

O Método de Newton para sistemas não-lineares e otimização, e comentários sobre a convergência

Seminários Poincarè

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20 de Novembro de 2015

1 Zeros de Funções

- Introdução
- Aproximação Linear
- Método de Newton

2 Equações não-lineares

- Introdução
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3 Otimização

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4 Convergência

- Uma dimensão
- Duas dimensões
- Exemplo Tradicional

5 Referências

Zeros de uma função real

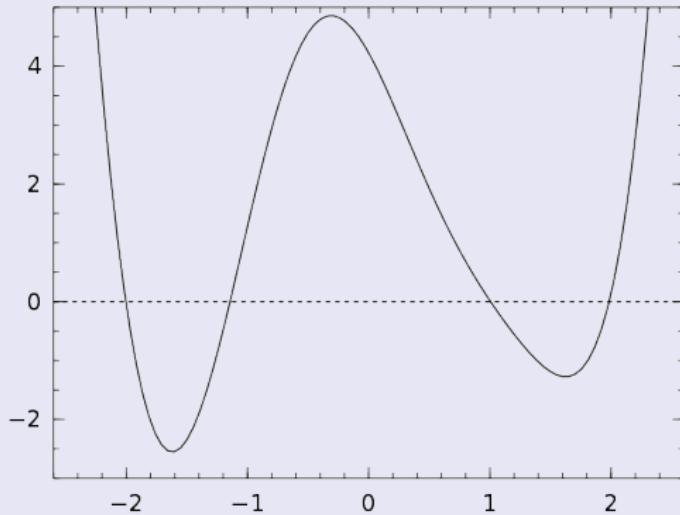
$$f(x) = 0, \quad f : \mathbb{R} \rightarrow \mathbb{R}$$

Zeros de uma função real

$$f(x) = (x^2 - 1)(x^2 - 4) + \sin(3x - 3)$$

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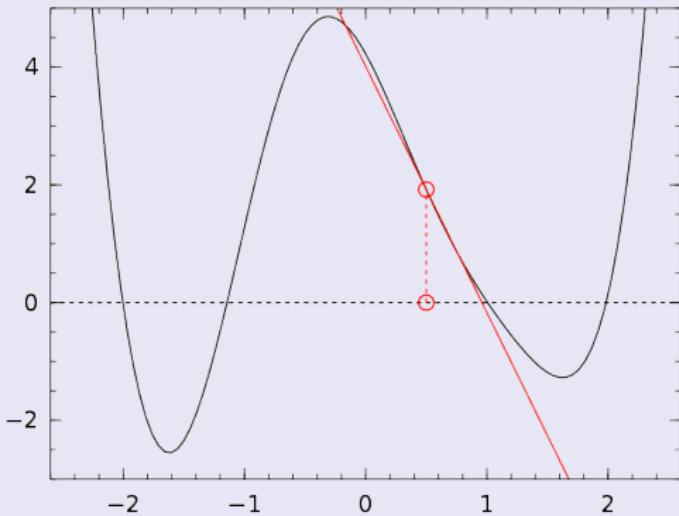


Aproximação linear

$$f(x) = f(a) + f'(a)(x - a) + E(x)$$

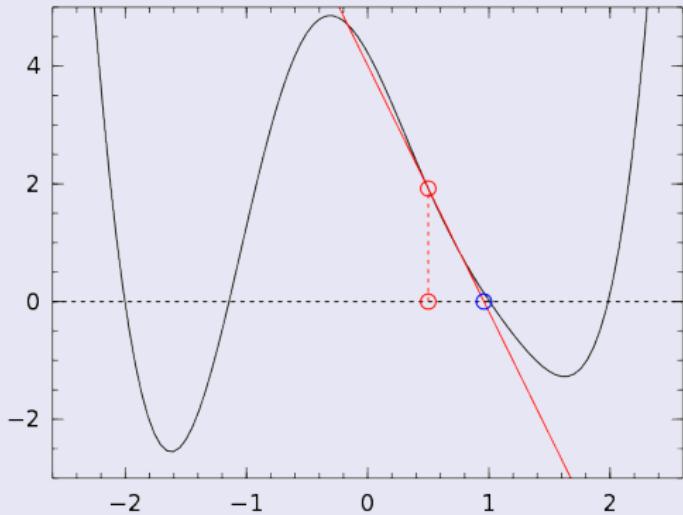
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O zero da função afim

$$L(x) = f(a) + f'(a)(x - a) = 0$$

O zero da função afim

$$L(x) = f(a) + f'(a)(x - a) = 0$$

$$x = a - \frac{f(a)}{f'(a)}, \quad f'(a) \neq 0$$

Método de Newton

Dado x^0 , defina a sequência

$$x^{k+1} = x^k - \frac{f(x^k)}{f'(x^k)}$$

se $f'(x^k) \neq 0$.

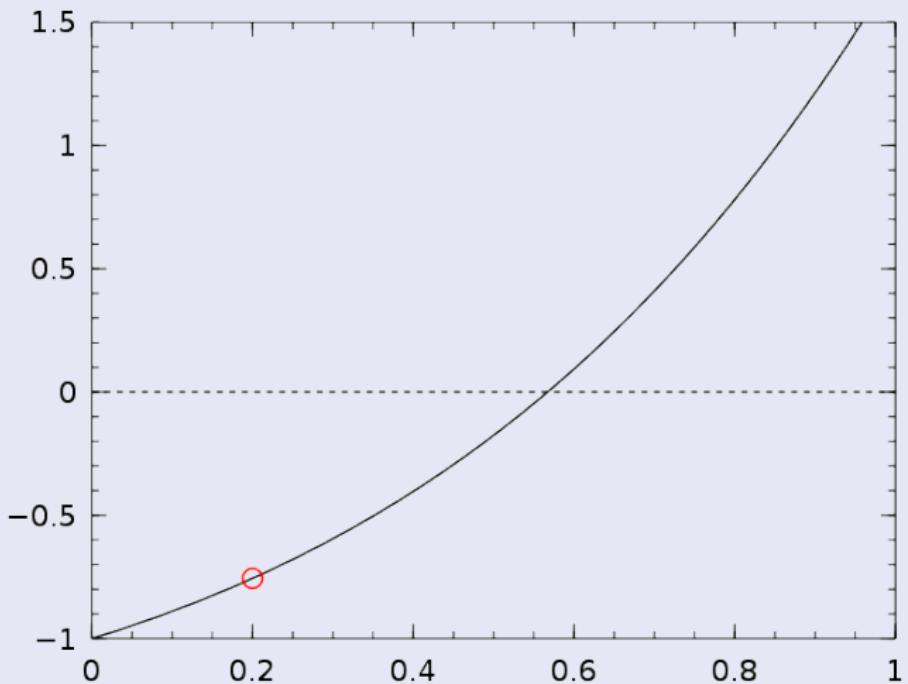
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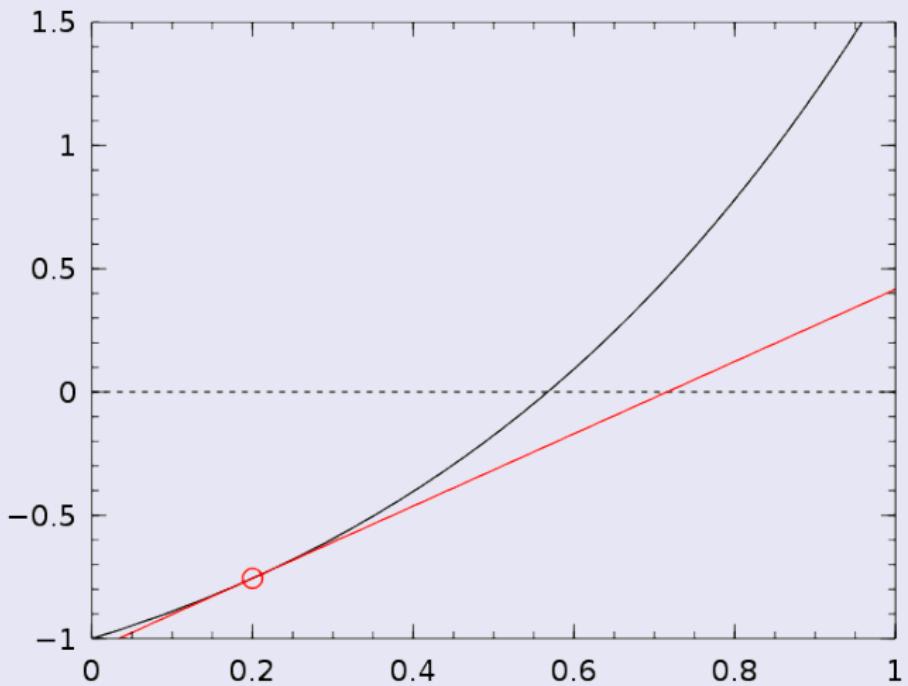
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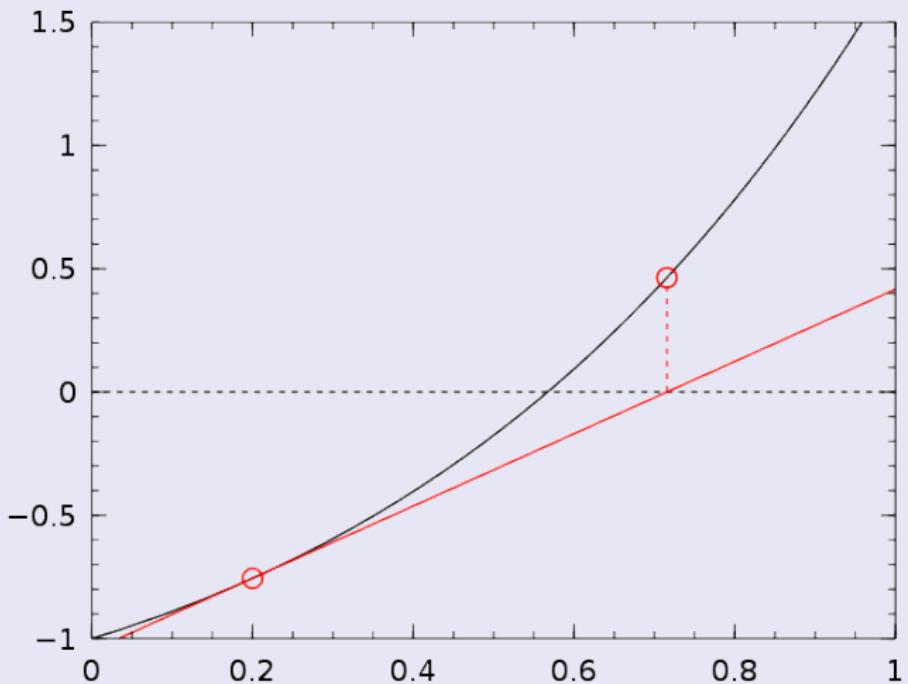
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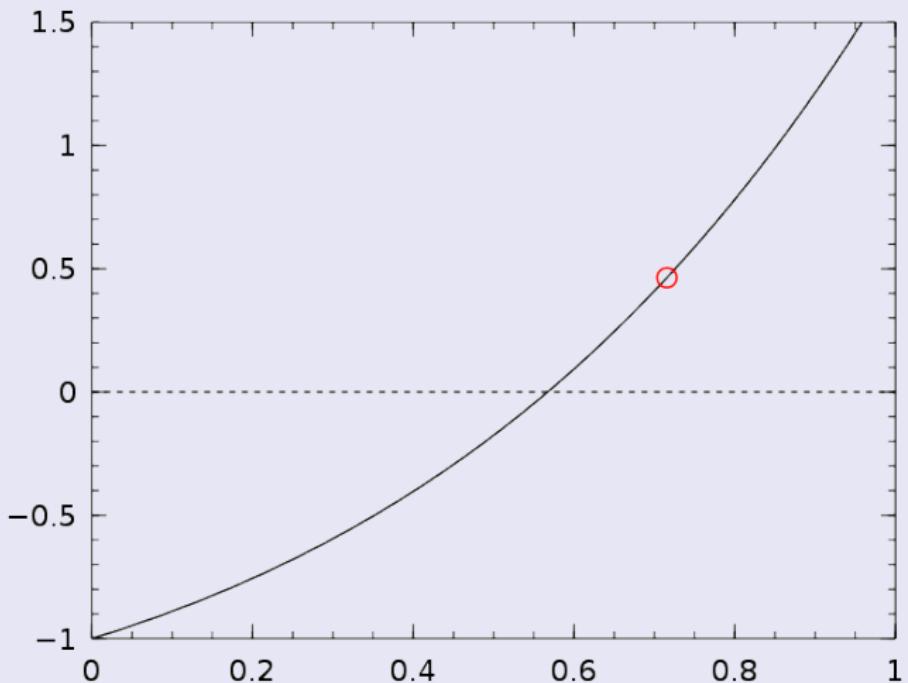
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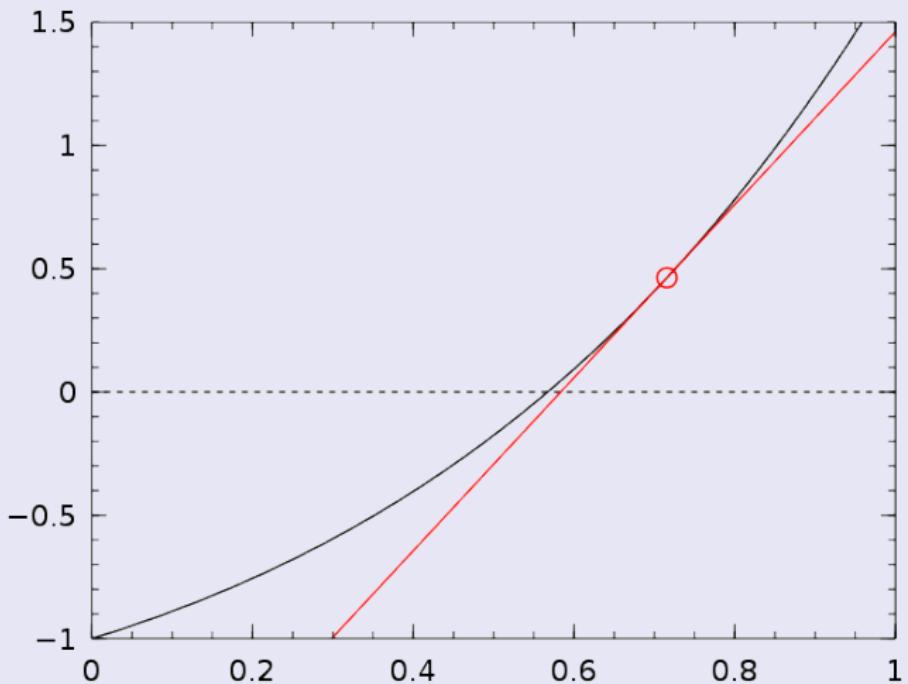
Sob **hipóteses**, $f'(x^k) \rightarrow 0$.

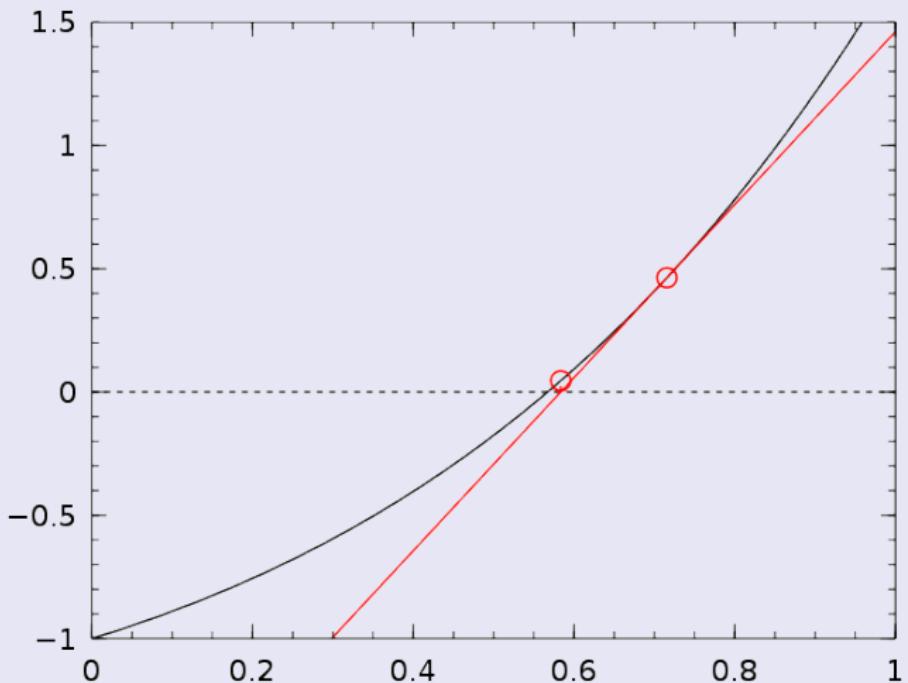


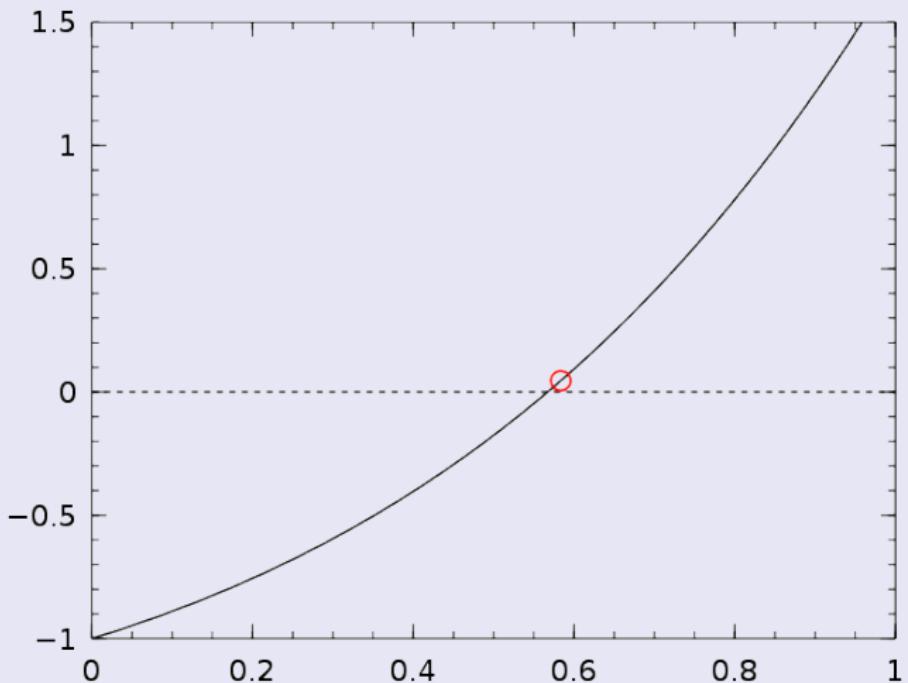


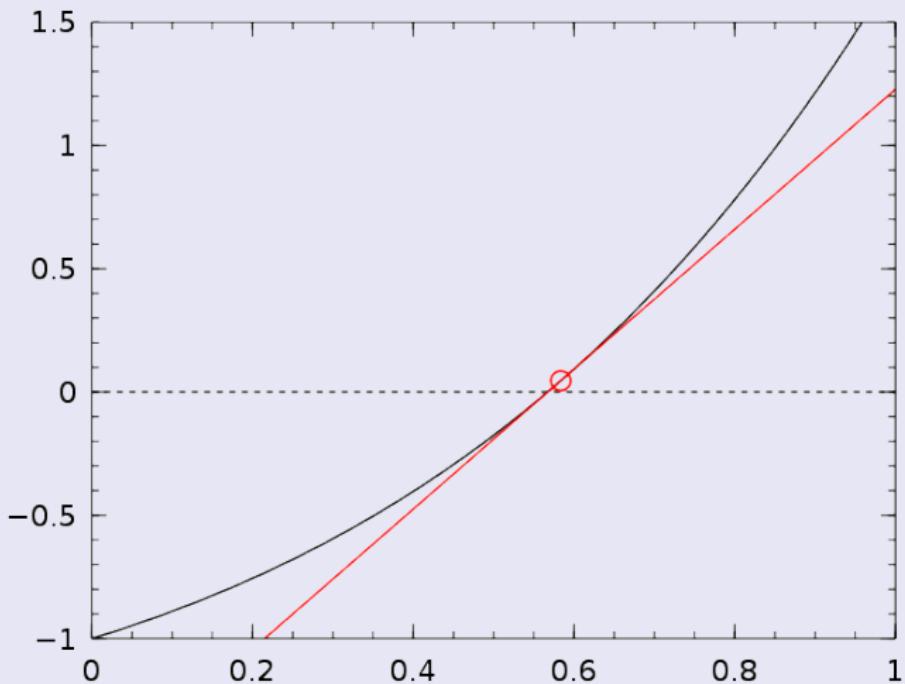


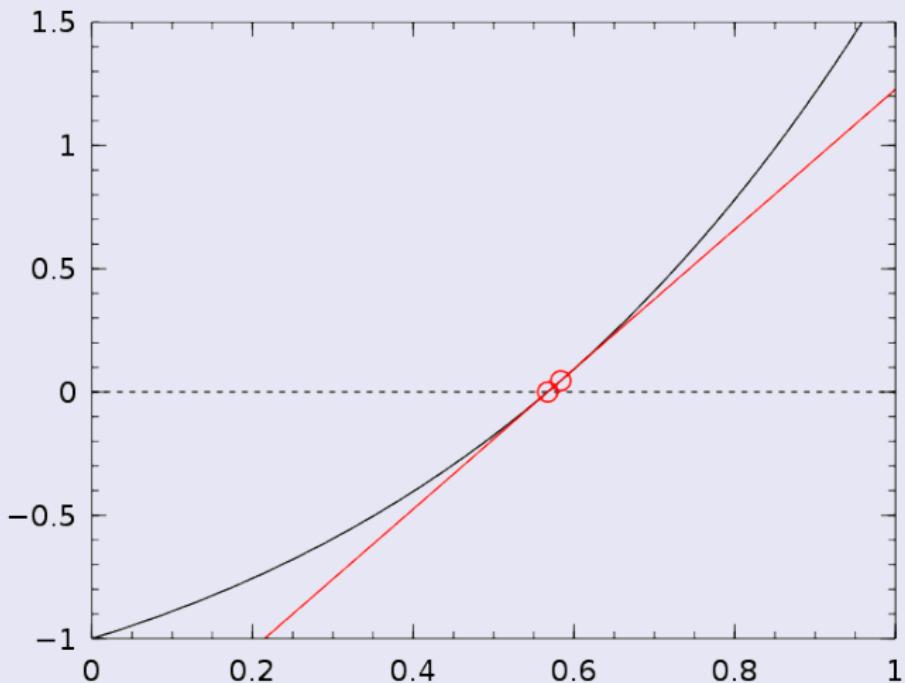












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Equações não-lineares

$$\begin{cases} x_1^2 + x_2^2 = 4 \\ x_1 x_2 = 1 \end{cases}$$

$$\begin{cases} x_1^2 + x_2^2 - e^{x_1+x_2} = 1 \\ \sqrt{1+x_1^2} + \frac{1}{x_2^2+1} = 1 \end{cases}$$

$$\begin{cases} x_1 x_2 x_3 = 1 \\ x_1 x_2 + x_1 x_3 + x_2 x_3 = 3 \\ x_1 + x_2 + x_3 = 3 \end{cases}$$

Equações não-lineares

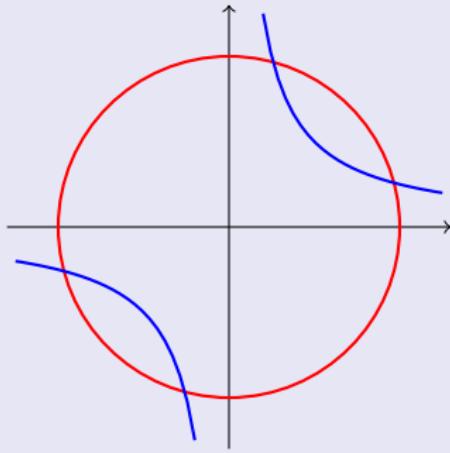
$$F(x) = 0, \quad F : \mathbb{R}^n \rightarrow \mathbb{R}^n.$$

$$\begin{cases} x_1^2 + x_2^2 = 4 \\ x_1 x_2 = 1 \end{cases}$$

$$F(x) = \begin{bmatrix} x_1^2 + x_2^2 - 4 \\ x_1 x_2 - 1 \end{bmatrix}.$$

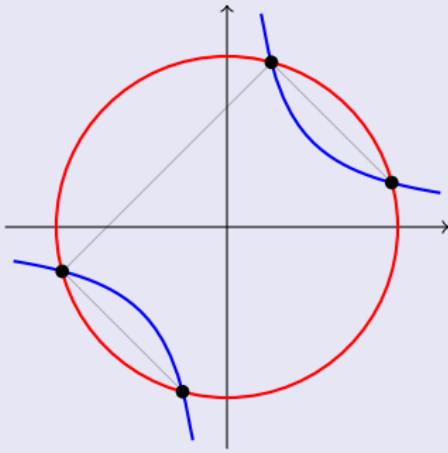
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A Aproximação linear

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$$F(x) \approx L(x) = F(a) + F'(a)(x - a).$$

$$F(x) = \begin{bmatrix} x_1^2 + x_2^2 - 4 \\ x_1 x_2 - 1 \end{bmatrix} \quad F'(x) = \begin{bmatrix} 2x_1 & 2x_2 \\ x_2 & x_1 \end{bmatrix} \quad a = \begin{bmatrix} 2 \\ 1 \end{bmatrix}.$$

A Aproximação linear

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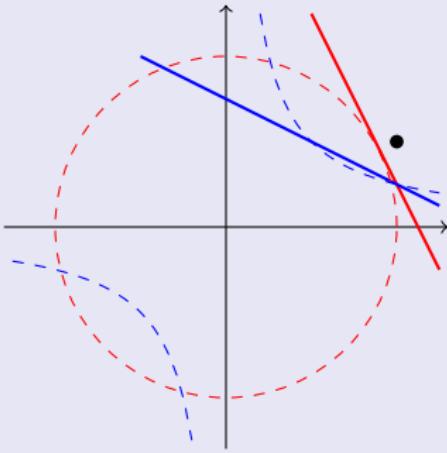
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$$F(2, 1) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad F'(2, 1) = \begin{bmatrix} 4 & 2 \\ 1 & 2 \end{bmatrix}$$

$$L(x) = \begin{bmatrix} 4x_1 + 2x_2 - 9 \\ x_1 + 2x_2 - 3 \end{bmatrix}.$$

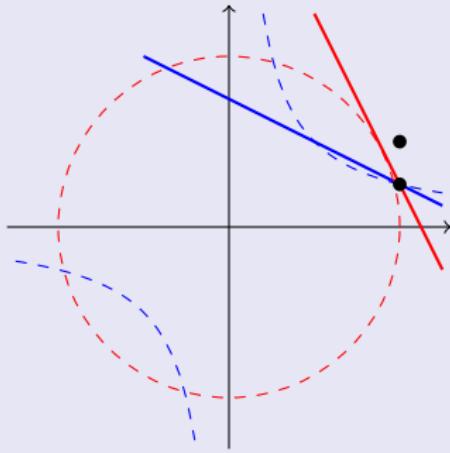
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A solução do sistema linear

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$$F'(a)(x - a) = -F(a),$$

$$x = a - [F'(a)]^{-1}F(a),$$

$F'(a)$ não singular.

O Método de Newton

Dado x^0 , defina as sequências $\{d^k\}$ e $\{x^k\}$ por

$$F'(x^k)d^k = -F(x^k),$$

$$x^{k+1} = x^k + d^k,$$

supondo-as bem definidas.

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Sob **hipóteses** $F(x^k) \rightarrow 0$.

O Método de Newton

$$x^0 = (2.00000, 1.00000), \quad F(x^0) = (1.00000, 1.00000)$$

$$x^1 = (2.00000, 0.50000), \quad F(x^1) = (0.25000, 0.00000)$$

$$x^2 = (1.93333, 0.51667), \quad F(x^2) = (0.00472, -0.00111)$$

$$x^3 = (1.93185, 0.51764), \quad F(x^3) = (0.00000, -0.00000)$$

* Com 5 casas decimais

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$$\min f(x), \quad f : \mathbb{R}^n \rightarrow \mathbb{R}, f \in C^2$$

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CN1 Se x^* é um minimizador local de f , então $\nabla f(x^*) = 0$.

Otimização

$$\min f(x), \quad f : \mathbb{R}^n \rightarrow \mathbb{R}, f \in C^2$$

CN1 Se x^* é um minimizador local de f , então $\nabla f(x^*) = 0$.

CN2 Se x^* é um minimizador local de f , então $\nabla f(x^*) = 0$ e

$\nabla^2 f(x^*)$ é semidefinida positiva.

Otimização

$$\min f(x), \quad f : \mathbb{R}^n \rightarrow \mathbb{R}, f \in C^2$$

- CN1** Se x^* é um minimizador local de f , então $\nabla f(x^*) = 0$.
- CN2** Se x^* é um minimizador local de f , então $\nabla f(x^*) = 0$ e $\nabla^2 f(x^*)$ é semidefinida positiva.
- CS2** Se $\nabla f(x^*) = 0$ e $\nabla^2 f(x^*)$ é definida positiva, então x^* é um minimizador local de f .

