

Learning features to compare distributions

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Barcelona Spain

Goal of this talk

- **Have:** Two collections of samples X, Y from unknown distributions P and Q .
- **Goal:** Learn distinguishing features that indicate how P and Q differ.



$\sim P$



$\sim Q$

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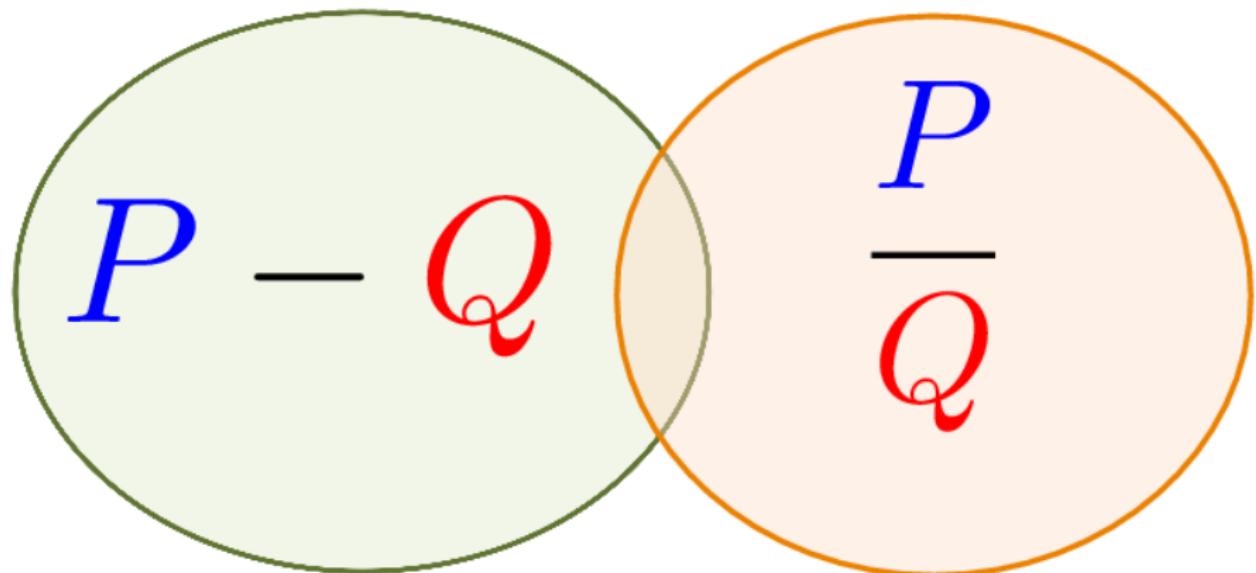


$\sim P$



$\sim Q$

Divergences



Divergences

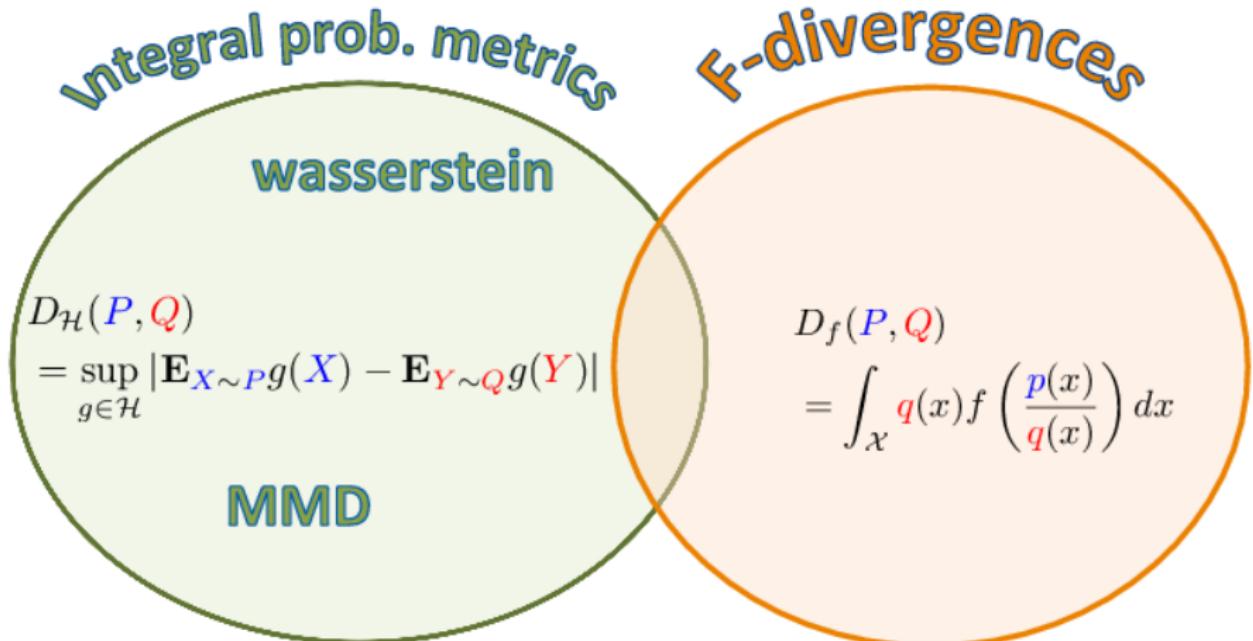
Integral prob. metrics

F-divergences

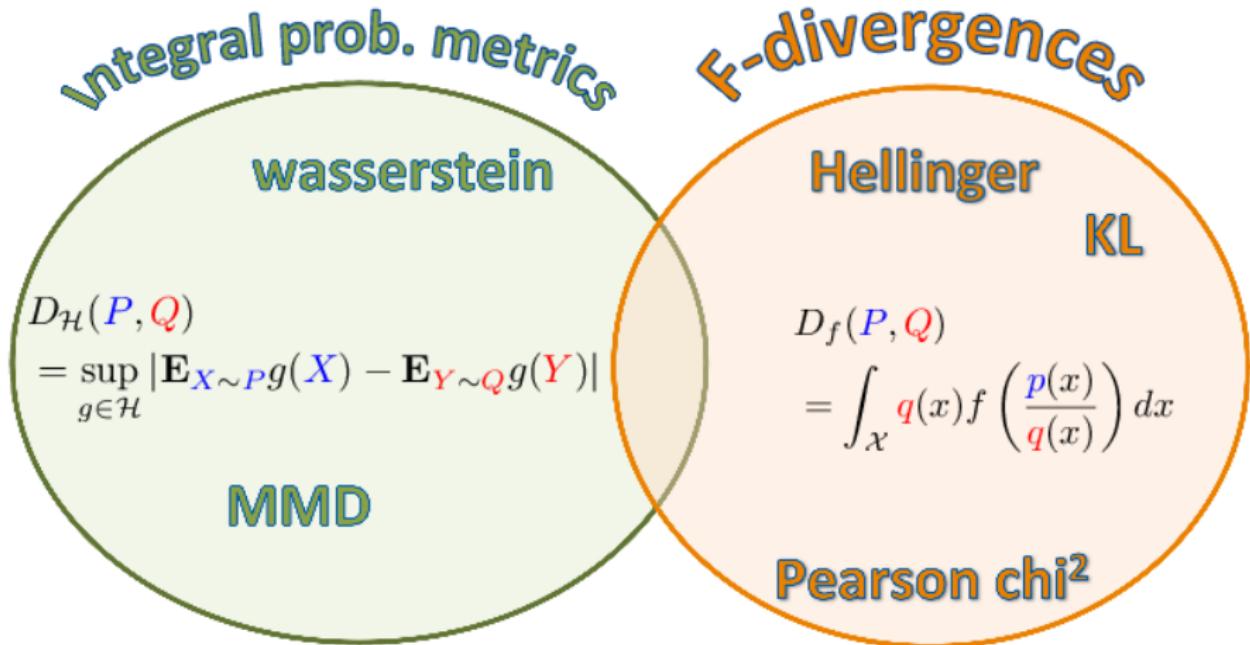
$$D_{\mathcal{H}}(\mathbf{P}, \mathbf{Q}) = \sup_{g \in \mathcal{H}} |\mathbf{E}_{X \sim \mathbf{P}} g(X) - \mathbf{E}_{Y \sim \mathbf{Q}} g(Y)|$$

$$D_f(\mathbf{P}, \mathbf{Q}) = \int_{\mathcal{X}} q(x) f\left(\frac{p(x)}{q(x)}\right) dx$$

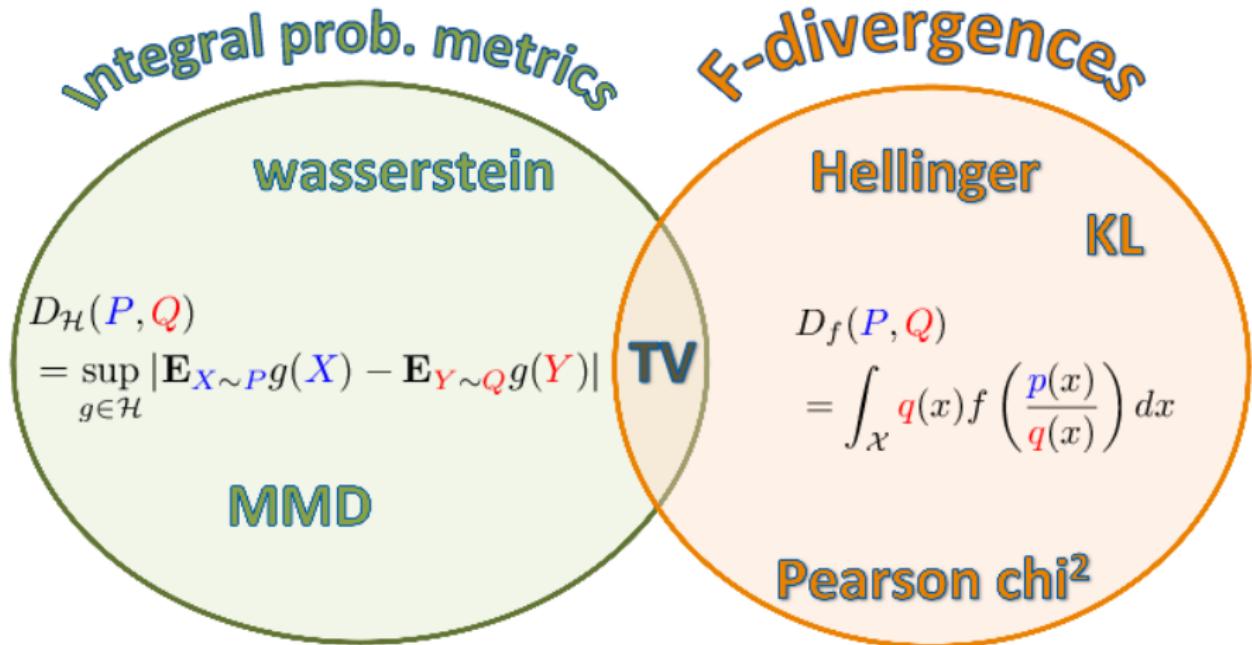
Divergences



Divergences



Divergences



Sriperumbudur, Fukumizu, G, Schoelkopf, Lanckriet (2012)

Overview

The Maximum mean discrepancy:

- How to compute and interpret the MMD
- How to train the MMD
- Application to troubleshooting GANs

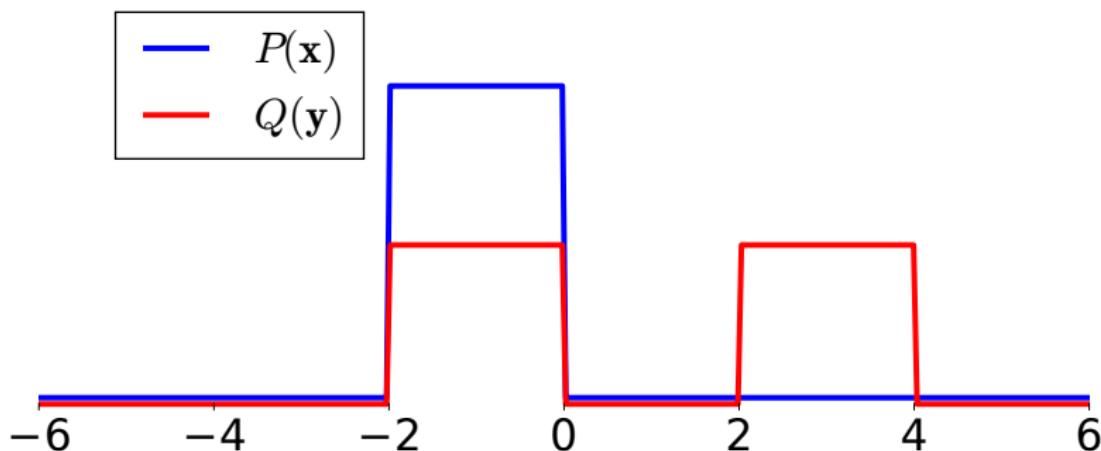
The ME test statistic:

- Informative, linear time features for comparing distributions
- How to learn these features

TL;DR: Variance matters.

