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In[4]:= (* baseline = 0.202 -- radius of circle on which hydrophones lie
        SoS = 1550 -- speed of sound*)

In[5]:= HydrophonePositions := {{baseline, 0}, {baseline, 0}.RotationMatrix[-2 Pi / 3],
        {baseline, 0}.RotationMatrix[-4 Pi / 3]}; HydrophonePositions // MatrixForm

Out[5]//MatrixForm=

$$\begin{pmatrix} \text{baseline} & 0 \\ -\frac{\text{baseline}}{2} & \frac{\sqrt{3} \text{baseline}}{2} \\ -\frac{\text{baseline}}{2} & -\frac{\sqrt{3} \text{baseline}}{2} \end{pmatrix}$$


In[6]:= RotatedPositions := HydrophonePositions . RotationMatrix[θ]; RotatedPositions // MatrixForm

Out[6]//MatrixForm=

$$\begin{pmatrix} \text{baseline} \cos[\theta] & -\text{baseline} \sin[\theta] \\ -\frac{1}{2} \text{baseline} \cos[\theta] + \frac{1}{2} \sqrt{3} \text{baseline} \sin[\theta] & \frac{1}{2} \sqrt{3} \text{baseline} \cos[\theta] + \frac{1}{2} \text{baseline} \sin[\theta] \\ -\frac{1}{2} \text{baseline} \cos[\theta] - \frac{1}{2} \sqrt{3} \text{baseline} \sin[\theta] & -\frac{1}{2} \sqrt{3} \text{baseline} \cos[\theta] + \frac{1}{2} \text{baseline} \sin[\theta] \end{pmatrix}$$


In[7]:= EstimatedDelays := RotatedPositions[[All, 2]] * Cos[φ] / SoS;
        EstimatedDelays * SoS // MatrixForm

Out[7]//MatrixForm=

$$\begin{pmatrix} -\text{baseline} \cos[\phi] \sin[\theta] \\ \cos[\phi] \left( \frac{1}{2} \sqrt{3} \text{baseline} \cos[\theta] + \frac{1}{2} \text{baseline} \sin[\theta] \right) \\ \cos[\phi] \left( -\frac{1}{2} \sqrt{3} \text{baseline} \cos[\theta] + \frac{1}{2} \text{baseline} \sin[\theta] \right) \end{pmatrix}$$


In[8]:= EstimatedLags :=
        FullSimplify[{EstimatedDelays[[1]] - EstimatedDelays[[2]], EstimatedDelays[[1]] -
        EstimatedDelays[[3]], EstimatedDelays[[2]] - EstimatedDelays[[3]]}];
        EstimatedLags / (baseline * Cos[φ] / SoS) // MatrixForm (* note manual factorization *)

Out[8]//MatrixForm=

$$\begin{pmatrix} \frac{1}{2} (-\sqrt{3} \cos[\theta] - 3 \sin[\theta]) \\ \frac{1}{2} (\sqrt{3} \cos[\theta] - 3 \sin[\theta]) \\ \sqrt{3} \cos[\theta] \end{pmatrix}$$


In[9]:= soln := Solve[{EstimatedLags[[1]] == m1,
        EstimatedLags[[2]] == m2, EstimatedLags[[3]] == m3}, {θ, φ}]; soln

Out[9]= {}

In[10]:= (* FAIL *)

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In[11]:= (* Aaannnnndddd... try another approach: conjugate gradient on sum-of-squared error *)

MSE := (m1 - EstimatedLags[[1]] * 10^6)^2 +
        (m2 - EstimatedLags[[2]] * 10^6)^2 + (m3 - EstimatedLags[[3]] * 10^6)^2; MSE

Out[11]=

$$\left( m3 - \frac{1\,000\,000 \sqrt{3} \text{baseline} \cos[\theta] \cos[\phi]}{\text{SoS}} \right)^2 +$$


$$\left( m2 - \frac{500\,000 \text{baseline} \cos[\phi] (\sqrt{3} \cos[\theta] - 3 \sin[\theta])}{\text{SoS}} \right)^2 +$$


$$\left( m1 + \frac{500\,000 \text{baseline} \cos[\phi] (\sqrt{3} \cos[\theta] + 3 \sin[\theta])}{\text{SoS}} \right)^2$$


In[12]:= subst := { Sqrt[3] (m1 - m2 - 2 m3) SoS → y, 3 (m1 + m2) SoS → z};