O Método de Newton para otimização

$$F(x) = \nabla f(x)$$

$$F'(x) = \nabla^2 f(x)$$

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$$\nabla^2 f(x^k) d^k = -\nabla f(x^k)$$

$$x^{k+1} = x^k + d^k$$

O Método de Newton para otimização

$$\nabla^2 f(x^k)d + \nabla f(x^k) = 0.$$

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$$m(d) = \frac{1}{2} d^T \nabla^2 f(x^k) d + \nabla f(x^k)^T d + f(x^k).$$

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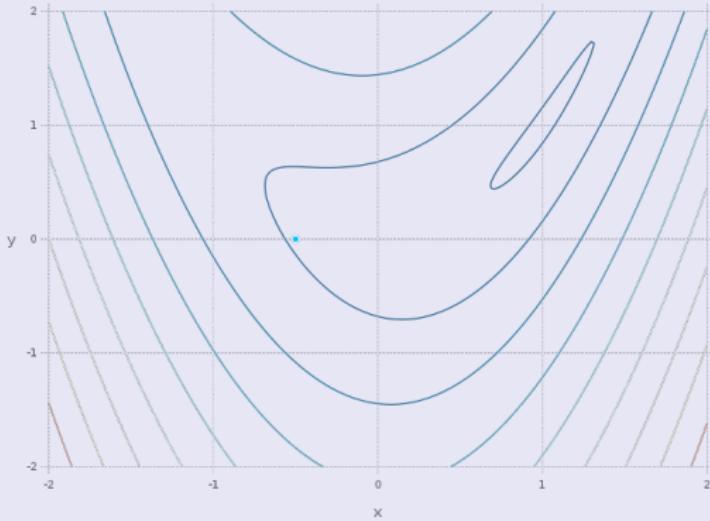
$$m(d) = \frac{1}{2} d^T \nabla^2 f(x^k) d + \nabla f(x^k)^T d + f(x^k).$$

$$d^k = \arg \min_d m(d).$$

$$x^{k+1} = \arg \min_x m(x - x^k).$$

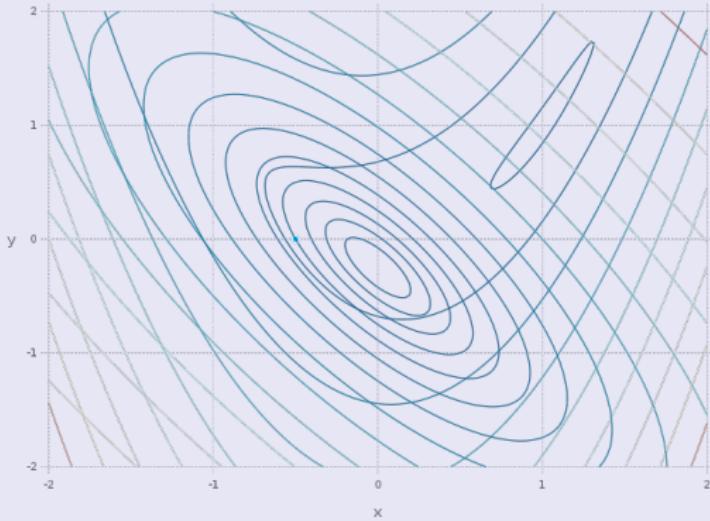
O Método de Newton para otimização

$$f(x) = (1 - x_1)^2 + 4(x_2 - x_1^2)^2, \quad x^0 = (-0.500, 0.000)$$



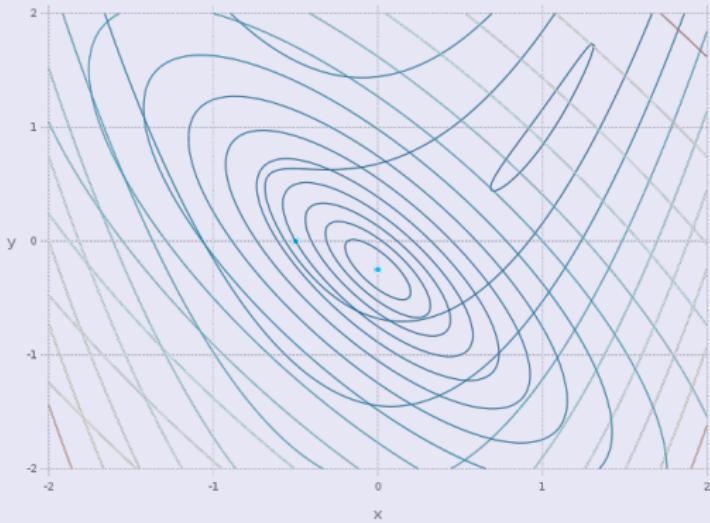
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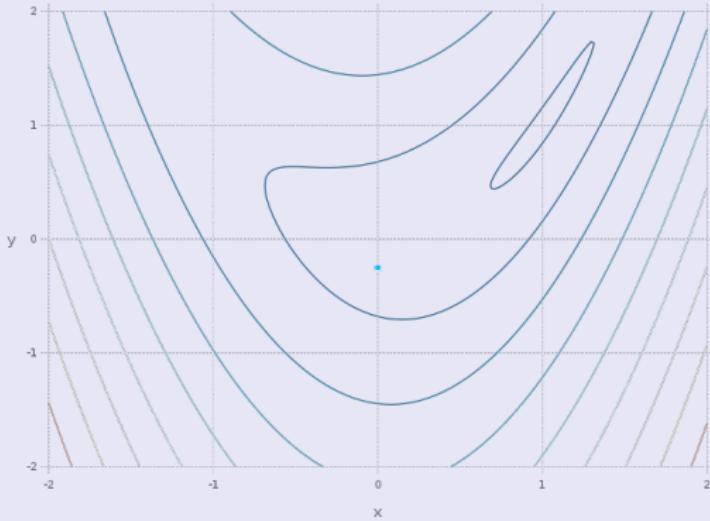
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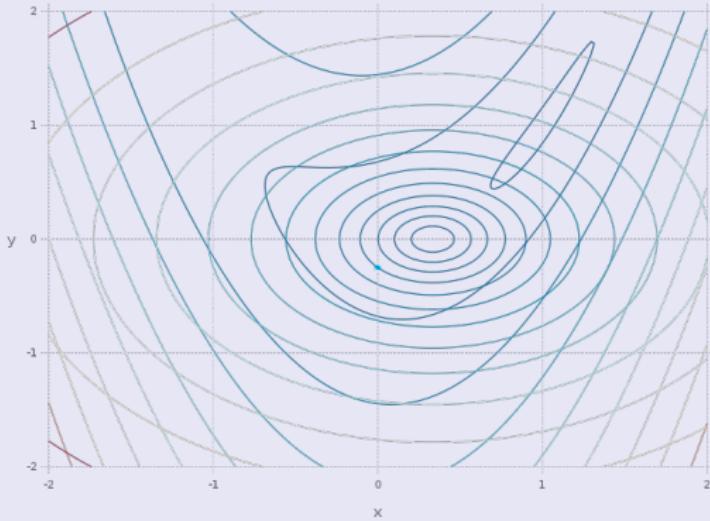
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$$f(x) = (1 - x_1)^2 + 4(x_2 - x_1^2)^2, \quad x^1 = (0.000, -0.250)$$



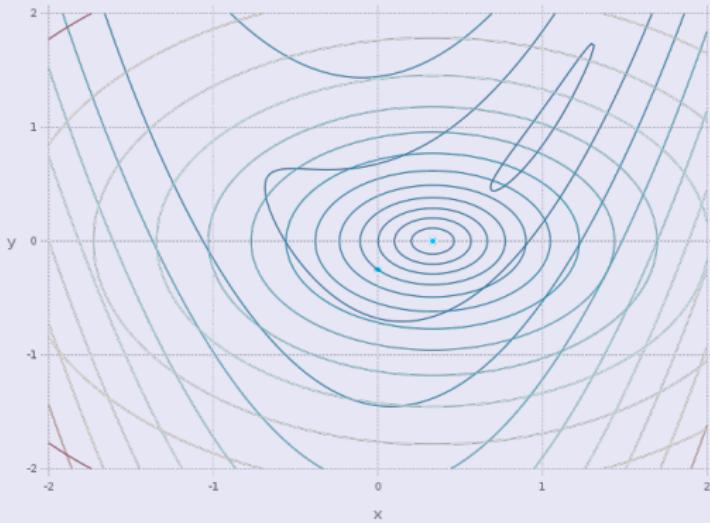
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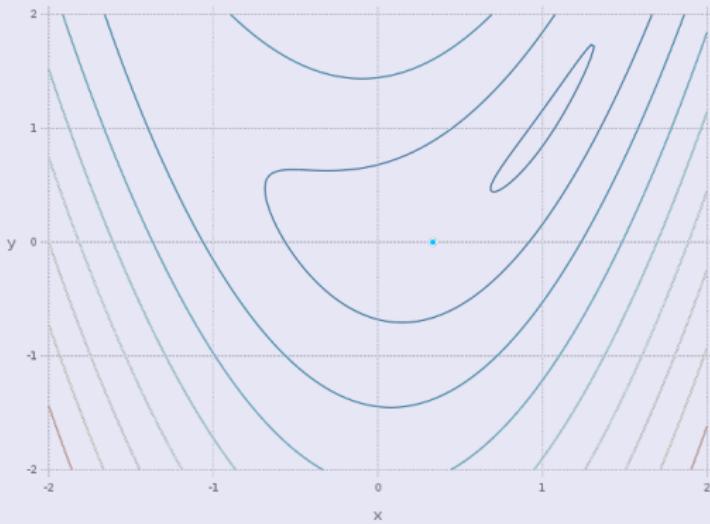
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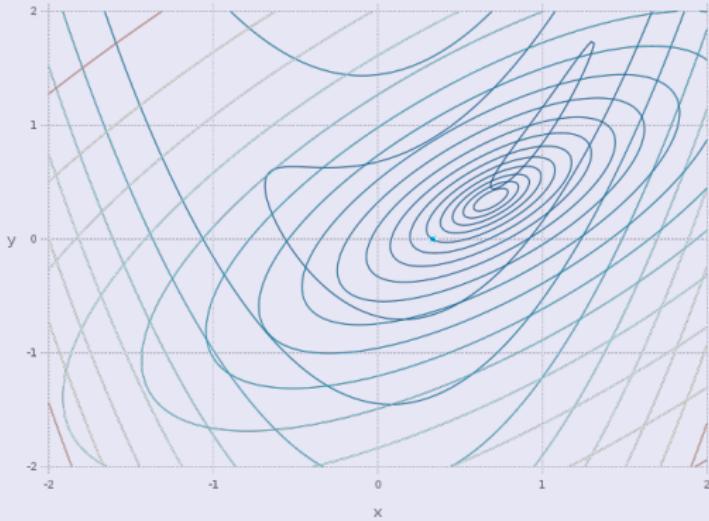
O Método de Newton para otimização

$$f(x) = (1 - x_1)^2 + 4(x_2 - x_1^2)^2, \quad x^2 = (0.333, 0.000)$$



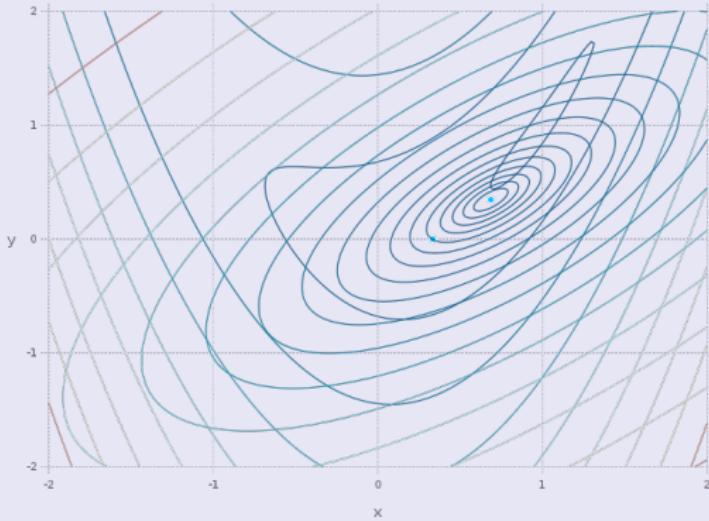
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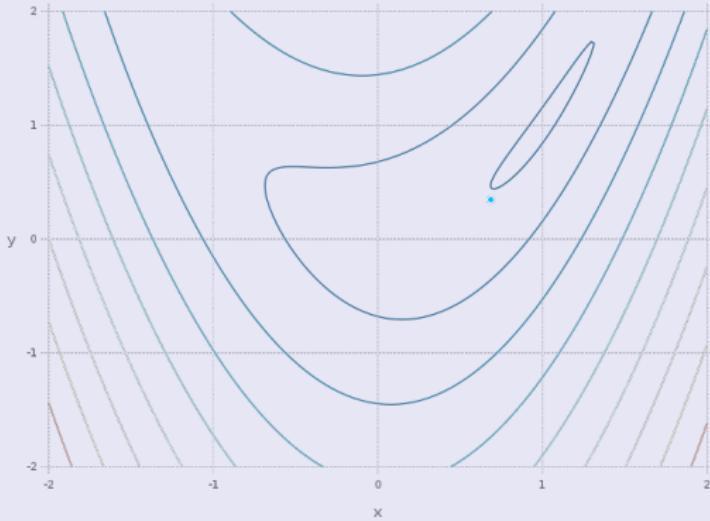
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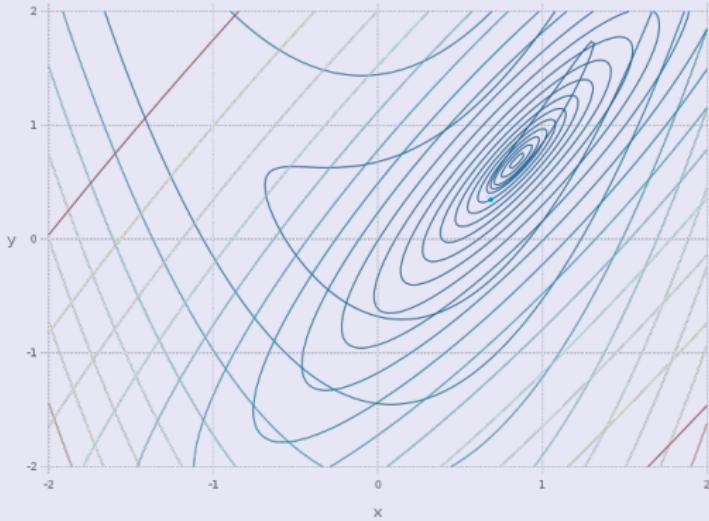
O Método de Newton para otimização

$$f(x) = (1 - x_1)^2 + 4(x_2 - x_1^2)^2, \quad x^3 = (0.686, 0.346)$$



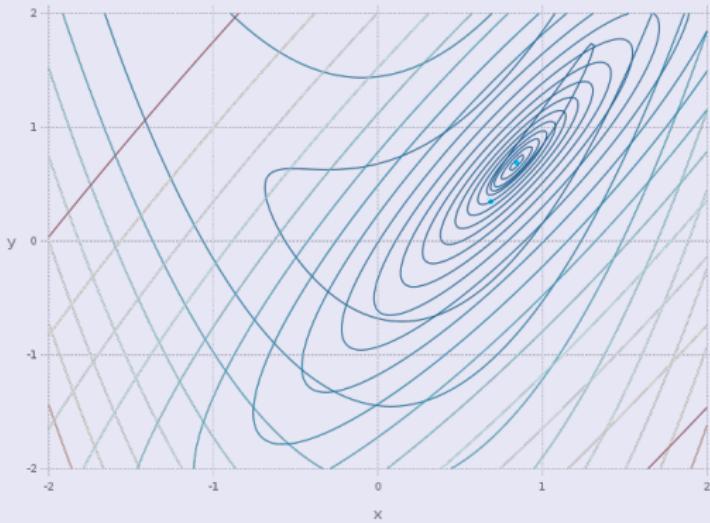
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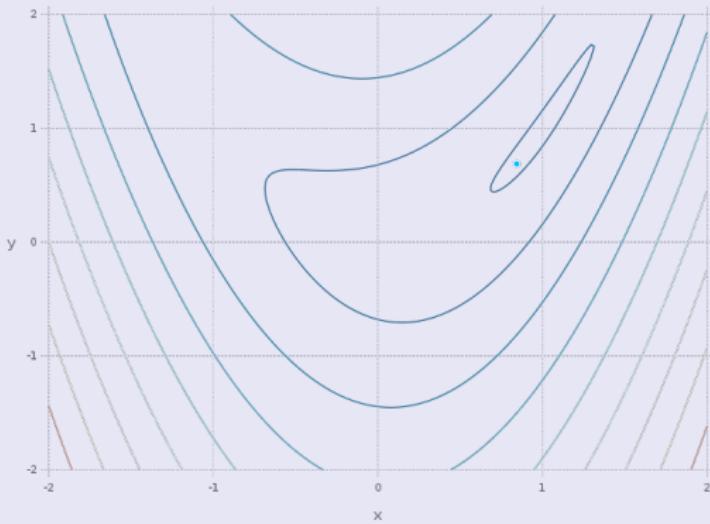
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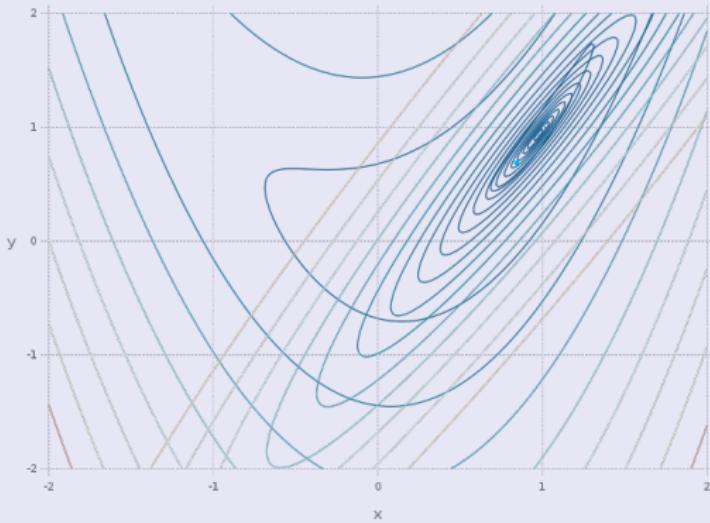
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$$f(x) = (1 - x_1)^2 + 4(x_2 - x_1^2)^2, \quad x^4 = (0.843, 0.687)$$



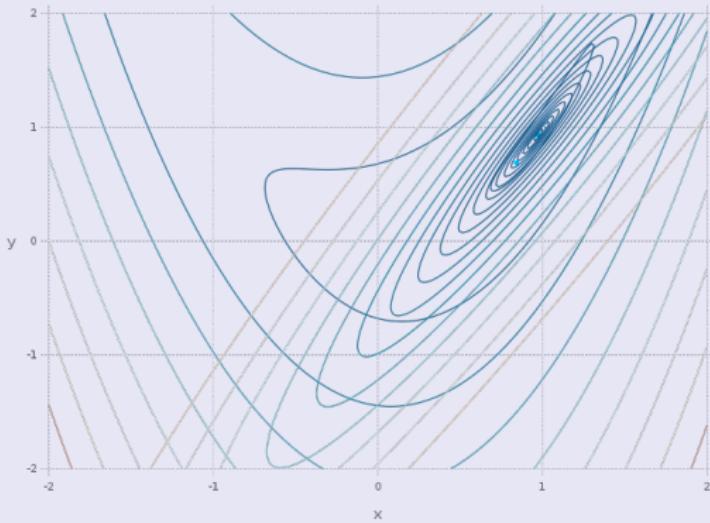
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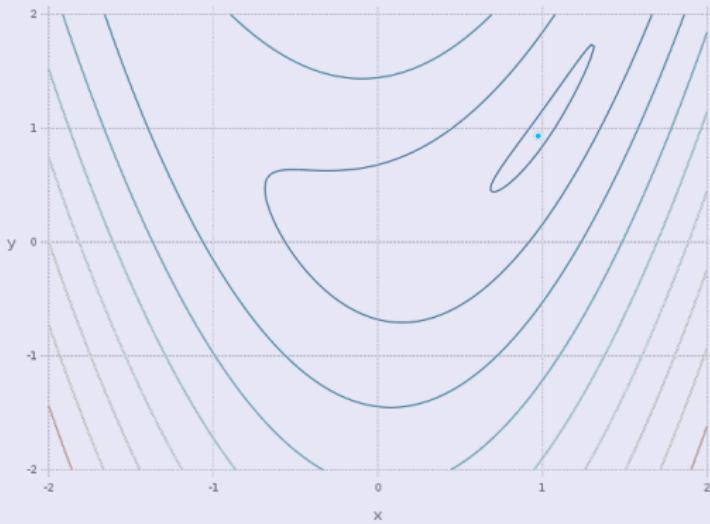
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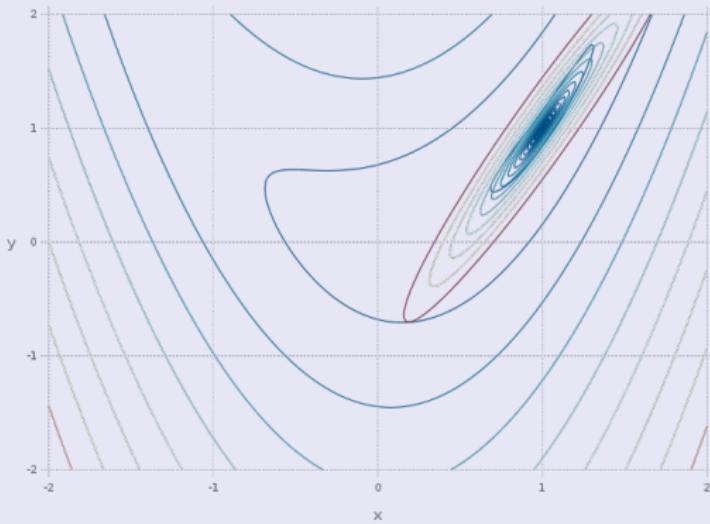
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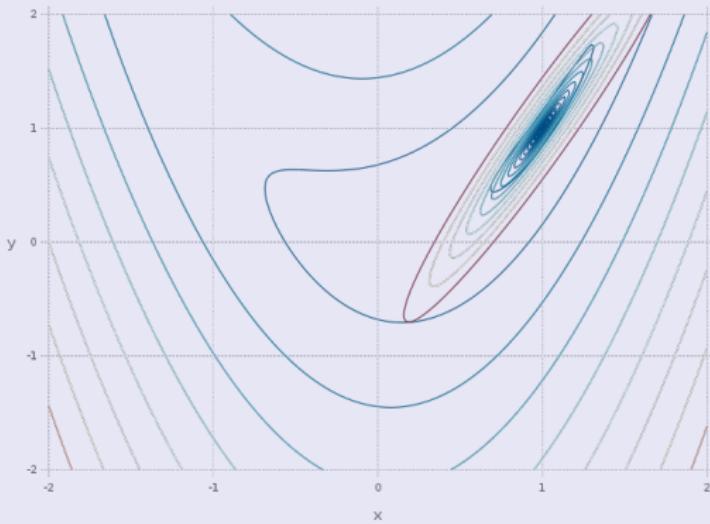
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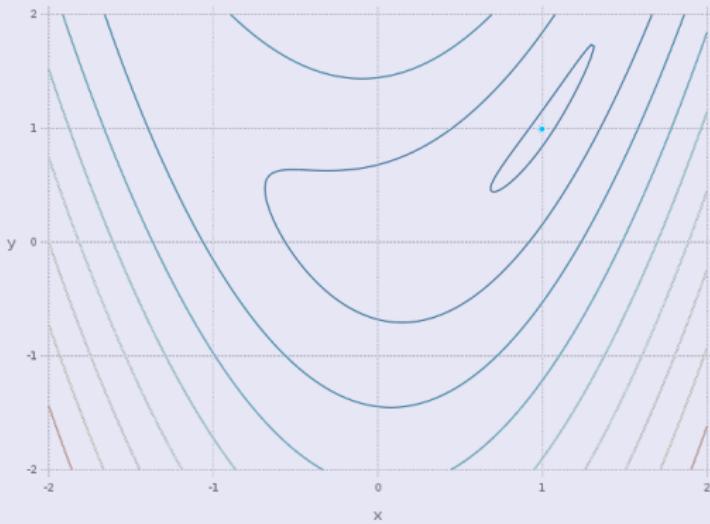
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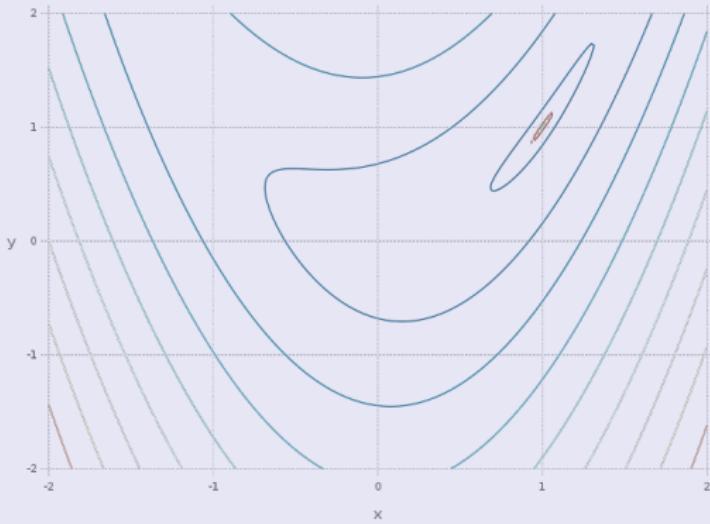
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$$f(x) = (1 - x_1)^2 + 4(x_2 - x_1^2)^2, \quad x^6 = (0.997, 0.993)$$



