# MAST30034 Assignment 1

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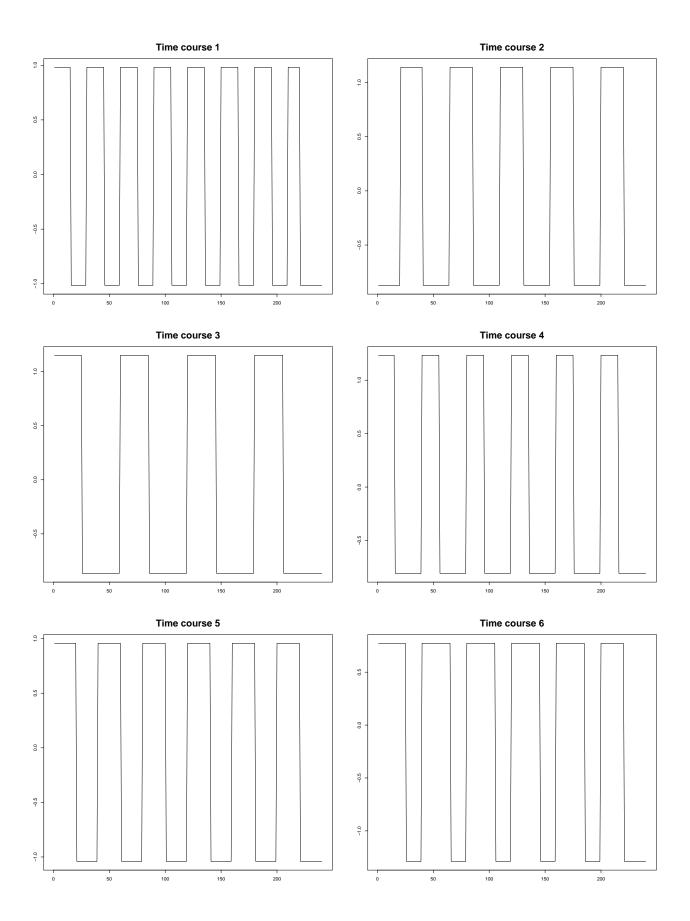
25/08/2021

## Question 1

### Part 1

It is better to standardise because each time course would have a different variance if they were normalised.

```
# Vectors from spec
AV \leftarrow c(0, 20, 0, 0, 0, 0)
IV \leftarrow c(30, 45, 60, 40, 40, 40)
duration_ones <- c(15, 20, 25, 15, 20, 25)
# Matrix to be populated with temporal sources
TC <- matrix(rep(0, 240*6), ncol=6)
par(mfrow = c(3,2))
# Create each temporal source based on the three vectors and plot it
for (i in (1:6)){
  tc <- rep(0, 240)
  arrival <- AV[i]</pre>
  interval <- IV[i]</pre>
  duration <- duration_ones[i]</pre>
  for (j in 1:(240-arrival)){
    if (j\\'interval <= duration){</pre>
      tc[j+arrival] <- 1
    }
  tc[221:240] \leftarrow rep(0, 20)
  TC[, i] <- scale(tc)</pre>
  plot(TC[, i], type="1", main = paste("Time course", i),
                            xlab = "", ylab = "",
                             cex.main = 2)
```

