Role Fit: Shure Senior Embedded Software Engineer

Context: This page maps the Shure job requirements to specific project evidence in this portfolio. Each section below corresponds to a key requirement, with links to relevant projects and explanations of how they demonstrate the skill.

Design, develop and test embedded software and associated components for audio products (C/C++)

- **Real-Time Audio Separation**: Teensy firmware, I2S/UART C/C++ code, Raspberry Pi processing and multithreaded Python demos demonstrating low-latency embedded audio capture and processing.
- **Analyzing Tennis Matches Based on Audio**: MATLAB-based audio signal processing and algorithm development (transient detection, spectral analysis) relevant to audio product R&D.
- **Stratum Synthesizer**: assembly-level audio engine and drivers showing deep knowledge of audio signal path and constraints.

Hardware drivers, embedded software applications, audio and control networking (C/C++)

- **Stratum Synthesizer**: speaker and SD drivers, low-level peripheral control.
- **Zumo Shield Robot**: STM32 PWM, timers, UART and GPIO; illustrates driver usage and hardware control.

Real-time, multitasking, RTOS concepts and debugging (Embedded Linux/FreeRTOS/etc)

- **Real-Time Audio Separation**: real-time constraints, multicore/multithreaded processing and synchronization.
- **Zumo Shield Robot**: real-time control loop design and hardware timing considerations (timers, interrupts, PWM).

Networking & protocols (UART, I2S, possibility to work with Ethernet/TCP/UDP/Wi-Fi)

- **Real-Time Audio Separation**: I2S audio capture and UART streaming; demonstrates protocol-level understanding and embedded networking concepts.

Software architecture, design, and testing (reviews, unit/integration tests)

- All projects include design notes and reports; the portfolio includes a test-oriented project (Toyota Auto-Validation) and unit tests in other repos (e.g., the archived Glasgow repo had tests). I prioritize clear documentation and testability.

Hardware debugging and release processes

- **Zumo Shield Robot** and **Stratum Synthesizer** show hardware bring-up, telemetry, and iterative debugging workflows; Toyota demo shows validation and reporting practices.

Version control and documentation

- Full repositories and README/USAGE/OVERVIEW docs are included with each project; this portfolio itself is version-controlled and deploy-ready.