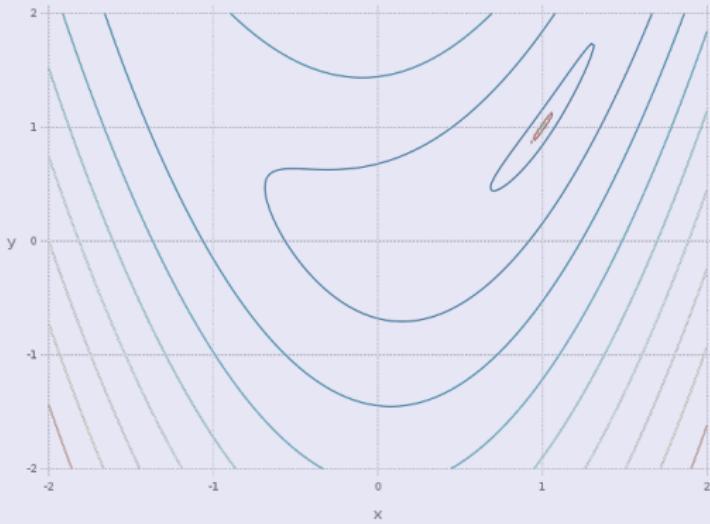
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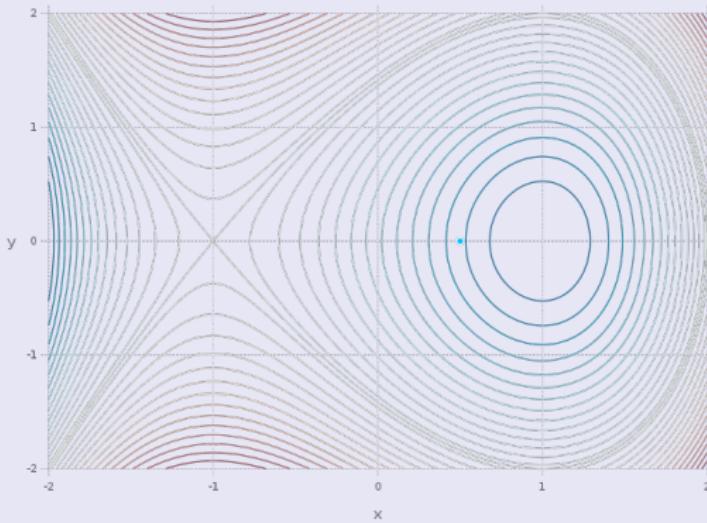
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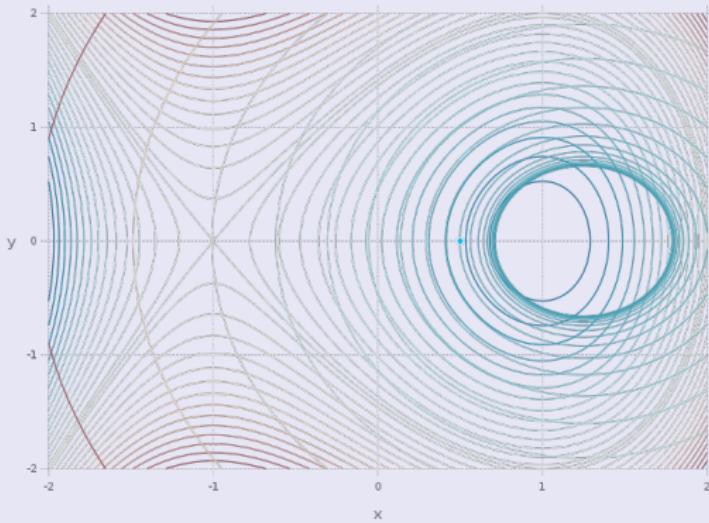
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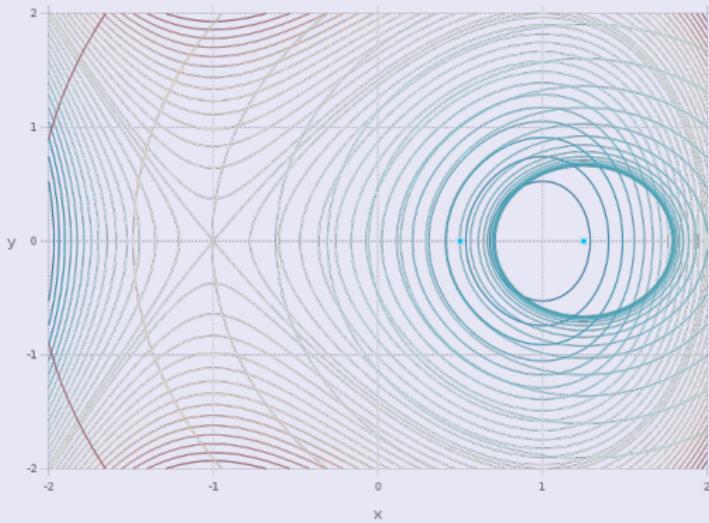
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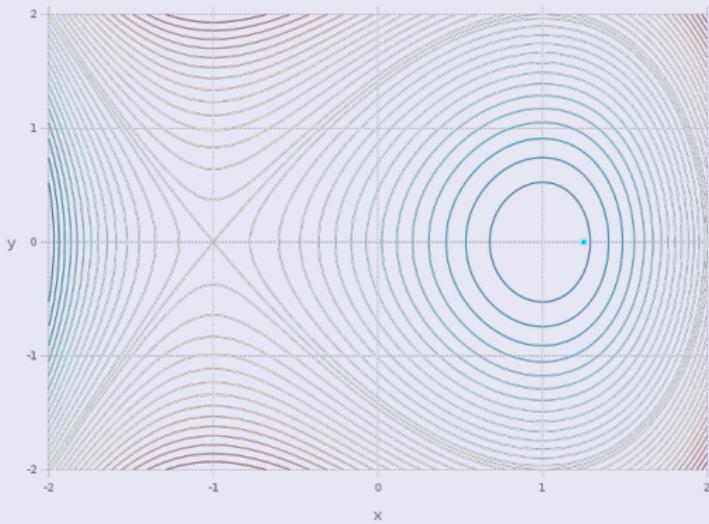
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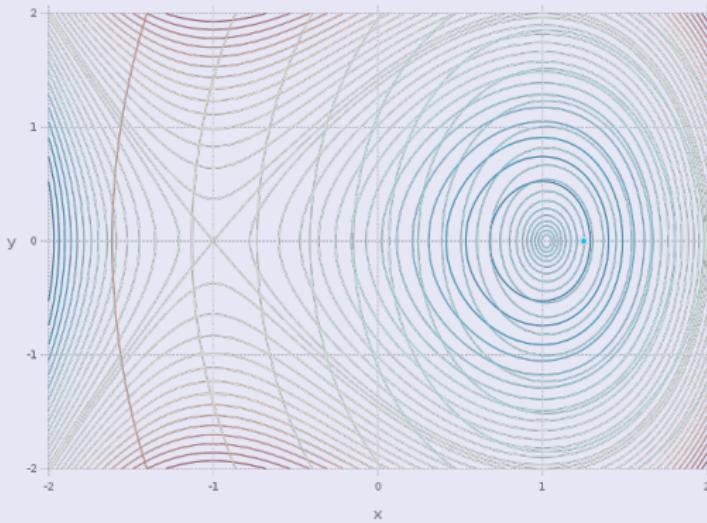
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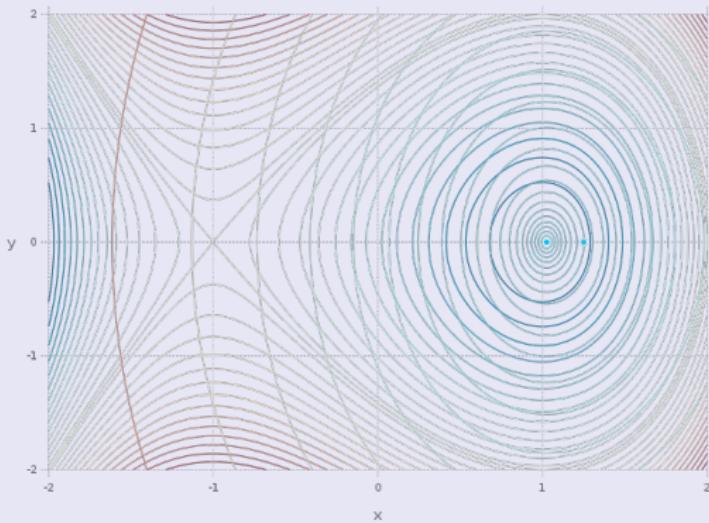
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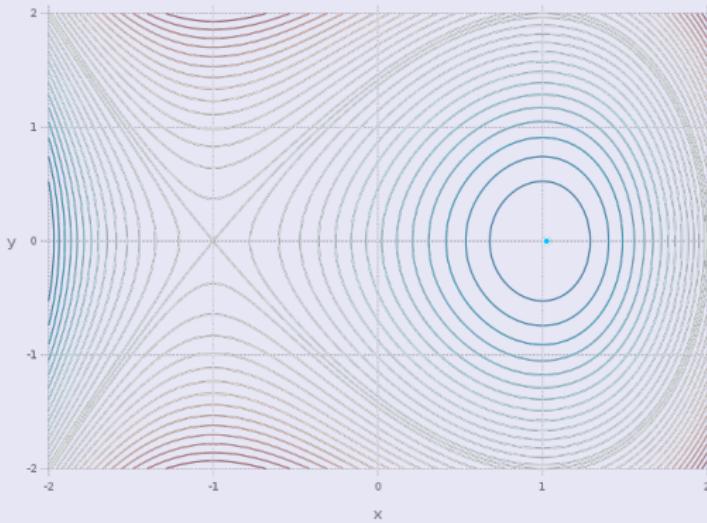
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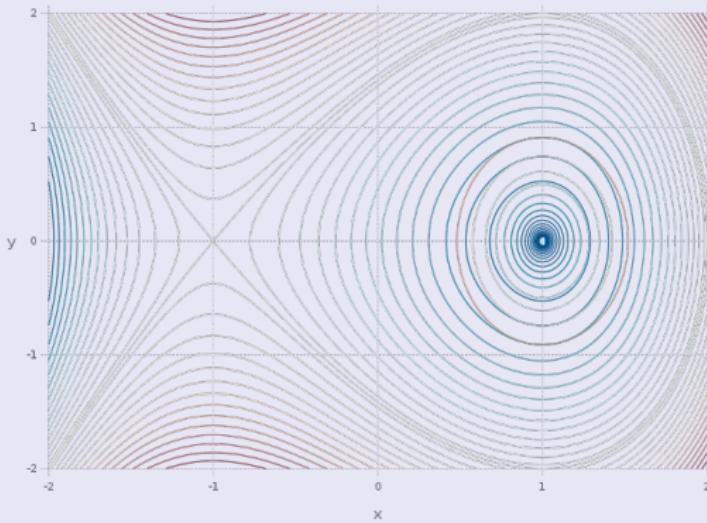
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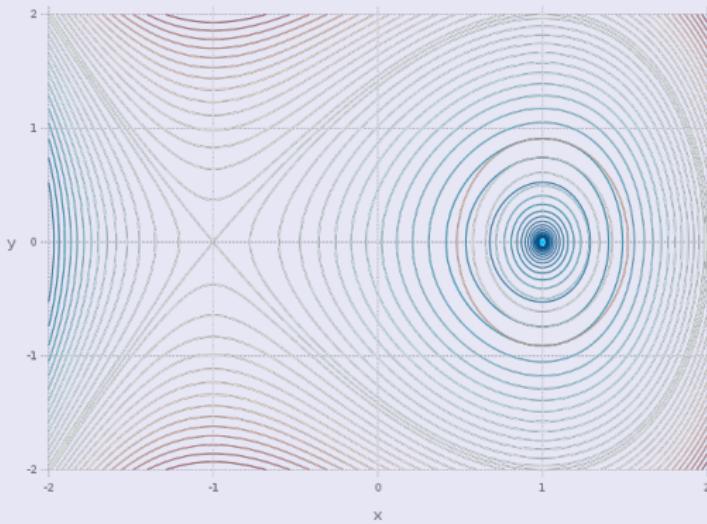
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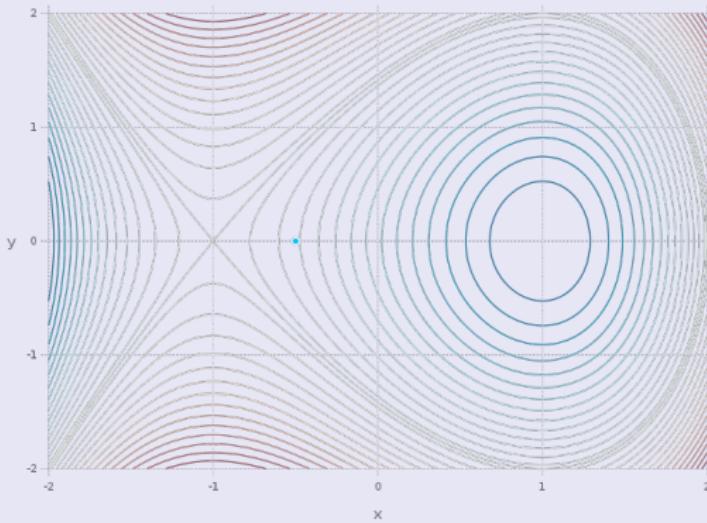
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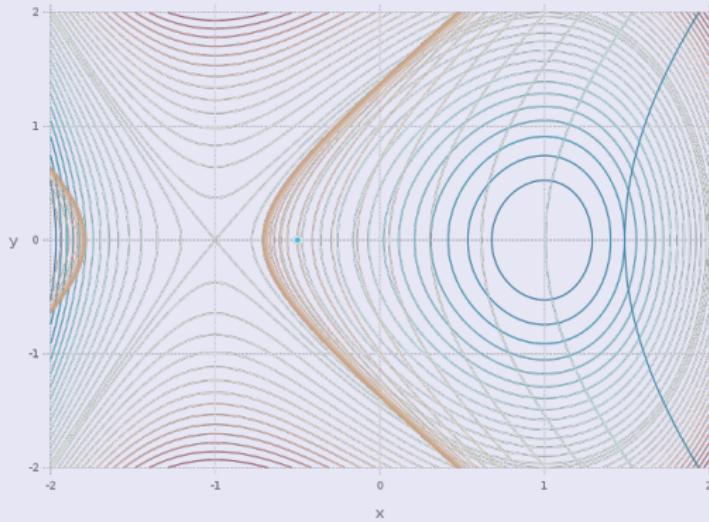
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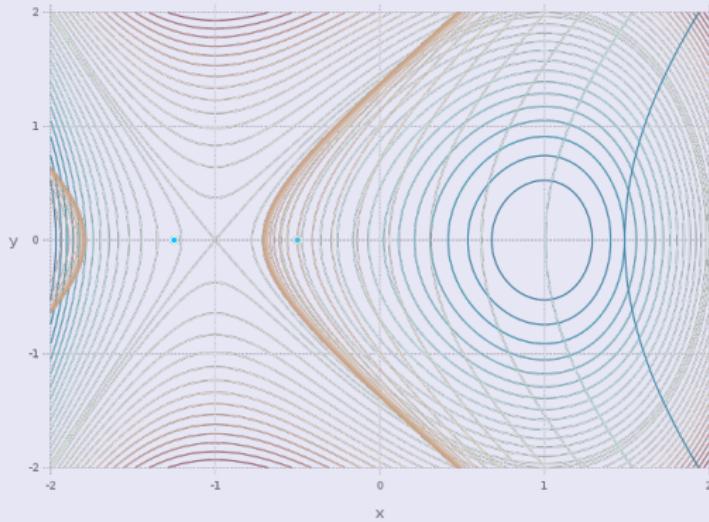
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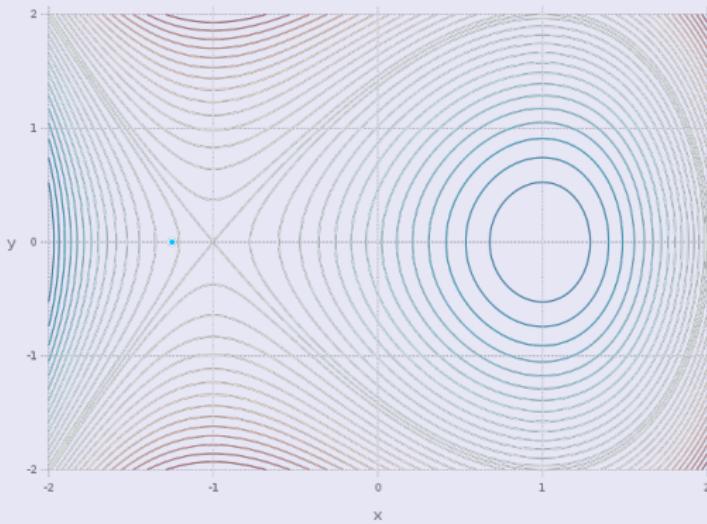
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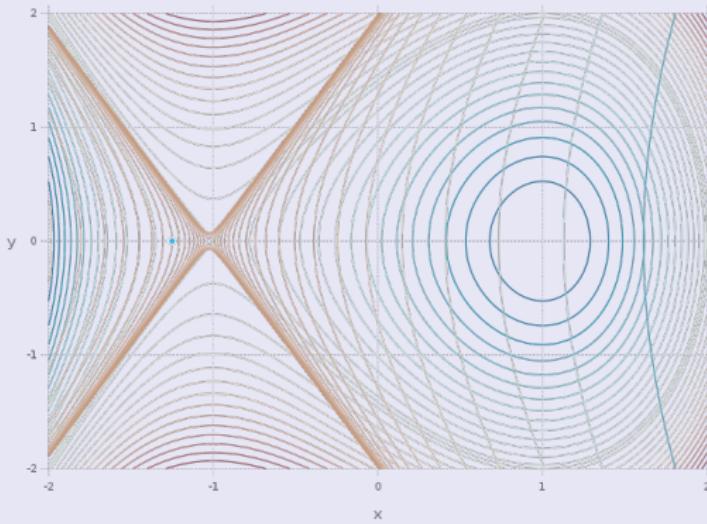
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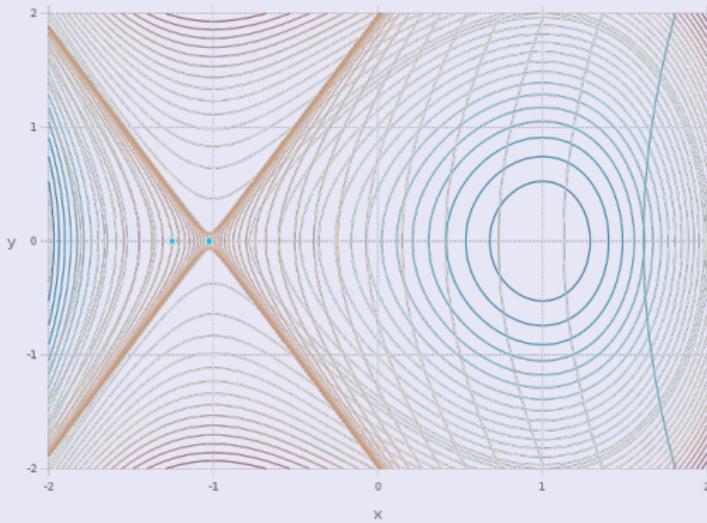
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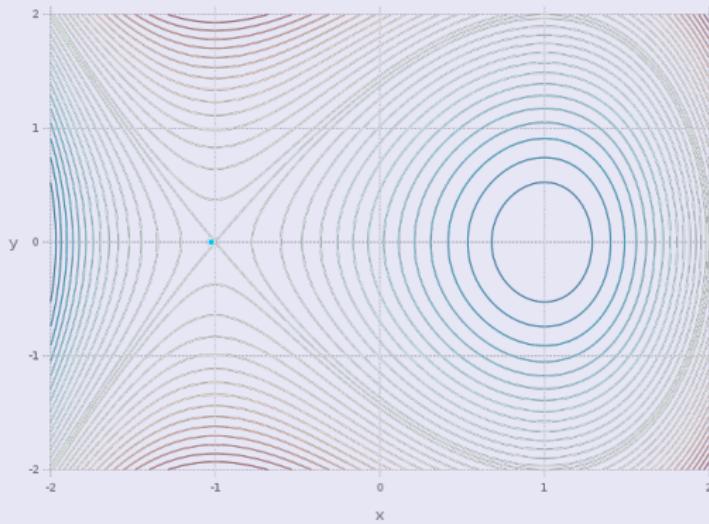
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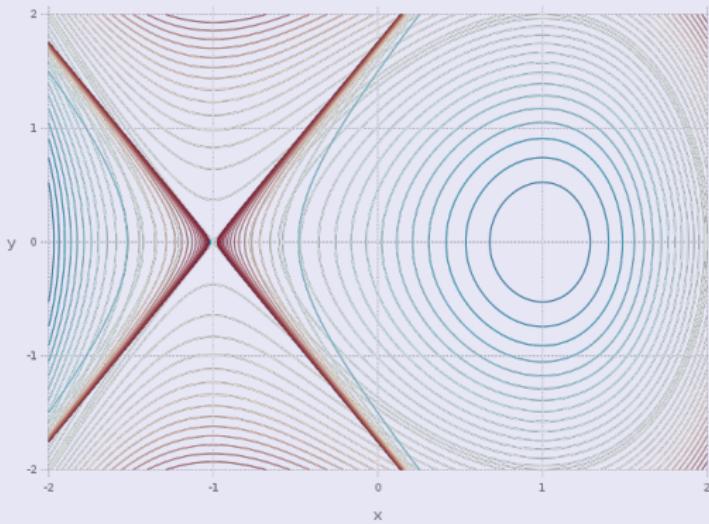
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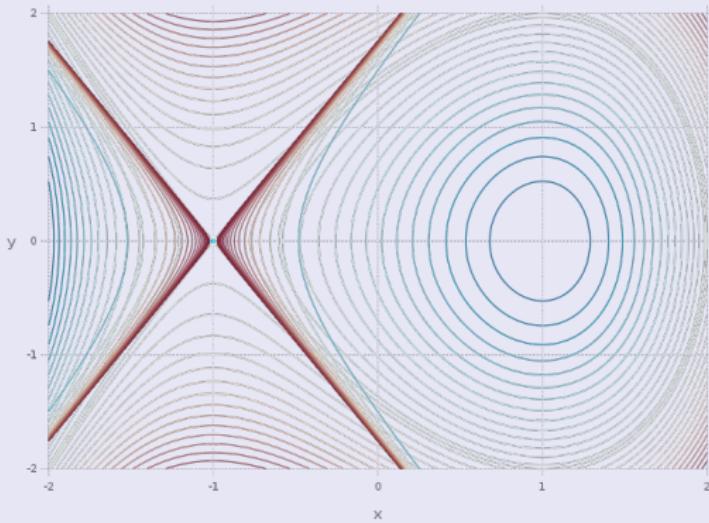
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1 Zeros de Funções

- Introdução
- Aproximação Linear
- Método de Newton

2 Equações não-lineares

- Introdução
- Aproximação Linear
- Método de Newton

3 Otimização

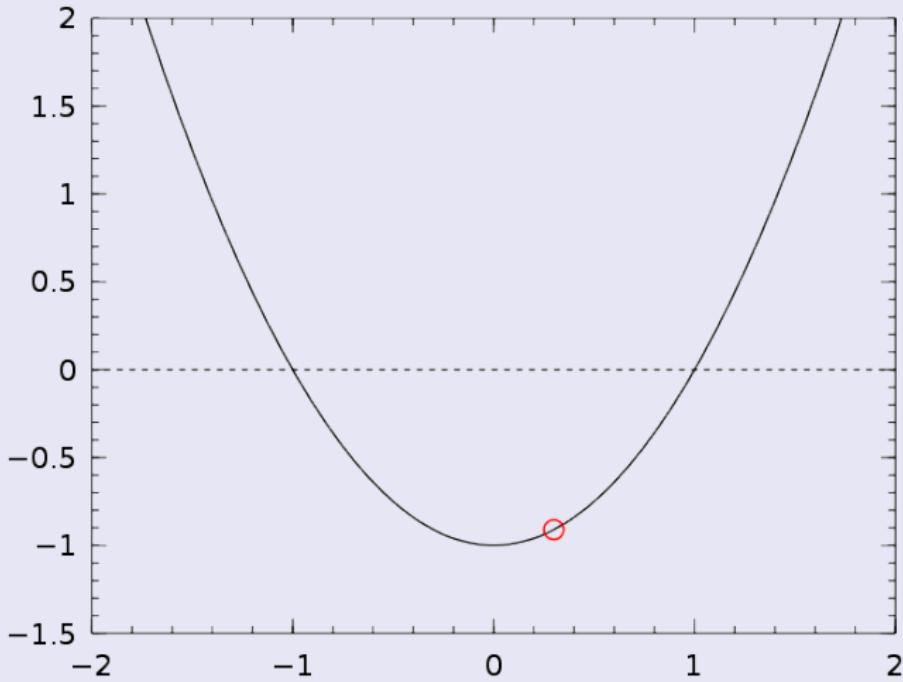
- Introdução
- O Método de Newton

4 Convergência

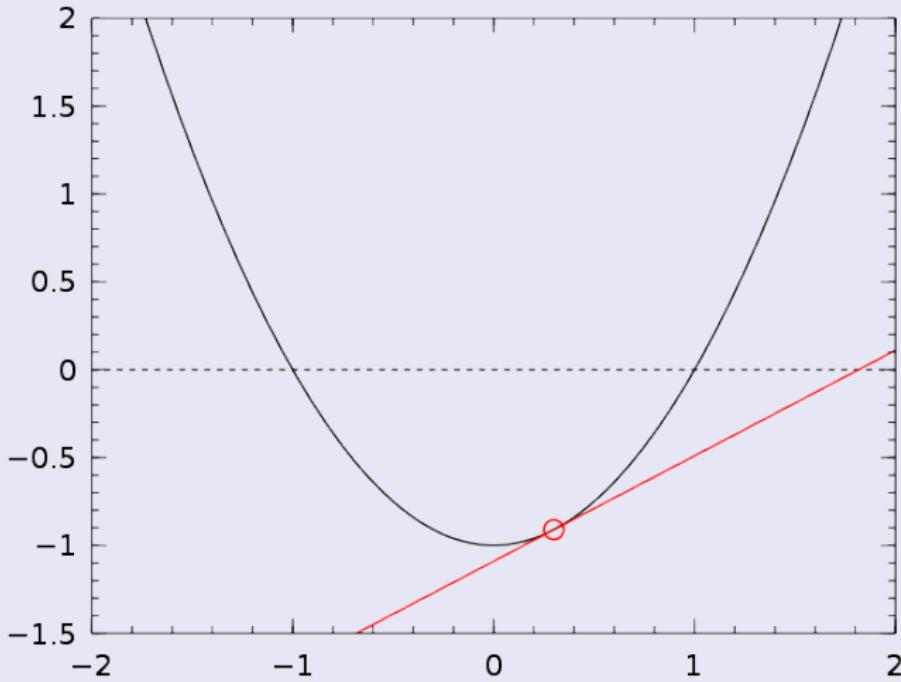
- Uma dimensão
- Duas dimensões
- Exemplo Tradicional