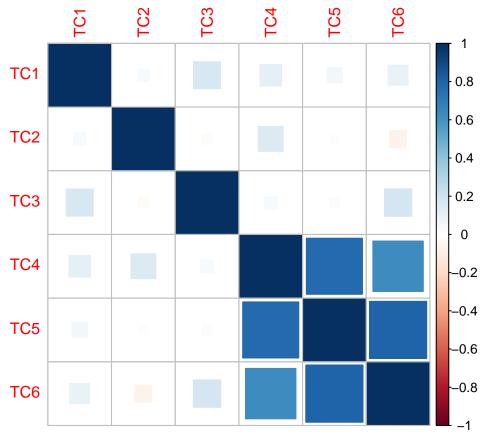


From the plot of the correlation matrix we can see that time courses four, five and six are highly correlated. In particular, four with five, and five with six. It makes sense that these time courses would be correlated as they have the same period and zero onset arrival, thus the nth series of ones in each of these series begins at the same time

```
library(corrplot)

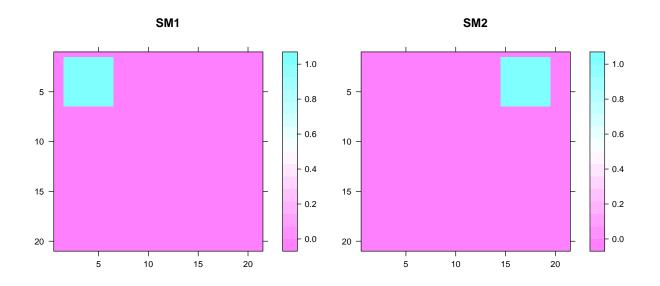
# Convert TC to a dataframe
TCdf <- as.data.frame(TC)
colnames(TCdf) <- c("TC1", "TC2", "TC3", "TC4", "TC5", "TC6")

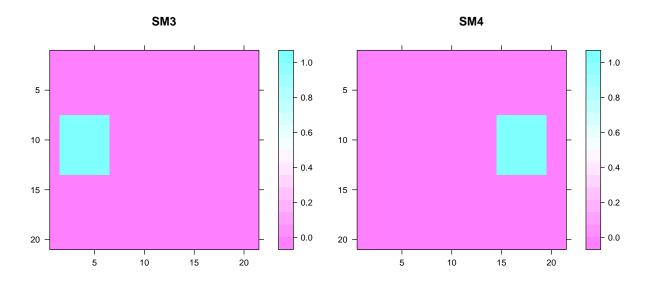
# Calculate and plot the correlation martrix
corrplot(cor(TCdf), method = "square")</pre>
```

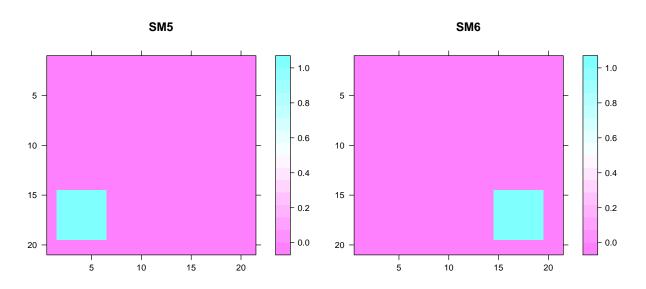


```
library(lattice)
library(gridExtra)
# Initialise array with zeroes
tmpSM \leftarrow array(0, dim = c(6, 21, 21))
# Add ones to the array per the spec
tmpSM[1,2:6,2:6] <- 1
tmpSM[2,15:19,2:6] <- 1
tmpSM[3,2:6,8:13] <- 1
tmpSM[4,15:19,8:13] <- 1
tmpSM[5,2:6,15:19] <- 1
tmpSM[6,15:19,15:19] <- 1
# Plot each SM source
par
## function (..., no.readonly = FALSE)
## {
       .Pars.readonly <- c("cin", "cra", "csi", "cxy", "din", "page")
##
##
       single <- FALSE
##
       args <- list(...)</pre>
##
       if (!length(args))
##
           args <- as.list(if (no.readonly)</pre>
##
                .Pars[-match(.Pars.readonly, .Pars)]
##
           else .Pars)
       else {
##
##
            if (all(unlist(lapply(args, is.character))))
##
                args <- as.list(unlist(args))</pre>
           if (length(args) == 1) {
##
                if (is.list(args[[1L]]) | is.null(args[[1L]]))
##
##
                    args <- args[[1L]]</pre>
##
                else if (is.null(names(args)))
##
                    single <- TRUE
##
           }
##
       }
       value <- .External2(C_par, args)</pre>
##
##
       if (single)
##
           value <- value[[1L]]</pre>
##
       if (!is.null(names(args)))
           invisible(value)
##
       else value
##
## }
## <bytecode: 0x7fe044029388>
## <environment: namespace:graphics>
p1 <- levelplot(tmpSM[1,,], xlab="", ylab="", main="SM1", ylim=c(21, 1))</pre>
p2 <- levelplot(tmpSM[2,,], xlab="", ylab="", main="SM2", ylim=c(21, 1))
p3 <- levelplot(tmpSM[3,,], xlab="", ylab="", main="SM3", ylim=c(21, 1))
p4 <- levelplot(tmpSM[4,,], xlab="", ylab="", main="SM4", ylim=c(21, 1))
p5 <- levelplot(tmpSM[5,,], xlab="", ylab="", main="SM5", ylim=c(21, 1))
p6 <- levelplot(tmpSM[6,,], xlab="", ylab="", main="SM6", ylim=c(21, 1))
```

grid.arrange(p1, p2, p3, p4, p5, p6, ncol=2)



