

$$X = aU + bV$$

$$Y = cU + dV$$

$$U, V \sim N(0, 1) \text{ iid}$$

$$a, b, c, d \rightarrow X(U, V), Y(U, V)$$

$$E[\bar{X}] = E[\bar{Y}] = 0$$

$$-1 \leq \rho \leq 1$$

$$\sigma_{\bar{X}}^2 = a^2 + b^2 \quad \sigma_{\bar{Y}}^2 = c^2 + d^2$$

$$\text{cov}[\bar{X}, \bar{Y}] = E[\bar{X}\bar{Y}] - E[\bar{X}]E[\bar{Y}] = \rho_{XY} \sigma_{\bar{X}} \sigma_{\bar{Y}} \quad \rightarrow =$$

$$\Rightarrow E[\underbrace{(aU + bV)}_X \underbrace{(cU + dV)}_Y] = ac \underbrace{E[U^2]}_1 + bd \underbrace{E[V^2]}_1 = ac + bd$$

$$\rho = \frac{ac + bd}{\sqrt{(a^2 + b^2)(c^2 + d^2)}}$$

$$a=1, b=0, c=0, d=1$$

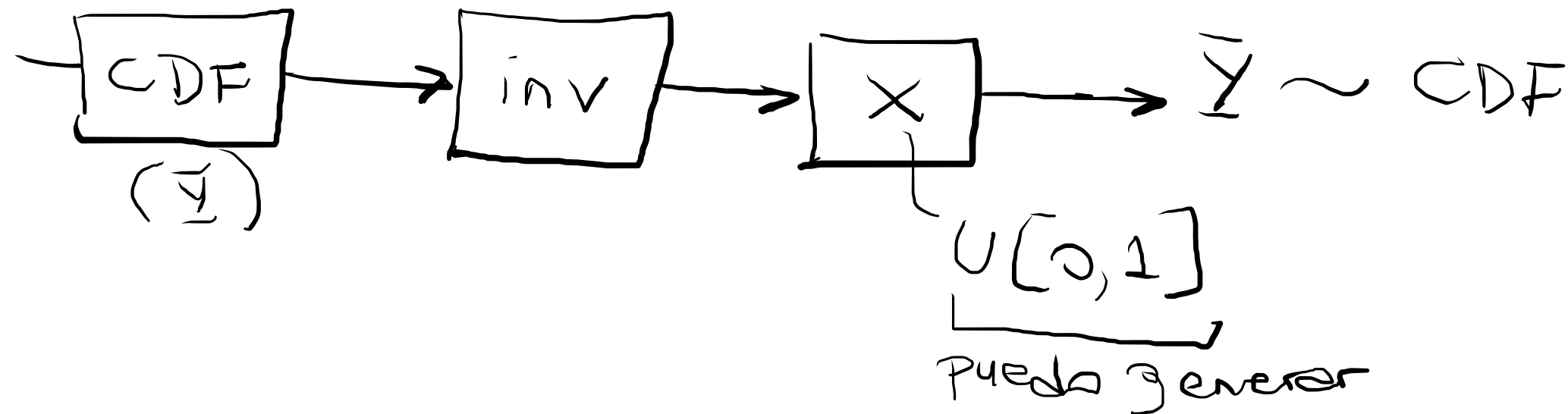
Transformaciones de V.A.

(Ej 3, Clase 2)

$\bar{Y} \sim \text{exponencial}$ par. λ
 $f_{\bar{Y}}(y) = \lambda e^{-\lambda y}, y \geq 0$; sino 0, $y < 0$.
 \hookrightarrow (pdf)

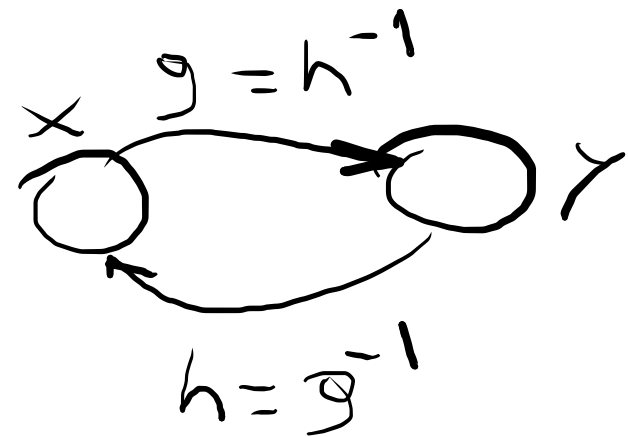
Busca la CDF: $F_{\bar{Y}}(y) = \int_{-\infty}^y f_{\bar{Y}}(y) dy = \int_0^y \lambda e^{-\lambda y} dy = 1 - e^{-\lambda y}, y \geq 0$