5 Referências

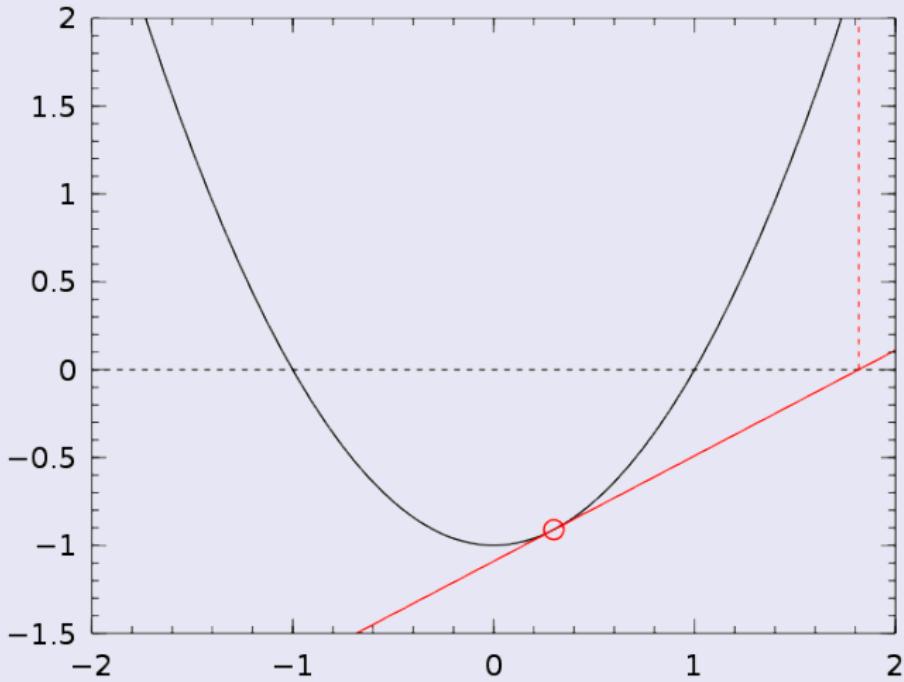
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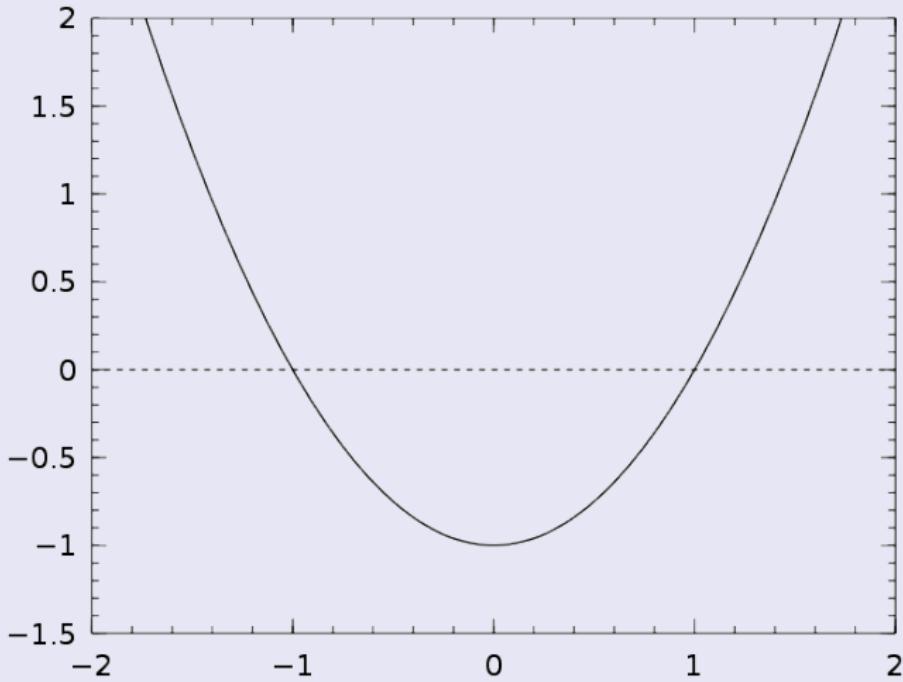
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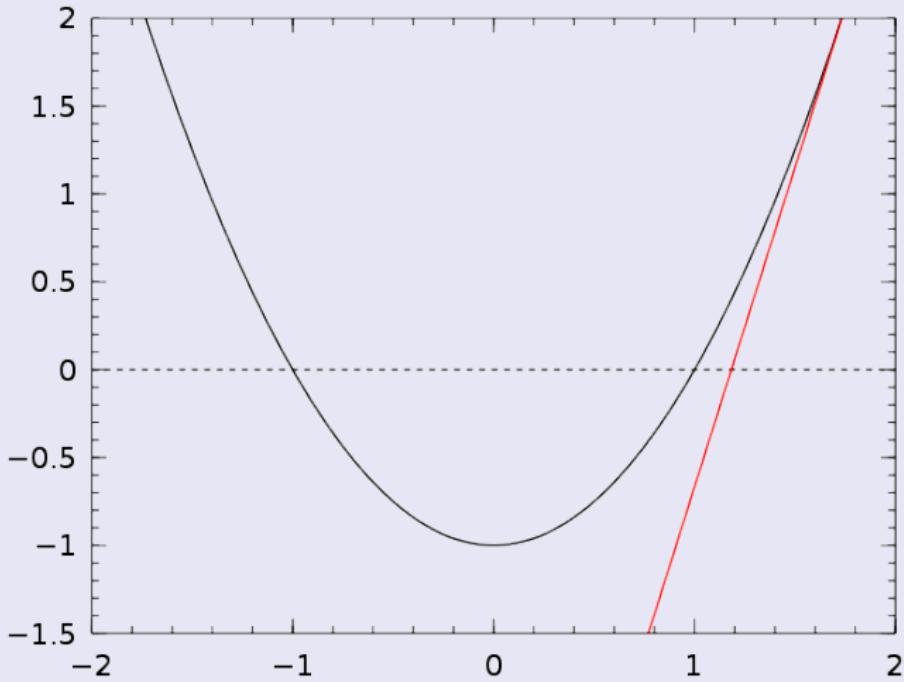
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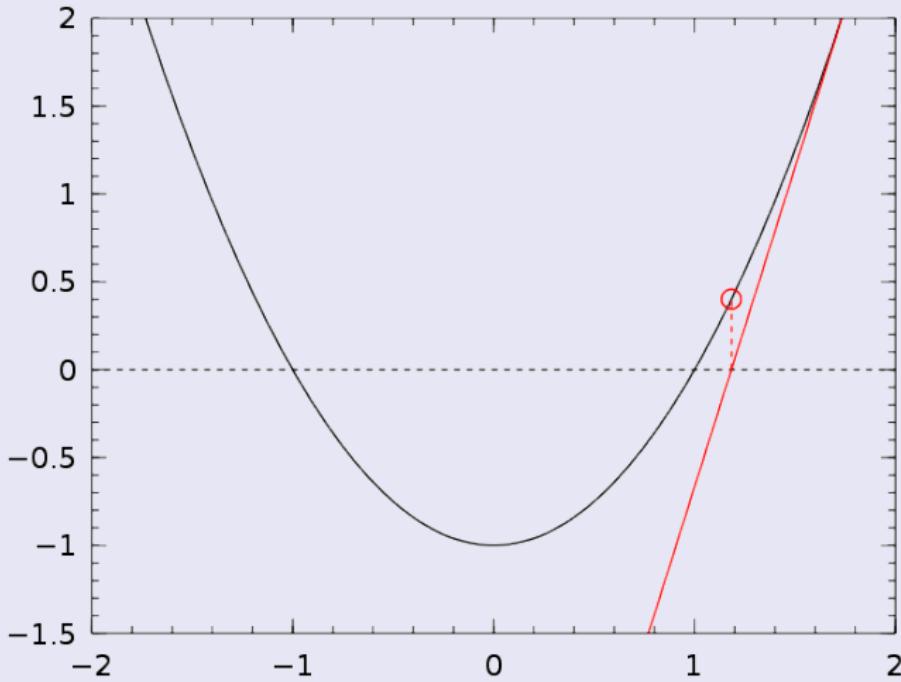
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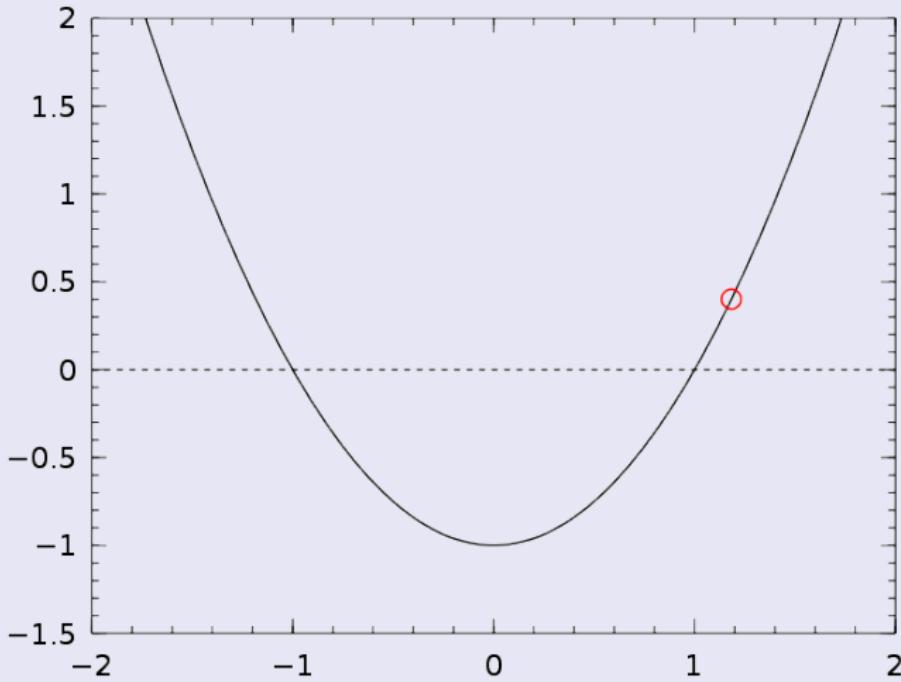
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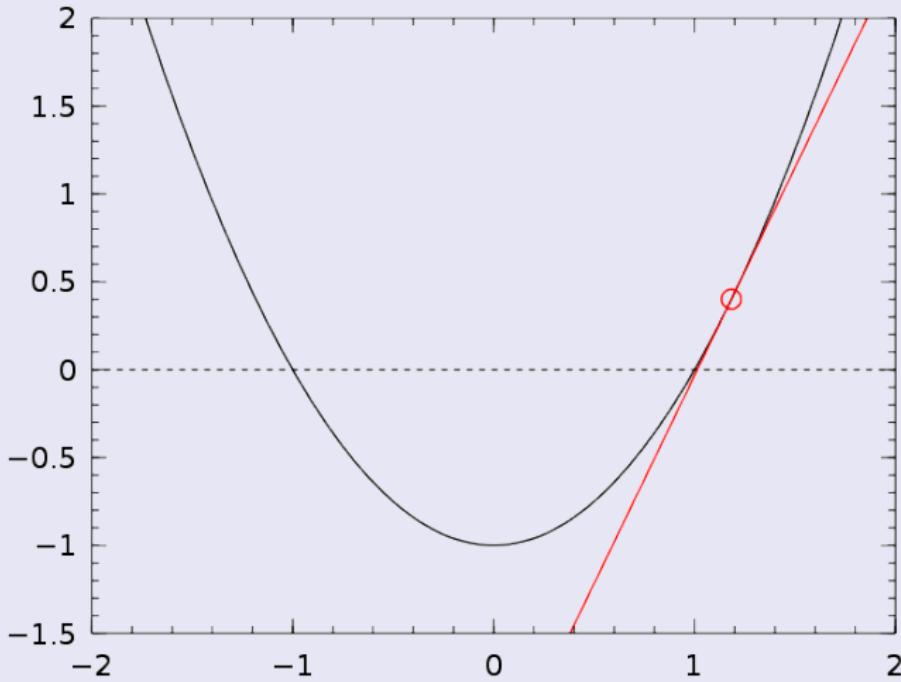
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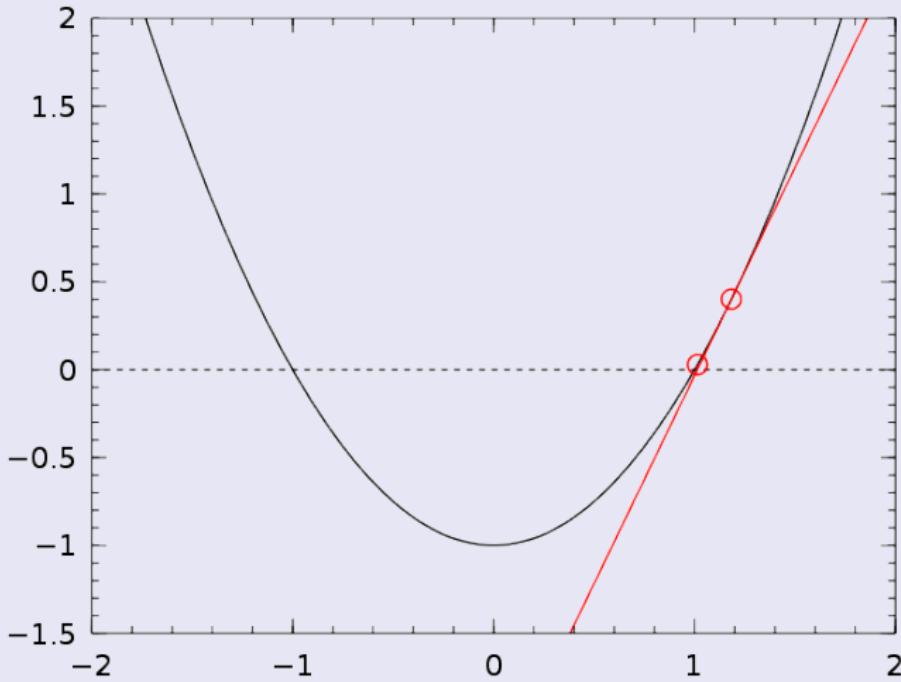
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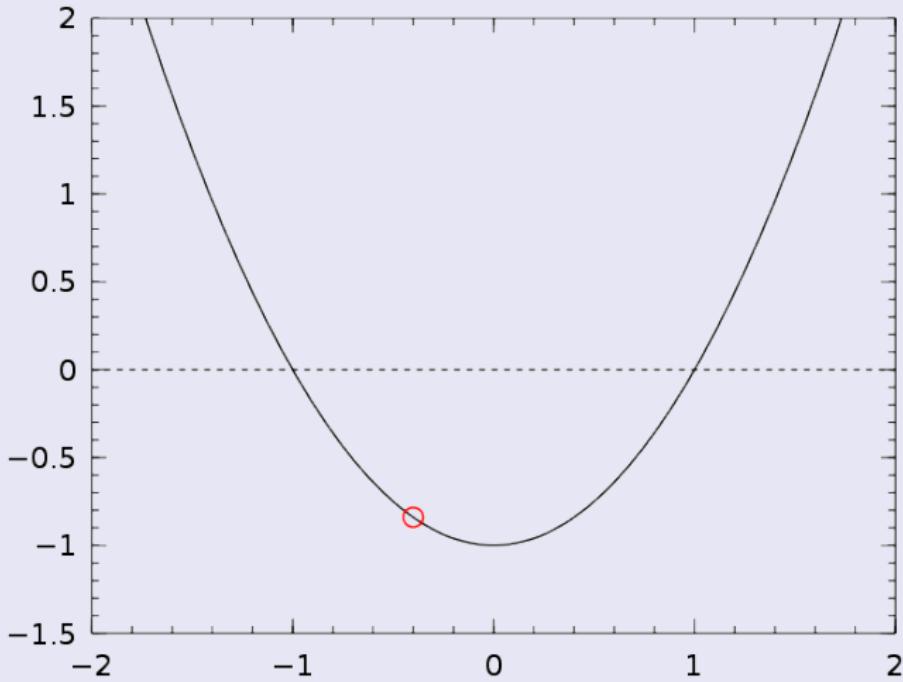
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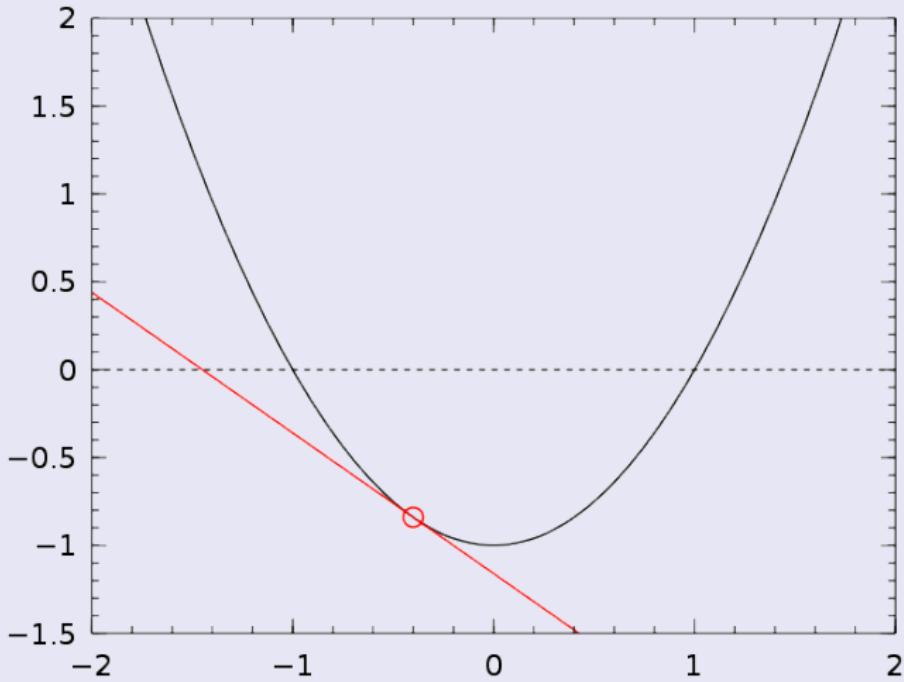
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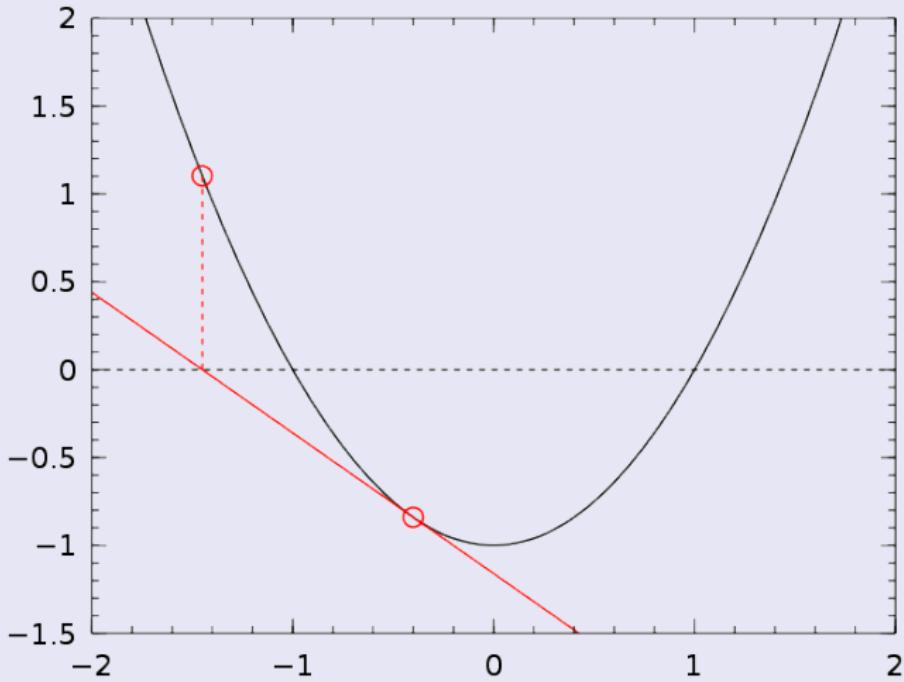
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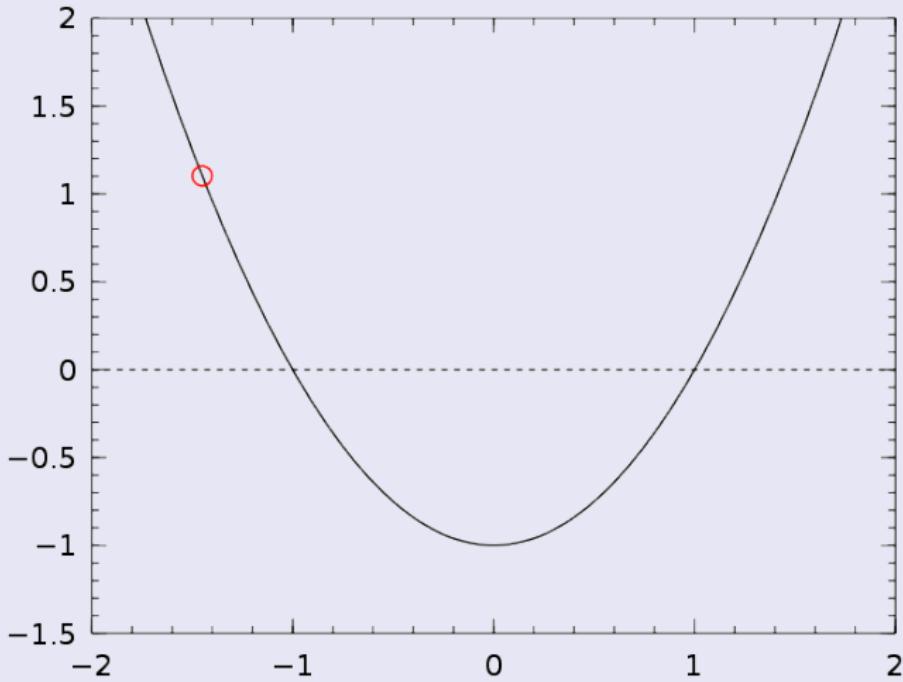
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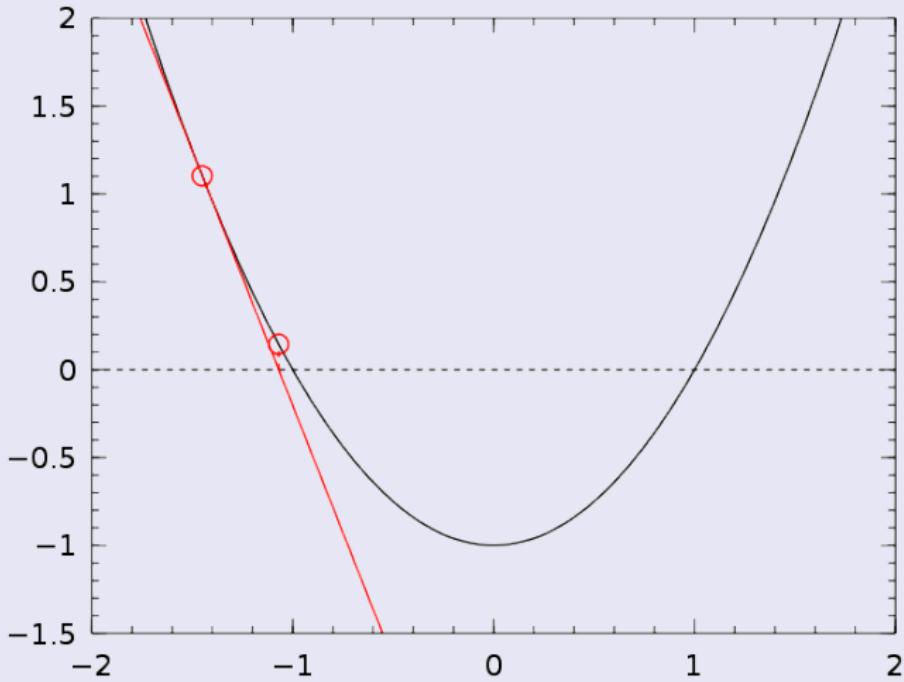
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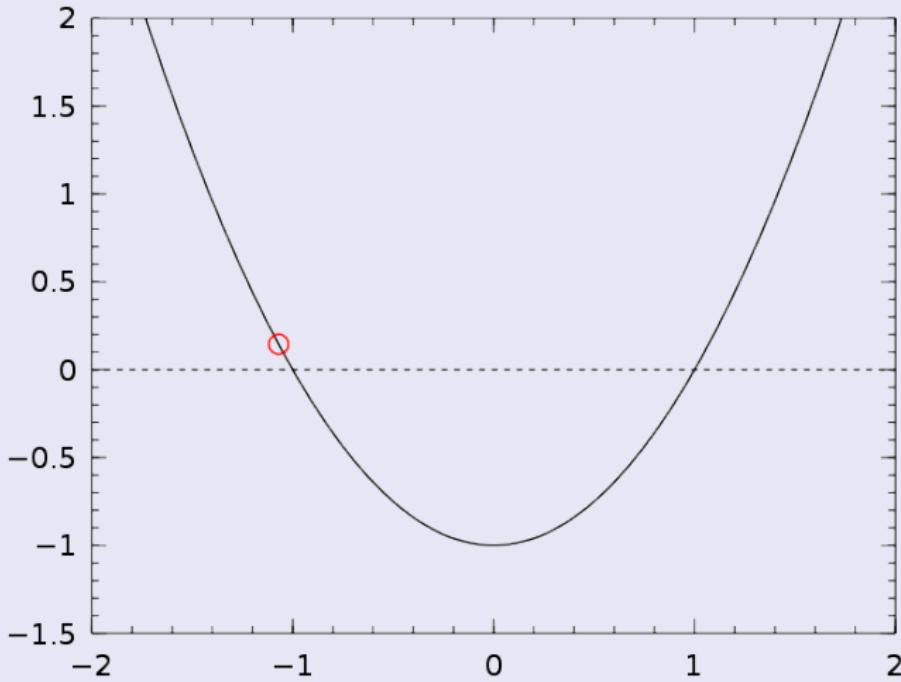
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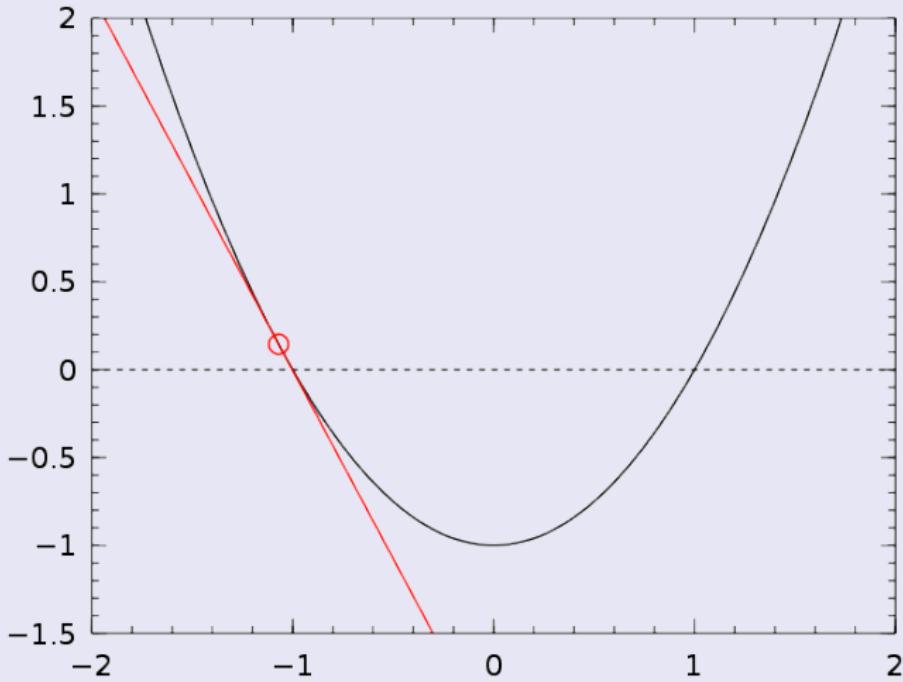
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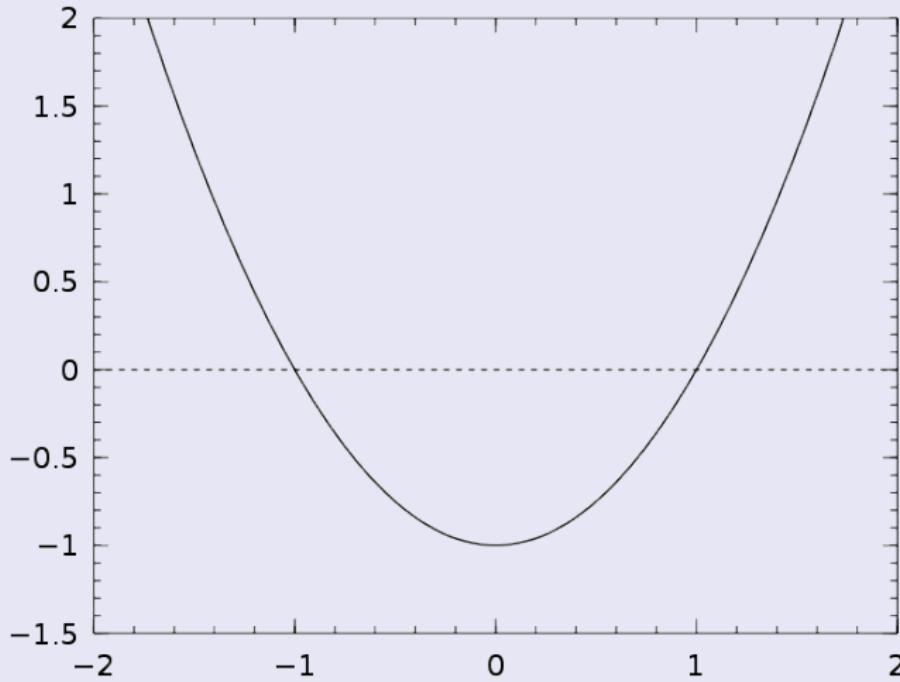
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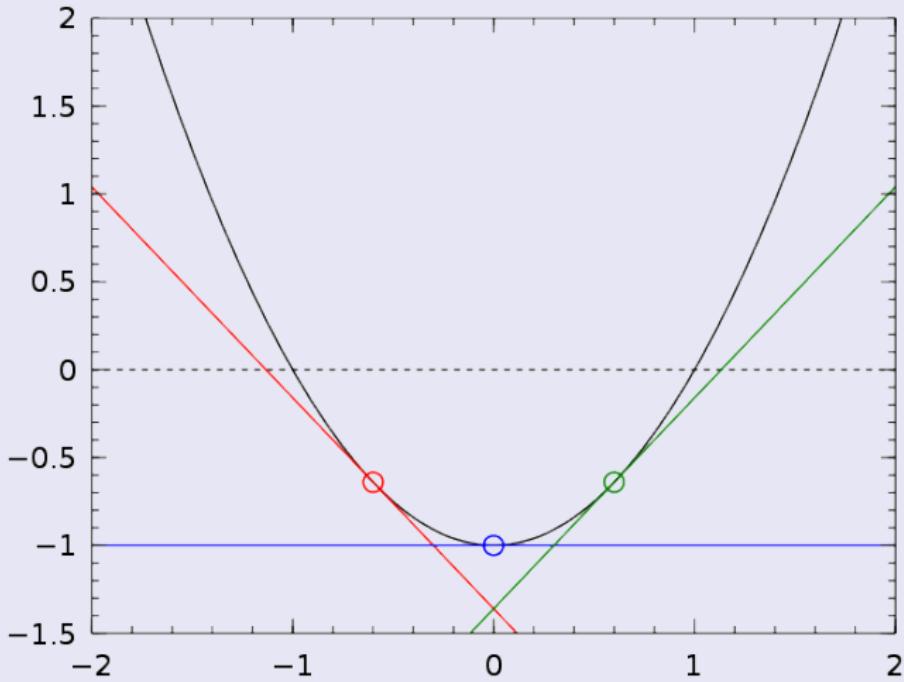
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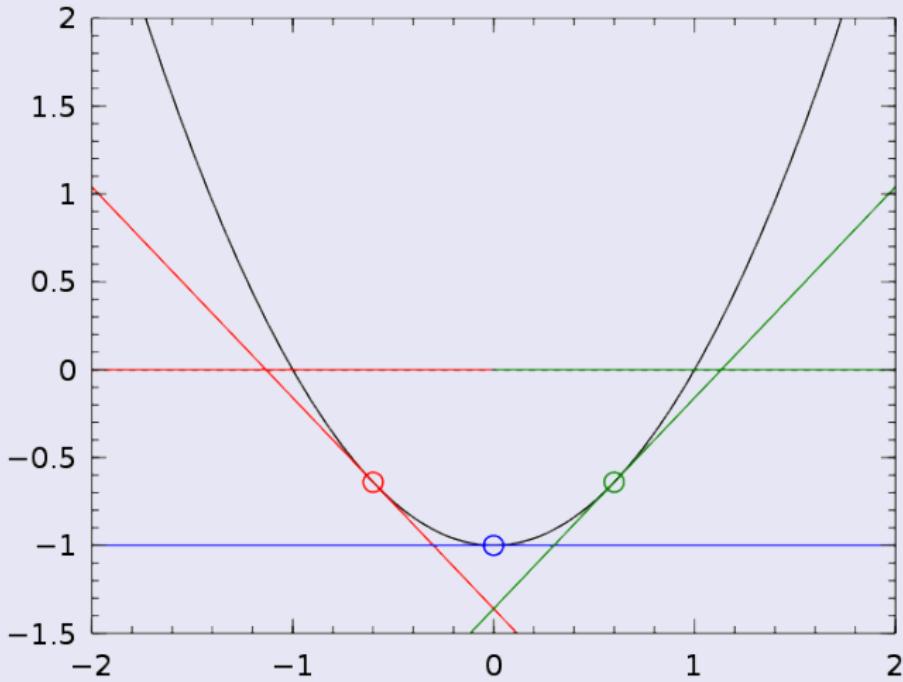
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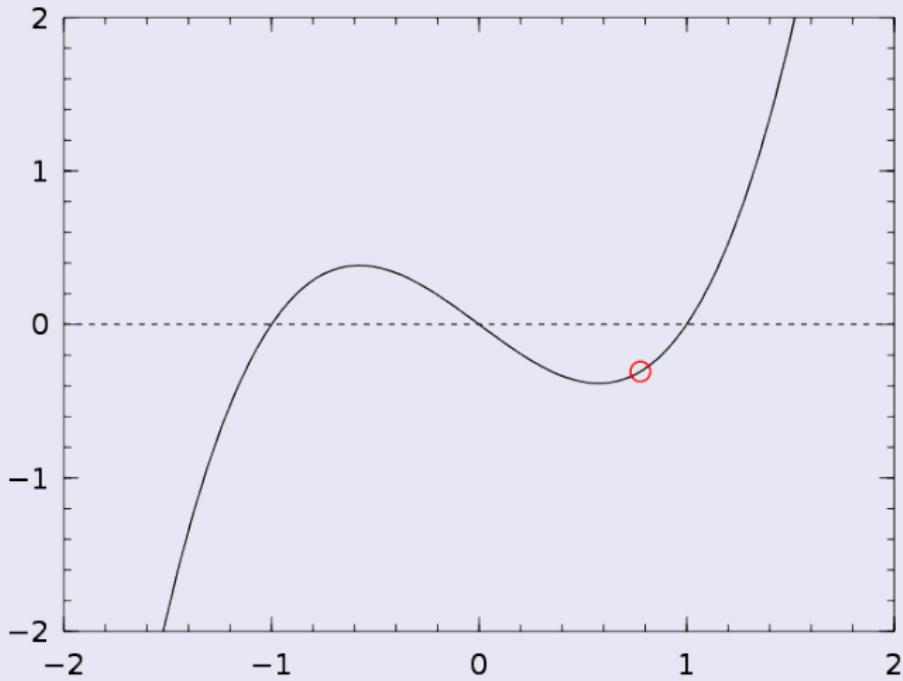
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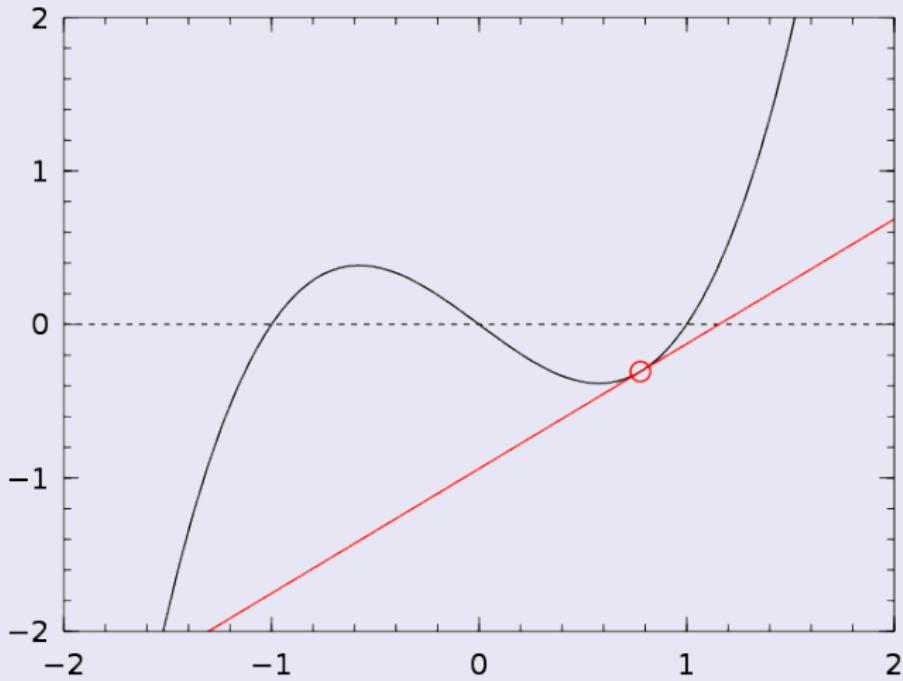
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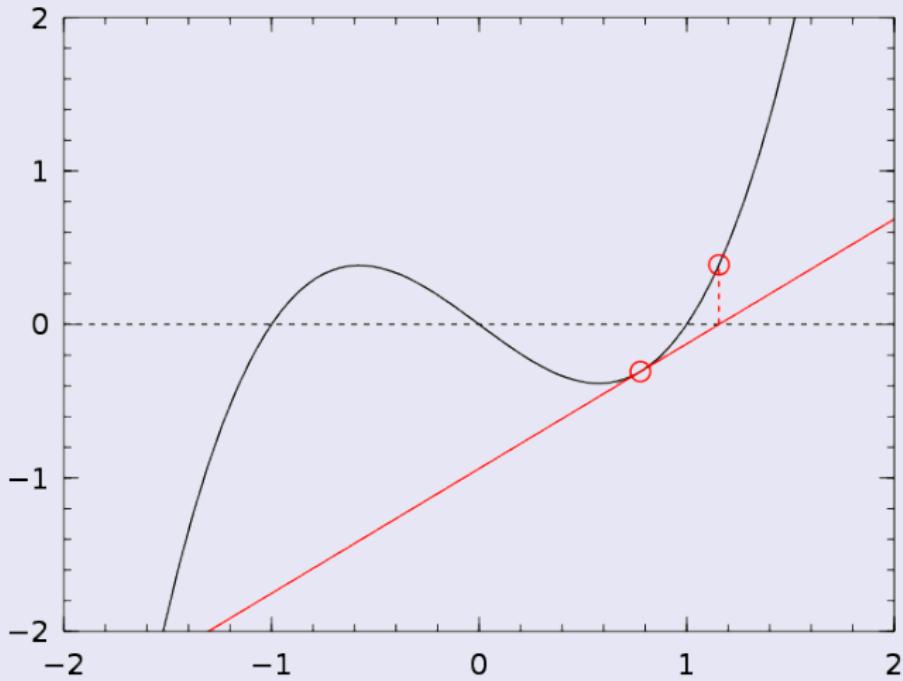
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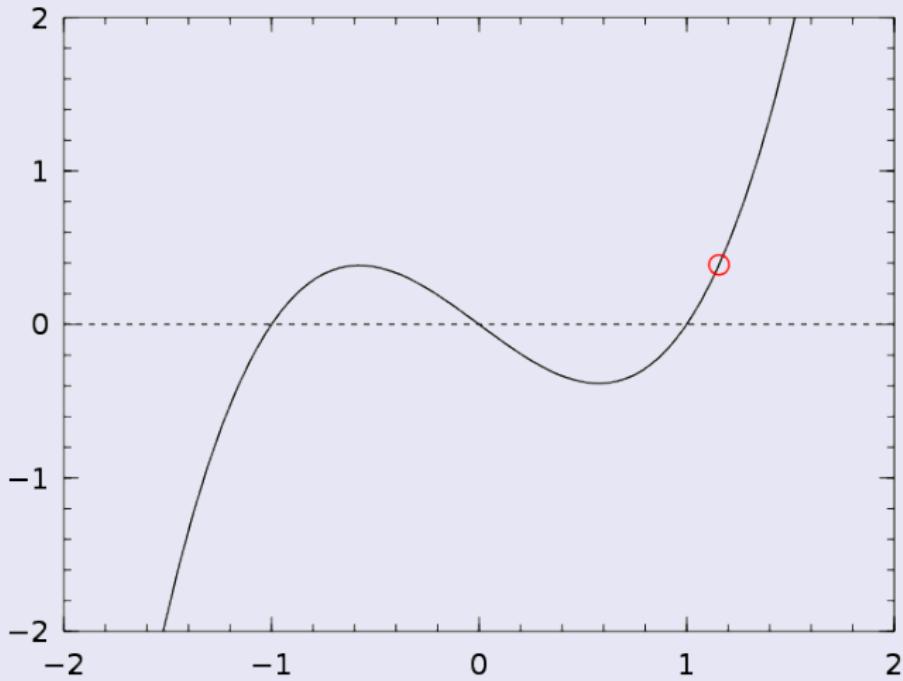
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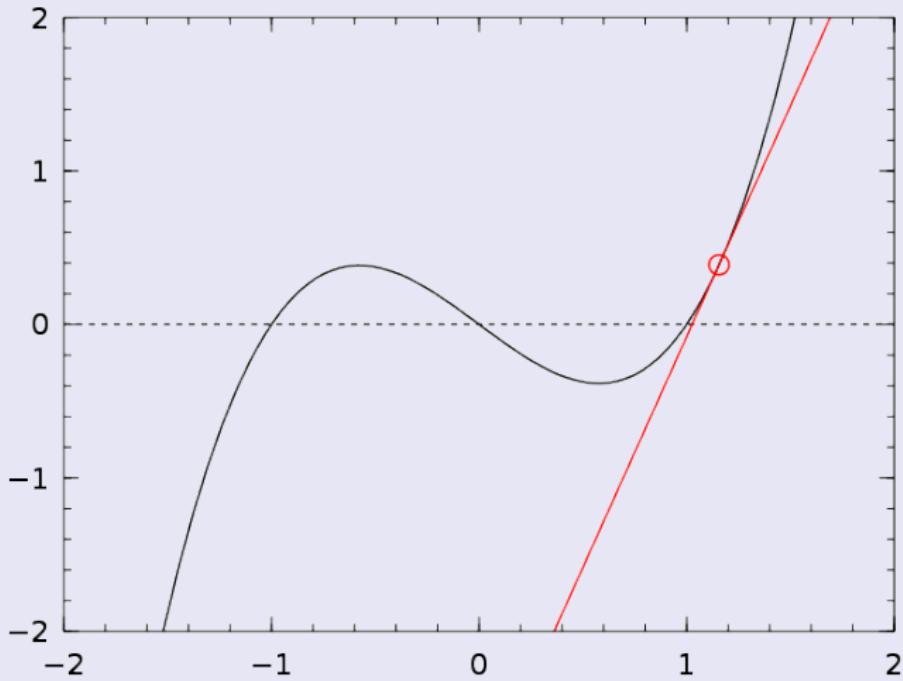