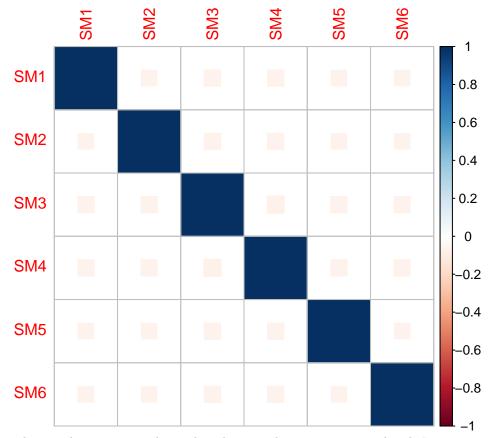




```
library(reticulate)
# Reshape the array into a 6 by 441 matrix
SM <- array_reshape(tmpSM, dim = c(6, 441))

# Convert SM to a dataframe
SMdf <- as.data.frame(t(SM))
colnames(SMdf) <- c("SM1", "SM2", "SM3", "SM4", "SM5", "SM6")

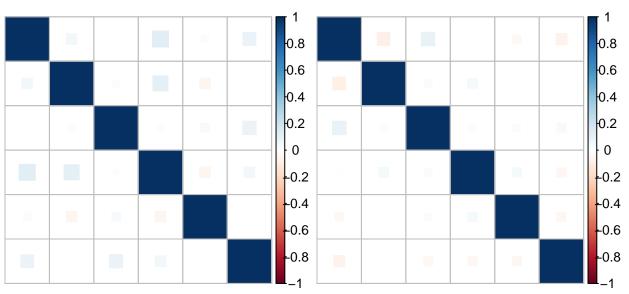
# Calculate and plot the correlation matrix
corrplot(cor(SMdf), method = "square")</pre>
```



The correlation matrix shows that the spatial maps are uncorrelated. It is not necessary to standardise the spatial maps as any difference in pixel values would be corrected when the synthetic dataset is standardised.

### remporar noise correlation

### Spatial Hoise Correlation

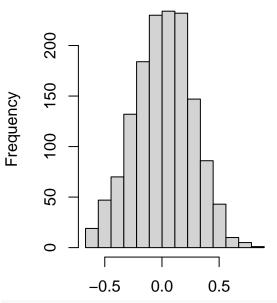


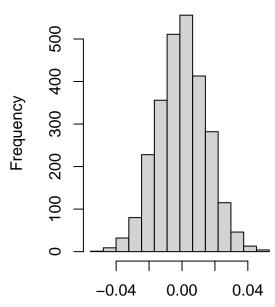
Both noise matrices are uncorrelated across sources.

```
# Plot histogram of both noise sources
par(mfrow = c(1, 2))
hist(noise_t, breaks = seq(min(noise_t), max(noise_t), length.out = 15),
    main = "Temporal noise distribution", xlab = NA)
hist(noise_s, breaks = seq(min(noise_s), max(noise_s), length.out = 15),
    main = "Spatial noise distribution", xlab = NA)
```

