 \not\sim q_0$:

- Enumerate **all binary relations** and show that none of them at the same time contains (s, t) and is a strong bisimulation. (Expensive: $2^{|Proc|^2}$ relations.)

How to Show Nonbisimilarity?

Given:

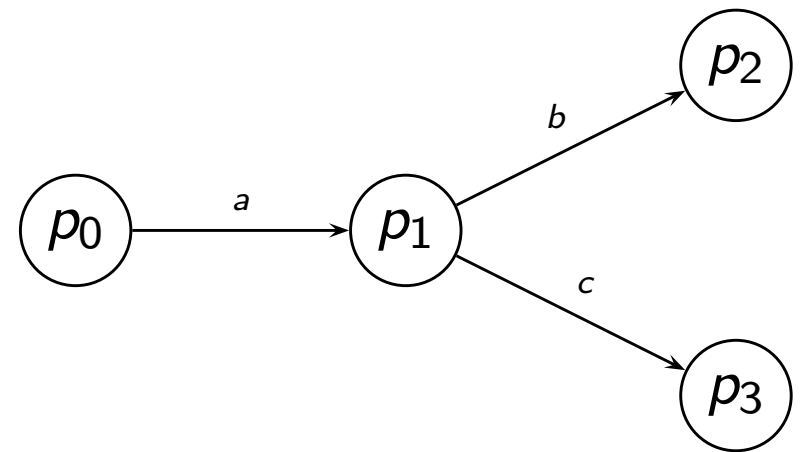
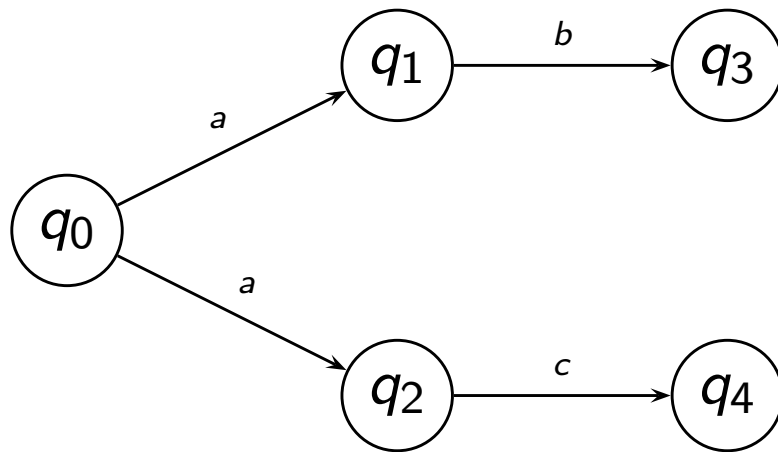


How to prove that $p_0 \not\sim q_0$:

- Enumerate **all binary relations** and show that none of them at the same time contains (s, t) and is a strong bisimulation. (Expensive: $2^{|Proc|^2}$ relations.)
- Make certain **observations** which enable us to disqualify many bisimulation candidates in one step.

How to Show Nonbisimilarity?

Given:



How to prove that $p_0 \not\sim q_0$:

- Enumerate **all binary relations** and show that none of them at the same time contains (s, t) and is a strong bisimulation. (Expensive: $2^{|Proc|^2}$ relations.)
- Make certain **observations** which enable us to disqualify many bisimulation candidates in one step.
- Use the **game characterization** of strong bisimilarity.

Strong Bisimulation Game

Let $(Proc, Act, \{\xrightarrow{a} \mid a \in Act\})$ be an LTS and $s, t \in Proc$.

We define a two-player game of an ‘attacker’ and a ‘defender’ starting from s and t .

- The game is played in **rounds**, and configurations of the game are pairs of states from $Proc \times Proc$.
- In every round exactly one configuration is called **current**. Initially the configuration (s, t) is the current one.

Strong Bisimulation Game

Let $(Proc, Act, \{\xrightarrow{a} \mid a \in Act\})$ be an LTS and $s, t \in Proc$.

We define a two-player game of an 'attacker' and a 'defender' starting from s and t .

- The game is played in **rounds**, and configurations of the game are pairs of states from $Proc \times Proc$.
- In every round exactly one configuration is called **current**. Initially the configuration (s, t) is the current one.

Intuition

The defender wants to show that s and t are strongly bisimilar while the attacker aims at proving the opposite.

Rules of the Bisimulation Games

Game Rules

In each round the players change the current configuration as follows:

- 1 the attacker chooses one of the processes in the current configuration and makes an \xrightarrow{a} -move for some $a \in Act$, and
- 2 the defender must respond by making an \xrightarrow{a} -move in the other process under the same action a .

The newly reached pair of processes becomes the current configuration. The game then continues by another round.

Rules of the Bisimulation Games

Game Rules

In each round the players change the current configuration as follows:

- 1 the attacker chooses one of the processes in the current configuration and makes an \xrightarrow{a} -move for some $a \in Act$, and
- 2 the defender must respond by making an \xrightarrow{a} -move in the other process under the same action a .

The newly reached pair of processes becomes the current configuration. The game then continues by another round.

Result of the Game

- If one player cannot move, the other player wins.
- If the game is infinite, the defender wins.

Game Characterization of Strong Bisimilarity

Theorem

- States s and t are strongly bisimilar if and only if the defender has a **universal** winning strategy starting from the configuration (s, t) .
- States s and t are not strongly bisimilar if and only if the attacker has a **universal** winning strategy starting from the configuration (s, t) .

Game Characterization of Strong Bisimilarity

Theorem

- States s and t are strongly bisimilar if and only if the defender has a **universal** winning strategy starting from the configuration (s, t) .
- States s and t are not strongly bisimilar if and only if the attacker has a **universal** winning strategy starting from the configuration (s, t) .

Remark

The bisimulation game can be used to prove both bisimilarity and nonbisimilarity of two processes. It very often provides elegant arguments for the negative case.