Método de la transf. inversa



Busca la inverse : $x = 1 - e^{-\lambda y} \Rightarrow y = -\frac{1}{\lambda} \ln(1-x)$

$\underbrace{x}_{h(y)} \Rightarrow \underbrace{-\frac{1}{\lambda} \ln(1-x)}_{g(x)}$



$$y \rightarrow f(x)$$

$h(y) \sim$ es CDF
 $\text{rango } [0, 1]$

pdf \underline{Y} : $f_{\underline{Y}}(y) = \underbrace{f_{\underline{X}}(x=h(y))}_1 \left| \frac{dh(y)}{dy} \right|$

$$\underline{X} \sim U[0, 1] \rightarrow 1$$

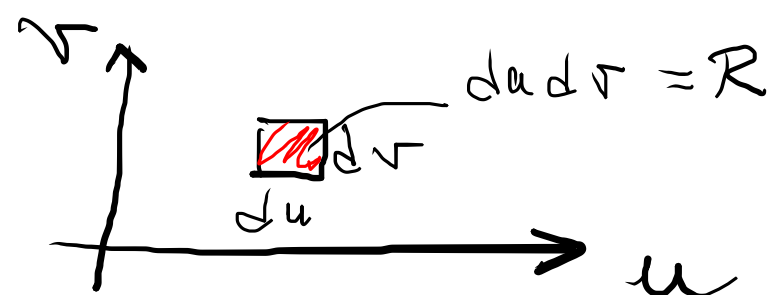
$$f_{\underline{Y}}(y) = \lambda e^{-\lambda y}, \quad y \geq 0.$$

Transformación de V. A. - Jacobiano

$$X = X(u, v)$$

$$Y = Y(u, v)$$

$$u-v \rightarrow x-y$$

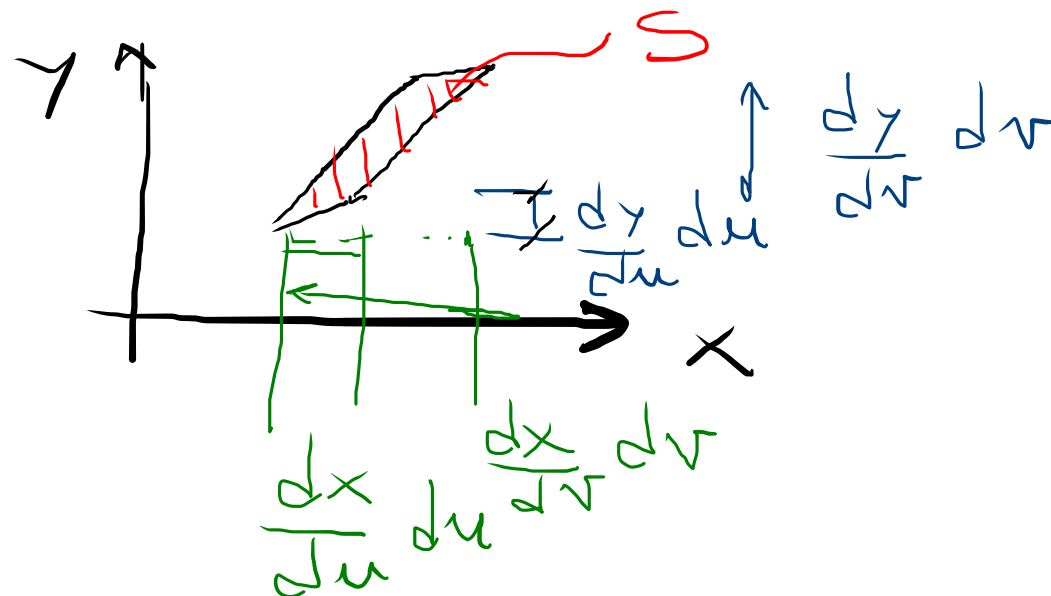


$$R \neq S$$

Al calcular las probabilidades (P) de un evento:

R, S deben dar la misma P .

$$S = |A \times B| = |J| \underbrace{dudv}_R$$



$$\begin{matrix} X & \xrightarrow{u} \\ Y & \xrightarrow{v} \end{matrix}$$

Jacobiano:

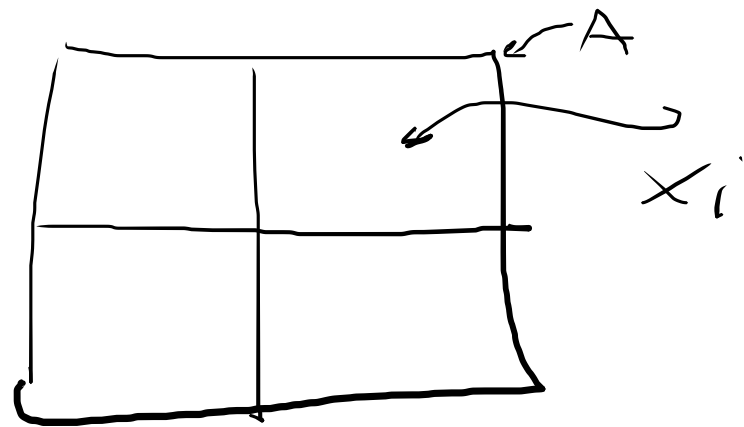
$$J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \quad \text{det.}$$

$$\overbrace{f_{xy} dx dy}^{\partial P} = \overbrace{f_{uv} du dv}^{\partial P}$$

◊ □

$$f_{uv} = f_{xy} |J| = f_{xy} \left| \frac{\partial(x, y)}{\partial(u, v)} \right|$$

$$f_{xy} = \frac{f_{uv}}{|J|} \rightarrow f_{\underline{x}\underline{y}}(x, y) = \frac{f_{uv}(u, v)}{|J(u, v)|} \left. \vphantom{\frac{f_{uv}(u, v)}{|J(u, v)|}} \right\} \begin{array}{l} u = u(x, y) \\ v = v(x, y) \end{array}$$



$$P(A) = \sum_i P(A \cap x_i)$$

$$= \sum_{x_i} P(A | x_i) P(x_i)$$

Dado con \underline{X} : número de dado
 A : evento de número.

Dado a priori : $P(\underline{X} = i) = \frac{1}{6}$

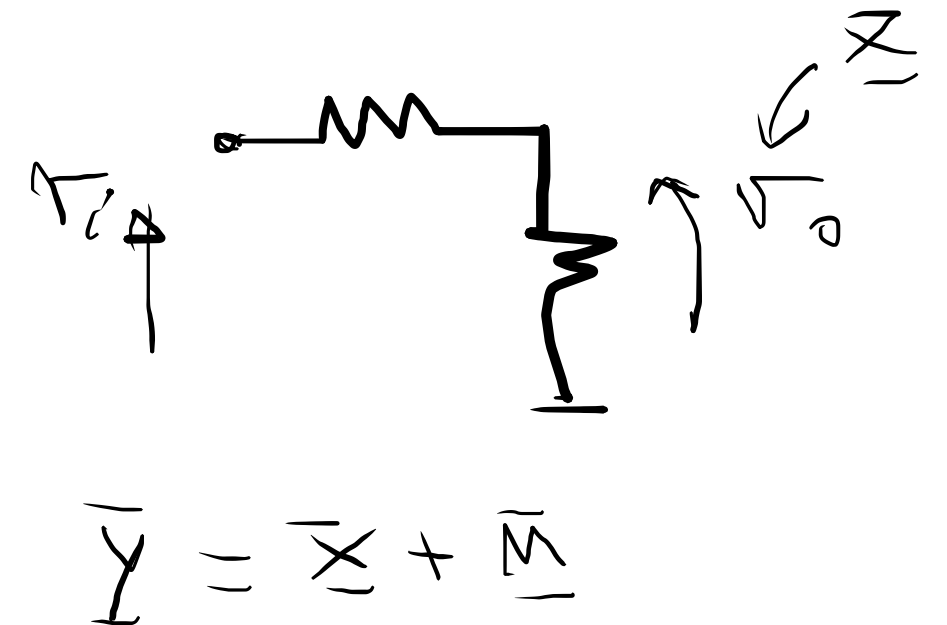
$$P(\underline{X} = i | A \text{ es par}) = \begin{cases} \frac{1}{3}, & x = 2, 4, 6. \\ 0, & x = 1, 3, 5 \end{cases}$$