### **Temporal noise distribution**

### **Spatial noise distribution**



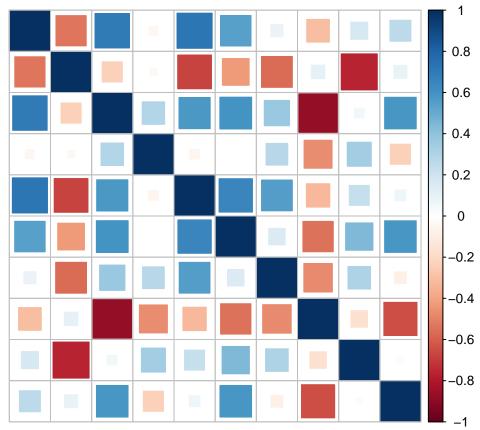


## [1] "Spatial noise: mean = 0 standard deviation = 0.015"

The mean and standard deviations of the noise sources fulfill the required criteria and the histograms show an approximately normal distribution.

```
# Calculate product of noise sources
noise_prod <- noise_t%*%noise_s

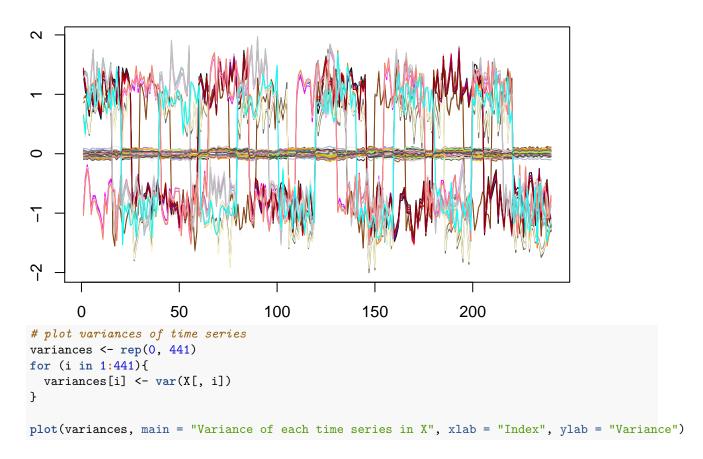
# Calculate and plot correlation matrix of a subset of the correlation variables
npdf <- as.data.frame(noise_prod[,1:10])
corrplot(cor(npdf), method = "square", tl.pos = "n")</pre>
```



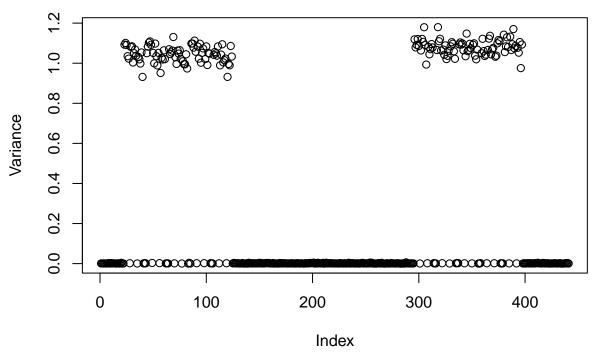
This correlation matrix shows that the  $\Gamma_t\Gamma_s$  is correlated across variables.

The products  $TC \times \Gamma_s$  and  $\Gamma_t \times SM$  exist and in the model they are captured by the error term. i.e.  $E = TC \times \Gamma_s + \Gamma_t \times SM + \Gamma_t \Gamma_s$ 