The maximum mean discrepancy

Are P and Q different?



Maximum mean discrepancy (on sample)

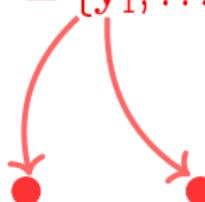


Maximum mean discrepancy (on sample)

Observe $X = \{x_1, \dots, x_n\} \sim P$

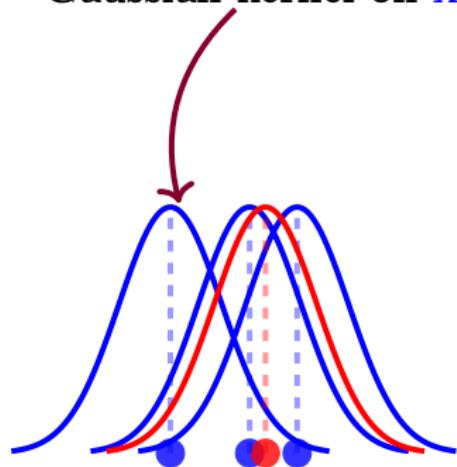


Observe $Y = \{y_1, \dots, y_n\} \sim Q$

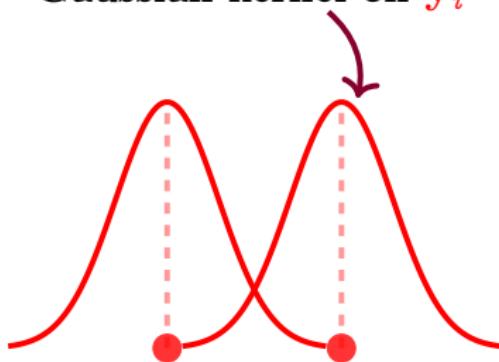


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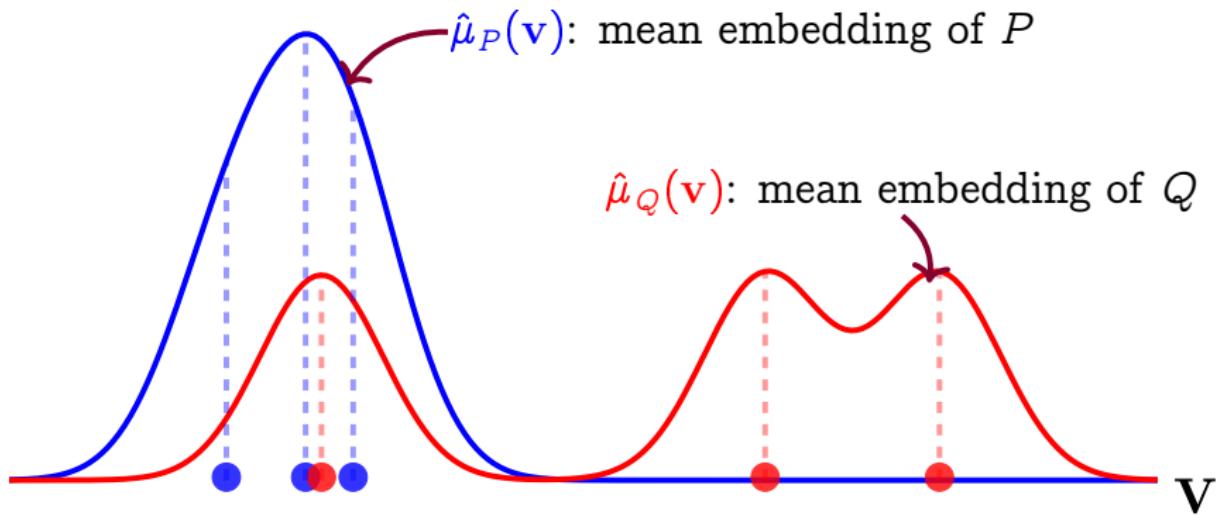
Gaussian kernel on x_i



Gaussian kernel on y_i

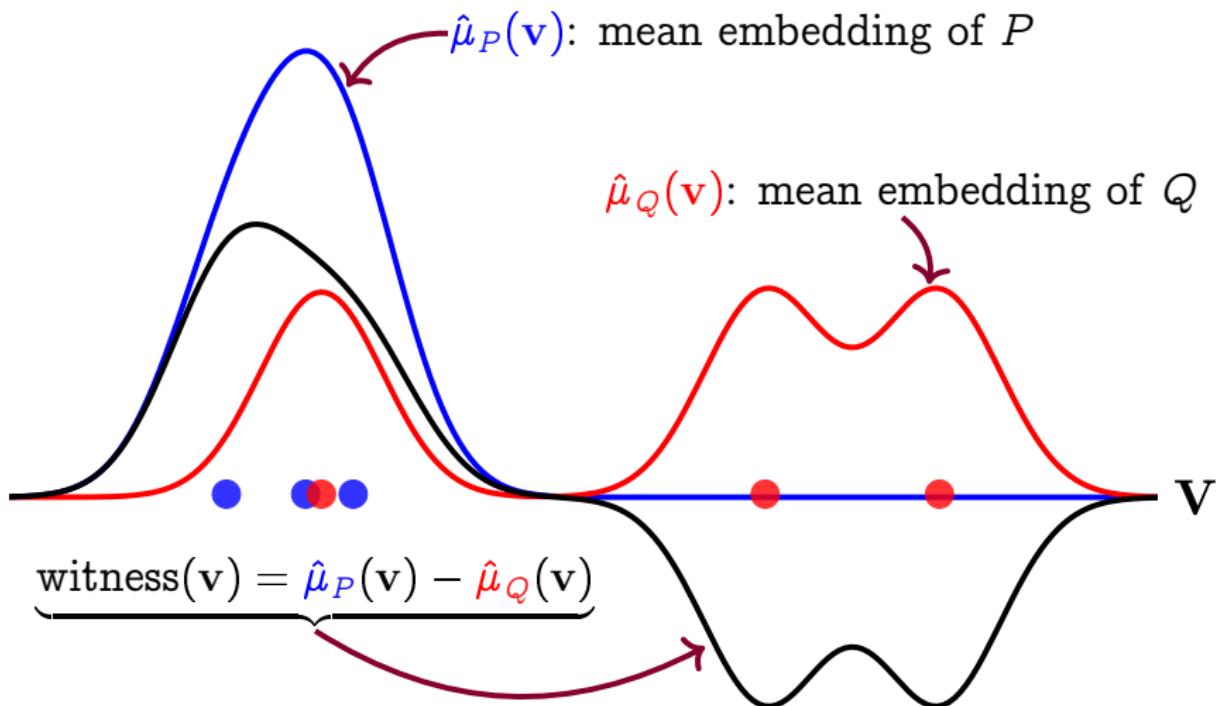


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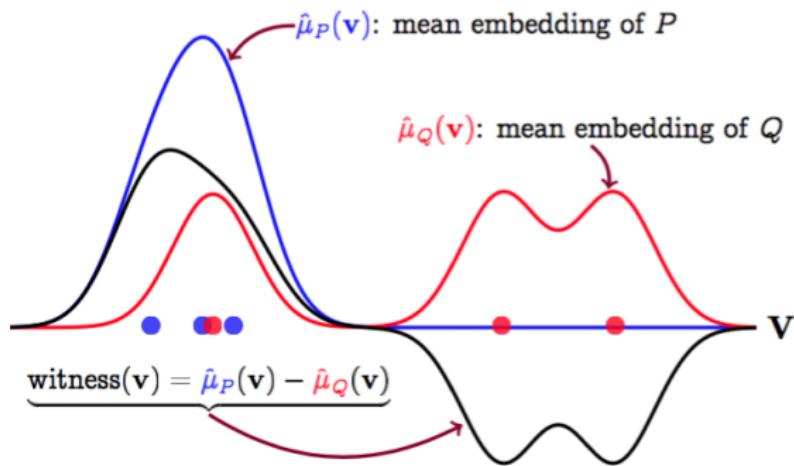


$$\hat{\mu}_P(v) := \frac{1}{m} \sum_{i=1}^m k(x_i, v)$$

Maximum mean discrepancy (on sample)



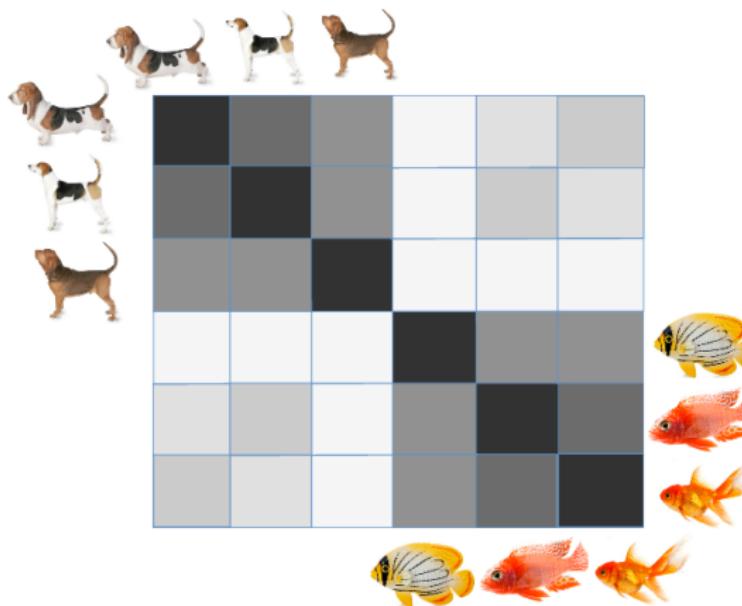
Maximum mean discrepancy (on sample)



$$\begin{aligned}\widehat{MMD}^2 &= \|\text{witness}(\mathbf{v})\|_{\mathcal{F}}^2 \\ &= \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathbf{x}_i, \mathbf{x}_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathbf{y}_i, \mathbf{y}_j) \\ &\quad - \frac{2}{n^2} \sum_{i,j} k(\mathbf{x}_i, \mathbf{y}_j)\end{aligned}$$

Overview

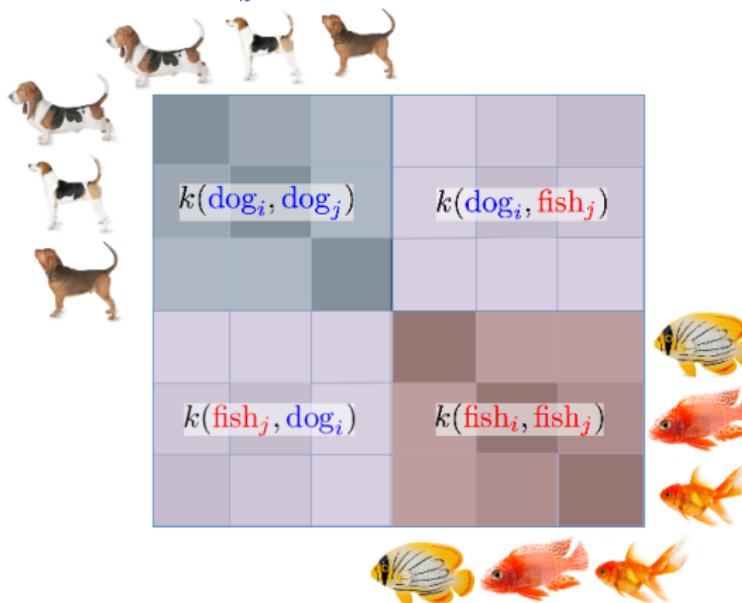
- Dogs ($= P$) and fish ($= Q$) example revisited
- Each entry is one of $k(\text{dog}_i, \text{dog}_j)$, $k(\text{dog}_i, \text{fish}_j)$, or $k(\text{fish}_i, \text{fish}_j)$



Overview

The maximum mean discrepancy:

$$\widehat{MMD}^2 = \frac{1}{n(n-1)} \sum_{i \neq j} k(\text{dog}_i, \text{dog}_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\text{fish}_i, \text{fish}_j) - \frac{2}{n^2} \sum_{i,j} k(\text{dog}_i, \text{fish}_j)$$



Asymptotics of MMD

- The MMD:

$$\widehat{MMD}^2 = \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathbf{x}_i, \mathbf{x}_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathbf{y}_i, \mathbf{y}_j) - \frac{2}{n^2} \sum_{i,j} k(\mathbf{x}_i, \mathbf{y}_j)$$

but how to choose the kernel?

