Computational Physics

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Preface

I first learned to program in 2011 in Dr. Richard O. Gray's computational physics course.

It was a revelatory experience that shaped my life. I enjoyed the class so much that I served as the TA the following year and later earned a PhD in Computational Science.

I've kept the lecture notes on my various computers ever since. Rather than posting the original notes unchanged, I'm converting them into a Quarto book, updating examples from C to Python and adding some of my own material.

Note: Most of the content and examples are taken from Dr. Gray's original course materials.

Colophon

This is a book created from markdown and executable code.

See Knuth (1984) for additional discussion of literate programming.

To learn more about Quarto books, visit https://quarto.org/docs/books

1 Interpolation

1.1 Linear Interpolation

A common computational problem in physics involves determining the value of a particular function at one or more points of interest from a tabulation of that function. For instance, we may wish to calculate the index of refraction of a type of glass at a particular wavelength, but be faced with the problem that that particular wavelength is not explicitly in the tabulation. In such cases, we need to be able to interpolate in the table to find the value of the function at the point of interest. Let us take a particular example.

BK-7 is a type of common optical crown glass. Its index of refraction n varies as a function of wavelength; for shorter wavelengths n is larger than for longer wavelengths, and thus violet light is refracted more strongly than red light, leading to the phenomenon of dispersion. The index of refraction is tabulated in Table 1.1.

Let us suppose that we wish to find the index of refraction at a wavelength of 5000. Unfortunately, that wavelength is not found in the table, and so we must estimate it from the values in the table. We must make some assumption about how n varies between the tabular values. Presumably it varies in a smooth sort of way and does not take wild excursions between the tabulated values. The simplest and quite often an entirely adequate assumption to make is that the actual function varies linearly between the tabulated values. This is the basis of **linear interpolation**.

Exercise 4.1

Determine, by hand, the value of the index of refraction of BK7 at 5000 using linear interpolation.

How do we carry out linear interpolation on the computer? Let us suppose that the function is tabulated at N points and takes on the values $y_1, y_2, y_3...y_N$ at the points $x_1, x_2, x_3...x_N$, and that we want to find the value of the function y at a point x that lies someplace in the interval between x_1 and x_N .

The first thing that we must do is to bracket x, that is we must find a j such that $x_j < x \le x_{j+1}$. This can be accomplished by the following code fragment:

Table 1.1: Refractive Index for BK7 Glass

			_		
$\lambda()$	n	$\lambda()$	_	\overline{n}	$\lambda()$
	1.52165	4965		1.53894	3511
8210	1.5213	5017	ţ	1.53648	3638
8300	1.52049	5145		1.53024	4047
8521	1.51947	5320		1.52669	4358
9040	1.51872	5461		1.52611	4416
10140	1.51672	5876		1.52462	4579
10600	1.51673	5893		1.52402 1.52395	4658
13000					
15000	1.51509	6328		1.52339	4727
15500	1.51472	6438		1.5231	4765
19701	1.51432	6563		1.52283	4800
23254	1.51322	6943		1.52238	4861
20201	1.51106	7860		1.52224	4880

```
for(i=1;i<N;i++) {
    if(xn[i] < x && xn[i+1] >= x) {
        j = i;
        break;
    }
}
```

where the xn's are the tabulated points. When the if statement is satisfied, j is assigned the value of i and the procedure drops out of the loop. Please note that this is not the most efficient way to accomplish this task, especially if N is very large. We will look at a more efficient way later on.

Once we have bracketed x, we can find the equation of the line between the points (x_j, y_j) and (x_{j+1}, y_{j+1}) . This equation will be of the form y = mx + b4wherem\$ is the slope and b is the y-intercept. As we all know, the slope is given by

$$m = \frac{y_{j+1} - y_j}{x_{j+1} - x_j}$$

and the intercept can be found by substituting one point, say, (x_j, y_j) into the resulting equation. Thus,

$$b=y-mx=y_j-\frac{y_{j+1}-y_j}{x_{j+1}-x_j}x_j$$

yielding for the equation of the line, after some rearrangement,

$$y == y_j + \left(\frac{y_{j+1}-y_j}{x_{j+1}-x_j}\right)(x-x_j)$$

It is left to the student to show (for future reference) that this equation may be rewritten

$$y = Ay_j + By_{j+1}$$

where

$$A = \frac{x_{j+1}-x}{x_{j+1}-x_j}$$

and

$$B = \frac{x - x_j}{x_{j+1} - x_j}$$

Exercise 4.2

Write a C-function that will linearly interpolate the tabular data for the index of refraction of BK-7 and return a value for n for wavelengths between 3511 and 23254. Write a driver program that will use this function to prompt the user for a wavelength and then print to screen the corresponding value of n.

i Exercise 4.3

The file data/boiling.dat contains data in two columns for the boiling point of water at different atmospheric pressures. The first column is the pressure in millibars, the second is the corresponding boiling point temperature in degrees Celsius. Write a C-function that initializes two vectors, P and T with the data in that data file (don't read in the datafile – hardwire the data into your program), accepts the pressure as a double floating-point parameter, and returns the value of the temperature of the boiling point at that pressure. You should also write a driver program that will prompt the user for an atmospheric pressure, check whether it is within the limits of the data ($50 \le P \le 2150$), calls your C-function, and prints to the screen the boiling point of water at that pressure.

2 Finding the Root of a Function

3 Minimization and Maximization of Functions

4 Numerical Integration

5 Numerical Integration of Ordinary Differential Equations

6 The Modeling of Data

References

Knuth, Donald E. 1984. "Literate Programming." Comput.~J.~27~(2): 97–111. https://doi.org/10.1093/comjnl/27.2.97.