### 100 time series



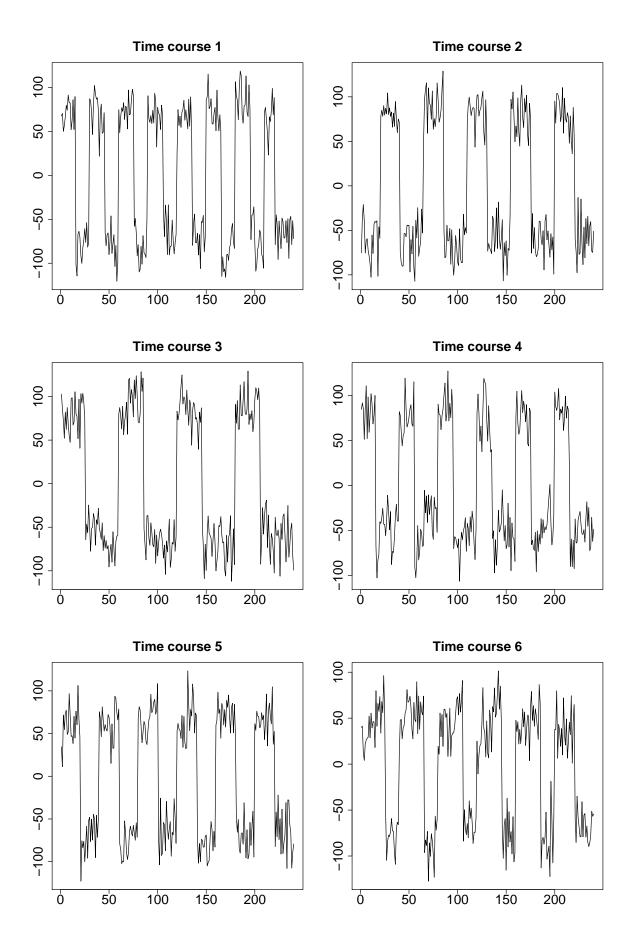
### Variance of each time series in X



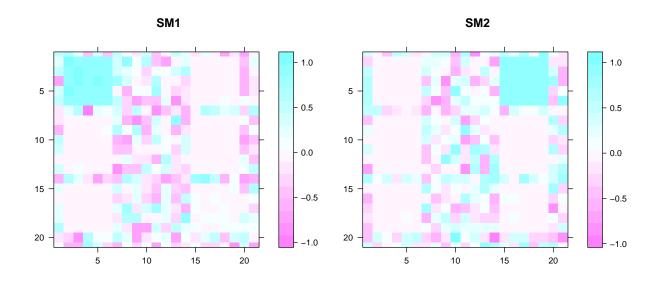
This scatter plot shows that the variance of most of the time series in X are close to 0. This is to be expected as most of the elements of SM are 0. Additionally, there are two distinct clusters of time-series with non-zero variance. This occurs because all the non-zero elements in the original spatial maps are between columns 2 and 6, and columns 15 and 19.

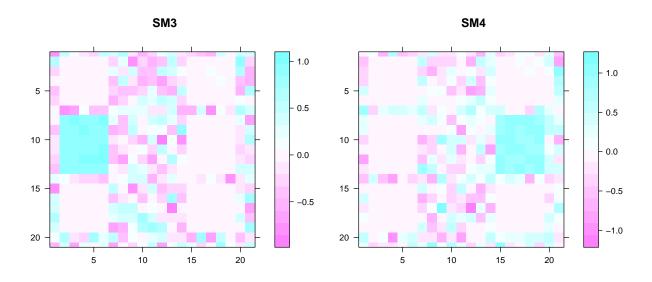
```
# Standardize columns of X
for (i in 1:441){
    X[, i] <- scale(X[, i])
}</pre>
```

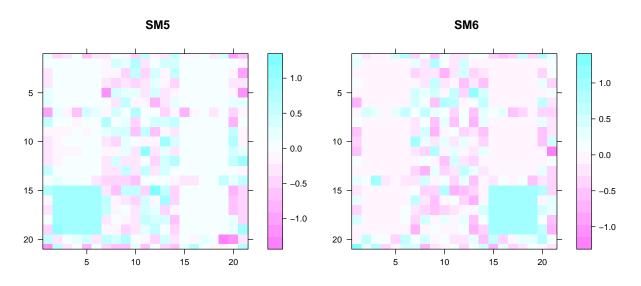
## Question 2



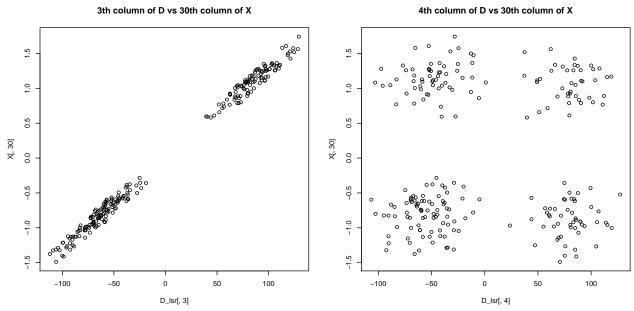
```
# Plot each retrieved spatial map
p1 <- levelplot(A_lsr_reshaped[1,,], xlab="", ylab="", main="SM1", ylim=c(21, 1))
p2 <- levelplot(A_lsr_reshaped[2,,], xlab="", ylab="", main="SM2", ylim=c(21, 1))
p3 <- levelplot(A_lsr_reshaped[3,,], xlab="", ylab="", main="SM3", ylim=c(21, 1))
p4 <- levelplot(A_lsr_reshaped[4,,], xlab="", ylab="", main="SM4", ylim=c(21, 1))
p5 <- levelplot(A_lsr_reshaped[5,,], xlab="", ylab="", main="SM5", ylim=c(21, 1))
p6 <- levelplot(A_lsr_reshaped[6,,], xlab="", ylab="", main="SM6", ylim=c(21, 1))</pre>
grid.arrange(p1, p2, p3, p4, p5, p6, ncol=2)
```