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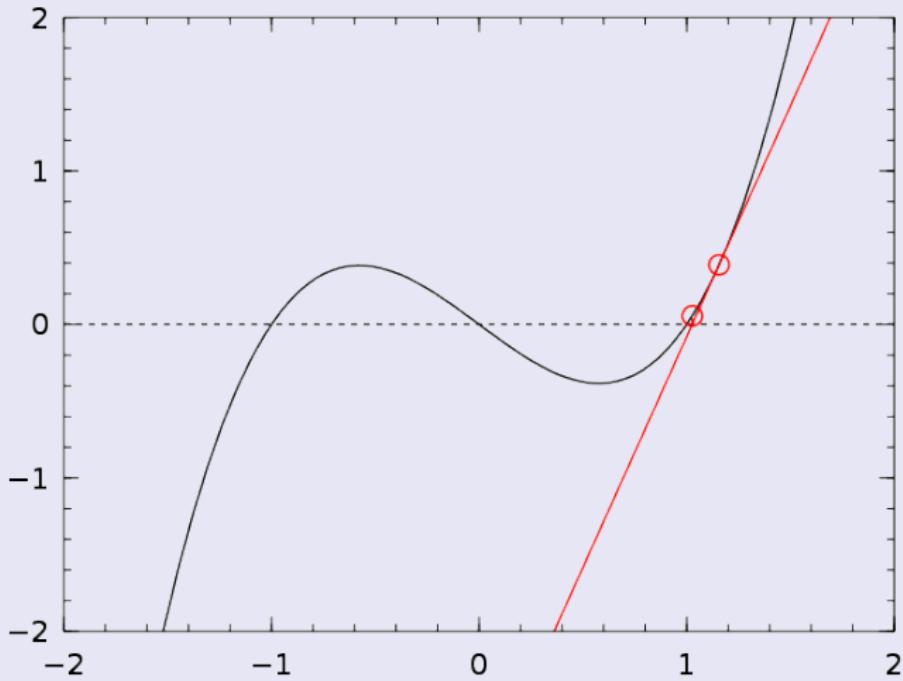
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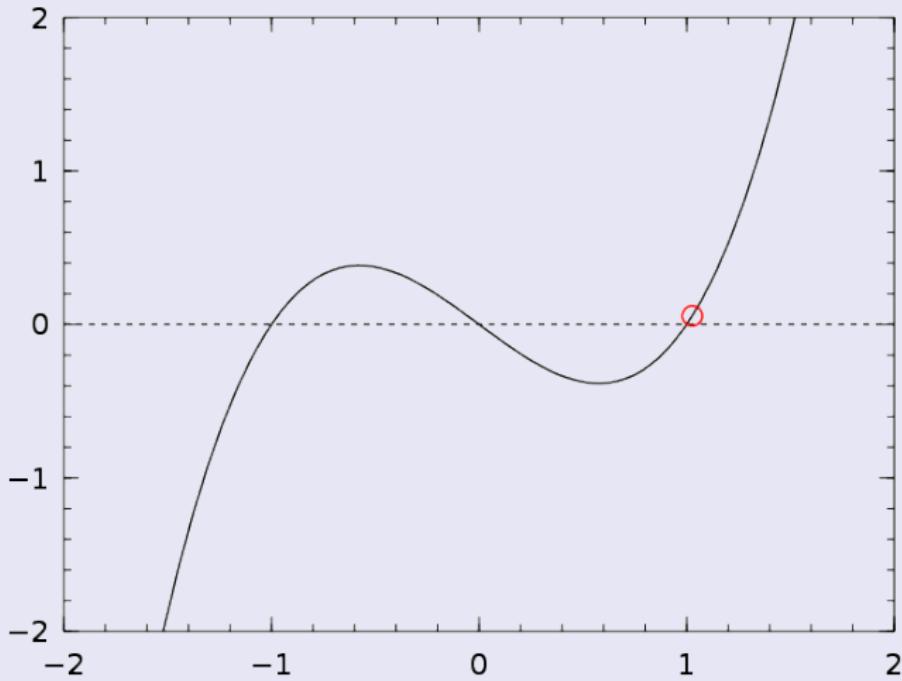
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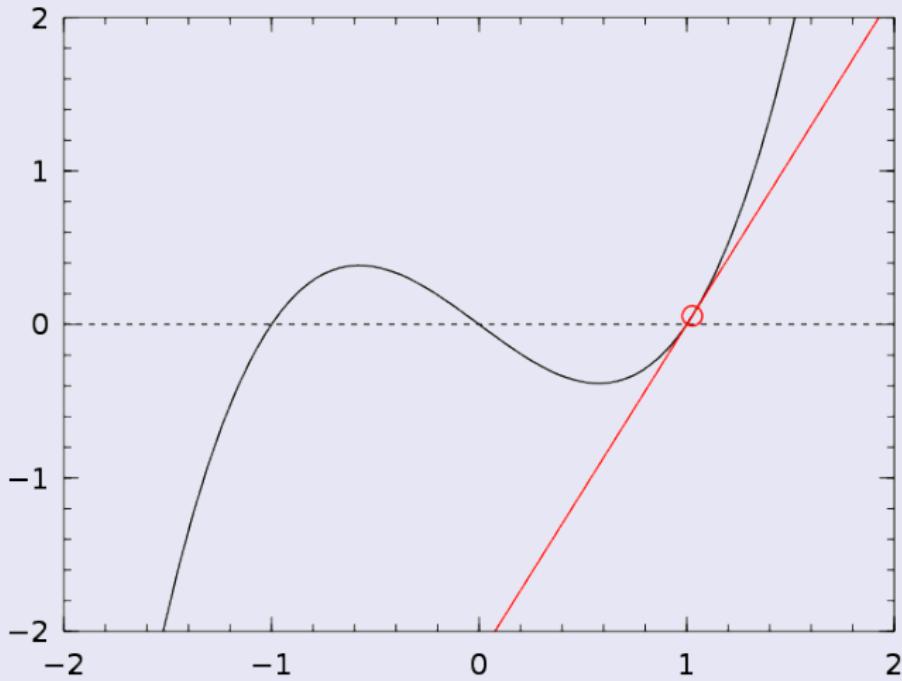
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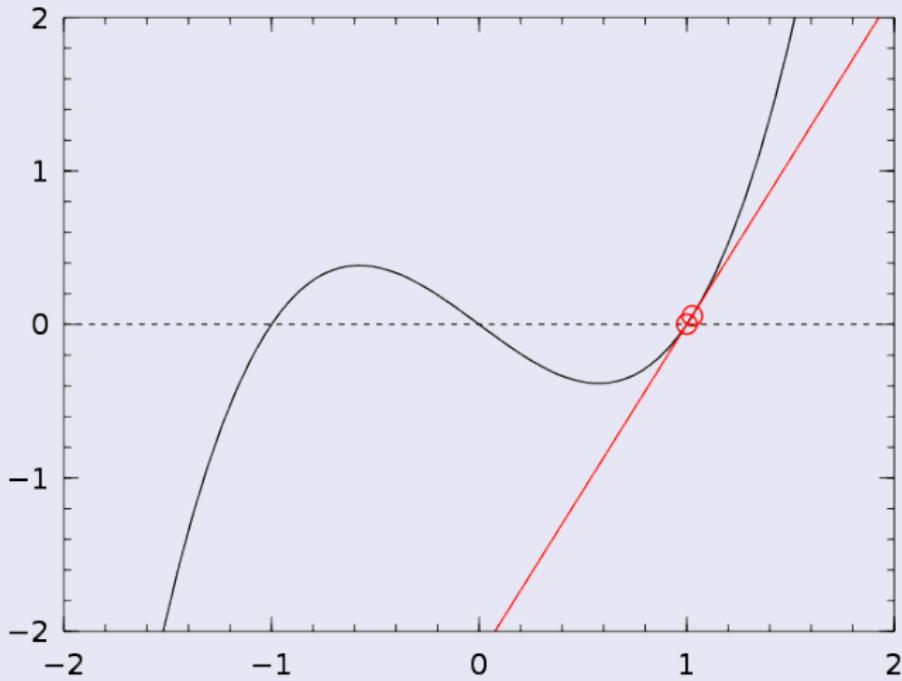
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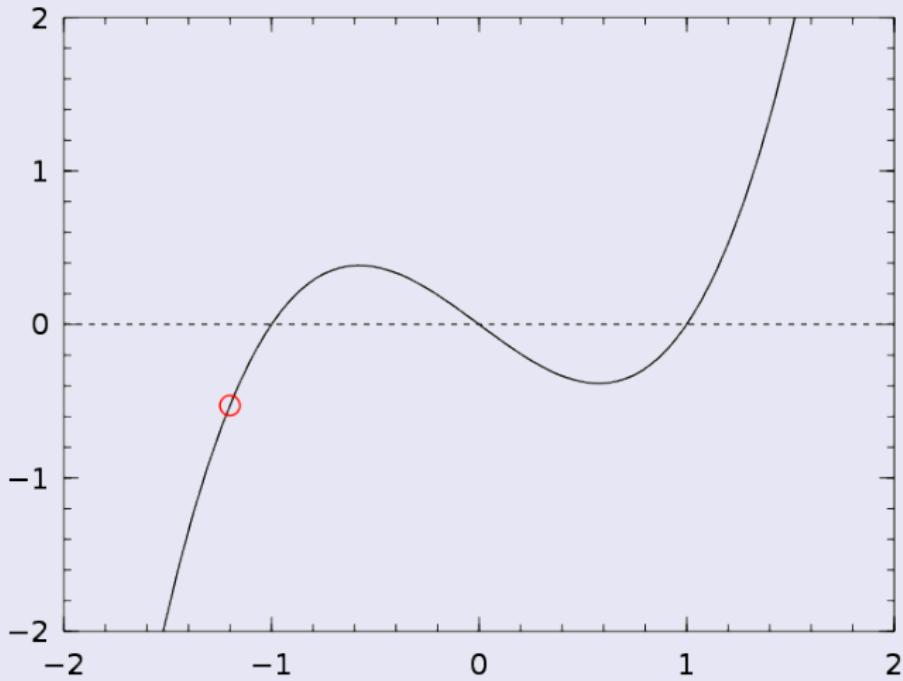
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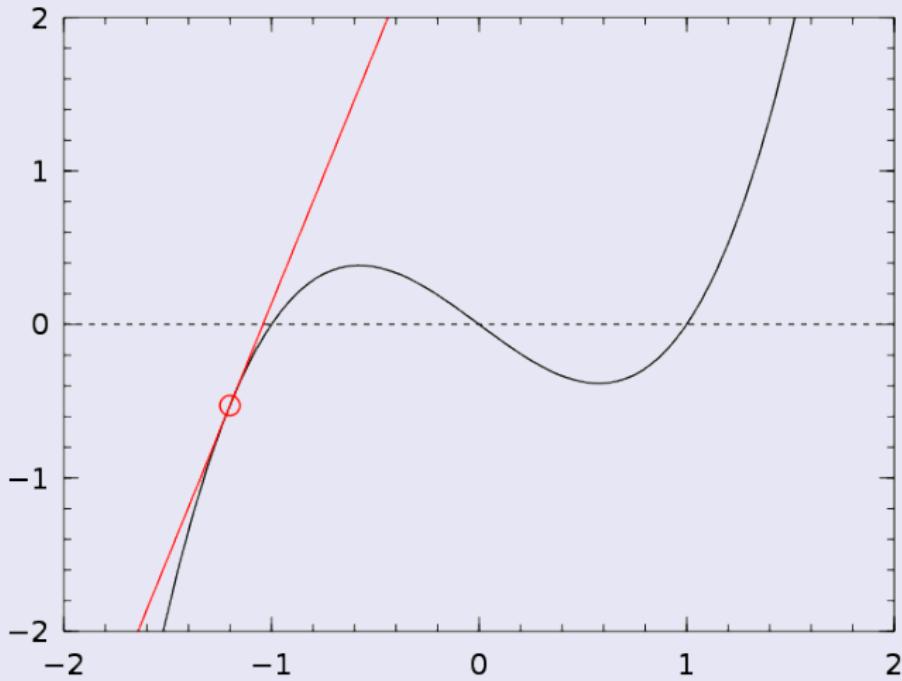
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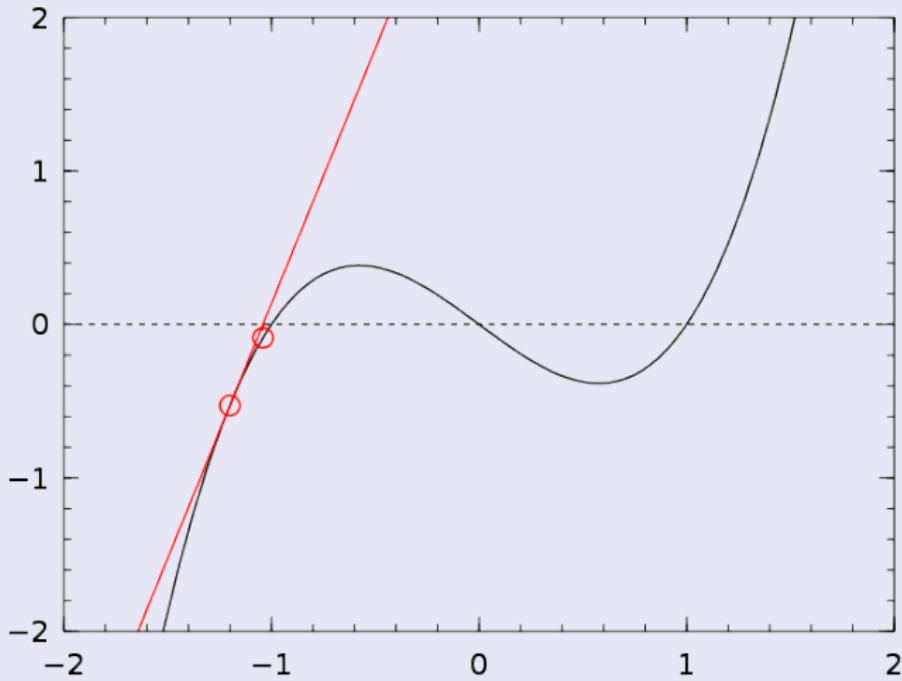
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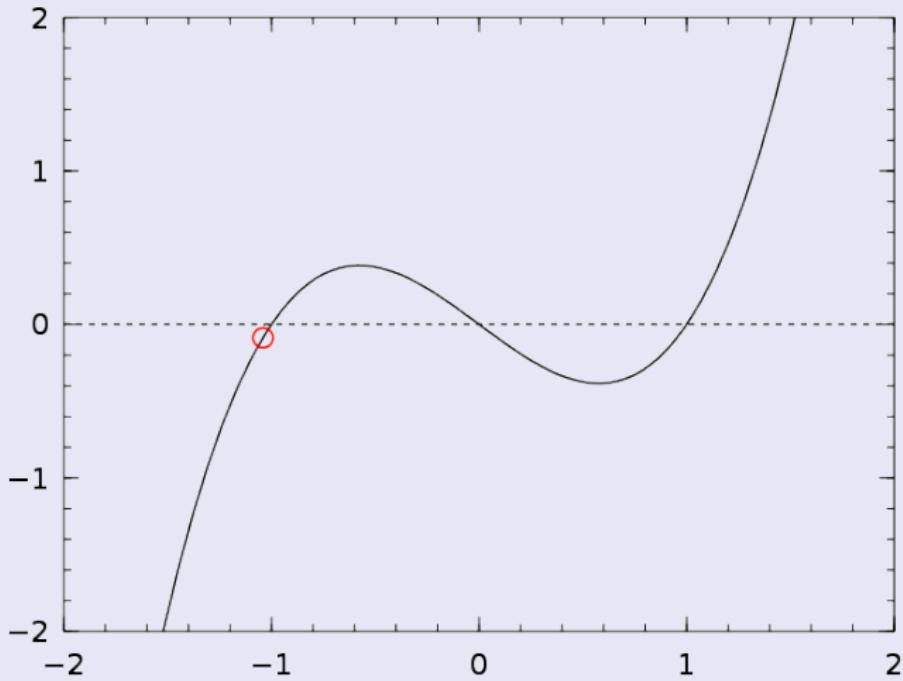
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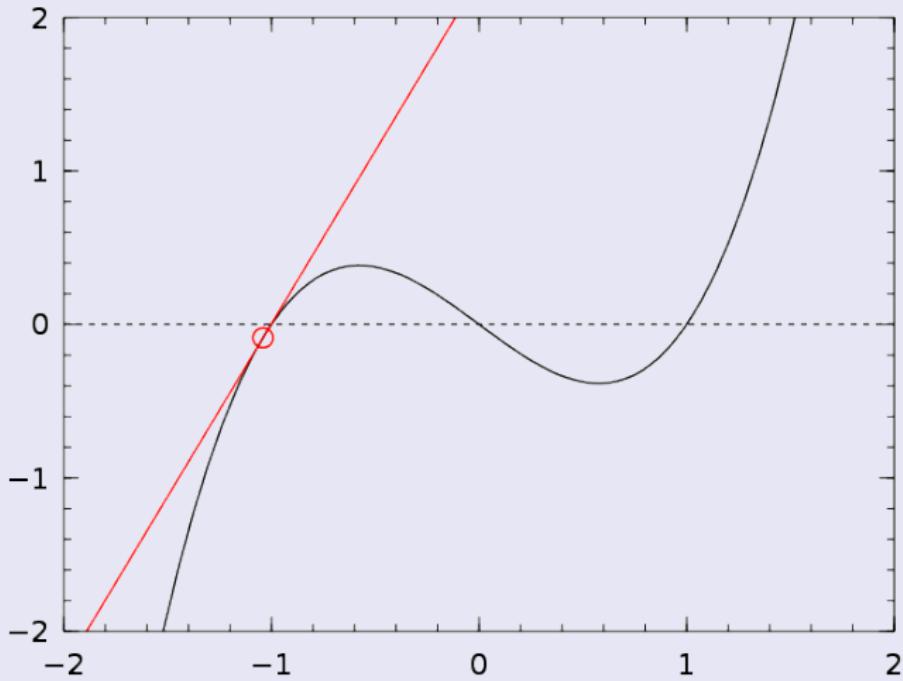
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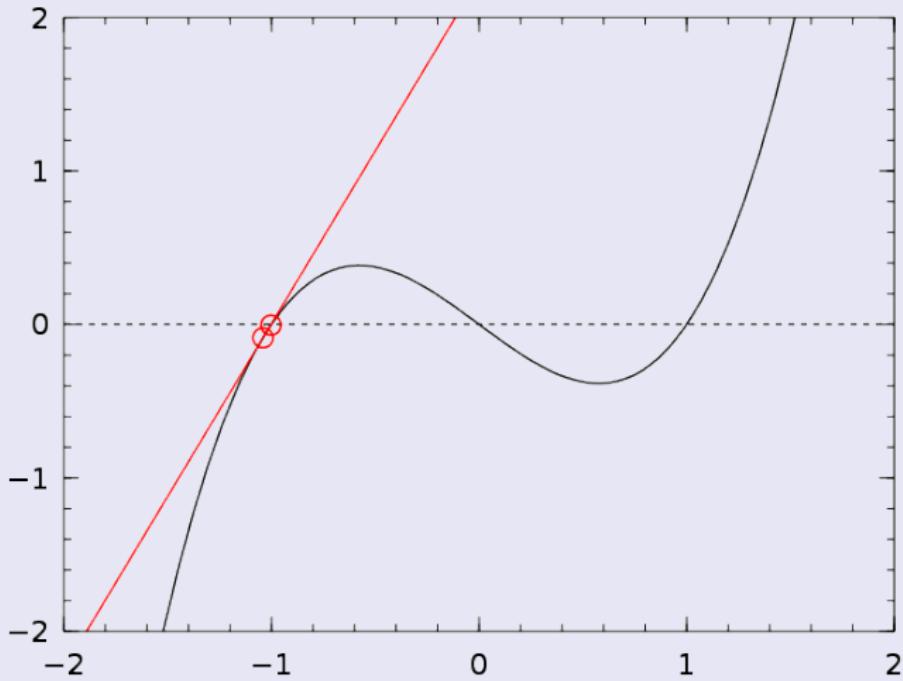
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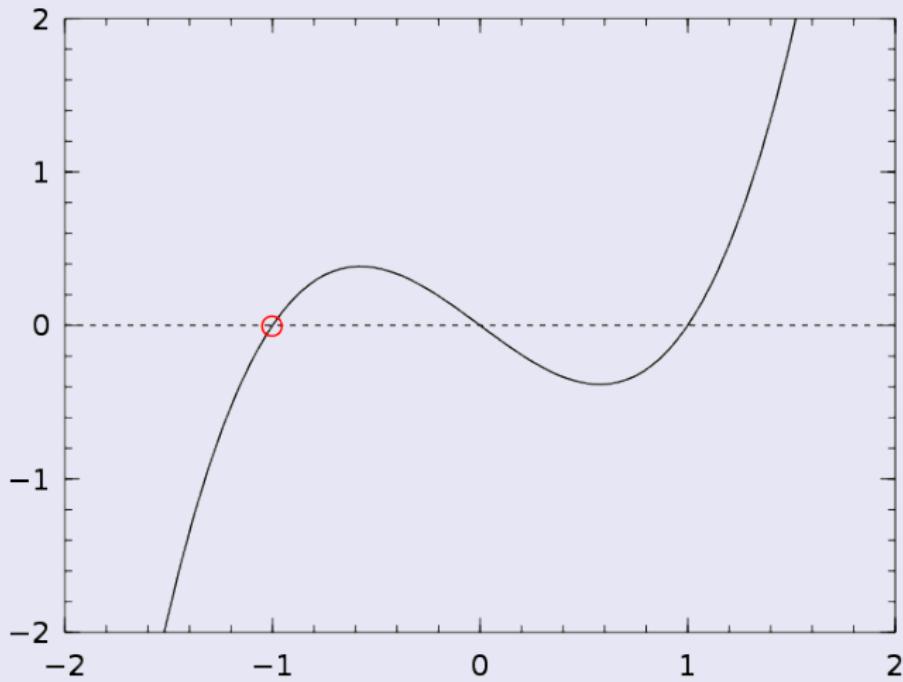
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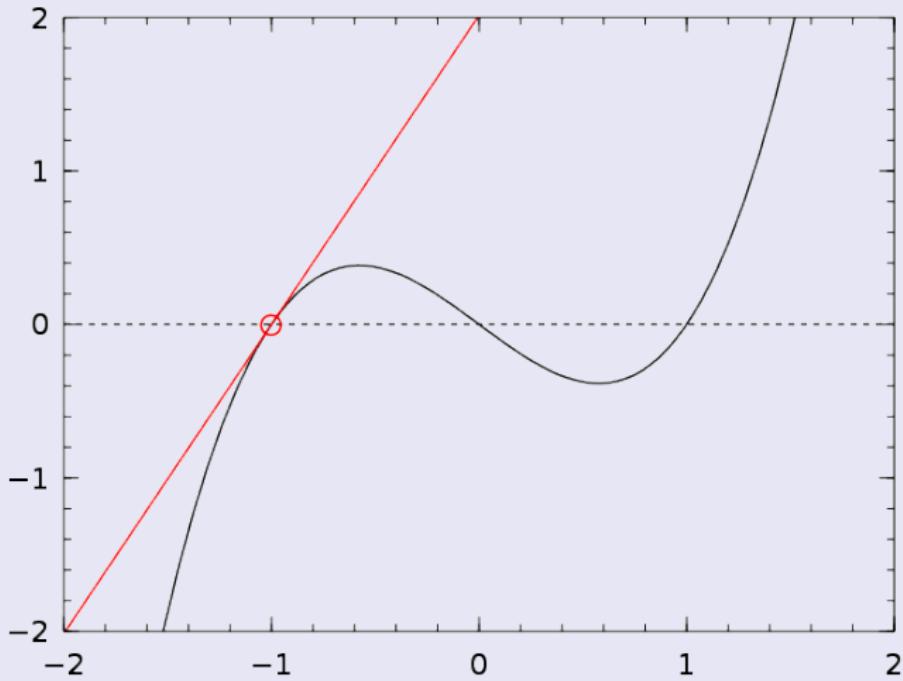
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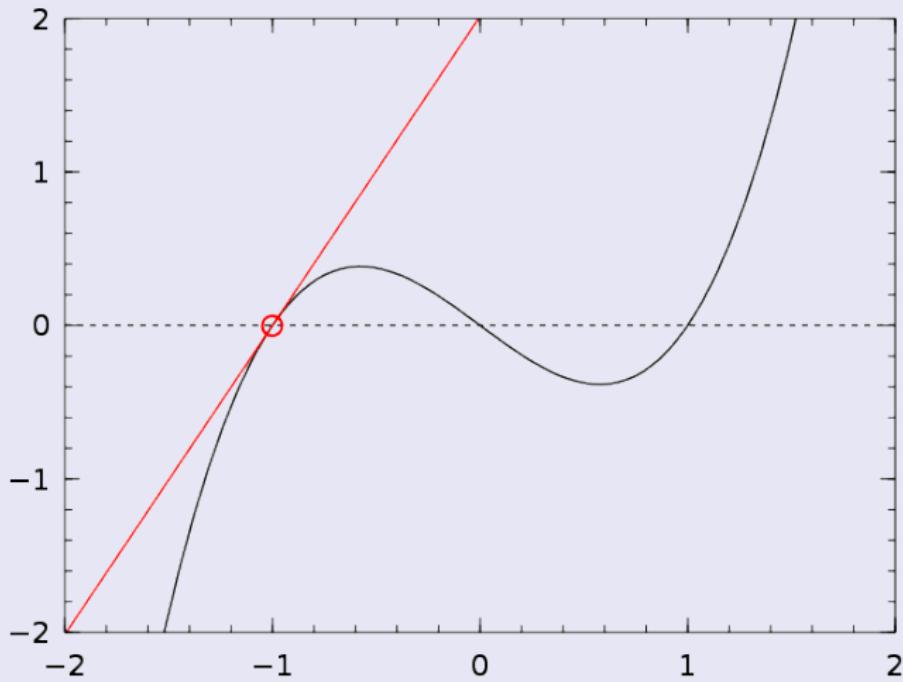
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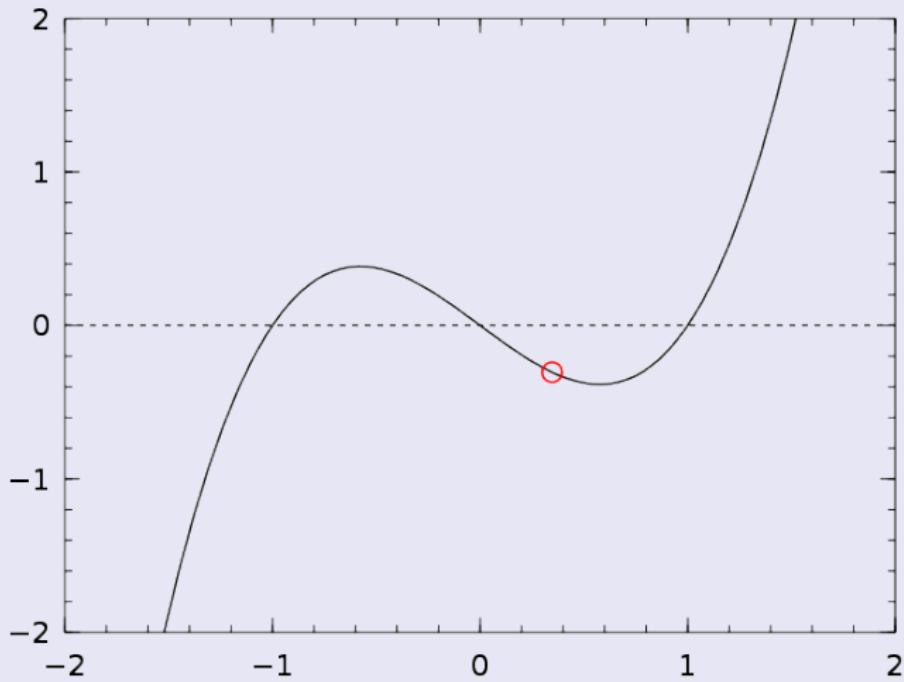
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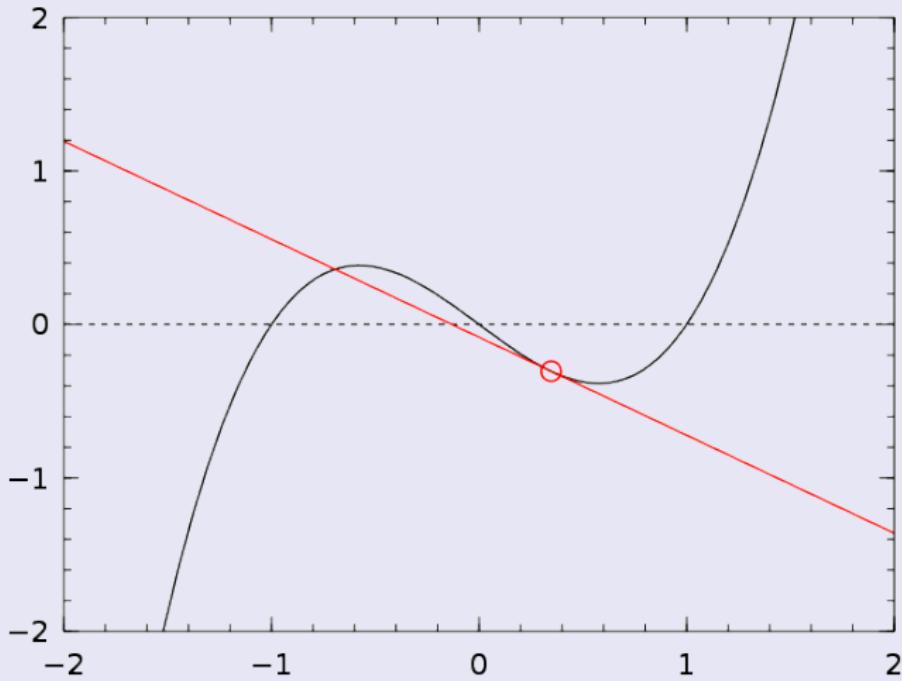
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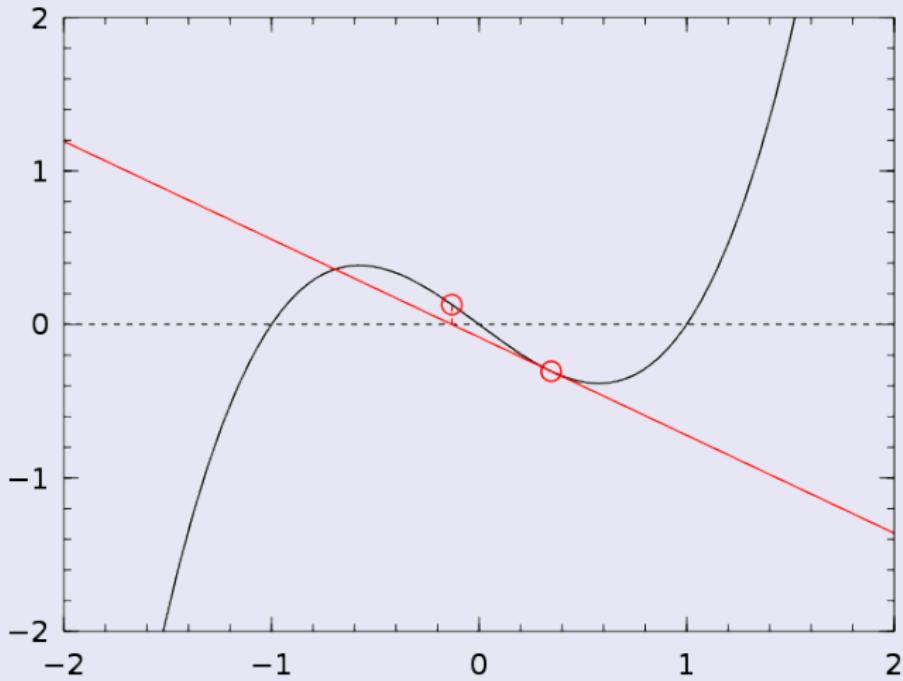
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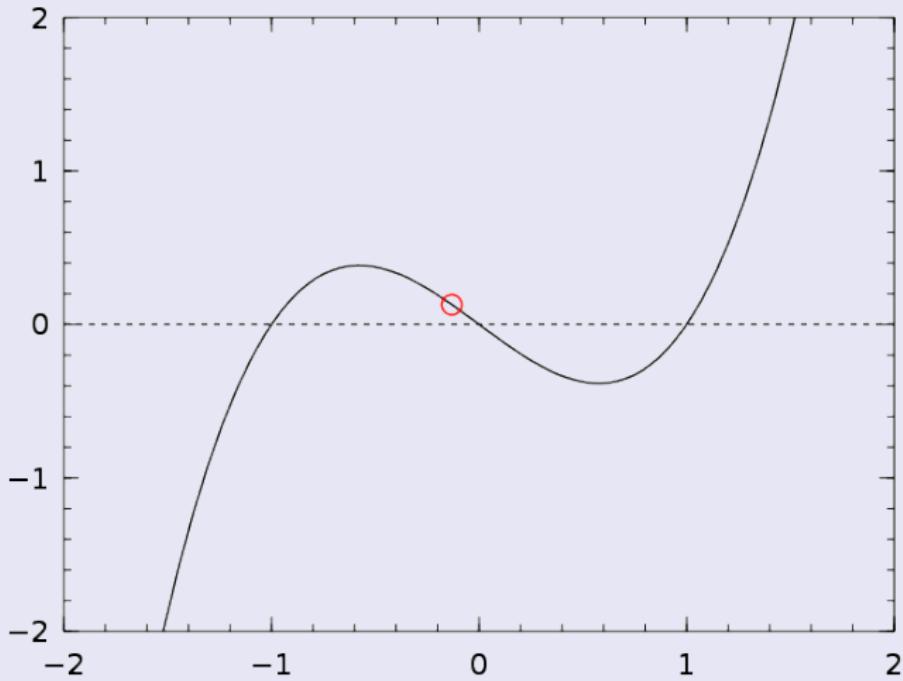
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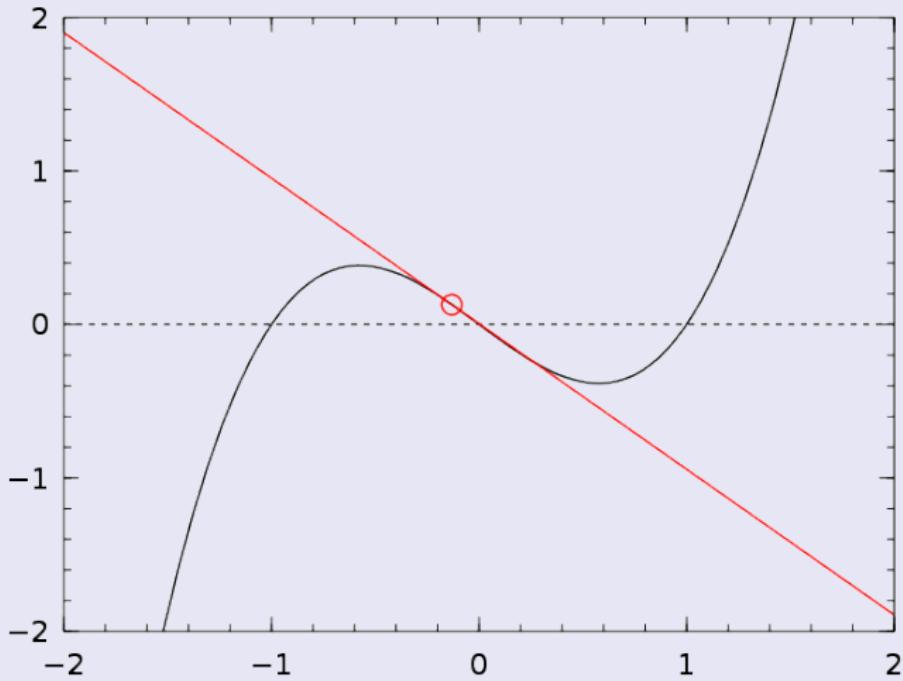
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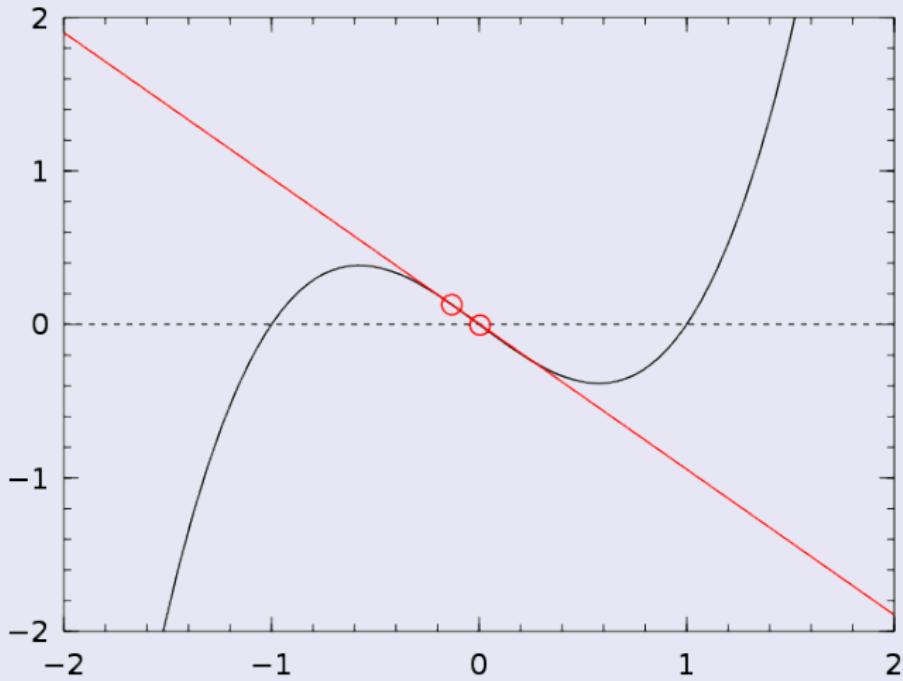
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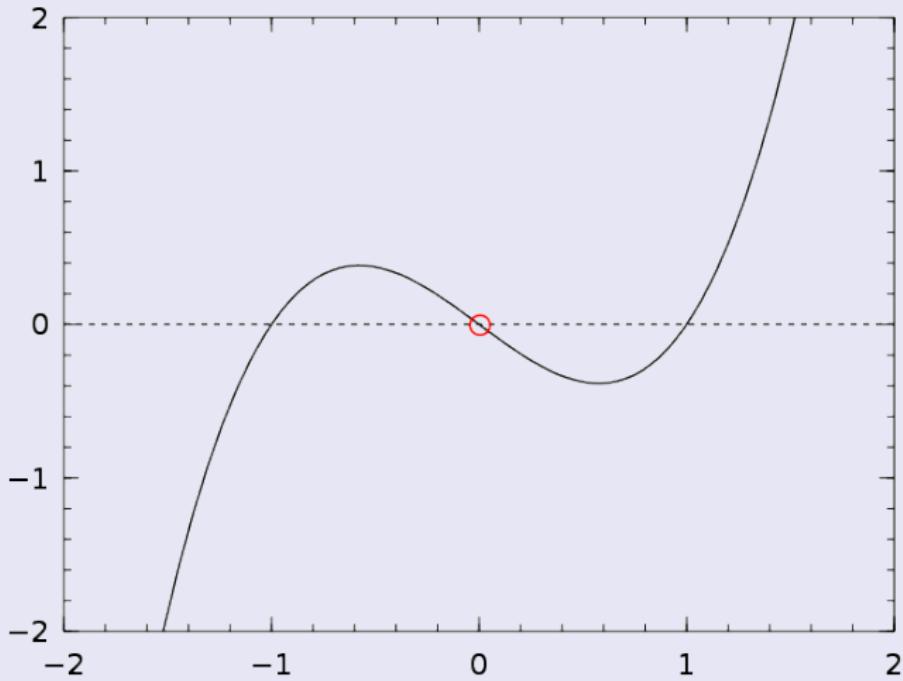
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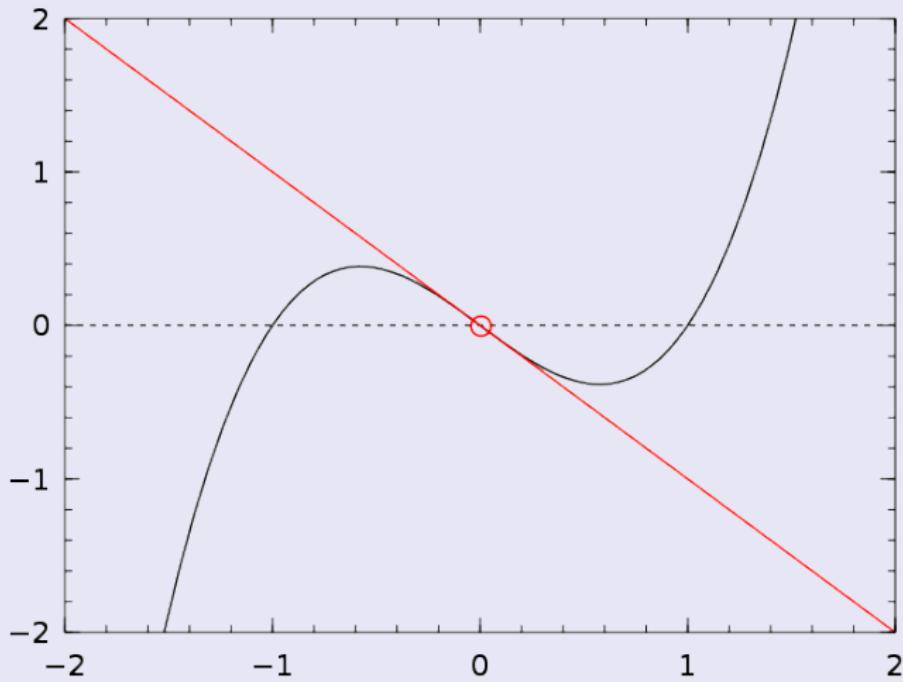
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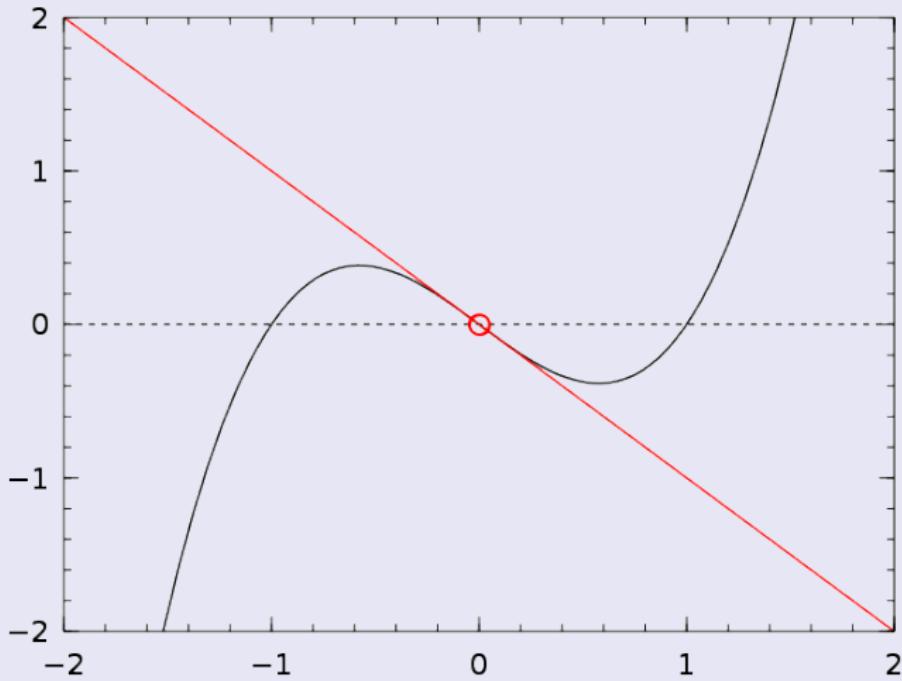