Simulation Relation

Strong Simulation

A relation $R \subseteq Q \times Q$ is *strong simulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, the following holds:

- for all $a \in A$ e $p' \in Q$, if $p \xrightarrow{a} p'$ then $q \xrightarrow{a} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;

Simulation Relation

Strong Simulation

A relation $R \subseteq Q \times Q$ is *strong simulation* if, for any pair of states $p \in q$ such that $\langle p, q \rangle \in R$, the following holds:

- for all $a \in A$ e $p' \in Q$, if $p \xrightarrow{a} p'$ then $q \xrightarrow{a} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;

Similarity

Two states $p, q \in Q$ are *strongly similar*, written $p \sqsubseteq q$, if there exists a strong simulation R such that $\langle p, q \rangle \in R$.

$$\sqsubseteq = \bigcup \{R \mid R \text{ is a strong simulation}\}$$

Double Similarity

Two states $p, q \in Q$ are *doubly similar*, written $p \simeq q$, if we have $p \sqsubseteq q$ and $q \sqsubseteq^{-1} p$ (i.e., $\simeq \triangleq \sqsubseteq \cap \sqsubseteq^{-1}$)

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers. Because of this we introduce three notions

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers. Because of this we introduce three notions

1 Observers

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers.

Because of this we introduce three notions

- 1 Observers
- 2 Observations

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers.

Because of this we introduce three notions

- 1 Observers
- 2 Observations
- 3 Successful Observations

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers.

Because of this we introduce three notions

- 1 Observers
- 2 Observations
- 3 Successful Observations

Those systems that satisfy (lead to successful observations) the same observers are considered equivalent.

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers.

Because of this we introduce three notions

- 1 Observers
- 2 Observations
- 3 Successful Observations

Those systems that satisfy (lead to successful observations) the same observers are considered equivalent.

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers.

Because of this we introduce three notions

- 1 Observers
- 2 Observations
- 3 Successful Observations

Those systems that satisfy (lead to successful observations) the same observers are considered equivalent.

- 1 An *observer* is an LTS having actions from $A_w \triangleq A \cup \{w\}$, with $w \notin A$;

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers.

Because of this we introduce three notions

- 1 Observers
- 2 Observations
- 3 Successful Observations

Those systems that satisfy (lead to successful observations) the same observers are considered equivalent.

- 1 An *observer* is an LTS having actions from $A_w \triangleq A \cup \{w\}$, with $w \notin A$;
- 2 To determine whether a state q satisfies an observer o the set $OBS(q, o)$ of all *computations* from $\langle q, o \rangle$ is considered

A General Observational Approach

When defining behavioural equivalences, we do not want to distinguish between systems that cannot be taken apart by external observers.

Because of this we introduce three notions

- 1 Observers
- 2 Observations
- 3 Successful Observations

Those systems that satisfy (lead to successful observations) the same observers are considered equivalent.

- 1 An *observer* is an LTS having actions from $A_w \triangleq A \cup \{w\}$, with $w \notin A$;
- 2 To determine whether a state q satisfies an observer o the set $OBS(q, o)$ of all *computations* from $\langle q, o \rangle$ is considered
- 3 A process may satisfy an observer **always** or **sometimes**.

Observations

Given two LTS $\langle Q, A, \rightarrow \rangle$ and $\langle O, A_w, \rightarrow \rangle$, and two states $q \in Q$ e $o \in O$, an *observation* c from $\langle q, o \rangle$ is a sequence of pairs $\langle q_i, o_i \rangle$, such that

- ❶ $\langle q_0, o_0 \rangle = \langle q, o \rangle$;
- ❷ the transition $\langle q_i, o_i \rangle \xrightarrow{a} \langle q_{i+1}, o_{i+1} \rangle$ can be proved using:

$$\frac{E \xrightarrow{a} E' \quad F \xrightarrow{a} F'}{\langle E, F \rangle \xrightarrow{a} \langle E', F' \rangle} \quad a \in A$$

- ❸ the last element of the sequence, say $\langle q_k, o_k \rangle$, is such that for no configuration $\langle q', o' \rangle$, with $q' \in Q$ e $o' \in O$, there exists $a \in A$ such that $\langle q_k, o_k \rangle \xrightarrow{a} \langle q', o' \rangle$ via the above rule.

Observations

Given two LTS $\langle Q, A, \rightarrow \rangle$ and $\langle O, A_w, \rightarrow \rangle$, and two states $q \in Q$ e $o \in O$, an *observation* c from $\langle q, o \rangle$ is a sequence of pairs $\langle q_i, o_i \rangle$, such that

- ❶ $\langle q_0, o_0 \rangle = \langle q, o \rangle$;
- ❷ the transition $\langle q_i, o_i \rangle \xrightarrow{a} \langle q_{i+1}, o_{i+1} \rangle$ can be proved using:

$$\frac{E \xrightarrow{a} E' \quad F \xrightarrow{a} F'}{\langle E, F \rangle \xrightarrow{a} \langle E', F' \rangle} \quad a \in A$$

- ❸ the last element of the sequence, say $\langle q_k, o_k \rangle$, is such that for no configuration $\langle q', o' \rangle$, with $q' \in Q$ e $o' \in O$, there exists $a \in A$ such that $\langle q_k, o_k \rangle \xrightarrow{a} \langle q', o' \rangle$ via the above rule.

$OBS(q, o)$ is the set of all observations from the initial configuration $\langle q, o \rangle$.

Experimentations

Successful Experiments

An observation $c \in OBS(q, o)$ is *successful* if there exists a configuration $\langle q_n, o_n \rangle \in c$, with $n \geq 0$, such that $o_n \xrightarrow{w}$.

Experimentations

Successful Experiments

An observation $c \in OBS(q, o)$ is *successful* if there exists a configuration $\langle q_n, o_n \rangle \in c$, with $n \geq 0$, such that $o_n \xrightarrow{w}$.

Satisfaction of Observers

- 1 q MAY SATISFY o if there exists an observation $c \in OBS(q, o)$ that is successful;
- 2 q MUST SATISFY o if all observations $c \in OBS(q, o)$ are successful.

May, Must and Testing Equivalences

May Equivalence

p is *may* equivalent to q , $p \simeq_m q$, if for all observers $o \in \mathcal{O}$ we have p MAY SATISFY o if and only if q MAY SATISFY o ;

May, Must and Testing Equivalences

May Equivalence

p is *may* equivalent to q , $p \simeq_m q$, if for all observers $o \in \mathcal{O}$ we have p MAY SATISFY o if and only if q MAY SATISFY o ;

Must Equivalence

p is *must* equivalent to q , $p \simeq_M q$, if for all observers $o \in \mathcal{O}$ we have p MUST SATISFY o if and only if q MUST SATISFY o .