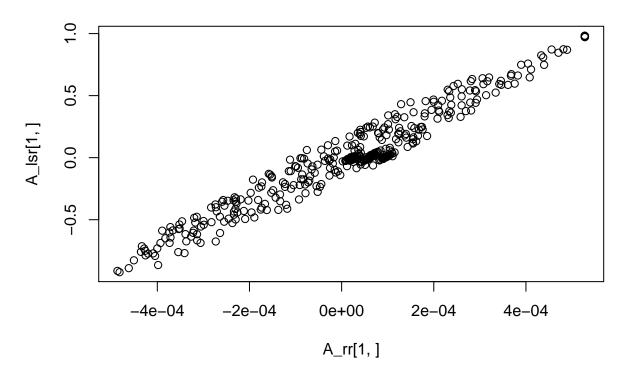
```
# Scatter plot of 3rd column of D and 30th column of X
plot(D_lsr[, 3], X[, 30], main="3th column of D vs 30th column of X")
# Scatter plot of 3rd column of D and 30th column of X
plot(D_lsr[, 4], X[, 30], main="4th column of D vs 30th column of X")
```



Because the shape map array was reshaped in a column-wise fashion, the 30th column of X corresponds to the signal at position (9, 2). This explains why there is a strong linear correlation between column 30 X and column 3 of  $D_{lsr}$ , but no correlation with column 4 of  $D_{lsr}$ . The third spatial map is the only one with a one in this position, hence, the 3rd time course is the only signal contributing to the series in this position.

```
library(matrixStats)
# Calculate ridge regression estimates
lambda <- 441*0.11
A_rr \leftarrow solve(t(TC)%*%TC + lambda*diag(6))%*%t(TC)%*%X
D_rr <- X%*%t(A_rr)</pre>
# Compute correlation vectors
c_tlsr <- rowMaxs(abs(cor(TC, D_lsr)))</pre>
c_trr <- rowMaxs(abs(cor(TC, D_rr)))</pre>
# Calculate sum of correlation vectors
sum(c_trr)
## [1] 5.806246
sum(c_tlsr)
## [1] 5.742089
# Calculate ridge regression estimates for lambda equals 1000 and plot first
# of A_rr vs first row of A_lsr
lambda <- 441*1000
A_{rr} \leftarrow solve(t(TC)%*%TC + lambda*diag(6))%*%t(TC)%*%X
D_rr <- X%*%t(A_rr)</pre>
plot(A_rr[1, ], A_lsr[1, ],
     main="First row of RR estimate vs First row of LSR estimate")
```

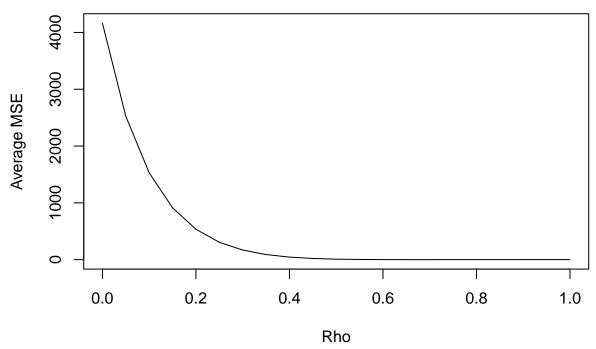
### First row of RR estimate vs First row of LSR estimate



This plot shows that with  $\lambda=1000,$  the values of  $\boldsymbol{a}_{RR}^1$  shrink to zero.

```
nsrcs <- 6
N < -240
V <- 441
x1 <- 21
x2 <- 21
MSE \leftarrow rep(0, 21)
for (i in 1:10){
  # Generate noise matrices
  noise_t <- matrix(rnorm(240*6, sd=0.25), 240, 6)
  noise_s <- matrix(rnorm(6*21*21, sd=0.015), 6, 21*21)
  # Generate synthetic dataset
  X <- (TC + noise_t)%*%(SM + noise_s)</pre>
  # Standardize columns of X
  for (i in 1:441){
    X[, i] <- scale(X[, i])</pre>
  for (j in 1:21){
    rho <- (j-1)*0.05
    # Calculate LR estimate (Code from spec)
    step <- 1/(norm(TC %*% t(TC)) * 1.1)</pre>
    thr <- rho*N*step
    Ao <- matrix(0, nsrcs, 1)
    A <- matrix(0, nsrcs, 1)
    A_lr <- matrix(0, nsrcs, x1*x2)
    for (k in 1:(x1*x2)) {
      A \leftarrow Ao+step*(t(TC) %*% (X[,k]-(TC%*%Ao)))
      A <- (1/(1+thr)) * (sign(A)*pmax(replicate(nsrcs, 0), abs(A)-thr))
      for (i in 1:10) {
        Ao <- A
        A \leftarrow Ao + step * (t(TC) % * %(X[,k] - (TC % * %Ao)))
        A <- (1/(1+thr)) * (sign(A)*pmax(replicate(nsrcs, 0), abs(A)-thr))
      A_{lr}[,k] \leftarrow A
    # Estimate D
    D_lr <- X%*%t(A_lr)</pre>
    # Calculate MSE
    MSE[j] <- MSE[j] + sum((X - D_lr%*%A_lr)^2)/(N*V)</pre>
```