Asymptotics of MMD

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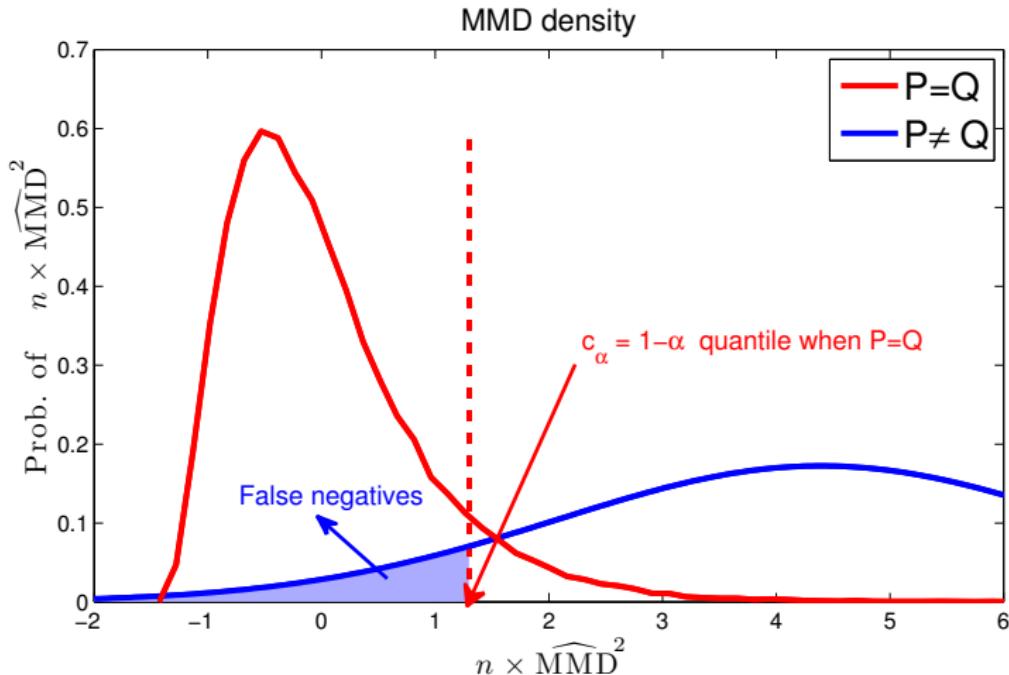
but how to choose the kernel?

■ Perspective from statistical hypothesis testing:

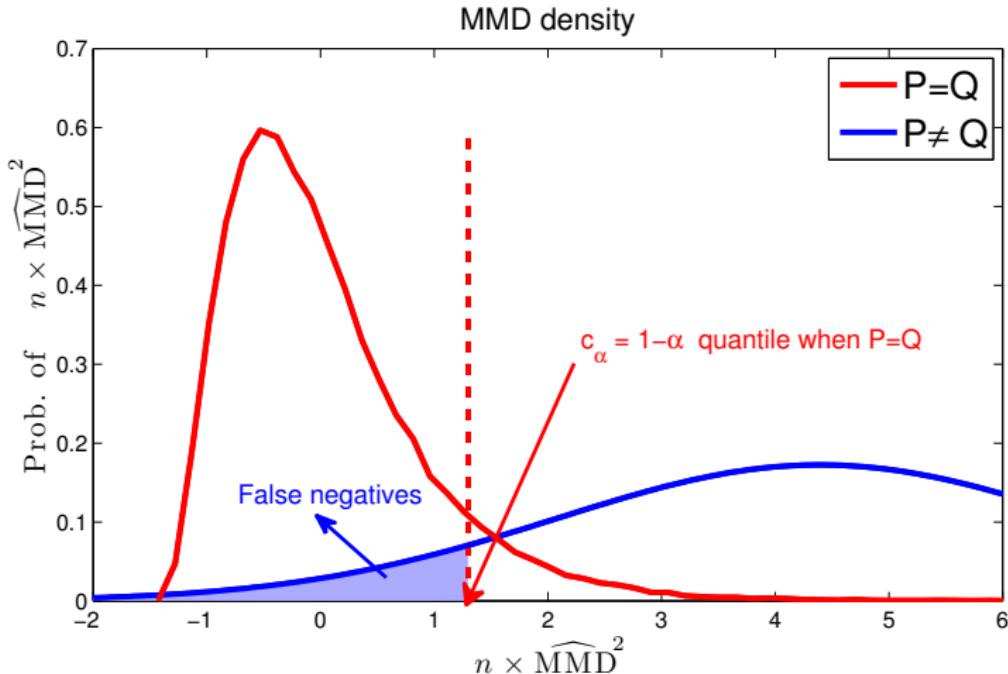
- When $P = Q$ then \widehat{MMD}^2 “close to zero”.
- When $P \neq Q$ then \widehat{MMD}^2 “far from zero”

■ Threshold c_α for \widehat{MMD}^2 gives false positive rate α

A statistical test

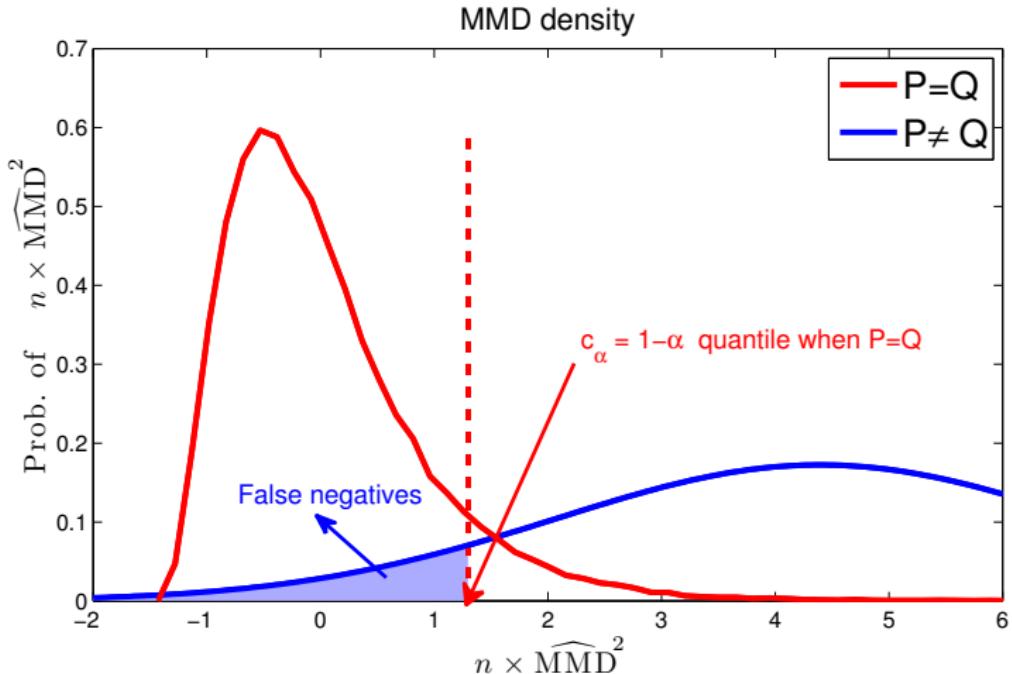


A statistical test



Best kernel gives lowest **false negative** rate (=highest **power**)

A statistical test



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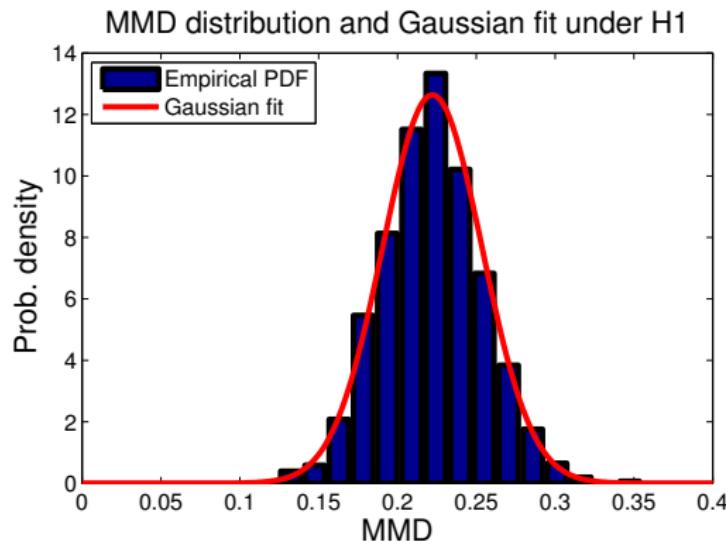
.... but can you train for this?

Asymptotics of MMD

- When $P \neq Q$, statistic is asymptotically normal,

$$\frac{\widehat{\text{MMD}}^2 - \text{MMD}(P, Q)}{\sqrt{V_n(P, Q)}} \xrightarrow{D} \mathcal{N}(0, 1),$$

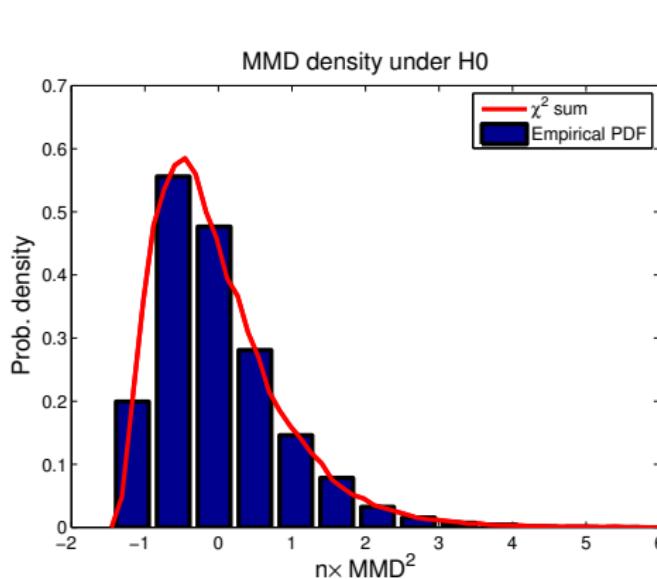
where $\text{MMD}(P, Q)$ is population MMD, and $V_n(P, Q) = O(n^{-1})$.