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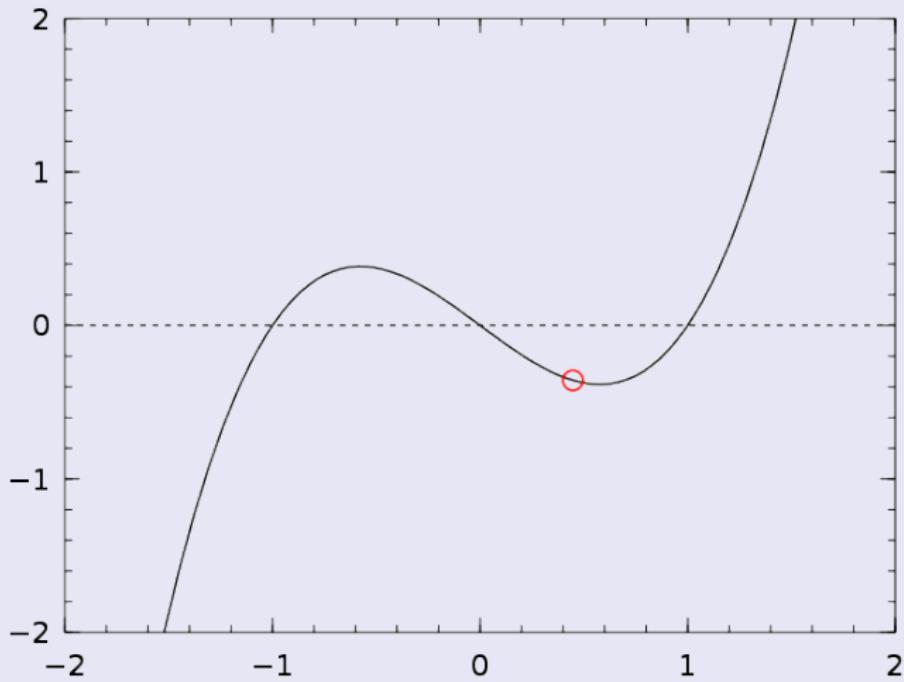
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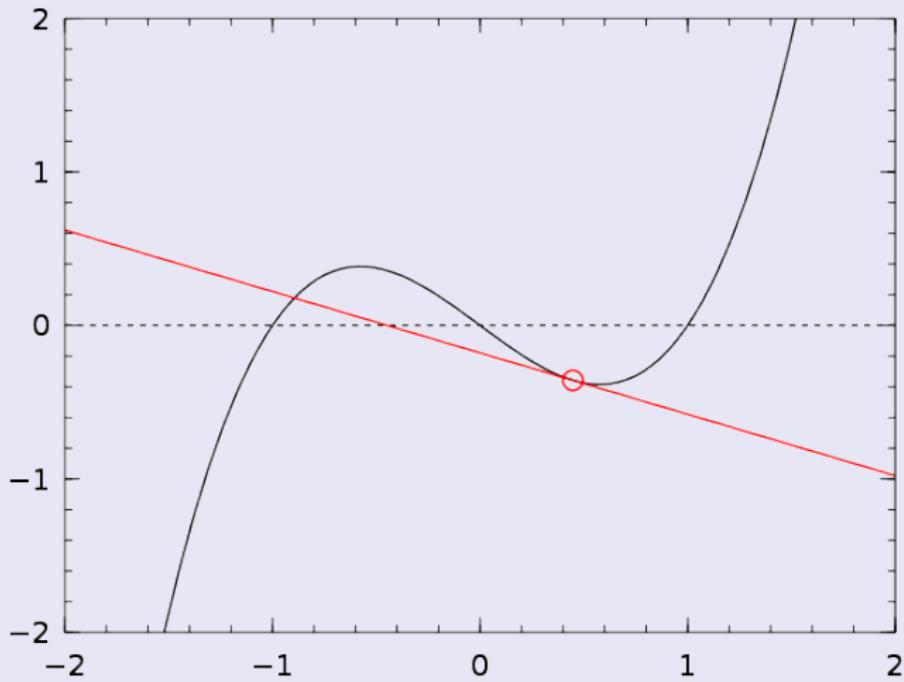
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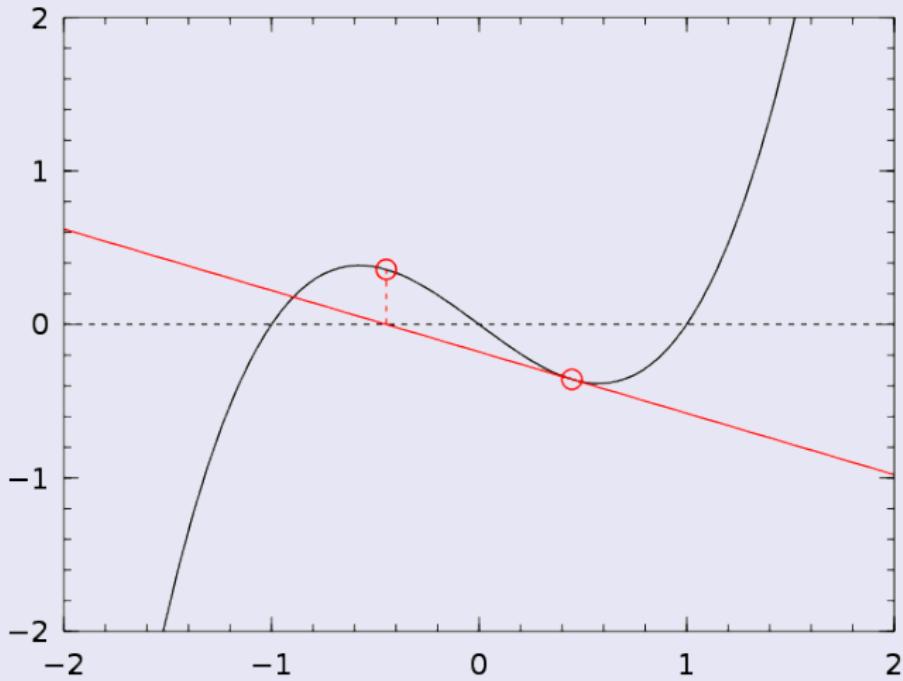
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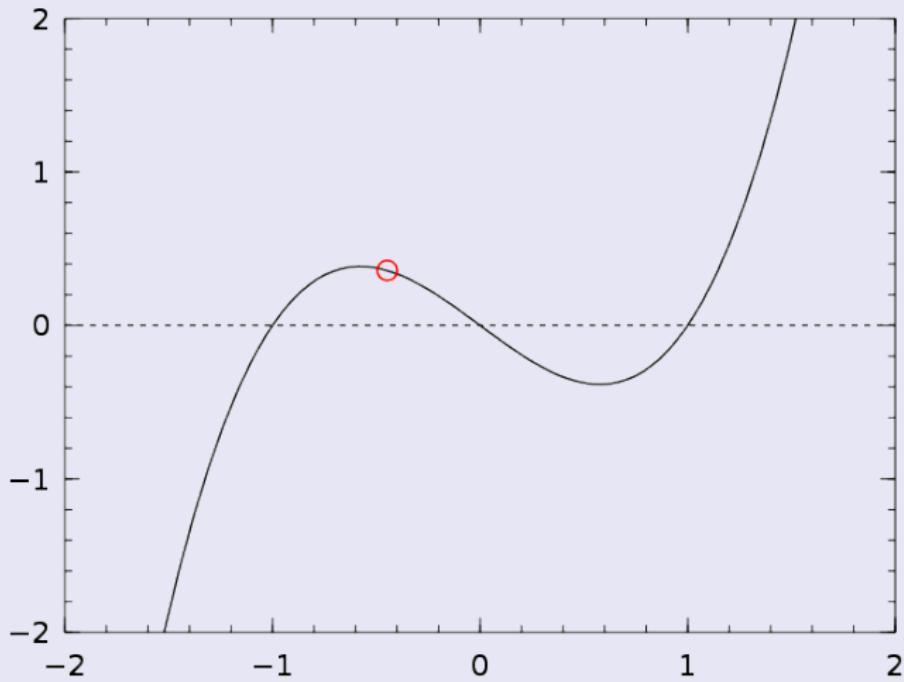
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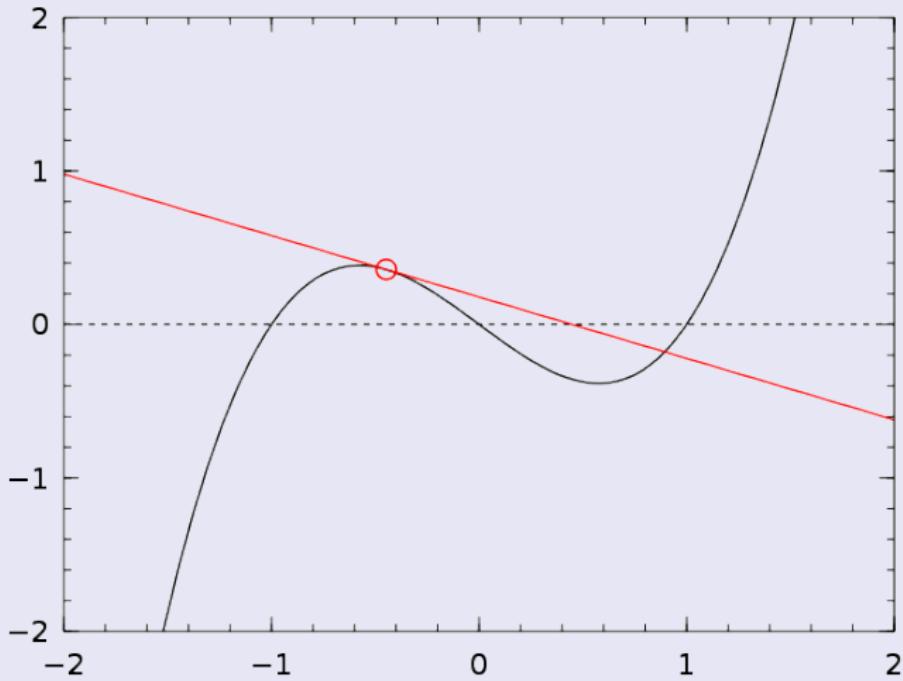
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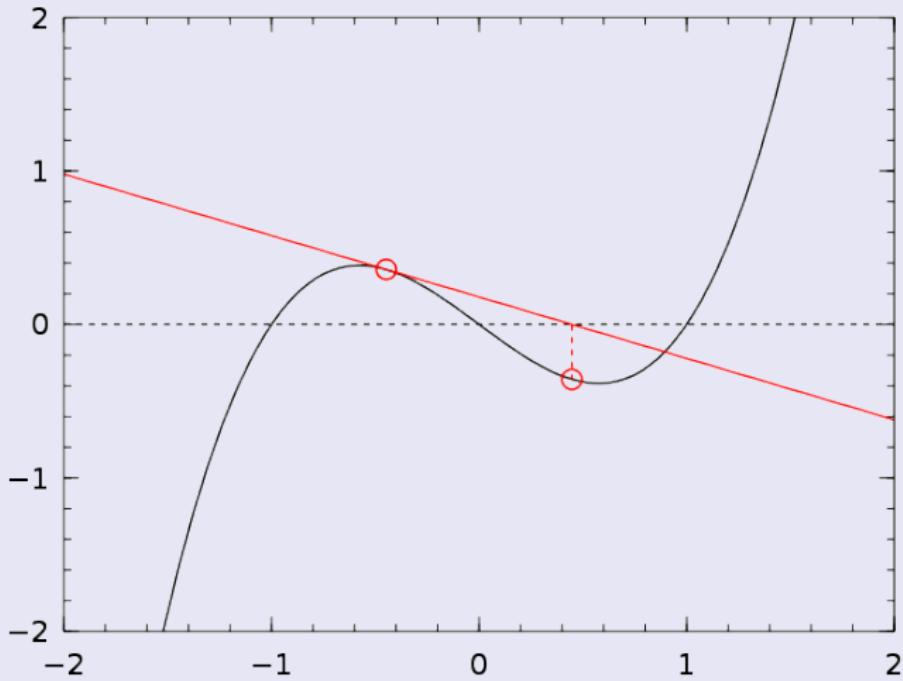
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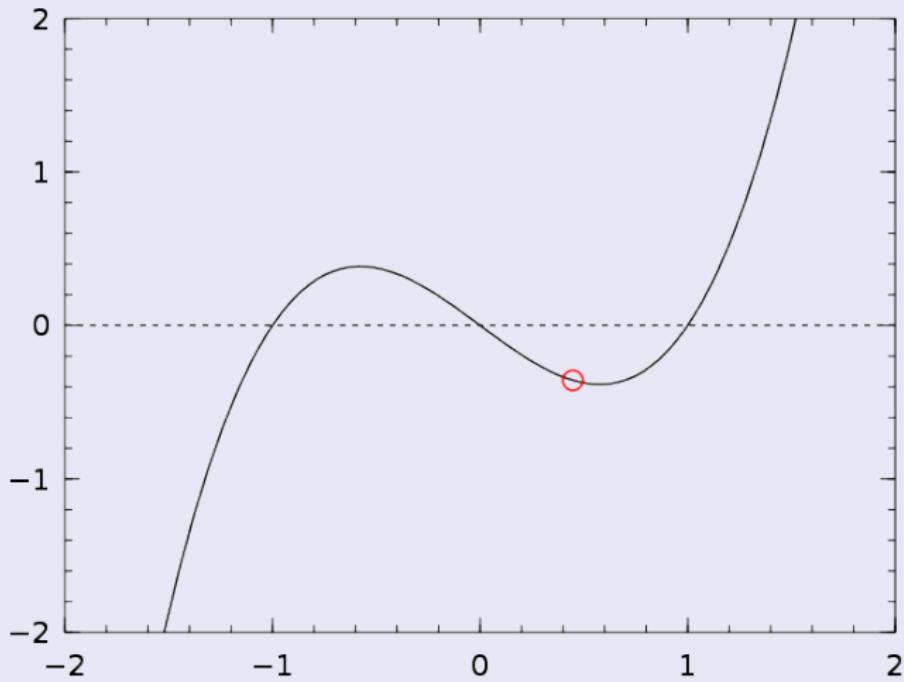
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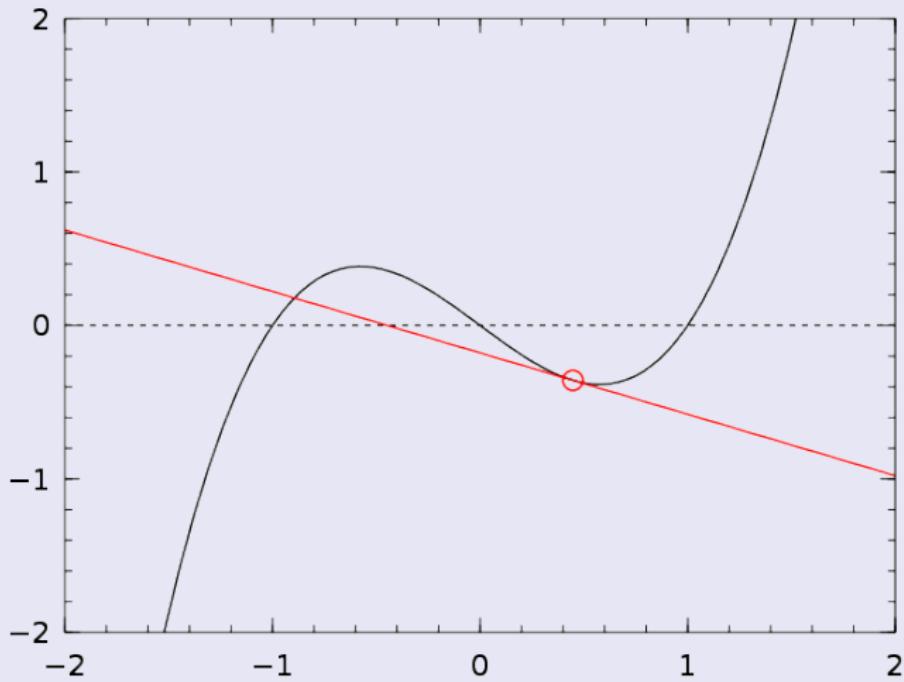
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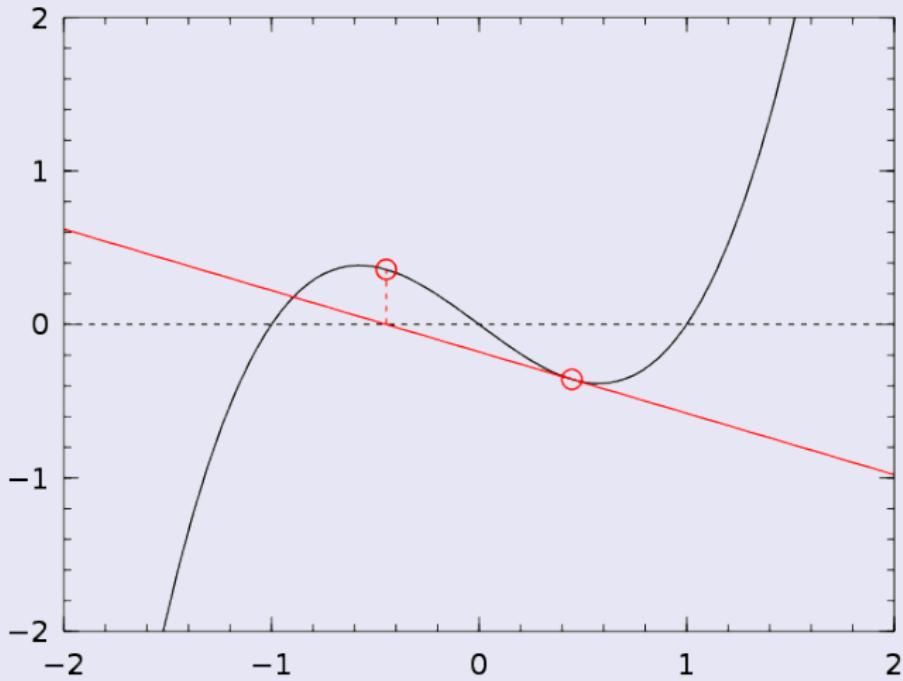
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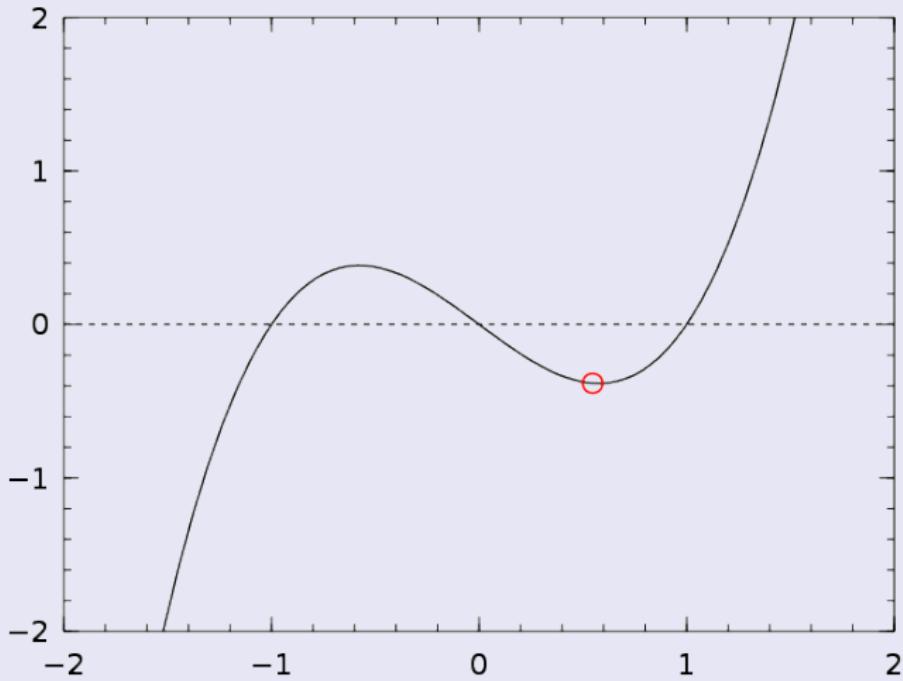
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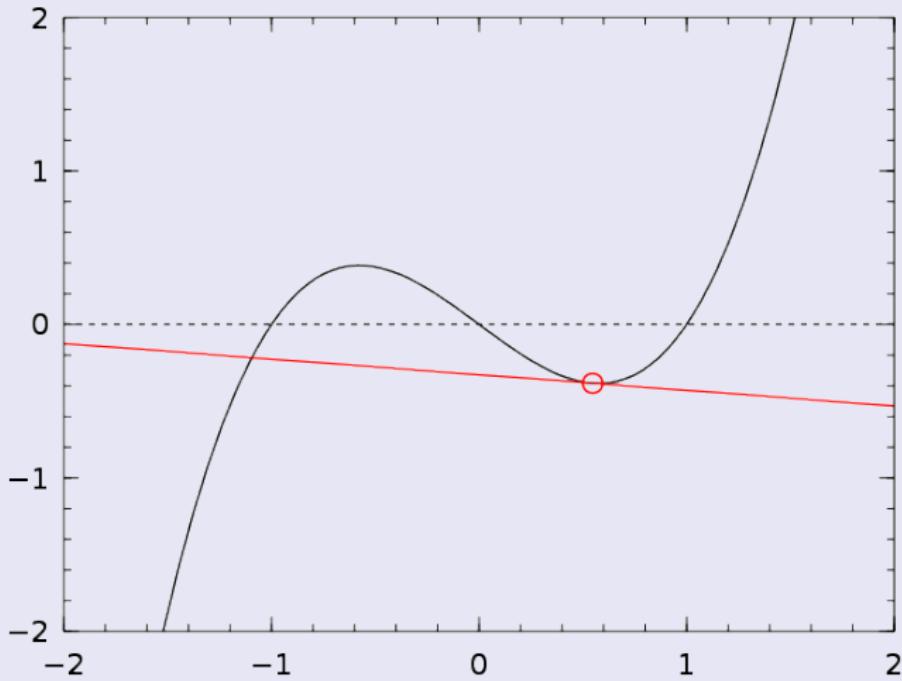
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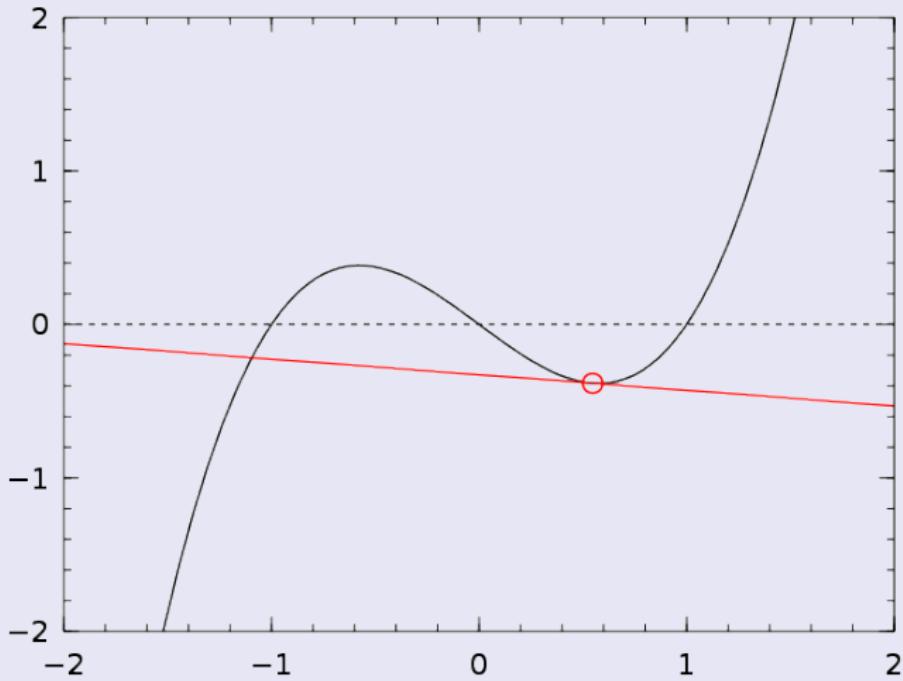
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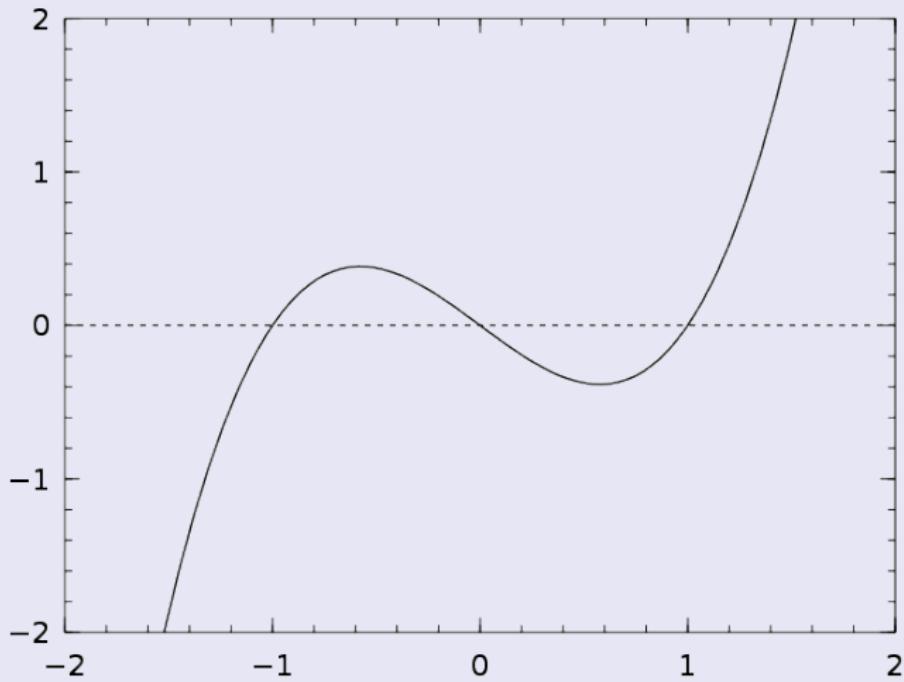
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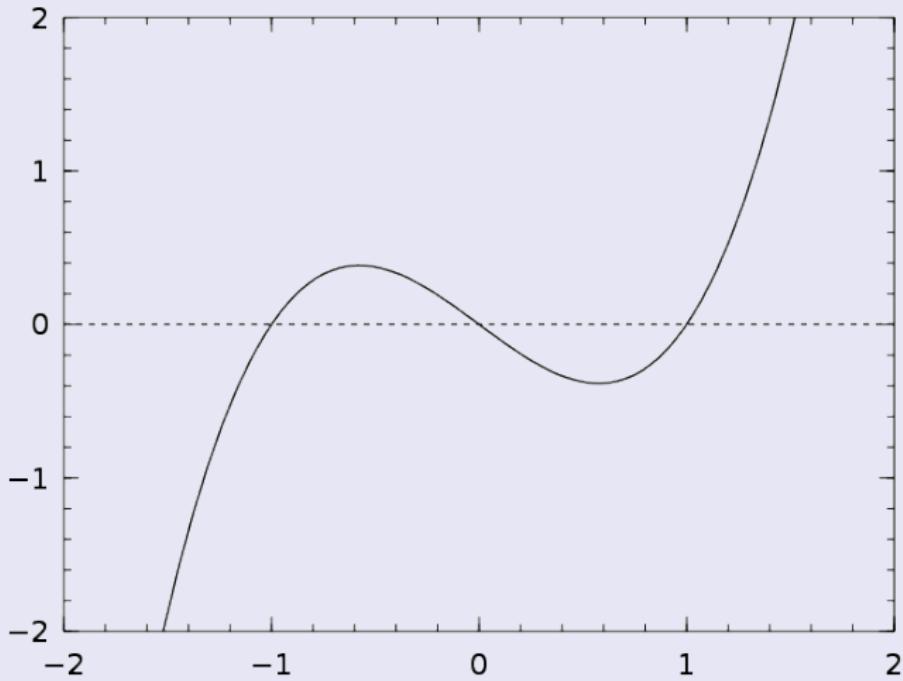
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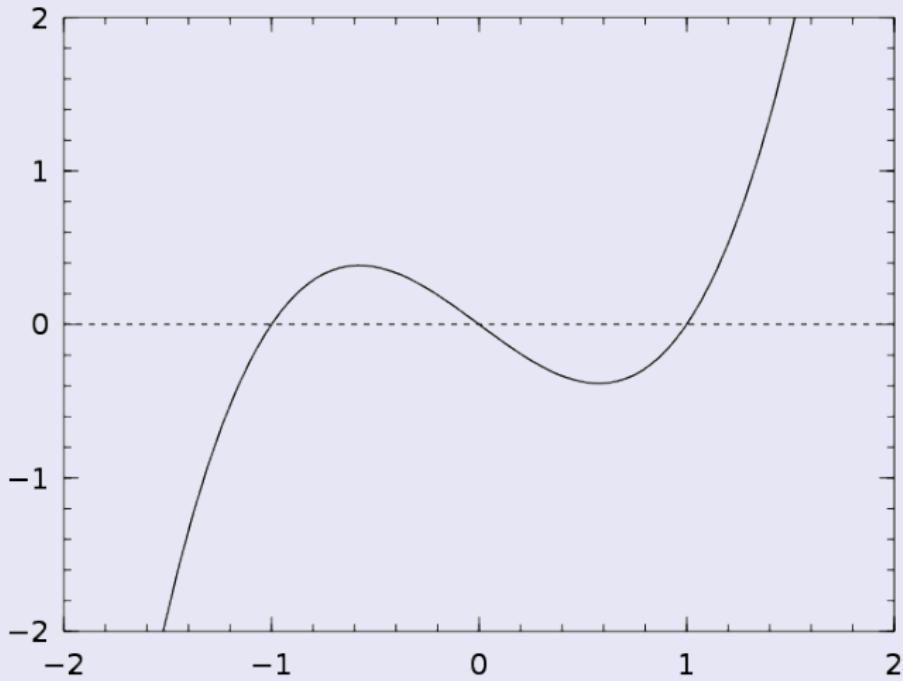
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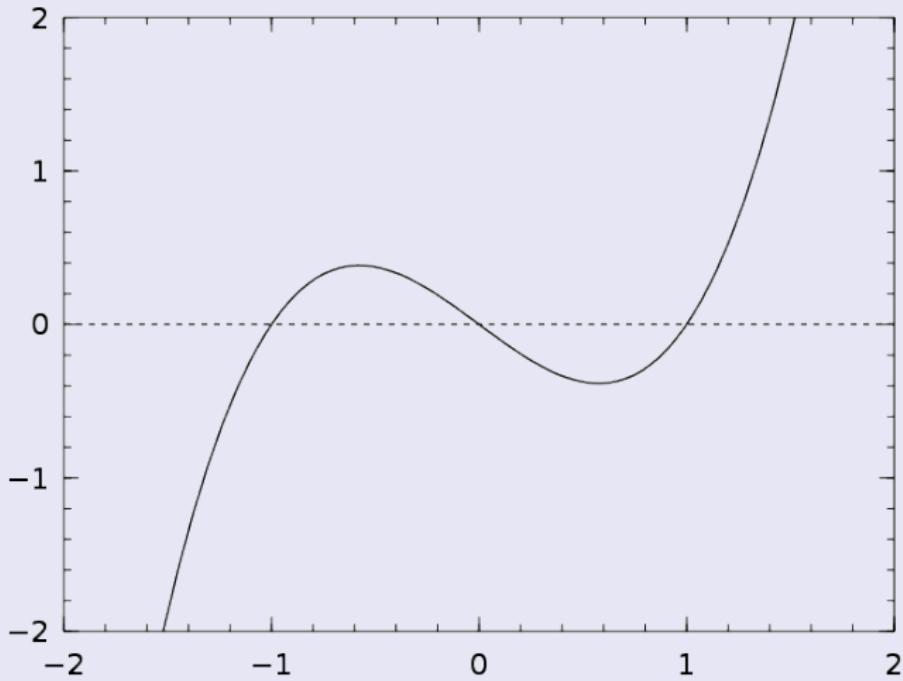
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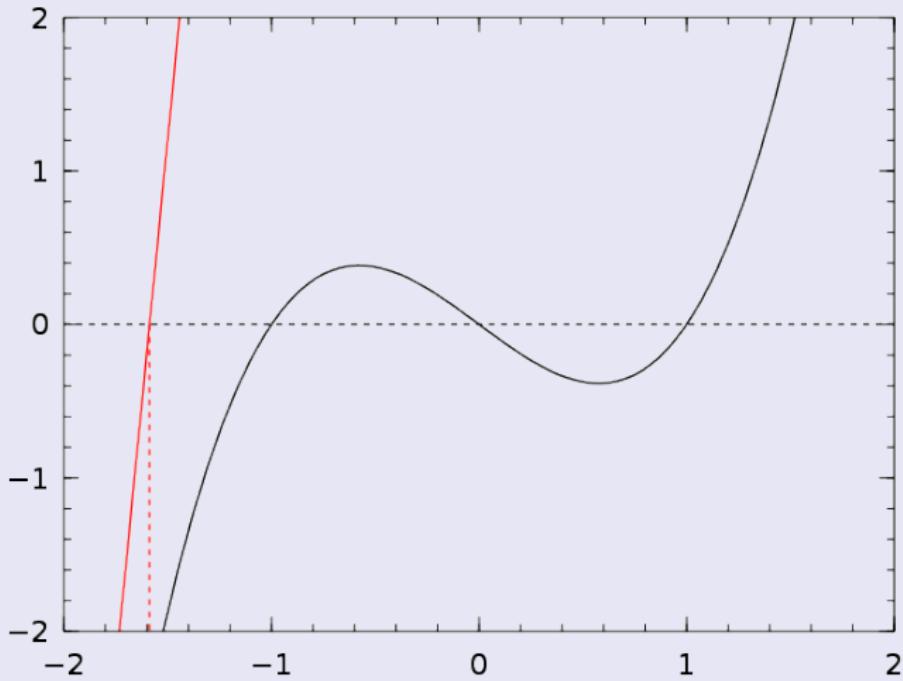
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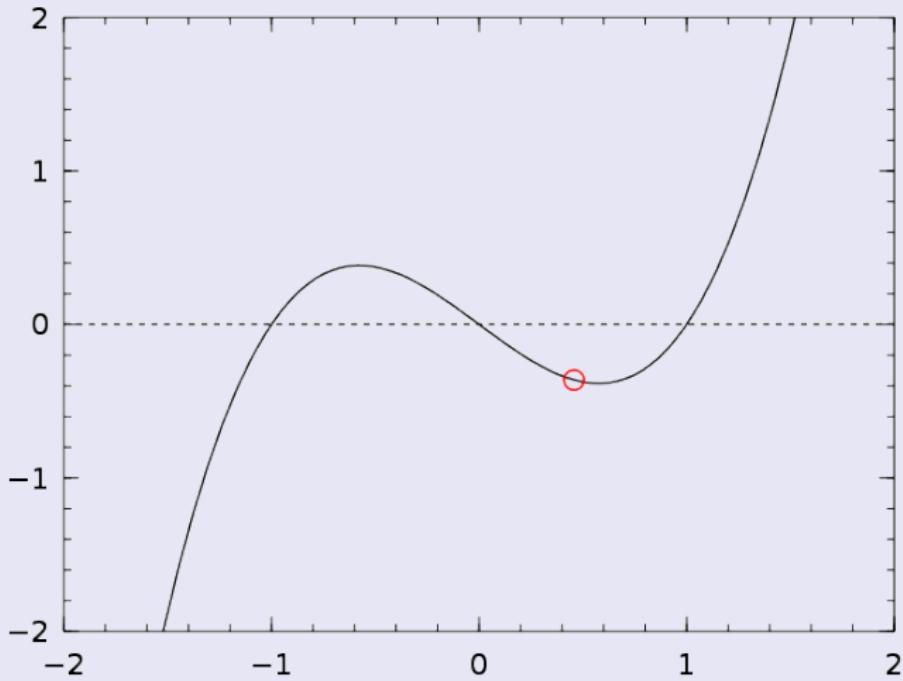
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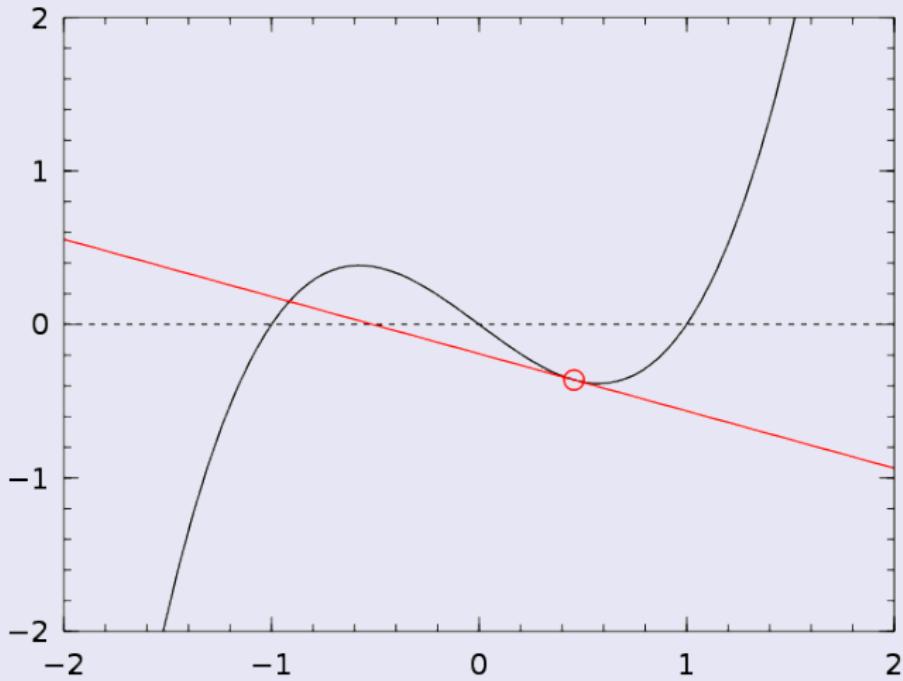
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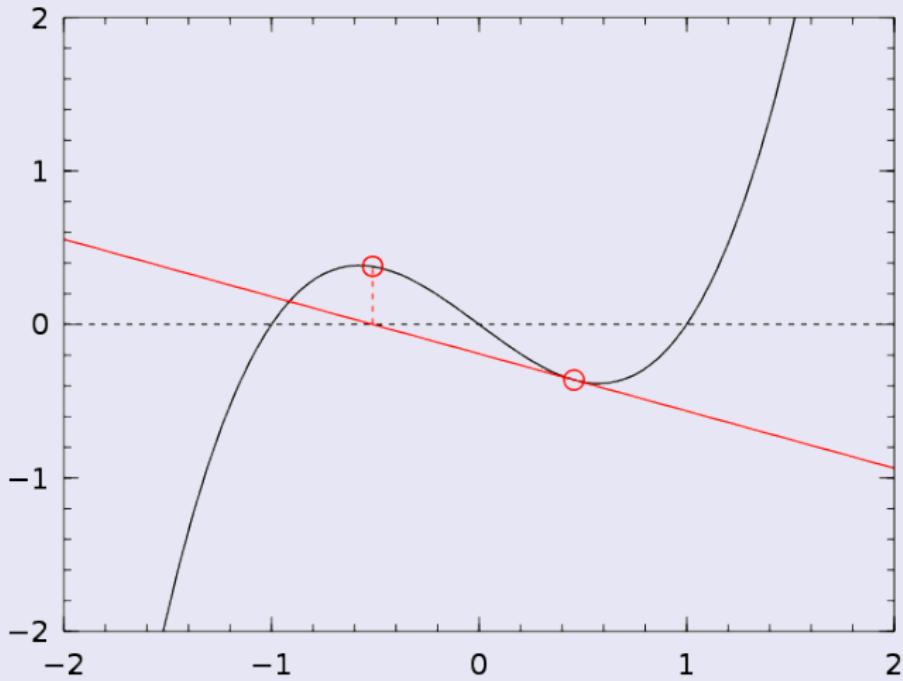
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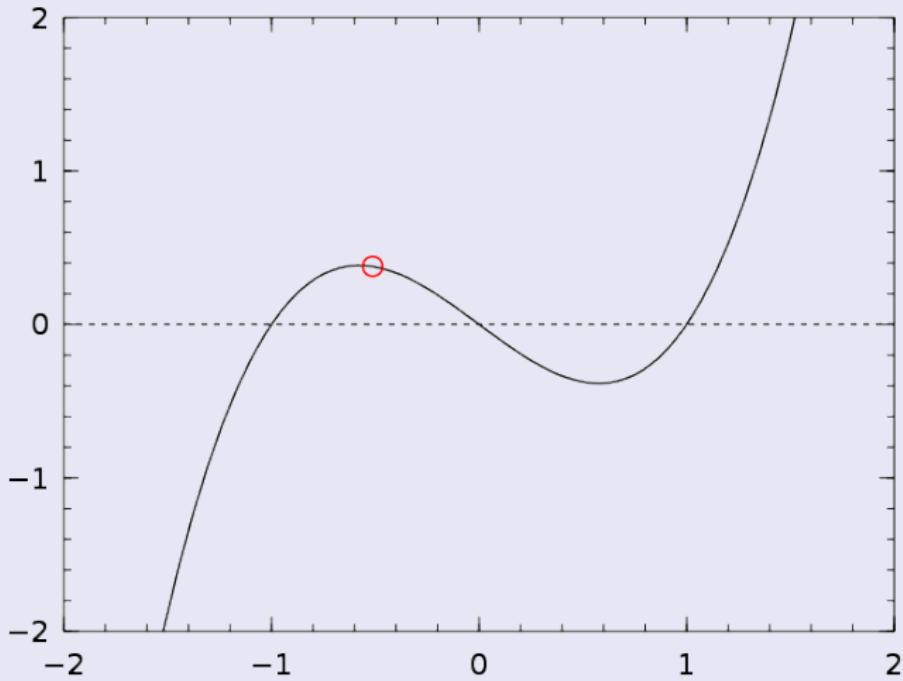
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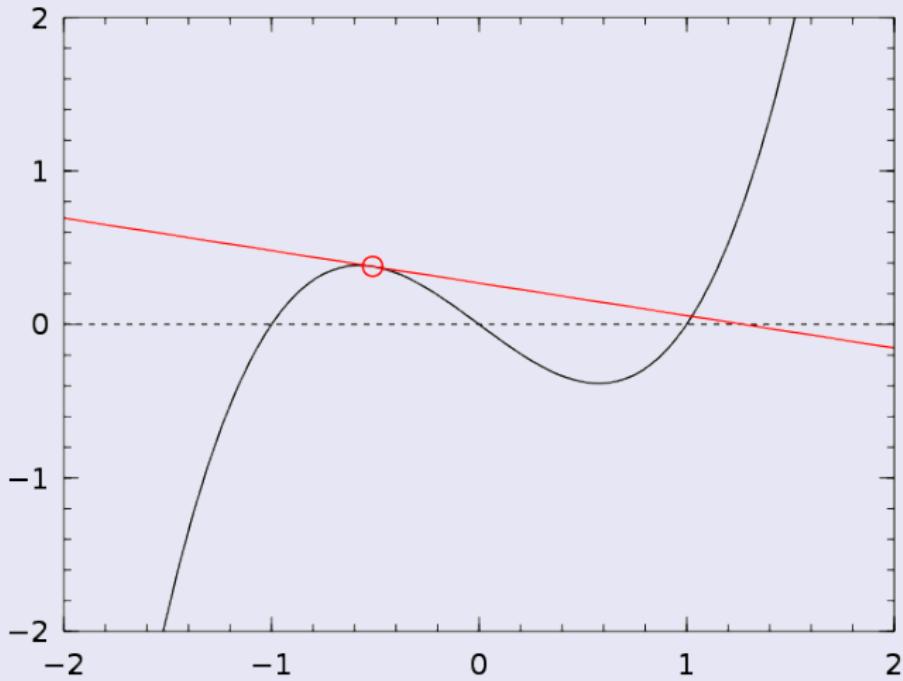