May, Must and Testing Equivalences

May Equivalence

p is *may* equivalent to q , $p \simeq_m q$, if for all observers $o \in \mathcal{O}$ we have p MAY SATISFY o if and only if q MAY SATISFY o ;

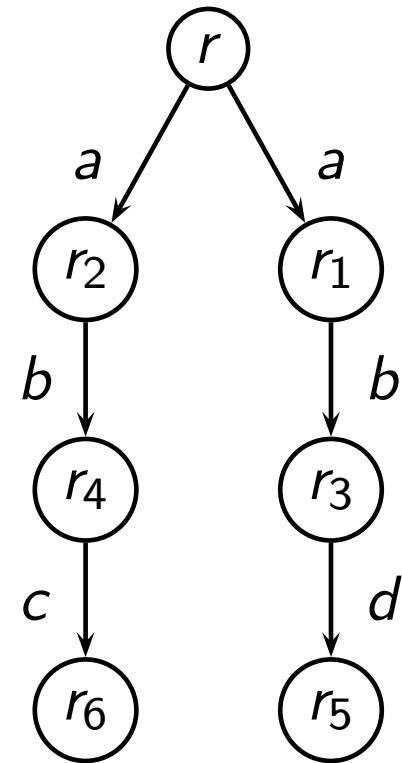
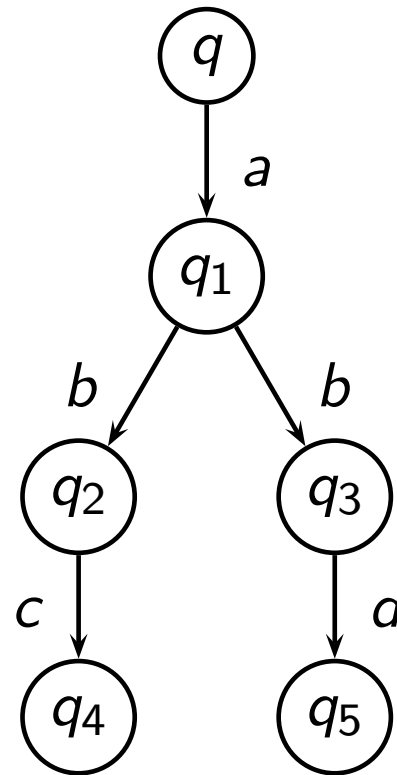
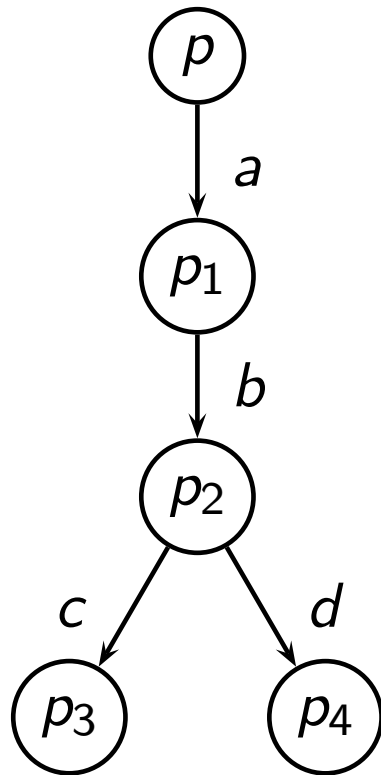
Must Equivalence

p is *must* equivalent to q , $p \simeq_M q$, if for all observers $o \in \mathcal{O}$ we have p MUST SATISFY o if and only if q MUST SATISFY o .

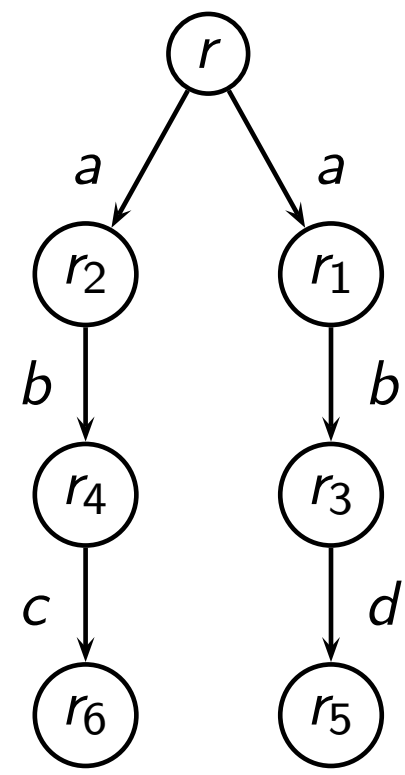
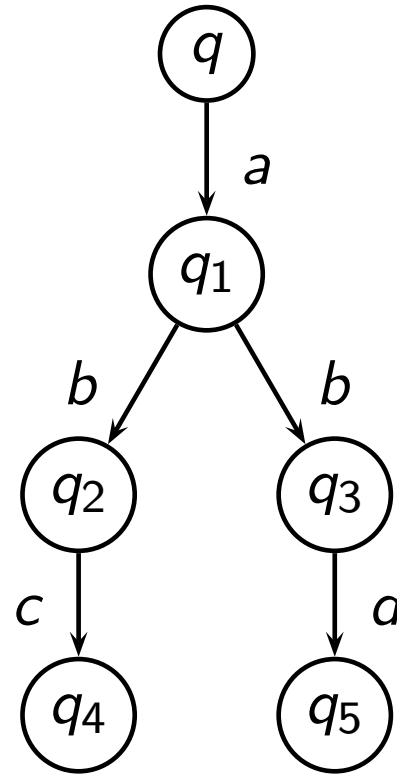
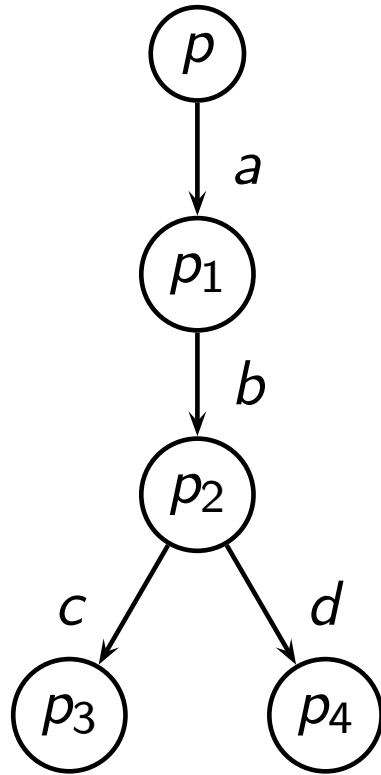
Testing Equivalence

p is *testing* equivalent to q , $p \simeq_{test} q$, if $p \simeq_m q$ and $p \simeq_M q$.