Asymptotics of MMD

Where $P = Q$, statistic has asymptotic distribution

$$n\widehat{\text{MMD}}^2 \sim \sum_{l=1}^{\infty} \lambda_l [z_l^2 - 2]$$



where

$$\lambda_i \psi_i(x') = \int_{\mathcal{X}} \underbrace{\tilde{k}(x, x')}_{\text{centred}} \psi_i(x) dP(x)$$

$$z_l \sim \mathcal{N}(0, 2) \quad \text{i.i.d.}$$

Optimizing test power

The power of our test (\Pr_1 denotes probability under $P \neq Q$):

$$\Pr_1 \left(n \widehat{\text{MMD}}^2 > \hat{c}_\alpha \right)$$

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$$\begin{aligned} & \Pr_1 \left(n \widehat{\text{MMD}}^2 > \hat{c}_\alpha \right) \\ & \rightarrow 1 - \Phi \left(\frac{c_\alpha}{n \sqrt{V_n(P, Q)}} - \frac{\text{MMD}^2(P, Q)}{\sqrt{V_n(P, Q)}} \right) \end{aligned}$$

where

- Φ is the CDF of the standard normal distribution.
- \hat{c}_α is an estimate of c_α test threshold.

Optimizing test power

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First term asymptotically negligible!

Optimizing test power

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To maximize test power, maximize

$$\frac{\text{MMD}^2(P, Q)}{\sqrt{V_n(P, Q)}}$$

(Sutherland, Tung, Strathmann, De, Ramdas, Smola, G., in review for ICLR 2017)

Code: github.com/douglalsutherland/opt-mmd

Troubleshooting for generative adversarial networks



MNIST samples

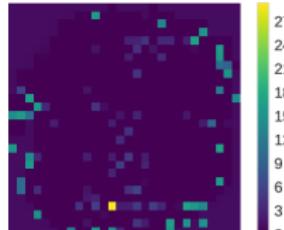


Samples from a GAN

Troubleshooting for generative adversarial networks



MNIST samples



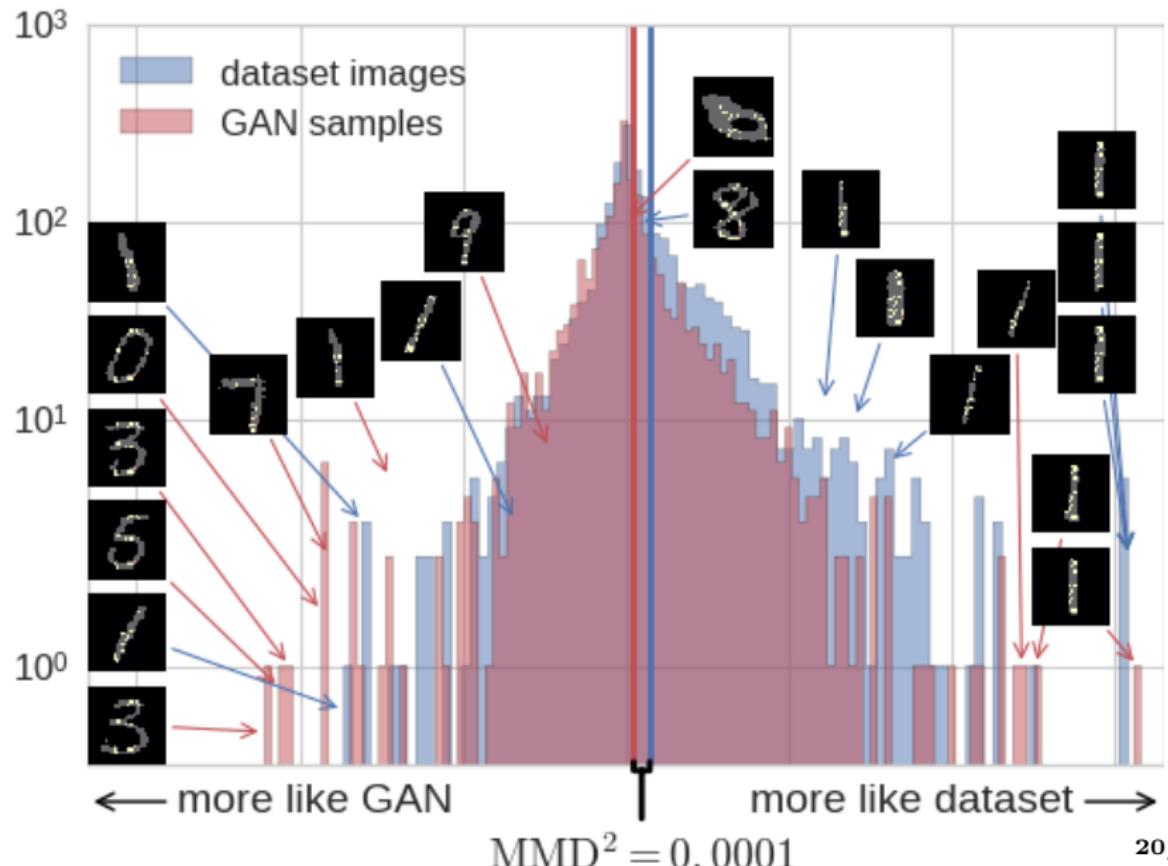
ARD map



Samples from a GAN

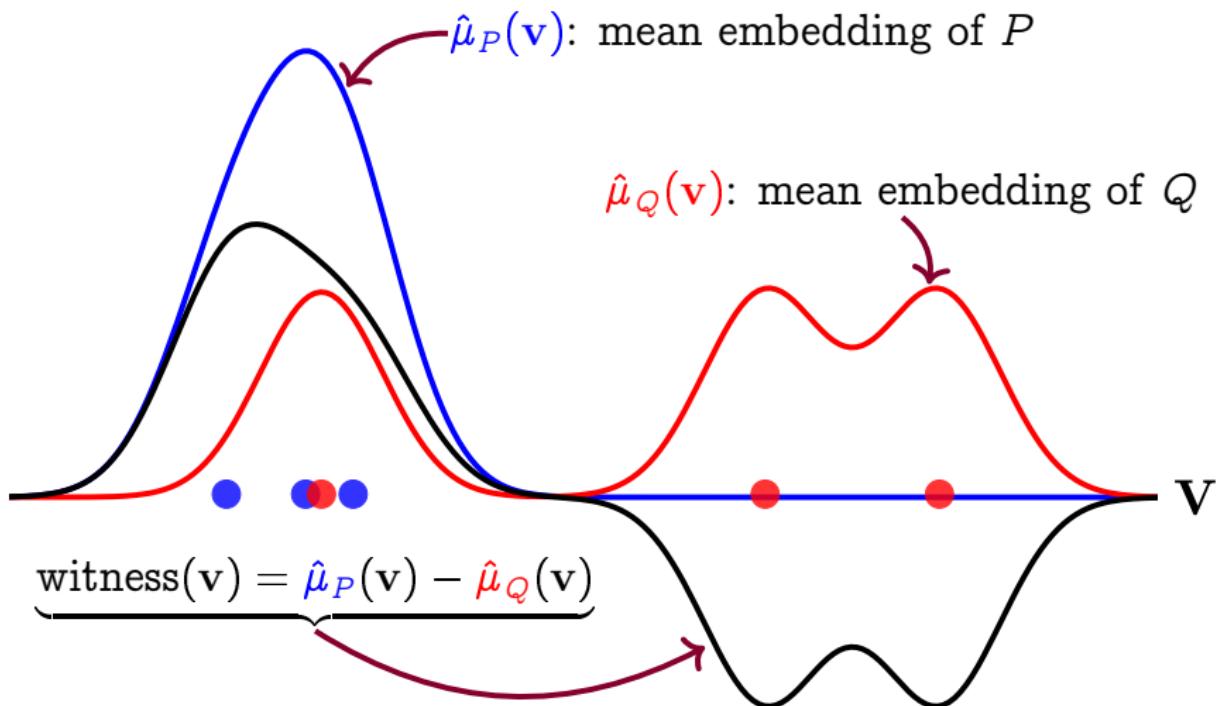
- Power for **optimized ARD kernel**: 1.00 at $\alpha = 0.01$
- Power for optimized RBF kernel: 0.57 at $\alpha = 0.01$

Benchmarking generative adversarial networks

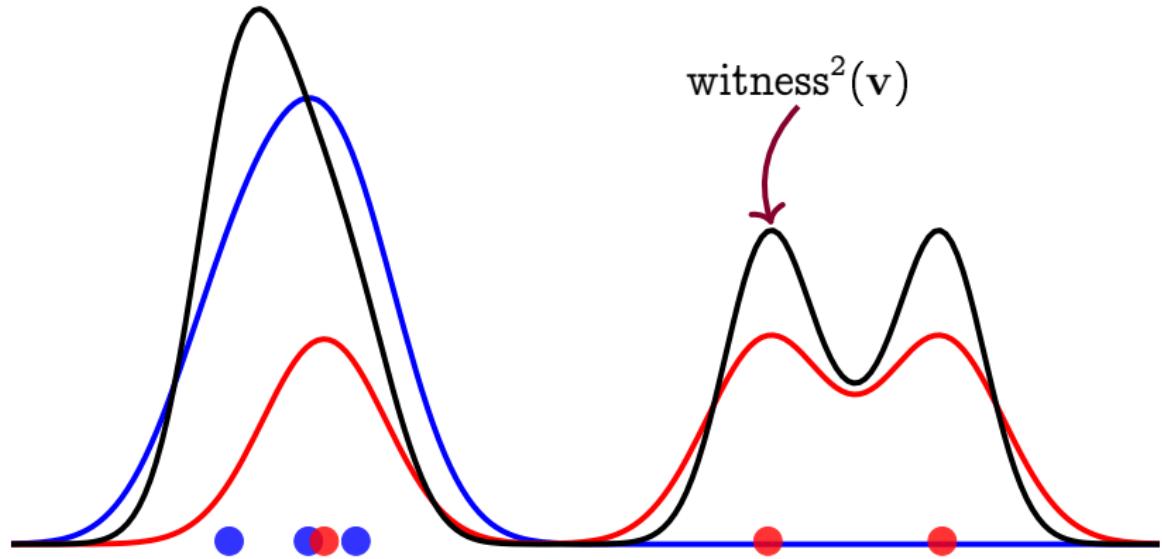


The ME statistic and test

Distinguishing Feature(s)

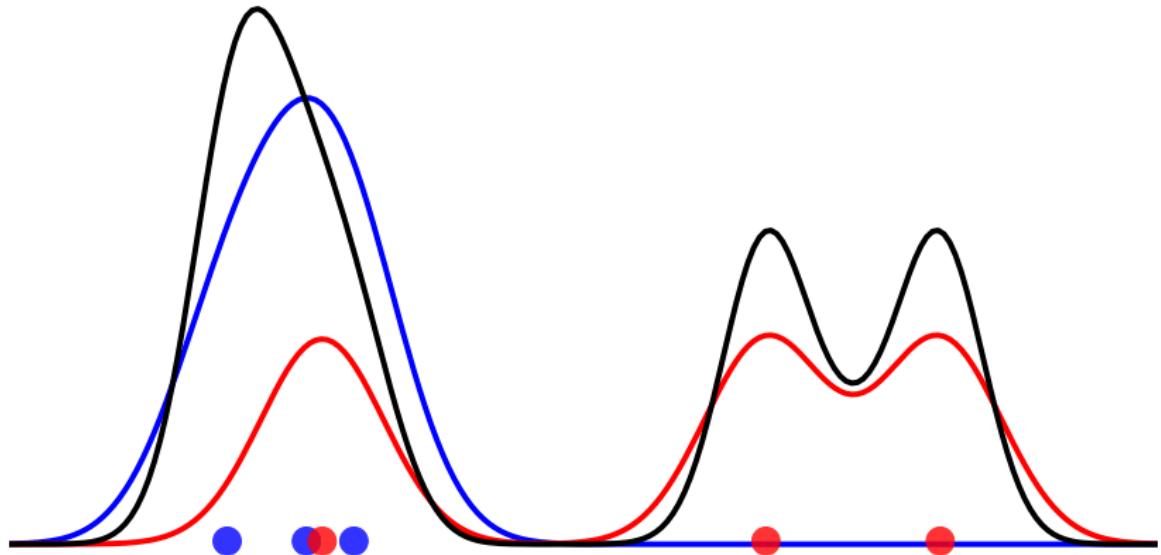


Distinguishing Feature(s)