## Average MSE vs Rho



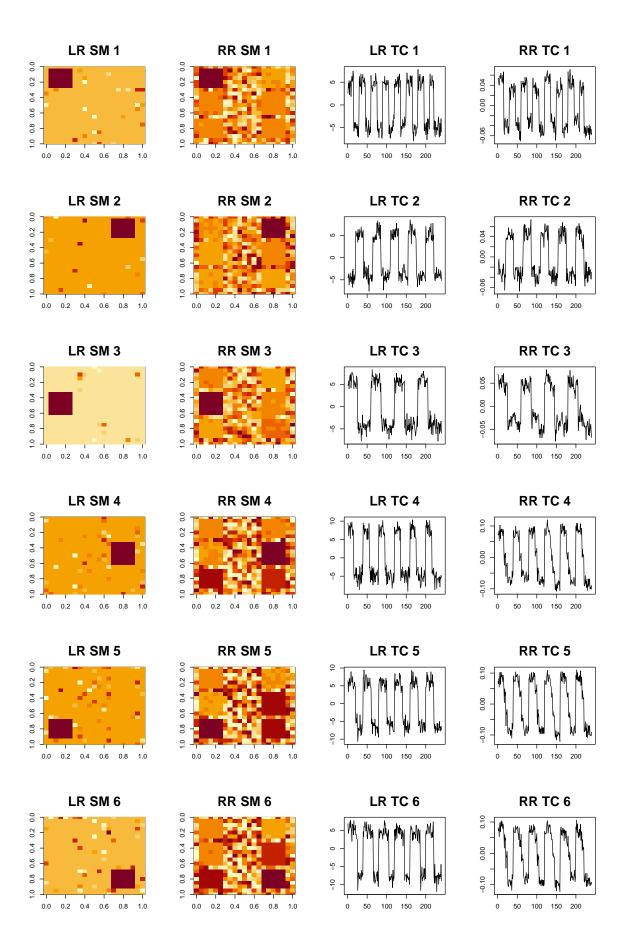
```
# Calculate rho that minimizes MSE
(rho <- (which.min(MSE)-1)*0.05)</pre>
```

#### ## [1] 0.7

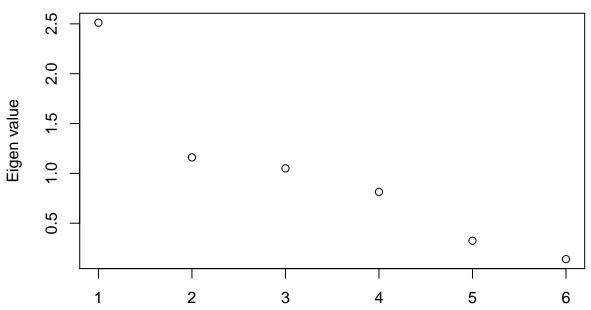
The value of  $\rho$  that minimised average MSE is 0.7, for values of  $\rho$  greater than this, MSE began to increase again. Give that this value was found to minimise MSE over several trials it is appropriate to select as it is unlikely to be overfit to noise.

```
# Calculate LR estimate (Code from spec)
step <- 1/(norm(TC %*% t(TC)) * 1.1)
thr <- rho*N*step
Ao <- matrix(0, nsrcs, 1)
A <- matrix(0, nsrcs, 1)
A_{lr} \leftarrow matrix(0, nsrcs, x1*x2)
for (k in 1:(x1*x2)) {
  A \leftarrow Ao+step*(t(TC) %*% (X[,k]-(TC%*%Ao)))
  A <- (1/(1+thr)) * (sign(A)*pmax(replicate(nsrcs, 0), abs(A)-thr))
  for (i in 1:10) {
    Ao <- A
    A \leftarrow Ao+step * (t(TC)%*%(X[,k]-(TC%*%Ao)))
    A \leftarrow (1/(1+thr)) * (sign(A)*pmax(replicate(nsrcs, 0), abs(A)-thr))
  A_{lr}[,k] \leftarrow A
# Estimate D_lr
D_lr <- X%*%t(A_lr)</pre>
# Compute correlation vectors
c_tlr <- rowMaxs(abs(cor(TC, D_lr)))</pre>
c_trr <- rowMaxs(abs(cor(TC, D_rr)))</pre>
c_slr <- rowMaxs(abs(cor(t(SM), t(A_lr))))</pre>
c_srr <- rowMaxs(abs(cor(t(SM), t(A_rr))))</pre>
# Calculate sums of correlation vectors
sum(c_tlr)
## [1] 5.829982
sum(c_trr)
## [1] 5.644746
sum(c_slr)
## [1] 5.422784
sum(c_srr)
## [1] 2.855429
```