Teorema de la Esperanza Total

$$E[\bar{X}] = \sum_k x_k P(\bar{X} = x_k)$$

$$E[\bar{X} | A] = \sum_k x_k P(\bar{X} = x_k | A)$$

$$E[\bar{X}] = \sum_y \underbrace{E[\bar{X} | \bar{Y} = y]}_{f(\bar{y})} P(\bar{Y} = y)$$



Ley de Esperanzas Iteradas

$$E[\bar{X}|\bar{Y}] = \sum_x x \underbrace{P(\bar{X}=x|\bar{Y}=y)}_{P(\bar{X}=x, \bar{Y}=y)}$$

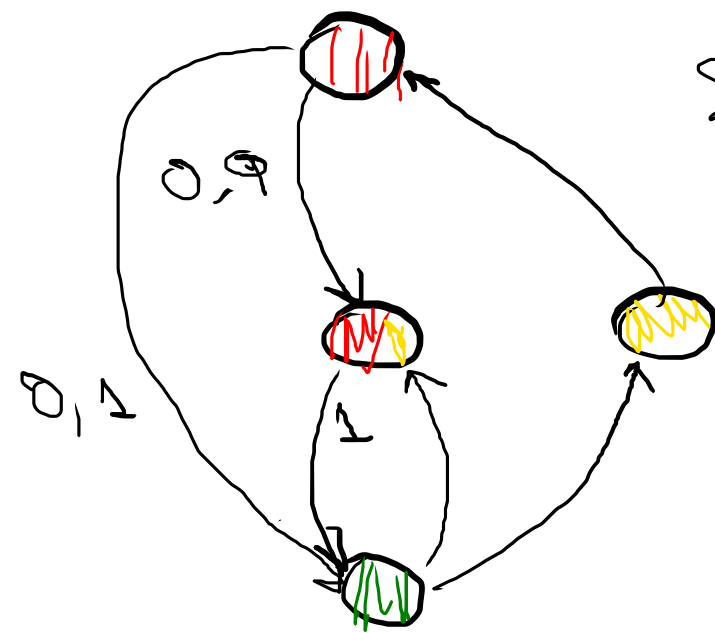
$$E[E[\bar{X}|\bar{Y}]] = \sum_y \underbrace{\sum_x x P(\bar{X}=x|\bar{Y}=y)}_{E[\bar{X}|\bar{Y}]} P(\bar{Y}=y)$$