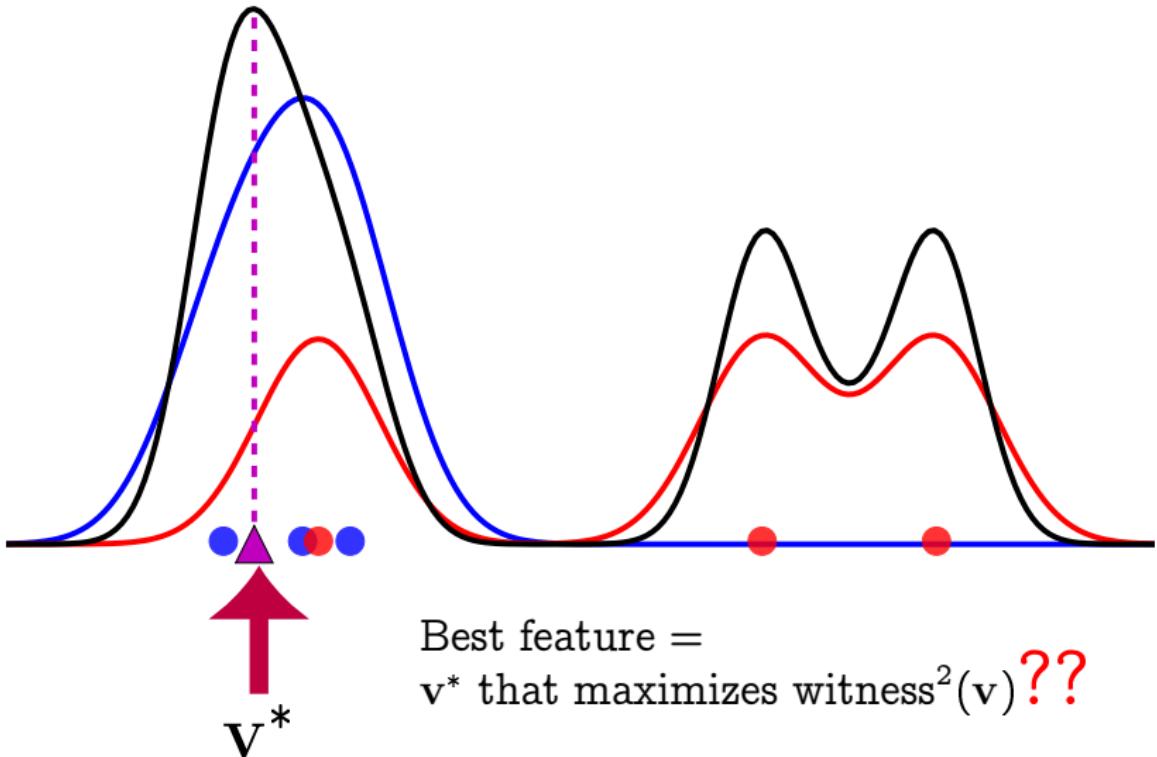
Take square of witness (only worry about amplitude)

Distinguishing Feature(s)

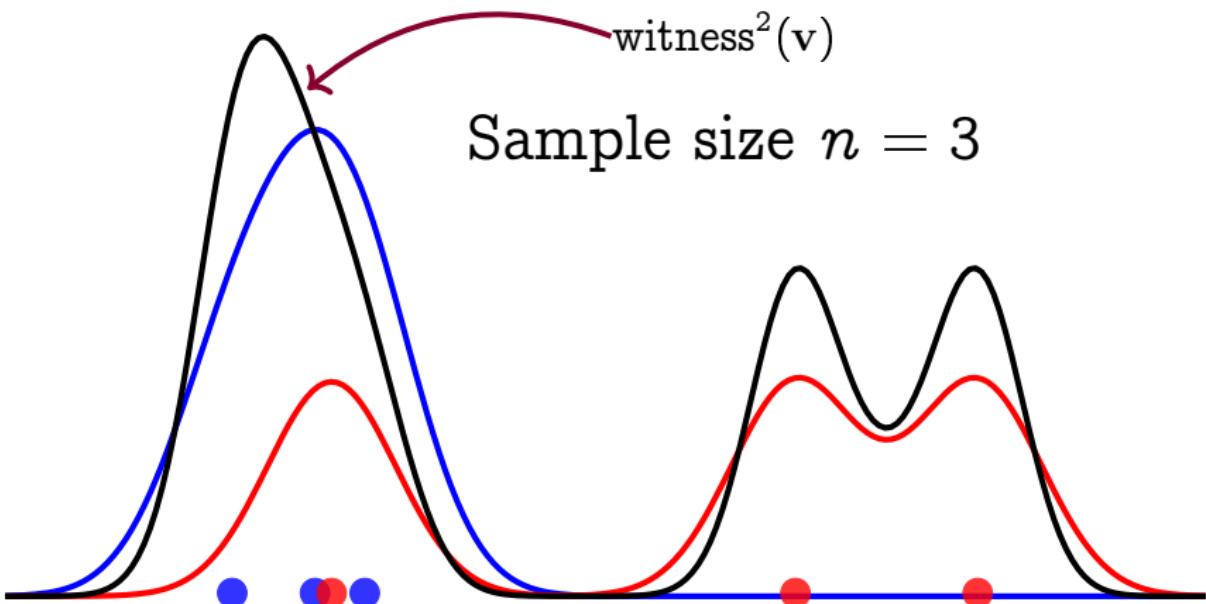


- New test statistic: witness² at a single v^* ;
- Linear time in number n of samples
-but how to choose best feature v^* ?

Distinguishing Feature(s)

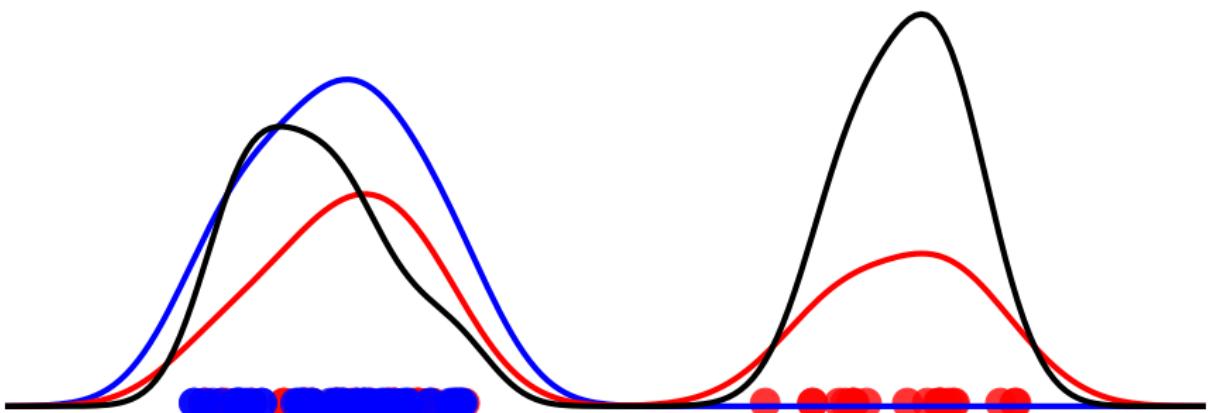


Distinguishing Feature(s)



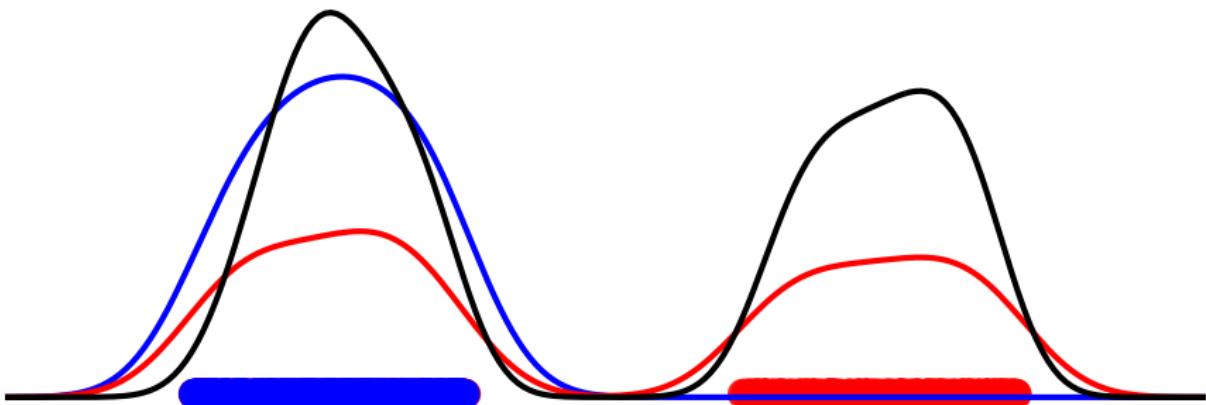
Distinguishing Feature(s)

Sample size $n = 50$

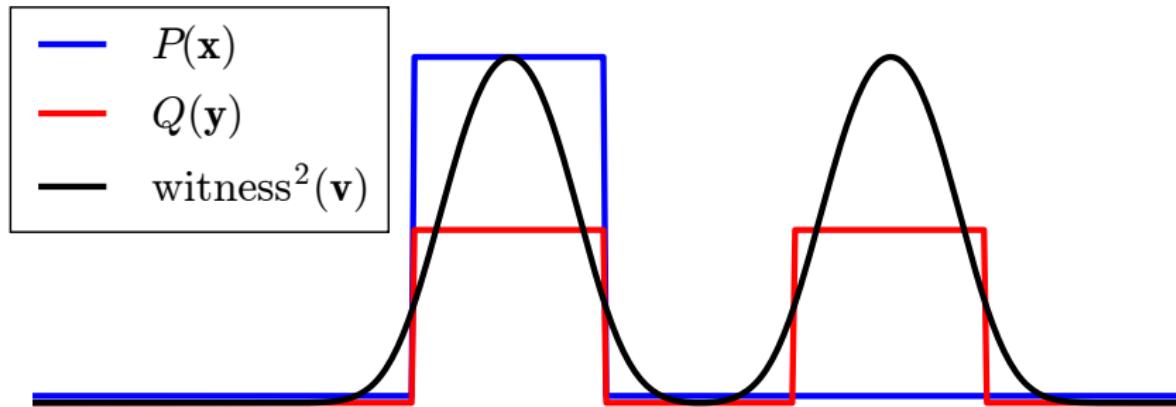


Distinguishing Feature(s)

Sample size $n = 500$



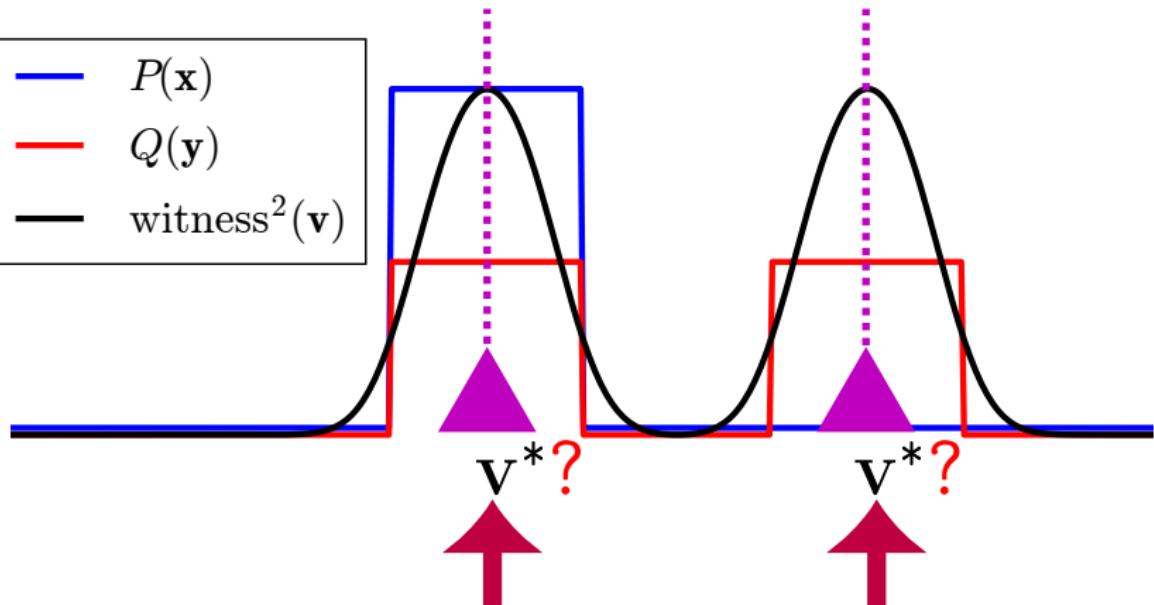
Distinguishing Feature(s)