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In[13]:= dEdθφ := FullSimplify[D[MSE, {{θ, φ}}]];
tmp := FullSimplify[dEdθφ / (baseline * 10^6)] //. subst; tmp
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$$\text{Out[13]} = \left\{ \frac{\cos[\phi] \left(3 (m_1 + m_2) \cos[\theta] + \sqrt{3} (-m_1 + m_2 + 2 m_3) \sin[\theta] \right)}{\text{SoS}}, \right. \\ \left. - \frac{(y \cos[\theta] + 9000000 \text{baseline} \cos[\phi] + z \sin[\theta]) \sin[\phi]}{\text{SoS}^2} \right\}$$

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In[14]:= FullSimplify[Numerator[tmp[[1]]] == ((1 / SoS * Cos[φ] * (z Cos[θ] - y Sin[θ])) /.
{y -> √3 (m1 - m2 - 2 m3) SoS, z -> 3 (m1 + m2) SoS})] ]
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Out[14]= True
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In[15]:= (* Measured Lags {m1, m2, m3} correspond to θ→6° and φ→26° *)
Plot3D[
Evaluate[MSE /. {m1 -> -114.58, m2 -> 84.63, m3 -> 199.22, baseline -> 0.202, SoS -> 1550}],
{θ, 0°, 12°}, {φ, 20°, 32°}];
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In[16]:= (* Plot derivatives *)
Plot3D[Evaluate[dEdθφ[[1]] /. {m1 -> -114.58, m2 -> 84.63, m3 -> 199.22,
baseline -> 0.202, SoS -> 1550}], {θ, 0°, 360°}, {φ, 0°, 89°}];
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In[17]:= Plot3D[Evaluate[
dEdθφ[[2]] /. {m1 -> -114.58, m2 -> 84.63, m3 -> 199.22, baseline -> 0.202, SoS -> 1550}],
{θ, 0°, 360°}, {φ, 0°, 89°}];
```

```
In[18]:= Reduce[dEdθφ[[1]] == 0, θ]
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$$\text{Out[18]} = \left(m_2 == -m_1 \ \&\& \left(\left(\frac{-\pi + \theta}{2\pi} \notin \text{Integers} \ \&\& \text{SoS} \neq 0 \ \&\& m_3 == m_1 \right) \mid \mid \right. \right. \\ \left. \left. \left(C[1] \in \text{Integers} \ \&\& m_1 - m_3 \neq 0 \ \&\& \text{SoS} \neq 0 \ \&\& \theta == 2\pi C[1] \right) \right) \mid \mid \right. \\ \left. \left(\text{SoS} \neq 0 \ \&\& (\text{baseline} == 0 \mid \mid \cos[\phi] == 0) \right) \mid \mid \right. \\ \left. \left(m_1 + m_2 \neq 0 \ \&\& C[1] \in \text{Integers} \ \&\& \left(\left(\left(2m_1^2 + 2m_1m_2 + 2m_2^2 - 2m_1m_3 + 2m_2m_3 + 2m_3^2 + \right. \right. \right. \right. \right. \\ \left. \left. \left. m_1 \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2} - m_2 \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2} - \right. \right. \right. \\ \left. \left. \left. 2m_3 \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2} \right) \text{SoS} \neq 0 \ \&\& \right. \right. \right. \\ \left. \left. \left. \theta == 2 \text{ArcTan} \left[\frac{-\sqrt{3} m_1 + \sqrt{3} m_2 + 2\sqrt{3} m_3 - 2\sqrt{3} \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2}}{3(m_1 + m_2)} \right] + \right. \right. \right. \\ \left. \left. \left. 2\pi C[1] \right) \mid \mid \left(\left(-2m_1^2 - 2m_1m_2 - 2m_2^2 + 2m_1m_3 - 2m_2m_3 - 2m_3^2 + \right. \right. \right. \right. \right. \\ \left. \left. \left. m_1 \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2} - m_2 \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2} - \right. \right. \right. \\ \left. \left. \left. 2m_3 \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2} \right) \text{SoS} \neq 0 \ \&\& \right. \right. \right. \\ \left. \left. \left. \theta == 2 \text{ArcTan} \left[\frac{-\sqrt{3} m_1 + \sqrt{3} m_2 + 2\sqrt{3} m_3 + 2\sqrt{3} \sqrt{m_1^2 + m_1m_2 + m_2^2 - m_1m_3 + m_2m_3 + m_3^2}}{3(m_1 + m_2)} \right] + \right. \right. \right. \\ \left. \left. \left. 2\pi C[1] \right) \right) \mid \mid \right) \\ \left(C[1] \in \text{Integers} \ \&\& \text{SoS} \neq 0 \ \&\& m_2 == -m_1 \ \&\& \theta == \pi (1 + 2C[1]) \right)$$