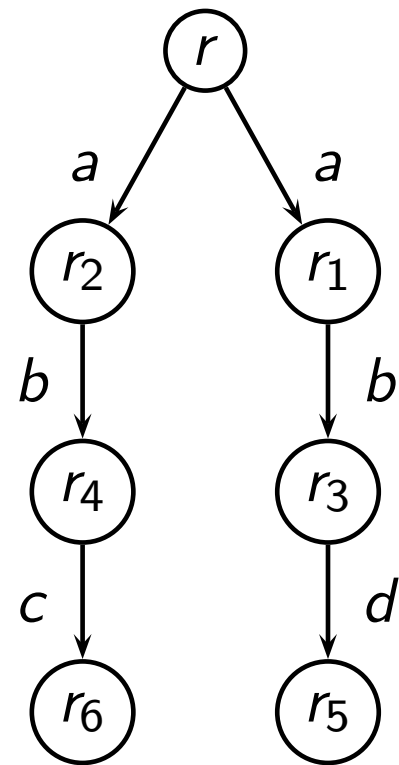
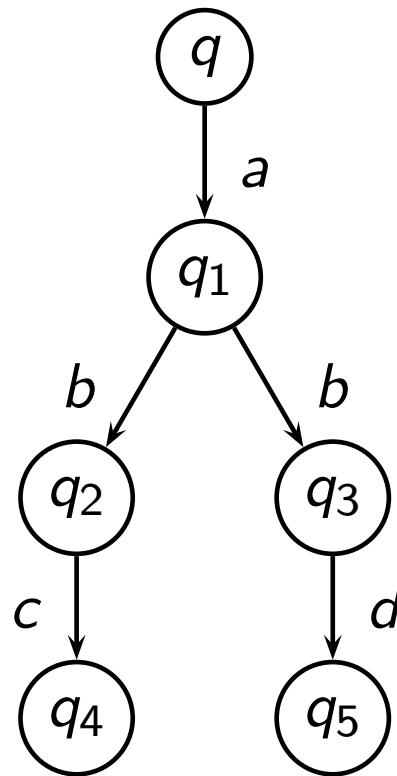
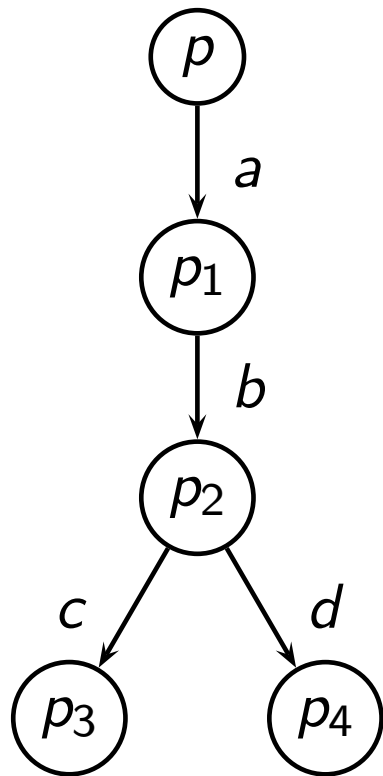
Examples for may, must and testing



Examples for may, must and testing

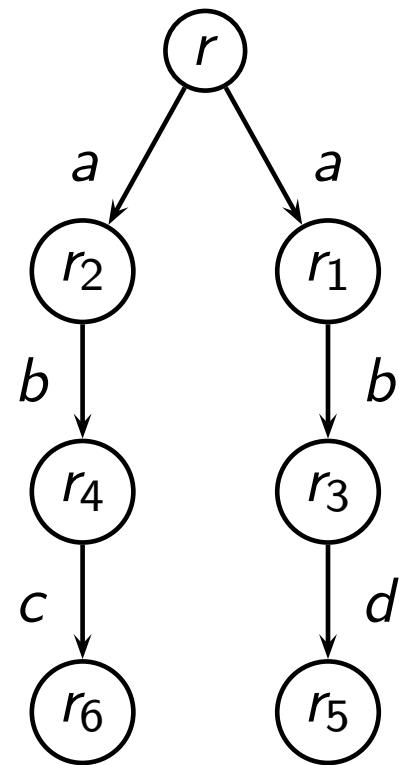
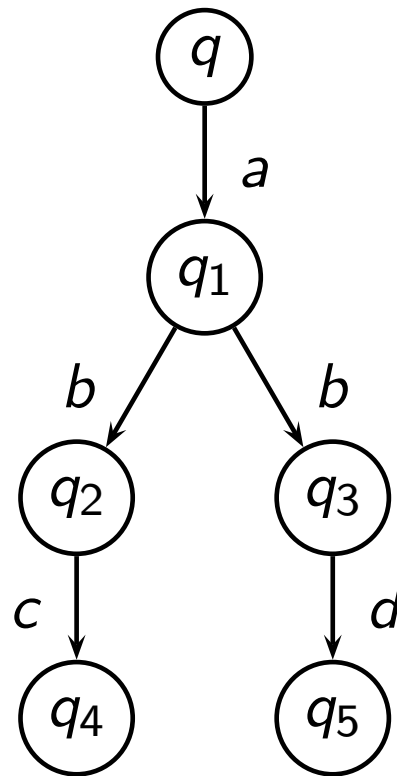
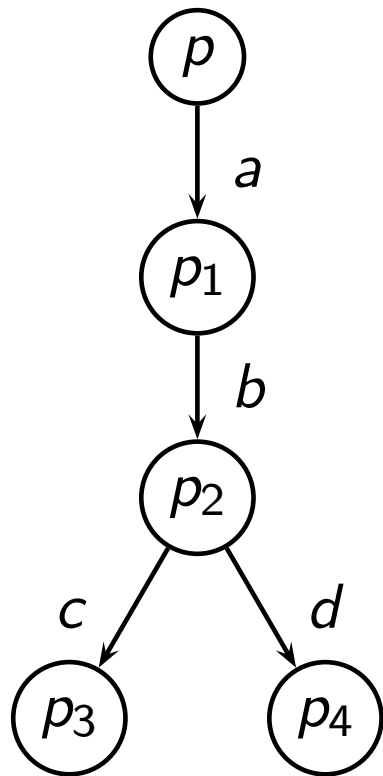