Population witness² function

Distinguishing Feature(s)

- $P(\mathbf{x})$
- $Q(\mathbf{y})$
- $\text{witness}^2(\mathbf{v})$



Variance of witness function

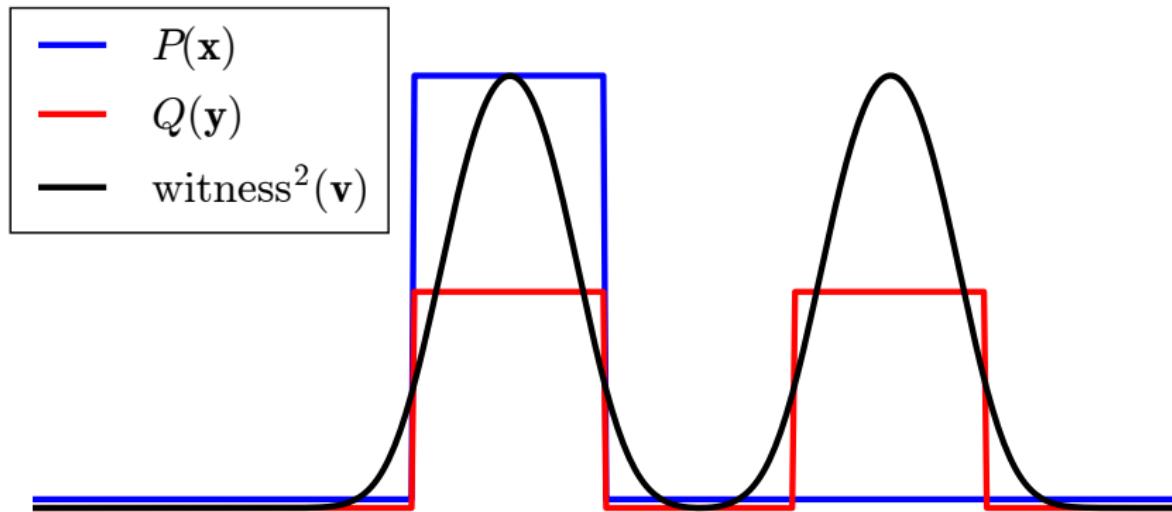
- Variance at \mathbf{v} = variance of X at \mathbf{v} + variance of Y at \mathbf{v} .
- ME Statistic: $\hat{\lambda}_n(\mathbf{v}) := n \frac{\text{witness}^2(\mathbf{v})}{\text{variance of } \mathbf{v}}$.

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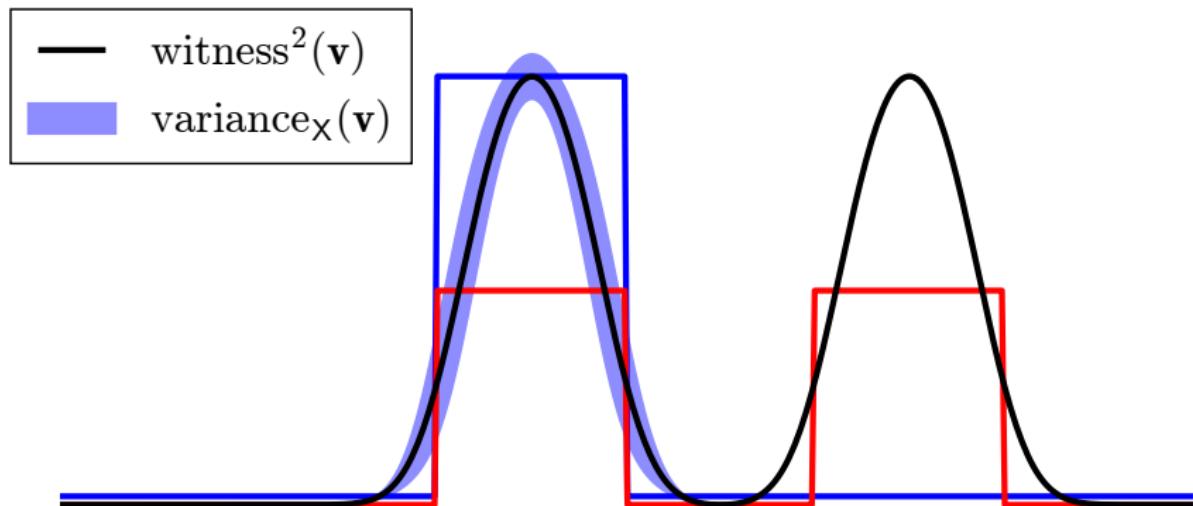
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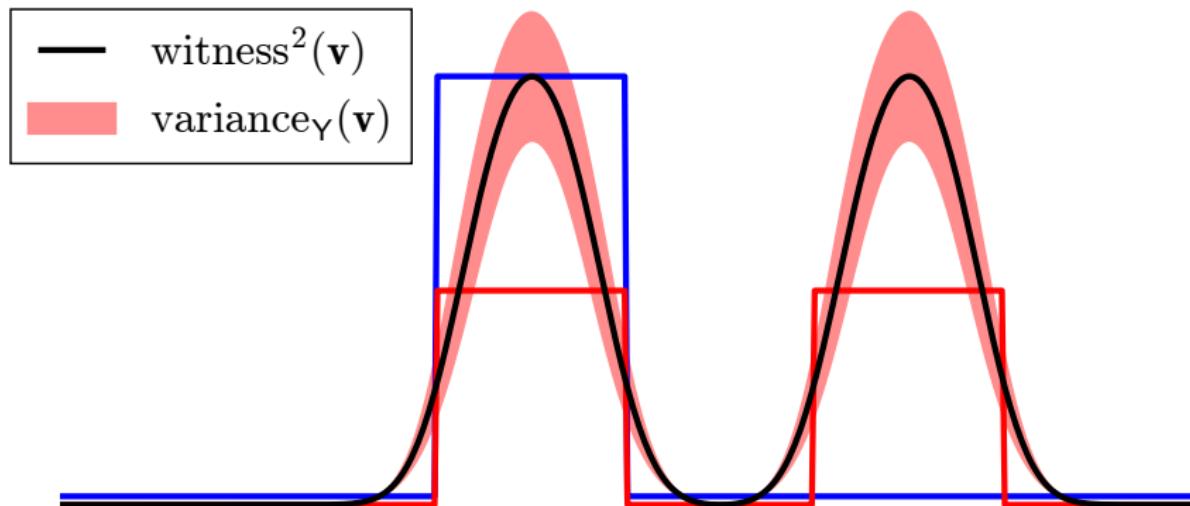
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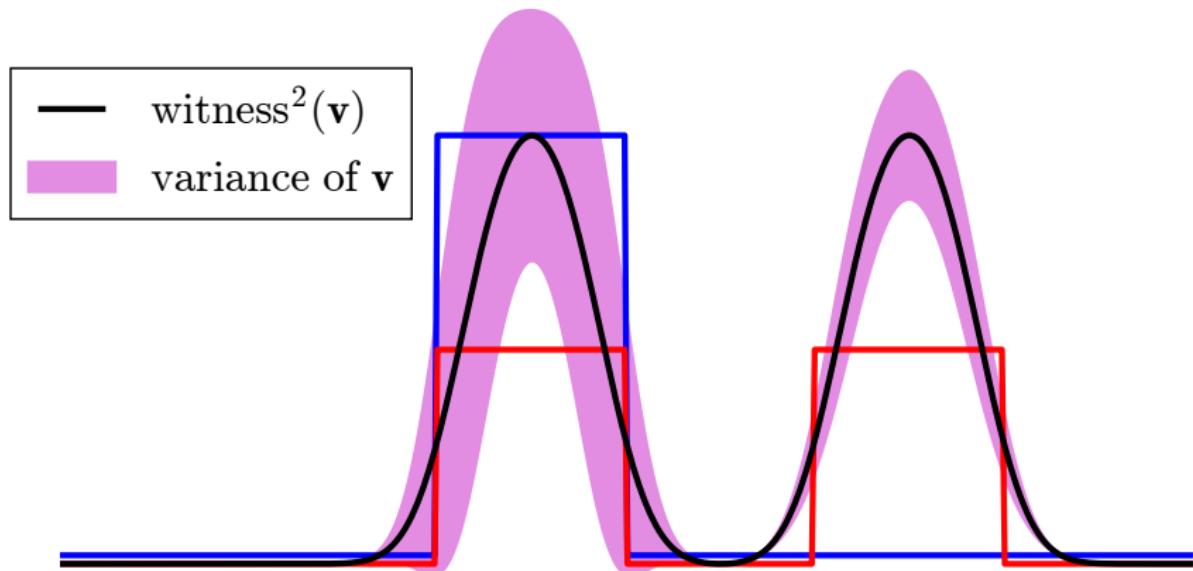
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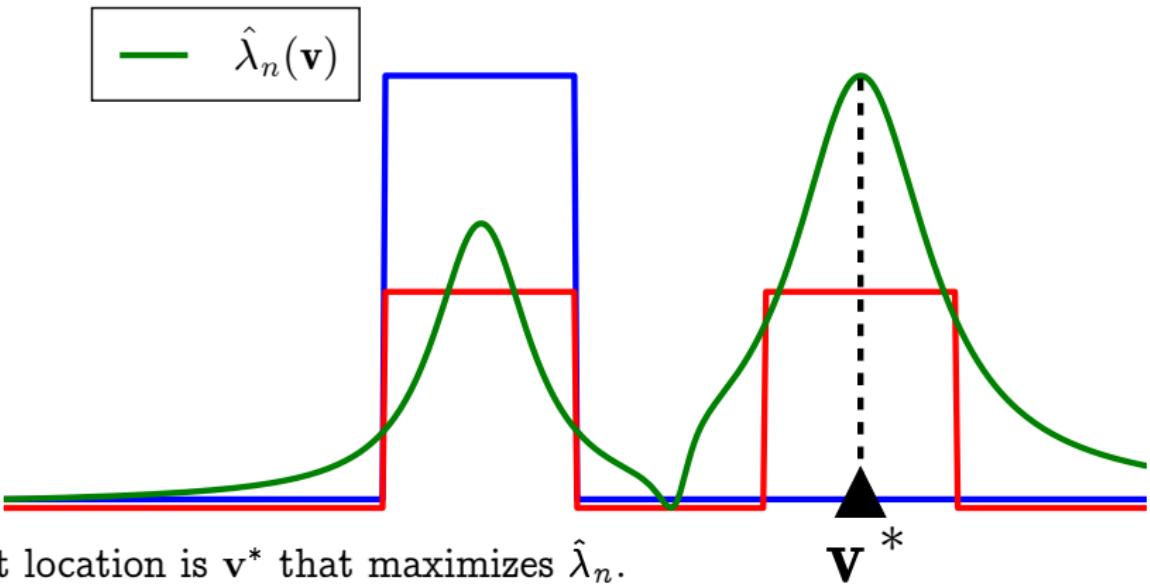
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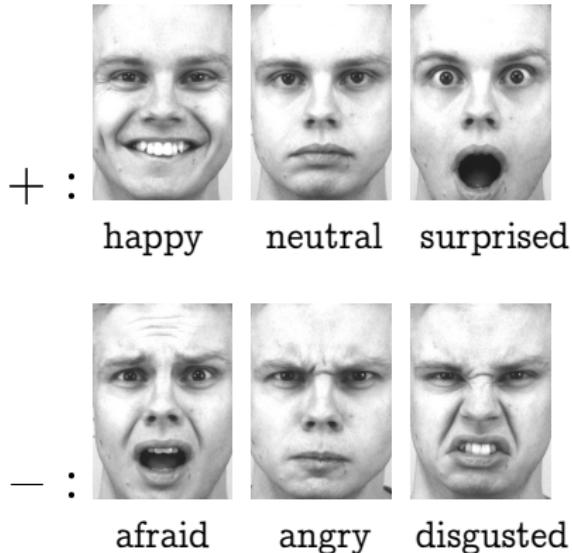
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- Best location is \mathbf{v}^* that maximizes $\hat{\lambda}_n$.
- Improve performance using multiple locations $\{\mathbf{v}_j^*\}_{j=1}^J$

