



Data Assimilation Studies

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4DVAR

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Original formulation

$$J(\mathbf{x}_0) = \frac{1}{2}(\mathbf{x}_0 - \mathbf{x}_0^b)^T \mathbf{B}^{-1}(\mathbf{x}_0 - \mathbf{x}_0^b) + \sum_t \frac{1}{2} [\mathbf{H}(\underline{M(\mathbf{x}_0)}) - \mathbf{y}_t^o]^T \mathbf{R}^{-1} [\mathbf{H}(\underline{M(\mathbf{x}_0)}) - \mathbf{y}_t^o]$$
$$\nabla J(\mathbf{x}_0) = \mathbf{B}^{-1}(\mathbf{x}_0 - \mathbf{x}_0^b) + \sum_{t=1}^T \underline{\mathbf{M}_0^T \cdots \mathbf{M}_{t-1}^T} \mathbf{H}^T \mathbf{R}_t^{-1} [\mathbf{H}(\underline{M(\mathbf{x}_0)}) - \mathbf{y}_t^o]$$

Nonlinear model

Tangent liner model

Increment formulation

$$\delta \mathbf{x} = \mathbf{x}_0 - \mathbf{x}_0^b$$
$$\mathbf{H}(M(\mathbf{x}_0)) - \mathbf{y}_t^o \approx \mathbf{H} \mathbf{M}_{t-1} \cdots \mathbf{M}_0 \delta \mathbf{x} - \mathbf{d}$$
$$\mathbf{d} = \mathbf{y}_t^o - \mathbf{H}(M(\mathbf{x}_0^b))$$

$$J(\delta \mathbf{x}) = \frac{1}{2}(\delta \mathbf{x})^T \mathbf{B}^{-1}(\delta \mathbf{x}) + \sum_t \frac{1}{2} [\underline{\mathbf{H} \mathbf{M}_{t-1} \cdots \mathbf{M}_0 \delta \mathbf{x} - \mathbf{d}}]^T \mathbf{R}^{-1} [\underline{\mathbf{H} \mathbf{M}_{t-1} \cdots \mathbf{M}_0 \delta \mathbf{x} - \mathbf{d}}]$$
$$\nabla J(\delta \mathbf{x}) = \mathbf{B}^{-1}(\delta \mathbf{x}) + \sum_{t=1}^T \underline{\mathbf{M}_0^T \cdots \mathbf{M}_{t-1}^T} \mathbf{H}^T \mathbf{R}_t^{-1} [\underline{\mathbf{H} \mathbf{M}_{t-1} \cdots \mathbf{M}_0 \delta \mathbf{x} - \mathbf{d}}]$$

comparison