Examples for may, must and testing



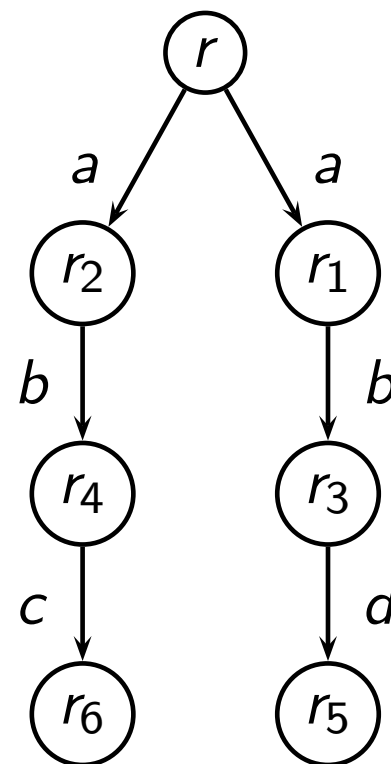
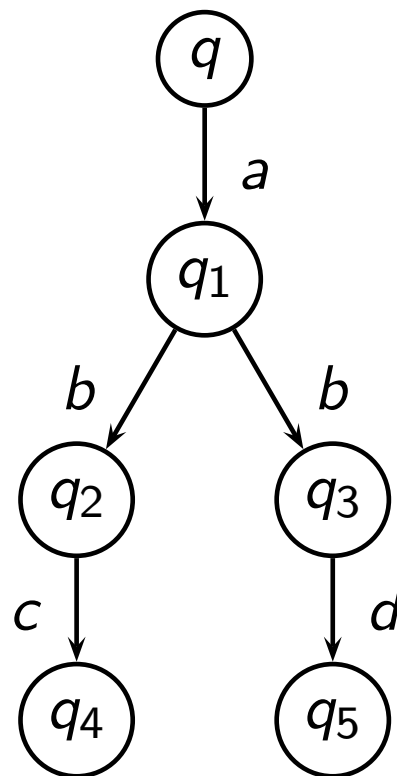
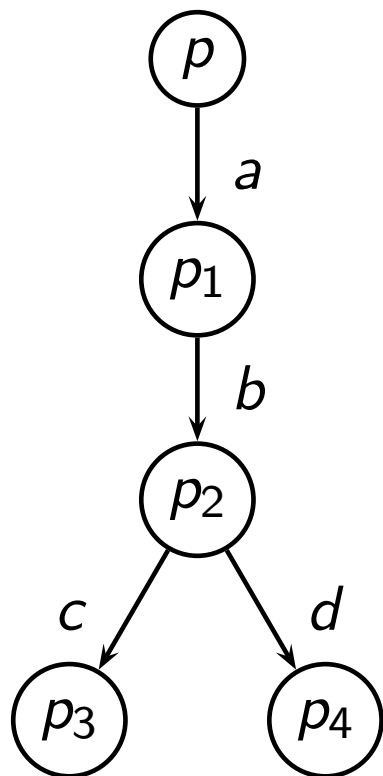
• $p \simeq_m q$

Examples for may, must and testing



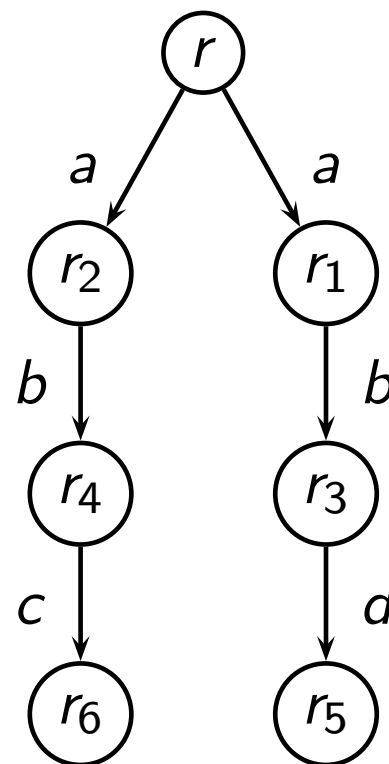
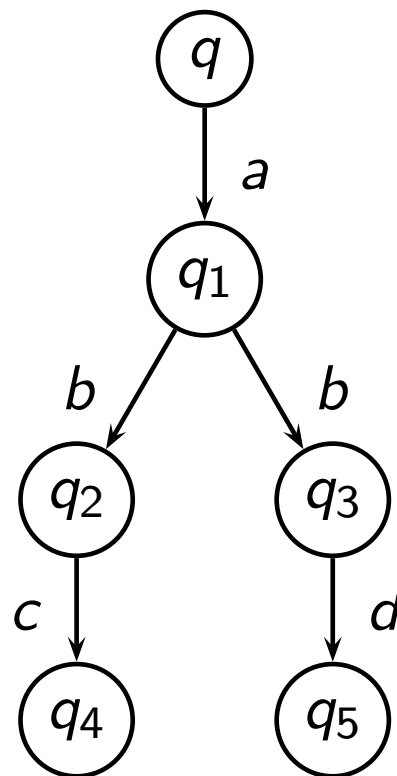
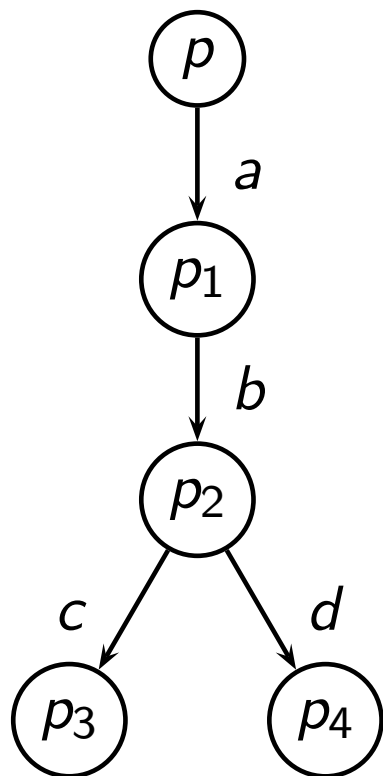
- $p \simeq_m q$
- NOT $p \simeq_M q$