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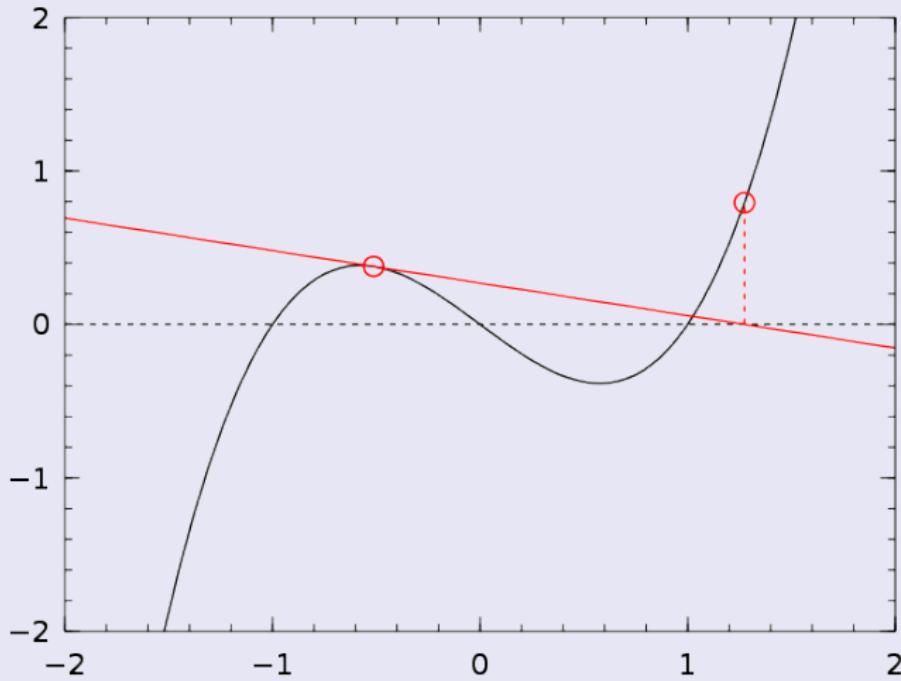
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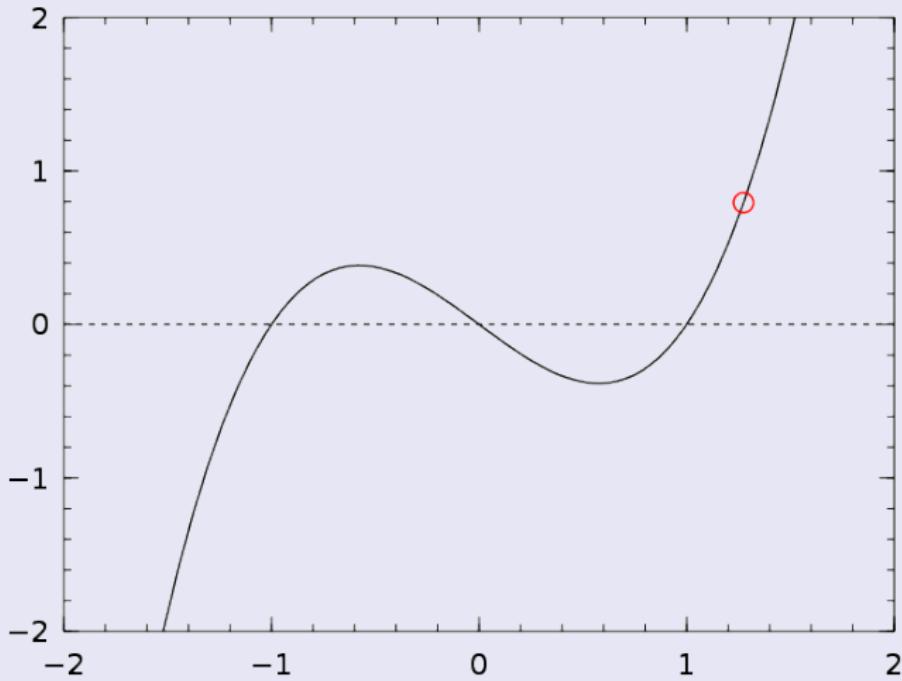
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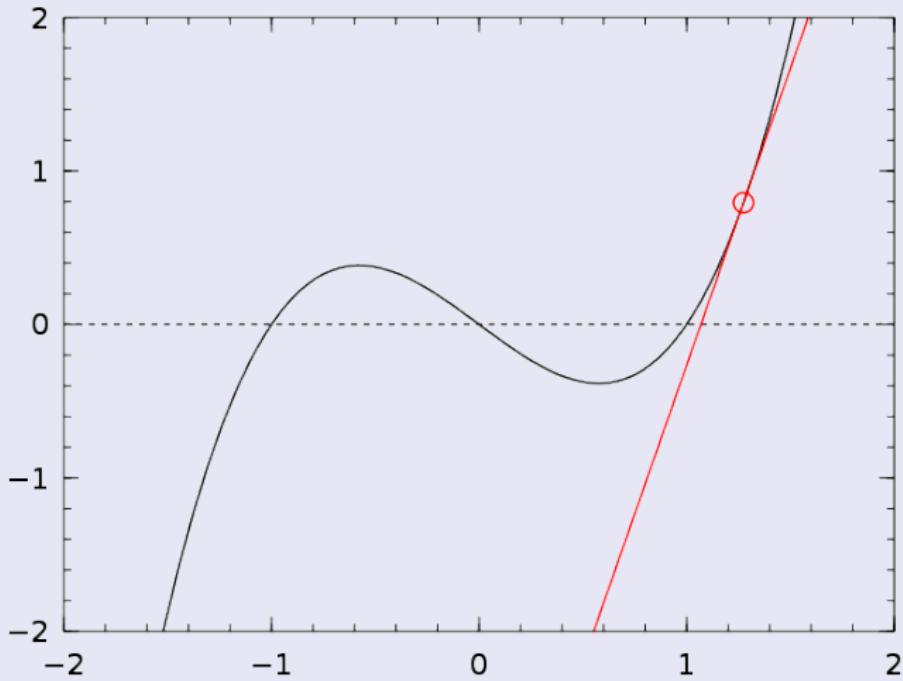
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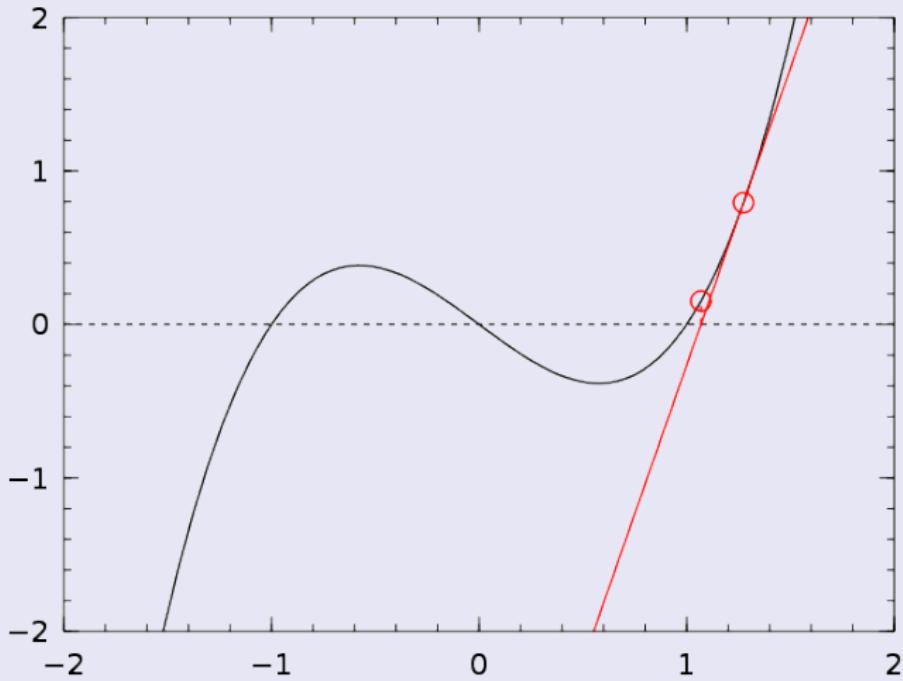
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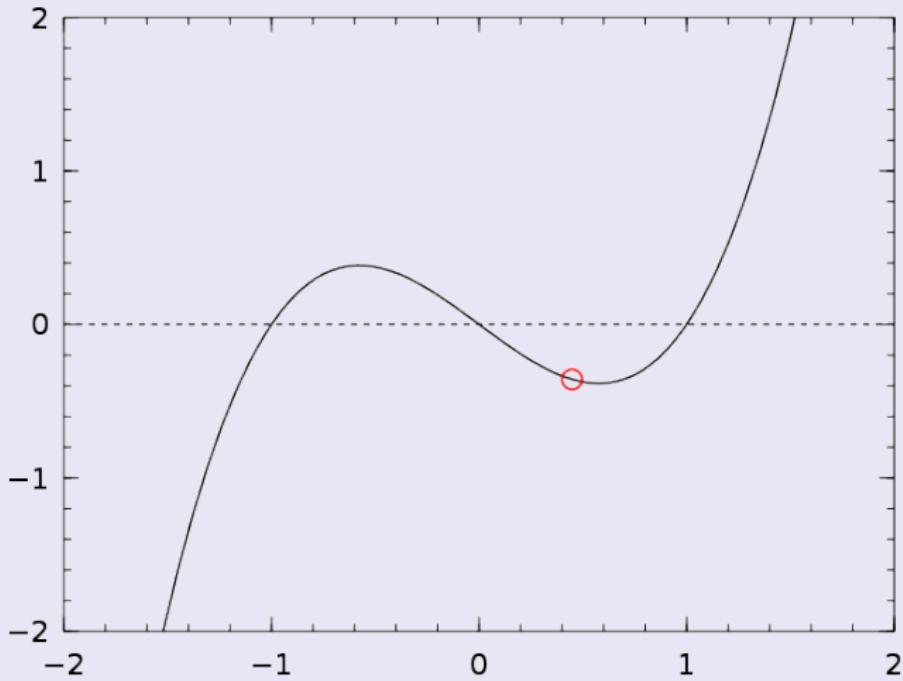
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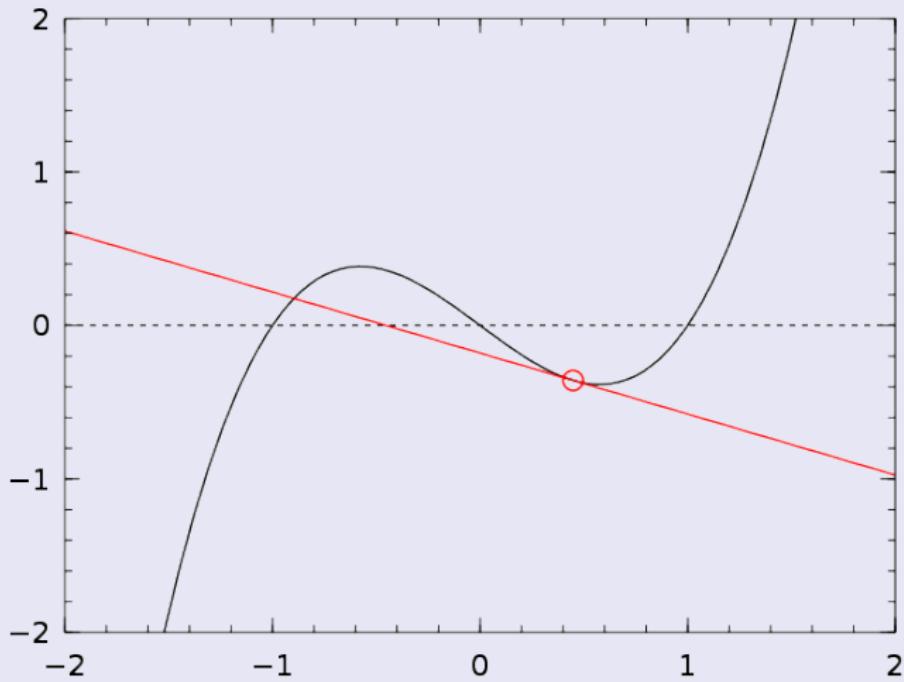
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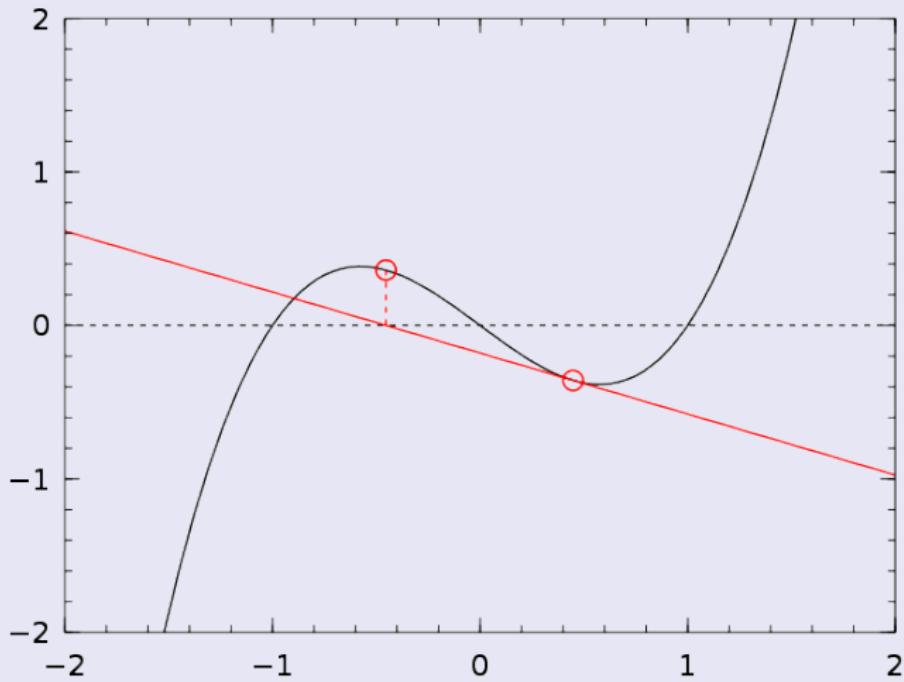
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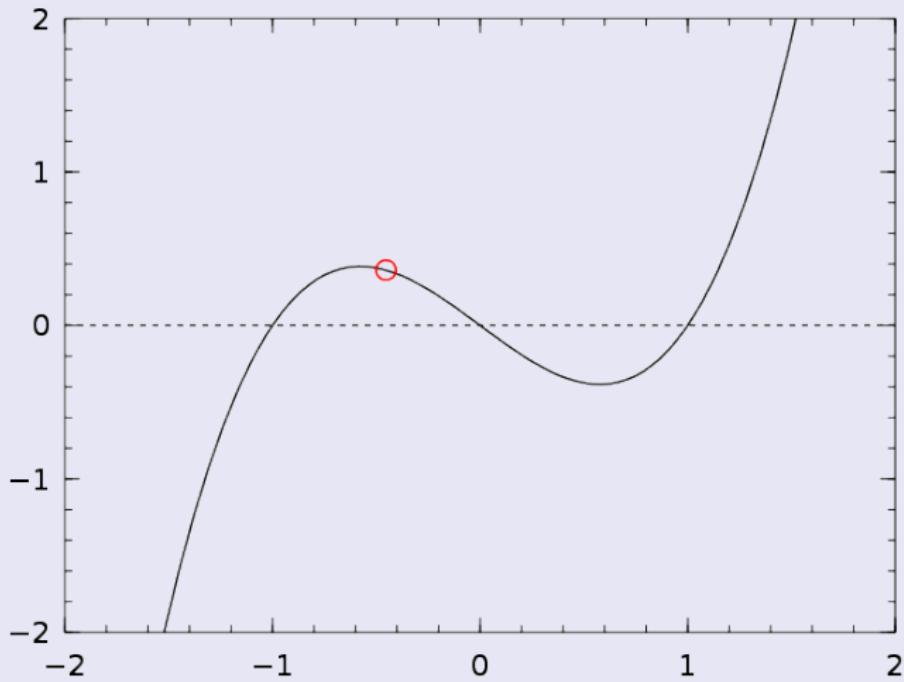
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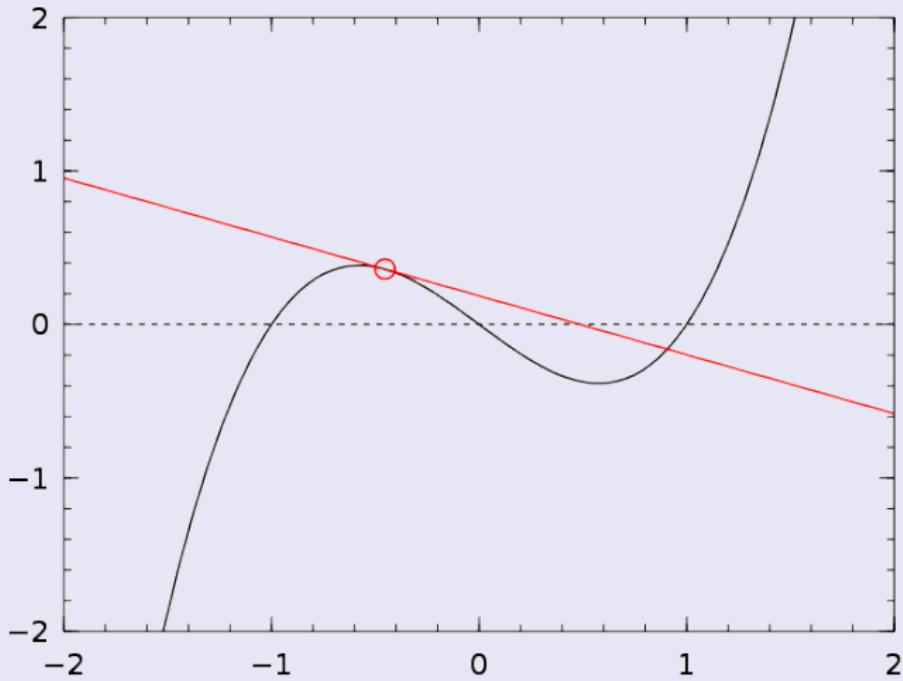
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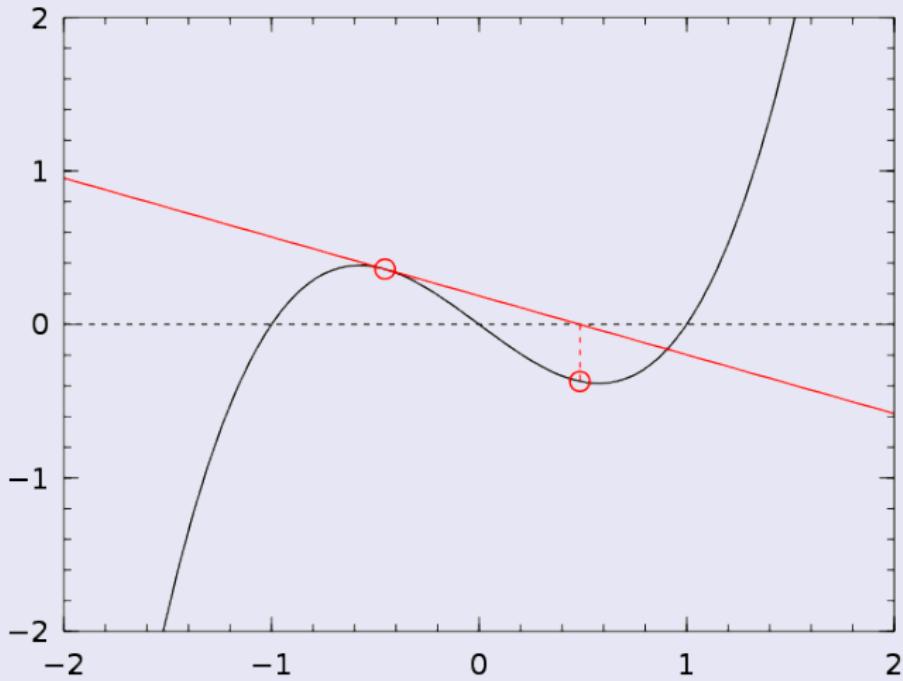
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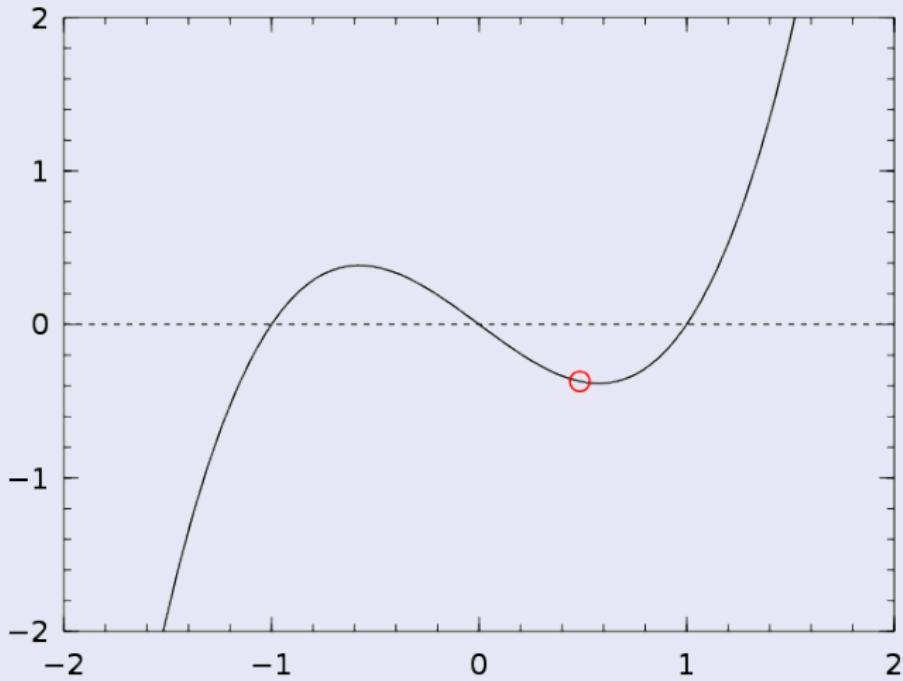
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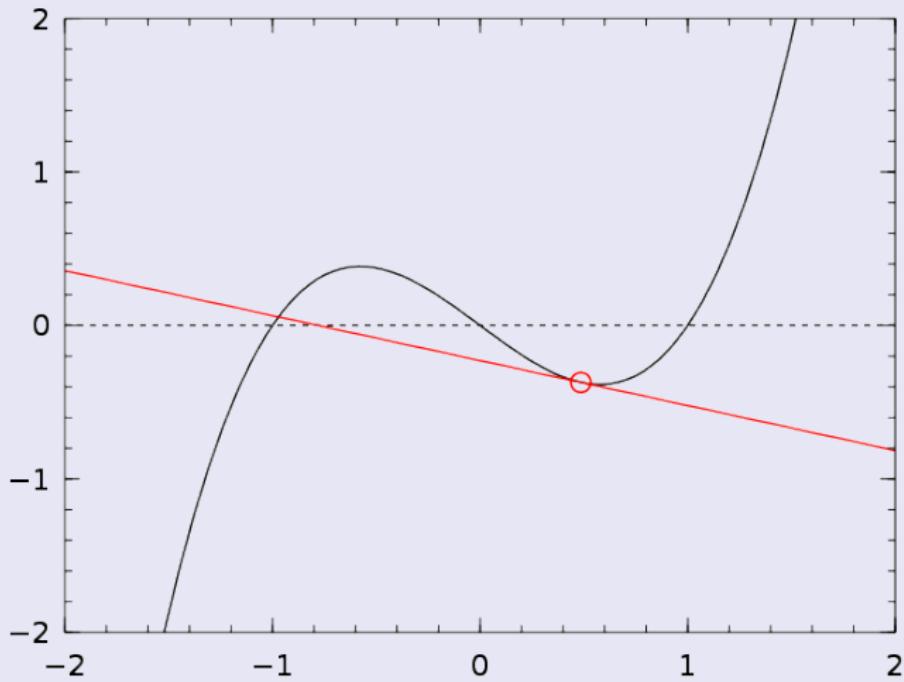
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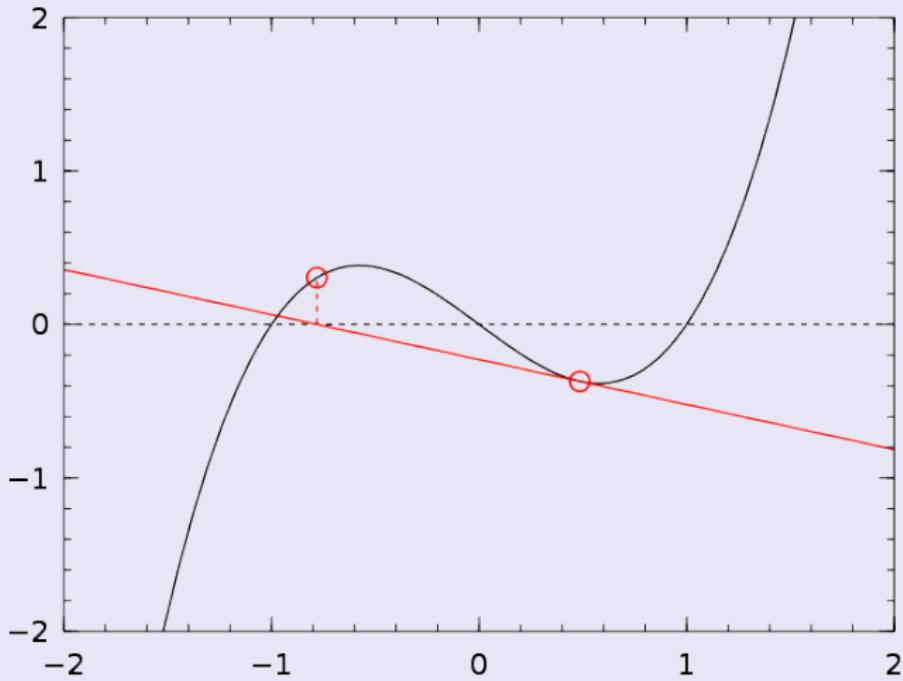
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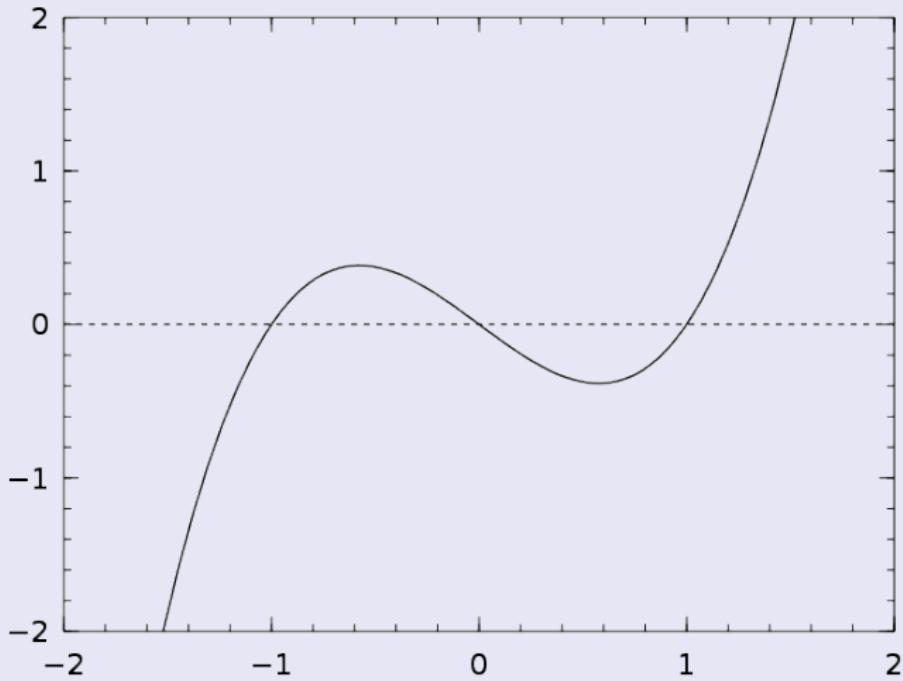
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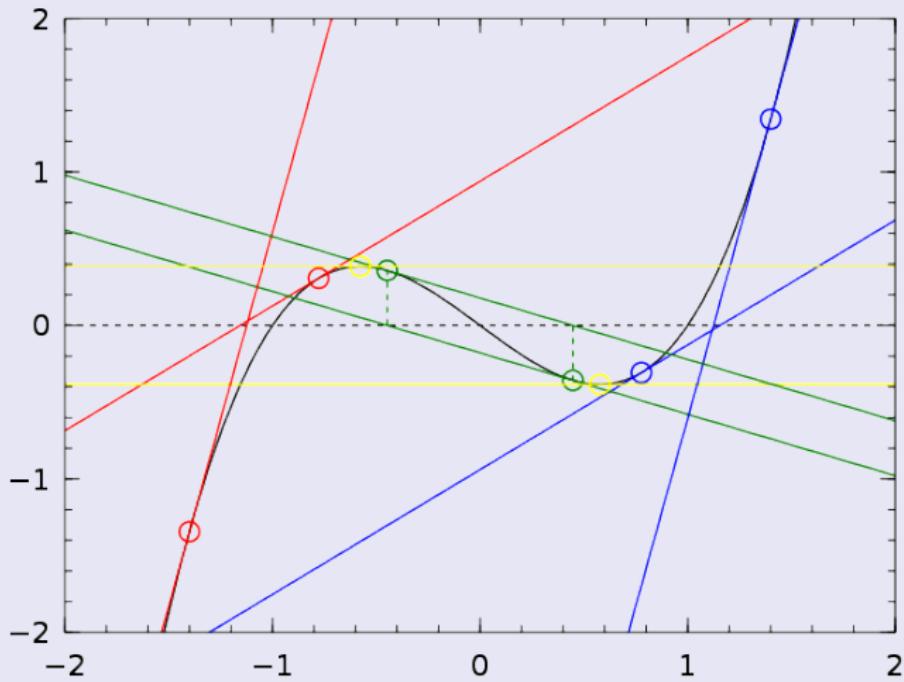
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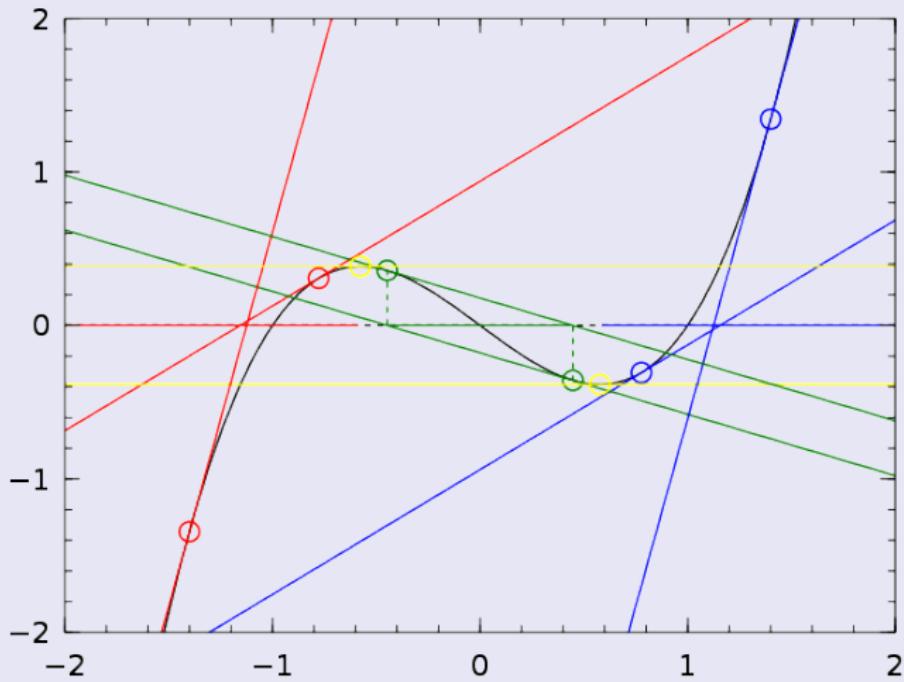
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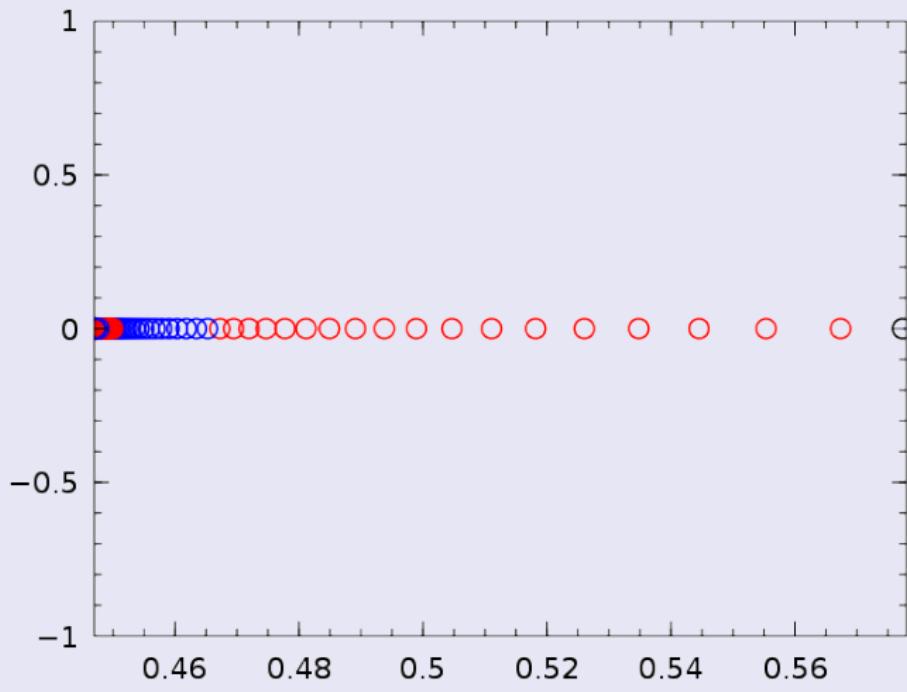
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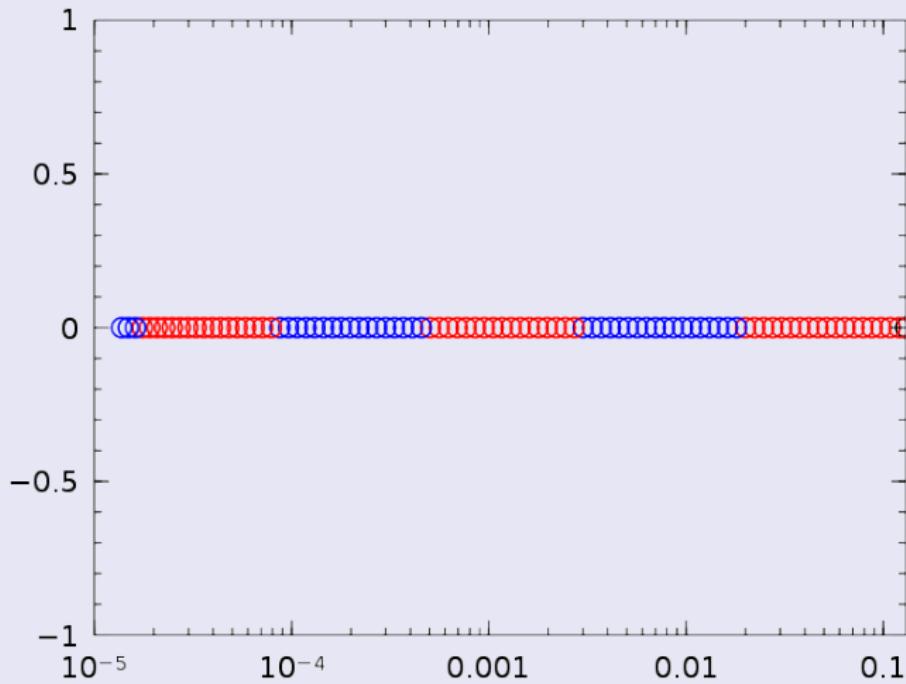
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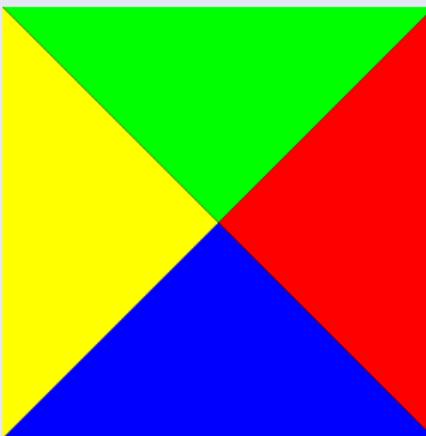
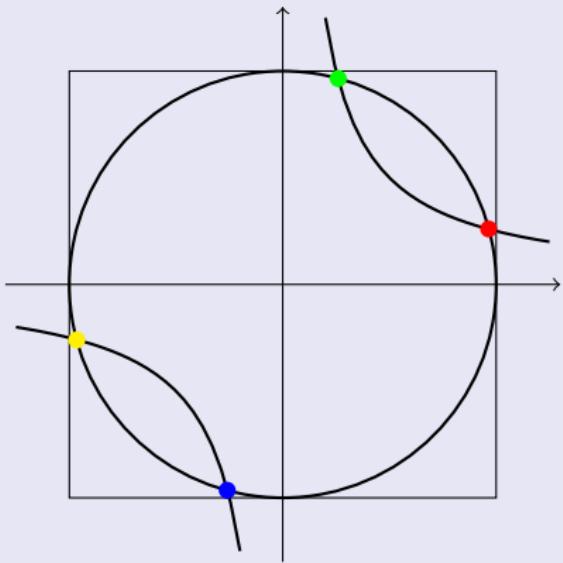
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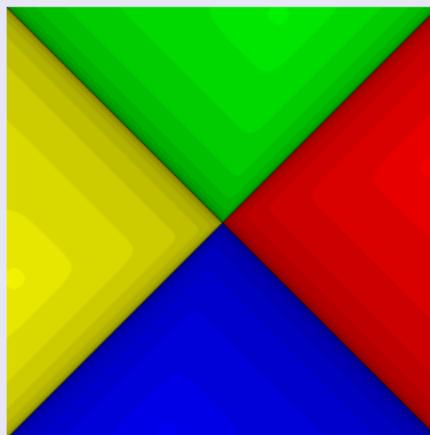
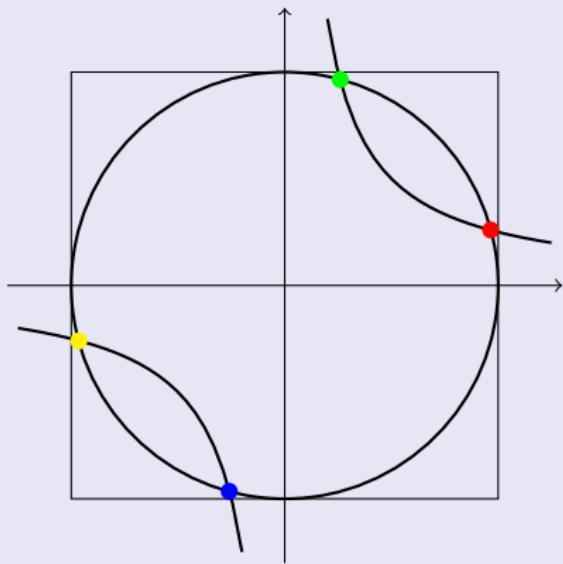
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$$\begin{cases} x_1^2 + x_2^2 = 4 \\ x_1 x_2 = 1 \end{cases}$$