$$\sum_x x \sum_y P(\bar{X}, \bar{Y}) = \sum_x x P(\bar{X}=x) = E[\bar{X}]$$

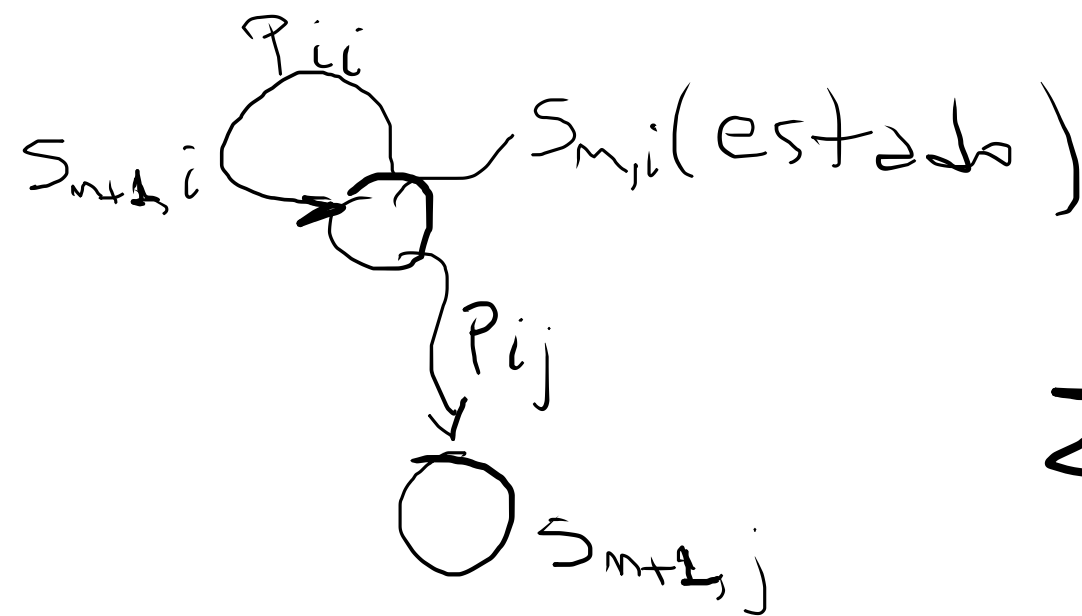
Proceso de Markov

$x(n) \quad x(n-1) \quad x(n-2) \dots$

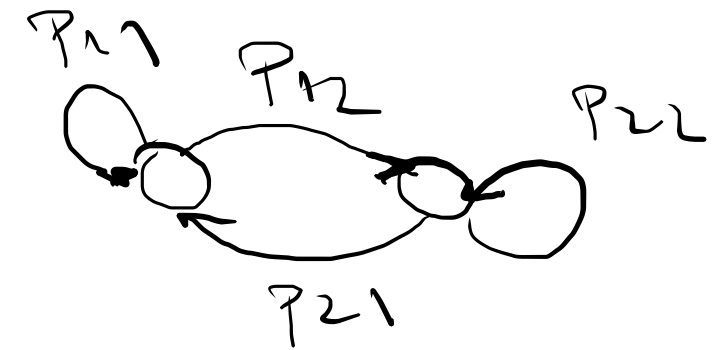
$\begin{bmatrix} x(n) \\ x(n-1) \\ \vdots \end{bmatrix} \leftarrow \text{memoria}$



Semáforo
funciona
mal

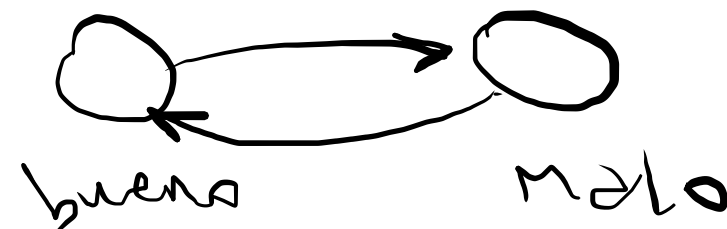
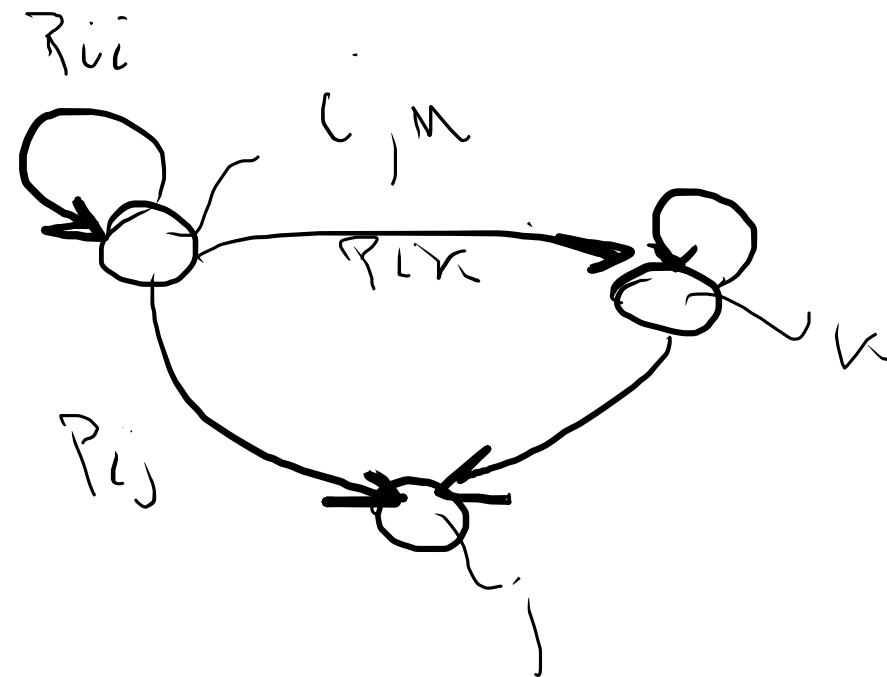
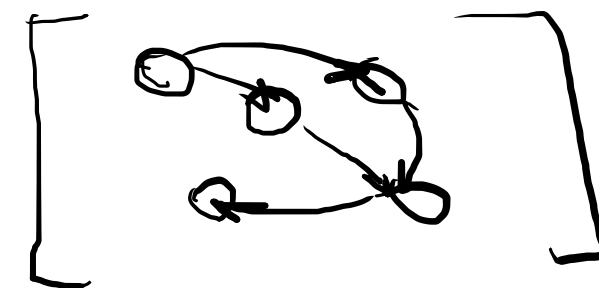