Examples for may, must and testing



- $p \simeq_m q$
- NOT $p \simeq_M q$
- $q \simeq_M r$

Examples for may, must and testing

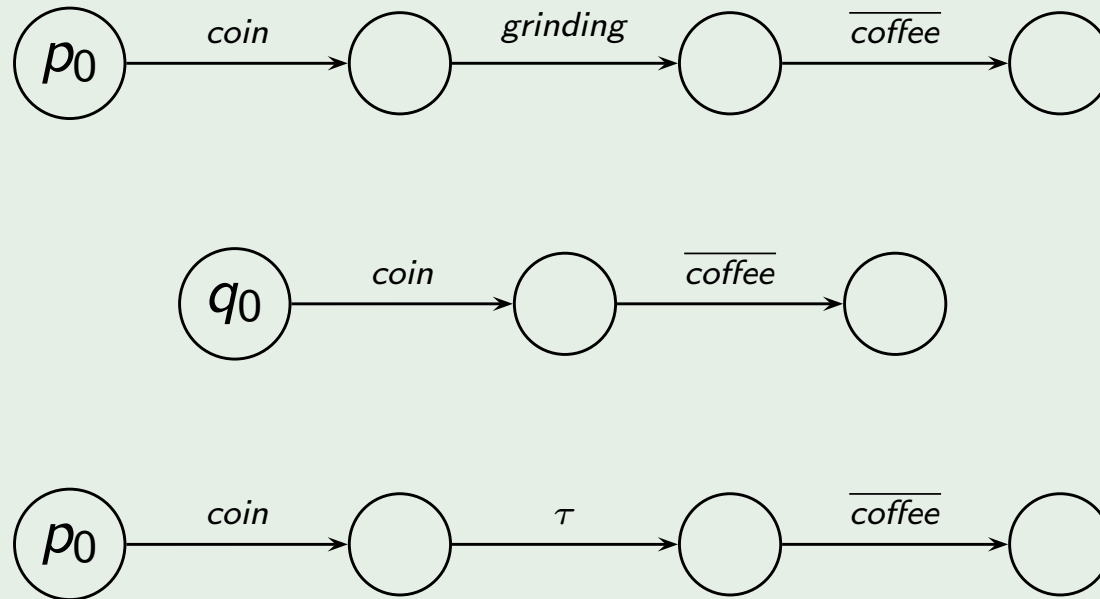


- $p \simeq_m q$
- NOT $p \simeq_M q$
- $q \simeq_M r$
- $q \simeq_{test} r$

Weak Equivalences

Is it right to consider different from a user point of view the three machine below, if

- grinding is an internal action?
- τ is an invisible action?



Weak Traces Equivalence

Let $\langle Q, A, \rightarrow \rangle$ be an LTS, with $q \in Q$ and $s \in A^*$ and

Let $q \xRightarrow{s} q'$ denote that q reduces to q' by performing the sequence s of visible actions each of which can be preceded or followed by internal actions τ .

Traces

- 1 s is a *weak trace* of q if there exists $q' \in Q$ s.t. $q \xRightarrow{s} q'$.
- 2 $L(q)$ represents the set of all weak traces of q

Weak Traces Equivalence

Let $\langle Q, A, \rightarrow \rangle$ be an LTS, with $q \in Q$ and $s \in A^*$ and

Let $q \xRightarrow{s} q'$ denote that q reduces to q' by performing the sequence s of visible actions each of which can be preceded or followed by internal actions τ .

Traces

- 1 s is a *weak trace* of q if there exists $q' \in Q$ s.t. $q \xRightarrow{s} q'$.
- 2 $L(q)$ represents the set of all weak traces of q

Traces Equivalence

Two states p e q are *trace equivalent*, written $p \approx_L q$, if $L(p) = L(p)$.

Weak Observations

To define the weak variants of may, must and testing equivalences it suffices to change experiments so that processes and observers can freely perform silent actions

Weak Observations

To define the weak variants of may, must and testing equivalences it suffices to change experiments so that processes and observers can freely perform silent actions

Given two LTS $\langle Q, A, \rightarrow \rangle$ and $\langle O, A_w, \rightarrow \rangle$, and two states $q \in Q$ e $o \in O$, a weak *experiment* c from $\langle q, o \rangle$ is a sequence of pairs $\langle q_i, o_i \rangle$, s.t.

- 1 $\langle q_0, o_0 \rangle = \langle q, o \rangle$;
- 2 the transition $\langle q_i, o_i \rangle \xrightarrow{a} \langle q_{i+1}, o_{i+1} \rangle$ can be proved using:

$$\frac{E \xrightarrow{\tau} E'}{\langle E, F \rangle \xrightarrow{\tau} \langle E', F \rangle} \quad \frac{F \xrightarrow{\tau} F'}{\langle E, F \rangle \xrightarrow{\tau} \langle E, F' \rangle} \quad \frac{E \xrightarrow{a} E' \quad F \xrightarrow{a} F'}{\langle E, F \rangle \xrightarrow{\tau} \langle E', F' \rangle} \quad a \in A$$

- 3 the last element of the sequence, say $\langle q_k, o_k \rangle$, is such that for no configuration $\langle q', o' \rangle$, with $q' \in Q$ e $o' \in O$, there exists $a \in A$ such that $\langle q_k, o_k \rangle \xrightarrow{a} \langle q', o' \rangle$ via the above rule.

Weak Bisimulation Relation: An immediate generalization

Weak Bisimulation

A relation $R \subseteq Q \times Q$ is *weak bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, for any $s \in A^*$, the following holds:

- 1 for all $a \in A$ e $p' \in Q$, if $p \xRightarrow{s} p'$ then $q \xRightarrow{s} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;
- 2 for all $a \in A$ e $q' \in Q$, if $q \xRightarrow{s} q'$ then $p \xRightarrow{s} p'$ for some $p' \in Q$ such that $\langle p', q' \rangle \in R$.

Weak Bisimulation Relation: An immediate generalization

Weak Bisimulation

A relation $R \subseteq Q \times Q$ is *weak bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, for any $s \in A^*$, the following holds:

- 1 for all $a \in A$ e $p' \in Q$, if $p \xRightarrow{s} p'$ then $q \xRightarrow{s} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;
- 2 for all $a \in A$ e $q' \in Q$, if $q \xRightarrow{s} q'$ then $p \xRightarrow{s} p'$ for some $p' \in Q$ such that $\langle p', q' \rangle \in R$.

Weak Bisimilarity

Two states $p, q \in Q$ of an LTS $\langle Q, A_\tau, \rightarrow \rangle$ are *weakly bisimilar*, written $p \approx q$, if there exists a weak bisimulation R such that $\langle p, q \rangle \in R$.