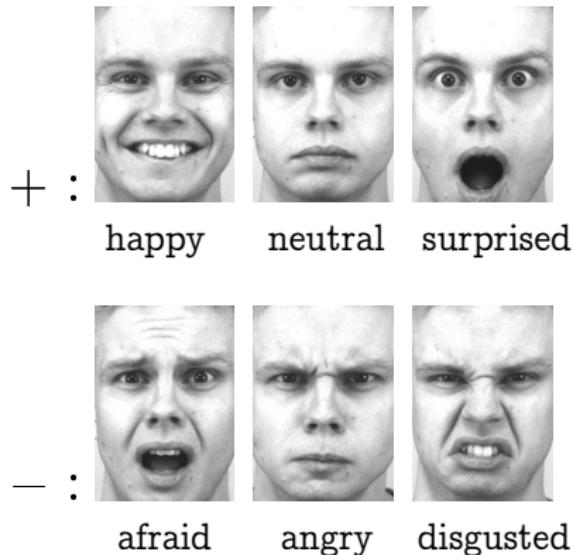
Distinguishing Positive/Negative Emotions



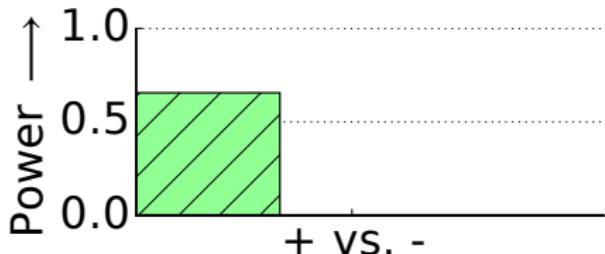
- 35 females and 35 males (Lundqvist et al., 1998).
- $48 \times 34 = 1632$ dimensions.
Pixel features.
- Sample size: 402.

- The proposed test achieves **maximum test power** in time $O(n)$.
- Informative features: differences at the nose, and smile lines.

Distinguishing Positive/Negative Emotions

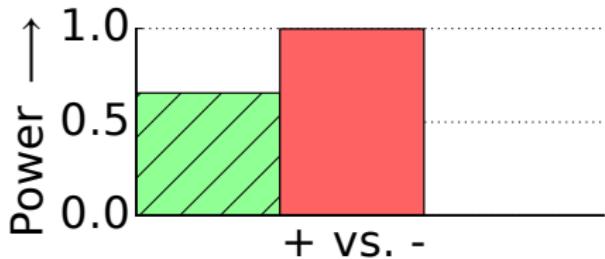
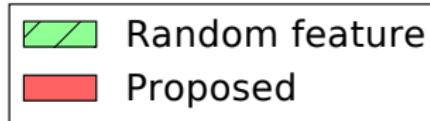
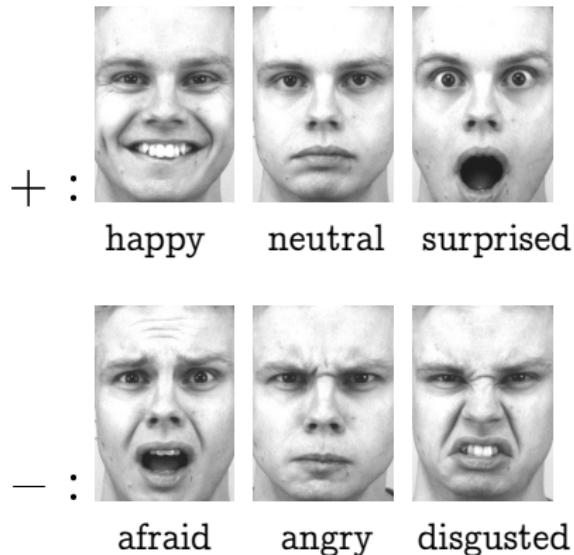


Random feature



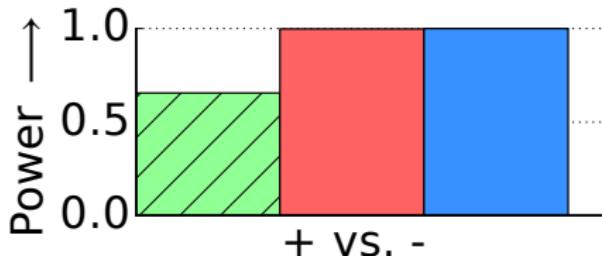
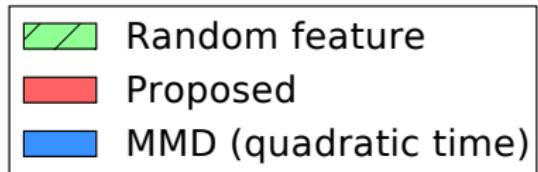
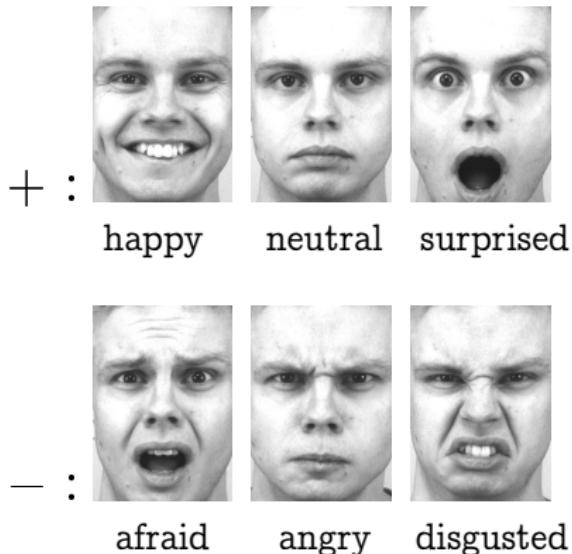
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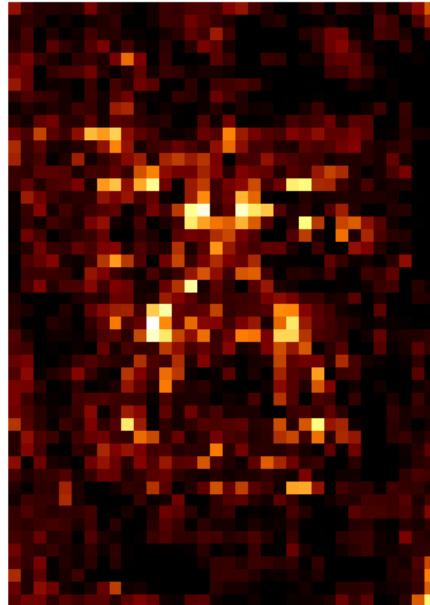
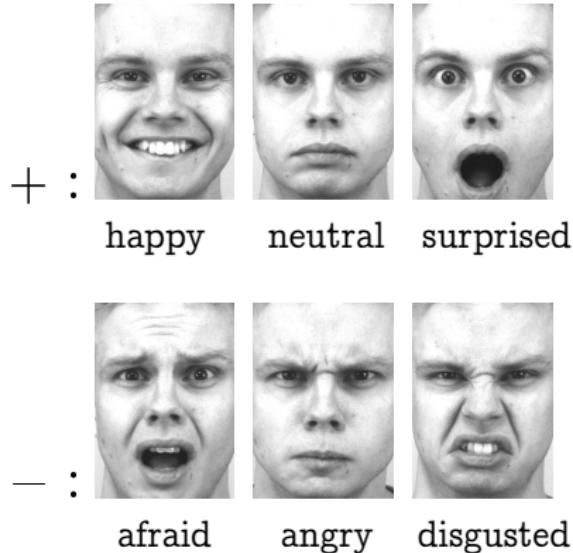
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Distinguishing Positive/Negative Emotions



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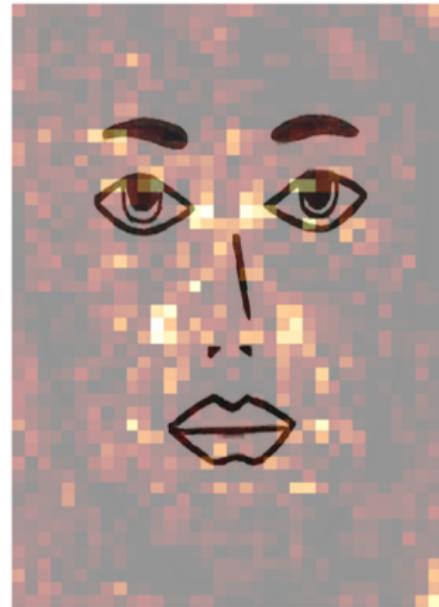
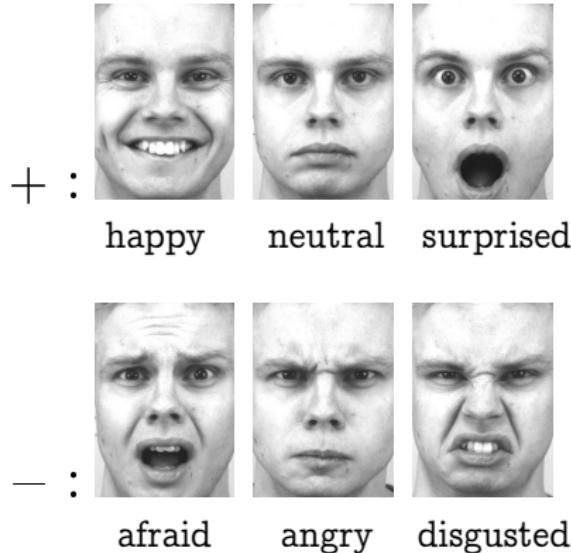
Distinguishing Positive/Negative Emotions



Learned feature

- The proposed test achieves **maximum test power** in time $O(n)$.
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Distinguishing Positive/Negative Emotions



Learned feature

- The proposed test achieves **maximum test power** in time $O(n)$.
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Final thoughts

Witness function approaches:

- Diversity of samples:
 - MMD test uses pairwise similarities between all samples
 - ME test uses similarities to J reference features
- Disjoint support of generator/data distributions
 - Witness function is smooth

Other discriminator heuristics:

- Diversity of samples by minibatch heuristic (add as feature **distances to neighbour samples**) Salimans et al. (2016)
- Disjoint support treated by **adding noise to “blur” images** Arjovsky and Bottou (2016), Sønderby et al (2016)

Co-authors

Students and postdocs:

- Kacper Chwialkowski (at Voleon)
- Wittawat Jitkrittum
- Heiko Strathmann
- Dougal Sutherland

Collaborators

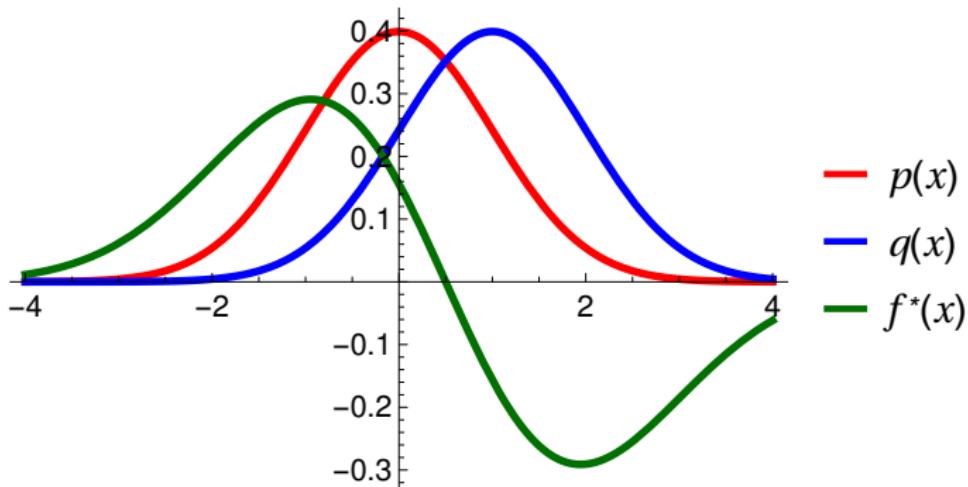
- Kenji Fukumizu
- Krikamol Muandet
- Bernhard Schoelkopf
- Bharath Sriperumbudur
- Zoltan Szabo

Questions?