$$\text{In[19]:= my}\theta = 2 \operatorname{ArcTan}\left[\frac{-\sqrt{3} m_1 + \sqrt{3} m_2 + 2 \sqrt{3} m_3 \pm 2 \sqrt{3} \sqrt{m_1^2 + m_1 m_2 + m_2^2 - m_1 m_3 + m_2 m_3 + m_3^2}}{3 (m_1 + m_2)}\right]$$

$$\text{Out[19]= } 2 \operatorname{ArcTan}\left[\frac{-\sqrt{3} m_1 + \sqrt{3} m_2 + \left(2 \sqrt{3} m_3 \pm 2 \sqrt{3} \sqrt{m_1^2 + m_1 m_2 + m_2^2 - m_1 m_3 + m_2 m_3 + m_3^2}\right)}{3 (m_1 + m_2)}\right]$$

$$\text{In[20]:= Reduce[dEd}\phi[[2]] = 0, \phi]$$

$$\begin{aligned} \text{Out[20]= } & \left(C[1] \in \text{Integers} \& \right. \\ & \left(\left(\text{baseline} \neq 0 \& \& \text{SoS} \neq 0 \& \left(\phi = -\operatorname{ArcCos}\left[\frac{1}{9\,000\,000 \text{ baseline}} \left(-\sqrt{3} m_1 \operatorname{SoS} \cos[\theta] + \sqrt{3} m_2 \operatorname{SoS} \right. \right. \right. \right. \right. \\ & \quad \left. \left. \left. \cos[\theta] + 2 \sqrt{3} m_3 \operatorname{SoS} \cos[\theta] - 3 m_1 \operatorname{SoS} \sin[\theta] - 3 m_2 \operatorname{SoS} \sin[\theta] \right) \right] + 2 \pi C[1] \mid \mid \right. \right. \\ & \quad \left. \phi = \operatorname{ArcCos}\left[\frac{1}{9\,000\,000 \text{ baseline}} \left(-\sqrt{3} m_1 \operatorname{SoS} \cos[\theta] + \sqrt{3} m_2 \operatorname{SoS} \cos[\theta] + \right. \right. \right. \\ & \quad \left. \left. \left. 2 \sqrt{3} m_3 \operatorname{SoS} \cos[\theta] - 3 m_1 \operatorname{SoS} \sin[\theta] - 3 m_2 \operatorname{SoS} \sin[\theta] \right) \right] + 2 \pi C[1] \right) \mid \mid \\ & \left. \left(\text{SoS} \neq 0 \& \& (\phi = 2 \pi C[1] \mid \mid \phi = \pi + 2 \pi C[1]) \right) \right) \mid \mid \left(\text{baseline} = 0 \& \& \right. \\ & \left(m_2 = -m_1 \& \& ((\text{SoS} \neq 0 \& \& m_3 = m_1) \mid \mid (m_1 - m_3 \neq 0 \& \& \text{SoS} \neq 0 \& \& \cos[\theta] = 0)) \right) \mid \mid \\ & \left. \left(m_1 + m_2 \neq 0 \& \& \text{SoS} \neq 0 \& \& \sin[\theta] = \frac{-\sqrt{3} m_1 \cos[\theta] + \sqrt{3} m_2 \cos[\theta] + 2 \sqrt{3} m_3 \cos[\theta]}{3 (m_1 + m_2)} \right) \right) \mid \mid \\ & \left. (\text{SoS} \neq 0 \& \& \text{baseline} = 0) \right) \end{aligned}$$

$$\text{In[21]:= my}\phi = \text{FullSimplify}\left[\operatorname{ArcCos}\left[\frac{1}{9\,000\,000 \text{ baseline}} \left(-\sqrt{3} m_1 \operatorname{SoS} \cos[\theta] + \sqrt{3} m_2 \operatorname{SoS} \cos[\theta] + 2 \sqrt{3} m_3 \operatorname{SoS} \cos[\theta] - 3 m_1 \operatorname{SoS} \sin[\theta] - 3 m_2 \operatorname{SoS} \sin[\theta] \right) \right]\right]$$

$$\text{Out[21]= } \operatorname{ArcCos}\left[-\frac{\operatorname{SoS} \left(\sqrt{3} (m_1 - m_2 - 2 m_3) \cos[\theta] + 3 (m_1 + m_2) \sin[\theta] \right)}{9\,000\,000 \text{ baseline}}\right]$$