Weak Bisimulation Relation: A simpler definition

Weak Bisimulation

A relation $R \subseteq Q \times Q$ is *weak bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, the following holds:

- 1 for all $a \in A$ e $p' \in Q$, if $p \xrightarrow{\mu} p'$ then $q \xRightarrow{\hat{\mu}} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;
- 2 for all $a \in A$ e $q' \in Q$, if $q \xrightarrow{\mu} q'$ then $p \xRightarrow{\hat{\mu}} p'$ for some $p' \in Q$ such that $\langle p', q' \rangle \in R$.

Weak Bisimulation Relation: A simpler definition

Weak Bisimulation

A relation $R \subseteq Q \times Q$ is *weak bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, the following holds:

- 1 for all $a \in A$ e $p' \in Q$, if $p \xrightarrow{\mu} p'$ then $q \xRightarrow{\hat{\mu}} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;
- 2 for all $a \in A$ e $q' \in Q$, if $q \xrightarrow{\mu} q'$ then $p \xRightarrow{\hat{\mu}} p'$ for some $p' \in Q$ such that $\langle p', q' \rangle \in R$.

where

$$\hat{\mu} = \begin{cases} \epsilon & \text{se } \mu = \tau \\ \mu & \text{se } \mu \neq \tau \end{cases}$$

Weak Bisimulation Relation: A simpler definition

Weak Bisimulation

A relation $R \subseteq Q \times Q$ is *weak bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, the following holds:

- 1 for all $a \in A$ e $p' \in Q$, if $p \xrightarrow{\mu} p'$ then $q \xRightarrow{\hat{\mu}} q'$ for some $q' \in Q$ such that $\langle p', q' \rangle \in R$;
- 2 for all $a \in A$ e $q' \in Q$, if $q \xrightarrow{\mu} q'$ then $p \xRightarrow{\hat{\mu}} p'$ for some $p' \in Q$ such that $\langle p', q' \rangle \in R$.

where

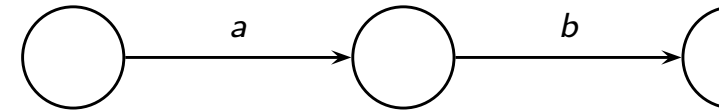
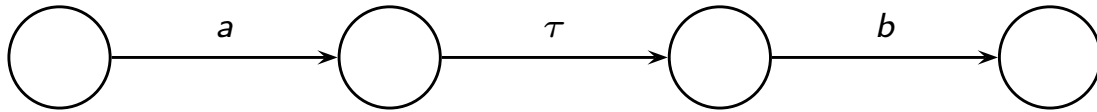
$$\hat{\mu} = \begin{cases} \epsilon & \text{se } \mu = \tau \\ \mu & \text{se } \mu \neq \tau \end{cases}$$

Weak Bisimilarity

Two states $p, q \in Q$ of an LTS $\langle Q, A_\tau, \rightarrow \rangle$ are *weakly bisimilar*, written $p \approx q$, if there exists a weak bisimulation R such that $\langle p, q \rangle \in R$.

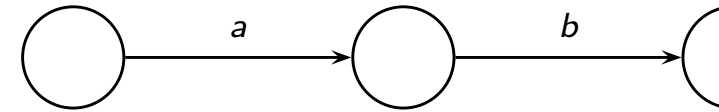
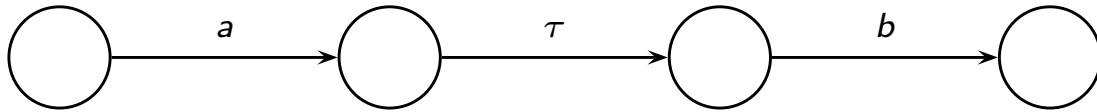
Two Pairs of Weakly Bisimilar Systems

Ignoring Tau's

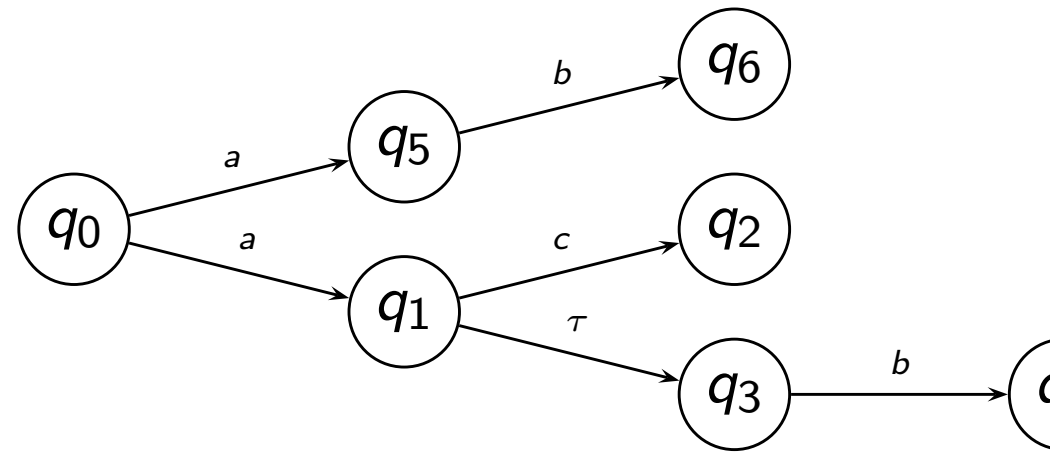
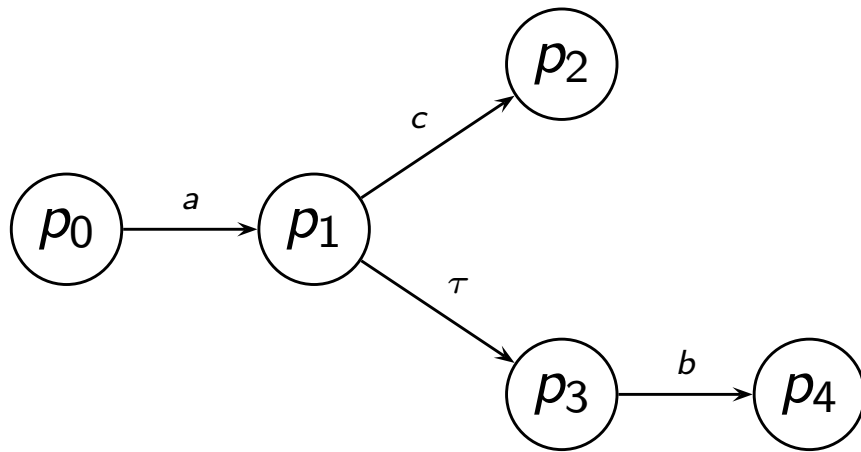


Two Pairs of Weakly Bisimilar Systems

Ignoring Tau's



Ignoring Tau's and Branching



An Alternative to Weak Bisimulation

Branching Bisimulation

A **symmetric** relation $R \subseteq Q \times Q$ is *weak bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, if $p \xrightarrow{\mu} p'$, with $\mu \in A_\tau$ and $p' \in Q$, at least one of the following conditions holds:

- ❶ $\mu = \tau$ e $\langle p', q \rangle \in R$
- ❷ $q \Rightarrow q'' \xrightarrow{\mu} q'$ per qualche $q', q'' \in Q$ tali che $\langle p, q'' \rangle \in R$ e $\langle p', q' \rangle \in R$.