$$\sum P_{\text{salientes}} = 1$$



$$\begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix}$$

Cadenas de Markov



Ruido Blanco

$$\delta(t) = \begin{cases} \infty, & t=0 \\ 0, & t \neq 0 \end{cases}$$

$$\int_{-\infty}^{+\infty} \delta(t) dt = 1$$

$$\int_{-\infty}^{+\infty} f(t) \delta(t) dt = f(0)$$

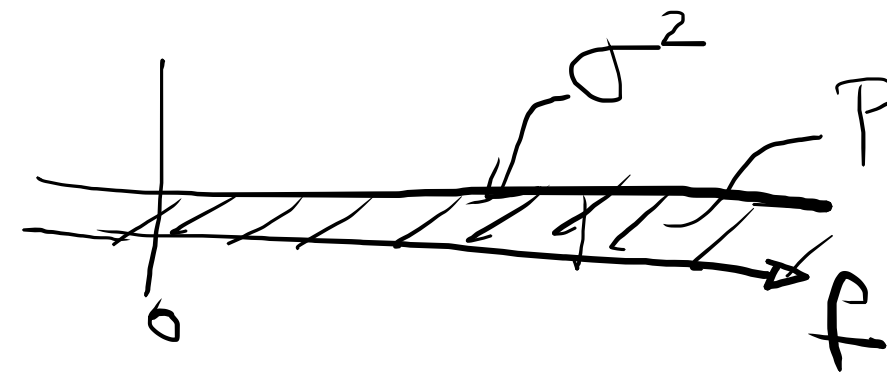
Función de Autocorrelación

$$\int_{n-t}^t \delta(t) dt = f(n)$$

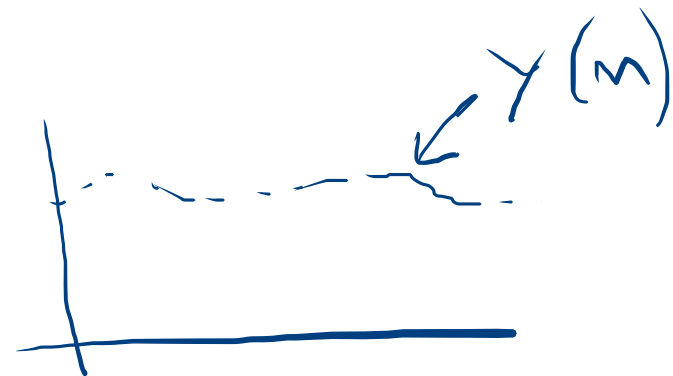
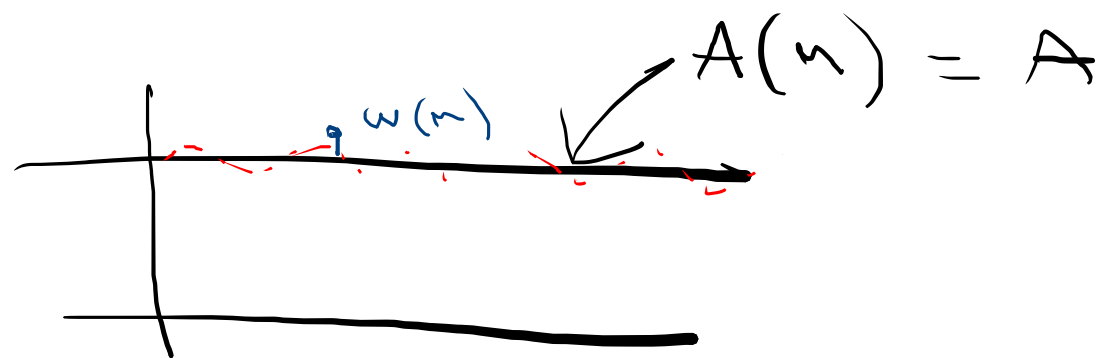
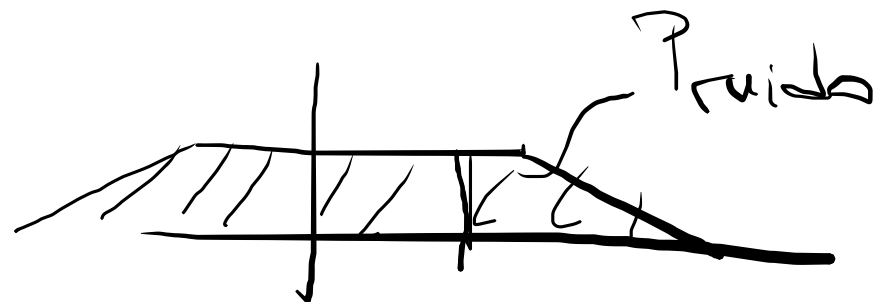
$$E[X(t)X(t+\tau)] = R(t, t+\tau)$$

Ruido blanco: $R(\tau)$

$$\sigma_x^2 = \int_{-\infty}^{+\infty} x^2 f_x(x) dx \rightarrow 0$$



$$P(f) = \int_{-\infty}^{+\infty} p_f df \rightarrow \infty$$



$$w \sim N(0, \sigma_w^2)$$

$$y \sim N(A, \sigma_w^2)$$

$$y = A + w$$

$$E[y] = E[A] + E[w] \quad \left| \quad \sigma_y^2 = \underbrace{\sigma^2(A)}_0 + \sigma_w^2 \right.$$

Proceso de Wiener

$w(t)$ es v.a. con distribución de Wiener

$$E[w(t)] = 0, \quad 0 < s < t < T$$

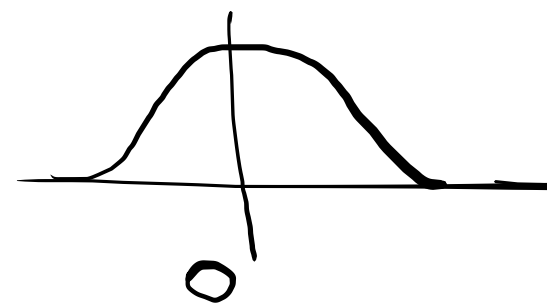
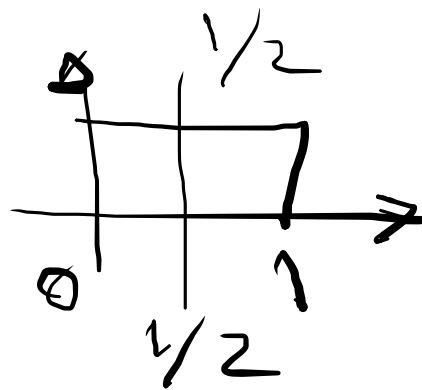
$$\begin{aligned} w(t) - w(s) &\sim Z \\ w(u) - w(r) &\sim Y \end{aligned} \quad \left. \begin{array}{l} \nearrow \\ \searrow \end{array} \right\} \text{independientes}$$



$$\begin{aligned} w(t) - w(s) &\sim \sqrt{t-s} \mathcal{N}(0, 1) \\ &= \mathcal{N}(0, t-s) \end{aligned}$$

Ej 3

$X, Y \sim U[0, 1]$ independientes.



$$Z = X + Y$$

$$\left[E[Z|X] = E[X+Y|X] = \underbrace{E[X|X]}_{\bar{X}=X} + \underbrace{E[Y|X]}_{E[Y]} = X + \frac{1}{2} \right]$$

$$\begin{aligned} \bar{X} &= x_k \\ \bar{X} &\in I \end{aligned}$$

$$P(\text{ahora está lloviendo} | \text{ahora está lloviendo}) = 1$$

$$E[X|X] = \sum_k x_k \underbrace{P(X=x_k|X=x_k)}_1 = X$$