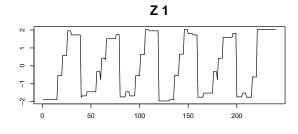
The retrieved spatial maps for Lasso regression have far fewer false positives than the spatial maps from Ridge regression, this is a result of the tendency of Lasso regression to set insignificant parameters to 0.

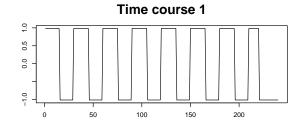


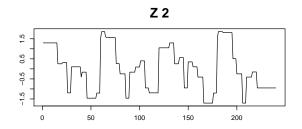
## Eigen values of principle components

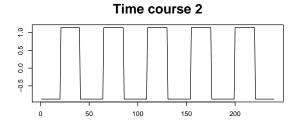


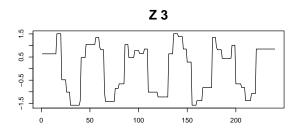
The sixth principle component by definition captures the least variance and thus has the lowest eigen value. The transformed regressors are a linear combination of the original time courses, and this process destroys their shape.

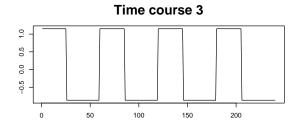


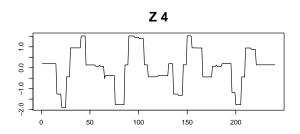


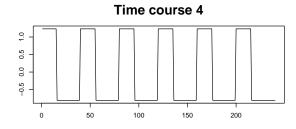


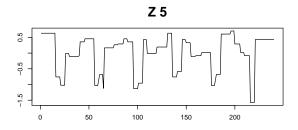


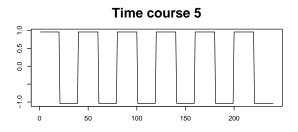


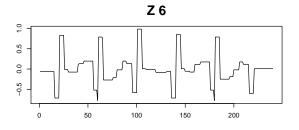


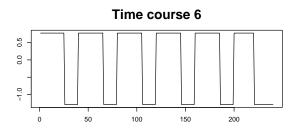












```
# Apply lasso regression with Z
rho <- 0.001
step <- 1/(norm(Z \%*\% t(Z)) * 1.1)
thr <- rho*N*step
Ao <- matrix(0, nsrcs, 1)
A <- matrix(0, nsrcs, 1)
A_pcr <- matrix(0, nsrcs, x1*x2)
for (k in 1:(x1*x2)) {
  A <- Ao+step*(t(Z) %*% (X[,k]-(Z%*%Ao)))
  A \leftarrow (1/(1+thr)) * (sign(A)*pmax(replicate(nsrcs, 0), abs(A)-thr))
  for (i in 1:10) {
    Ao <- A
    A \leftarrow Ao + step * (t(Z) % * %(X[,k] - (Z % * %Ao)))
    A \leftarrow (1/(1+thr)) * (sign(A)*pmax(replicate(nsrcs, 0), abs(A)-thr))
  A_pcr[,k] \leftarrow A
# Apply inverse principle component transformation
A_pcr <- t(t(A_pcr)%*%solve(pc$rotation))
# Estimate D_pcr
D_pcr <- X%*%t(A_pcr)</pre>
```

The results from principle component regression are inferior to the results from standard lasso regression, however from the following plots it is not obvious to tell that they are inferior to ridge or least squares regression. Additionally, it is only obvious that they are inferior in extracting the source spatial map. A possible explanation for this reduced performance is that in the principle component space the regressors are not spatially independent. It is also interesting to note that the performance deteriorates for each spatial map source (spatial maps 1 and 2 are retrieved more accurately than spatial maps 5 and 6).

