

```

1  l=0
2
3  for a=1:1:5
4
5      for b=1:1:5
6          l=l+1;
7          A(a,b)=rand;           %Potential seed function
8          position(1,1)=a;
9          position(1,2)=b;
10     end
11 end
12
13 q=1           %Particle charge
14 particlex=2   %Initial particle x position
15 particley=2   %Initial particle y position
16
17 for t=0:pi/4:2*pi
18     l=0
19     for j=1:1:5
20         for k=1:1:5
21             l=l+1;
22             fprintf('%f',t);
23             potentialt=(0.9)*A(j,k)+0.0001*(rand-0.5); %Random walk based on potential at previous time
24             A(j,k)=potentialt; %Potential at each grid point
25             position(1,3)=potentialt; %Store each potential in an array related to a grid point
26             [ex, ey] = differentiate(sf, [j, k]) %Electric field calculated as derivative of potential
27             fx(j,k) = q*ex; %Force in x direction
28             fy(j,k) = q*ey; %Force in y direction
29         end
30     end
31
32 scatter3(position(:,1),position(:,2),position(:,3))
33 sf=fit([position(:,1), position(:,2)], position(:,3), 'biharmonicinterp') %fits surface to potential
34 plot(sf,[position(:,1), position(:,2)], position(:,3))
35 figure
36 partpot=interp2(A,particlex,particley) %potential at particle position
37 partforcej=interp2(fj,particlex,particley) %force in j direction at particle position
38 partforcek=interp2(fk,particlex,particley) %force in k direction at particle position
39
40 end
41

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1  l=0
2
3  for a=1:1:5
4
5      for b=1:1:5
6          l=l+1;
7          A(a,b)=rand;           %potential seed function
8          position(1,1)=a;       %storing the x position of the grid
9          position(1,2)=b;       %storing the y position of the grid
10     end
11 end
12
13 q=1           %particle charge
14 m=1           %particle mass
15 particlex=2   %initial particle x position
16 particley=2   %initial particle y position
17
18 for t=0:pi/4:2*pi
19     l=0
20     for j=1:1:5
21         for k=1:1:5
22             l=l+1;
23             fprintf('%f',t);
24             potentialt=(0.9)*A(j,k)+0.0001*(rand-0.5); %random walk based on potential at previous time
25             A(j,k)=potentialt; %potential at each grid point
26             position(1,3)=potentialt; %store each potential in an array related to a grid point
27         end
28     end
29
30 scatter3(position(:,1),position(:,2),position(:,3))
31 sf=fit([position(:,1), position(:,2)], position(:,3), 'biharmonicinterp') %fits surface to potential
32 plot(sf,[position(:,1), position(:,2)], position(:,3))
33 figure
34 [ex, ey] = differentiate(sf, [particlex, particley]) %Electric field calculated as derivative of potential at particle position
35 fx = q*ex; %Force at particle position in j direction
36 fy = q*ey; %Force at particle position in k direction
37 ax = fx/m; %acceleration in x direction
38 ay = fy/m; %acceleration in y direction
39 particlex = particlex+ax*(pi/4)^2; %particle x position at each time
40 particley = particley+ay*(pi/4)^2; %particle y position at each time
41 end
42

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```

1 - l=0;
2 - n=5; %Grid size
3 - for a=1:1:n
4 -     for b=1:1:n
5 -         l=l+1; %Potential seed function
6 -         A(a,b)=rand; %Storing the x position of the grid
7 -         position(1,1)=a; %Storing the y position of the grid
8 -         position(1,2)=b;
9 -     end
10 - end
11
12 - q=1 %Particle charge
13 - m=1 %Particle mass
14 - particlex=5.5 %Initial particle x position
15 - particley=2 %Initial particle y position
16 - dt=pi/4; %Time step
17
18 - for t=0:pi/4:2*pi
19 -     l=0 %Reset the array position to 0
20 -     for j=1:1:n
21 -         for k=1:1:n
22 -             l=l+1; %Move to next row in array
23 -             %pot=diff('A','x');
24 -             potentialt=(0.9)*A(j,k)+0.0001*(rand-0.5); %Random walk based on potential at previous time
25 -             A(j,k)=potentialt; %Potential at each grid point
26 -             position(1,3)=potentialt; %Store each potential in an array related to a grid point
27 -         end
28 -     end
29
30 -     scatter3(position(:,1),position(:,2),position(:,3));
31 -     sf=fit([position(:,1), position(:,2)], position(:,3), 'biharmonicinterp'); %fits surface to potential
32 -     plot(sf, [position(:,1), position(:,2)], position(:,3));
33 -     if (particlex<= 4 && particley<=n) %For particle within the grid
34 -         [ex, ey] = differentiate(sf, [particlex,particley]) %Electric field calculated as derivative of potential at particle position
35 -         fx = q*ex %Force at particle position in x direction
36 -         fy = q*ey %Force at particle position in y direction
37 -         ax = fx/m %Acceleration of particle in x direction
38 -         ay = fy/m %Acceleration of particle in y direction
39 -         particlex = particlex+ax*dt^2 %Particle x position at each time
40 -         particley = particley+ay*dt^2 %Particle y position at each time
41 -         elseif (particlex>n-1 && particley<=n-1) %If particle moves out of the grid
42 -             partpot=interp2(A,particlex-(n),particley)
43 -         elseif (particlex<=n-1 && particley>n-1)
44 -             partpot=interp2(A,particlex,particley-(n))
45 -         else
46 -
47 -
48 -     end
49
50 - end
51

```