An Alternative to Weak Bisimulation

Branching Bisimulation

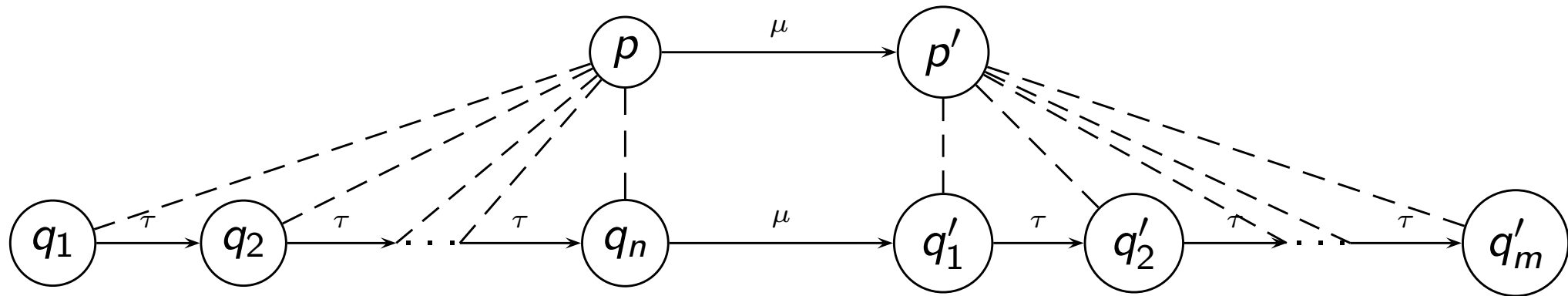
A **symmetric** relation $R \subseteq Q \times Q$ is *weak bisimulation* if, for any pair of states p e q such that $\langle p, q \rangle \in R$, if $p \xrightarrow{\mu} p'$, with $\mu \in A_\tau$ and $p' \in Q$, at least one of the following conditions holds:

- ❶ $\mu = \tau$ e $\langle p', q \rangle \in R$
- ❷ $q \Rightarrow q'' \xrightarrow{\mu} q'$ per qualche $q', q'' \in Q$ tali che $\langle p, q'' \rangle \in R$ e $\langle p', q' \rangle \in R$.

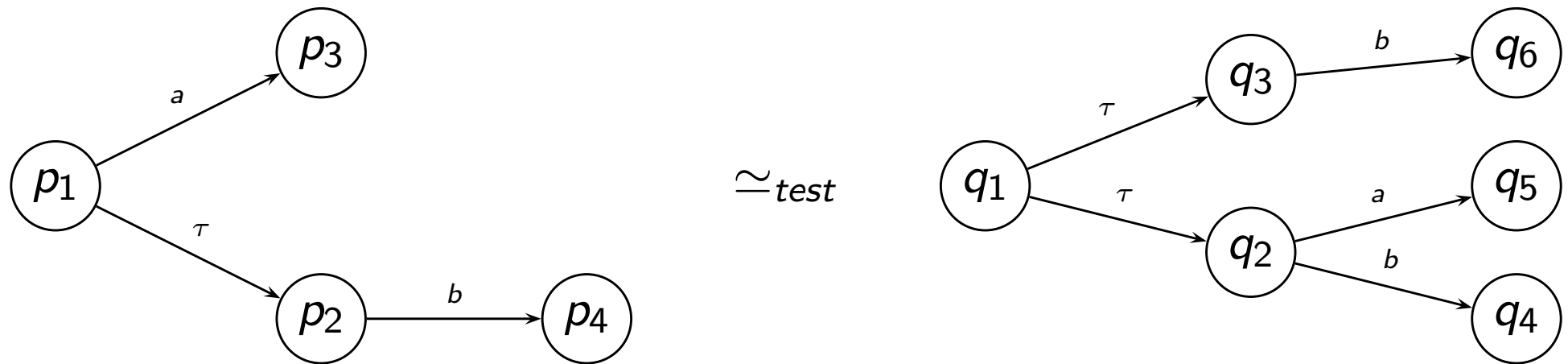
Branching Bisimilarity

Two states $p, q \in Q$ of an LTS $\langle Q, A_\tau, \rightarrow \rangle$ are *Branching bisimilar*, written $p \approx_b q$, if there exists a branching bisimulation R such that $\langle p, q \rangle \in R$.

Branching Bisimulation, ... pictorially

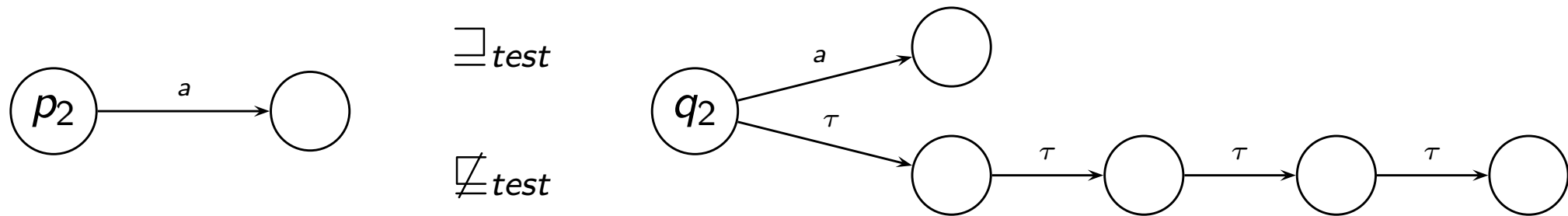


Testing vs Bisimulation - 1



The systems above are weakly testing equivalent but NOT weakly (nor branching) bisimilar

Testing vs Bisimulation - 2



The systems above are NOT testing equivalent but are weakly (and branching) bisimilar

Equivalences Hierarchies

For strongly convergent systems we have:

