INSTRUCTIONS:

Fill out the hazard analysis and risk assessment below.

HA-001 should be for the lane departure warning function as discussed in the lecture.

HA-002 should be for the lane keeping assistance function as discussed in the lecture.

Then come up with your own situations and hazards for the lane assistance system. Fill ir When finished, export your spreadsheet as a pdf file so that a reviewer can easily see you

Hazard ID			S	ituational Analysis
	Operational Mode	Operational Scenario	Environmental Details	Situation Details
HA-001	OM03 - Normal driving	OS04 - Highway	EN06 - Rain (slippery road)	SD02 - High speed
HA-002	OM03 - Normal driving	OS03 - Country Road	EN01 - Normal conditions	SD02 - High speed
HA-003	OM03 - Normal driving	OS04 - Highway	EN04 - Snowfall (degraded view)	SD01 - Low speed
HA-004	OM03 - Normal driving	OS10 - Road with construction site	EN01 - Normal conditions	SD02 - High speed

1 the HA-003 and HA-004 rows. r work.

Other Details (optional)	Item Usage (function)	Situation Description	Function	Deviation
The system operates normally	IU01 - Correctly used	Normal driving on a Highway during Rain (slippery road) and Correctly used system	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the	DV04 - Actor effect is too much
			driver with haptic feedback	
The driver is misusing the LKA function as an autonomous function	used	High speed and Incorrectly used system	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	
view) the Camera subsystem is not able to recignize the Lane lines	IU01 - Correctly used	view) with Low speed and Correctly used system	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	
On the Road with construction site the Camera subsystem can confuse the lane lines	IU01 - Correctly used	Normal driving on a Road with a construction site with High speed and Correctly used system	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	DV03 - Function always activated

Hazard Identification			
Deviation Details	Hazardous Event (resulting effect)	Event Details	
The LDW function applies an oscillating torque with very high torque (above limit)	EV00 - Collision with other vehicle	High haptic feedback can affect driver's ability to steer as intended. The driver could lose control of the vehicle and collide with another vehicle or with road infrastructure	
The LKA function is always activated applying the steering torque in order to stay in the ego lane	EV00 - Collision with other vehicle	Misusing the LKA function makes potencial for vehicle collision	
The LKA function is always activated regardless the Enviromental Details	EV00 - Collision with other vehicle	The LKA function degrades in Snowfall and vehicle can collide with other vehicle or road infrastructure	
The LKA function is always activated regardless the Operational Scenario	EV-04 - Front collision with obstacle	The LKA function degrades on a Road with construction site and vehicle can collide with obstacle	

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Hazardous Event	Exposure	Rationale	Severity
Description	(of situation)	(for exposure)	(of potential harm)
The LDW function applies too high an oscillating torque to the	E3 - Medium	Highway driving during Rain (slippery road)	S3 - Life-threatening or fatal injuries
steering wheel (above limit)	probability	(Silppery Toad)	ratai irijunes
The driver was misusing the LKA function by taking both hands off the wheel and incorrectly treating the car as a	E2 - Low probability	The combination of driving on Country Road and misusing the function is not happening too often	S3 - Life-threatening or fatal injuries
fully autonomous vehicle. Snowfall condition makes it	E2 - Low	Driving in Snowfall condition is not	S0 - No injuries
difficult for Camera subsystem to detect lane line so the LKA function degrades and vehicle can collide with other vehicle or road infrastructure	probability	happening to often	·
On the Road with a construction site the lane lines can be missing or confusing, the LKA function degrades and vehicle can collide with obstacle	E2 - Low probability	Driving on Road with construction site is not happening to often	S3 - Life-threatening or fatal injuries

dous Event Classification			
Rationale (for severity)	Controllability (of hazardous event)	Rationale (for controllability)	
On the Highway the dtriver was travelling at high speed (> 40 km/h)	C3 - Difficult to control or uncontrollable	When the LDW function causes an excessive vibration of the steering wheel, most drivers would have difficulty controlling the vehicle	
On the Highway the driver was travelling at high speed (>40 km/h)		The malfunction was that the LKA function was always on and had no time limit, so drivers could take both hands off the wheel. Because hands aren't on the wheel at high speeds, a vehicle accident would not be controllable.	
Driving in Snowfall condition is difficult, at Low speed (< 40 km/h). The collision would not injure the driver		It is difficult to control the vehicle when driving in Snowfall (degraded view).	
It could be construction on Highway with speed limit 80 km/h and the driver was travelling at high speed (>40 km/h)	uncontrollable	It is difficult to control the vehicle when driving in on Road with construction site at high speed.	

Determination of ASIL and Safety Goals		
ASIL Determination	Safety Goal	
С	The oscillating steering torque from the LDW fuction shall be limited	
В	The LKA function shall be time limited and additional steering torque shall end after given time interval so that the driver could not misuse the system for autonomous driving	
QM	The Lane Assistance system shall be deactivated when driving in Snowfall condition. The Camera subsystem shall be enhanced to recognize the Snowfall (degraded view) condition and disable activation of the LA system.	
В	The Lane Assistance system shall be deactivated when driving on Road with construction site. The Camera subsystem shall be enhanced to detect a Road with construction site (traffic sign recognition) and disable activation of the LA system.	