Testing against a probabilistic model

Statistical model criticism

$$MMD(\textcolor{red}{P}, \textcolor{blue}{Q}) = \|f^*\|^2 = \sup_{\|f\|_{\mathcal{F}} \leq 1} [E_{\textcolor{teal}{Q}} f - E_{\textcolor{red}{P}} f]$$



$f^*(x)$ is the witness function

Can we compute MMD with samples from $\textcolor{blue}{Q}$ and a **model** $\textcolor{red}{P}$?

Problem: usually can't compute $E_{\textcolor{red}{P}} f$ in closed form.

Stein idea

To get rid of $E_{\textcolor{red}{p}} f$ in

$$\sup_{\|f\|_{\mathcal{F}} \leq 1} [E_q f - E_{\textcolor{red}{p}} f]$$

we define the **Stein operator**

$$T_{\textcolor{red}{p}} f = \partial_x f + f (\partial_x \log \textcolor{blue}{p})$$

Then

$$E_{\textcolor{red}{P}} T_{\textcolor{red}{P}} f = 0$$

subject to appropriate boundary conditions. (Oates, Girolami, Chopin, 2016)

Maximum Stein Discrepancy

Stein operator

$$T_{\textcolor{red}{p}} f = \partial_x f + f \partial_x (\log \textcolor{red}{p})$$

Maximum Stein Discrepancy (MSD)

$$MSD(\textcolor{red}{p}, q, \mathcal{F}) = \sup_{\|\textcolor{teal}{g}\|_{\mathcal{F}} \leq 1} E_q T_{\textcolor{red}{p}} g - E_{\textcolor{red}{p}} T_{\textcolor{red}{p}} g$$

Maximum Stein Discrepancy

Stein operator

$$T_{\textcolor{red}{p}} f = \partial_x f + f \partial_x (\log \textcolor{red}{p})$$

Maximum Stein Discrepancy (MSD)

$$MSD(\textcolor{red}{p}, q, \mathcal{F}) = \sup_{\|g\|_{\mathcal{F}} \leq 1} E_q T_{\textcolor{red}{p}} g - \cancel{E_p T_{\textcolor{red}{p}} g}$$

Maximum Stein Discrepancy

Stein operator

$$T_{\textcolor{red}{p}} f = \partial_x f + f \partial_x (\log \textcolor{red}{p})$$

Maximum Stein Discrepancy (MSD)

$$MSD(\textcolor{red}{p}, q, \mathcal{F}) = \sup_{\|g\|_{\mathcal{F}} \leq 1} E_q T_{\textcolor{red}{p}} g - \cancel{E_{\textcolor{red}{p}} T_{\textcolor{red}{p}} \cancel{g}} = \sup_{\|g\|_{\mathcal{F}} \leq 1} E_q T_{\textcolor{red}{p}} g$$

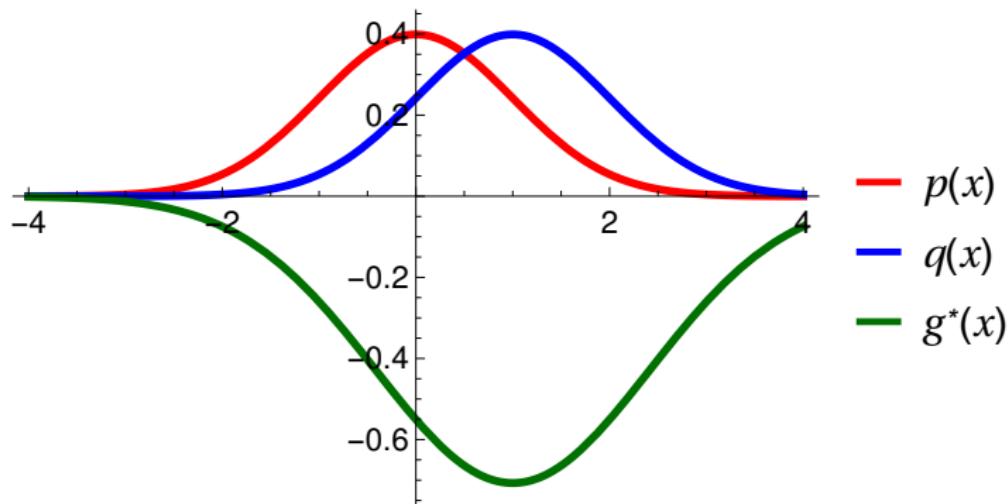
Maximum Stein Discrepancy

Stein operator

$$T_p f = \partial_x f + f \partial_x (\log p)$$

Maximum Stein Discrepancy (MSD)

$$MSD(p, q, \mathcal{F}) = \sup_{\|g\|_{\mathcal{F}} \leq 1} E_q T_p g - \cancel{E_p T_p g} = \sup_{\|g\|_{\mathcal{F}} \leq 1} E_q T_p g$$



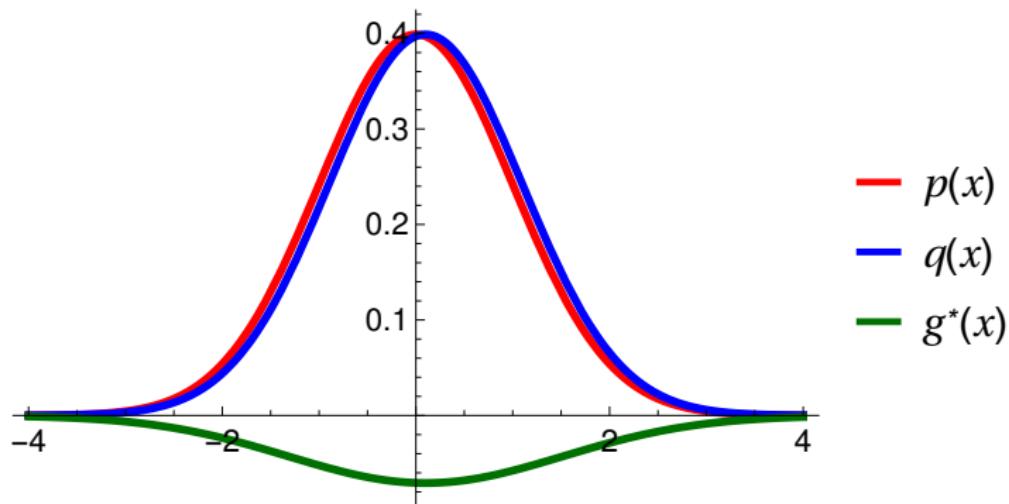
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Maximum Stein Discrepancy (MSD)

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Maximum stein discrepancy

Closed-form expression for MSD: given $Z, Z' \sim q$, then (Chwialkowski, Strathmann, G., 2016) (Liu, Lee, Jordan 2016)

$$\text{MSD}(p, q, \mathcal{F}) = E_q h_p(Z, Z')$$

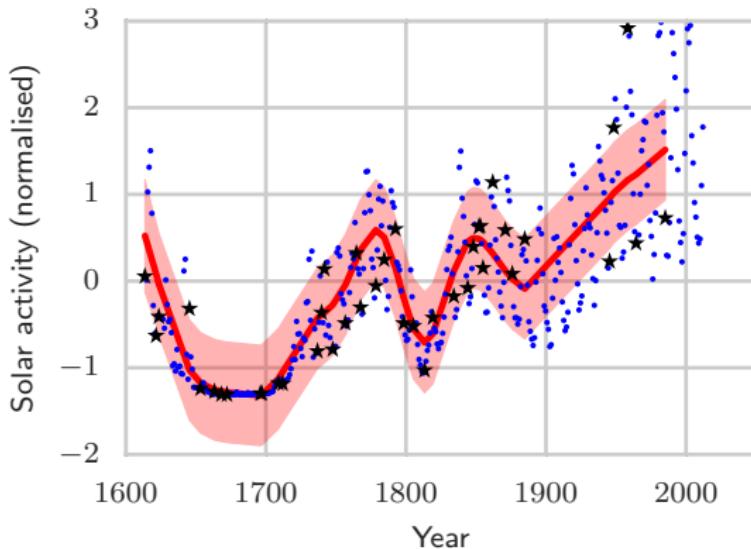
where

$$\begin{aligned} h_p(x, y) := & \partial_x \log p(x) \partial_x \log p(y) k(x, y) \\ & + \partial_y \log p(y) \partial_x k(x, y) \\ & + \partial_x \log p(x) \partial_y k(x, y) \\ & + \partial_x \partial_y k(x, y) \end{aligned}$$

and k is RKHS kernel for \mathcal{F}

Only depends on kernel and $\partial_x \log p(x)$. Do not need to normalize p , or sample from it.

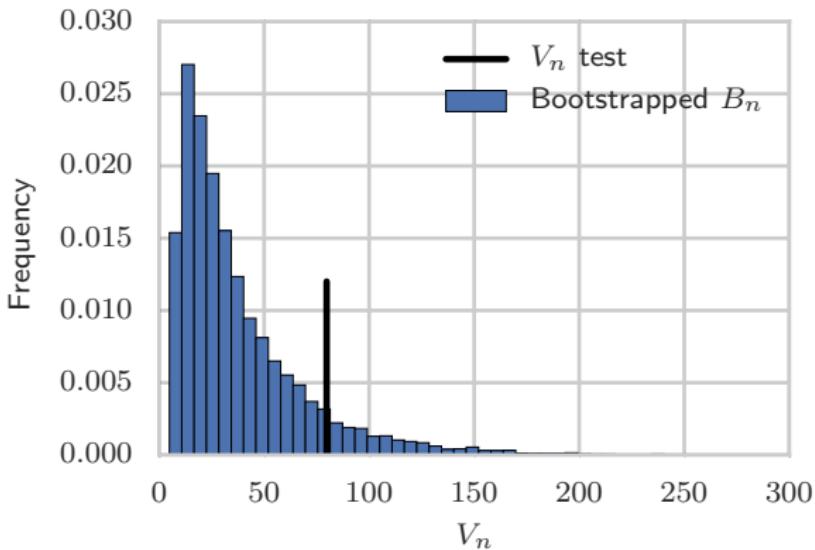
Statistical model criticism



Test the hypothesis that a Gaussian process **model**, learned from **data** \star , is a good fit for the test data (example from Lloyd and Ghahramani, 2015)

Code: https://github.com/karlnapf/kernel_goodness_of_fit

Statistical model criticism



Test the hypothesis that a Gaussian process **model**, learned from data \star , is a good fit for the test data