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O Exemplo Tradicional

$$z^3 = 1, \quad z \in \mathbb{C}$$

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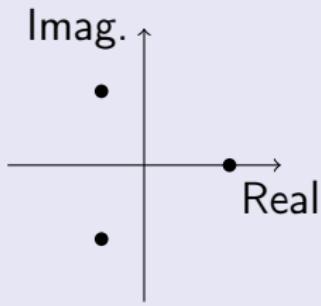
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$$z = 1, \frac{-1 + \sqrt{3}i}{2}, \frac{-1 - \sqrt{3}i}{2}.$$

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$$z = x + yi$$

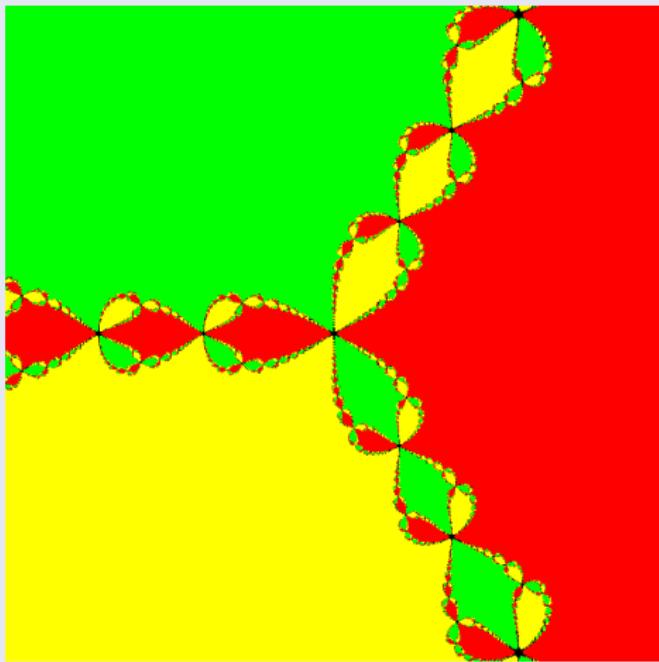
$$z = x + yi$$

$$z^3 = (x^3 - 3xy^2) + (3x^2y - y^3)i$$

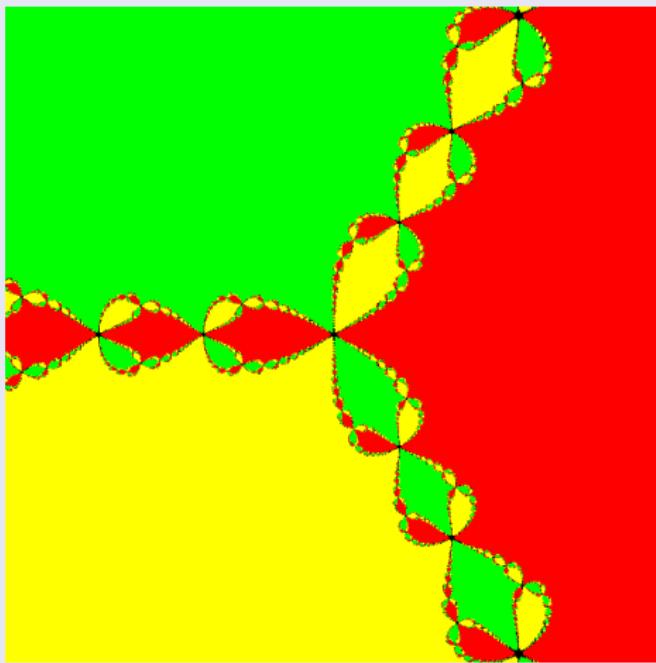
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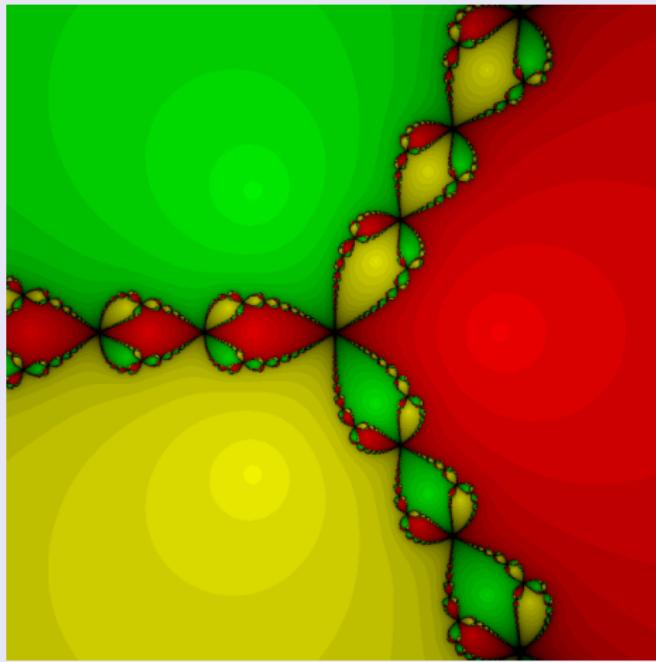
$$F(x, y) = \begin{bmatrix} x^3 - 3xy^2 - 1 \\ 3x^2y - y^3 \end{bmatrix}$$



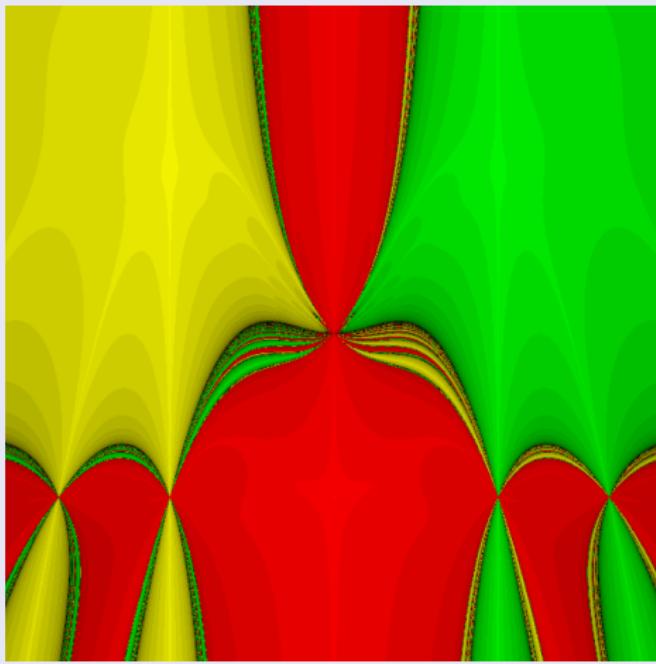
O fractal de Newton



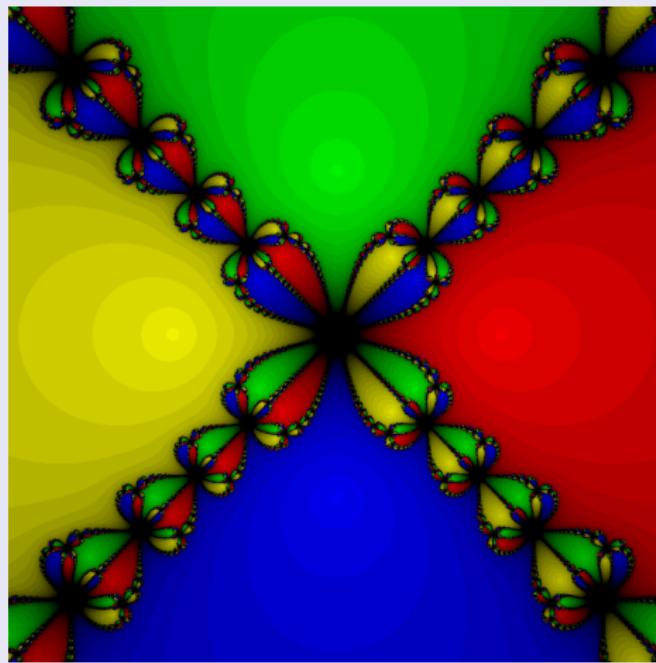
O fractal de Newton



$$F(x, y) = \begin{bmatrix} x(y - x^2) \\ (x^2 - 1)(y + 1) \end{bmatrix}$$



$$z^4 = 1, \quad z \in \mathbb{C}$$



1 Zeros de Funções

- Introdução
- Aproximação Linear
- Método de Newton

2 Equações não-lineares

- Introdução
- Aproximação Linear
- Método de Newton

3 Otimização

- Introdução
- O Método de Newton

4 Convergência

- Uma dimensão
- Duas dimensões
- Exemplo Tradicional

5 Referências

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Obrigado



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